Technical documentation

3 Design \& development

# SN74LXC1T45-Q1 Automotive Single-Bit Dual-Supply Bus Transceiver With Configurable Level Shifting 

## 1 Features

- Fully configurable dual-rail design allows each port to operate from 1.1 V to 5.5 V
- Robust, glitch-free power supply sequencing
- Up to $420-\mathrm{Mbps}$ support for 3.3 V to 5.0 V
- Schmitt-trigger inputs allow for slow or noisy inputs
- I/O's with integrated dynamic pull-down resistors help reduce external component count
- Control inputs with integrated static pull-down resistors allow for floating control inputs
- High drive strength (up to 32 mA at 5 V )
- Low power consumption
- $3-\mu \mathrm{A}$ maximum $\left(25^{\circ} \mathrm{C}\right)$
- $6-\mu \mathrm{A}$ maximum $\left(-40^{\circ} \mathrm{C}\right.$ to $125^{\circ} \mathrm{C}$ )
- $V_{C C}$ isolation and $V_{c C}$ disconnect ( $l_{\text {off-float }}$ ) feature
- If either $V_{C C}$ supply is $<100 \mathrm{mV}$ or disconnected, all I/O's get pulled-down and then become high-impedance
- $\mathrm{I}_{\text {off }}$ supports partial-power-down mode operation
- Compatible with LVC family level shifters
- Control logic (DIR and $\overline{\mathrm{OE}}$ ) are referenced to $\mathrm{V}_{\mathrm{CCA}}$
- Operating temperature from $-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$
- Latch-up performance exceeds 100 mA per JESD 78, class II
- ESD protection exceeds JESD 22
- 4000-V human-body model
- 1000-V charged-device model


## 2 Applications

- Eliminate slow or noisy input signals
- Driving indicator LEDs or buzzers
- Debouncing a mechanical switch
- General purpose I/O level shifting


## 3 Description

The SN74LXC1T45-Q1 is a 1-bit, dual-supply noninverting bidirectional voltage level translation device. The I/O pin A and control pin (DIR) are referenced to $\mathrm{V}_{\text {CCA }}$ logic levels, and the I/O pin $B$ are referenced to $\mathrm{V}_{\text {CCB }}$ logic levels. The A pin is able to accept I/O voltages ranging from 1.1 V to 5.5 V , while the B pin can accept I/O voltages from 1.1 V to 5.5 V . A high on DIR allows data transmission from $A$ to $B$ and a low on DIR allows data transmission from B to A. See Device Functional Modes for a summary of the operation of the control logic.

Package Information ${ }^{(1)}$

| PART NUMBER | PACKAGE | BODY SIZE (NOM) |
| :---: | :--- | :--- |
| SN74LXC1T45-Q1 | SOT (DRL) (6) | $1.60 \mathrm{~mm} \times 1.20 \mathrm{~mm}$ |
|  | SON (DRY) (6) | $1.45 \mathrm{~mm} \times 1.00 \mathrm{~mm}$ |
|  | SC70 (DCK) (6) | $2.00 \mathrm{~mm} \times 1.25 \mathrm{~mm}$ |

(1) For all available packages, see the orderable addendum at the end of the data sheet.


SN74LXC1T45-Q1 Block Diagram

| SN74LXC1T45-Q1 | TEXAS |
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## Table of Contents

1 Features ..... 1
2 Applications ..... 1
3 Description ..... 1
4 Revision History ..... 2
5 Pin Configuration and Functions ..... 3
6 Specifications ..... 4
6.1 Absolute Maximum Ratings ..... 4
6.2 ESD Ratings ..... 4
6.3 Recommended Operating Conditions ..... 5
6.4 Thermal Information ..... 5
6.5 Electrical Characteristics .....  6
6.6 Switching Characteristics, $\mathrm{V}_{\mathrm{CCA}}=1.2 \pm 0.1 \mathrm{~V}$ ..... 9
6.7 Switching Characteristics, $\mathrm{V}_{\mathrm{CCA}}=1.5 \pm 0.1 \mathrm{~V}$ ..... 10
6.8 Switching Characteristics, $\mathrm{V}_{\mathrm{CCA}}=1.8 \pm 0.15 \mathrm{~V}$ ..... 11
6.9 Switching Characteristics, $\mathrm{V}_{\mathrm{CCA}}=2.5 \pm 0.2 \mathrm{~V}$ ..... 12
6.10 Switching Characteristics, $\mathrm{V}_{\mathrm{CCA}}=3.3 \pm 0.3 \mathrm{~V}$ ..... 13
6.11 Switching Characteristics, $\mathrm{V}_{\mathrm{CCA}}=5.0 \pm 0.5 \mathrm{~V}$ ..... 14
6.12 Switching Characteristics: $\mathrm{T}_{\mathrm{sk}}, \mathrm{T}_{\mathrm{MAX}}$ ..... 15
6.13 Operating Characteristics ..... 15
6.14 Typical Characteristics ..... 16
7 Parameter Measurement Information ..... 17
7.1 Load Circuit and Voltage Waveforms ..... 17
8 Detailed Description ..... 19
8.1 Overview ..... 19
8.2 Functional Block Diagram ..... 19
8.3 Feature Description ..... 19
8.4 Device Functional Modes ..... 22
9 Application and Implementation. ..... 23
9.1 Application Information ..... 23
9.2 Enable Times ..... 23
9.3 Typical Application ..... 23
10 Power Supply Recommendations ..... 24
11 Layout ..... 24
11.1 Layout Guidelines ..... 24
11.2 Layout Example. ..... 24
12 Device and Documentation Support ..... 25
12.1 Device Support ..... 25
12.2 Documentation Support. ..... 25
12.3 Receiving Notification of Documentation Updates ..... 25
12.4 Support Resources. ..... 25
12.5 Trademarks ..... 25
12.6 Electrostatic Discharge Caution ..... 25
12.7 Glossary ..... 25
13 Mechanical, Packaging, and Orderable Information ..... 25

## 4 Revision History

| DATE | REVISION | NOTES |
| :---: | :---: | :---: |
| August 2022 | $*$ | Initial Release |

## 5 Pin Configuration and Functions



Figure 5-2. DRL Package Preview, 6-Pin SOT (Top View)

Figure 5-1. DCK Package, 6-Pin SC70 (Top View)


Figure 5-3. DRY Package Preview, 6-Pin SON (Top View)

Table 5-1. Pin Functions

| PIN |  | TYPE $^{(1)}$ |  |
| :--- | :---: | :---: | :--- |
| NAME | NO. |  |  |
| $\mathrm{V}_{\mathrm{CCA}}$ | 1 | - | A-port supply voltage. $1.1 \mathrm{~V} \leq \mathrm{V}_{\mathrm{CCA}} \leq 5.5 \mathrm{~V}$. |
| GND | 2 | - | Ground. |
| A | 3 | I/O | Input or output A. Referenced to $\mathrm{V}_{\mathrm{CCA}}$. |
| B | 4 | I/O | Input or output $B$. Referenced to $\mathrm{V}_{\mathrm{CCB}}$. |
| DIR | 5 | I | Direction-control signal for all ports. Referenced to $\mathrm{V}_{\mathrm{CCA}}$. |
| $\mathrm{V}_{\mathrm{CCB}}$ | 6 | - | B-port supply voltage. $1.1 \mathrm{~V} \leq \mathrm{V}_{\mathrm{CCB}} \leq 5.5 \mathrm{~V}$. |

(1) I $=$ Input, $\mathrm{O}=$ Output, GND = ground

SN74LXC1T45-Q1

## 6 Specifications

### 6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)( ${ }^{(1)}$

|  |  |  | MIN | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {CCA }}$ | Supply voltage A |  | -0.5 | 6.5 | V |
| $\mathrm{V}_{\text {CCB }}$ | Supply voltage B |  | -0.5 | 6.5 | V |
|  |  | I/O Ports (A Port) | -0.5 | 6.5 |  |
| $V_{1}$ | Input Voltage ${ }^{(2)}$ | I/O Ports (B Port) | -0.5 | 6.5 | V |
|  |  | Control Inputs | -0.5 | 6.5 |  |
|  | Voltage applied to any output in the high-impedance or power-off | A Port | -0.5 | 6.5 |  |
|  | state ${ }^{(2)}$ | B Port | -0.5 | 6.5 |  |
| $\mathrm{V}_{0}$ | (3) | A Port |  | +0.5 | V |
| Vo |  | B Port | -0.5 | +0.5 |  |
| $\mathrm{I}_{\mathrm{IK}}$ | Input clamp current | $\mathrm{V}_{1}<0$ | -50 |  | mA |
| lok | Output clamp current | $\mathrm{V}_{\mathrm{o}}<0$ | -50 |  | mA |
| Io | Continuous output current |  | -50 | 50 | mA |
|  | Continuous current through V CC or GND |  | -200 | 200 | mA |
| $\mathrm{T}_{\mathrm{j}}$ | Junction Temperature |  |  | 150 | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{T}_{\text {stg }}$ | Storage temperature |  | -65 | 150 | ${ }^{\circ} \mathrm{C}$ |

(1) Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. If briefly ooperating outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, this device may not sustain damage, but it may not be fully functional. Operating the device in this manner may affect device reliability, functionality, performance, and shorten the device lifetime.
(2) The input voltage and output negative-voltage ratings may be exceeded if the input and output current ratings are observed.
(3) The output positive-voltage rating may be exceeded up to 6.5 V maximum if the output current rating is observed.

