

ED113反向系列规格书

EC11 FORWARD DIRECTION SERIES SPECIFICATION

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1. 一般事项 General

1-1. 适用规格 Scope

本规格书适用于微小电流回路的电子设备，属11型回转型编码器。

This specification applies to 11mm size low-profile rotary encoder (incremental type) for microscopic current circuits, used in electronic equipment.

1-2. 标准状态 Standard atmospheric conditions

除另有规定外，测量应在以下状态下进行：

Unless otherwise specified, the standard range of atmospheric conditions for making measurements and test is as following limits:

温 度 Ambient temperature : 15°C to 35°C

相对湿度 Relative humidity : 25% to 85%

气 压 Air pressure : 86kpa to 106kpa

如果对在上述所提到的条件中所做的实测值有疑问的话，应使用以下条件进行测量：

If doubt arises on the decision based on the measured values under the above-mentioned conditions, the following conditions shall be employed:

温 度 Ambient temperature : 20±1°C

相对湿度 Relative humidity : 63% to 67%

气 压 Air pressure : 86kpa to 106kpa

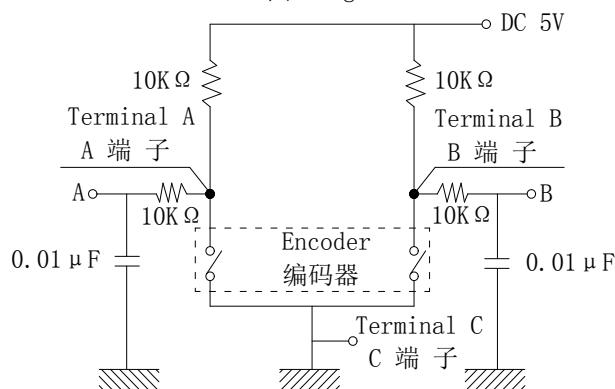
1-3. 使用温度范围

Operating temperature range : -30°C to +80°C

1-4. 保存温度范围

Storage temperature range : -40°C to +85°C

图1 fig. 1



2. 构造 Construction

2-1. 尺寸 Dimensions

见所附成品图 Refer to attached drawing

3. 额定值 Rating

3-1. 额定电压

Rated voltage: DC 5V

3-2. 最大额定电流 (阻抗负载)

Maximum operating current (resistive load)

各相导线 Each lead: 0.5mA (Max 5mA; Min 0.5mA)

公共导线 Common lead: 1mA (Max 10mA; Min 0.5mA)

4. 使用上的事项 Application Notes

4-1. 避免储藏于高温潮湿及腐蚀的场所。产品购入后尽可能在6个月内使用完。拆包装后未使用完的剩余产品需储藏于防潮防毒的环境下。

Avoid storing the products in a place at high temperature, high humidity and in Corrosive gases. Please use this product as soon as possible with 6 months limitation. If any remainder left after packing is opened, please store it with proper moistureproofing, gasproofing etc.

4-2. 编码器信号的计算方法应将操作的速度, 信号的取样时间及电子回路中的微电脑软体等考虑进去。

The encoder pulses count method should be designed with taking operating speed, sampling time and esign of the microcomputer software into cosideration.

4-3. 此产品在定位点的输出波形参照 (5-1)，因此在设计软体时请留意其状态，推荐以A相位为参考基准。

With this products the detent position output consult fig. 5-1. Therefore make the A phase the reference at the soft ware design stage. Recommended that use A output signal for the reference.

4-4. 在设计时要考虑到杂讯, 建议使用R/C滤波电路, (图1)

At design of the pulse count process. Using the C/R filter circuit is Recommended. (fig .1)

4-5. 本产品请勿碰触到水, 可能会导致输出波形的异常。

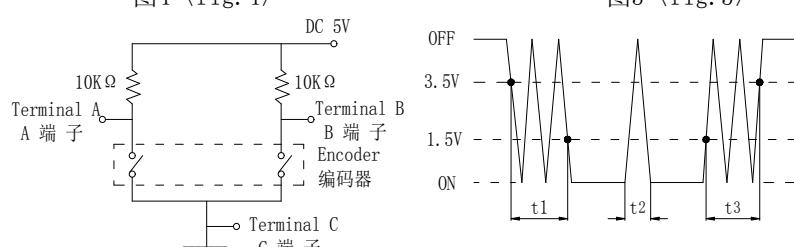
Care must be taken not to expose this product to water or dew to prevent possible problem in pluses output waveform.

