

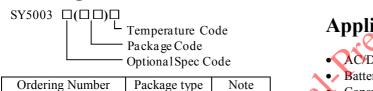
# Application Note:AN\_SY5003C Flyback controller For adapters or chargers

## **General Description**

SY5003C is a PWM/PFM controller with several features to enhance performance of Flyback converters that targeting at adapter or charger applications. It drives Flyback controller in the Quasi-Resonant mode for higher efficiency and better EMI performance. SY5003C adopt burst mode control for improved efficiency and the output current is detected by internal primary detection technology to achieve more reliable Over Current Protection and Short Circuit Protection. The output voltage is achieved by secondary side control technology for good load and line regulation.

## **Ordering Information**

SY5003CABC



SOT23-6

### Features

- Quasi-Resonant (QR) mode operation: Valley turnon of the primary MOSFET to achieve low switching losses
- Output current is monitored by primary detection for reliable Over Current Protection and Short Circuit Protection
- PWM/PFM control for higher average efficiency
- Burst mode control for low no load loss and efficiency
- Low start up current: 4µA typical
- Internal high current MOSFET driver: 120mA
- Auto-Recovery for OVP/OCP/SCP/OTP
- Maximum frequency limitation 125kHz
- Compact package: SOT23-6

# Applications

- AC/DC Adapters
- Battery Chargers
- Consumer Electronics
- Auxiliary power supplies

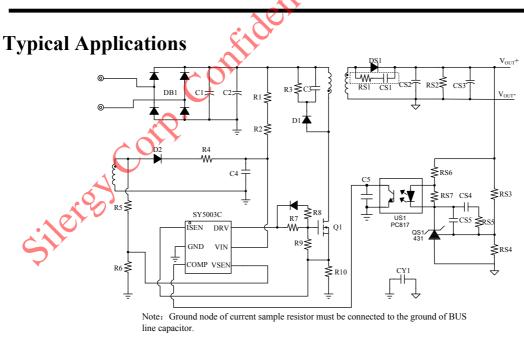


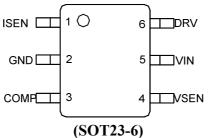
Fig.1 Schematic Diagram

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### Pinout (top view)



Top Mark: Bdxyz (device code: Bd, x=year code, y=week code, z= lot number code)

Pin	Name	Description
1	ISEN	Current sense pin. Connect this pin to the source of the primary switch.
2	GND	Ground pin.
3	COMP	Feedback input pin. The PWM ducy cycle is determined by voltage level into this pin. It's connected to a optocoupler.
4	VSEN	Inductor current zero-crossing detection pin. This pin receives the auxiliary winding voltage by a resistor divider and detects the inductor current zero crossing point.
5	VIN	Power supply pin.
6	DRV	Gate driver pin. Connect this pin to the gate of primary MOSPEC
	Siler	Power supply pin. Gate driver pin. Connect this pin to the gate of primary MOSPET



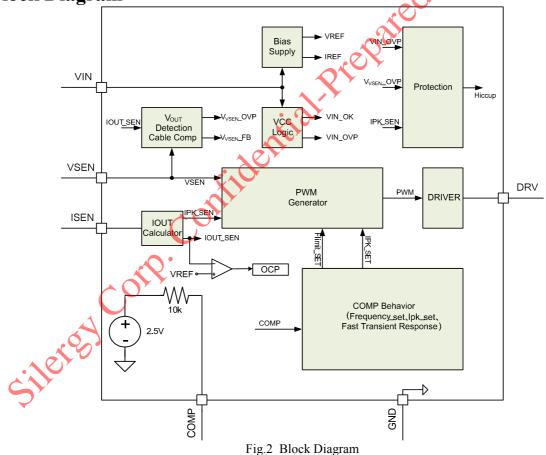
### Absolute Maximum Ratings (Note 1)

VIN	
Supply Current I <sub>VIN</sub>	20mA
VSEN	
DRV	
ISEN, COMP	
Power Dissipation, @ TA = 25°C SOT23-6	1.1W
Package Thermal Resistance (Note 2)	
SOT23-6,θ <sub>JA</sub>	125°C/W
SOT23-6, θ <sub>JC</sub>	60°C/W
Junction Temperature Range	45°C to 150°C
Lead Temperature (Soldering, 10 sec.) Storage Temperature Range	65°C to 150°C

### **Recommended Operating Conditions** (Note 3)

VIN		9V~17 5V
The strength of the sector of	X	y 11.51
Junction Temperature Range		40°C to 125°C
Ambient Temperature Range		40°C to 105°C