### 6.2 ESD Ratings

| $\mathrm{V}_{\text {(ESD) }}$ |  |  | Electrostatic discharge | Human body model (HBM), per AEC Q100-002(1) |
| :---: | :---: | :--- | :---: | :---: |
|  |  | VALUE |  |  |

(1) AEC Q100-002 indicates that HBM stressing shall be in accordance with the ANSI/ESDA/JEDEC JS-001 specification

### 6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted) (1) (2) (3)

|  |  |  |  | MIN | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {CCA }}$ | Supply voltage A |  |  | 1.1 | 5.5 | V |
| $\mathrm{V}_{\text {CCB }}$ | Supply voltage B |  |  | 1.1 | 5.5 | V |
| IOH | High-level output current |  | $\mathrm{V}_{\mathrm{CcO}}=1.1 \mathrm{~V}$ |  | -0.1 | mA |
|  |  |  | $\mathrm{V}_{\mathrm{CcO}}=1.4 \mathrm{~V}$ |  | -4 |  |
|  |  |  | $\mathrm{V}_{\text {cco }}=1.65 \mathrm{~V}$ |  | -8 |  |
|  |  |  | $\mathrm{V}_{\mathrm{CcO}}=2.3 \mathrm{~V}$ |  | -12 |  |
|  |  |  | $\mathrm{V}_{\text {cco }}=3 \mathrm{~V}$ |  | -24 |  |
|  |  |  | $\mathrm{V}_{\mathrm{CcO}}=4.5 \mathrm{~V}$ |  | -32 |  |
| loL | Low-level output current |  | $\mathrm{V}_{\mathrm{CcO}}=1.1 \mathrm{~V}$ |  | 0.1 | mA |
|  |  |  | $\mathrm{V}_{\mathrm{CcO}}=1.4 \mathrm{~V}$ |  | 4 |  |
|  |  |  | $\mathrm{V}_{\text {CCO }}=1.65 \mathrm{~V}$ |  | 8 |  |
|  |  |  | $\mathrm{V}_{\mathrm{CcO}}=2.3 \mathrm{~V}$ |  | 12 |  |
|  |  |  | $\mathrm{V}_{\text {CCO }}=3 \mathrm{~V}$ |  | 24 |  |
|  |  |  | $\mathrm{V}_{\mathrm{CcO}}=4.5 \mathrm{~V}$ |  | 32 |  |
| V | Input voltage ${ }^{(3)}$ |  |  | 0 | 5.5 | V |
| $\mathrm{V}_{0}$ | Output voltage | Active State |  | 0 | $\mathrm{V}_{\mathrm{CcO}}$ | V |
|  |  | Tri-State |  | 0 | 5.5 |  |
| $\mathrm{T}_{\mathrm{A}}$ | Operating free-air temperature |  |  | -40 | 125 | ${ }^{\circ} \mathrm{C}$ |

(1) $\mathrm{V}_{\mathrm{CI}}$ is the $\mathrm{V}_{\mathrm{CC}}$ associated with the input port.
(2) $\mathrm{V}_{\mathrm{CCO}}$ is the $\mathrm{V}_{\mathrm{CC}}$ associated with the output port.
(3) All control inputs and data I/Os of this device have weak pulldowns to ensure the line is not floating when undefined external to the device. The input leakage from these weak pulldowns is defined by the $l_{\text {I }}$ specification indicated under Electrical Characteristics.

### 6.4 Thermal Information

| THERMAL METRIC ${ }^{(1)}$ |  | SN74LXC1T45-Q1 |  |  | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | DCK (SC70) | DRL (SOT) | DRY (SON) |  |
|  |  | 6 PINS | 6 PINS | 6 PINS |  |
| $\mathrm{R}_{\text {өJA }}$ | Junction-to-ambient thermal resistance | 216.1 | TBD | 293.4 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |
| $\mathrm{R}_{\text {өJC(top) }}$ | Junction-to-case (top) thermal resistance | 143.6 | TBD | 184.0 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |
| $\mathrm{R}_{\text {өJB }}$ | Junction-to-board thermal resistance | 75.9 | TBD | 164.9 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |
| $\mathrm{Y}_{\mathrm{JT}}$ | Junction-to-top characterization parameter | 58.5 | TBD | 28.3 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |
| $Y_{J B}$ | Junction-to-board characterization parameter | 75.6 | TBD | 164.0 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |
| $\mathrm{R}_{\text {өJC(bottom) }}$ | Junction-to-case (bottom) thermal resistance | N/A | TBD | N/A | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.

### 6.5 Electrical Characteristics

over operating free-air temperature range (unless otherwise noted) ${ }^{(1)}{ }^{(2)}$

| PARAMETER |  | TEST CONDITIONS | $\mathbf{V}_{\text {CCA }}$ | $\mathrm{V}_{\text {ccB }}$ | Operating free-air temperature ( $\mathrm{T}_{\mathrm{A}}$ ) |  |  |  |  |  |  |  |  | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $25^{\circ} \mathrm{C}$ |  |  | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ |  |  |  |
|  |  | MIN |  |  | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX |  |
| $\mathrm{V}_{\mathrm{T}+}$ | Positivegoing inputthreshold voltage |  | Data Inputs (Ax, Bx) (Referenced to $\mathrm{V}_{\mathrm{CLI}}$ ) | 1.1 V | 1.1 V |  |  |  | 0.44 |  | 0.88 | 0.44 |  | 0.88 | V |
|  |  |  |  | 1.4 V | 1.4 V |  |  |  | 0.60 |  | 0.98 | 0.60 |  | 0.98 |  |
|  |  | 1.65 V |  | 1.65 V |  |  |  | 0.76 |  | 1.13 | 0.76 |  | 1.13 |  |  |
|  |  | 2.3 V |  | 2.3 V |  |  |  | 1.08 |  | 1.56 | 1.08 |  | 1.56 |  |  |
|  |  | 3 V |  | 3 V |  |  |  | 1.48 |  | 1.92 | 1.48 |  | 1.92 |  |  |
|  |  | 4.5 V |  | 4.5 V |  |  |  | 2.19 |  | 2.74 | 2.19 |  | 2.74 |  |  |
|  |  | 5.5 V |  | 5.5 V |  |  |  | 2.65 |  | 3.33 | 2.65 |  | 3.33 |  |  |
|  |  | Control Input (DIR) <br> (Referenced to $\mathrm{V}_{\mathrm{CCA}}$ ) | 1.1 V | 1.1 V |  |  |  | 0.44 |  | 0.88 | 0.44 |  | 0.88 | V |  |
|  |  |  | 1.4 V | 1.4 V |  |  |  | 0.60 |  | 0.98 | 0.60 |  | 0.98 |  |  |
|  |  |  | 1.65 V | 1.65 V |  |  |  | 0.76 |  | 1.13 | 0.76 |  | 1.13 |  |  |
|  |  |  | 2.3 V | 2.3 V |  |  |  | 1.08 |  | 1.56 | 1.08 |  | 1.56 |  |  |
|  |  |  | 3 V | 3 V |  |  |  | 1.48 |  | 1.92 | 1.48 |  | 1.92 |  |  |
|  |  |  | 4.5 V | 4.5 V |  |  |  | 2.19 |  | 2.74 | 2.19 |  | 2.74 |  |  |
|  |  |  | 5.5 V | 5.5 V |  |  |  | 2.65 |  | 3.33 | 2.65 |  | 3.33 |  |  |
| $\mathrm{V}_{\mathrm{T}-}$ | Negativegoing inputthreshold voltage | Data Inputs (Ax, Bx) (Referenced to $\mathrm{V}_{\mathrm{CCI}}$ ) | 1.1 V | 1.1 V |  |  |  | 0.17 |  | 0.48 | 0.17 |  | 0.48 | V |  |
|  |  |  | 1.4 V | 1.4 V |  |  |  | 0.28 |  | 0.59 | 0.28 |  | 0.59 |  |  |
|  |  |  | 1.65 V | 1.65 V |  |  |  | 0.35 |  | 0.69 | 0.35 |  | 0.69 |  |  |
|  |  |  | 2.3 V | 2.3 V |  |  |  | 0.56 |  | 0.97 | 0.56 |  | 0.97 |  |  |
|  |  |  | 3 V | 3 V |  |  |  | 0.89 |  | 1.5 | 0.89 |  | 1.5 |  |  |
|  |  |  | 4.5 V | 4.5 V |  |  |  | 1.51 |  | 1.97 | 1.51 |  | 1.97 |  |  |
|  |  |  | 5.5 V | 5.5 V |  |  |  | 1.88 |  | 2.4 | 1.88 |  | 2.4 |  |  |
|  |  | Control Input (DIR) <br> (Referenced to $\mathrm{V}_{\mathrm{CCA}}$ ) | 1.1 V | 1.1 V |  |  |  | 0.17 |  | 0.48 | 0.17 |  | 0.48 | V |  |
|  |  |  | 1.4 V | 1.4 V |  |  |  | 0.28 |  | 0.6 | 0.28 |  | 0.6 |  |  |
|  |  |  | 1.65 V | 1.65 V |  |  |  | 0.35 |  | 0.71 | 0.35 |  | 0.71 |  |  |
|  |  |  | 2.3 V | 2.3 V |  |  |  | 0.56 |  | 1 | 0.56 |  | 1 |  |  |
|  |  |  | 3 V | 3 V |  |  |  | 0.89 |  | 1.5 | 0.89 |  | 1.5 |  |  |
|  |  |  | 4.5 V | 4.5 V |  |  |  | 1.51 |  | 2 | 1.51 |  | 2 |  |  |
|  |  |  | 5.5 V | 5.5 V |  |  |  | 1.88 |  | 2.46 | 1.88 |  | 2.46 |  |  |
| $\Delta \mathrm{V}_{\mathrm{T}}$ | Inputthreshold hysteresis$\left(\mathrm{V}_{\mathrm{T}_{+}-}-\mathrm{V}_{\mathrm{T}_{-}}\right)$ | Data Inputs (Ax, Bx) (Referenced to $\mathrm{V}_{\mathrm{CCI}}$ ) | 1.1 V | 1.1 V |  |  |  | 0.2 |  | 0.4 | 0.2 |  | 0.4 | V |  |
|  |  |  | 1.4 V | 1.4 V |  |  |  | 0.25 |  | 0.5 | 0.25 |  | 0.5 |  |  |
|  |  |  | 1.65 V | 1.65 V |  |  |  | 0.3 |  | 0.55 | 0.3 |  | 0.55 |  |  |
|  |  |  | 2.3 V | 2.3 V |  |  |  | 0.38 |  | 0.65 | 0.38 |  | 0.65 |  |  |
|  |  |  | 3 V | 3 V |  |  |  | 0.46 |  | 0.72 | 0.46 |  | 0.72 |  |  |
|  |  |  | 4.5 V | 4.5 V |  |  |  | 0.58 |  | 0.93 | 0.58 |  | 0.93 |  |  |
|  |  |  | 5.5 V | 5.5 V |  |  |  | 0.69 |  | 1.06 | 0.69 |  | 1.06 |  |  |
|  |  | Control Input (DIR) <br> (Referenced to $\mathrm{V}_{\mathrm{CCA}}$ ) | 1.1 V | 1.1 V |  |  |  | 0.2 |  | 0.4 | 0.2 |  | 0.4 | V |  |
|  |  |  | 1.4 V | 1.4 V |  |  |  | 0.25 |  | 0.5 | 0.25 |  | 0.5 |  |  |
|  |  |  | 1.65 V | 1.65 V |  |  |  | 0.3 |  | 0.55 | 0.3 |  | 0.55 |  |  |
|  |  |  | 2.3 V | 2.3 V |  |  |  | 0.38 |  | 0.65 | 0.38 |  | 0.65 |  |  |
|  |  |  | 3 V | 3 V |  |  |  | 0.46 |  | 0.72 | 0.46 |  | 0.72 |  |  |
|  |  |  | 4.5 V | 4.5 V |  |  |  | 0.58 |  | 0.93 | 0.58 |  | 0.93 |  |  |
|  |  |  | 5.5 V | 5.5 V |  |  |  | 0.69 |  | 1.06 | 0.69 |  | 1.06 |  |  |

