Terminal Voltages ±5V, 32 Taps, Log Taper

X9314

Single Digitally Controlled Potentiometer (XDCP™)

FEATURES

- **Solid State Potentiometer**
- **32 Taps**
- **10KΩ End to End Resistance**
- **Three-Wire Up/Down Serial Interface**
- **Wiper Resistance, 40Ω Typical**
- **Nonvolatile Storage and Recall on Power Up of Wiper Position Standby Current < 500µA Max (Total Package)**
- **V_{CC} = 3V to 5.5V Operation**
- **100 Year Data Retention**
- **Offered in MSOP, SOIC Packages**

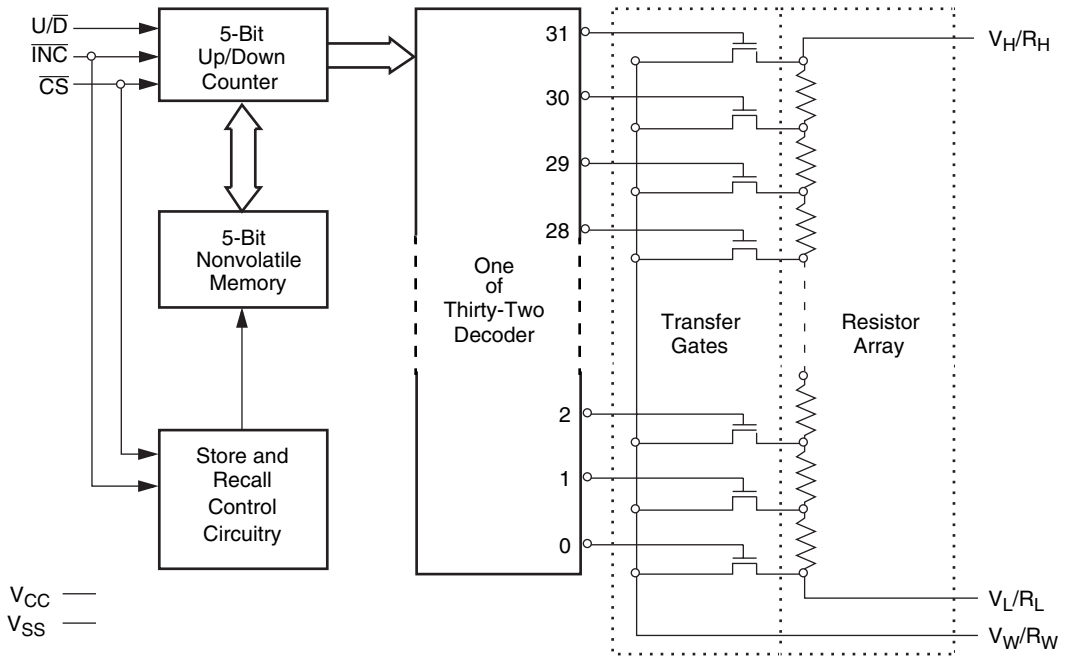
DESCRIPTION

The Xicor X9314 is a solid state nonvolatile potentiometer and is ideal for digitally controlled resistance trimming.

The X9314 is a resistor array composed of 31 resistive elements. Between each element and at either end are tap points accessible to the wiper element. The position of the wiper element is controlled by the $\overline{CS}$, U/$\overline{D}$, and $\overline{INC}$ inputs. The position of the wiper can be stored in nonvolatile memory and then be recalled upon a subsequent power-up operation.

The XDCP can be used as a three-terminal potentiometer or as a two-terminal variable resistor in a wide variety of applications including control, parameter adjustments, and signal processing.

BLOCK DIAGRAM



XDCP is a trademark of Xicor, Inc.

PIN DESCRIPTIONS

V_H/R_H and V_L/R_L

The high (V_H/R_H) and low (V_L/R_L) terminals of the X9314 are equivalent to the fixed terminals of a mechanical potentiometer. The minimum voltage is –5V and the maximum is +5V. It should be noted that the terminology of V_L/R_L and V_H/R_H references the relative position of the terminal in relation to wiper movement direction selected by the U/$\overline{D}$ input and not the voltage potential on the terminal.