# **Block Diagram**





## **Electrical Characteristics**

 $(V_{IN} = 12V, T_A = 25^{\circ}C \text{ unless otherwise specified})$ 

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
Power Supply Section	Symbol	Test conditions	IVIIII	199	mux	Oint
VCC turn-on threshold	V <sub>VCC,ON</sub>		13.7	14.7	15.7	V
VCC turn-off threshold	V <sub>VCC,OFF</sub>		6.3	7	8.3	V
VCC OVP voltage	V <sub>VCC,OVP</sub>		17.5	18.5	19.5	V
Start up Current	I <sub>ST</sub>	V <sub>VCC</sub> <v<sub>VCC,OFF</v<sub>		1.2	4	μA
Operating Current	Ivcc	C <sub>L</sub> =100pF,f=100kHz		1		mA
Quiescent Current	IQ	• · ·		400		μA
Shunt current in OVP mode	Ivcc,ovp	V <sub>VCC</sub> >V <sub>VCC,OVP</sub>		7.5		mA
Current feedback modulato		~				
Internal reference voltage	V <sub>REFI</sub>		0.4137	0.42	0.4263	V
ISEN pin Section					>	
Current limit Valtage	V	$V_{FBV} < 0.4V$	0.6	0.7	0.8	V
Current limit Voltage	V <sub>ISEN,LIM</sub>	$V_{FBV} > 0.4V$	0.95	1	1.05	V
Latch Voltage for ISEN	V <sub>ISEN,EX</sub>		C	2		V
CC feedforward resistor	R <sub>k2</sub>		225	300	375	Ω
VSEN pin Section			~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~			
OVP voltage threshold	V <sub>VSEN,OVP</sub>		13775	1.45	1.5225	V
COMP section						
Internal voltage bias	V <sub>CVB</sub>	<b>C</b>	6	2.5		V
Sleep mode voltage ON threshold	VCOMP-ON	NO NO		0.4		V
Sleep mode voltage OFF threshold	V <sub>COMP-OFF</sub>			0.45		V
Internal pull-up resistor	R <sub>COMPV</sub>	• • • •		10		kΩ
Gate Driver Section						
Gate driver voltage	V <sub>Gate</sub>			12		V
Maximum. source current	I <sub>SOURCE,max.</sub>			120		mA
Maximum. sink current	I <sub>SINK,max.</sub>			500		mA
Max ON Time	ton,max	Vcomp=2.5V		24		μs
Min ON Time	t <sub>ON,MIN</sub>				300	ns
Max OFF Time	toff,max		400	500	700	μs
Min OFF Time	Toff,min			1.2		μs
Maximum frequency	f <sub>MAX</sub>		110	125	145	kHz
Thermal Section	<u>×                                    </u>					
Thermal Shutdown Temperature	T <sub>SD</sub>			150		°C

**Note 1**: Stresses beyond the "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, Functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Note 2:  $\theta_{JA}$  is measured in the natural convection at  $T_A = 25^{\circ}C$  on a low effective single layer thermal conductivity test board of JEDEC 51-3 thermal measurement standard. Test condition: Device mounted on" 2x 2" FR-4 substrate PCB, 2oz copper, with minimum recommended pad on top layer and thermal vias to bottom layer ground plane.

Note 3: Increase VIN pin voltage gradually higher than  $V_{VIN,ON}$  voltage then turn down to 12V.



## Operation

SY5003C is a PWM/PFM controller with several features to enhance performance of Flyback converters.

To achieve higher efficiency and better EMI performance, SY5003C drives Flyback converters in the Quasi-Resonant mode; the start up current of the device is rather small(4 $\mu$ A typically) to reduce the standby power loss further and the maximum switching frequency is limited below 125kHz.

In order to improve the stability, the self-adaption compensation is applied.

The output current is monitored by primary side detection technology, and the maximum output current can be programmed in Over Current Protection and Short Circuit Protection. In addition to SY5003C provides Over Voltage Protection(OVP), Over Temperature Protection (OTP), Output voltage OVP protection , VSEN pin short protection ,etc..

SY5003C can be applied in AC/DC adapters, Battery Chargers and other consumer electronics.

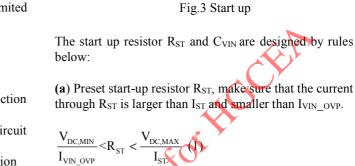
SY5003C is available with SOT23-6 package.

## **Applications Information**

#### <u>Start up</u>

After AC supply or DC BUS is powered on the capacitor  $C_{\rm VIN}$  across VIN and GND pin is charged up by BUS voltage through a start up resistor  $R_{\rm ST}$ . Once  $V_{\rm VIN}$  rises up to  $V_{\rm VIN-ON}$ , the internal blocks start to work.  $V_{\rm VIN}$  will be pulled down by internal consumption of IC until the auxiliary winding of Flyback transformer could supply enough energy to maintain  $V_{\rm VIN}$  above  $V_{\rm VIN-OFF}$ .

The whole start up procedure is divided into two sections shown in Fig.3. t<sub>STC</sub> is the C<sub>VIN</sub> charged up section, and t<sub>STO</sub> is the output voltage built-up section. The start up time t<sub>ST</sub> composes of t<sub>STC</sub> and t<sub>STO</sub>, and usually t<sub>STO</sub> is much smaller than t<sub>STC</sub>.



Va

Rsi

Where  $V_{DC}$  is the BUS line voltage.

(b) Select  $C_{VIN}$  to obtain an ideal start up time  $t_{ST_i}$  and ensure the output voltage is built up at one time.

Vvir

Man.

Vou

SY5003C



(c) If the  $C_{VIN}$  is not big enough to build up the output voltage at one time. Increase  $C_{VIN}$  and decrease  $R_{ST}$ , go back to step (a) and redo such design flow until the ideal start up procedure is obtained.

#### Shut down

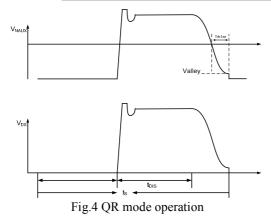
After AC supply or DC BUS is powered off, the energy stored in the BUS capacitor will be discharged. When the auxiliary winding of Flyback transformer cannot supply enough energy to VIN pin,  $V_{VIN}$  will drop down. Once  $V_{VIN}$  is below  $V_{VIN-OFF}$ , the IC will stop working.

#### Quasi-Resonant Operation(valley detection)

QR mode operation provides low turn-on switching losses for Flyback converter.

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The voltage across drain and source of the primary MOSFET is reflected by the auxiliary winding of the Flyback transformer. ZCS pin detects the voltage across the auxiliary winding by a resistor divider. When the voltage on VSEN pin across zero, the MOSFET would be turned on after 400ns delay.

#### **Output Voltage Control(CV control)**

SY5003C is compatible with opto-coupler to achieve output voltage control, which is shown by Fig.5.

