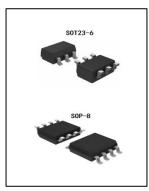


## **Bi-Direction Relay Driver**

#### **SSP8023D**

#### **General Description**

SSP8023D is a bi-direction relay driver circuit, used to control the DC motor and the magnetic latching relay, with large output capability, ultra-low power consumption. It can be widely used in smart meters and other pulses, level control applications.



#### **Features**

- Max input voltage: 40V. Limit operating voltage: 30V. Recommended safe working voltage:  $5\sim24\text{V}$  (The recommended safe operating voltage range is for commercially available  $9\sim12$  relays (Internal resistance is about  $50\Omega$ ), Other specifications of relays should be determined according to the measured conditions.)
- Limit operating current: 800mA
- The input high low conversion level is about 1.5V, which is compatible with various microcontrollers
- Integrated high speed continuation diode with built-in reverse voltage function to cancel TVS tubes in general applications
- Typical operating power: 5W (It is equivalent to 400mA output current at 12V working voltage. When the working voltage increases, the corresponding output current should decrease.)
- Limit power: 10W (It is equivalent to 800mA output current at 12V working voltage. When the working voltage increases, the corresponding output current should decrease. Working beyond the limit can cause chip damage.)

## **Applications**

- Smart Meter
- Motor drive
- Magnetic latching relay control

## Order specification

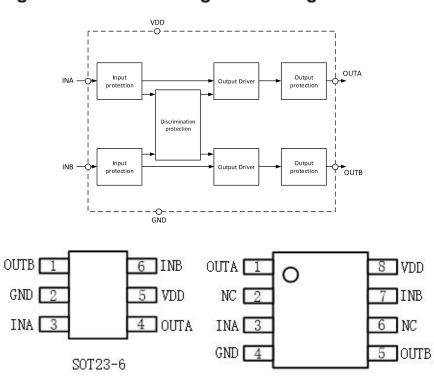
Part No	Package	Manner of Packing	Devices per bag/reel
SSP8023D	SOP23-6	Reel	3000
SSP8023D	SOP8	Reel	4000



### **Print rules**

Package	Marking		
SOT23-6	8023S		
SOP8	8023S		

# **Block Diagram and Pin Arrangement Diagram**



# Pin Assignment

Pin No.		Pin Name	Description		
SOT23-6	SOP8	Pili Naille	Description		
5	8	VDD	Supply input voltage		
2	4	GND	Ground.		
3	3	INA	Input A		
4	1	OUTA	Output A		
6	7	INB	Input B		
1	5	OUTB	Output B		

SOP8



### **Functional Description**

SSP8023D is a bi-direction relay driver circuit, used to control the DC motor and the magnetic latching relay. INA and INB are triggered by pulse, so long as the input terminal is directly connected with the output terminal of the corresponding device, it can work; The trigger pulse is triggered according to the function list state and the relay acts accordingly.

#### LOGIC FUNCTION TABLE

Inj	out	Output		
INA	INB	OUTA	OUTB	
0	0	High-impedance	High-impedance	
0	1	0	1	
1	0	1	0	
1	1	High-impedance	High-impedance	

### **Absolute Maximum Ratings**

T<sub>amb</sub>=25°C,unless specified otherwise.

Parameter	Symbol	Value	Unit
Max Input Voltage	V <sub>DD</sub> -V <sub>GND</sub>	+40	V
OUTA/OUTB Voltage	V <sub>OUTA</sub> /V <sub>OUTB</sub>	+40	V
Other Input / Output Voltage	$V_{\rm IN}/V_{\rm OUT}$	VGND-0.4~VDD+0.4	V
Max Junction Temperature	Tj	150	°C
Operating Temperature	To	-40~85	°C
Storage Temperature	$T_{\rm stg}$	-65~150	°C
Thermal Resistance (Junction to Ambient)	R <sub>ja</sub>	120	°C/W
ESD (Human-Body Model)	НВМ	8000	V
ESD (Machine Model)	MM	200	V

Note: These are stress ratings only. Stresses exceeding the range specified under "Absolute Maximum Ratings" may cause substantial damage to the device. Functional operation of this device at other conditions beyond those listed in the specification is not implied and prolonged exposure to extreme conditions may affect device reliability.

## Recommended operating conditions

Parameter	Symbol	Value	Unit
Input voltage range	$V_{\rm IN}$	+36(MAX.)	V
Operating temperature range	Tj	-40~85	°C

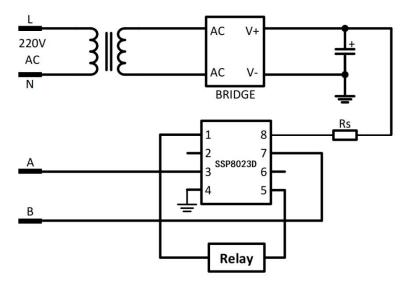


# Electrical Characteristics(1)(2)

T<sub>amb</sub>=25°C,unless specified otherwise.

