

## DESCRIPTION

The MP8716 is a high frequency synchronous rectified step-down switch mode converter with built in internal power MOSFETs. It offers a very compact solution to achieve 3A continuous output current over a wide input supply range with excellent load and line regulation. The MP8716 has synchronous mode operation for higher efficiency over output current load range.

Current mode operation provides fast transient response and eases loop stabilization.

Full protection features include OCP and thermal shut down.

The MP8716 requires a minimum number of readily available standard external components and is available in a space saving 8-pin SOIC package with an exposed pad.

## FEATURES

- Wide 4.5V to 21V Operating Input Range
- 3A Output Current
- Low Rds(on) Internal Power MOSFETs
- Proprietary Switching Loss Reduction Technique
- High Efficiency Synchronous Mode Operation
- Fixed 500kHz Switching Frequency
- Sync from 300kHz to 2MHz External Clock
- 1.5ms Internal Soft-Start Time
- Internal Compensation
- OCP Protection and Hiccup
- Thermal Shutdown
- Output Adjustable from 0.8V
- Available in a Thermally Enhanced 8-pin SOIC package

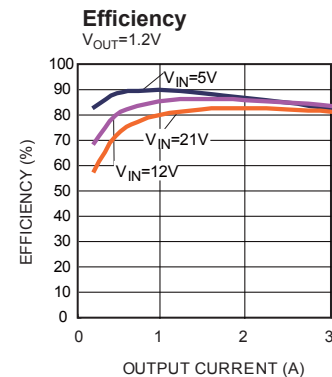
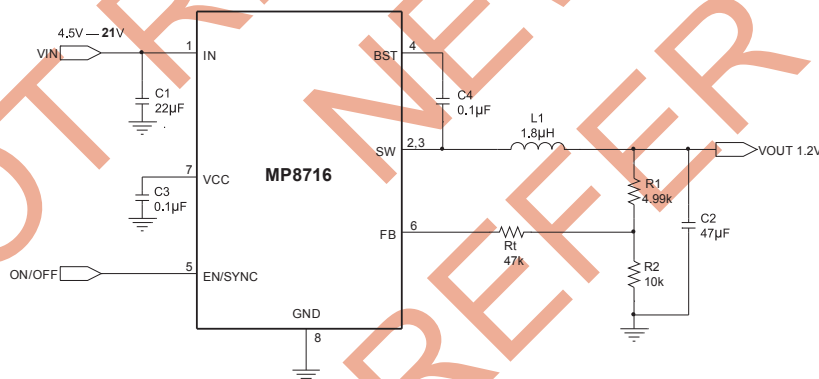
## APPLICATIONS

- Notebook Systems and I/O Power
- Networking Systems
- Digital Set Top Boxes
- Personal Video Recorders
- Flat Panel Television and Monitors
- Distributed Power Systems

"MPS" and "The Future of Analog IC Technology" are Registered Trademarks of Monolithic Power Systems, Inc.

The information in this datasheet about the product and its associated technologies are proprietary and intellectual property of Monolithic Power Systems and are protected by copyright and pending patent applications

## TYPICAL APPLICATION

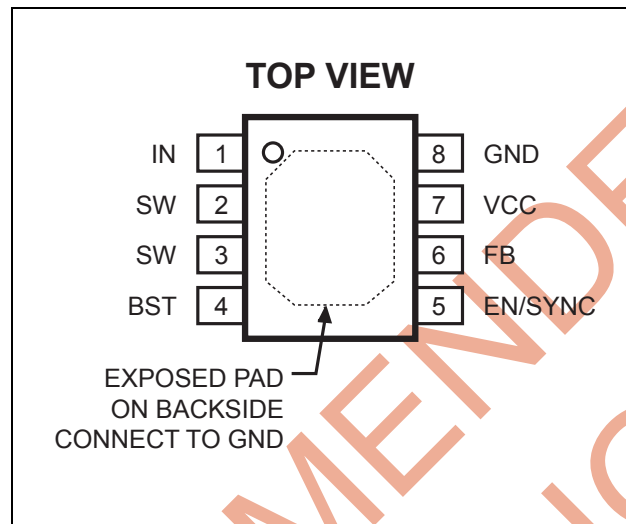


### ORDERING INFORMATION

Part Number*	Package	Top Marking	Free Air Temperature (T <sub>A</sub> )
MP8716EN	SOIC8E	MP8716EN	-20°C to +85°C

\* For Tape & Reel, add suffix -Z (e.g. MP8716EN-Z);  
 For RoHS compliant packaging, add suffix -LF; (e.g. MP8716EN-LF-Z)

### PACKAGE REFERENCE



#### ABSOLUTE MAXIMUM RATINGS <sup>(1)</sup>

Supply Voltage V <sub>IN</sub> .....	22V
V <sub>SW</sub> .....	-0.3V (-5V for < 10ns) to 23V
V <sub>BS</sub> .....	V <sub>SW</sub> + 6V
All Other Pins .....	-0.3V to +6V
Operating Temperature .....	-20°C to +85°C
Continuous Power Dissipation (T <sub>A</sub> = +25°C) <sup>(2)</sup>	2.5W
Junction Temperature .....	150°C
Lead Temperature .....	260°C
Storage Temperature .....	-65°C to +150°C

#### Recommended Operating Conditions <sup>(3)</sup>

Supply Voltage V <sub>IN</sub> .....	4.5V to 21V
Operating Junct. Temp (T <sub>J</sub> ) .....	-20°C to +125°C

Thermal Resistance <sup>(4)</sup>	$\theta_{JA}$	$\theta_{JC}$
SOIC8E (Exposed Pad) .....	50	10 ... °C/W

#### Notes:

- Exceeding these ratings may damage the device.
- The maximum allowable power dissipation is a function of the maximum junction temperature T<sub>J</sub>(MAX), the junction-to-ambient thermal resistance  $\theta_{JA}$ , and the ambient temperature T<sub>A</sub>. The maximum allowable continuous power dissipation at any ambient temperature is calculated by P<sub>D</sub>(MAX)=(T<sub>J</sub>(MAX)-T<sub>A</sub>)/ $\theta_{JA}$ . Exceeding the maximum allowable power dissipation will cause excessive die temperature, and the regulator will go into thermal shutdown. Internal thermal shutdown circuitry protects the device from permanent damage.
- The device is not guaranteed to function outside of its operating conditions.
- Measured on JESD51-7, 4-layer PCB.