### 6.5 Electrical Characteristics (continued)

over operating free-air temperature range (unless otherwise noted) ${ }^{(1)}{ }^{(2)}$


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### 6.5 Electrical Characteristics (continued)

over operating free-air temperature range (unless otherwise noted) ${ }^{(1)}{ }^{(2)}$

| PARAMETER |  | TEST CONDITIONS | $\mathrm{V}_{\text {cCA }}$ | $\mathrm{V}_{\text {cCB }}$ | Operating free-air temperature ( $\mathrm{T}_{\mathrm{A}}$ ) |  |  |  |  |  |  |  |  | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $25^{\circ} \mathrm{C}$ |  |  | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ |  |  |  |
|  |  | MIN |  |  | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX |  |
| $\begin{aligned} & \Delta \\ & \mathrm{I}_{\mathrm{CCA}} \end{aligned}$ | $V_{\text {CCA }}$ additional supply current per input |  | Control input (DIR): <br> $\mathrm{V}_{\mathrm{I}}=\mathrm{V}_{\mathrm{CCA}}-0.6 \mathrm{~V}$ <br> A port = VCCA or GND <br> B Port = open | $3.0 \mathrm{~V}-5.5 \mathrm{~V}$ | $3.0 \mathrm{~V}-5.5 \mathrm{~V}$ |  |  |  |  |  | 50 |  |  | 75 | $\mu \mathrm{A}$ |
|  |  |  | $\begin{aligned} & \text { A Port: } V_{I}=V_{C C A}- \\ & 0.6 \mathrm{~V} \\ & \text { DIR }=V_{C C A}, B \text { Port } \\ & =\text { open } \end{aligned}$ | $3.0 \mathrm{~V}-5.5 \mathrm{~V}$ | $3.0 \mathrm{~V}-5.5 \mathrm{~V}$ |  |  |  |  |  | 50 |  |  | 75 |  |
| $\begin{array}{\|l\|l} \Delta \\ \mathrm{I}_{\mathrm{CCB}} \end{array}$ | $\mathrm{V}_{\mathrm{CCB}}$ <br> additional <br> supply <br> current per <br> input | $\begin{aligned} & \text { B Port: } V_{1}=V_{C C B}- \\ & 0.6 \mathrm{~V} \\ & \text { DIR }=\text { GND, A Port } \\ & =\text { open } \end{aligned}$ | $3.0 \mathrm{~V}-5.5 \mathrm{~V}$ | $3.0 \mathrm{~V}-5.5 \mathrm{~V}$ |  |  |  |  |  | 50 |  |  | 75 | $\mu \mathrm{A}$ |  |
| $\mathrm{C}_{i}$ | Control Input Capacitanc e | $\mathrm{V}_{1}=3.3 \mathrm{~V}$ or GND | 3.3 V | 3.3 V |  | 2.2 |  |  |  | 5 |  |  | 5 | pF |  |
| $\mathrm{C}_{\text {io }}$ | Data I/O Capacitanc e | $\begin{aligned} & \mathrm{V}_{\mathrm{CCO}}=0 \mathrm{~V} \mathrm{~V}_{\mathrm{O}} \\ & =1.65 \mathrm{VDC}+1 \\ & \mathrm{MHz}-16 \mathrm{dBm} \text { sine } \\ & \text { wave } \end{aligned}$ | 3.3 V | 3.3 V |  | 4.3 |  |  |  | 10.5 |  |  | 10.5 | pF |  |

(1) $V_{C C I}$ is the $V_{C C}$ associated with the input port.
(2) $\mathrm{V}_{\mathrm{CCO}}$ is the $\mathrm{V}_{\mathrm{CC}}$ associated with the output port.
(3) Tested at $\mathrm{V}_{1}=\mathrm{V}_{\mathrm{T}+(\mathrm{MAX})}$.
(4) Tested at $\mathrm{V}_{\mathrm{I}}=\mathrm{V}_{\mathrm{T} \text {-(MIN) }}$.
(5) For I/O ports, the parameter I I includes the loz current.
(6) Floating is defined as a node that is both not actively driven by an external device and has leakage not exeeding 10 nA .

### 6.6 Switching Characteristics, $\mathrm{V}_{\mathrm{CCA}}=1.2 \pm 0.1 \mathrm{~V}$

See Figure 7-1 and Table 7-1 for test circuit and loading. See Figure 7-2, Figure 7-3, and Figure 7-4 for measurement waveforms.

| PARAMETER |  | FROM | то | Test Conditions | B-Port Supply Voltage ( $\mathrm{V}_{\mathrm{ccB}}$ ) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $1.2 \pm 0.1 \mathrm{~V}$ |  |  | $1.5 \pm 0.1 \mathrm{~V}$ |  |  | $1.8 \pm 0.15 \mathrm{~V}$ |  |  | $2.5 \pm 0.2 \mathrm{~V}$ |  |  | $3.3 \pm 0.3 \mathrm{~V}$ |  |  | $5.0 \pm 0.5 \mathrm{~V}$ |  |  |  |
|  |  | MIN |  |  | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX |  |
| d | Propagation delay |  | A | B | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 6 |  | 85 | 4 |  | 41 | 3 |  | 36 | 1 |  | 33 | 1 |  | 34 | 1 |  | 44 | ns |
|  |  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 6 |  | 85 | 4 |  | 41 | 3 |  | 36 | 1 |  | 33 | 1 |  | 34 | 1 |  | 44 |  |
|  |  | B | A | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 6 |  | 85 | 5 |  | 71 | 4 |  | 67 | 3 |  | 60 | 3 |  | 57 | 3 |  | 58 |  |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 6 |  | 85 | 5 |  | 71 | 4 |  | 67 | 3 |  | 60 | 3 |  | 57 | 3 |  | 58 |  |  |
| $\mathrm{t}_{\text {dis }}$ | Disable time | DIR | A | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 5 |  | 53 | 5 |  | 53 | 5 |  | 53 | 5 |  | 53 | 5 |  | 53 | 4 |  | 53 | ns |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 5 |  | 53 | 5 |  | 53 | 5 |  | 53 | 5 |  | 53 | 5 |  | 53 | 4 |  | 53 |  |  |
|  |  | DIR | B | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 10 |  | 85 | 7 |  | 47 | 6 |  | 41 | 5 |  | 34 | 5 |  | 33 | 4 |  | 32 |  |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 10 |  | 85 | 7 |  | 47 | 6 |  | 41 | 5 |  | 34 | 5 |  | 33 | 4 |  | 32 |  |  |
| $\mathrm{t}_{\text {en }}$ | Enable time | DIR | A | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 21 |  | 150 | 17 |  | 110 | 16 |  | 99 | 13 |  | 86 | 13 |  | 83 | 12 |  | 85 | ns |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 21 |  | 150 | 17 |  | 110 | 16 |  | 99 | 13 |  | 86 | 13 |  | 83 | 12 |  | 85 |  |  |
|  |  | DIR | B | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 16 |  | 118 | 14 |  | 89 | 13 |  | 84 | 12 |  | 81 | 11 |  | 82 | 11 |  | 92 |  |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 16 |  | 118 | 14 |  | 89 | 13 |  | 84 | 12 |  | 81 | 11 |  | 82 | 11 |  | 92 |  |  |

