

Data sheet for SINAMICS G120X

Article No.: 6SL3230-1YH28-0UP0

Client order no. : Order no.: Offer no. : Remarks:

Rated data						
Input						
1	Number of phases	3 AC				
l	ine voltage	500 690 V +10 %	-20 %			
l	ine frequency	47 63 Hz				
F	Rated voltage	690V IEC	600V NEC			
	Rated current (LO)	18.00 A	18.00 A			
	Rated current (HO)	14.60 A	14.60 A			
Ou	tput					
1	Number of phases	3 AC				
F	Rated voltage	690V IEC	600V NEC 1)			
	Rated power (LO)	15.00 kW	15.00 hp			
	Rated power (HO)	11.00 kW	10.00 hp			
	Rated current (LO)	19.00 A	19.00 A			
	Rated current (HO)	14.00 A	14.00 A			
	Rated current (IN)	20.00 A				
	Max. output current	26.00 A				
Pulse frequency		2 kHz				
Ou	tput frequency for vector control	0 200 Hz				
Ou	tput frequency for V/f control	0 550 Hz				
Overload capability						

Low Overload (LO)

110% base load current IL for 60 s in a 300 s cycle time

High Overload (HO)

Communication

150% x base load current IH for 60 s within a 600 s cycle time

US device (e.g. via S7-

Communication PROFIBUS DP



Item no. : Consignment no. : Project :

Inputs /	Inputs / outputs				
Standard digital inputs					
Number	6				
Switching level: $0 \rightarrow 1$	11 V				
Switching level: $1 \rightarrow 0$	5 V				
Max. inrush current	15 mA				
Fail-safe digital inputs					
Number	1				
Digital outputs					
Number as relay changeover contact	2				
Output (resistive load)	DC 30 V, 5.0 A				
Number as transistor	0				
Analog / digital inputs					
Number	2 (Differential input)				
Resolution	10 bit				
Switching threshold as digital input					
0 → 1	4 V				
1 → 0	1.6 V				
Analog outputs					
Number	1 (Non-isolated output)				

PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\text{C}$

Closed-loop control techniques		
V/f linear / square-law / parameterizable	Yes	
V/f with flux current control (FCC)	Yes	
V/f ECO linear / square-law	Yes	
Sensorless vector control	Yes	
Vector control, with sensor	No	
Encoderless torque control	No	
Torque control, with encoder	No	

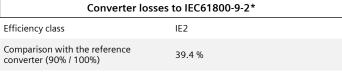


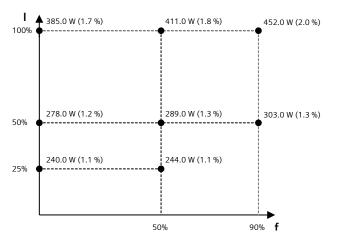
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Ambie	Ambient conditions				
Standard board coating type	Class 3C3, according to IEC 60721-3-3: 2002				
Cooling	Air cooling using an integrated fan				
Cooling air requirement	0.055 m ³ /s (1.942 ft ³ /s)				
Installation altitude	1,000 m (3,280.84 ft)				
Ambient temperature					
Operation	-20 45 °C (-4 113 °F)				
Transport	-40 70 °C (-40 158 °F)				
Storage	-25 55 °C (-13 131 °F)				
Relative humidity					
Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible				
Connections					
Signal cable					
Conductor cross-section	0.15 1.50 mm ² (AWG 24 AWG 16)				
Line side					
Version	screw-type terminal				
Conductor cross-section	10.00 35.00 mm ² (AWG 8 AWG 2)				
Motor end					
Version	Screw-type terminals				
Conductor cross-section	10.00 35.00 mm ² (AWG 8 AWG 2)				
DC link (for braking resistor)					
PE connection	Screw-type terminals				
Max. motor cable length					
Shielded	200 m (656.17 ft)				
Unshielded	300 m (984.25 ft)				

Mechanical data				
Degree of protection	IP20 / UL open type			
Frame size	FSD			
Net weight	16.6 kg (36.60 lb)			
Dimensions				
Width	200 mm (7.87 in)			
Height	472 mm (18.58 in)			
Depth	248 mm (9.76 in)			
Standards				
Compliance with standards	UL, cUL, CE, C-Tick (RCM), EAC, KCC, SEMI F47, REACH			
CE marking	EMC Directive 2004/108/EC, Low-Voltage Directive 2006/95/EC			





The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

*converted values

¹⁾ The output current and HP ratings are valid for the voltage range 550V-600V

³⁾Typical value. More information can be found in the element group "Converter losses to IEC 61800-9-2" in this datasheet.