

# Hall-Effect End-of-Shaft Rotary Position Sensor



# **KEY FEATURES**



# True, contactless operation

Without any gears or mechanical interfaces the sensor is easily assembled and calibrated and subject to limited wear and tear over lifetime.



# 360 degree absolute position feedback

Endless mechanical rotational angle without dead band, keeps the position on power loss with programmable electrical angles from 15 to 360 degrees.



## Made for harsh environments

The rugged package protects the sensor from dust, moisture, vibration and extreme temperatures for usage in the most demanding environments.



# Durable and robust design

The non-contacting design allows for an extra-long product lifetime of up to 50 million cycles.



# Integrated shaft

The magnet is securely fastened to the shaft and acts as only moving component in the sensor.



# Adaptable to your requirements

Programmable transfer function and switch outputs as well as different output protocols and redundancy levels available.

### **DESCRIPTION**

The robust PSC-360 is a cost-effective noncontacting rotary position sensor that provides high performance in harsh environments such as transportation, industrial and medical applications.

This compact sensor of Piher Sensing Systems is truly non-contacting with a permanent magnet that is securely fastened to the shaft and acts as the only moving component in the sensor. Redundant versions provide independent voltage outputs with fully customizable characteristics. Additionally a switch output can optionally be configured.

The endless rotation sensor is highly configurable with a programmable angular range between 15 and 360 degrees, different signal output options and support for low and high-voltage power supply. Sealed, flange mounted for easy positioning and with fly leads, it can be customized to fit any desired connector configuration.

Multi-turn configurations are available on request.

### **APPLICATIONS**

# Industrial

- ► Autonomous warehouse robotics
- ▶ Robotics and automation feedback
- ► Robot arm position
- ▶ Valve monitoring
- ► Conveyor operation

## **Transportation**

- ► Steering wheel angle
- ▶ Pedal Position
- ► Suspension/height detection
- Fork height and mast tilt
- ▶ Bucket position
- ► Hitch position
- ► Transmission gear shift

# Marine

► Steering and shifter sensor

# Home and Building Automation

► HVAC systems

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### **MECHANICAL SPECIFICATIONS** PSC-360 PSC-360U Rotational life Up to 50.000.000 cycles Mechanical range 360° (endless rotation) Shaft diameter 6,35mm 6mm

# **ELECTRICAL SPECIFICATIONS**

	PSC-360	PSC-360U				
Linearity <sup>1</sup>	±1% absolute (±0.5% on request)					
Electrical angular range	Programmable from 15° to 360°					
Output protocols	Analog (Ratiometric), PWM Serial Protocol (SPI) upon request CAN SAE J1939 CAN OPEN	Analog (Ratiometric), PWM Serial Protocol (SPI)				
Output	Simple Redundant Full-redundant					
Switch output	On request	Configurable				
Resolution CAN, Analog, PWM SPI	l :	Up to 12 bit Up to 14 bit				
Supply voltage <sup>2</sup>	5V ±10% 7V to 15V	5V ±10% 12V ±10% 15V ±10%				
Single version Supply current Redundant version CAN version						
Voltage protection	±10V					
Self-diagnostic features	yes					

<sup>&</sup>lt;sup>1</sup> Ferromagnetic materials close to the sensor (i.e. shaft, mounting surface) may affect the sensor's linearity. <sup>2</sup> Voltages up to 25V possible on request.

ENVIRONMENTAL SPECIFICATIONS	
Operating and storage temperature <sup>1</sup>	-40° to +125°C
Shock	50g
Vibration	5-2000 Hz; 20g; Amax 0,75 mm

<sup>&</sup>lt;sup>1</sup>Other specifications available

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# PSC-36002 PSC-360U - panel mount version | PSC-3600 - panel mount version | PSC-360U - panel mount



Sensor shown with the shaft at 0° position. Nut and washer included.

Sensor delivered at random position. Assembly of any type of connector on request.

# **MOUNTING INSTRUCTIONS**

Sensor shown with the shaft at zero position.