### 6.7 Switching Characteristics, $\mathrm{V}_{\mathrm{CCA}}=1.5 \pm 0.1 \mathrm{~V}$

See Figure 7-1 and Table 7-1 for test circuit and loading. See Figure 7-2, Figure 7-3, and Figure 7-4 for measurement waveforms.

| PARAMETER |  | FROM | то | Test Conditions | B-Port Supply Voltage ( $\mathrm{V}_{\mathrm{CCB}}$ ) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $1.2 \pm 0.1 \mathrm{~V}$ |  |  | $1.5 \pm 0.1 \mathrm{~V}$ |  |  | $1.8 \pm 0.15 \mathrm{~V}$ |  |  | $2.5 \pm 0.2 \mathrm{~V}$ |  |  | $3.3 \pm 0.3 \mathrm{~V}$ |  |  | $5.0 \pm 0.5 \mathrm{~V}$ |  |  |  |
|  |  | MIN |  |  | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX |  |
| $\mathrm{t}_{\mathrm{pd}}$ | Propagation delay |  | A | B | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 5 |  | 71 | 3 |  | 29 | 1 |  | 24 | 1 |  | 20 | 1 |  | 19 | 1 |  | 19 | ns |
|  |  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 5 |  | 71 | 3 |  | 30 | 1 |  | 25 | 1 |  | 21 | 1 |  | 20 | 1 |  | 20 |  |
|  |  | B | A | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 4 |  | 41 | 3 |  | 29 | 2 |  | 27 | 1 |  | 23 | 1 |  | 22 | 1 |  | 21 |  |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 4 |  | 41 | 3 |  | 30 | 2 |  | 27 | 1 |  | 24 | 1 |  | 22 | 1 |  | 22 |  |  |
| $\mathrm{t}_{\text {dis }}$ | Disable time | DIR | A | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 2 |  | 26 | 2 |  | 26 | 2 |  | 26 | 2 |  | 26 | 2 |  | 26 | 2 |  | 26 | ns |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 2 |  | 27 | 2 |  | 27 | 2 |  | 27 | 2 |  | 27 | 2 |  | 27 | 2 |  | 27 |  |  |
|  |  | DIR | B | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 8 |  | 71 | 6 |  | 38 | 5 |  | 32 | 3 |  | 25 | 3 |  | 24 | 2 |  | 22 |  |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 8 |  | 71 | 6 |  | 39 | 5 |  | 34 | 3 |  | 26 | 3 |  | 25 | 2 |  | 23 |  |  |
| $\mathrm{t}_{\mathrm{en}}$ | Enable time | DIR | A | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 17 |  | 106 | 13 |  | 63 | 12 |  | 54 | 9 |  | 44 | 9 |  | 41 | 8 |  | 39 | ns |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 17 |  | 106 | 13 |  | 64 | 12 |  | 56 | 9 |  | 45 | 9 |  | 42 | 8 |  | 40 |  |  |
|  |  | DIR | B | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 12 |  | 90 | 10 |  | 51 | 9 |  | 45 | 8 |  | 40 | 7 |  | 39 | 7 |  | 39 |  |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 12 |  | 90 | 10 |  | 51 | 9 |  | 47 | 8 |  | 42 | 7 |  | 40 | 7 |  | 40 |  |  |

### 6.8 Switching Characteristics, $\mathrm{V}_{\mathrm{CCA}}=1.8 \pm 0.15 \mathrm{~V}$

See Figure 7-1 and Table 7-1 for test circuit and loading. See Figure 7-2, Figure 7-3, and Figure 7-4 for measurement waveforms.

| PARAMETER |  | FROM | то | Test Conditions | B-Port Supply Voltage ( $\mathrm{V}_{\mathrm{CCB}}$ ) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $1.2 \pm 0.1 \mathrm{~V}$ |  |  | $1.5 \pm 0.1 \mathrm{~V}$ |  |  | $1.8 \pm 0.15 \mathrm{~V}$ |  |  | $2.5 \pm 0.2 \mathrm{~V}$ |  |  | $3.3 \pm 0.3 \mathrm{~V}$ |  |  | $5.0 \pm 0.5 \mathrm{~V}$ |  |  |  |
|  |  | MIN |  |  | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX |  |
| $\mathrm{t}_{\mathrm{pd}}$ | Propagation delay |  | A | B | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 4 |  | 67 | 2 |  | 27 | 1 |  | 22 | 1 |  | 18 | 1 |  | 16 | 1 |  | 16 | ns |
|  |  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 4 |  | 67 | 2 |  | 27 | 1 |  | 22 | 1 |  | 18 | 1 |  | 17 | 1 |  | 16 |  |
|  |  | B | A | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 3 |  | 36 | 1 |  | 24 | 1 |  | 22 | 1 |  | 19 | 1 |  | 18 | 1 |  | 17 |  |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 3 |  | 36 | 1 |  | 25 | 1 |  | 22 | 1 |  | 19 | 1 |  | 18 | 1 |  | 18 |  |  |
| $\mathrm{t}_{\text {dis }}$ | Disable time | DIR | A | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 2 |  | 21 | 2 |  | 21 | 2 |  | 21 | 2 |  | 21 | 2 |  | 21 | 1 |  | 21 | ns |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 2 |  | 22 | 2 |  | 22 | 2 |  | 22 | 2 |  | 22 | 2 |  | 22 | 1 |  | 22 |  |  |
|  |  | DIR | B | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 7 |  | 65 | 5 |  | 35 | 4 |  | 29 | 2 |  | 22 | 2 |  | 21 | 1 |  | 19 |  |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 7 |  | 65 | 5 |  | 36 | 4 |  | 30 | 2 |  | 24 | 2 |  | 22 | 1 |  | 20 |  |  |
| $\mathrm{t}_{\mathrm{en}}$ | Enable time | DIR | A | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 15 |  | 96 | 11 |  | 54 | 10 |  | 46 | 8 |  | 36 | 7 |  | 34 | 6 |  | 31 | ns |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 15 |  | 96 | 11 |  | 56 | 10 |  | 48 | 8 |  | 38 | 7 |  | 35 | 6 |  | 33 |  |  |
|  |  | DIR | B | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 11 |  | 80 | 9 |  | 42 | 7 |  | 37 | 7 |  | 33 | 6 |  | 31 | 6 |  | 30 |  |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 11 |  | 80 | 9 |  | 43 | 7 |  | 39 | 7 |  | 34 | 6 |  | 33 | 6 |  | 32 |  |  |

### 6.9 Switching Characteristics, $\mathrm{V}_{\mathrm{CCA}}=2.5 \pm 0.2 \mathrm{~V}$

See Figure 7-1 and Table 7-1 for test circuit and loading. See Figure 7-2, Figure 7-3, and Figure 7-4 for measurement waveforms.