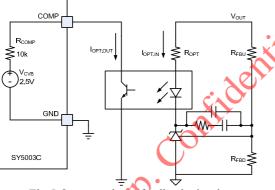


Fig.5 Output voltage feedback circuit

The OFF time of MOSFET is up to the valley detection of VSEN pin, and the ON time of MOSFET is a function of  $V_{COMP}$ , so the output power can be controlled by  $V_{COMP}$ .

SY5003C integrates an internal 2.5V voltage bias and 10k $\Omega$  resistor to interface the output of opto-coupler. V<sub>COMP</sub> is in relation with the output current of the opto-coupler I<sub>OPT,OUT</sub> by

$$V_{\text{COMP}} = V_{\text{CVB}} - I_{\text{OPT,OUT}} \times R_{\text{COMP}}$$
(3)

 $R_{OPT}$  is the resistor across the output node and the anode of the opto-coupler. The selection of  $R_{OPT}$  is related with system loop stability, and higher loop gain of the system is achieved by smaller  $R_{OPT}$ .

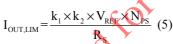
At the same time, R<sub>OPT</sub> is designed by

 $V_{\text{CVB}} - I_{\text{OPT,IN,MAX}} \times \beta \times R_{\text{COMP}} < V_{\text{COMP,ON}}$  (4)

Where  $\beta$  is the transfer ratio of the opto-coupler;  $I_{OPT,IN,MAX}$  is the maximum input current through the opto-coupler, which is limited by  $R_{OPT}$ .

#### Output current detection by Primary side(CC control)

The output current is monitored by SY5003C with primary side detection technology. The maximum output current I<sub>OUT,LIM</sub> can be regulated by:

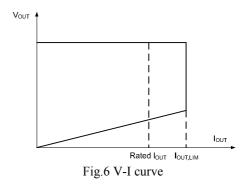


Where  $k_1$  is the output current weight coefficient;  $k_2$  is the output modification coefficient;  $V_{REF}$  is the internal reference voltage;  $N_{PS}$  is the turns ratio of the Flyback transformer,  $R_S$  is the current sense resistor.

 $k_1$ ,  $k_2$  and  $V_{REF}$  are all internal constant parameters, lour, LIM can be programmed by  $N_{PS}$  and  $R_S$ .

$$R_{\rm s} = \frac{k_1 \times k_2 \times V_{\rm REF} \times N_{\rm PS}}{I_{\rm OUT}}$$
(6)

When over current operation or short circuit operation happens.  $V_{COMP}$  will be pulled down, and the output current will be limited at  $I_{OUT,LIM}$ . The V-I curve is shown as Fig.6.



#### Line regulation modification

The IC provides line regulation modification function to improve line regulation performance of the output current.



Due to the sample delay of ISEN pin and other internal delay, the output current increases with increasing input BUS line voltage. A small compensation voltage  $\Delta V_{ISEN-C}$  is added to ISEN pin during ON time to improve such performance. This  $\Delta V_{ISEN-C}$  is adjusted by the upper resistor of the divider connected to VSEN pin.

$$\Delta V_{\text{ISEN,C}} = V_{\text{BUS}} \times \frac{N_{\text{AUX}}}{N_{\text{P}}} \times \frac{1}{R_{\text{VSENU}}} \times k_{3} (7)$$

Where  $R_{VSENU}$  is the upper resistor of the divider; k3 is an internal constant as the modification coefficient.

The compensation is mainly related with  $R_{VSENU}$ , larger compensation is achieved with smaller  $R_{VSENU}$ . Normally,  $R_{VSENU}$  ranges from  $50k\Omega{\sim}150k\Omega$ .

#### **Short Circuit Protection (SCP)**

There are two kinds of situations, one is the valley signal cannot be detected by VSEN, the other is the valley signal can be detected by VSEN.

When the output is shorted to ground, the output voltage is clamped to zero. The voltage of the auxiliary winding is proportional to the output winding, so valley signal cannot be detected by VSEN. There are two cases , the one is without valley detection, MOSFET cannot be turned on until maximum off time is reached. If MOSFET is turned on with maximum off-time for 64 times continuously which can not detected valley, IC will be shut down and enter into hiccup mode. The other is that IC will be shut down and enter into hiccup mode when  $V_{VIN}$  below  $V_{VIN-OFF}$  within 64 times.

When the output voltage is not low enough to disable valley detection in short condition, SY5003C will operate in CC mode until VIN is below VIN-OFF.

In order to guarantee SCP function not effected by voltage spike of auxiliary winding, a filter resistor  $R_{AUX}$  is needed.

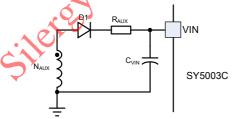


Fig. 7 Filter resistor RAUX

#### **Output voltage OVP protection**

The secondary maximum voltage is limited by the SY5003C.When the VSEN pin signal exceeds 1.45V, SY5003C will stop switching and discharge the VIN voltage. Once  $V_{VIN}$  is below  $V_{VIN-OFF}$ , the IC will shut down and be charged again by HV start up.

#### **VSEN pin short protection**

The SY5003C has a protection against faults caused by a shorted VSEN pin or a shorted pull-down resistor. During start-up, the voltage on the VSEN pin is monitored. In normal situations, the voltage on the VSEN pin reaches the sense protection trigger level. When the VSEN voltage does not reach this level, the VSEN pin is shorted and the protection is activated. The IC stops switching and discharge the VIN voltage. Once  $V_{VIN}$  is below  $V_{VIN-OFF}$ , the IC will shut down and be charged again by HV start up. In order to ensure reliable detection, the pull-down resistor should larger than  $2k\Omega$ .