V_W/R_W

V_W/R_W is the wiper terminal, equivalent to the movable terminal of a mechanical potentiometer. The position of the wiper within the array is determined by the control inputs. The wiper terminal series resistance is typically 40Ω.

Up/Down (U/$\overline{D}$)

The U/$\overline{D}$ input controls the direction of the wiper movement and whether the counter is incremented or decremented.

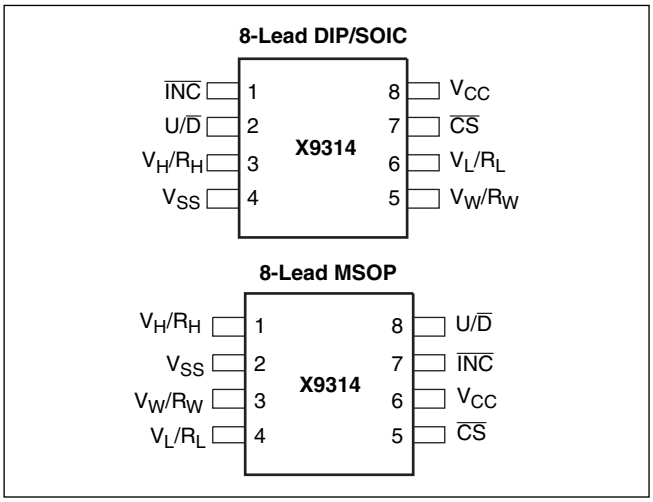
Increment ($\overline{INC}$)

The $\overline{INC}$ input is negative-edge triggered. Toggling $\overline{INC}$ will move the wiper and either increment or decrement the counter in the direction indicated by the logic level on the U/$\overline{D}$ input.

Chip Select ($\overline{CS}$)

The device is selected when the $\overline{CS}$ input is LOW. The current counter value is stored in nonvolatile memory when $\overline{CS}$ is returned HIGH while the $\overline{INC}$ input is also HIGH. After the store operation is complete the X9314 will be placed in the low power standby mode until the device is selected once again.