| PARAMETER |  | FROM | то | Test Conditions | B-Port Supply Voltage ( $\mathrm{V}_{\mathrm{CCB}}$ ) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $1.2 \pm 0.1 \mathrm{~V}$ |  |  | $1.5 \pm 0.1 \mathrm{~V}$ |  |  | $1.8 \pm 0.15 \mathrm{~V}$ |  |  | $2.5 \pm 0.2 \mathrm{~V}$ |  |  | $3.3 \pm 0.3 \mathrm{~V}$ |  |  | $5.0 \pm 0.5 \mathrm{~V}$ |  |  |  |
|  |  | MIN |  |  | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX |  |
| $\mathrm{t}_{\mathrm{pd}}$ | Propagation delay |  | A | B | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 3 |  | 60 | 1 |  | 23 | 1 |  | 19 | 1 |  | 15 | 1 |  | 14 | 1 |  | 13 | ns |
|  |  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 3 |  | 60 | 1 |  | 24 | 1 |  | 19 | 1 |  | 15 | 1 |  | 14 | 1 |  | 13 |  |
|  |  | B | A | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 1 |  | 33 | 1 |  | 20 | 1 |  | 18 | 1 |  | 15 | 1 |  | 14 | 1 |  | 14 |  |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 1 |  | 33 | 1 |  | 21 | 1 |  | 18 | 1 |  | 15 | 1 |  | 14 | 1 |  | 14 |  |  |
| $\mathrm{t}_{\text {dis }}$ | Disable time | DIR | A | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 1 |  | 15 | 1 |  | 15 | 1 |  | 15 | 1 |  | 15 | 1 |  | 15 | 1 |  | 15 | ns |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 1 |  | 15 | 1 |  | 15 | 1 |  | 15 | 1 |  | 15 | 1 |  | 15 | 1 |  | 15 |  |  |
|  |  | DIR | B | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 5 |  | 54 | 4 |  | 30 | 3 |  | 25 | 2 |  | 19 | 2 |  | 18 | 1 |  | 16 |  |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 5 |  | 54 | 4 |  | 31 | 3 |  | 26 | 2 |  | 21 | 2 |  | 19 | 1 |  | 17 |  |  |
| $\mathrm{t}_{\mathrm{en}}$ | Enable time | DIR | A | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 12 |  | 82 | 9 |  | 44 | 8 |  | 37 | 6 |  | 29 | 6 |  | 27 | 5 |  | 24 | ns |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 12 |  | 82 | 9 |  | 45 | 8 |  | 39 | 6 |  | 31 | 6 |  | 29 | 5 |  | 26 |  |  |
|  |  | DIR | B | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 8 |  | 67 | 6 |  | 33 | 5 |  | 29 | 4 |  | 25 | 4 |  | 23 | 4 |  | 22 |  |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 8 |  | 67 | 6 |  | 34 | 5 |  | 30 | 4 |  | 26 | 4 |  | 24 | 4 |  | 23 |  |  |

### 6.10 Switching Characteristics, $\mathrm{V}_{\mathrm{CCA}}=3.3 \pm 0.3 \mathrm{~V}$

See Figure 7-1 and Table 7-1 for test circuit and loading. See Figure 7-2, Figure 7-3, and Figure 7-4 for measurement waveforms.

| PARAMETER |  | FROM | то | Test Conditions | B-Port Supply Voltage ( $\mathrm{V}_{\mathrm{ccB}}$ ) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $1.2 \pm 0.1 \mathrm{~V}$ |  |  | $1.5 \pm 0.1 \mathrm{~V}$ |  |  | $1.8 \pm 0.15 \mathrm{~V}$ |  |  | $2.5 \pm 0.2 \mathrm{~V}$ |  |  | $3.3 \pm 0.3 \mathrm{~V}$ |  |  | $5.0 \pm 0.5 \mathrm{~V}$ |  |  |  |
|  |  | MIN |  |  | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX |  |
| $\mathrm{t}_{\mathrm{pd}}$ | Propagation delay |  | A | B | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 3 |  | 57 | 1 |  | 22 | 1 |  | 18 | 1 |  | 14 | 1 |  | 13 | 1 |  | 12 | ns |
|  |  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 3 |  | 57 | 1 |  | 22 | 2 |  | 18 | 1 |  | 14 | 1 |  | 13 | 1 |  | 12 |  |
|  |  | B | A | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 1 |  | 34 | 1 |  | 19 | 1 |  | 16 | 1 |  | 13 | 1 |  | 13 | 1 |  | 12 |  |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 1 |  | 34 | 1 |  | 20 | 1 |  | 17 | 1 |  | 14 | 1 |  | 13 | 1 |  | 12 |  |  |
| $\mathrm{t}_{\text {dis }}$ | Disable time | DIR | A | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 1 |  | 14 | 1 |  | 14 | 1 |  | 14 | 1 |  | 14 | 1 |  | 14 | 1 |  | 14 | ns |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 1 |  | 14 | 1 |  | 14 | 1 |  | 14 | 1 |  | 14 | 1 |  | 14 | 1 |  | 14 |  |  |
|  |  | DIR | B | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 5 |  | 49 | 3 |  | 27 | 3 |  | 23 | 1 |  | 18 | 2 |  | 17 | 1 |  | 15 |  |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 5 |  | 49 | 3 |  | 28 | 3 |  | 24 | 1 |  | 19 | 2 |  | 18 | 1 |  | 16 |  |  |
| $\mathrm{t}_{\text {en }}$ | Enable time | DIR | A | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 12 |  | 78 | 8 |  | 39 | 7 |  | 33 | 6 |  | 26 | 5 |  | 25 | 4 |  | 22 | ns |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 12 |  | 78 | 8 |  | 40 | 7 |  | 35 | 6 |  | 28 | 5 |  | 26 | 4 |  | 23 |  |  |
|  |  | DIR | B | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 8 |  | 64 | 6 |  | 30 | 5 |  | 26 | 4 |  | 23 | 4 |  | 21 | 4 |  | 20 |  |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 8 |  | 64 | 6 |  | 31 | 5 |  | 27 | 4 |  | 24 | 4 |  | 22 | 4 |  | 21 |  |  |

### 6.11 Switching Characteristics, $\mathrm{V}_{\mathrm{CCA}}=5.0 \pm 0.5 \mathrm{~V}$

See Figure 7-1 and Table 7-1 for test circuit and loading. See Figure 7-2, Figure 7-3, and Figure 7-4 for measurement waveforms.

| PARAMETER |  | FROM | то | Test Conditions | B-Port Supply Voltage ( $\mathrm{V}_{\mathrm{cCB}}$ ) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $1.2 \pm 0.1 \mathrm{~V}$ |  |  | $1.5 \pm 0.1 \mathrm{~V}$ |  |  | $1.8 \pm 0.15 \mathrm{~V}$ |  |  | $2.5 \pm 0.2 \mathrm{~V}$ |  |  | $3.3 \pm 0.3 \mathrm{~V}$ |  |  | $5.0 \pm 0.5 \mathrm{~V}$ |  |  |  |
|  |  | MIN |  |  | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX |  |
| $\mathrm{t}_{\mathrm{pd}}$ | Propagation delay |  | A | B | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 3 |  | 58 | 1 |  | 21 | 1 |  | 17 | 1 |  | 14 | 1 |  | 12 | 1 |  | 11 | ns |
|  |  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 3 |  | 58 | 1 |  | 22 | 1 |  | 18 | 1 |  | 14 | 1 |  | 13 | 1 |  | 11 |  |
|  |  | B | A | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 1 |  | 44 | 1 |  | 19 | 1 |  | 16 | 1 |  | 13 | 1 |  | 12 | 1 |  | 11 |  |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 1 |  | 44 | 1 |  | 20 | 1 |  | 16 | 1 |  | 13 | 1 |  | 12 | 1 |  | 11 |  |  |
| $\mathrm{t}_{\text {dis }}$ | Disable time | DIR | A | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 1 |  | 12 | 1 |  | 12 | 1 |  | 12 | 1 |  | 12 | 1 |  | 12 | 1 |  | 12 | ns |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 1 |  | 12 | 1 |  | 12 | 1 |  | 12 | 1 |  | 12 | 1 |  | 12 | 1 |  | 12 |  |  |
|  |  | DIR | B | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 5 |  | 48 | 3 |  | 26 | 3 |  | 21 | 1 |  | 16 | 2 |  | 16 | 1 |  | 14 |  |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 5 |  | 48 | 3 |  | 26 | 3 |  | 22 | 1 |  | 17 | 2 |  | 17 | 1 |  | 15 |  |  |
| $\mathrm{t}_{\text {en }}$ | Enable time | DIR | A | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 11 |  | 87 | 8 |  | 38 | 7 |  | 31 | 5 |  | 24 | 5 |  | 22 | 4 |  | 20 | ns |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 11 |  | 87 | 8 |  | 39 | 7 |  | 32 | 5 |  | 25 | 5 |  | 24 | 4 |  | 21 |  |  |
|  |  | DIR | B | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 7 |  | 63 | 5 |  | 28 | 4 |  | 24 | 3 |  | 20 | 3 |  | 19 | 2 |  | 18 |  |  |
|  |  |  |  | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ | 7 |  | 63 | 5 |  | 28 | 4 |  | 25 | 3 |  | 21 | 3 |  | 19 | 2 |  | 18 |  |  |