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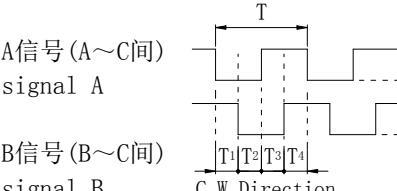
5. 电气性能 Electrical Characteristics

| 项目 ITEM | 条件 CONDITIONS | | 规格 SPECIFICATIONS | | | | | | | | | | | | |
|---|--|---|--|----------------|---------------|-----------------------------|-----------|-----------------------------|-----------|------------------|-----------------------------|-----------|-----------------------------|-----------|--|
| | A、B两信号输出相位差，输出波形详细见（图2/3）（虚线表示带卡点装置的上擎子处位置） 2 Phase-different signals (signal A, signal B) Details shown in<fig. 2/3> (The broken line shows detent position.) | | | | | | | | | | | | | | |
| 5-1. 输出信号 Output signal format | <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="text-align: left;">轴回转方向 Shaft rotati- onal direction</th> <th style="text-align: left;">信号 Signal</th> <th style="text-align: right;">输出波形 Output</th> </tr> </thead> <tbody> <tr> <td rowspan="4" style="vertical-align: middle; text-align: center;">顺时针方向 C. W</td> <td>A(A-C端子间) A(TerminalA-C)</td> <td style="text-align: right;">图2 fig. 2</td> </tr> <tr> <td>B(B-C端子间) B(TerminalB-C)</td> <td style="text-align: right;">图3 fig. 3</td> </tr> <tr> <td rowspan="4" style="vertical-align: middle; text-align: center;">逆时针方向 C. C. W</td> <td>A(A-C端子间) A(TerminalA-C)</td> <td style="text-align: right;">图2 fig. 2</td> </tr> <tr> <td>B(B-C端子间) B(TerminalB-C)</td> <td style="text-align: right;">图3 fig. 3</td> </tr> </tbody> </table> | 轴回转方向 Shaft rotati- onal direction | 信号 Signal | 输出波形 Output | 顺时针方向 C. W | A(A-C端子间) A(TerminalA-C) | 图2 fig. 2 | B(B-C端子间) B(TerminalB-C) | 图3 fig. 3 | 逆时针方向 C. C. W | A(A-C端子间) A(TerminalA-C) | 图2 fig. 2 | B(B-C端子间) B(TerminalB-C) | 图3 fig. 3 | |
| 轴回转方向 Shaft rotati- onal direction | 信号 Signal | 输出波形 Output | | | | | | | | | | | | | |
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| | | B(B-C端子间) B(TerminalB-C) | 图3 fig. 3 | | | | | | | | | | | | |
| 5-2. 分解能力 Resolution | | 回转360° 的输出脉冲数。 Number of pulses in 360° rotation. | <input type="checkbox"/> 15 个脉冲/360° (图2) 15pulses/360° (fig. 2) <input checked="" type="checkbox"/> 20个脉冲/360° (图3) 20pulses/360° (fig. 3) | | | | | | | | | | | | |
| 5-3. 开关特性 Switching characteristics | | <p>下(图4)所示回路, 轴以360° /S的速度转动测定。 Measurement shall be made under the condition as follows. Shaft rotational speed : 360° /S Test circuit : (fig. 4)</p> <p style="text-align: center;">图4 (fig. 4) 图5 (fig. 5)</p>  <p>(注) 编码OFF指输出电压3.5V以上的状态(fig. 5). Code-OFF area :The area which the voltage is 3.5V or more(fig. 5). 编码ON指输出电压1.5V以下的状态(fig. 5). Code-ON area : The area which the voltage is 1.5V or less(fig. 5).</p> | | | | | | | | | | | | | |
| 5-3-1. 振荡 Chattering | 编码从OFF→ON或ON→OFF时, 输出1.5V~3.5V的通过时间。应符合规定Specified by the signal's passage time from 1.5V to 3.5V of each switching position(code OFF~ON or ON~OFF) | $t_1, t_3 \leqslant 3\text{mS}$ | | | | | | | | | | | | | |
| 5-3-2. 滑动杂讯 (突跳) Sliding noise (Bounce) | 编码ON部份的1.5V以上的电压变动时间在振荡t1, t3之间会产生1ms以上, 1.5V以下的ON部份. 另外, 如果各突跳1.5V以下的范围在1ms以上时, 则判定为另一个突跳。 Specified by the time of voltage change exceed 1.5V in code-ON area . When the bounce has code-ON time less than 1ms between chattering (t1 or t3) the voltage change shall be regarded as a part of chattering. When the code-ON time between 2 bounces is less than 1ms, they are regarded as 1 linked bounce. | $t_2 \leqslant 2\text{mS}$ | | | | | | | | | | | | | |