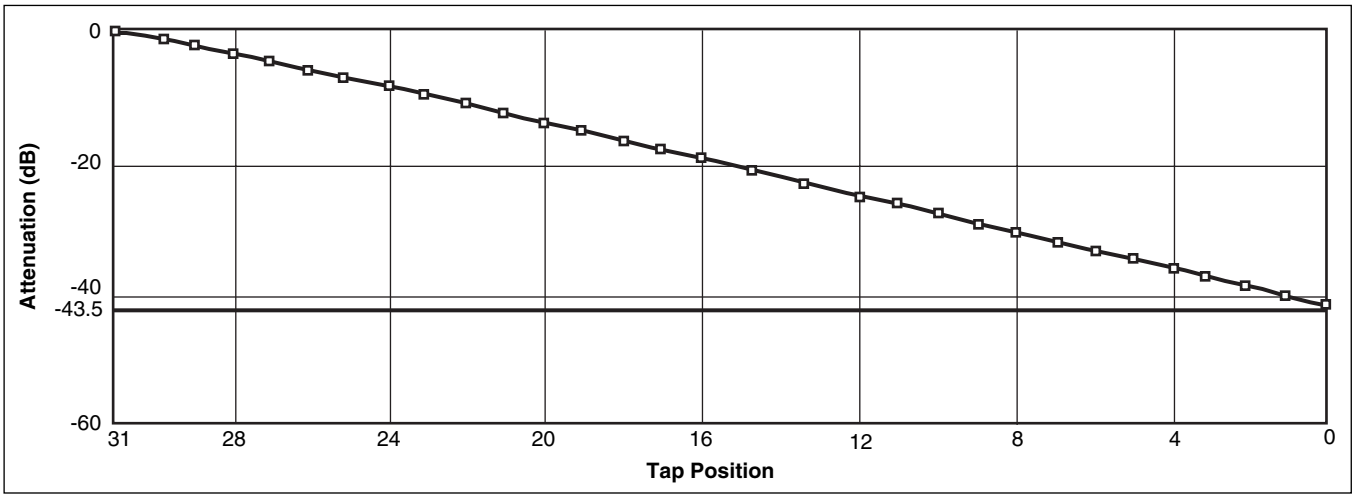
PIN CONFIGURATION



PIN NAMES

Symbol	Description
V_H/R_H	High Terminal
V_W/R_W	Wiper Terminal
V_L/R_L	Low Terminal
V_{SS}	Ground
V_{CC}	Supply Voltage
U/$\overline{D}$	Up/Down Input
INC	Increment Input
$\overline{CS}$	Chip Select Input

Typical Attenuation Characteristics (dB)



PRINCIPLES OF OPERATION

There are three sections of the X9314: the input control, counter and decode section; the nonvolatile memory; and the resistor array. The input control section operates just like an up/down counter. The output of this counter is decoded to turn on a single electronic switch connecting a point on the resistor array to the wiper output. Under the proper conditions the contents of the counter can be stored in nonvolatile memory and retained for future use. The resistor array is comprised of 31 individual resistors connected in series. At either end of the array and between each resistor is an electronic switch that transfers the potential at that point to the wiper.

The $\overline{INC}$, U/$\overline{D}$ and $\overline{CS}$ inputs control the movement of the wiper along the resistor array. With $\overline{CS}$ set LOW the X9314 is selected and enabled to respond to the

U/$\overline{D}$ and $\overline{INC}$ inputs. HIGH to LOW transitions on $\overline{INC}$ will increment or decrement (depending on the state of the U/$\overline{D}$ input) a five bit counter. The output of this counter is decoded to select one of thirty-two wiper positions along the resistive array.

The wiper, when at either fixed terminal, acts like its mechanical equivalent and does not move beyond the last position. That is, the counter does not wrap around when clocked to either extreme.

The value of the counter is stored in nonvolatile memory whenever $\overline{CS}$ transistions HIGH while the $\overline{INC}$ input is also HIGH.

When the X9314 is powered-down, the last counter position stored will be maintained in the nonvolatile memory. When power is restored, the contents of the memory are recalled and the counter is reset to the value last stored.

Operation Notes

The system may select the X9314, move the wiper and deselect the device without having to store the latest wiper position in nonvolatile memory. The wiper movement is performed as described above; once the new position is reached, the system would keep the $\overline{INC}$ LOW while taking $\overline{CS}$ HIGH. The new wiper position would be maintained until changed by the system or until a power-up/down cycle recalled the previously stored data.

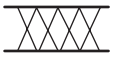
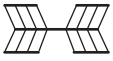
This would allow the system to always power-up to a preset value stored in nonvolatile memory; then during system operation minor adjustments could be made. The adjustments might be based on user preference, system parameter changes due to temperature drift, etc...

The state of U/$\overline{D}$ may be changed while $\overline{CS}$ remains LOW. This allows the host system to enable the X9314 and then move the wiper up and down until the proper trim is attained.

t_{IW}/R_{TOTAL}

The electronic switches on the X9314 operate in a “make before break” mode when the wiper changes tap positions. If the wiper is moved several positions multiple taps are connected to the wiper for t_{IW} ($\overline{INC}$ to V_W change). The R_{TOTAL} value for the device can temporarily be reduced by a significant amount if the wiper is moved several positions.

SYMBOL TABLE

WAVEFORM	INPUTS	OUTPUTS
	Must be steady	Will be steady
	May change from Low to High	Will change from Low to High
	May change from High to Low	Will change from High to Low
	Don’t Care: Changes Allowed	Changing: State Not Known
	N/A	Center Line is High Impedance

ABSOLUTE MAXIMUM RATINGS

Temperature under bias .....–65°C to +135°C
Storage temperature .....–65°C to +150°C
Voltage on $\overline{CS}$, $\overline{INC}$, U/$\overline{D}$, and
V_{CC} with respect to V_{SS} .....–1V to +7V
Voltage on V_H/R_H and V_L/R_L referenced
to V_{SS}.....-8V to +8V
$\Delta V = |V_H/R_H – V_L/R_L|$..... 10V
Lead temperature (soldering 10 seconds).....300°C
Wiper current ..... ±1mA
I_W (10 seconds) ..... ±8.8mA

