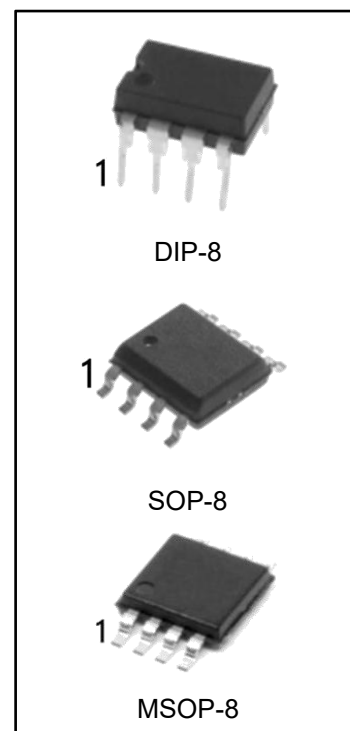


Features

- Wide Voltage Operation
VCC = 1.8V to 5.5V
- Operating Ambient Temperature: -40°C to +85°C
- Internally Organized:
 - HX24LC32B , 4096 X 8 (32K bits)
 - HX24LC64B , 8192X 8 (64K bits)
- Two-wire Serial Interface
- Schmitt Trigger, Filtered Inputs for Noise Suppression
- Bidirectional Data Transfer Protocol
- 1 MHz (5V), 400 kHz (1.8V, 2.5V, 2.7V) Compatibility
- Write Protect Pin for Hardware Data Protection
- 32-byte Page (32K,64K) Write Modes
- Partial Page Writes Allowed
- Self-timed Write Cycle (5 ms max)
- High-reliability
 - Endurance: 1 Million Write Cycles
 - Data Retention: 100 Years



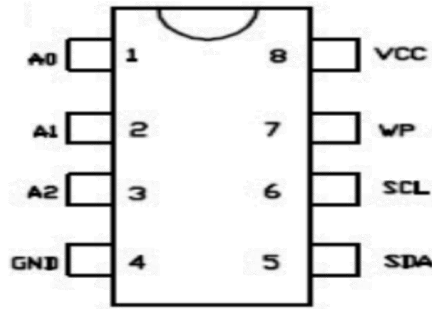
Ordering Information

DEVICE	Package Type	MARKING	Packing	Packing Qty
HX24LC32BPG	DIP-8	24LC32B	TUBE	2000/box
HX24LC64BPG	DIP-8	24LC64B	TUBE	2000/box
HX24LC32BDRG	SOP-8	24LC32B	REEL	2500/reel
HX24LC64BDRG	SOP-8	24LC64B	REEL	2500/reel
HX24LC32BDGKRG	MSOP-8	LC32B	REEL	3000/reel
HX24LC64BDGKRG	MSOP-8	LC64B	REEL	3000/reel

General Description

The HX24LC32B / 64B provides 32,768/ 65,536 bits of serial electrically erasable and programmable read-only memory (EEPROM) organized as 4096/8192 words of 8 bits each. The device is optimized for use in many industrial and commercial applications where low-power and low-voltage operations are essential. The HX24LC32B / 64B is available in space-saving 8-lead DIP, 8-lead SOP, and 8-lead MSOP packages and is accessed via a two-wire serial interface.