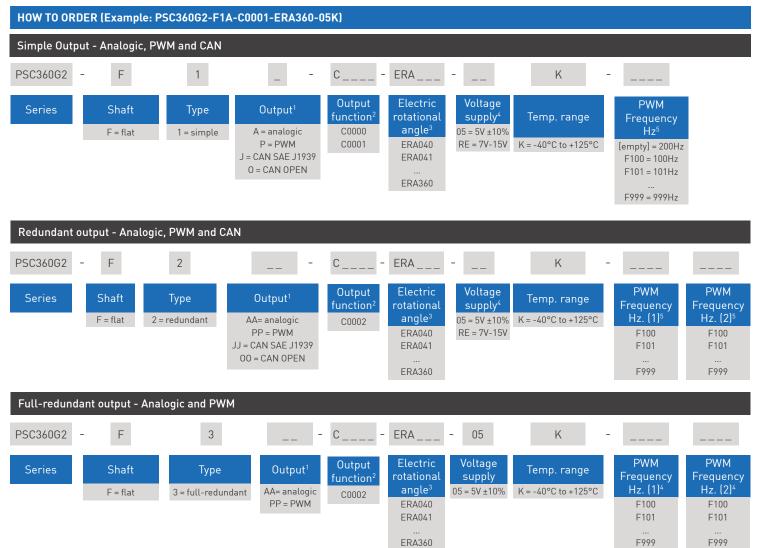
- 1. Place the component on a flat surface.
- 2. Fit the actuator onto the shaft avoiding any mechanical play/wobble.
- 3. Fasten the two M4 screws (M4 washers are recommended).

CONNECTION SCHEME							
Color	Simple		Redundant		Full-redundant	CAN	SPI
	5V	7V to 15V	5V	7V to 15V			
Brown	Power supply	Power supply	Power supply	Power supply	Power supply 1	Power supply	Power supply
Blue	Ground	Ground	Ground	Ground	Ground 1	Ground	Ground
Black	Signal output	Signal output	Signal output 1	Signal output 1	Ground 2	CAN High	MOSI
White	n/a	n/a	Signal output 2	Signal output 2	Signal output 2	CAN Low	/SS
Red	n/a	n/a	n/a	n/a	Power supply 2	n/a	n/a
Yellow	n/a	n/a	n/a	n/a	Signal output 1	n/a	n/a
Grey	n/a	Not used	n/a	Not used	n/a	n/a	SCLK

 $\label{thm:model} \mbox{More instructions of use on www.piher.net.} \ \mbox{Connector assembly available on request.}$ 

# Hall-Effect End-of-Shaft Rotary Position Sensor





- 1 The analog output is ratiometric, proportional:
- for supply voltage "5V" to input voltage;
   for supply voltage "RE" to 5V.
- 101 Supply voltage RE 10 DV.

  2 Other output functions available, please check availability. Enter CXXXX as long as the new output function is not defined.

  3 Models with ERA < 40° available on request

  4 Voltages up to 25V possible on request.

  5 Leave empty if not applicable. Default frequency is 200 Hz

OUTPUT FUNCTIONS						
			ERA	Standard	Inverted	Redundant
		360°	C0000	C0001	C0002	
90%	******		270°	C0208	C0158	C0031
		************	180°	C0007	C0072	C0036
		*****	120°	C0024		C0032
	standard inverted		90°	C0011		C0025
ERA 270 → 45°	Mechanical Rotational Angle 180°	315°	70°	C0150	On request	C0149
180 → 90° 120 → 120°	180° 180°	270° 240°	60°	C0006		C0020
090 → 135° 040 → 160°	180° 180°	225° 200°	40°	C0026		C0123
2						

Custom output functions on request.