COMMENT

Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only; functional operation of the device (at these or any other conditions above those listed in the operational sections of this specification) is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

RECOMMENDED OPERATING CONDITIONS

Temperature	Min.	Max.
Commercial	0°C	+70°C
Industrial	–40°C	+85°C

Supply Voltage (V_{CC})	Limits
X9314	5V ±10%
X9314-3	3V to 5.5V

POTENTIOMETER CHARACTERISTICS (Over recommended operating conditions unless otherwise stated.)

Symbol	Parameter	Limits				Test Conditions/ Notes
		Min.	Typ.	Max.	Units	
R_{TOTAL}	End to End Resistance Tolerance			±20	%	
	V_H/R_H Terminal Voltage	-5		+5	V	
$V_{VL/RL}$	V_L/R_L Terminal Voltage	-5		+5	V	
	Power Rating			10	mW	at 25°C
R_W	Wiper Resistance		40	100	Ω	I_W = ±1mA, V_{CC} = 5V
I_W	Wiper Current			±4.4	mA	
	Noise		-120		dBV	Ref: 1kHz
	Relative variation. Error in step size between taps.	0.07-0.003		0.07 + 0.003		log ($R_{w(n)}$)–log $R_{w(n-1)}$)
	R_{TOTAL} Temperature Coefficient		±600		ppm/°C	for -40°C to +85°C
	Ratiometric Temperature Coefficient			±20	ppm/°C	
$C_H/C_L/C_W$	Potentiometer Capacitance		10/10/25	pF		See Circuit #3

Notes: (1) This parameter is periodically sampled and not 100% tested.

POWER UP AND DOWN REQUIREMENT

The are no restrictions on the sequencing of V_{CC} and the voltages applied to the potentiometer pins during power-up or power-down conditions. During power-up, the data sheet parameters for the DCP do not fully apply until 1 millisecond after V_{CC} reaches its final value. The V_{CC} ramp rate spec is always in effect.

D.C. OPERATING CHARACTERISTICS (Over recommended operating conditions unless otherwise specified.)

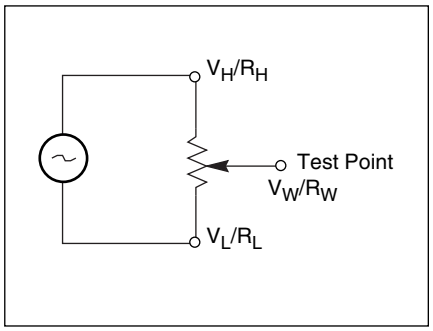
Symbol	Parameter	Limits			Units	Test Conditions
		Min.	Typ.(4)	Max.		
I_{CC}	V_{CC} Active Current		1	3	mA	$\overline{CS}$ = V_{IL}, U/$\overline{D}$ = V_{IL} or V_{IH} and $\overline{INC}$ = 0.4V/2.4V @ max. t_{CYC}
I_{SB}	Standby Supply Current			500	µA	$\overline{CS}$ = V_{CC} – 0.3V, U/$\overline{D}$ and $\overline{INC}$ = V_{SS} or V_{CC} – 0.3V
I_{LI}	$\overline{CS}$, $\overline{INC}$, U/$\overline{D}$ Input Leakage Current			±10	µA	V_{IN} = V_{SS} to V_{CC}
V_{IH}	$\overline{CS}$, $\overline{INC}$, U/$\overline{D}$ Input HIGH Voltage	2		V_{CC} + 1	V	
V_{IL}	$\overline{CS}$, $\overline{INC}$, U/$\overline{D}$ Input LOW Voltage	–1		0.8	V	
C_{IN}(5)	$\overline{CS}$, $\overline{INC}$, U/$\overline{D}$ Input Capacitance			10	pF	V_{CC} = 5V, V_{IN} = V_{SS}, T_A = 25°C, f = 1MHz