Pin Configuration



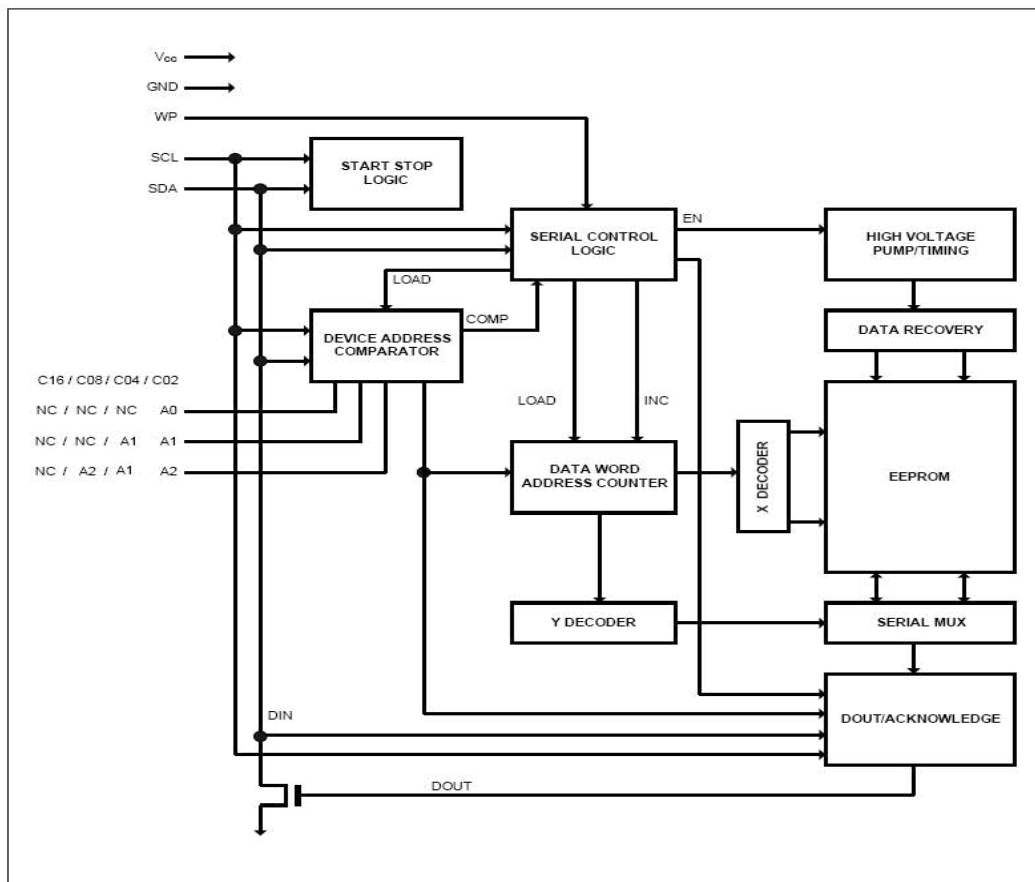
SOP-8/DIP-8/MSOP-8

Pin Descriptions

Table 1: Pin Configuration

Pin Designation	Type	Name and Functions
A0 - A2	I	Address Inputs
SDA	I/O & Open-drain	Serial Data
SCL	I	Serial Clock Input
WP	I	Write Protect
GND	P	Ground
VCC	P	Power Supply

Block Diagram



Pin Descriptions

DEVICE/PAGE ADDRESSES (A2, A1 and A0): The A2, A1 and A0 pins are device address inputs that are hard wired for the HX24LC32B / 64B. Eight 32K/64K devices may be addressed on a single bus system (device addressing is discussed in detail under the Device Addressing section).

SERIAL DATA (SDA): The SDA pin is bi-directional for serial data transfer. This pin is open-draindriven and may be wire-ORed with any number of other open-drain or open- collector devices.

SERIAL CLOCK (SCL): The SCL input is used to positive edge clock data into each EEPROMdevice and negative edge clock data out of each device.

WRITE PROTECT (WP): The HX24LC32B/HX24LC64B has a Write Protect pin that provides hardware data protection. The Write Protect pin allows normal read/write operations when connected to ground (GND). When the Write Protect pin is connected to VCC, the write protection feature is enabled and operates as shown in the following Table 2.

Table 2: Write Protect

WP Pin Status	Part of the Array Protected	
	HX24LC32B	HX24LC64B
At VCC	Full (32K) Array	Full (64K) Array
At GND	Normal Read/Write Operations	

Memory Organization

HX24LC32B, 32K SERIAL EEPROM: Internally organized with 128 pages of 32 bytes each, the 32K requires an 12-bit data word address for random word addressing.

HX24LC64B, 64K SERIAL EEPROM: Internally organized with 256 pages of 32 bytes each, the 64K requires a 13-bit data word address for random word address

Device Operation

CLOCK and DATA TRANSITIONS: The SDA pin is normally pulled high with an external device. Data on the SDA pin may change only during SCL low time periods (see to Figure 1 on page 5). Data changes during SCL high periods will indicate a start or stop condition as defined below.

START CONDITION: A high-to-low transition of SDA with SCL high is a start condition which must precede any other command (see to Figure 2 on page 5).

STOP CONDITION: A low-to-high transition of SDA with SCL high is a stop condition. After a read sequence, the stop command will place the EEPROM in a standby power mode (see Figure 2 on page 5).

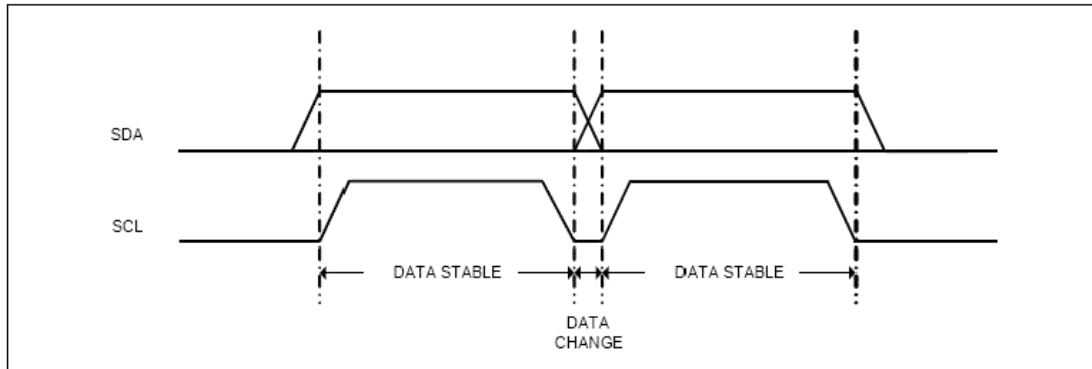
ACKNOWLEDGE: All addresses and data words are serially transmitted to and from the EEPROM in 8-bit words. The EEPROM sends a "0" to acknowledge that it has received each word. This happens during the ninth clock cycle.