## ELECTRICAL CHARACTERISTICS

$V_{IN} = 12V$ ,  $T_A = +25^{\circ}C$ , unless otherwise noted.

Parameters	Symbol	Condition	Min	Typ	Max	Units
Supply Current (Shutdown)	$I_{IN}$	$V_{EN} = 0V$			10	$\mu A$
Supply Current (Quiescent)	$I_Q$	$V_{EN} = 2V$ , $V_{FB} = 1V$		0.7		mA
HS Switch On Resistance <sup>(5)</sup>	$HS_{RDS-ON}$			120		m $\Omega$
LS Switch On Resistance <sup>(5)</sup>	$LS_{RDS-ON}$			20		m $\Omega$
Switch Leakage	$SW_{LKG}$	$V_{EN} = 0V$ , $V_{SW} = 0V$ or $12V$		0	10	$\mu A$
Current Limit <sup>(5)</sup>	$I_{LIMIT}$			6.1		A
Oscillator Frequency	$F_{SW}$	$V_{FB} = 0.75V$	425	500	575	kHz
Fold-back Frequency	$F_{FB}$	$V_{FB} = 300mV$		0.25		f <sub>sw</sub>
Maximum Duty Cycle	$D_{MAX}$	$V_{FB} = 700mV$	85	90		%
Sync Frequency Range	$F_{SYNC}$		0.3		2	MHz
Feedback Voltage	$V_{FB}$	$T_A = -20^{\circ}C$ to $+85^{\circ}C$	789	805	821	mV
Feedback Current	$I_{FB}$	$V_{FB} = 800mV$		10	50	nA
EN Rising Threshold	$V_{EN\_RISING}$		1.1	1.3	1.6	V
EN Threshold Hysteresis	$V_{EN\_HYS}$			0.4		V
EN Input Current	$I_{EN}$	$V_{EN} = 2V$		2		$\mu A$
		$V_{EN} = 0V$		0		
EN Turn Off Delay	$EN_{Td-Off}$			5		$\mu s$
$V_{IN}$ Under Voltage Lockout Threshold Rising	$INUV_{Vth}$		3.8	4.0	4.2	V
$V_{IN}$ Under Voltage Lockout Threshold Hysteresis	$INUV_{HYS}$			880		mV
VCC Regulator	$V_{CC}$			5		V
VCC Load Regulation		$I_{CC}=2mA$		5		%
Soft-Start Period				1.5	2	ms
Thermal Shutdown	$T_{SD}$			150		$^{\circ}C$

**Note:**

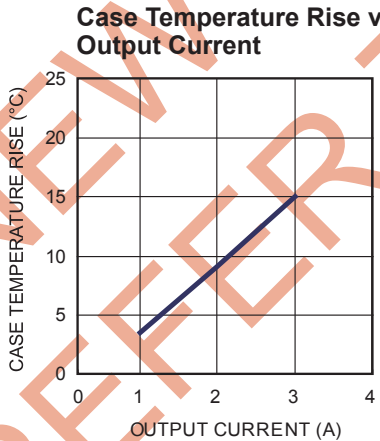
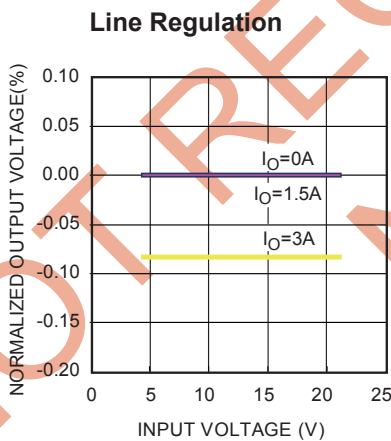
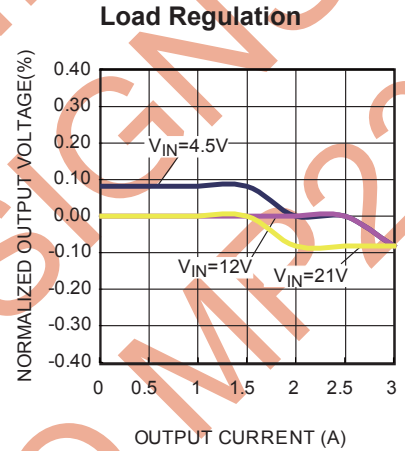
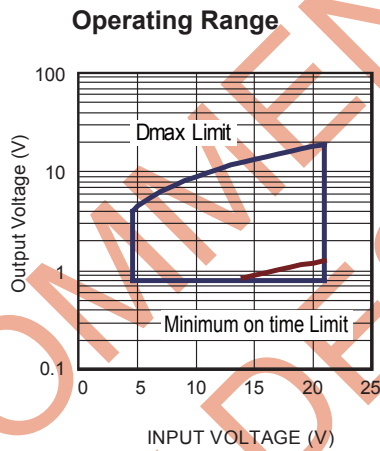
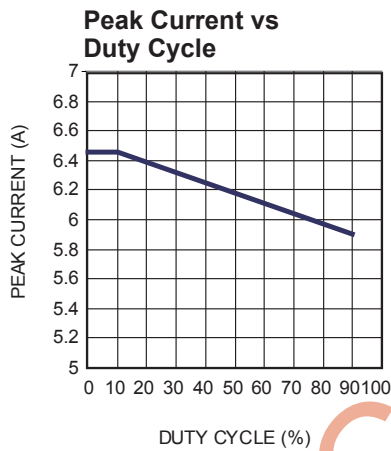
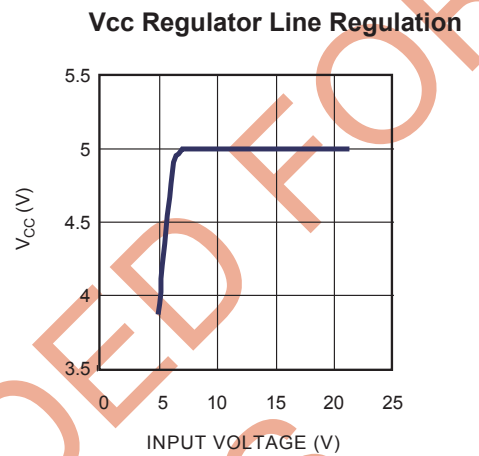
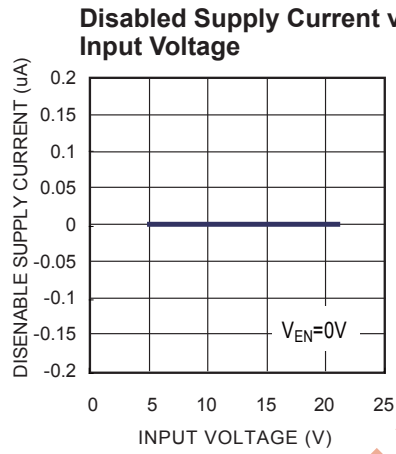
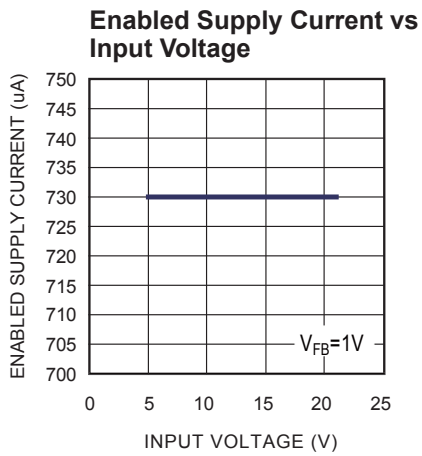
5) Guaranteed by design.