When the operation condition is with maximum input voltage and full load, the voltage stress of MOSFET and secondary power diode is maximized.

$$V_{\text{MOS}\_DS\_MAX} = \sqrt{2} V_{\text{AC}\_MAX} + N_{\text{PS}} \times (V_{\text{OUT}} + V_{\text{D},\text{F}}) + \Delta V_{\text{S}} (8)$$
$$V_{\text{D}\_R\_MAX} = \frac{\sqrt{2} V_{\text{AC}\_MAX}}{N_{\text{PS}}} + V_{\text{OUT}} (9)$$

Where  $V_{AC,MAX}$  is maximum input AC RMS voltage;  $N_{PS}$  is the turns ratio of the Flyback transformer;  $V_{OUT}$  is the rated output voltage;  $V_{D,F}$  is the forward voltage of secondary power diode;  $\Delta V_S$  is the overshoot voltage clamped by RCD snubber during OFF time.

When the operation condition is with minimum input voltage and full load, the current stress of MOSFET and power diode is maximized.

$$I_{MOS_{PK_MAX}} = I_{P_{PK_MAX}} (10)$$

$$I_{MOS_{RMS_MAX}} = I_{P_{RMS_MAX}} (11)$$

$$I_{D_{PK_MAX}} = N_{PS} \times I_{P_{PK_MAX}} (12)$$

$$I_{D_{AVG}} = I_{OUT} (13)$$

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Where  $I_{P-PK-MAX}$  and  $I_{P-RMS-MAX}$  are maximum primary peak current and RMS current, which will be introduced later.

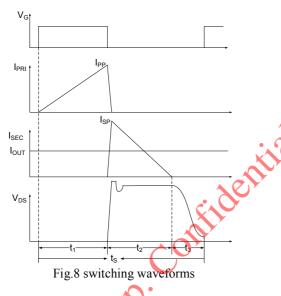
#### Transformer (N<sub>PS</sub> and L<sub>M</sub>)

 $N_{\text{PS}}$  is limited by the electrical stress of the power MOSFET:

$$N_{PS} \leq \frac{V_{MOS\_(BR)DS} \times 90\% - \sqrt{2}V_{AC\_MAX} - \Delta V_{S}}{V_{OUT} + V_{D F}}$$
(14)

Where  $V_{MOS,(BR)DS}$  is the breakdown voltage of the power MOSFET;  $V_{AC,MAX}$  is maximum input AC RMS voltage.

In Quasi-Resonant mode, each switching period cycle  $t_s$  consists of three parts: current rising time  $t_1$ , current falling time  $t_2$  and quasi-resonant time  $t_3$  shown in Fig.8.



When the operation condition is with minimum input AC RMS voltage and full load the switching frequency is minimum frequency, the maximum peak current through MOSFET and the transformer happens.

Once the minimum frequency  $f_{S,MIN}$  is set, the inductance of the transformer could be induced. The design flow is shown as below:

(a)Select N<sub>PS</sub>;  $N_{PS} \leq \frac{V_{MOS_{(BR)DS}} \times 90\% \cdot \sqrt{2} V_{AC_{MAX}} \cdot \Delta V_{S}}{V_{OUT} + V_{D_{F}}}$ (15)

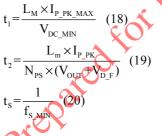
(b) Preset minimum frequency  $f_{S-MIN}$ ;

(c) Compute inductor  $L_M$  and maximum primary peak current  $I_{PK-MAX}$ ;

$$I_{P_{PK_{MAX}}} = \frac{2P_{OUT}}{\eta \times V_{DC_{MIN}}} + \frac{2P_{OUT}}{\eta \times N_{PS} \times (V_{OUT} + V_{D_{P}F})} (16)$$
$$+ \pi \sqrt{\frac{2P_{OUT}}{\eta} \times C_{Drain} \times f_{S_{MIN}}}$$
$$L_{M} = \frac{2P_{OUT}}{\eta \times I_{P_{P}PK_{MAX}}^{2} \times f_{S_{MIN}}} (17)$$

Where  $C_{Drain}$  is the parasitic capacitance at drain of MOSFET;  $\eta$  is the efficiency;  $P_{OUT}$  is rated full load power;  $V_{DC\_MIN}$  is minimum input DC RMS voltage.

(d) Compute current rising time  $t_1$  and current falling time  $t_2$ ;



(e) Compute primary maximum RMS current I<sub>P-RMS-MAX</sub> for the transformer fabrication ;

$$I_{P_{-RMS_{-MAX}}} = \frac{\sqrt{3}}{3} I_{P_{-}PK_{-MAX}} \sqrt{\frac{t_1}{t_s}}$$
(21)

(f) Compute secondary maximum peak current  $I_{S\text{-}PK\text{-}MAX}$  and RMS current  $I_{S\text{-}RMS\text{-}MAX}$  for the transformer fabrication .

$$I_{S_{PK_{MAX}}} = N_{PS} \times I_{P_{PK_{MAX}}} (22)$$
$$I_{S_{RMS_{MAX}}} = \frac{\sqrt{3}}{3} N_{PS} \times I_{P_{PK_{MAX}}} \times \sqrt{\frac{t_2}{t_s}} (23)$$

Transformer design (NP, NS, NAUX)

The design of the transformer is similar with ordinary Flyback transformer. The parameters below are necessary:

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Necessary parameters	
Turns ratio	N <sub>PS</sub>
Inductance	L <sub>M</sub>
Primary maximum current	I <sub>P-PK-MAX</sub>
Primary maximum RMS current	I <sub>P-RMS-MAX</sub>
Secondary maximum RMS current	I <sub>S-RMS-MAX</sub>

The design rules are as followed:



(a) Select the magnetic core style, identify the effective area  $A_{\text{e}}\,;$ 

(b) Preset the maximum magnetic flux  $\Delta B$ ;

 $\Delta B=0.22\sim0.26T$ 

(c) Compute primary turn N<sub>P</sub>;

$$N_{p} = \frac{L_{M} \times I_{P_{P} K_{MAX}}}{\Delta B \times A_{e}}$$
(24)

(d) Compute secondary turn N<sub>S</sub>;

$$N_{\rm S} = \frac{N_{\rm P}}{N_{\rm PS}} (25)$$

(e) compute auxiliary turn N<sub>AUX</sub>;

$$N_{AUX} = N_S \times \frac{V_{VIN}}{V_{OUT}}$$
 (26)

Where  $V_{VIN}$  is the working voltage of VIN pin (11V~15V is recommended);

(f) Select an appropriate wire diameter;

With I<sub>P-RMS-MAX</sub> and I<sub>S-RMS-MAX</sub>, select appropriate wire to make sure the current density ranges from 4A/mm<sup>2</sup> to 10A/mm<sup>2</sup>.