STANDBY MODE: The HX24LC32B / 64B features a low-power standby mode which is enabled:
(a) upon power-up and (b) after the receipt of the STOP bit and the completion of any internal operations

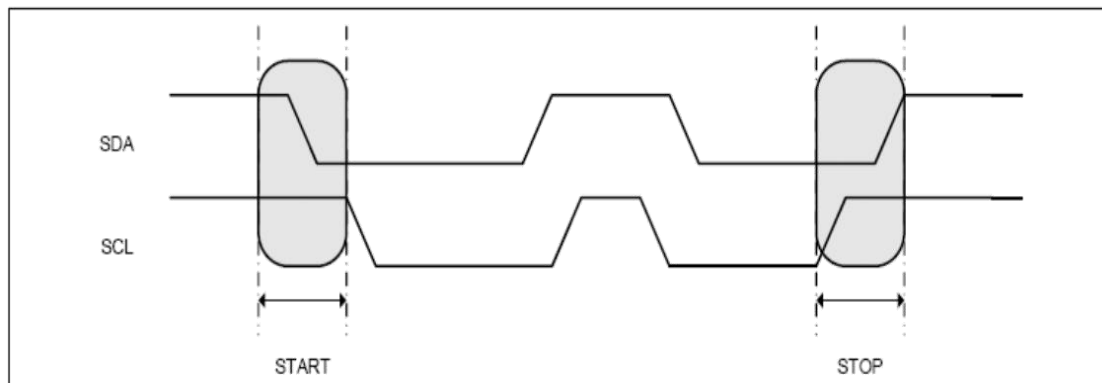
MEMORY RESET: After an interruption in protocol, power loss or system reset, any two-wire part can be reset by following these steps:

1. Clock up to 9 cycles.
2. Look for SDA high in each cycle while SCL is high.
3. Create a start condition.

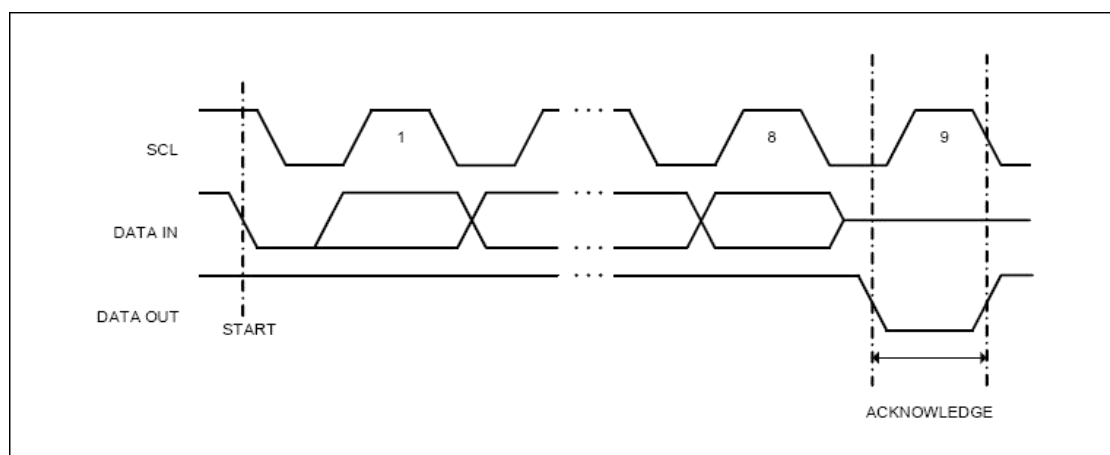
● Figure 1: Data Validity



● Figure 2: Start and Stop Definition



● Figure 3: Output Acknowledge



Device Addressing

The 32K and 64K EEPROM devices all require an 8-bit device address word following a start condition to enable the chip for a read or write operation (see to Figure 4 on page 7).

The device address word consists of a mandatory "1", "0" sequence for the first four most significant bits as shown. This is common to all the Serial EEPROM devices.

The next 3 bits are the A2, A1 and A0 device address bits for the 32K/64K EEPROM. These 3 bits must compare to their corresponding hardwired input pins.

The eighth bit of the device address is the read/write operation select bit. A read operation is initiated if this bit is high and a write operation is initiated if this bit is low.

Upon a compare of the device address, the EEPROM will output a "0". If a compare is not made, the chip will return to a standby state.

