

## 600kHz 18V 5A Synchronous COT Step-Down Converter

### Features

- 40mΩ/20mΩ Low  $R_{DS(ON)}$  internal FETs
- High Efficiency Synchronous-Mode Operation
- Wide Input Range: 4.5V to 18V
- Feedback Voltage Accuracy 0.8V±2%
- 600kHz Switch Frequency
- Up to 5A Output Current
- COT control to achieve fast transient responses
- Power Save Mode at Light Load
- Integrated internal compensation
- Stable with Low ESR Ceramic Output Capacitors
- Over Current Protection with Hiccup Mode
- Thermal Shutdown
- Inrush Current Limit and Soft Start
- Build in Input Over Voltage Protection
- Available in DFN2x2-6FC Package

### Description

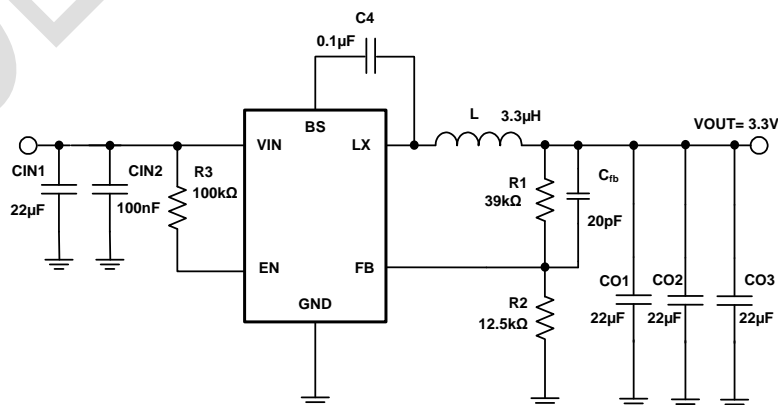
The TMI3255 is a high efficiency 600kHz, Constant on-Time (COT) control mode synchronous step-down DC-DC converter capable of delivering up to 5A current. TMI3255 integrates main switch and synchronous switch with very low  $R_{DS(ON)}$  to minimize the conduction loss. Low output voltage ripple and small external inductor and capacitor size are achieved with 600kHz switching frequency. It adopts the COT architecture to achieve fast transient responses for high voltage step down applications.

The TMI3255 requires a minimum number of readily available standard external components and is available in a 6-pin DFN2x2-6FC ROHS compliant package.

### Application

- Digital Set Top Boxes
- Flat Panel Television and Monitors
- Notebook computer
- Wireless and DSL Modems

### Typical Application

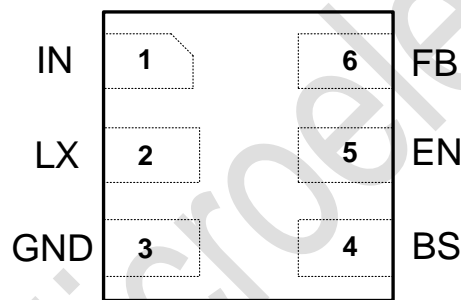


**TMI3255 Typical Application Circuits**

## Absolute Maximum Ratings (Note 1)

Parameter	Min	Max	Unit
Input Supply Voltage, EN	-0.3	20	V
LX Voltages	-0.3	20	V
LX Voltages (<10ns transient)	-4.5	22	V
FB Voltage	-0.3	6	V
BS Voltage	-0.3	23	V
Storage Temperature Range	-65	150	°C
Junction Temperature <small>(Note2)</small>	160		°C
Power Dissipation	1500		mW
Lead Temperature (Soldering, 10s)	260		°C

## Package



Top View

DFN2x2-6FC

Top Marking: TM5XXX

TM5: Device Code

XXX: Inside Code

## Order Information

Part Number	Package	Top Marking	Quantity/Reel
TMI3255	DFN2x2-6FC	TM5XXX	3000

TMI3255 devices are Pb-free and RoHS compliant.

## Pin Functions

Pin	Name	Function
1	IN	Power supply Pin
2	LX	Switching Pin
3	GND	Ground Pin
4	BS	Bootstrap. A capacitor connected between LX and BS pins is required to form a floating supply across the high-side switch driver.
5	EN	Drive this pin to a logic-high to enable the IC. Drive to a logic-low to disable the IC and enter micro-power shutdown mode. Don't floating EN.
6	FB	Output Voltage feedback input. Connect FB to the center point of the external resistor divider.