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| | | |
|--|--|---|
| 5-3-3. 滑动噪音 Sliding noise | 编码OFF部份的电压变动。 The voltage change in code-OFF area. | 3.5V以上 3.5Vmin |
| 5-4. 相位差 Phase difference | 下(图6)所示回路, 轴以360° /S的速度转动测定。 Measurement shall be made under the condition which the shaft is rotated at 60r/min  图6 fig.6 | T1、T2、T3、T4≥0.08T 见图6 (fig. 6) |
| 5-5. 绝缘阻抗 Insulation resistance | 在端子和支架间施加电压 250V DC。 Measurement shall be made under the condition which a voltage of 250V DC is applied between individual terminals and frame. | 100MΩ 以上 100MΩ Min |
| 5-6. 耐电压 Dielectric strength | 在端子和支架间施加AC300V电压1分钟 A voltage of 300V AC shall be applied for 1 minute between individual terminals and frame. | 不得有绝缘破坏 Without arcing or breakdown. |
| 5-7. 端子间接触阻抗 Contact resistance | 输出信号处于ON时安定状态条件下测定。 Measurement shall be stable condition which a output signal is ON. | 1Ω 以下 1Ω Max |
| 6. 机械性能 Mechanical Characteristics | | |
| 6-1. 全回转角度 Total rotational angle | | 360° (无止档点) 360° (Endless) |
| 6-2. 定位点力矩 Detent torque | 只适用于附卡点装置 Only suitable for C. C. equipment. | 2~15mN. m. (20~150gf. cm) |
| 6-3. 定位点数及位置 Number and position of detent | 只适用于附卡点装置 Only suitable for C. C. equipment. | <input type="checkbox"/> 30点定位间隔角度12° ±2° 30detents Step angle:12° ±2° <input checked="" type="checkbox"/> 20点定位间隔角度18° ±2° 20detents Step angle:18° ±2° |
| 6-4. 轴的推拉强度 Push-pull strength of shaft | 在轴端, 沿轴向施加 8Kg 的静负荷力推和拉各10秒钟 (产品焊锡固定在PCB上。) Push and pull static load of 8Kg shall be applied to the shaft in the axial direction for 10s. (After soldering of the PC board) | 轴向虚位间隙0.4以内 Shaft play in axial direction 0.4 Max |
| 6-5. 端子强度 Terminal strength | 在端子的前端施加5N (500g) 的力1分钟。 A static load of 5N(500g)be applied to the tip of terminals for 1 minute in any direction. | 端子无损坏, 无过度的松动. 允许变形. Without damage or excessive looseness of terminals. terminal bend is permitted. |
| 6-6. 轴套螺纹紧固强度 Bushing Nut Tighten Strength | | 7.0kgf. cm以上 7.0kgf. cm Min |
| 6-7. 轴向间隙 Shaft play in axial direction | | 0.4mm 以下 0.4mm Max |
| 6-8. 轴摆动 Shaft wobble | 在距离轴顶端5MM处, 沿径向瞬间施加50mN. m(500gf. cm) 的力测试 A momentary load of 500gf. cm should be applied at the point 5mm from the tip of the shaft in a direction perpendicular to the axis of shaft. | 0.7*L/30mm p-p 以下 (L: 指安装平面到轴的柄端的距离.) 0.7*L/30mm p-p Max L: Distance between mounting surface and measuring point on the shaft |
| 6-9. 轴的回转方向摆动 Shaft play in rotational wobble | 用角度板测定。 Testing by angle board. | 5° 以下 5° Max |