Write Operations

BYTE WRITE: A write operation requires an 8-bit data word address following the device address word and acknowledgment. Upon receipt of this address, the EEPROM will again respond with a "0" and then clock in the first 8-bit data word. Following receipt of the 8-bit data word, the EEPROM will output a "0" and the addressing device, such as a microcontroller, must terminate the write sequence with a stop condition. At this time the EEPROM enters an internally timed write cycle, t_{WR} , to the nonvolatile memory. All inputs are disabled during this write cycle and the EEPROM will not respond until the write is complete (see Figure 5 on page 7).

PAGE WRITE: The 32K/64K EEPROM is capable of a 32-byte page write.

A page write is initiated the same as a byte write, but the microcontroller does not send a stop condition after the first data word is clocked in. Instead, after the EEPROM acknowledges receipt of the first data word, the microcontroller can transmit up to 31 (32K, 64K) more data words. The EEPROM will respond with a "0" after each data word received. The microcontroller must terminate the page write sequence with a stop condition (see Figure 6 on page 8).

The data word address lower five (32K, 64K) bits are internally incremented following the receipt of each data word. The higher data word address bits are not incremented, retaining the memory page row location. When the word address, internally generated, reaches the page boundary, the following byte is placed at the beginning of the same page. If more than 32 (32K, 64K) data words are transmitted to the EEPROM, the data word address will "roll over" and previous data will be overwritten.

ACKNOWLEDGE POLLING: Once the internally timed write cycle has started and the EEPROM inputs are disabled, acknowledge polling can be initiated. This involves sending a start condition followed by the device address word. The read/write bit is representative of the operation desired.

Only if the internal write cycle has completed will the EEPROM respond with a "0", allowing the read or write sequence to continue.

Read Operations

Read operations are initiated the same way as write operations with the exception that the read/write select bit in the device address word is set to "1". There are three read operations: current address read, random address read and sequential read.

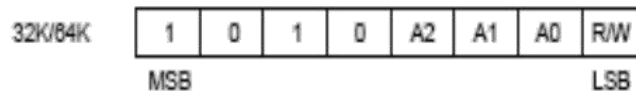
CURRENT ADDRESS READ: The internal data word address counter maintains the last address accessed during the last read or write operation, incremented by one. This address stays valid between operations as long as the chip power is maintained. The address "roll over" during read is from the last byte of the last memory page to the first byte of the first page. The address "roll over" during write is from the last byte of the current page to the first byte of the same page.

Once the device address with the read/write select bit set to "1" is clocked in and acknowledged by the EEPROM, the current address data word is serially clocked out. The microcontroller does not respond with an input "0" but does generate a following stop condition (see Figure 7 on page 8).

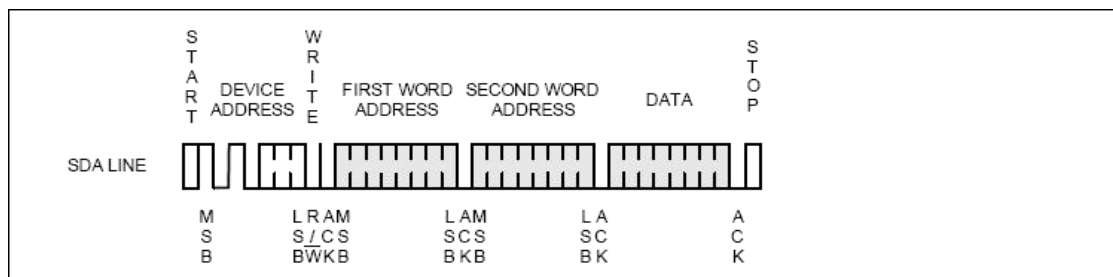
RANDOM READ: A random read requires a "dummy" byte write sequence to load in the data word address. Once the device address word and data word address are clocked in and acknowledged by the EEPROM, the microcontroller must generate another start condition. The microcontroller now initiates a current address read by sending a device address with the read/write select bit high. The EEPROM acknowledges the device address and serially clocks out the data word. The microcontroller does not respond with a "0" but does generate a following stop condition (see Figure 8 on page 8).

SEQUENTIAL READ: Sequential reads are initiated by either a current address read or a random address read. After the microcontroller receives a data word, it responds with an acknowledge. As long as the EEPROM receives an acknowledge, it will continue to increment the data word address and serially clock out sequential data words. When the memory address limit is reached, the data word address will "roll over" and the sequential read will continue. The sequential read operation is terminated when the microcontroller does not respond with a "0" but does generate a following stop condition (see Figure 9 on page 9).