## PIN FUNCTIONS

Pin #	Name	Description
1	IN	Supply Voltage. The MP8716 operates from a +4.5V to +21V input rail. C1 is needed to decouple the input rail. Use wide PCB trace to make the connection.
2,3	SW	Switch Output. Use wide PCB trace to make the connection.
4	BST	Bootstrap. A capacitor connected between SW and BS pins is required to form a floating supply across the high-side switch driver.
5	EN/SYNC	EN=1 to enable the chip. External clock can be applied to EN pin for changing switching frequency. For automatic start-up, connect EN pin to VIN by proper EN resistor divider as Figure 2 shows.
6	FB	Feedback. An external resistor divider from the output to GND, tapped to the FB pin, sets the output voltage. To prevent current limit run away during a short circuit fault condition the frequency fold-back comparator lowers the oscillator frequency when the FB voltage is below 500mV.
7	VCC	Bias Supply. Decouple with 0.1uF~0.22uF cap. And the capacitance should be no more than 0.22uF
8	GND, Exposed Pad	System Ground. This pin is the reference ground of the regulated output voltage. For this reason care must be taken in PCB layout. Suggested to be connected to GND with copper and vias.

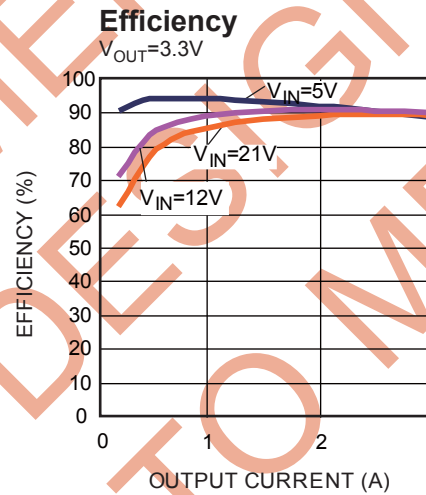
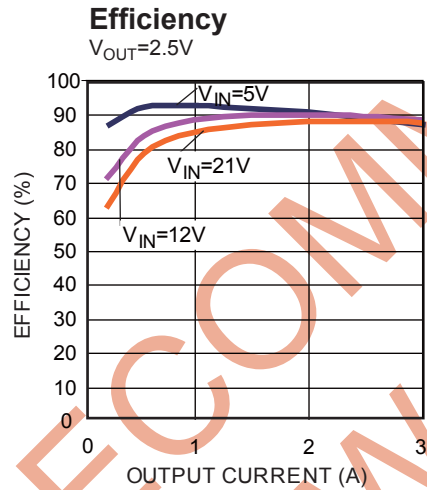
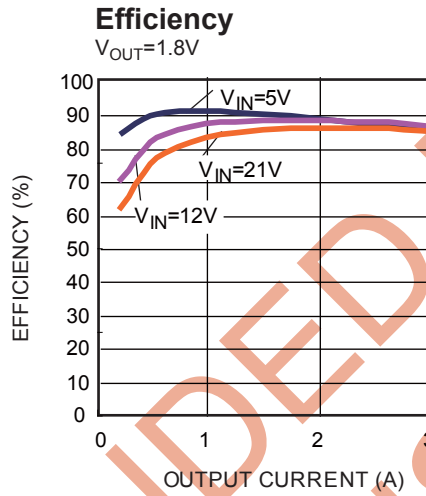
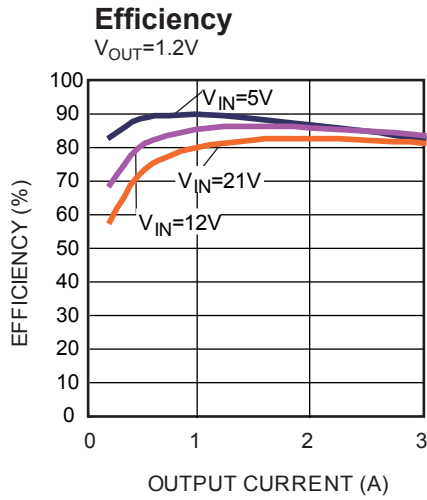
### TYPICAL PERFORMANCE CHARACTERISTICS

$V_{IN} = 12V$ ,  $V_{OUT} = 1.2V$ ,  $L=1.8\mu H$ ,  $T_A = +25^\circ C$ , unless otherwise noted.