### 6.12 Switching Characteristics: $\mathrm{T}_{\text {sk }}, \mathrm{T}_{\text {MAX }}$

over operating free-air temperature range (unless otherwise noted)

| PARAMETER | TEST CONDITIONS |  | $\mathrm{V}_{\mathrm{CCI}}$ | $\mathrm{V}_{\text {cco }}$ | $\begin{array}{\|c\|} \hline \begin{array}{l} \text { Operating free-air } \\ \text { temperature }\left(\mathrm{T}_{\mathrm{A}}\right) \end{array} \\ \hline-40^{\circ} \mathrm{C} \text { to } 125^{\circ} \mathrm{C} \\ \hline \end{array}$ |  |  | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  |  |  |  |
|  |  |  | MIN |  | TYP | MAX |  |
| TMAX-Maximum Data Rate | 50\% Duty Cycle Input One channel switching $20 \%$ of pulse $>0.7^{*} V_{\text {CCO }}$ $20 \%$ of pulse $<0.3^{*} \mathrm{~V}_{\text {Cco }}$ | Up Translation |  | $3.0 \mathrm{~V}-3.6 \mathrm{~V}$ | $4.5 \mathrm{~V}-5.5 \mathrm{~V}$ | 200 | 420 |  | Mbps |
|  |  |  | $2.25 \mathrm{~V}-2.75 \mathrm{~V}$ | $4.5 \mathrm{~V}-5.5 \mathrm{~V}$ | 150 | 300 |  |  |  |
|  |  |  | $1.65 \mathrm{~V}-1.95 \mathrm{~V}$ | $4.5 \mathrm{~V}-5.5 \mathrm{~V}$ | 100 | 200 |  |  |  |
|  |  |  | $1.1 \mathrm{~V}-1.3 \mathrm{~V}$ | $4.5 \mathrm{~V}-5.5 \mathrm{~V}$ | 20 | 40 |  |  |  |
|  |  |  | $1.65 \mathrm{~V}-1.95 \mathrm{~V}$ | $3.0 \mathrm{~V}-3.6 \mathrm{~V}$ | 100 | 210 |  |  |  |
|  |  |  | $1.1 \mathrm{~V}-1.3 \mathrm{~V}$ | $3.0 \mathrm{~V}-3.6 \mathrm{~V}$ | 10 | 20 |  |  |  |
|  |  |  | $1.1 \mathrm{~V}-1.3 \mathrm{~V}$ | $1.65 \mathrm{~V}-1.95 \mathrm{~V}$ | 5 | 10 |  |  |  |
|  |  | Down Translation | $4.5 \mathrm{~V}-5.5 \mathrm{~V}$ | $3.0 \mathrm{~V}-3.6 \mathrm{~V}$ | 100 | 210 |  |  |  |
|  |  |  | $4.5 \mathrm{~V}-5.5 \mathrm{~V}$ | $2.25 \mathrm{~V}-2.75 \mathrm{~V}$ | 75 | 140 |  |  |  |
|  |  |  | $4.5 \mathrm{~V}-5.5 \mathrm{~V}$ | $1.65 \mathrm{~V}-1.95 \mathrm{~V}$ | 50 | 75 |  |  |  |
|  |  |  | $4.5 \mathrm{~V}-5.5 \mathrm{~V}$ | $1.1 \mathrm{~V}-1.3 \mathrm{~V}$ | 15 | 30 |  |  |  |
|  |  |  | $3.0 \mathrm{~V}-3.6 \mathrm{~V}$ | $1.65 \mathrm{~V}-1.95 \mathrm{~V}$ | 40 | 75 |  |  |  |
|  |  |  | $3.0 \mathrm{~V}-3.6 \mathrm{~V}$ | $1.1 \mathrm{~V}-1.3 \mathrm{~V}$ | 10 | 20 |  |  |  |
|  |  |  | $1.65 \mathrm{~V}-1.95 \mathrm{~V}$ | $1.1 \mathrm{~V}-1.3 \mathrm{~V}$ | 5 | 10 |  |  |  |

### 6.13 Operating Characteristics

## $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}^{(1)}$

| PARAMETER |  | Test Conditions | Supply Voltage ( $\mathrm{V}_{\mathrm{CCB}}=\mathrm{V}_{\mathrm{CCA}}$ ) |  |  |  |  |  | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $1.2 \pm 0.1 \mathrm{~V}$ | $1.5 \pm 0.1 \mathrm{~V}$ | $1.8 \pm 0.15 \mathrm{~V}$ | $2.5 \pm 0.2 \mathrm{~V}$ | $3.3 \pm 0.3 \mathrm{~V}$ | $5.0 \pm 0.5 \mathrm{~V}$ |  |
|  |  | TYP | TYP | TYP | TYP | TYP | TYP |  |
| $\mathrm{C}_{\mathrm{pdA}}{ }^{(2)}$ | A to B |  | A Port$\begin{aligned} & \mathrm{CL}=0, \mathrm{RL}=\text { Open } \\ & \mathrm{f}=10 \mathrm{MHz} \\ & \mathrm{t}_{\text {rise }}=\mathrm{t}_{\text {fall }}=1 \mathrm{~ns} \end{aligned}$ | 3.2 | 3.4 | 3.5 | 3.7 | 3.9 | 5.1 | pF |
|  | B to A |  |  | 19.4 | 19.6 | 19.8 | 20.4 | 21.8 | 25.7 |  |
| $\mathrm{C}_{\mathrm{pdB}}{ }^{(2)}$ | A to B | $\begin{aligned} & \text { B Port } \\ & \mathrm{CL}=0, \mathrm{RL}=\text { Open } \\ & \mathrm{f}=10 \mathrm{MHz} \\ & \mathrm{t}_{\text {rise }}=\mathrm{t}_{\text {fall }}=1 \mathrm{~ns} \end{aligned}$ | 19.3 | 19.5 | 19.7 | 20.4 | 21.6 | 25.3 | pF |  |
|  | B to A |  | 3.3 | 3.5 | 3.6 | 4.0 | 4.4 | 5.0 |  |  |

(1) For more information about power dissipation capacitance, see the CMOS Power Consumption and $C_{p d}$ Calculation application report.
(2) $\mathrm{C}_{\mathrm{pdA}}$ and $\mathrm{C}_{\mathrm{pdB}}$ are repectively A-Port and B-Port power dissipation capacitances per transceiver.

### 6.14 Typical Characteristics



Figure 6-1. Typical $\left(\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}\right)$ Output High Voltage $\left(\mathrm{V}_{\mathrm{OH}}\right)$ vs Source Current ( $\mathrm{I}_{\mathrm{OH}}$ )


Figure 6-3. Typical $\left(\mathrm{T}_{\mathrm{A}}=\mathbf{2 5 ^ { \circ }} \mathrm{C}\right)$ Output High Voltage $\left(\mathrm{V}_{\mathrm{OL}}\right)$ vs Sink Current (lol)


Figure 6-5. Typical $\left(\mathrm{T}_{\mathrm{A}}=\mathbf{2 5 ^ { \circ }} \mathrm{C}\right)$ Supply Current $\left(\mathrm{I}_{\mathrm{Cc}}\right)$ vs Input Voltage ( $\mathrm{V}_{\mathrm{IN}}$ )


Figure 6-2. Typical $\left(\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}\right)$ Output High Voltage $\left(\mathrm{V}_{\mathrm{OH}}\right)$ vs Source Current ( $\mathrm{IOH}_{\mathrm{OH}}$


Figure 6-4. Typical $\left(\mathrm{T}_{\mathrm{A}}=\mathbf{2 5 ^ { \circ }} \mathrm{C}\right)$ Output High Voltage $\left(\mathrm{V}_{\mathrm{OL}}\right)$ vs Sink Current (loL)


Figure 6-6. Typical $\left(\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}\right)$ Supply Current $\left(\mathrm{I}_{\mathrm{cc}}\right)$ vs Input Voltage ( $\mathbf{V I N}_{\text {IN }}$ )

## 7 Parameter Measurement Information

### 7.1 Load Circuit and Voltage Waveforms

Unless otherwise noted, all input pulses are supplied by generators having the following characteristics:

- $\mathrm{f}=1 \mathrm{MHz}$
- $\mathrm{Z}_{\mathrm{O}}=50 \Omega$
- $\Delta \mathrm{t} / \Delta \mathrm{V} \leq 1 \mathrm{~ns} / \mathrm{V}$


1. $C_{L}$ includes probe and jig capacitance.

Figure 7-1. Load Circuit
Table 7-1. Load Circuit Conditions

| Parameter | $\mathbf{V}_{\mathbf{C c o}}$ | $\mathbf{R}_{\mathbf{L}}$ | $\mathbf{C}_{\mathbf{L}}$ | $\mathbf{S}_{\mathbf{1}}$ | $\mathbf{V}_{\mathbf{T P}}$ |
| :--- | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{t}_{\mathrm{pd}} \quad$ Propagation (delay) time | $1.1 \mathrm{~V}-5.5 \mathrm{~V}$ | $2 \mathrm{k} \Omega$ | 15 pF | Open | $\mathrm{N} / \mathrm{A}$ |
| $\mathrm{t}_{\text {en }}, \mathrm{t}_{\text {dis }}$ Enable time, disable time | $1.1 \mathrm{~V}-1.6 \mathrm{~V}$ | $2 \mathrm{k} \Omega$ | 15 pF | $2 \times \mathrm{V}_{\mathrm{CCO}}$ | 0.1 V |
|  | $1.65 \mathrm{~V}-2.7 \mathrm{~V}$ | $2 \mathrm{k} \Omega$ | 15 pF | $2 \times \mathrm{V}_{\mathrm{CCO}}$ | 0.15 V |
|  | $3.0 \mathrm{~V}-5.5 \mathrm{~V}$ | $2 \mathrm{k} \Omega$ | 15 pF | $2 \times \mathrm{V}_{\mathrm{CCO}}$ | 0.3 V |
|  | $1.1 \mathrm{~V}-1.6 \mathrm{~V}$ | $2 \mathrm{k} \Omega$ | 15 pF | GND | 0.1 V |
|  | $1.65 \mathrm{~V}-2.7 \mathrm{~V}$ | $2 \mathrm{k} \Omega$ | 15 pF | GND | 0.15 V |
|  | $3.0 \mathrm{~V}-5.5 \mathrm{~V}$ | $2 \mathrm{k} \Omega$ | 15 pF | GND | 0.3 V |

Input A, B


1. $\mathrm{V}_{\mathrm{CCI}}$ is the supply pin associated with the input port.
2. $\mathrm{V}_{\mathrm{OH}}$ and $\mathrm{V}_{\mathrm{OL}}$ are typical output voltage levels that occur with specified $R_{L}, C_{L}$, and $S_{1}$

Input A, B


1. $\mathrm{V}_{\mathrm{CCI}}$ is the supply pin associated with the input port.
2. $\mathrm{V}_{\mathrm{OH}}$ and $\mathrm{V}_{\mathrm{OL}}$ are typical output voltage levels that occur with specified $R_{L}, C_{L}$, and $S_{1}$
Figure 7-3. Input Transition Rise and Fall Rate

Figure 7-2. Propagation Delay


1. Illustrative purposes only. Enable time is a calculation as described in Enable Times.
2. Output waveform on the condition that input is driven to a valid Logic low.
3. Output waveform on the condition that input is driven to a valid Logic high.
4. $\quad \mathrm{V}_{\mathrm{CCI}}$ is the supply pin associated with the input port.
5. $\quad \mathrm{V}_{\mathrm{CCO}}$ is the supply pin associated with the output port.
6. $V_{O H}$ and $V_{O L}$ are typical output voltage levels with specified $R_{L}, C_{L}$, and $S_{1}$.

