

MLFB-Ordering data

6SL3220-1YE36-0AF0



Client order no.: Order no. : Offer no. : Remarks:

Item no.: Consignment no. : Project :

Rated data				
Input				
Number of phases	3 AC			
Line voltage	380 480 V +10 % -20 %			
Line frequency	47 63 Hz			
Rated voltage	400V IEC	480V NEC		
Rated current (LO)	72.00 A	61.00 A		
Rated current (HO)	62.00 A	54.00 A		
Output				
Number of phases	3 AC			
Rated voltage	400V IEC	480V NEC		
Rated power (LO)	37.00 kW	50.00 hp		
Rated power (HO)	30.00 kW	30.00 hp		
Rated current (LO)	75.00 A	65.00 A		
Rated current (HO)	60.00 A	52.00 A		
Rated current (IN)	77.00 A			
Max. output current	102.00 A			
Pulse frequency	4 kHz			
Output frequency for vector control	0 200 Hz			
Output frequency for V/f control	0 550 Hz			

General tech. specifications				
Power factor λ	0.90 0.95			
Offset factor cos φ	0.99			
Efficiency η	0.98			
Sound pressure level (1m)	70 dB			
Power loss	1.020 kW			
Filter class (integrated)	RFI suppression filter for Category C2			
EMC category (with accessories)	Category C2			
Ambient conditions				
Standard board coating type	Class 3C2, according to IEC 60721-3-3: 2002			

	3: 2002
Cooling	Air cooling using an integrated fan
Cooling air requirement	0.055 m³/s (1.942 ft³/s)
Installation altitude	1000 m (3280.84 ft)
Ambient temperature	
Operation	-20 45 °C (-4 113 °F)
Transport	-40 70 °C (-40 158 °F)
Storage	-25 55 °C (-13 131 °F)

Low Overload (LO)

110% base load current IL for 60 s in a 300 s cycle time

High Overload (HO)

150% x base load current IH for 60 s within a 600 s cycle time

Overload capability

Relative humidity

Max. operation

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95~% At 40 °C (104 °F), condensation and icing not permissible



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Mechanical data		Closed-loop con	Closed-loop control techniques	
Degree of protection	IP20 / UL open type	We linear I square law I parameterine la		
Size	FSD	V/f linear / square-law / parameteri	zable Yes	
Net weight	20 kg (44.09 lb)	V/f with flux current control (FCC)	Yes	
Width	200 mm (7.87 in)	V/f ECO linear / square-law	Yes	
Height	472 mm (18.58 in)	Sensorless vector control	Yes	
Depth	248 mm (9.76 in)	Vector control, with sensor	No	
 Inputs / ou		Encoderless torque control	Yes	Yes
Standard digital inputs	tputs			
		Torque control, with encoder	No	
Number	6	Communication		
Switching level: 0→1	11 V	Communication	PROFINET, EtherNet/IP	
Switching level: 1→0	5 V	Connections		
Max. inrush current	15 mA	Signal cable		
Fail-safe digital inputs		Signal Cable		
Number	1	Conductor cross-section	0.15 1.50 mm ² (AWG 24 AWG 16)	
Digital outputs		Line side		
Number as relay changeover contact	2	Version	screw-type terminal	
Output (resistive load)	DC 30 V, 5.0 A	Conductor cross-section	10.00 35.00 mm ² (AWG 8 AWG 2)	
Number as transistor	0	Motor end		
Analog / digital inputs		Version	Screw-type terminals	
Number	2 (Differential input)	Conductor cross-section	10.00 35.00 mm ² (AWG 8 AWG 2)	
Resolution	10 bit	DC link (for braking resistor)	(WG 5 / WG 2)	
Switching threshold as digital in	put			
0→1	4 V	PE connection	Screw-type terminals	
1→0	1.6 V	Max. motor cable length		
	7.0 v	Shielded	150 m (492.13 ft)	
Analog outputs				
	4 (1)			

Number

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^{\circ}\text{C}$

1 (Non-isolated output)



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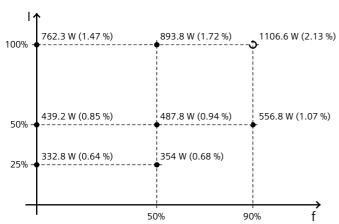
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Figure similar

Converter losses to EN 50598-2*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	-44.80 %



 $The \ percentage \ values \ show \ the \ losses \ in \ relation \ to \ the \ rated \ apparent \ power \ of \ the \ converter.$

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

Standards

Compliance with standards

UL, cUL, CE, C-Tick (RCM), EAC, KCC, SEMI F47, REACH

CE marking

EMC Directive 2004/108/EC, Low-Voltage Directive 2006/95/EC

^{*}converted values