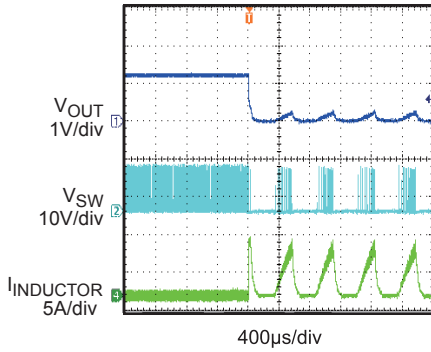
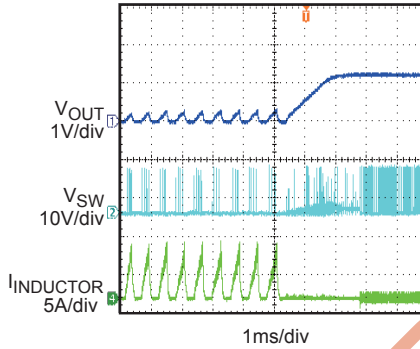
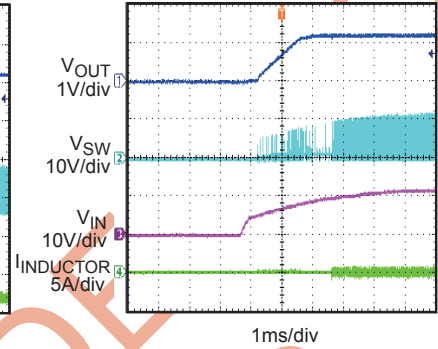
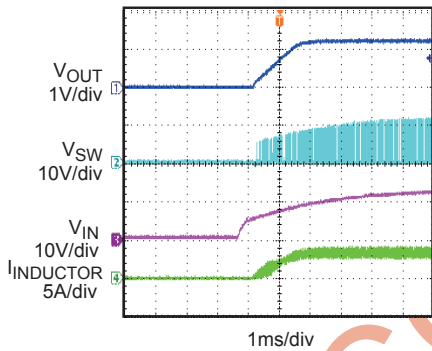
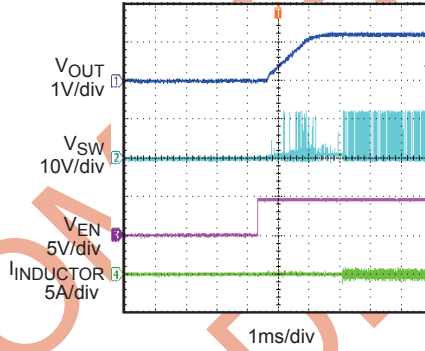
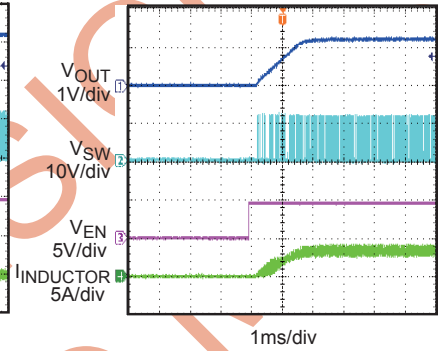
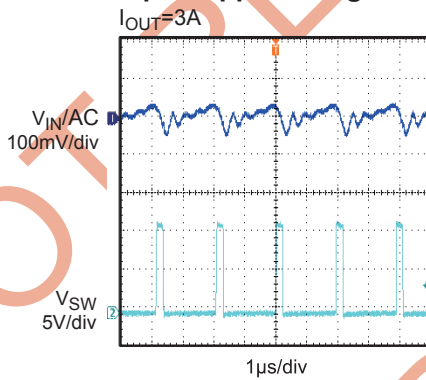
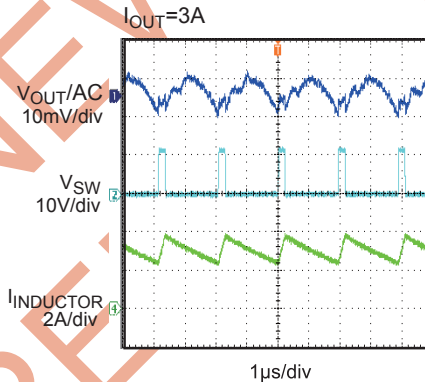
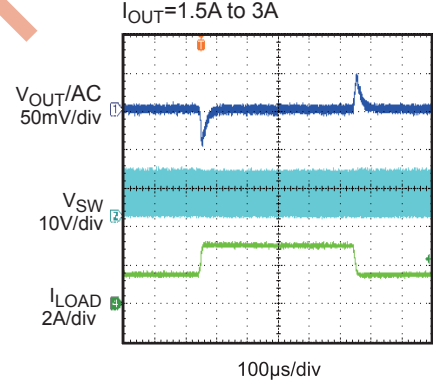