Figure 7-4. Enable Time And Disable Time

## 8 Detailed Description

### 8.1 Overview

The SN74LXC1T45-Q1 is a 1-bit translating transceiver that uses two individually configurable power-supply rails. The device is operational with both $\mathrm{V}_{\mathrm{CCA}}$ and $\mathrm{V}_{\mathrm{CCB}}$ supplies as low as 1.1 V and as high as 5.5 V . Additionally, the device can be operated with $\mathrm{V}_{\mathrm{CCA}}=\mathrm{V}_{\mathrm{CCB}}$. The A port is designed to track $\mathrm{V}_{\mathrm{CCA}}$, and the B port is designed to track $\mathrm{V}_{\mathrm{CCB}}$.
The SN74LXC1T45-Q1 device is designed for asynchronous communication between devices and transmits data from $A$ to $B$ or from $B$ to $A$ based on the logic level of the direction-control input (DIR). The control pins of the SN74LXC1T45-Q1 (DIR) is referenced to $V_{\text {CCA }}$. The input circuitry on both $A$ and $B$ ports is always active and must have a logic HIGH or LOW level applied to prevent excess ICC and ICCZ.
This device is fully specified for partial-power-down applications using the $\mathrm{I}_{\text {off }}$ current. The $\mathrm{I}_{\text {off }}$ protection circuitry ensures that no excessive current is drawn from or sourced into an input, output, or I/O while the device is powered down.

The $\mathrm{V}_{\mathrm{CC}}$ isolation or $\mathrm{V}_{\mathrm{CC}}$ disconnect feature ensures that if either $\mathrm{V}_{\mathrm{CC}}$ is less than 100 mV or disconnected with the complementary supply within the recommended operating conditions, then both I/O ports are weakly pulled-down and then set to the high-impedance state by disabling their outputs while the supply current is maintained. The $\mathrm{I}_{\text {off-float }}$ circuitry ensures that no excessive current is drawn from or sourced into an input, output, or I/O while the supply is floating.
Glitch-free power supply sequencing allows either supply rail to be powered on or off in any order while providing robust power sequencing performance.

### 8.2 Functional Block Diagram



### 8.3 Feature Description

### 8.3.1 CMOS Schmitt-Trigger Inputs with Integrated Pulldowns

Standard CMOS inputs are high impedance and are typically modeled as a resistor in parallel with the input capacitance given in the Electrical Characteristics. The worst case resistance is calculated with the maximum input voltage, given in the Absolute Maximum Ratings, and the maximum input leakage current, given in the Electrical Characteristics, using ohm's law ( $\mathrm{R}=\mathrm{V} \div \mathrm{I}$ ).

The Schmitt-trigger input architecture provides hysteresis as defined by $\Delta \mathrm{V}_{\mathrm{T}}$ in the Electrical Characteristics, which makes this device extremely tolerant to slow or noisy inputs. Driving the inputs slowly will increase dynamic current consumption of the device. For additional information regarding Schmitt-trigger inputs, see Understanding Schmitt Triggers.

### 8.3.1.1 I/O's with Integrated Dynamic Pull-Down Resistors

Input circuits of the data I/O's are always active even when the device is disabled. It is recommended to keep a valid voltage level at the I/O's to avoid high current consumption. To help avoid floating inputs on the I/O's during disabling, this device has $100-\mathrm{k} \Omega$ typical integrated weak dynamic pull-downs on all data I/O's. When the device is disabled, the dynamic pull-downs are activated for only a short period of time to help drive and keep low any floating inputs before the device I/O's become high impedance. If the I/O lines are floated after the device is disabled, then it is recommended to keep them at a valid input voltage level using the external pull-downs. This feature is ideal for loads of 30 pF or less. If greater capactive loading is present, then external pull-downs are recommended. If an external pull-up is required, then it should be no larger than $15 \mathrm{k} \Omega$ to avoid contention with the $100 \mathrm{k} \Omega$ internal pull-down.

### 8.3.1.2 Control Inputs with Integrated Static Pull-Down Resistors

Similar to the data I/O's, a floating control input can cause high current consumption. To help avoid this concern, this device has integrated weak static pull-downs of $5-\mathrm{M} \Omega$ typical on the control input (DIR). These pull-downs are always present. For example, if the DIR pin is left floating, then the $B$ port will be configured as an input and the A port configured as an output.

### 8.3.2 Balanced High-Drive CMOS Push-Pull Outputs

A balanced output allows the device to sink and source similar currents. The high drive capability of this device creates fast edges into light loads, so routing and load conditions should be considered to prevent ringing. Additionally, the outputs of this device are capable of driving larger currents than the device can sustain without being damaged. The electrical and thermal limits defined in the Absolute Maximum Ratings must be followed at all times.

### 8.3.3 Partial Power Down (loff)

The inputs and outputs for this device enter a high-impedance state when the device is powered down, inhibiting current backflow into the device. The maximum leakage into or out of any input or output pin on the device is specified by Ioff in the Electrical Characteristics.

### 8.3.4 $\mathrm{V}_{\mathrm{cc}}$ Isolation and $\mathbf{V}_{\mathbf{c c}}$ Disconnect (loff-float)

This device has I/O's with Integrated Dynamic Pull-Down Resistors. The I/O's will get pulled down and then enter a high-impedance state when either supply is $<100 \mathrm{mV}$ or left floating (disconnected), while the other supply is still connected to the device. It is recommended that the I/O's for this device are not driven and kept at a logic low state prior to floating (disconnecting) either supply.
The maximum supply current is specified by $\mathrm{I}_{\mathrm{CC}}$, while $\mathrm{V}_{\mathrm{CCx}}$ is floating, in the Electrical Characteristics. The maximum leakage into or out of any input or output pin on the device is specified by $\mathrm{I}_{\text {off(float) }}$ in the Electrical Characteristics.


Figure 8-1. $\mathrm{V}_{\mathrm{CC}}$ Disconnect Feature

### 8.3.5 Over-Voltage Tolerant Inputs

Input signals to this device can be driven above the supply voltage so long as they remain below the maximum input voltage value specified in the Recommended Operating Conditions.

### 8.3.6 Glitch-Free Power Supply Sequencing

Either supply rail may be powered on or off in any order without producing a glitch on the I/Os (that is, where the output erroneously transitions to VCC when it should be held low or vice versa). Glitches of this nature can be misinterpreted by a peripheral as a valid data bit, which could trigger a false device reset of the peripheral, a false device configuration of the peripheral, or even a false data initialization by the peripheral.

### 8.3.7 Negative Clamping Diodes

Figure $8-2$ shows the inputs and outputs to this device that have negative clamping diodes.

## CAUTION

Voltages beyond the values specified in the Absolute Maximum Ratings table can cause damage to the device. The input negative voltage and output voltage ratings may be exceeded if the input and output clamp current ratings are observed.


Figure 8-2. Electrical Placement of Clamping Diodes for Each Input and Output

### 8.3.8 Fully Configurable Dual-Rail Design

Both the $\mathrm{V}_{\mathrm{CCA}}$ and $\mathrm{V}_{\text {CCB }}$ pins can be supplied at any voltage from 1.1 V to 5.5 V , making the device suitable for translating between any of the voltage nodes ( $1.2 \mathrm{~V}, 1.5 \mathrm{~V}, 1.8 \mathrm{~V}, 3.3 \mathrm{~V}$, and 5.0 V ).

### 8.3.9 Supports High-Speed Translation

The SN74LXC1T45-Q1 device can support high data rate applications. The translated signal data rate can be up to 420 Mbps when the signal is translated from 3.3 V to 5.0 V .

### 8.4 Device Functional Modes

Table 8-1. Function Table

| CONTROL INPUTS ${ }^{(1)}$ | PORT STATUS |  | OPERATION |
| :---: | :---: | :---: | :---: |
| DIR | A PORT | B PORT |  |
| L | Output (Enabled) <br> Input (Hi-Z) | Input (Hi-Z) <br> Output (Enabled) | B data to A bus <br> A data to B bus |

(1) Input circuits of the data I/Os are always active and should be kept at a valid logic level.

## 9 Application and Implementation


#### Abstract

Note Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. Tl's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.