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7 耐久性能 Endurance Characteristics

| 项目 ITEM | 条件 CONDITIONS | 规格 SPECIFICATIONS |
|--|--|--|
| 7-1. 回转寿命 Rotational life | <p>在无负荷条件下轴以600~1000周/小时速度回转，一日连续5000~8000次。</p> <p>The shaft of encoder shall be rotated at a speed of 600~1000cycles/H without electrical load, after with measurements shall be made.</p> <p>(5000 to 8000 continuous cycles for 24 hours.)</p> | <p>■ 在力矩≤100gf. cm时30, 000±200周 30, 000±200cycles per below 100gf. cm.</p> <p>□ 在力矩>100gf. cm时15, 000±200周。 15, 000±200cycles per above 100gf. cm.</p> <p>振荡 t1, t3≤5mS. 突跳 t2≤3mS. 尚余有轻微定位感. 端子间接触阻抗200Ω以下 Chattiring t1, t3≤5mS. Bounce t2≤3mS. Detent feeling has to remains Contact resistance 200Ω Max</p> |
| 7-2. 耐湿性 Damp heat | <p>温度40±2°C, 湿度90~95%的恒温恒湿槽中放置96±4小时后, 在常温、常湿中放置1.5小时后测试。The encoder shall be stored at temperature of 40 ±2°C with relative humidity of 90% to95% for96±4H in a thermostatic chamber. And the encoder shall be subjected to standard atmospheric conditions for 1.5H, After which measurements shall be made.</p> | <p>所有项应满足初期规格 Specifications in clause all items is shall be satisfied.</p> |
| 7-3. 耐热性 Dry heat | <p>温度85±3°C的恒温箱中放置96±4小时, 常温、常湿放置1.5小时后测试。</p> <p>The encoder shall be stored at a temperature of 85±3°Cfor 96±4H in a thermostatic chamber. And then the encoder. shall be subjected to standard atmospheric conditions for 1.5H, After which measurements shall be made.</p> | <p>所有项应满足初期规格。 Specifications in clause all items is shall be satisfied.</p> |
| 7-4. 低温特性 Cold | <p>温度-40±3°C的恒温箱中放置96±4小时, 常温、常湿放置1.5小时后测试。</p> <p>The encoder shall be stored at a temperature of -40±3°Cfor 96±4H in a thermostatic chamber. And then the encoder. shall be subjected to standard atmospheric conditions for 1.5H, After which measurements shall be made.</p> | <p>所有项应满足初期规格。 Specifications in clause all items is shall be satisfied.</p> |
| 7-5. 焊锡耐热性 Resistance to Soldering heat | <p>槽焊 Dip soldering. 使用基板:t=1.6mm的单面覆铜板. Printed wiring board:single-sided copper clad laminate board with thickness of 1.6mm. 预热:基板表面温度100°C以下, 时间1分钟以内. Preheating:1. Surface temperature of board:100°C. or less 2. Preheating time:within 1 minute. 焊接:温度260±5°C或以下, 时间3秒以内. Soldering:Solder temperature:260±5°C or less Immersion time:within 3S 手焊 Manual soldering. 温度300°C以下, 时间3秒以内. Bit temperature of soldering iron:300°Cless than Application time of soldering iron:within 3S</p> | <p>不得有绝缘体的破损、变形、接触无异常. Electrical characteristics shall be satisfied No mechanical abnormality.</p> |
| 7-6. 焊锡性 Solderability | <p>端子在260°C±5°C温度的焊锡槽内浸锡3秒±0.5秒。 The terminals shall be immersed into solder bath at 260°Cfor 3S±0.5S.</p> | <p>浸渍面须有75%以上焊锡附着 A new uniform coating of solder shall cover75% minimum of the surface being immersed.</p> |

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推动开关部分Push Switch Portion

备注：以下规格适用于EC11编码器带开关系列。

Note: The following specification is only suitable for the one type with switch construction of RE11 encoder series.