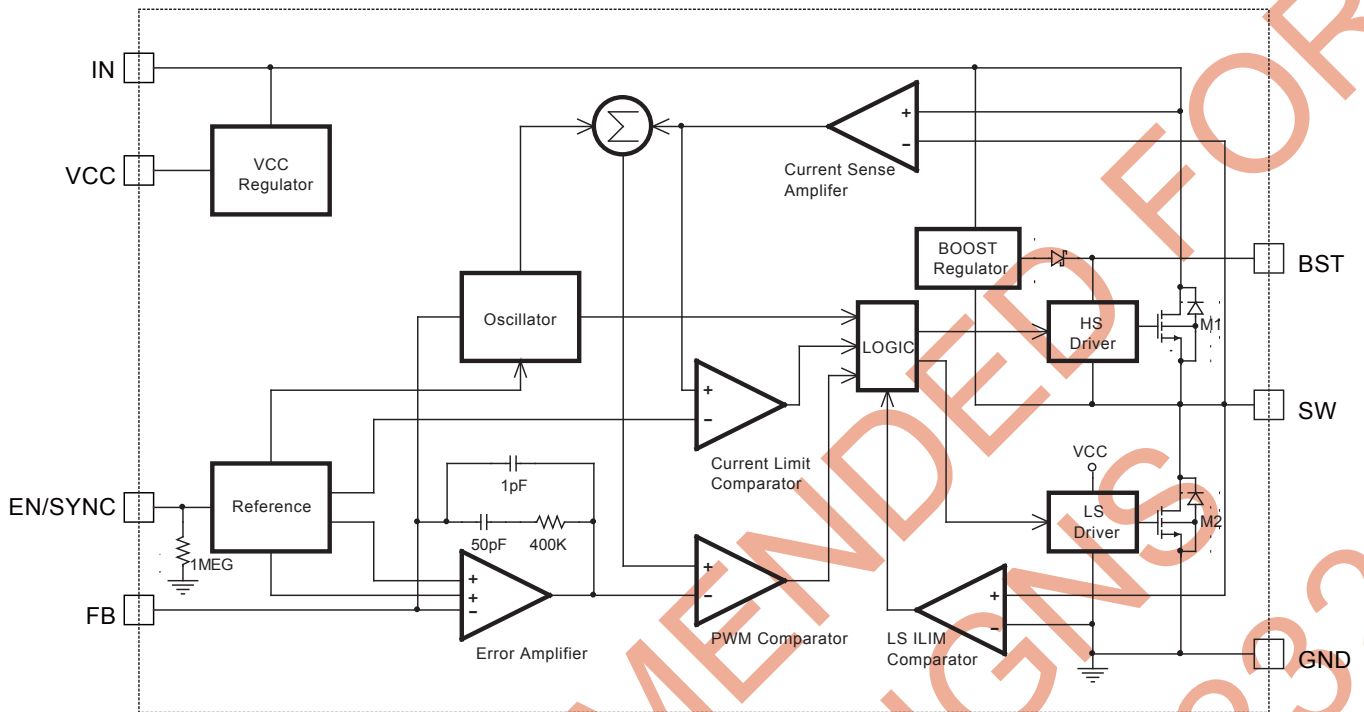
**TYPICAL PERFORMANCE CHARACTERISTICS** *(continues)*

$V_{IN} = 12V$ ,  $V_{OUT} = 1.2V$ ,  $L=1.8\mu H$ ,  $T_A = +25^\circ C$ , unless otherwise noted.



**TYPICAL PERFORMANCE CHARACTERISTICS (continues)**
 $V_{IN} = 12V$ ,  $V_{OUT} = 1.2V$ ,  $L=1.8\mu H$ ,  $T_A = +25^\circ C$ , unless otherwise noted.

**Short Entry**

**Short Recovery**

**Power up without Load**

**Power up with 3A Load**

**Enable Startup without Load**

**Enable Startup with 3A Load**

**Input Ripple Voltage**

**Output Ripple Voltage**

**Load Transient Response**


**BLOCK DIAGRAM**

**Figure 1—Functional Block Diagram**



## OPERATION

The MP8716 is a high frequency synchronous rectified step-down switch mode converter with built in internal power MOSFETs. It offers a very compact solution to achieve 3A continuous output current over a wide input supply range with excellent load and line regulation.

The MP8716 operates in a fixed frequency, peak current control mode to regulate the output voltage. A PWM cycle is initiated by the internal clock. The integrated high-side power MOSFET is turned on and remains on until its current reaches the value set by the COMP voltage. When the power switch is off, it remains off until the next clock cycle starts. If, in 90% of one PWM period, the current in the power MOSFET does not reach the COMP set current value, the power MOSFET will be forced to turn off

### Internal Regulator

Most of the internal circuitries are powered from the 5V internal regulator. This regulator takes the VIN input and operates in the full VIN range. When VIN is greater than 5.0V, the output of the regulator is in full regulation. When VIN is lower than 5.0V, the output decreases, a 0.1uF ceramic capacitor for decoupling purpose is required.

### Error Amplifier

The error amplifier compares the FB pin voltage with the internal 0.805V reference (REF) and outputs a current proportional to the difference between the two. This output current is then used to charge or discharge the internal compensation network to form the COMP voltage, which is used to control the power MOSFET current. The optimized internal compensation network minimizes the external component counts and simplifies the control loop design.

### Enable/Sync Control

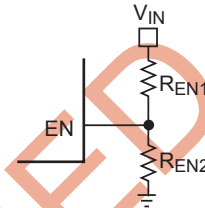
EN/Sync is a digital control pin that turns the regulator on and off. Drive EN high to turn on the regulator, drive it low to turn it off. There is an internal 1MEG resistor from EN/Sync to GND thus EN/Sync can be floated to shut down the chip.

1) Enabled by external logic H/L signal

The chip starts up once the enable signal goes higher than EN/SYNC input high voltage (2V), and is shut down when the signal is lower than

EN/SYNC input low voltage (0.4V). To disable the chip, EN must be pulled low for at least 5μs. The input is compatible with both CMOS and TTL.

2) Enabled by Vin through voltage divider. Connect EN with Vin through a resistive voltage divider for automatic startup as the figure 2 shows.



**Figure 2—Enable Divider Circuit**

Choose the value of the pull-up resistor  $R_{EN1}$  and pull-down resistor  $R_{EN2}$  to reset the automatic start-up voltage:

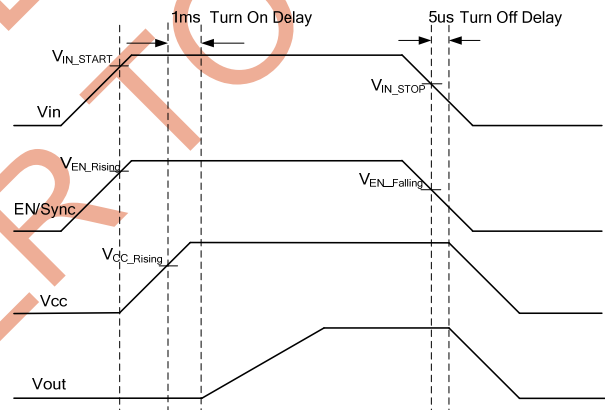
$$V_{IN\_START} = V_{EN\_RISING} \cdot \frac{(R_{EN1} + R_{EN2} \parallel 1M\Omega)}{R_{EN2} \parallel 1M\Omega}$$