STANDARD PARTS

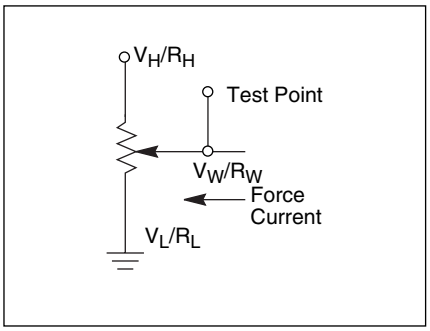
Part Number	Maximum Resistance	Wiper Increments	Minimum Resistance
X9314W	10KΩ	Log Taper	40Ω

Notes: (4) Typical values are for T_A = 25°C and nominal supply voltage.
(5) This parameter is periodically sampled and not 100% tested.

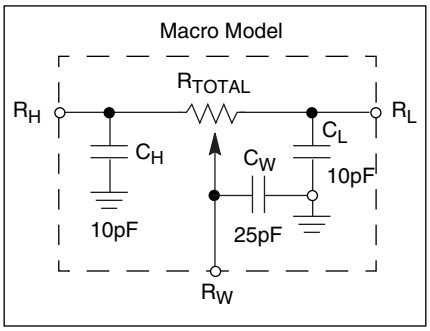
Test Circuit #1



Test Circuit #2



Circuit #3 SPICE Macromodel



A.C. CONDITIONS OF TEST

Input Pulse Levels	0V to 3V
Input rise and fall times	10ns
Input reference levels	1.5V

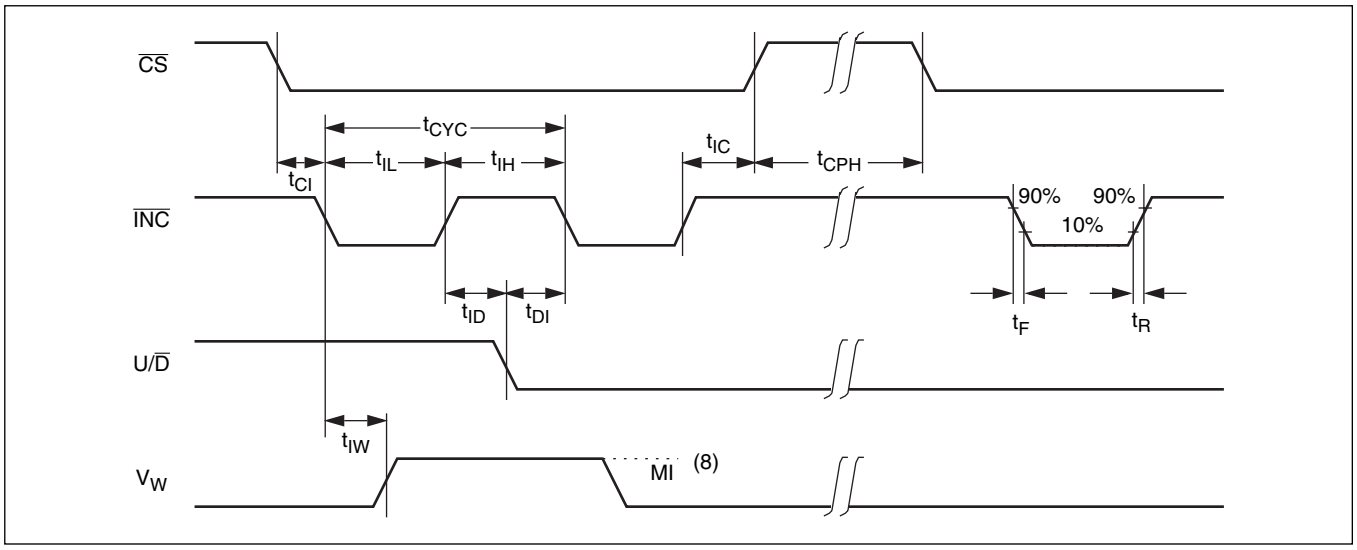
MODE SELECTION

$\overline{CS}$	$\overline{INC}$	U/$\overline{D}$	Mode
L	↘	H	Wiper up
L	↘	L	Wiper down
↗	H	X	Store wiper position
H	X	X	Standby
↗	L	X	No store, return to standby