(g) If the winding area of the core and bobbin is not enough, reselect the core style, go to (a) and redesign the transformer until the ideal transformer is achieved.

#### Input capacitor CBUS

Generally, the input capacitor  $C_{BUS}$  is selected by  $C_{BUS}=2\sim 3\mu F/W$ 

Or more accurately by  $C_{BUS} = \frac{\arctan\left(1 - \frac{V_{DC,MIN}}{\sqrt{2}}\right) + \frac{\pi}{2}}{\pi} \frac{P_{OUT}}{\eta} \frac{1}{2f_{IN}V_{AC_{MIN}}^{2}(1 - \frac{V_{DC,MIN}}{\sqrt{2}V_{AC_{MIN}}})^{2}}$ (27) Where  $V_{DC-MIN}$  is the minimum voltage of BUS line and  $\Delta V_{BUS}$  is the voltage ripple of BUS line ;  $f_{IN}$  is AC line frequency ;

#### **RCD snubber for MOSFET**

The power loss of the snubber  $P_{RCD}$  is evaluated first .

$$P_{\text{RCD}} = \frac{N_{\text{PS}} \times (V_{\text{OUT}} + V_{\text{D}_{\text{F}}}) + \Delta V_{\text{S}}}{\Delta V_{\text{S}}} \times \frac{L_{\text{K}}}{L_{\text{M}}} \times P_{\text{OUT}} \quad (28)$$

Where  $N_{PS}$  is the turns ratio of the Flyback transformer;  $V_{OUT}$  is the output voltage;  $V_{D-F}$  is the forward voltage of the power diode;  $\Delta V_S$  is the overshoot voltage clamped by RCD snubber;  $L_K$  is the leakage inductor;  $L_M$  is the inductance of the Flyback transformer;  $P_{OUT}$  is the output power.

The R<sub>RCD</sub> is related with the power loss:

$$R_{\rm RCD} = \frac{\left[N_{\rm PS} \times (V_{\rm OLT} + V_{\rm D_{-}F}) + \Delta V_{\rm S}\right]^2}{P_{\rm PCD}}$$
(29)

The C<sub>RCD</sub> is related with the voltage ripple of the snubber  $\Delta V_{C-RCD}$ .

$$C_{RCD} = \frac{N_{PS} \times (V_{OUT} + V_{D_{-}F}) + \Delta V_{S}}{R_{RCD} \times f_{S} \times \Delta V_{C_{-}RCD}} \quad (30)$$

### Layout

(a) To achieve better EMI performance and reduce line frequency ripples, the output of the bridge rectifier should be connected to the BUS line capacitor first, then to the switching circuit;

(b) The ground of the BUS line capacitor, the ground of the current sample resistor and the signal ground of the IC should be connected in a star connection;

(c) The circuit loop of all switching circuit should be kept small: primary power loop, secondary loop and auxiliary power loop.



## **Design Example**

A design example of typical application is shown below step by step.

#### **#1.** Identify Design Specification

Design Specific	ation			
V <sub>AC,MIN</sub>	90V	V <sub>AC,MAX</sub>	264V	
V <sub>OUT</sub>	12V	I <sub>OUT</sub>	2A	
POUT	24W	η	86%	
f <sub>IN,MIN</sub>	60KHz			
<b>#2.</b> Transformer Refer to Power	Design $(N_{PS} and L_M)$ Device Design		the contract	
Conditions				

Conditions			
V <sub>AC,MIN</sub>	90V	V <sub>AC-MAX</sub>	264
POUT	24W	f <sub>S-MIN</sub>	60kHz
Parameters design	ed		
V <sub>MOS-(BR)DS</sub>	600V	$\Delta V_{S}$	₹ <u>75</u> ▼
C <sub>Drain</sub>	100pF	$V_{D,F}$	1V
$=\frac{600\mathrm{V}\times0.9}{12}$	$\frac{\langle 90\% - \sqrt{2}V_{AC_MAX} - \Delta V_S}{V_{OUT} + V_{D,F}}$ $\frac{\sqrt{2} \times 264V - 75V}{V + 1V}$	dential Y	- -
=7.05		C V	
		N	

$$N_{PS} \leq \frac{V_{MOS_{(BR)DS}} \times 90\% - \sqrt{2}V_{AC_{MAX}} - \Delta V_{S}}{V_{OUT} + V_{D,F}}$$

$$= \frac{600V \times 0.9 - \sqrt{2} \times 264V - 75V}{12V + 1V}$$

$$= 7.05$$
N<sub>PS</sub> is set to

ort

 $N_{PS}=7$ 

(b)f<sub>S,MIN</sub> is preset ;