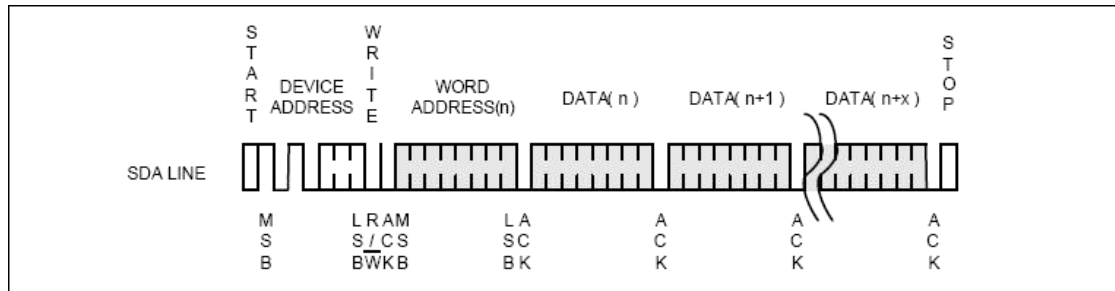
- Figure 4: Device Address



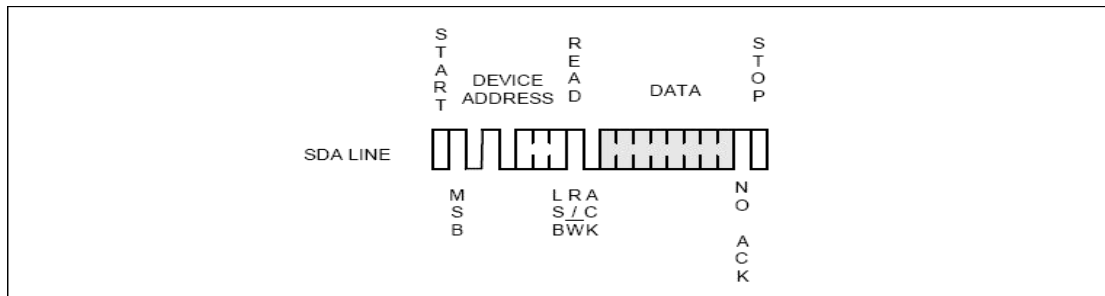
- Figure 5: Byte Write



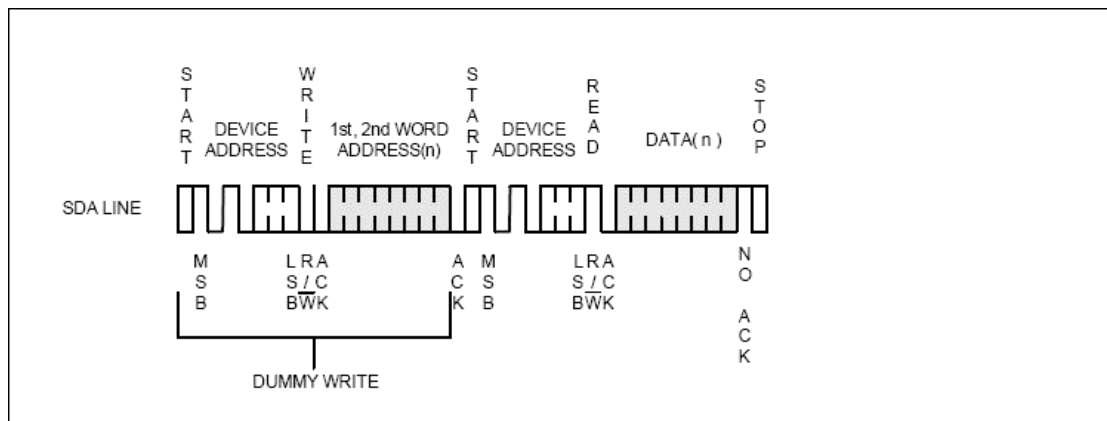
● Figure 6: Page Write



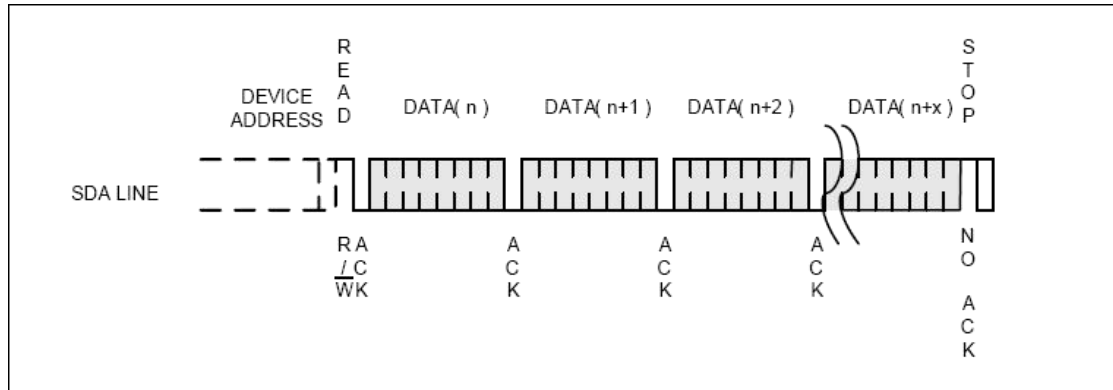
● Figure 7: Current Address Read



● Figure 8: Random Read



● Figure 9: Sequential Read



Absolute Maximum Stress Ratings

Comments Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to this device.