Where  $V_{EN\_RISING}$  is 1.3V

$$V_{IN\_STOP} = V_{EN\_FALLING} \cdot \frac{(R_{EN1} + R_{EN2} \parallel 1M\Omega)}{R_{EN2} \parallel 1M\Omega}$$

Where  $V_{EN\_FALLING}$  is 0.9V

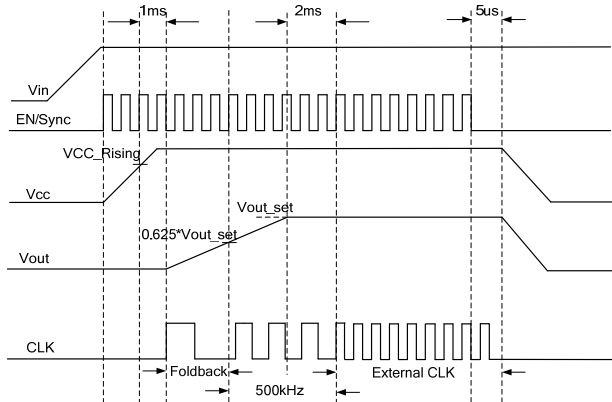
For example,  $R_{EN1}=100k\Omega$  and  $R_{EN2}=20k\Omega$ , the  $V_{IN\_START}$  is set at 7.9V,  $V_{IN\_STOP}$  is set at 5.49V. The startup sequence is as below using the EN divider.  $V_{CC\_Rising}$  is the VCC UVLO rising threshold which is about 4.0V.



**Figure 3—Startup Sequence Using EN Divider**

3) Synchronized by External Sync Clock Signal  
The chip can be synchronized to external clock range from 300kHz up to 2MHz through this pin 2ms right after output voltage is set, with the

internal clock rising edge synchronized to the external clock rising edge.



**Figure 4—Startup Sequence Using External Sync Clock Signal**

### Under-Voltage Lockout (UVLO)

Under-voltage lockout (UVLO) is implemented to protect the chip from operating at insufficient supply voltage. The MP8716 UVLO comparator monitors the output voltage of the internal regulator, VCC. The UVLO rising threshold is about 4.0V while its falling threshold is a consistent 3.2V.

### Internal Soft-Start

The soft-start is implemented to prevent the converter output voltage from overshooting during startup. When the chip starts, the internal circuitry generates a soft-start voltage (SS) ramping up from 0V to 1.2V. When it is lower than the internal reference (REF), SS overrides REF so the error amplifier uses SS as the reference. When SS is higher than REF, REF regains control. The SS time is internally fixed to 4ms.

### Over-Current-Protection and Hiccup

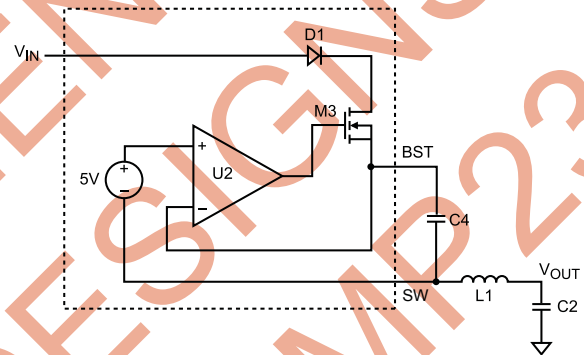
The MP8716 has cycle-by-cycle over current limit when the inductor current peak value exceeds the set current limit threshold. Meanwhile, output voltage starts to drop until FB is below the Under-Voltage (UV) threshold, typically 30% below the reference. Once a UV is triggered, the MP8716 enters hiccup mode to periodically restart the part. This protection mode is especially useful when the output is dead-short to ground. The average short circuit current is greatly reduced to alleviate the thermal issue and to protect the regulator. The MP8716 exits the hiccup mode once the over current condition is removed.

### Thermal Shutdown

Thermal shutdown is implemented to prevent the chip from operating at exceedingly high temperatures. When the silicon die temperature is higher than 150°C, it shuts down the whole chip. When the temperature is lower than its lower threshold, typically 140°C, the chip is enabled again.

### Floating Driver and Bootstrap Charging

The floating power MOSFET driver is powered by an external bootstrap capacitor. This floating driver has its own UVLO protection. This UVLO's rising threshold is 2.2V with a hysteresis of 150mV. The bootstrap capacitor voltage is regulated internally by VIN through D1, M3, C4, L1 and C2 (Figure 2). If (VIN-VSW) is more than 5V, U2 will regulate M3 to maintain a 5V BST voltage across C4.



**Figure 2—Internal Bootstrap Charging Circuit**

### Startup and Shutdown

If both VIN and EN are higher than their appropriate thresholds, the chip starts. The reference block starts first, generating stable reference voltage and currents, and then the internal regulator is enabled. The regulator provides stable supply for the remaining circuitries.

Three events can shut down the chip: EN low, VIN low and thermal shutdown. In the shutdown procedure, the signaling path is first blocked to avoid any fault triggering. The COMP voltage and the internal supply rail are then pulled down. The floating driver is not subject to this shutdown command.

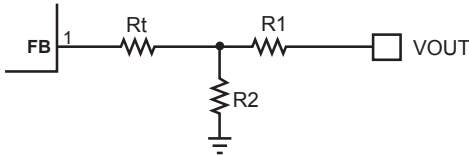
## APPLICATION INFORMATION

### Setting the Output Voltage

The external resistor divider is used to set the output voltage (see Typical Application on page 1). The feedback resistor R1 also sets the feedback loop bandwidth with the internal compensation capacitor (see Typical Application on page 1). Choose R1 to be around 40.2kΩ for optimal transient response. R2 is then given by:

$$R2 = \frac{R1}{\frac{V_{OUT}}{V_{FB}} - 1}$$

The T-type network is highly recommended when  $V_O$  is low, as Figure 3 shows.