A.C. OPERATING CHARACTERISTICS (Over recommended operating conditions unless otherwise specified)

Symbol	Parameter	Limits			Units
		Min.	Typ.(6)	Max.	
t_{CI}	$\overline{CS}$ to $\overline{INC}$ Setup	100			ns
t_{ID}	$\overline{INC}$ HIGH to U/$\overline{D}$ Change	100			ns
t_{DI}	U/$\overline{D}$ to $\overline{INC}$ Setup	2.9			µs
t_{IL}	$\overline{INC}$ LOW Period	1			µs
t_{IH}	$\overline{INC}$ HIGH Period	1			µs
t_{IC}	$\overline{INC}$ Inactive to $\overline{CS}$ Inactive	1			µs
t_{CPH}	$\overline{CS}$ Deselect Time	20			ms
t_{IW}	$\overline{INC}$ to V_W Change		100	500	µs
t_{CYC}	$\overline{INC}$ Cycle Time	4			µs
t_R, t_F(7)	$\overline{INC}$ Input Rise and Fall Time			500	µs
t_{PU}(7)	Power up to Wiper Stable			500	µs
t_R V_{CC}	V_{CC} Power-up Rate	0.2		50	mV/µs

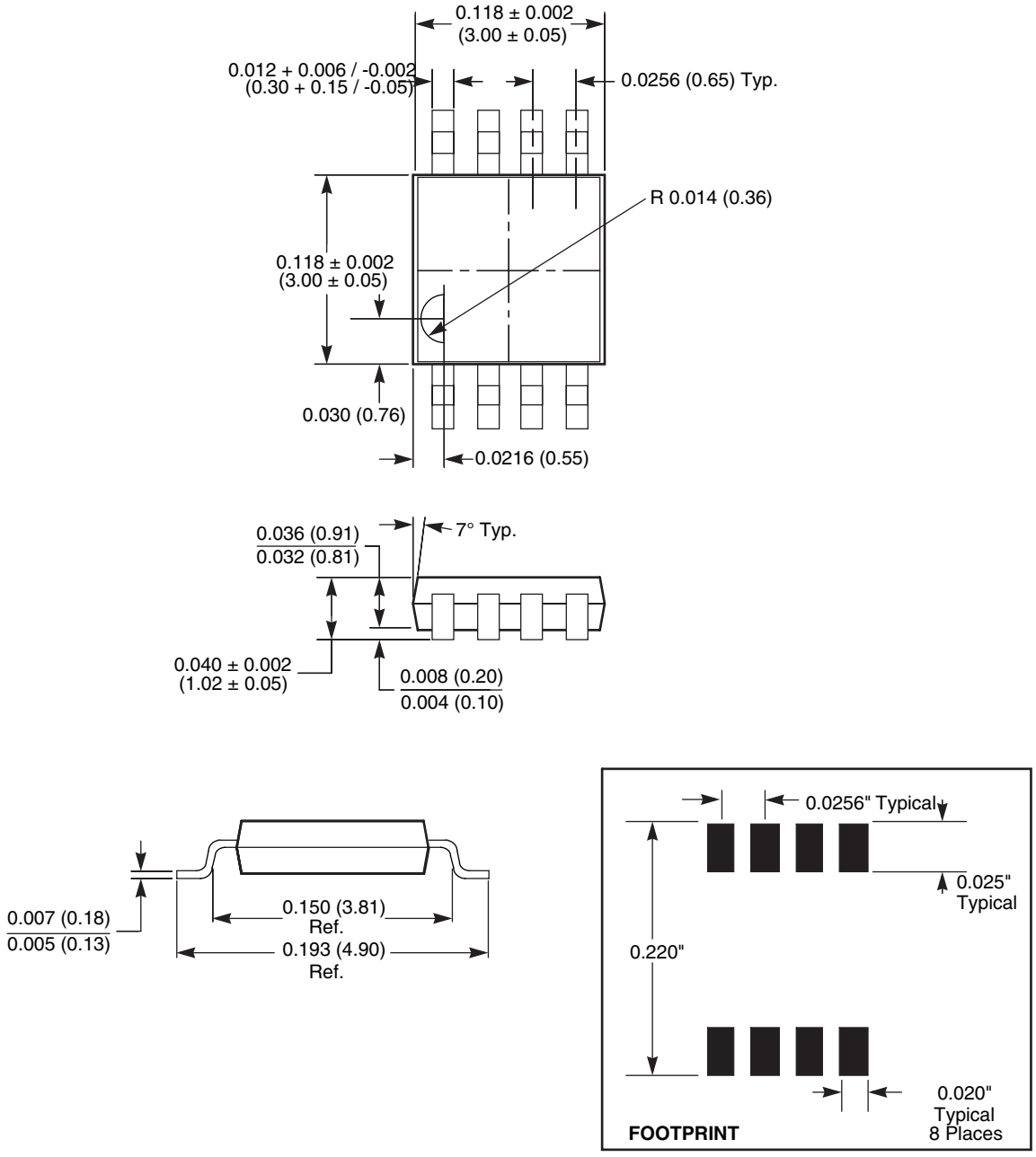
A.C. Timing



Notes: (6) Typical values are for T_A = 25°C and nominal supply voltage.
(7) This parameter is periodically sampled and not 100% tested.
(8) MI in the A.C. timing diagram refers to the minimum incremental change in the V_W output due to a change in the wiper position.

PACKAGING INFORMATION

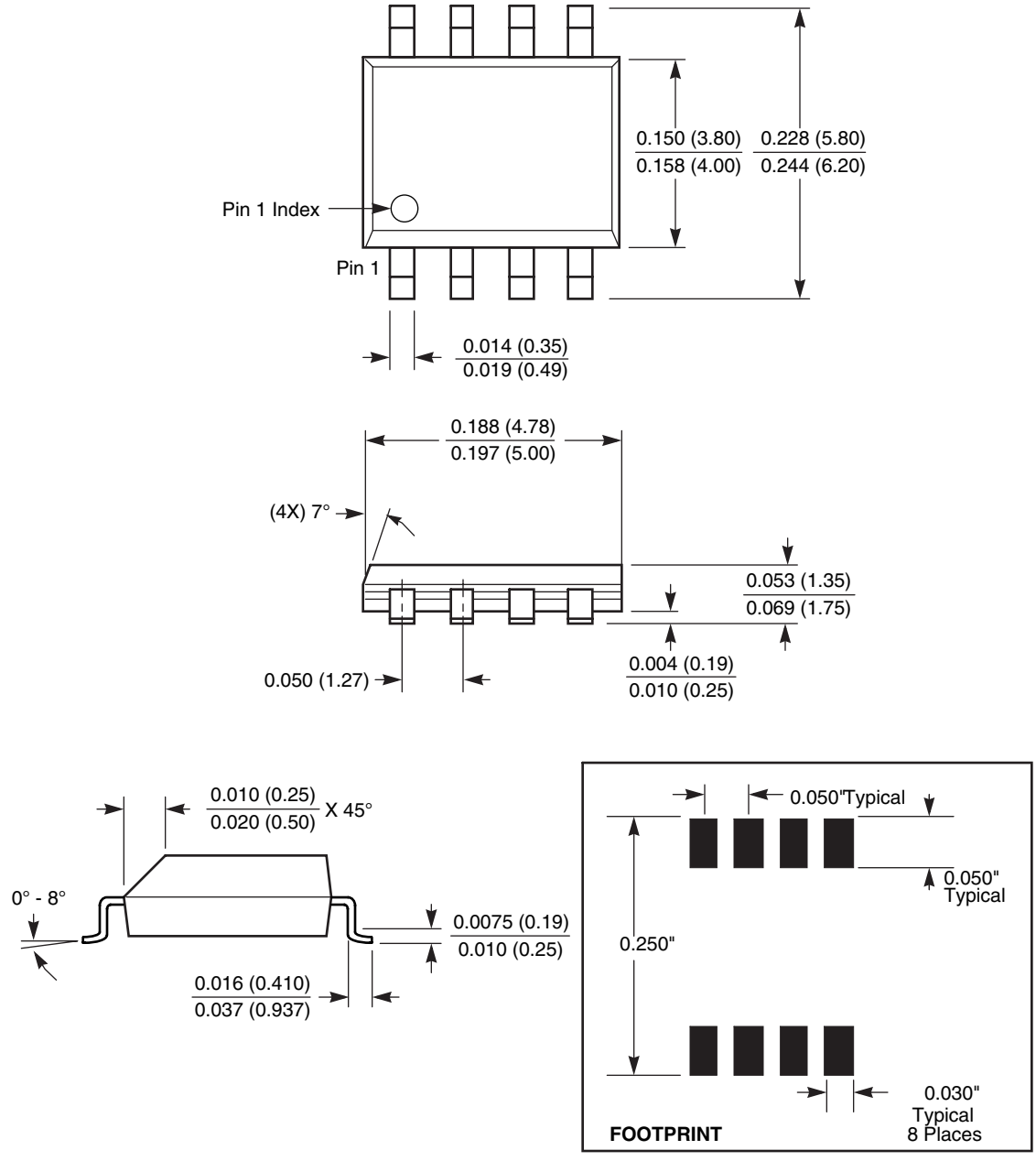
8-Lead Miniature Small Outline Gull Wing Package Type M



