

MLFB-Ordering data

6SL3220-1YH64-0CP0



Client order no. : Order no. :

Item no. : Consignment no. :

Project :

Order no. : Offer no. : Remarks :

Rated data			General tech	General tech. specifications	
nput			Power factor λ	0.75 0.93	
Number of phases	3 AC		Offset factor cos φ	0.96	
ine voltage	500 690 V +10 % -10 %		Efficiency η	0.98	
Line frequency	47 63 Hz		Sound pressure level (1m)	74 dB	
Rated voltage	690V IEC	600V NEC	Power loss	8.134 kW	
Rated current (LO)	596.00 A	591.00 A	Filter class (integrated)	RFI suppression filter for Category C3	
Rated current (HO)	461.00 A	501.00 A	Filter class (integrated)		
utput			EMC category (with accessories)	Category C3	
Number of phases	3 AC				
Rated voltage	690V IEC	600V NEC	Ambient conditions		
Rated power (LO)	500.00 kW	500.00 hp	Standard board coating type	Class 3C2, according to IEC 607 3: 2002	
Rated power (HO)	450.00 kW	500.00 hp			
Rated current (LO)	520.00 A	546.00 A	Cooling	Air cooling using an integrated	
Rated current (HO)	470.00 A	482.00 A			
Rated current (IN)	581.00 A		Cooling air requirement	0.450 m³/s (15.892 ft³/s)	
Max. output current	768.00 A		Installation altitude	1000 m (3280.84 ft)	
Pulse frequency	2 kHz		Ambient temperature		
Output frequency for vector control	0 100 Hz		Operation	0 45 °C (32 113 °F)	
· · · ·			Transport	-40 70 °C (-40 158 °F)	
Output frequency for V/f control	0 100 Hz		Storage	-25 55 °C (-13 131 °F)	
			Relative humidity		
			Max. operation	95 % At 40 °C (104 °F), condense	

Overload capability

Low Overload (LO)

110% base load current IL for 60 s in a 300 s cycle time

High Overload (HO)

150% x base load current IH for 60 s within a 600 s cycle time



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			Figu	
Mechanical data		Closed-loop control techniques		
Degree of protection	IP20 / UL open type	V/f linear / square-law / parame	eterizable Yes	
Size	FSJ			
Net weight	236 kg (520.29 lb)	V/f with flux current control (F		
Width	801 mm (31.54 in)	V/f ECO linear / square-law	Yes	
Height	1621 mm (63.82 in)	Sensorless vector control	Yes	
Depth	393 mm (15.47 in)	Vector control, with sensor	No	
Inputs / outputs		Encoderless torque control	Yes	
tandard digital inputs	•	Torque control, with encoder	No	
Number	6			
Switching level: 0→1	11 V	Communication		
Switching level: 1→0	5 V	Communication	PROFIBUS DP	
Max. inrush current	15 mA	Connections		
ail-safe digital inputs		Signal cable		
Number	1	Conductor cross-section	0.15 1.50 mm ² (AWG 24 AWG 16)	
Digital outputs		Line side		
Number as relay changeover contact	2	Version	M12 screw	
Output (resistive load)	DC 30 V, 5.0 A	Conductor cross-section	240.00 mm² (MCM 4 x 500 MCM 6 x 500)	
Number as transistor	0	Motor end		
nalog / digital inputs		Version	M12 screw	
Number	2 (Differential input)	Conductor cross-section 240.00 mm ² (MCM 4 x 500 MCM		
Resolution	10 bit	DC link (for broking recistor)	(IVICIAL 1 X 300 IVICIAL 0 X 300)	
witching threshold as digital in	put	DC link (for braking resistor)		
0→1	4 V	PE connection	M12 screw	
	1.6 V	Max. motor cable length		
1→0	1.0 V	Shielded	150 m (492.13 ft)	
Analog outputs				
Number	1 (Non-isolated output)			

PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^{\circ}\text{C}$



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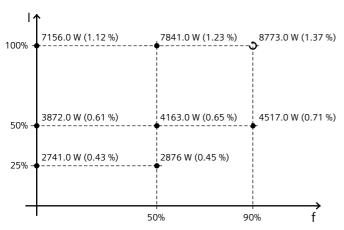
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Figure similar

Converter losses to EN 50598-2*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	-33.90 %



 $The \ percentage \ values \ show \ the \ losses \ in \ relation \ to \ the \ rated \ apparent \ power \ of \ the \ converter.$

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

Standards

Compliance with standards

UL, cUL, CE, C-Tick (RCM), EAC, KCC, SEMI F47, REACH

CE marking

EMC Directive 2004/108/EC, Low-Voltage Directive 2006/95/EC

^{*}converted values