 $f_{S MIN} = 60 kHz$ 

(c) Compute inductor  $L_M$  and maximum primary peak current  $I_{P,PK,MAX}$ ;

$$I_{P,PK,MAX} = \frac{2P_{OUT}}{\eta \times (\sqrt{2}V_{AC,MIN} - \Delta V_{BUS})} + \frac{2P_{OUT}}{\eta \times N_{PS} \times (V_{OUT} + V_{D,F})} + \pi \sqrt{\frac{2P_{OUT}}{\eta} \times C_{Drain} \times f_{S,MIN}} = \frac{2 \times 24W}{0.86 \times (\sqrt{2} \times 90V - 0.3 \times \sqrt{2} \times 90V)} + \frac{2 \times 24W}{0.86 \times 7 \times (12V + 1V)} + \pi \times \sqrt{\frac{2 \times 24W}{0.86} \times 100 \text{pF} \times 60 \text{KHz}} = 1.297 \text{A}$$



$$L_{m} = \frac{2P_{OUT}}{\eta \times I_{P,PK,MAX}^{2} \times f_{S,MIN}}$$
$$= \frac{2 \times 24W}{0.86 \times (1.297A)^{2} \times 60KHz}$$

= 0.553mH

Set

L<sub>M</sub>=0.55mH

(d) Compute current rising time  $t_1$  and current falling time  $t_2$ ;

$$t_{1} = \frac{L_{M} \times I_{P,PK,MAX}}{V_{BUS}} = \frac{0.55 \text{mH} \times 1.297 \text{A}}{\sqrt{2} \times 90 \text{V}} = 5.61 \mu \text{s}$$

$$t_{2} = \frac{L_{m} \times I_{P,PK,MAX}}{N_{PS} \times (V_{OUT} + V_{D,F})} = \frac{0.55mH \times 1.297A}{7 \times (12V + 1V)} = 7.84\mu s$$

$$t_3 = \pi \times \sqrt{L_M \times C_{Drain}} = \pi \times \sqrt{0.55 \text{mH} \times 100 \text{pF}} = 0.74 \mu \text{s}$$

edforthectic  $t_s = t_1 + t_2 + t_3 = 5.61 \mu s + 7.84 \mu s + 0.74 \mu s = 14.19 \mu s$ (e) Compute primary maximum RMS current I<sub>P-RMS-MAX</sub> for the transformer fabrication ;

$$I_{P,RMS,MAX} = \frac{\sqrt{3}}{3} I_{P,PK,MAX} \times \sqrt{\frac{t_1}{t_s}} = \frac{\sqrt{3}}{3} \times 1.261A \times \sqrt{\frac{5.61\mu s}{14.19\mu s}} = 0.471$$

(f) Compute secondary maximum peak current IS-PK-MAX and RMS current IS-RMS-MAX for the transformer fabrication .

$$I_{S_{PK_{MAX}}} = N_{PS} \times I_{P_{PK_{MAX}}} = 7 \times 1.297 A = 9.081 A$$

$$I_{S,RMS,MAX} = N_{PS} \times \frac{\sqrt{3}}{3} I_{P,PK,MAX} \times \sqrt{\frac{t_2}{t_s}} = 7 \times \frac{\sqrt{3}}{3} \times 0.905 A \times \sqrt{\frac{7.84 \mu s}{14.19 \mu s}} = 3.898 A$$

#### **#3.** MOSFET and Diode Design

Conditions	<b>.</b> .		
V <sub>AC-MAX</sub>	264V	N <sub>PS</sub>	7
Vout	12V	V <sub>D-F</sub>	1V
$\Delta V_{S}$	75V	η	86%

(a) Compute the voltage and the current stress of MOSFET :

$$V_{MOS-DS-MAX} = \sqrt{2} V_{AC_MAX} + N_{PS} \times (V_{OUT} + V_{D_F}) + \Delta V_S$$
  
=  $\sqrt{2} \times 264V + 7 \times (12V + 1V) + 75V$   
= 539V

 $I_{MOS_{PK}MAX} = I_{P_{PK}MAX} = 1.297A$ 

 $I_{MOS RMS MAX} = I_{P RMS MAX} = 0.471A$ 



(b) Compute the voltage and the current stress of secondary power diode

$$V_{D_{D_{R}}MAX} = \frac{\sqrt{2}V_{AC_MAX}}{N_{PS}} + V_{OUT}$$
$$= \frac{\sqrt{2} \times 264V}{7} + 12V$$
$$= 65.3V$$

 $I_{D_{PK}MAX} = N_{PS} \times I_{P_{PK}MAX} = 7 \times 1.297A = 9.081A$ 

$I_{D_AVG} = I_{OUT} = 2A$			Actor
#4. Start up design			
Refer to Start up			
Conditions			
V <sub>DC,MIN</sub>	90V×1.414	V <sub>DC,MAX</sub>	264 🗸 🔨 1.414
I <sub>ST</sub>	4µA (typical)	V <sub>IN-ON</sub>	14.7V (typical)
I <sub>VIN-OVP</sub>	7.5mA (typical)		
Designed by user			
t <sub>ST</sub>	2s		
(a) $R_{ST}$ is preset $R_{ST} < \frac{V_{BUS}}{I_{ST}} = \frac{90V \times 1.4}{4\mu A}$	$\frac{14}{1}$ =31.81MO	1.Pr	
$R_{ST} > \frac{V_{BUS}}{I_{VIN_{OVP}}} = \frac{264V}{7.51}$	$\frac{(1.414)}{nA} = 49.77 k\Omega$	dentialP	
Set	$C_{O}$		

$$R_{ST} < \frac{V_{BUS}}{I_{ST}} = \frac{90V \times 1.414}{4\mu A} = 31.81M\Omega ,$$

$$R_{ST} > \frac{V_{BUS}}{I_{VIN_OVP}} = \frac{264V \times 1.414}{7.5mA} = 49.77k\Omega$$
Set
$$R_{ST} = 6M\Omega$$
(b) Design C<sub>VIN</sub>

$$C_{VIN} = \frac{(\frac{V_{BUS}}{R_{ST}} - I_{ST}) \times I_{ST}}{V_{VIN_ON}} = \frac{90V \times 1.414}{14.7V} - 4\mu A) \times 2s$$