1. 额定值 Rating

1-1. 额定电压

Rated voltage:DC 5V

1-2. 最大额定电流 (阻抗负载)

Maximum operating current (resistive load):10mA Max

2. 电气性能 Electrical Characteristics

| 项目 ITEM | 条件 CONDITIONS | 规格 SPECIFICATIONS |
|------------------------------------|--|--|
| 2-1. 接触电阻 Contact resistance | 用DC 5V 1mA 电压测定. Voltage test at DC 5V 1mA. | $\leq 100\text{m}\Omega$ 100 $\text{m}\Omega$ or less |
| 2-2. 绝缘阻抗 Insulation resistance | 在端子和安装板间施加电压 250V DC. Measurement shall be made under the condition which a voltage of 250V DC is applied between individual terminals and bushing and plank. | 100M Ω 以上 100M Ω Min |
| 2-3. 振荡 Bouncing | 以1秒钟1往返(OFF-ON-OFF)按压动作. Shaft shall be push at 1 cycles/s(OFF-ON-OFF) | $\leq 10\text{mS}$ 10mS or less |
| 2-4. 耐电压 Dielectric strength | 在端子和安装板间施加AC300V电压1分钟 A voltage of 300V AC shall be applied for 1 minute between individual terminals and bushing and plank. | 不得有绝缘破坏 Without arcing or breakdown. |

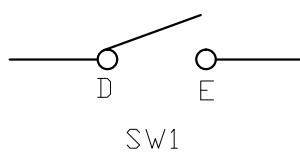
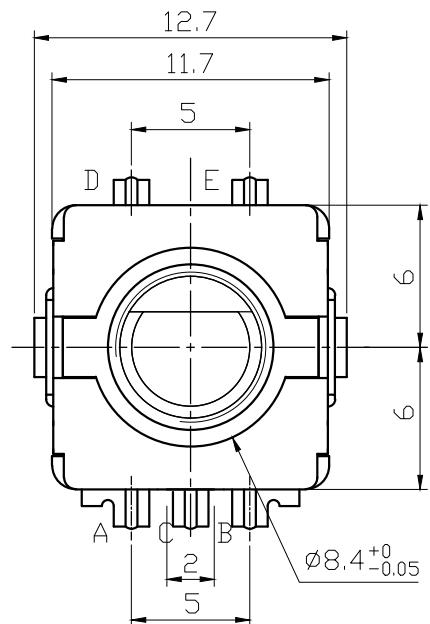
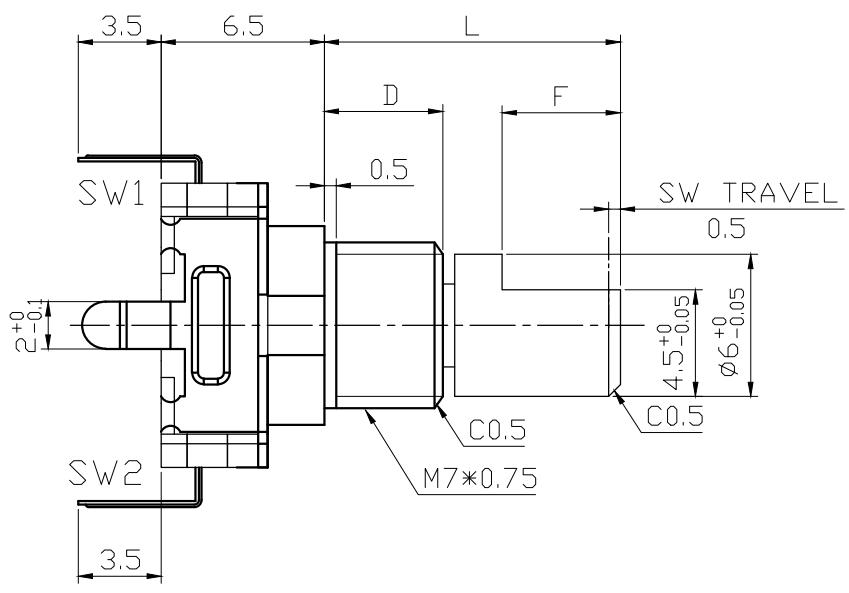
3 机械性能 Mechanical Characteristics