## ESD Rating

Items	Description	Value	Unit
V <sub>ESD_HBM</sub>	Human Body Model for all pins	±2000	V
V <sub>ESD_CDM</sub>	Charged Device Model for all pins	±2000	V

JEDEC specification JS-001

## Recommended Operating Conditions

Items	Description	Min	Max	Unit
Voltage Range	IN	4.5	18	V
T <sub>J</sub>	Operating Junction Temperature	-40	125	°C

## Thermal Resistance (Note3)

Items	Description	Value	Unit
θ <sub>JA</sub>	Junction-to-ambient thermal resistance	90	°C/W
θ <sub>JC</sub>	Junction-to-case(top) thermal resistance	26	°C/W

## Electrical Characteristics

$V_{IN}=12V$ ,  $V_{OUT}=1.2V$ ,  $T_A = 25^{\circ}C$ , unless otherwise noted.

Parameter	Conditions	Min	Typ	Max	Units
Input Voltage Range		4.5		18	V
OVP Threshold			19.3		V
UVLO Rising Threshold			4.2		V
UVLO Hysteresis			0.35		V
Quiescent Current	$V_{EN}=2V$ , $V_{FB}=V_{REF} \times 105\%$		300		$\mu A$
Shutdown Current	$V_{IN}=12V$ , $EN=0V$		5	10	$\mu A$
Regulated Feedback Voltage	$T_A=25^{\circ}C$ , $4.5V \leq V_{IN} \leq 18V$	0.784	0.8	0.816	V
High-Side Switch On-Resistance			40		m $\Omega$
Low-Side Switch On-Resistance			20		m $\Omega$
High-Side Switch Leakage Current	$V_{EN}=0V$ , $V_{LX}=0V$	1		10	$\mu A$
High-side Switch Peak Current Limit			8		A
Low-side Switch Valley Current Limit			6.5		A
On Time	$V_{IN}=12V$ , $V_{OUT}=1.2V$ , $I_{OUT}=1A$	132	166	200	ns
Oscillation Frequency		500	600	700	kHz
Maximum Duty Cycle			90		%
Minimum On-Time <sub>(Note 4)</sub>		70	80	100	ns
Soft Start Time			1		ms
Hiccup on Time <sub>(Note 4)</sub>			1.2		ms
Hiccup Time Before Restart <sub>(Note 4)</sub>			3.6		ms
EN Rising Threshold			1.0		V
EN Falling Threshold			0.9		V
EN Hysteresis			100		mV
Thermal Shutdown Threshold <sub>(Note 4)</sub>			165		$^{\circ}C$
Thermal Shutdown Hysteresis <sub>(Note 4)</sub>			30		$^{\circ}C$

**Note 1:** Absolute Maximum Ratings are those values beyond which the life of a device may be impaired.

**Note 2:**  $T_J$  is calculated from the ambient temperature  $T_A$  and power dissipation  $P_D$  according to the following formula:  $T_J = T_A + P_D \times \theta_{JA}$ . The maximum allowable continuous power dissipation at any ambient temperature is calculated by  $P_{D(MAX)} = (T_{J(MAX)} - T_A) / \theta_{JA}$ .