Parameter	Symbol	Test Conditions	Min.	Тур.	Max.	Unit	
Static Shutdown Characteristics							
Output Breakdown Current	BV <sub>DSS</sub>	V <sub>INA</sub> =V <sub>INB</sub> =0V, I <sub>D</sub> =250uA	40			V	
Output Leakage Current	I <sub>DSS</sub>	$V_{INA}=V_{INB}=0V, V_D=24V$			10	μΑ	
Static Opening Characterist	ics						
Input Threshold Voltage	VTH			1.5	2	V	
		$V_{DD}=12V$ , $R_L=80\Omega$		7	10	Ω	
Output On registeres	D	$V_{DD}=30V$ , $R_L=80\Omega$		6	10	Ω	
Output On-resistance	R <sub>DS(ON)</sub>	$V_{DD}=12V$ , $R_L=40\Omega$		7	10	Ω	
		$V_{DD}=30V$ , $R_L=40\Omega$		6	10	Ω	
Input Characteristics							
Equivalent Input Resistor	R <sub>IN</sub>	$V_{DD}=12V$ , $V_{INA}=V_{INB}=0V$		120		kΩ	
I (C)	$I_{\rm IN}$	V <sub>INA</sub> =3V or V <sub>INB</sub> =3V		250	400	μΑ	
Input Current		V <sub>INA</sub> =5V or V <sub>INB</sub> =5V		450	600	μΑ	
FWD Characteristics							
Forward Conduction Voltage	$V_{SD}$	$I_S=1A$		1.5	2	V	
Reverse Recovery Time	$T_{RR}$	$V_{DD}=12V, R_L=80\Omega$		190		ns	
Transmission Characteristics							
Rise Time	$T_R$	$V_{DD}=12V, R_L=80\Omega$		50		ns	
Turn ON Delay Time	T <sub>D(ON)</sub>	$V_{DD}=12V, R_L=80\Omega$		60		ns	
Fall Time	$T_{\mathrm{F}}$	$V_{DD}=12V, R_L=80\Omega$		50		ns	
Turn OFF Delay Time	T <sub>D(OFF)</sub>	$V_{DD}=12V, R_L=80\Omega$		2		ns	

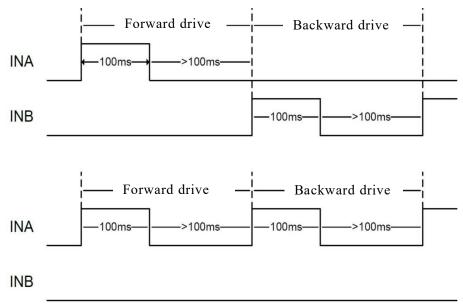
# **Application Circuits**



**Typical Application Diagram** 

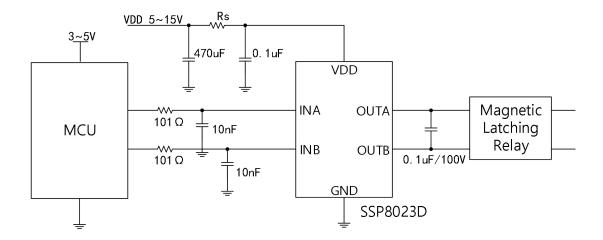


The input terminals A and B are triggered by pulse. The input terminal of the chip is connected with the output terminal of the corresponding device to work. The trigger pulse is triggered according to the function list state and the relay acts accordingly. In smart meter applications, the recommended pulse width=100ms. The length of the intervals should be longer than 100ms. These intervals include: intervals between forward drive pulse and next backward drive pulse, intervals between forward drive pulse, intervals between backward drive pulse and next forward drive pulse, intervals between backward drive pulse and next forward drive pulse, intervals between backward drive pulse and next backward drive pulse.



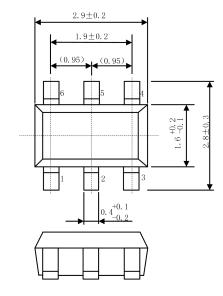
Schematic diagram of pulse excitation

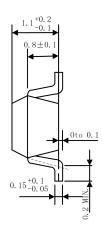
#### Recommended circuit



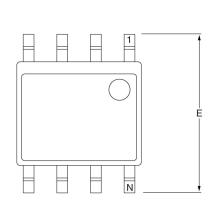


# Package Information (SOT23-6)

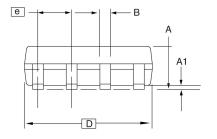




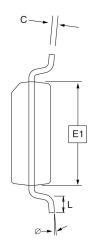
# Package Information (SOP8)



Top View



Side View



**End View** 

#### COMMON DIMENSIONS (Unit of Measure = mm)

SYMBOL	MIN	NOM	MAX	NOTE
Α	1.35	-	1.75	
A1	0.10	-	0.25	
b	0.31	-	0.51	
С	0.17	-	0.25	
D	4.80	-	5.00	
E1	3.81	-	3.99	
E	5.79	-	6.20	
е	1.27 BSC			
L	0.40	_	1.27	
Ø	0°	-	8°	



### **Special Instructions**

The company reserves the right of final interpretation of this specification.

## **Version Change Description**

Version: V1.4	Author:	Yang	Time:	2021.8.18
Modify the record:				
1. Re-typesetting the manual an	d checkin	g some data		
Version: V1.5	Author:	Yang	Time:	2021.11.26
Modify the record:				
1. Add print rules				
Version: V1.6	Author:	Yang	Time:	2021.12.22
Modify the record:				
1. Add the recommended circuit				
Version: V1.7	Author:	Yang	Time:	2022.5.23
Modify the record:				
1. Update order specification				
Version: V1.8	Author:	Yang	Time:	2022.8.16
Modify the record:				
1. Add recommended operating	condition	S		

## **Statement**

The information in the usage specification is correct at the time of publication, Shanghai Siproin Microelectronics Co. has the right to change and interpret the specification, and reserves the right to modify the product without prior notice. Users can obtain the latest version information from our official website or other effective channels before confirmation, and verify whether the relevant information is complete and up to date.

With any semiconductor product, there is a certain possibility of failure or failure under certain conditions. The buyer is responsible for complying with safety standards and taking safety measures when using the product for system design and complete machine manufacturing. The product is not authorized to be used as a critical component in life-saving or life-sustaining products or systems, in order to avoid potential failure risks that may cause personal injury or property loss.