**Figure 3— T-type Network**

Table 1 lists the recommended T-type resistors value for common output voltages.

**Table 1—Resistor Selection for Common Output Voltages**

$V_{OUT}$ (V)	R1 (kΩ)	R2 (kΩ)	Rt (kΩ)	L (μH)	$C_{OUT}$ (μF, Ceramic)
1.05	4.99	16.5	47	1-4.7	47
1.2	4.99	10.2	47	1-4.7	47
1.5	4.99	5.76	47	1-4.7	47
1.8	4.99	4.02	47	1-4.7	47
2.5	82	39.2	0	1-4.7	47
3.3	82.5	26.7	0	1-4.7	47
5	54.9	10.5	0	1-4.7	47

**Note:**

The above feedback resistor table applies to a specific load capacitor condition as shown in the table 1. Other capacitive loading conditions will require different values.

### Selecting the Inductor

A 1μH to 10μH inductor with a DC current rating of at least 25% percent higher than the maximum load current is recommended for most applications. For highest efficiency, the inductor DC resistance should be less than 15mΩ. For most designs, the inductance value can be derived from the following equation.

$$L = \frac{V_{OUT} \times (V_{IN} - V_{OUT})}{V_{IN} \times \Delta I_L \times f_{OSC}}$$

Where  $\Delta I_L$  is the inductor ripple current.

Choose inductor ripple current to be approximately 30% if the maximum load current, 3A. The maximum inductor peak current is:

$$I_{L(MAX)} = I_{LOAD} + \frac{\Delta I_L}{2}$$

Under light load conditions below 100mA, larger inductance is recommended for improved efficiency.

### Selecting the Input Capacitor

The input current to the step-down converter is discontinuous, therefore a capacitor is required to supply the AC current to the step-down converter while maintaining the DC input voltage. Use low ESR capacitors for the best performance. Ceramic capacitors with X5R or X7R dielectrics are highly recommended because of their low ESR and small temperature coefficients. For most applications, a 22μF capacitor is sufficient.

Since the input capacitor (C1) absorbs the input switching current it requires an adequate ripple current rating. The RMS current in the input capacitor can be estimated by:

$$I_{C1} = I_{LOAD} \times \sqrt{\frac{V_{OUT}}{V_{IN}} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right)}$$

The worse case condition occurs at  $V_{IN} = 2V_{OUT}$ , where:

$$I_{C1} = \frac{I_{LOAD}}{2}$$

For simplification, choose the input capacitor whose RMS current rating greater than half of the maximum load current.

The input capacitor can be electrolytic, tantalum or ceramic. When electrolytic or tantalum capacitors are used, a small, high quality ceramic capacitor, i.e. 0.1μF, should be placed as close to the IC as possible. When using ceramic capacitors, make sure that they have enough capacitance to provide sufficient charge to prevent excessive voltage ripple at input. The input voltage ripple caused by capacitance can be estimated by:

$$\Delta V_{IN} = \frac{I_{LOAD}}{f_s \times C1} \times \frac{V_{OUT}}{V_{IN}} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right)$$

### Selecting the Output Capacitor

The output capacitor (C2) is required to maintain the DC output voltage. Ceramic, tantalum, or low ESR electrolytic capacitors are recommended. Low ESR capacitors are preferred to keep the output voltage ripple low. The output voltage ripple can be estimated by:

$$\Delta V_{OUT} = \frac{V_{OUT}}{f_s \times L} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right) \times \left(R_{ESR} + \frac{1}{8 \times f_s \times C2}\right)$$

Where L is the inductor value and R<sub>ESR</sub> is the equivalent series resistance (ESR) value of the output capacitor.

In the case of ceramic capacitors, the impedance at the switching frequency is dominated by the capacitance. The output voltage ripple is mainly caused by the capacitance. For simplification, the output voltage ripple can be estimated by:

$$\Delta V_{OUT} = \frac{V_{OUT}}{8 \times f_s^2 \times L \times C2} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right)$$

In the case of tantalum or electrolytic capacitors, the ESR dominates the impedance at the switching frequency. For simplification, the output ripple can be approximated to:

$$\Delta V_{OUT} = \frac{V_{OUT}}{f_s \times L} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right) \times R_{ESR}$$

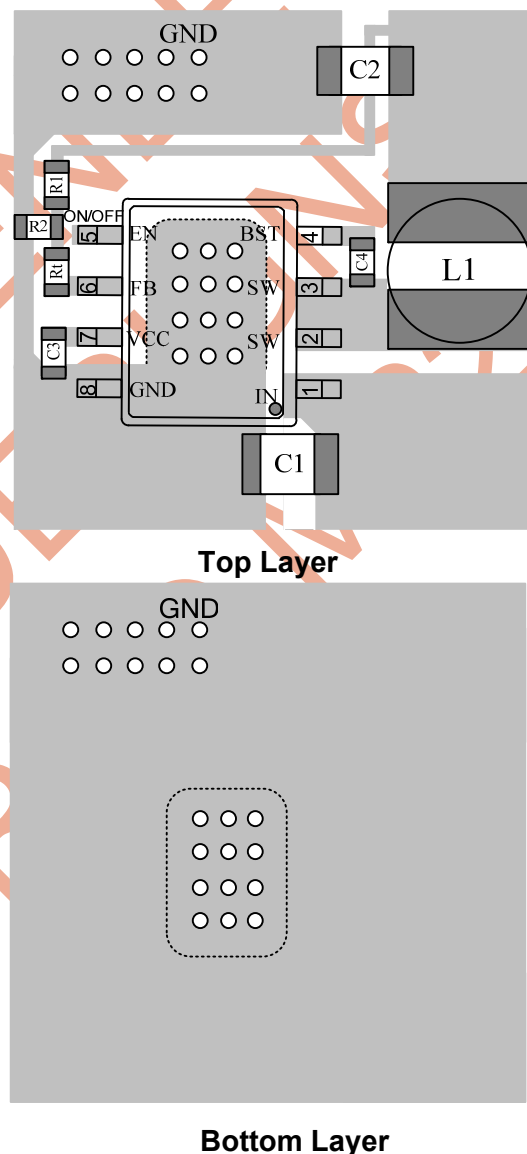
The characteristics of the output capacitor also affect the stability of the regulation system. The MP8716 can be optimized for a wide range of capacitance and ESR values.