Condition	Min	Max
DC Supply Voltage	-0.3V	+6.5V
Input / Output Voltage	GND-0.3V	VCC+0.3V
Operating Ambient Temperature	-40°C	+85°C
Storage Temperature	-65°C	+150°C
Lead Temperature(Soldering, 10 seconds)	-	245°C

These are stress ratings only. Functional operation of this device at these or any other conditions above those indicated in the operational sections of this specification is not implied or intended. Exposure to the absolute maximum rating conditions for extended periods may affect device reliability.

DC Electrical Characteristics

Applicable over recommended operating range from: TA = -40°C to +85°C, VCC = +1.8V to +5.5V (unless otherwise noted)

Parameter	Symbol	Min.	Typ.	Max.	Unit	Condition
Supply Voltage	Vcc	1.8	-	5.5	V	
Supply Current Vcc=5.0V	Icc1	-	0.4	1.0	mA	Read @100KHz
Supply Current Vcc=5.0V	Icc2	-	2.0	3.0	mA	Write @100KHz
Standby Current	ISB	-	-	2.0	uA	Vin=Vcc or GND
Input Leakage Current	ILI	-	-	3.0	uA	Vin=Vcc or GND
Output Leakage Current	ILO	-	0.05	3.0	uA	Vout=Vcc or GND
Input Low Level	VIL	-0.6	-	Vcc×0.3	V	
Input High Level	VIH	Vcc×0.7	-	Vcc + 0.5	V	
Output Low Level Vcc=5.0V	VOL3	-	-	0.4	V	IOL=3.0mA
Output Low Level Vcc=3.0V	VOL2	-	-	0.4	V	IOL=2.1mA
Output Low Level Vcc=1.8V	VOL1	-	-	0.2	V	IOL=0.15mA

Pin Capacitance

Applicable over recommended operating range from TA = 25°C, f = 1.0 MHz, VCC = +1.8V

Parameter	Symbol	Min.	Typ.	Max.	Unit	Condition
Input/Output Capacitance (SDA)	CI/O	-	-	8	pF	VI/O = 0V
Input Capacitance (A0, A1, A2, SCL)	CIN	-	-	6	pF	VIN = 0V

AC Electrical Characteristics

Applicable over recommended operating range from TA = -40°C to +85°C, VCC = +1.8V to +5.5V, CL = 1 TTL Gate and 100 pF (unless otherwise noted)

Parameter	Symbol	1.8-volt			5.0-volt			Units
		Min.	Typ.	Max.	Min.	Typ.	Max.	
Clock Frequency, SCL	fSCL	-	-	400	-	-	1000	KHz
Clock Pulse Width Low	tLOW	1.2	-	-	0.6	-	-	us
Clock Pulse Width High	tHIGH	0.6	-	-	0.4	-	-	us
Noise Suppression Time	tI	-	-	50	-	-	40	us
Clock Low to Data Out Valid	tAA	0.05	-	0.9	0.05	-	0.55	us
Time the bus must be free before a new transmission can start	tBUF	1.2	-	-	0.5	-	-	us
Start Hold Time	tHD.STA	0.6	-	-	0.25	-	-	us
Start Setup Time	tSU.STA	0.6	-	-	0.25	-	-	us
Data In Hold Time	tHD.DAT	0	-	-	0	-	-	us
Data In Setup Time	tSU.DAT	100	-	-	100	-	-	ns
Inputs Rise Time(1)	tR	-	-	0.3	-	-	0.3	us
Inputs Fall Time(1)	tF	-	-	300	-	-	100	ns
Stop Setup Time	tSU.STO	0.6	-	-	0.25	-	-	us
Data Out Hold Time	tDH	50	-	-	50	-	-	ns
Write Cycle Time	tWR	-	-	5	-	-	5	ms
5.0V, 25°C, Byte Mode	Endurance	1M	-	-	-	-	-	Write Cycles

Note

1. This parameter is characterized and is not 100% tested.
2. AC measurement conditions: RL (connects to VCC): 1.3 kΩ (2.5V, 5V), 10 kΩ (1.8V)