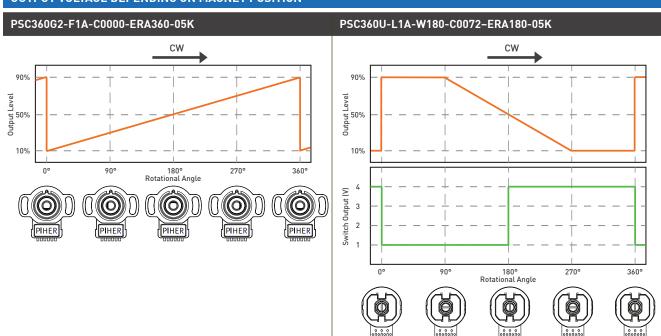
# PSC-360U Panel Mount Version



### HOW TO ORDER - PANEL MOUNT VERSION (Example: PSC360U-F1A-C0000-ERA360-05E) Simple Output - Analogic and PWM PSC360U ERA Switch Output Electric Voltage **PWM** Output1 Series Shaft Type Switch position function<sup>(</sup> rotational supply Temp. range Frequency [empty] 000 016 F = flat shaft [empty] = none C0000 angle4 05 = 5VHz<sup>5</sup> 1 = simple A = analogic L= slot shaft 12 = 12VP = PWM C0001 ERA040 $E = -40^{\circ}C \text{ to } + 85^{\circ}C$ W = switch [empty] = 200Hz15 = 15V K = -40°C to +125°C ERA041 F100 = 100Hz 360 F101 = 101Hz ERA360 F999 = 999Hz Simple output - SPI Annotations: С PSC360U S ERA 1. The analog output is ratiometric, proportional: - For supply voltage 5V: to input supply voltage. Output Electric Voltage - For supply voltage 12V and 15V: to 5V. Shaft Output Series Type Temp. range 2. Leave empty if not applicable. Switch function diagram: see next page. supply function<sup>3</sup> rotationa 3. Other output functions available, please check availability. Enter CXXXX as long as the new output S = SPI C0000 angle<sup>4</sup> 05 = 5VE = -40°C to +85°C F = flat shaft 1 = simple function is not defined. L= slot shaft C0001 12 = 12VK = -40°C to +125°C ERA040 4. Models with ERA < 40° available on request ERA041 15 = 15V 5. Leave empty if not applicable. Default frequency is 200 Hz ERA360 Redundant output - Analogic and PWM PSC360U ERA Switch1 Switch2 Output Electric Voltage **PWM PWM** Shaft Output1 Switch1 Switch2 Series Type Temp. range position position function<sup>3</sup> rotational Frequency Frequency supply Hz. [1]<sup>5</sup> Hz. [2]<sup>5</sup> F = flat shaft AA= analogic [empty] C0002 angle4 05 = 5V $E = -40^{\circ}C \text{ to } + 85^{\circ}C$ 2 = redundant [empty] = none [empty] = none [empty] 000 016 L= slot shaft PP = PWM C0003 ERA040 12 = 12V $K = -40^{\circ}C \text{ to } +125^{\circ}C$ W = switch W = switch F100 F100 016 ERA041 F101 F101 15 = 15V F999 360 360 ERA360 F999 Full-redundant output - Analogic and PWM PSC360U ERA Switch2 **Electric PWM PWM** Switch1 Output Voltage Switch2 Shaft Output1 Switch1 Series Type Temp. range oosition<sup>:</sup> position<sup>2</sup> function<sup>3</sup> rotational supply Frequency Frequency Hz. [1]<sup>5</sup> Hz. [2]<sup>5</sup> angle4 F = flat shaft 3 = redundant AA= analogic [empty] = none [empty] 000 [empty] = none [empty] C0002 05 = 5V $E = -40^{\circ}C \text{ to } + 85^{\circ}C$ L= slot shaft 000 016 PP = PWM $K = -40^{\circ}C \text{ to } +125^{\circ}C$ W = switch W = switch C0003 ERA040 F100 F100 016 F101 ERA041 F101 360 360 F999 ERA360 F999

# Hall-Effect End-of-Shaft Rotary Position Sensor

# **OUTPUT VOLTAGE DEPENDING ON MAGNET POSITION**



Custom output functions on request.

### CONTACT PIHER SENSING SYSTEMS FOR CUSTOM SOLUTIONS





# **OUR ADVANTAGE**

- ► Leading-edge innovative position sensing solutions
  - Contactless (Hall-effect and Inductive Technology)
  - Contacting (Potentiometers, Printed Electronics)
- ► Engineering design-in support
- ▶ All our products can be customized to fit target application and customer requirement
- ▶ Capability to move seamlessly from development to true high-volume production
- A global footprint with global engineering and commercial support
- ▶ One-stop shop not limited to position sensors (temperature, pressure, gas,...) through group collaboration
- ▶ Flexibility and entrepreneurship of a medium-sized company with the backing of Amphenol Corporation









Please always use the latest updated datasheets and 3D models published on our website.

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