$$= 2.34\mu F$$
Set

 $C_{VIN} = 3.3 \mu F$ **#5**. Output voltage control



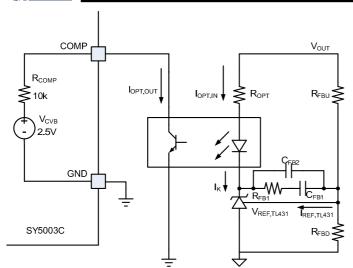


Fig.8 Output voltage feedback circuit

GND SY5003C Fig.8 Outpu	$\downarrow$	Cuit	FORHCEEP
Conditions			
V <sub>CVB</sub>	2.5V	V <sub>COMP-ON</sub>	0.4V
R <sub>COMP</sub>	10kΩ	V <sub>OPT</sub>	1.2V
β	1	V <sub>REF,TL431</sub>	2.5V
I <sub>K,MIN</sub>	1mA	I <sub>K,MAX</sub>	100mA
I <sub>REF,TL431</sub>	2~4µA		

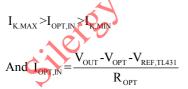
Where  $V_{OPT}$  is the input forward voltage of the opto-coupler,  $I_K$  is the cathode current of the TL431;  $I_{REF,TL431}$  is the reference input current of the TL431.

#### (a) ROPT Design

The maximum input current of the opto-coupler is limited by

$$I_{OPT,IN,MAX} > \frac{V_{CVB} - V_{COMP-ON}}{R_{COMP}} \times \frac{1}{\beta}$$
$$= \frac{2.5V - 0.4V}{10K\Omega} \times 1$$
$$= 0.21 \text{ mA}$$

At the same time, I<sub>OPT,IN</sub> is limited by the current range of TL431 cathode.



Hence,



$$R_{OPT} < \frac{V_{OUT} - V_{REF,TLA1}}{I_{OPT,INMAX}} \\ = \frac{12V \cdot 1.2V \cdot 2.5V}{0.21 \text{mA}} \\ = 39.52 \text{K}\Omega$$

$$R_{OPT} > \frac{V_{OUT} - V_{REF,TLA1}}{I_{KMAX}} \\ = \frac{12V \cdot 1.2V \cdot 2.5V}{I_{00mA}} \\ = 83\Omega$$
Set
$$R_{OPT} = 510\Omega$$
(b) resistor divider design
To achieve accurate voltage reference, R<sub>FBD</sub> is limited by
$$R_{FBD} \leq \frac{V_{REF,TLA1}}{100I_{REF,TLA1}} = \frac{2.5V}{100 \times 2\mu\text{A}} = 12.5 \text{K}\Omega$$
Set
$$R_{FBD} = 10\text{K}$$

$$R_{FBD} = \frac{V_{OUT} - V_{REF,TLA1}}{V_{REF,TLA1}} \times R_{FBD} = \frac{12V \cdot 2.5V}{2.5V} \times 10 \text{K}\Omega = 38 \text{K}\Omega^{-1} \text{M}^{-1} \text{M}$$

### **#6.** Output Current Protection design

Refer to Primary-side constant-current control

Conditions			
k <sub>1</sub>	0.5	N <sub>PS</sub>	7
V <sub>REF</sub>	0.42V		
Parameters designed	·		
I <sub>OUT,OCP</sub>	2.4A		

 $I_{\text{OUT,LIM}}$  is the maximum output current .

The current sense resistor is



$$R_{s} = \frac{k_{1} \times V_{REF} \times N_{PS}}{I_{OUT}}$$
$$= \frac{0.5 \times 0.42 \times 7}{2.4 A}$$
$$= 0.613 \Omega$$

#### **#7**. Input Capacitor $C_{BUS}$ Design

Conditions				
V <sub>AC,MIN</sub>	90V	$\Delta V_{BUS}$	30% V <sub>AC,MIN</sub>	
arcsin(1 C <sub>BUS</sub> =	$\frac{-\frac{\Delta V_{BUS}}{\sqrt{2}V_{AC,MIN}}) + \frac{\pi}{2}}{\pi} \times \frac{P_{OUT}}{\eta} > $	$<\frac{1}{2f_{IN}V_{AC,MIN}^2\left[1-\left(1-\frac{\Delta V_{BU}}{\sqrt{2}V_{AC}}\right)\right]}$	$\frac{ 30/3 \sqrt{AC,MIN}}{ 30/3 \sqrt{AC,MIN}}$	
$=\frac{\arcsin(1-\frac{0.3}{2})}{2}$	$\frac{\times\sqrt{2}\times90\mathrm{V}}{\sqrt{2}\times90\mathrm{V}}) + \frac{\pi}{2}}{\pi} \times \frac{24\mathrm{W}}{0.86} \times$	$\frac{1}{2\times 50 \text{Hz} \times 90 \text{V}^2 \times [1 - (1 - \frac{1}{2})]}$	$\frac{1}{\sqrt{2} \times 90 \text{V}} \left[ \frac{1}{\sqrt{2} \times 90 \text{V}} \right]^2}{\sqrt{2} \times 90 \text{V}}$	
$= 50.45 \mu F$				
Set			ePar	
$C_{\text{BUS}} = 44 \mu F$		$\mathbf{Q}$	<b>&gt;</b>	
<b>#8.</b> set VSEN pi	n			
First identify R <sub>v</sub>	SENU need for line regulat	ion.		
Conditions				
k3	68			
I diameters Desi	giicu			
R <sub>VSENU</sub>	100kΩ			
Then compute R	RVSEND			
Conditions				
V <sub>VSEN_OVP</sub>	1.45V	V <sub>OUT</sub>	12V	
Parameters desig				
V <sub>OVP</sub>	14V	R <sub>VSENU</sub>	100kΩ	
Ns/Naux	1			
siler				