Input pulse voltages: 0.3 VCC to 0.7 VCC

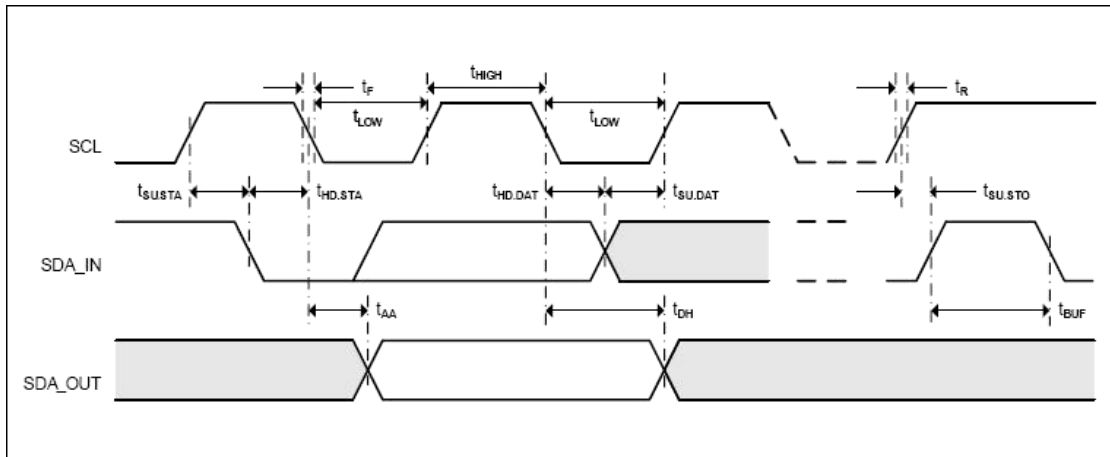
Input rise and fall time: ≤50 ns

Input and output timing reference voltages: 0.5 VCC

The value of RL should be concerned according to the actual loading on the user's system.

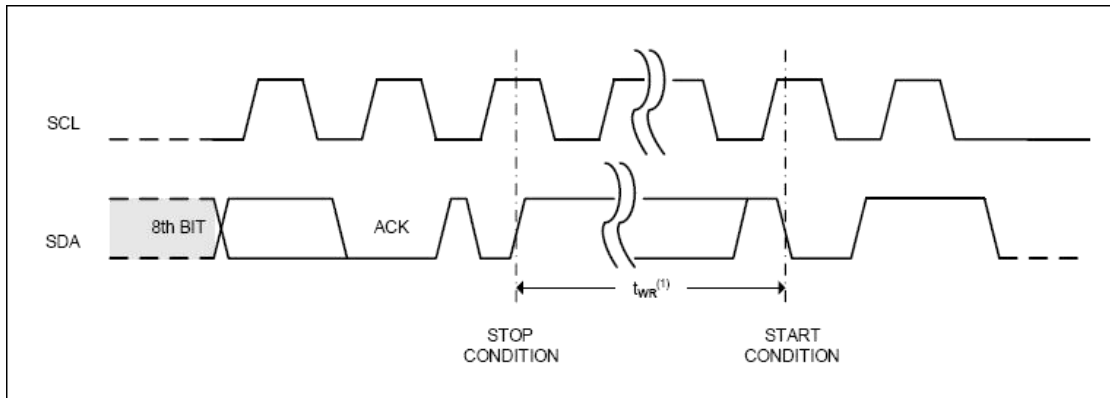
Bus Timing

- Figure 10: SCL: Serial Clock, SDA: Serial Data I/O



Write Cycle Timing

- Figure 11: SCL: Serial Clock, SDA: Serial Data I/O

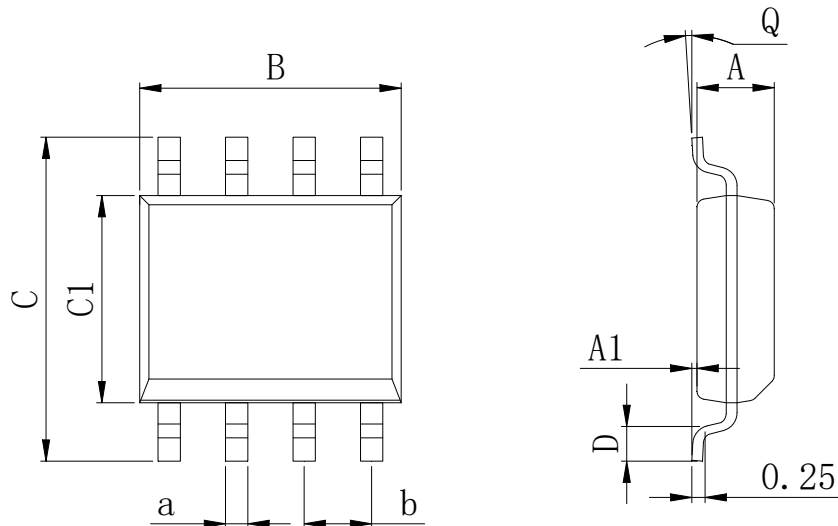


Note

1. The write cycle time t_{WR} is the time from a valid stop condition of a write sequence to the end of the internal clear/write cycle.