### PCB Layout

PCB layout is very important to achieve stable operation. Please follow these guidelines and take Figure 4 for references.

- 1) Keep the connection of input ground and GND pin as short and wide as possible.
- 2) Keep the connection of input capacitor and IN pin as short and wide as possible.

- 3) Ensure all feedback connections are short and direct. Place the feedback resistors and compensation components as close to the chip as possible.
- 4) Route SW away from sensitive analog areas such as FB.
- 5) Connect IN, SW, and especially GND respectively to a large copper area to cool the chip to improve thermal performance and long-term reliability.
- 6) Adding RC snubbed circuit from IN pin to SW pin can reduce SW spikes.



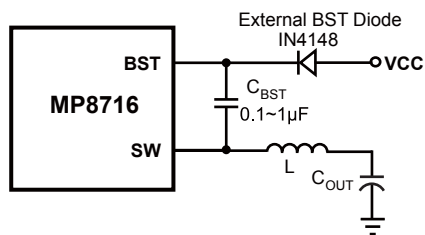
**Figure 4—PCB Layout**

### External Bootstrap Diode

An external bootstrap diode may enhance the efficiency of the regulator, the applicable conditions of external BST diode is:

- Duty cycle is high:  $D = \frac{V_{OUT}}{V_{IN}} > 65\%$

In this case, an external BST diode is recommended from the VCC pin to BST pin, as shown in Figure 5

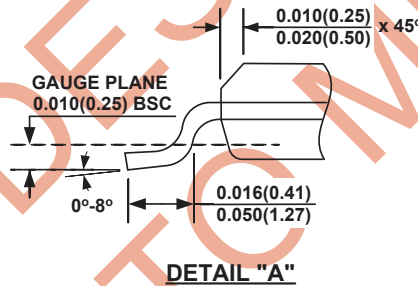
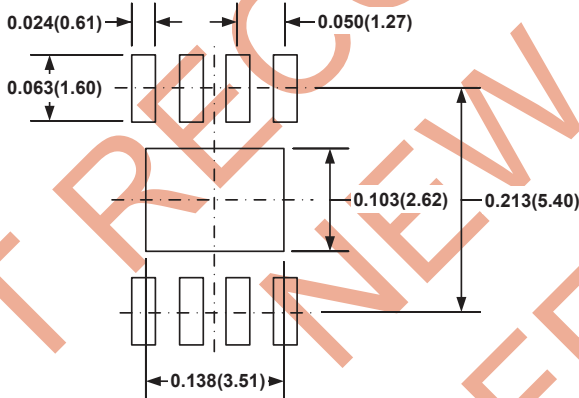
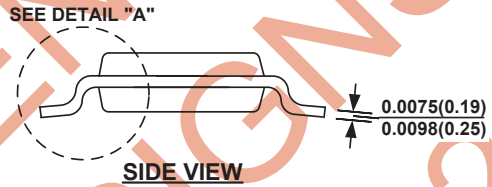
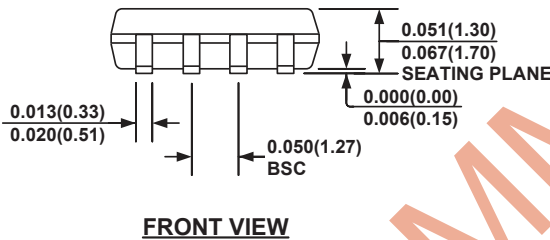
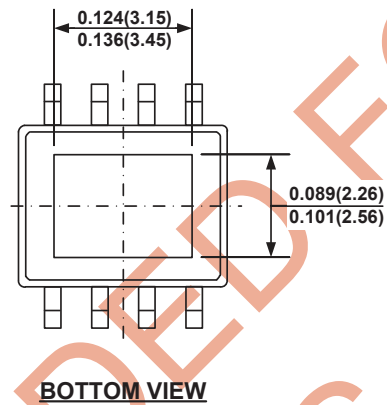
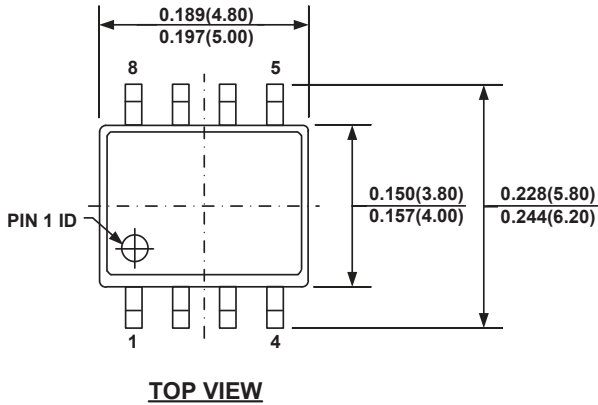


**Figure 5—Add Optional External Bootstrap Diode to Enhance Efficiency**

The recommended external BST diode is IN4148, and the BST cap is 0.1~1µF.

PACKAGE INFORMATION

SOIC8E (EXPOSED PAD)



**NOTE:**

- 1) CONTROL DIMENSION IS IN INCHES. DIMENSION IN BRACKET IS IN MILLIMETERS.
- 2) PACKAGE LENGTH DOES NOT INCLUDE MOLD FLASH, PROTRUSIONS OR GATE BURRS.
- 3) PACKAGE WIDTH DOES NOT INCLUDE INTERLEAD FLASH OR PROTRUSIONS.
- 4) LEAD COPLANARITY (BOTTOM OF LEADS AFTER FORMING) SHALL BE 0.004" INCHES MAX.
- 5) DRAWING CONFORMS TO JEDEC MS-012, VARIATION BA.
- 6) DRAWING IS NOT TO SCALE.

**NOTICE:** The information in this document is subject to change without notice. Users should warrant and guarantee that third party Intellectual Property rights are not infringed upon when integrating MPS products into any application. MPS will not assume any legal responsibility for any said applications.