

MLFB-Ordering data

6SL3220-1YE34-0UF0



Client order no. : Order no. : Offer no. : Remarks:

Item no.: Consignment no. : Project :

Rated data		
Input		
Number of phases	3 AC	
Line voltage	380 480 V +10 % -20 %	
Line frequency	47 63 Hz	
Rated voltage	400V IEC	480V NEC
Rated current (LO)	59.00 A	49.00 A
Rated current (HO)	47.00 A	41.00 A
Output		
Number of phases	3 AC	
Rated voltage	400V IEC	480V NEC
Rated power (LO)	30.00 kW	40.00 hp
Rated power (HO)	22.00 kW	25.00 hp
Rated current (LO)	60.00 A	52.00 A
Rated current (HO)	45.00 A	40.00 A
Rated current (IN)	62.00 A	
Max. output current	81.00 A	
Pulse frequency	4 kHz	
Output frequency for vector control	0 200 Hz	
Output frequency for V/f control	0 550 Hz	

General tech. specifications		
Power factor λ	0.90 0.95	
Offset factor cos φ	0.99	
Efficiency η	0.98	
Sound pressure level (1m)	70 dB	
Power loss	0.770 kW	
Filter class (integrated)	Unfiltered	
EMC category (with accessories)	without	
Ambient conditions		
Standard board coating type	Class 3C2, according to IEC 60721-3-3: 2002	

Ambient conditions		
Standard board coating type	Class 3C2, according to IEC 60721-3-3: 2002	
Cooling	Air cooling using an integrated fan	
Cooling air requirement	0.055 m³/s (1.942 ft³/s)	
Installation altitude	1000 m (3280.84 ft)	
Ambient temperature		
Operation	-20 45 °C (-4 113 °F)	
Transport	-40 70 °C (-40 158 °F)	
Storage	-25 55 °C (-13 131 °F)	

Relative humidity

	95 % At 40 °C (104 °F), condensation
Max. operation	and icing not permissible

Overload capability

Low Overload (LO)

110% base load current IL for 60 s in a 300 s cycle time

High Overload (HO)

150% x base load current IH for 60 s within a 600 s cycle time



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Figure simi	

			Figure similar
Mechanical	data	Closed-loop co	ntrol techniques
Degree of protection	IP20 / UL open type	V/f linear / square-law / parameter	rizable Yes
Size	FSD		
Net weight	17 kg (37.48 lb)	V/f with flux current control (FCC)	
Width	200 mm (7.87 in)	V/f ECO linear / square-law	Yes
Height	472 mm (18.58 in)	Sensorless vector control	Yes
Depth	248 mm (9.76 in)	Vector control, with sensor	No
Inputs / out	tputs	Encoderless torque control	Yes
Standard digital inputs		Torque control, with encoder	No
Number	6	Commu	unication
Switching level: 0→1	11 V		
Switching level: 1→0	5 V	Communication	PROFINET, EtherNet/IP
Max. inrush current	15 mA	Connections	
Fail-safe digital inputs		Signal cable	
Number	1	Conductor cross-section	0.15 1.50 mm ² (AWG 24 AWG 16)
Digital outputs		Line side	
Number as relay changeover contact	2	Version	screw-type terminal
Output (resistive load)	DC 30 V, 5.0 A	Conductor cross-section	10.00 35.00 mm² (AWG 8 AWG 2)
Number as transistor	0	Motor end	
Analog / digital inputs		Version	Screw-type terminals
Number	2 (Differential input)	Conductor cross-section	10.00 35.00 mm² (AWG 8 AWG 2)
Resolution	10 bit	DC link (for braking resistor)	
Switching threshold as digital in	put	PE connection	Screw-type terminals
0→1	4 V	Max. motor cable length	• •
1→0	1.6 V	Shielded	200 m (656.17 ft)
Analog outputs		Unshielded	300 m (984.25 ft)
Number	1 (Non-isolated output)		
PTC/ KTY interface			

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1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^{\circ}\text{C}$



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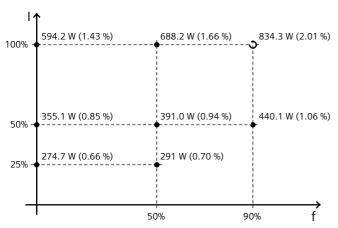
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Figure similar

Converter losses to EN 50598-2*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	-41.90 %



 $The \ percentage \ values \ show \ the \ losses \ in \ relation \ to \ the \ rated \ apparent \ power \ of \ the \ converter.$

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

Standards

Compliance with standards

UL, cUL, CE, C-Tick (RCM), EAC, KCC, SEMI F47, REACH

CE marking

EMC Directive 2004/108/EC, Low-Voltage Directive 2006/95/EC

^{*}converted values