Physical Dimensions

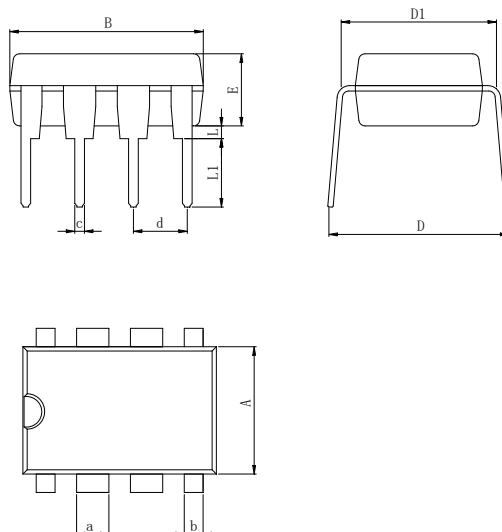
SOP-8



Dimensions In Millimeters(SOP-8)

Symbol:	A	A1	B	C	C1	D	Q	a	b
Min:	1.35	0.05	4.90	5.80	3.80	0.40	0°	0.35	1.27 BSC
Max:	1.55	0.20	5.10	6.20	4.00	0.80	8°	0.45	

DIP-8

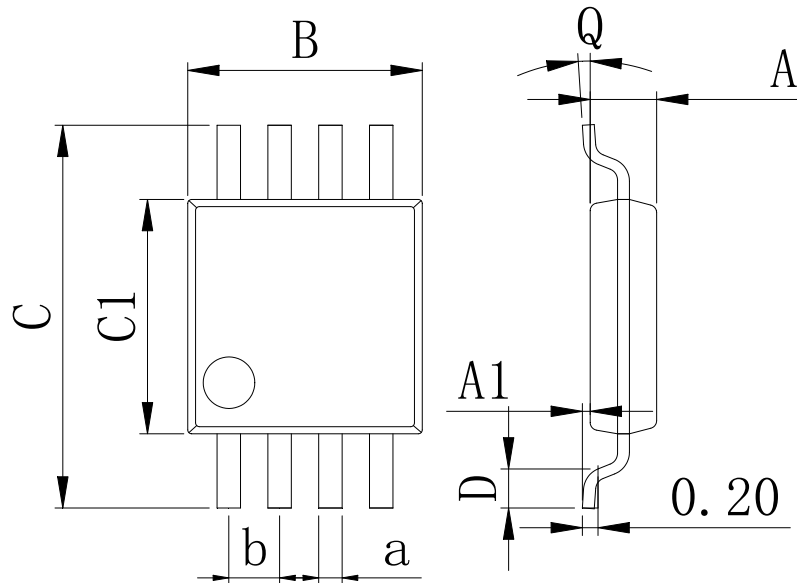


Dimensions In Millimeters(DIP-8)

Symbol:	A	B	D	D1	E	L	L1	a	b	c	d
Min:	6.10	9.00	8.10	7.42	3.10	0.50	3.00	1.50	0.85	0.40	2.54 BSC
Max:	6.68	9.50	10.9	7.82	3.55	0.70	3.60	1.55	0.90	0.50	

Physical Dimensions

MSOP-8



Dimensions In Millimeters(MSOP-8)									
Symbol:	A	A1	B	C	C1	D	Q	a	b
Min:	0.80	0.05	2.90	4.75	2.90	0.35	0°	0.25	0.65 BSC
Max:	0.90	0.20	3.10	5.05	3.10	0.75	8°	0.35	

Revision History

DATE	REVISION	PAGE
2019-10-8	New	1-14
2023-9-11	Update encapsulation type、 Update Lead Temperature、 Updated DIP-8 dimension	1、 8、 11

IMPORTANT STATEMENT:

Hanschip Semiconductor reserves the right to change its products and services without notice. Before ordering, the customer shall obtain the latest relevant information and verify whether the information is up to date and complete. Hanschip Semiconductor does not assume any responsibility or obligation for the altered documents.

Customers are responsible for complying with safety standards and taking safety measures when using Hanschip Semiconductor products for system design and machine manufacturing. You will bear all the following responsibilities: select the appropriate Hanschip Semiconductor products for your application; Design, validate and test your application; Ensure that your application meets the appropriate standards and any other safety, security or other requirements. To avoid the occurrence of potential risks that may lead to personal injury or property loss.

Hanschip Semiconductor products have not been approved for applications in life support, military, aerospace and other fields, and Hanschip Semiconductor will not bear the consequences caused by the application of products in these fields. All problems, responsibilities and losses arising from the user's use beyond the applicable area of the product shall be borne by the user and have nothing to do with Hanschip Semiconductor, and the user shall not claim any compensation liability against Hanschip Semiconductor by the terms of this Agreement.

The technical and reliability data (including data sheets), design resources (including reference designs), application or other design suggestions, network tools, safety information and other resources provided for the performance of semiconductor products produced by Hanschip Semiconductor are not guaranteed to be free from defects and no warranty, express or implied, is made. The use of testing and other quality control technologies is limited to the quality assurance scope of Hanschip Semiconductor. Not all parameters of each device need to be tested.

The documentation of Hanschip Semiconductor authorizes you to use these resources only for developing the application of the product described in this document. You have no right to use any other Hanschip Semiconductor intellectual property rights or any third party intellectual property rights. It is strictly forbidden to make other copies or displays of these resources. You should fully compensate Hanschip Semiconductor and its agents for any claims, damages, costs, losses and debts caused by the use of these resources. Hanschip Semiconductor accepts no liability for any loss or damage caused by infringement.