# SIEMENS

Data sheet for SINAMICS G120X

### Article No. :

### 6SL3230-1YE44-0UP0



Figure similar

Client order no. :
Order no. :
Offer no. :
Remarks :

Rated data			
Input			
Number of phases	3 AC		
Line voltage	380 480 V +10 g	% -20 %	
Line frequency	47 63 Hz		
Rated voltage	400V IEC	480V NEC	
Rated current (LO)	172.00 A	151.00 A	
Rated current (HO)	154.00 A	132.00 A	
Output			
Number of phases	3 AC		
Rated voltage	400V IEC	480V NEC <sup>1)</sup>	
Rated power (LO)	90.00 kW	125.00 hp	
Rated power (HO)	75.00 kW	100.00 hp	
Rated current (LO)	178.00 A	156.00 A	
Rated current (HO)	145.00 A	124.00 A	
Rated current (IN)	183.00 A		
Max. output current	241.00 A		
Pulse frequency	4 kHz		
Output frequency for vector control	0 200 Hz		
Output frequency for V/f control	0 550 Hz		

#### **Overload capability**

Low Overload (LO)

110% base load current IL for 60 s in a 300 s cycle time

High Overload (HO)

150% x base load current IH for 60 s within a 600 s cycle time

General tech. specifications			
Power factor $\lambda$	0.90 0.95		
Offset factor $\cos \phi$	0.99		
Efficiency η	0.97		
Sound pressure level (1m)	72 dB		
Power loss 3)	2.610 kW		
Filter class (integrated)	Unfiltered		
EMC category (with accessories)	without		
Safety function "Safe Torque Off"	without SIRIUS device (e.g. via S7- 1500F)		
Communication			
Communication	PROFIBUS DP		

ltem no. : Consignment no. : Project :

Inputs / outputs			
Standard digital inputs			
Number	6		
Switching level: $0 \rightarrow 1$	11 V		
Switching level: $1 \rightarrow 0$	5 V		
Max. inrush current	15 mA		
Fail-safe digital inputs			
Number	1		
Digital outputs			
Number as relay changeover contact	2		
Output (resistive load)	DC 30 V, 5.0 A		
Number as transistor	0		
Analog / digital inputs			
Number	2 (Differential input)		
Resolution	10 bit		
Switching threshold as digital input			
$0 \rightarrow 1$	4 V		
$1 \rightarrow 0$	1.6 V		
Analog outputs			
Number	1 (Non-isolated output)		
PTC/ KTY interface			
1 motor temperature sensor input, sen Thermo-Click, accuracy ±5 °C	nsors that can be connected PTC, KTY and		

Closed-loop control techniques		
V/f linear / square-law / parameterizable	Yes	
V/f with flux current control (FCC)	Yes	
V/f ECO linear / square-law	Yes	
Sensorless vector control	Yes	
Vector control, with sensor	No	
Encoderless torque control	No	
Torque control, with encoder	No	

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Ambient conditions			
Standard board coating type	Class 3C3, according to IEC 60721-3-3: 2002		
Cooling	Air cooling using an integrated fan		
Cooling air requirement	0.153 m³/s (5.403 ft³/s)		
Installation altitude	1,000 m (3,280.84 ft)		
Ambient temperature			
Operation	-20 45 °C (-4 113 °F)		
Transport	-40 70 °C (-40 158 °F)		
Storage	-25 55 °C (-13 131 °F)		
Relative humidity			
Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible		
Conn	ections		
Signal cable			
Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)		
Line side			
Version	M10 screw		
Conductor cross-section	35.00 2 x 120.00 mm² (AWG 1 AWG 2 x 4/0)		
Motor end			
Version	M10 screw		
Conductor cross-section	35.00 2 x 120.00 mm² (AWG 1 AWG 2 x 4/0)		
DC link (for braking resistor)			
PE connection	M10 screw		
Max. motor cable length			
Shielded	300 m (984.25 ft)		
Unshielded	450 m (1,476.38 ft)		

echanical data	
IP20 / UL open type	
FSF	
61 kg (134.48 lb)	
305 mm (12.01 in)	
709 mm (27.91 in)	
369 mm (14.53 in)	
Standards	
UL, cUL, CE, C-Tick (RCM), EAC, KCC, SEMI F47, REACH	
EMC Directive 2004/108/EC, Low- Voltage Directive 2006/95/EC	
losses to IEC61800-9-2*	
IE2	
50.6 %	
2,060.0 W (1.7 %) 2,570.0 W (2.1	%)
1,070.0 W (0.9 %) 1,240.0 W (1.0	%)
748.0 W (0.6 %)	
	IP20 / UL open type   FSF   61 kg (134.48 lb)   305 mm (12.01 in)   709 mm (27.91 in)   369 mm (14.53 in)   Standards   UL, cUL, CE, C-Tick (RCM), EAC, Kd SEMI F47, REACH   ID55es to IEC61800-9-2*   IE2   50.6 %   2,060.0 W (1.7 %)   1,070.0 W (0.9 %)   1,240.0 W (1.0

The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

\*converted values

<sup>1)</sup>The output current and HP ratings are valid for the voltage range 440V-480V

<sup>3)</sup>Typical value. More information can be found in the element group "Converter losses to IEC 61800-9-2" in this datasheet.