| | | |
|--|---|---|
| 3-1. 开关电路 接点数 Switch circuit and number of pulse | | 单极单投(按压ON) Single pole and single throw (push ON) |
| 3-2. 开关动作力 Operation force of switch | 在轴端, 沿轴向施加的按压力. Push static load to the shaft in the axial direction | $500 \pm 200\text{gf}$ |
| 3-3. 开关移动量 Travel of switch | | <input checked="" type="checkbox"/> $0.5 \pm 0.3\text{ mm}$ <input type="checkbox"/> $1.5 \pm 0.5\text{ mm}$ |

4 耐久性能 Endurance Characteristics

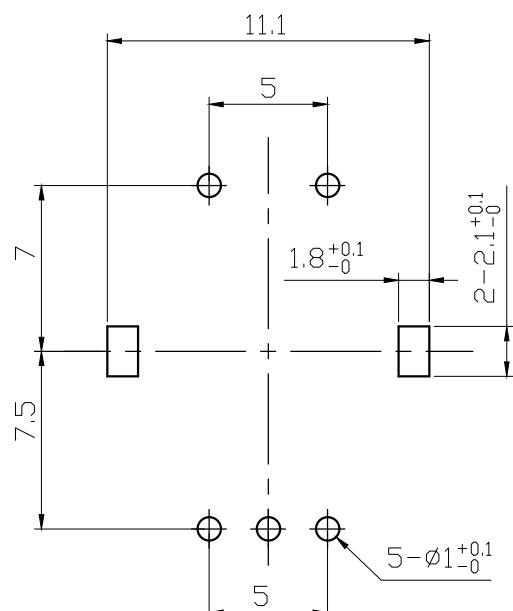
| | | |
|------------------------|---|---|
| 4-1. 按压寿命 Push-life | 在无负荷条件下沿轴向施以1Kgf以下的力, 以600次/小时的速度按压。 Push 1Kgf to the shaft of encoder in the axial direction under non-load conditions, and with a speed of 600 times/hour. | <input checked="" type="checkbox"/> $30,000 \pm 200$ 次. (0.5行程) $30,000 \pm 200$ cycles. (0.5 Travel) <input type="checkbox"/> $15,000 \pm 200$ 次. (1.5行程) $15,000 \pm 200$ cycles. (1.5 Travel) |
| | | 接触电阻: $\leq 200\text{m}\Omega$. 其它应满足初期规格. Contact resistance: $200\text{m}\Omega$ or less. Specification in clause shall be satisfied. |

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| 版本 VERSION: A0 | | | | | |



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|---|------|
| L | 18.5 |
| F | 10 |

| X | T | G | I |
|---|-----|---|-----|
| D | 3.5 | 5 | 7 ✓ |



P C B MOUNTING DETAIL

| VERSION | 东莞市长泰尔电子有限公司 | DRAW | | | SCALE |
|---------|--------------|---------------------------------|--------|-----------------------------|---------------|
| | | ED11305M-FB18.5A10-E20-160-G219 | | | |
| A0 | | DRAWING NO: | | | 3:1 |
| .ISSU. | DATE | REVISION | Design | TOL. UNLESS OTHERWISE SPEC. | CHKD |
| 00 | | | | BASIC DIMENSIONS | TOL. |
| 01 | | | | $L \leq 10$ | ± 0.3 |
| 02 | | | | $10 < L$ | ± 0.5 |
| 03 | | | | $100 \leq L$ | ± 0.8 |
| 04 | | | | ANGLE | $\pm 5^\circ$ |

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2021.07.26
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