NOTE:
1. ALL DIMENSIONS IN INCHES AND (MILLIMETERS)

PACKAGING INFORMATION

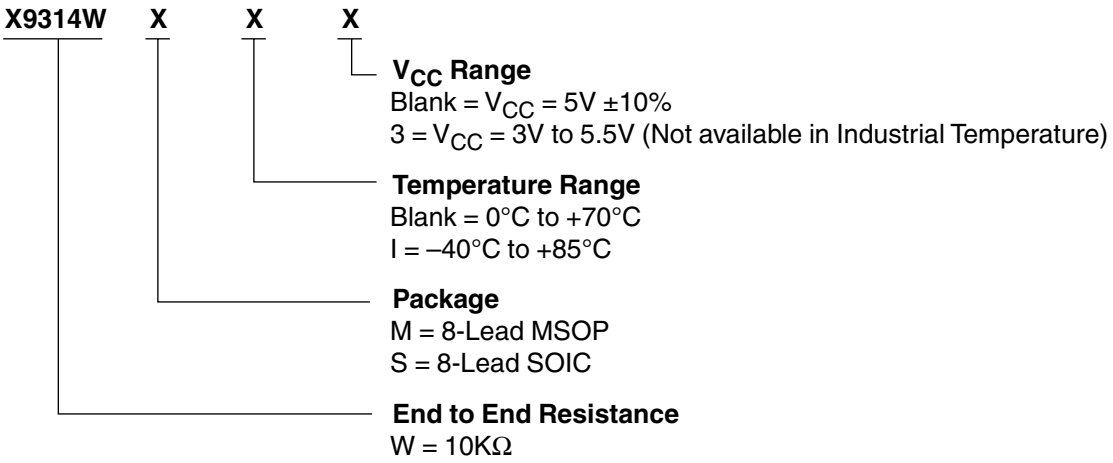
8-Lead Plastic Small Outline Gull Wing Package Type S



NOTE: ALL DIMENSIONS IN INCHES (IN PARENTHESES IN MILLIMETERS)

Ordering Information

X9314 XDCP 10KΩ, Log Taper



Part Mark Convention

X9314W **X**

Blank = 8-Lead SOIC

(Date Code) **X**

Blank = 5V ±10%, 0°C to 70°C
I = 5V ±10%, -40°C to +85°C
D = 3V to 5.5V, 0°C to 70°C
E = 3V to 5.5V, -40°C to +85°C