### 9.1 Application Information

The SN74LXC1T45-Q1 device can be used in level-translation applications for interfacing devices or systems operating at different interface voltages with one another. The SN74LXC1T45-Q1 device is ideal for use in applications where a push-pull driver is connected to the data I/O. The maximum data rate can be up to 420 Mbps when the device translates a signal from 3.3 V to 5.0 V .

### 9.2 Enable Times

Calculate the enable times for the SN74LXC1T45-Q1 using the following formulas:

$$
\begin{align*}
& \left.\mathrm{t}_{\mathrm{A}_{\mathrm{e}}}(\text { DIR to } \mathrm{A})=\mathrm{t}_{\text {dis }} \text { (DIR to } \mathrm{B}\right)+\mathrm{t}_{\text {pd }}(\mathrm{B} \text { to } \mathrm{A})  \tag{1}\\
& \left.\mathrm{t}_{\mathrm{B} \_ \text {en }}(\text { DIR to } \mathrm{B})=\mathrm{t}_{\text {dis }} \text { (DIR to } \mathrm{A}\right)+\mathrm{t}_{\text {pd }}(\mathrm{A} \text { to B) } \tag{2}
\end{align*}
$$

In a bidirectional application, these enable times provide the maximum delay time from the time the DIR bit is switched until an output is expected. For example, if the SN74LXC1T45-Q1 initially is transmitting from A to B, then the DIR bit is switched; the B port of the device must be disabled ( $\mathrm{t}_{\text {dis }}$ ) before presenting it with an input. After the B port has been disabled, an input signal applied to it appears on the corresponding A port after the specified propagation delay ( $\mathrm{t}_{\text {pd }}$ ). To avoid bus contention, care should be taken to not apply an input signal prior to the output being disabled ( $\mathrm{t}_{\text {dis }}$ maximum).

### 9.3 Typical Application



Figure 9-1. LED Driver Application

### 9.3.1 Design Requirements

For this design example, use the parameters listed in Table 9-1.
Table 9-1. Design Parameters

| DESIGN PARAMETERS | EXAMPLE VALUES |
| :---: | :---: |
| Input voltage range | 1.1 V to 5.5 V |
| Output voltage range | 1.1 V to 5.5 V |

### 9.3.2 Detailed Design Procedure

To begin the design process, determine the following:

- Input voltage range
- Use the supply voltage of the device that is driving the SN74LXC1T45-Q1 device to determine the input voltage range. For a valid logic-high, the value must exceed the positive-going input-threshold voltage $\left(\mathrm{V}_{\mathrm{t}}\right)$ of the input port. For a valid logic low the value must be less than the negative-going input-threshold voltage $\left(\mathrm{V}_{\mathrm{t}}\right.$ ) of the input port.
- Output voltage range
- Use the supply voltage of the device that the SN74LXC1T45-Q1 device is driving to determine the output voltage range.


## 10 Power Supply Recommendations

Always apply a ground reference to the GND pins first. This device is designed for glitch free power sequencing without any supply sequencing requirements such as ramp order or ramp rate.
This device was designed with various power supply sequencing methods in mind to help prevent unintended triggering of downstream devices, as described in Glitch-free Power Supply Sequencing.

## 11 Layout

### 11.1 Layout Guidelines

To ensure reliability of the device, the following common printed-circuit board layout guidelines are recommended:

- Use bypass capacitors on the power supply pins and place them as close to the device as possible. A 0.1 $\mu \mathrm{F}$ capacitor is recommended, but transient performance can be improved by having both $1 \mu \mathrm{~F}$ and $0.1 \mu \mathrm{~F}$ capacitors in parallel as bypass capacitors.
- The high drive capability of this device creates fast edges into light loads so routing and load conditions should be considered to prevent ringing.


### 11.2 Layout Example



Figure 11-1. Layout Example - SN74LXC1T45-Q1

## 12 Device and Documentation Support

### 12.1 Device Support

### 12.1.1 Regulatory Requirements

No statutory or regulatory requirements apply to this device.
There are no special characteristics for this product.

### 12.2 Documentation Support

### 12.2.1 Related Documentation

For related documentation, see the following:

- Texas Instruments, Understanding Schmitt Triggers application report


### 12.3 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on Subscribe to updates to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

### 12.4 Support Resources

TI E2E ${ }^{\text {TM }}$ support forums are an engineer's go-to source for fast, verified answers and design help - straight from the experts. Search existing answers or ask your own question to get the quick design help you need.
Linked content is provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect Tl's views; see TI's Terms of Use.

### 12.5 Trademarks

TI E2E ${ }^{\text {TM }}$ is a trademark of Texas Instruments.
All trademarks are the property of their respective owners.

### 12.6 Electrostatic Discharge Caution

This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.
ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

### 12.7 Glossary

TI Glossary This glossary lists and explains terms, acronyms, and definitions.

## 13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

INSTRUMENTS

## PACKAGING INFORMATION

| Orderable Device | Status <br> (1) | Package Type | Package Drawing | Pins | Package Qty | Eco Plan <br> (2) | Lead finish/ Ball material <br> (6) | MSL Peak Temp <br> (3) | Op Temp ( ${ }^{\circ} \mathrm{C}$ ) | Device Marking <br> (4/5) | Samples |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| SN74LXC1T45QDCKRQ1 | ACTIVE | SC70 | DCK | 6 | 3000 | RoHS \& Green | NIPDAU | Level-1-260C-UNLIM | -40 to 125 | 2NMT | Samples |
| SN74LXC1T45QDRYRQ1 | ACTIVE | SON | DRY | 6 | 5000 | RoHS \& Green | NIPDAU | Level-1-260C-UNLIM | -40 to 125 | MI | Samples |

${ }^{(1)}$ The marketing status values are defined as follows:
ACTIVE: Product device recommended for new designs.
LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
NRND: Not recommended for new designs. Device is in production to support existing customers, but Tl does not recommend using this part in a new design.
PREVIEW: Device has been announced but is not in production. Samples may or may not be available.
OBSOLETE: TI has discontinued the production of the device.
${ }^{(2)}$ RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed $0.1 \%$ by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free"
RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption
Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement
${ }^{(3)}$ MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature
${ }^{(4)}$ There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
${ }^{(5)}$ Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a " $\sim$ " will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
${ }^{(6)}$ Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

Important Information and Disclaimer:The information provided on this page represents Tl's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

OTHER QUALIFIED VERSIONS OF SN74LXC1T45-Q1 :

- Catalog : SN74LXC1T45

NOTE: Qualified Version Definitions:

- Catalog - TI's standard catalog product

TAPE AND REEL INFORMATION


TAPE DIMENSIONS


| A0 | Dimension designed to accommodate the component width |
| :---: | :--- |
| B0 | Dimension designed to accommodate the component length |
| K0 | Dimension designed to accommodate the component thickness |
| W | Overall width of the carrier tape |
| P1 | Pitch between successive cavity centers |

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

*All dimensions are nominal

| Device | Package <br> Type | Package <br> Drawing | Pins | SPQ | Reel <br> Diameter <br> $(\mathbf{m m})$ | Reel <br> Width <br> W1 $(\mathbf{m m})$ | A0 <br> $(\mathbf{m m})$ | B0 <br> $(\mathbf{m m})$ | K0 <br> $(\mathbf{m m})$ | P1 <br> $(\mathbf{m m})$ | W <br> $(\mathbf{m m})$ | Pin1 <br> Quadrant |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| SN74LXC1T45QDCKRQ1 | SC70 | DCK | 6 | 3000 | 178.0 | 9.0 | 2.4 | 2.5 | 1.2 | 4.0 | 8.0 | Q3 |
| SN74LXC1T45QDRYRQ1 | SON | DRY | 6 | 5000 | 180.0 | 9.5 | 1.2 | 1.65 | 0.7 | 4.0 | 8.0 | Q1 |


*All dimensions are nominal

| Device | Package Type | Package Drawing | Pins | SPQ | Length (mm) | Width (mm) | Height (mm) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| SN74LXC1T45QDCKRQ1 | SC70 | DCK | 6 | 3000 | 190.0 | 190.0 | 30.0 |
| SN74LXC1T45QDRYRQ1 | SON | DRY | 6 | 5000 | 189.0 | 185.0 | 36.0 |



Images above are just a representation of the package family, actual package may vary. Refer to the product data sheet for package details.


4222207/B 02/2016
NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.


NOTES: (continued)
3. For more information, see QFN/SON PCB application report in literature No. SLUA271 (www.ti.com/lit/slua271).


SOLDER PASTE EXAMPLE BASED ON 0.075-0.1 mm THICK STENCIL

SCALE:40X

## NOTES: (continued)

4. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

DCK (R-PDSO-G6)

## PLASTIC SMALL-OUTLINE PACKAGE



NOTES: A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Body dimensions do not include mold flash or protrusion. Mold flash and protrusion shall not exceed 0.15 per side.
D. Falls within JEDEC MO-203 variation AB.

DCK (R-PDSO-G6)


NOTES: A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Customers should place a note on the circuit board fabrication drawing not to alter the center solder mask defined pad.
D. Publication IPC-7351 is recommended for alternate designs.
E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Example stencil design based on a $50 \%$ volumetric metal load solder paste. Refer to IPC-7525 for other stencil recommendations.

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