**Note 3:** Measured on JESD51-7, 4-layer PCB.

**Note 4:** Guaranteed by design.

## Block Diagram

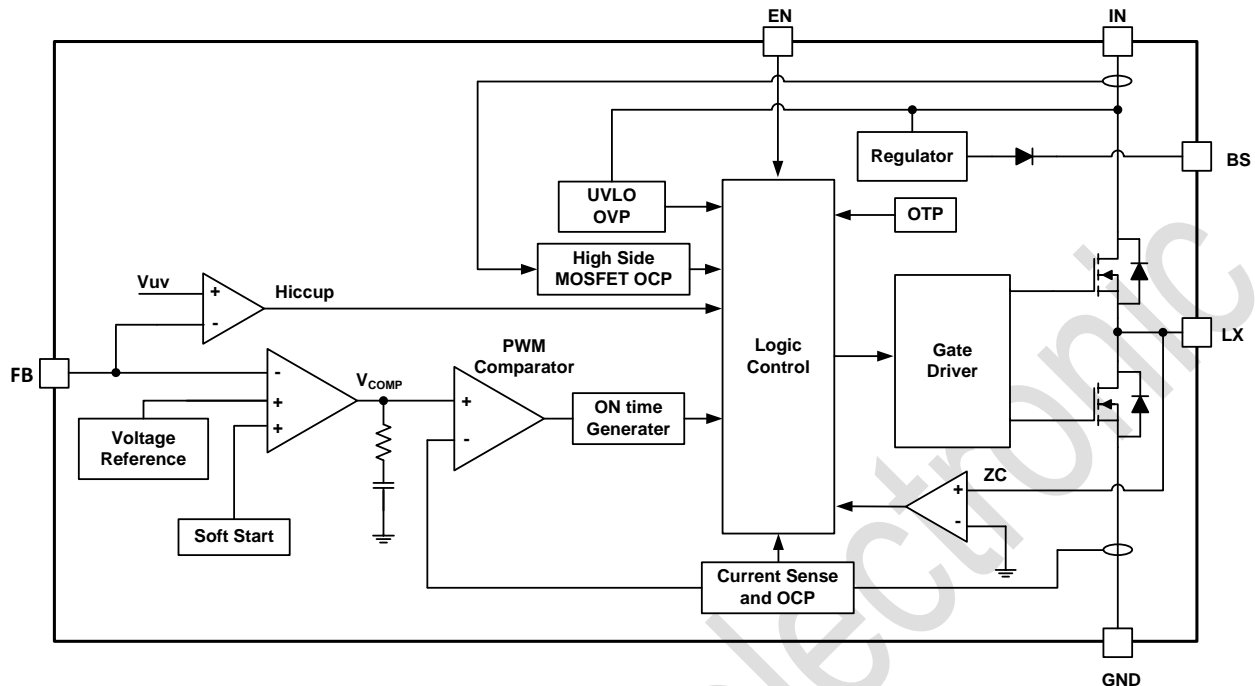


Figure 1. TMI3255 Block Diagram

## Operation Description

### Internal Regulator

The TMI3255 is a constant on-time (COT) step down DC/DC converter that provides excellent transient response with no extra external compensation components. This device contains low resistance, high voltage high side and low side power MOSFETs, and operates at 600kHz operating frequency to ensure a compact, high efficiency design with excellent AC and DC performance.

### Error Amplifier

TMI3255 adopts operational transconductance amplifier (OTA) as error amplifier. The error amplifier compares the FB pin voltage with the internal FB reference ( $V_{REF}$ ) and outputs a current proportional to the difference between the two. This output current is then used to charge or discharge the internal compensation network to form the  $V_{COMP}$  voltage, which is used to compare with the low side power MOSFET current sensing signal and trigger on time pulse. The optimized internal compensation network minimizes the external component counts and simplifies the control loop design.

### Internal Soft-Start

The soft-start is implemented to prevent the converter output voltage from overshooting during startup. When the chip starts, the internal circuitry generates a soft-start voltage (SS) ramping up from 0V to  $V_{REF}$ . When it is lower than the internal FB reference ( $V_{REF}$ ), SS overrides REF so the error amplifier uses SS as the reference. When SS is higher than  $V_{REF}$ ,  $V_{REF}$  regains control. The SS time is internally fixed to 1ms typically.

## Over-Current-Protection and Short Circuits Protection

The TMI3255 has both high-side and low-side MOSFET cycle-by-cycle current limit function. When the inductor current peak value is larger than the switch peak current limit after the blinking time, high side MOSFET is turned off immediately. When inductor current valley value is larger than the valley current limit during low side MOSFET on state, the device enters into valley over current protection mode and low side MOSFET keeps on state until inductor current drops down to the value equal or lower than the valley current limit, and then on time pulse could be generated and high side MOSFET could turn on again.

If the output is short to GND and the output voltage drop until feedback voltage  $V_{FB}$  is below the output under-voltage  $V_{UV}$  threshold which is typically 65% of  $V_{REF}$ , TMI3255 enters into hiccup mode to periodically disable and restart switching operation. The hiccup mode helps to reduce power dissipation and thermal rise during output short condition. The period of TMI3255 hiccup mode is typically 4.8ms.

## Startup and Shutdown

If both  $V_{IN}$  and  $EN$  are higher than their appropriate thresholds, the chip starts switching operation. The reference block starts first, generating stable reference voltage and currents, and then the internal regulator is enabled. The regulator provides stable supply for the remaining circuitries. Three events can shut down the chip:  $EN$  low,  $V_{IN}$  low and thermal shutdown. In the shutdown procedure, the signaling path is first blocked to avoid any fault triggering. The  $V_{COMP}$  voltage and the internal supply rail are then pulled down. The floating driver is not subject to this shutdown command.