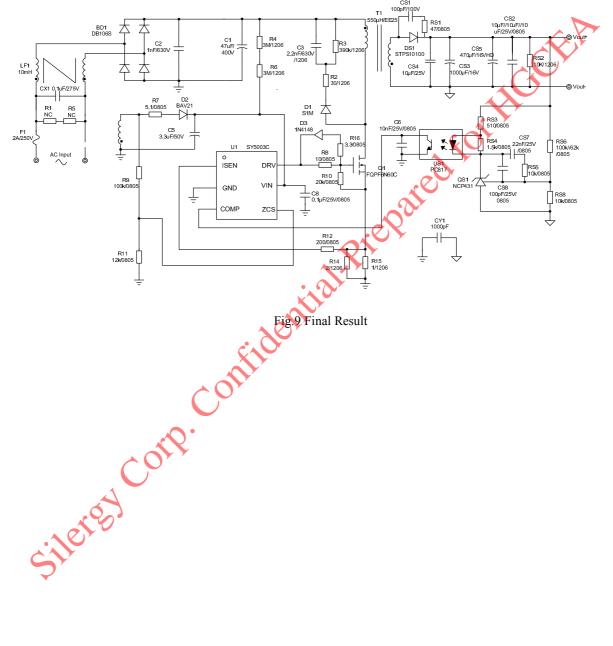
 $< \frac{\frac{V_{vsen_ovp}}{V_{out}} \times \frac{N_s}{N_{aux}}}{1 - \frac{V_{vsen_ovp}}{V} \times \frac{N_s}{N_s}} \times R_{vsenu}$  $R_{_{V\!SEND}}$  $\overline{N}_{AUX}$ V<sub>OUT</sub>  $=\frac{\frac{1.45\mathrm{V}}{12\mathrm{V}}\times1}{1-\frac{1.45\mathrm{V}}{12\mathrm{V}}\times1}\times100\mathrm{k}\Omega$ ited. =15.4k $\Omega$  $R_{\text{VSEND}} \geq \frac{\frac{V_{\text{VSEN}\_OVP}}{V_{\text{OVP}}} \times \frac{N_{\text{S}}}{N_{\text{AUX}}}}{1 - \frac{V_{\text{VSEN}\_OVP}}{V_{\text{OVP}}} \times \frac{N_{\text{S}}}{N_{\text{AUX}}}} \times R_{\text{VSENU}}$  $=\frac{\frac{1.45V}{14V}\times1}{1-\frac{1.45V}{14V}\times1}\times100k\Omega$ 14V  $=11.5k\Omega$ R<sub>VSEND</sub> is set to  $R_{VSEND} = 12k\Omega$ **#9.** Design RCD snubber Refer to Power Device Design Conditions Vout 12V 7  $L_K/L_M$ 1%  $N_{PS}$  $P_{\text{OUT}}$ 24W The power loss of the snubber is  $P_{RCD} = \frac{N_{PS} \times (V_{OUT} + V_{D_F}) + \Delta V_S}{\Delta V_S} \times \frac{L_K}{L_M} \times P_{OUT}$  $=\frac{7 \times (12V+1V) + 75V}{75V} \times 0.01 \times 24W$ =0.53W The resistor of the snubber is  $R_{RCD} = \frac{\left[N_{PS} \times (V_{OUT} + V_{D_{F}}) + \Delta V_{S}\right]^{2}}{P_{RCD}}$  $=\frac{\left[7 \times (12V+1V)+75V\right]^{2}}{0.53W}$ 



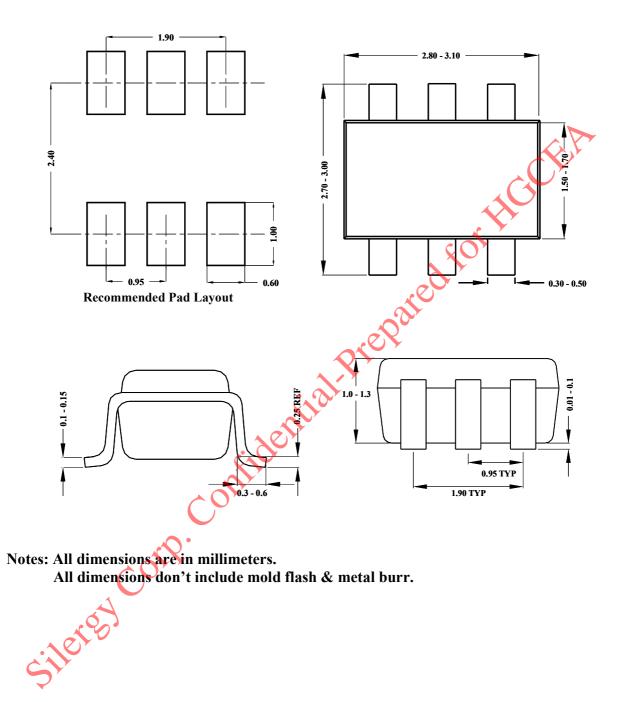
The capacitor of the snubber is

$$C_{\text{RCD}} = \frac{N_{\text{PS}} \times (V_{\text{OUT}} + V_{\text{D}_{-}F}) + \Delta V_{\text{S}}}{R_{\text{RCD}} f_{\text{S,MIN}} \Delta V_{\text{C}_{-}\text{RCD}}}$$
$$= \frac{7 \times (12V + 1V) + 75V}{53k\Omega \times 60kHz \times 25V}$$
$$= 2.08nF$$

**#10.** Final Result







SOT23-6 Package Outline & PCB Layout Design



# **Taping & Reel Specification**

## 1. Taping orientation for packages (SOT23-6)