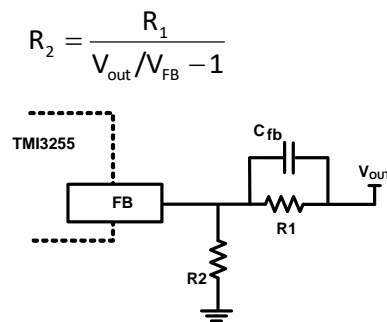
## Application Information

### Setting the Output Voltage

The external resistor divider is used to set the output voltage (see Typical Application on page 1). Choose  $R_1$  to be around 39k $\Omega$  for optimal transient response.  $R_2$  is then given by:

**Table 1: Selection for Common Output Voltages ( $V_{FB}=0.8V$ )**

$V_{OUT}$ (V)	$R_1$ (k $\Omega$ )	$R_2$ (k $\Omega$ )	$C_{FB}$ (pF)	$L$ ( $\mu$ H)
5	39	7.5	20	3.3
3.3	39	12.4	20	3.3
2.5	39	18.2	20	3.3
1.8	39	30.9	20	2.2
1.5	39	44.2	20	2.2
1.2	39	78.7	20	1.5
1	18	71.5	20	1.0



**Figure 2. Feedback Network**

### Selecting the Inductor

A 1.0 $\mu$ H to 4.7 $\mu$ H inductor with a DC current rating of at least 25% percent higher than the maximum load current is recommended for most applications. For highest efficiency, the inductor DC resistance should be as small as possible. For most designs, the inductance value can be derived from the following equation.

$$L = \frac{V_{out} \times (V_{in} - V_{out})}{V_{in} \times \Delta I_L \times f_{OSC}}$$

Where  $\Delta I_L$  is the inductor ripple current. Choose inductor ripple current to be approximately 30% if the maximum load current 5A. The maximum inductor peak current is:

$$I_{L(MAX)} = I_{LOAD} + \frac{\Delta I_L}{2}$$

Under light load conditions below 100mA, larger inductance is recommended for improved efficiency.

### Selecting the Output Capacitor

The output capacitors are required to maintain the DC output voltage. Ceramic, tantalum, or low ESR electrolytic capacitors are recommended. Low ESR capacitors are preferred to keep the output voltage ripple low. The output voltage ripple can be estimated by:

$$\Delta V_{OUT} = \frac{V_{OUT}}{f_s \times L} \times \left[ 1 - \frac{V_{OUT}}{V_{IN}} \right] \times \left[ R_{ESR} + \frac{1}{8 \times f_s \times C_2} \right]$$

Where L is the inductor value and  $R_{ESR}$  is the equivalent series resistance (ESR) value of the output capacitor. In the case of ceramic capacitors, the impedance at the switching frequency is dominated by the capacitance. The output voltage ripple is mainly caused by the capacitance. For simplification, the output voltage ripple can be estimated by:

$$\Delta V_{OUT} = \frac{V_{OUT}}{8 \times f_s^2 \times L \times C_2} \times \left[ 1 - \frac{V_{OUT}}{V_{IN}} \right]$$

In the case of tantalum or electrolytic capacitors, the ESR dominates the impedance at the switching frequency. For simplification, the output ripple can be approximated to:

$$\Delta V_{OUT} = \frac{V_{OUT}}{f_s \times L} \times \left[ 1 - \frac{V_{OUT}}{V_{IN}} \right] \times R_{ESR}$$

The characteristics of the output capacitor also affect the stability of the regulation system. The TMI3253 can be optimized for a wide range of capacitance and ESR values.

### PCB Layout Guide

PCB layout is very important to achieve stable operation. Please follow these guidelines for reference.

- 1) Keep the path of switching current short and minimize the loop area formed by Input capacitor, IN pin and GND.
- 2) Bypass ceramic capacitors are suggested to be put close to the IN Pin.
- 3) Ensure all feedback connections are short and direct. Place the feedback resistors as close to the chip as possible.
- 4) VOUT, LX away from sensitive analog areas such as FB.
- 5) Connect IN, LX, and especially GND respectively to a large copper area to cool the chip to improve thermal performance and long-term reliability.





