

# **MLFB-Ordering data**

6SL3220-1YE44-0AP0



Client order no. : Order no. :

Offer no. :

Item no.: Consignment no. : Project :

Remarks:

Rated data			General tech. specifications	
Input			Power factor λ	0.90 0.95
Number of phases	3 AC		Offset factor cos φ	0.99
Line voltage	380 480 V +10 % -20 %		Efficiency η	0.98
Line frequency	47 63 Hz		Sound pressure level (1m)	72 dB
Rated voltage	400V IEC	480V NEC	Power loss	1.570 kW
Rated current (LO)	177.00 A	151.00 A	Filter class (integrated)	RFI suppression filter for Category C2
Rated current (HO)	154.00 A	132.00 A		
Output			EMC category (with accessories)	Category C2
Number of phases	3 AC			
Rated voltage	400V IEC	480V NEC	Ambient conditions	
Rated power (LO)	90.00 kW	125.00 hp	Standard board coating type	Class 3C2, according to IEC 60721-3 3: 2002
Rated power (HO)	75.00 kW	75.00 hp		
Rated current (LO)	178.00 A	156.00 A	Cooling	Air cooling using an integrated fan
Rated current (HO)	145.00 A	124.00 A		
Rated current (IN)	183.00 A		Cooling air requirement	0.153 m³/s (5.403 ft³/s)
Max. output current	241.00 A		Installation altitude	1000 m (3280.84 ft)
Pulse frequency	4 kHz		Ambient temperature	
Output frequency for vector control	0 200 Hz		Operation	-20 45 °C (-4 113 °F)
			Transport	-40 70 °C (-40 158 °F)
Output frequency for V/f control	0 550 Hz		Storage	-25 55 °C (-13 131 °F)
			Relative humidity	
Overload capability			Max. operation	95 % At 40 °C (104 °F), condensatio and icing not permissible

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#### Low Overload (LO)

110% base load current IL for 60 s in a 300 s cycle time

### High Overload (HO)

150% x base load current IH for 60 s within a 600 s cycle time

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			Figure simila		
Mechanical data		Closed-loop co	Closed-loop control techniques		
Degree of protection	IP20 / UL open type				
Size	FSF	V/f linear / square-law / parameter	<b>izable</b> Yes		
Net weight	68 kg (149.91 lb)	V/f with flux current control (FCC)	Yes		
Width	305 mm (12.01 in)	V/f ECO linear / square-law	Yes		
Height	709 mm (27.91 in)	Sensorless vector control	Yes		
Depth	369 mm (14.53 in)	Vector control, with sensor	No		
Inputs / ou	tputs	Encoderless torque control	Yes		
Standard digital inputs		Torque control, with encoder	No		
Number	6	Commu	Communication		
Switching level: 0→1	11 V				
Switching level: 1→0	5 V	Communication	PROFIBUS DP		
Max. inrush current	15 mA	Connections			
Fail-safe digital inputs		Signal cable			
Number	1	Conductor cross-section	0.15 1.50 mm <sup>2</sup> (AWG 24 AWG 16)		
Digital outputs		Line side			
Number as relay changeover contact	2	Version	M10 screw		
Output (resistive load)	DC 30 V, 5.0 A	Conductor cross-section	35.00 120.00 mm² (AWG 1 AWG 4/0)		
Number as transistor	0	Motor end			
Analog / digital inputs		Version	M10 screw		
Number	2 (Differential input)	Conductor cross-section	35.00 120.00 mm² (AWG 1 AWG 4/0)		
Resolution	10 bit	DC link (for braking resistor)	( we ran we we)		
Switching threshold as digital input					
0→1	4 V	PE connection	M10 screw		
1→0	1.6 V	Max. motor cable length			
		Shielded	150 m (492.13 ft)		
Analog outputs					

## PTC/ KTY interface

Number

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy  $\pm 5~^{\circ}\text{C}$ 

1 (Non-isolated output)



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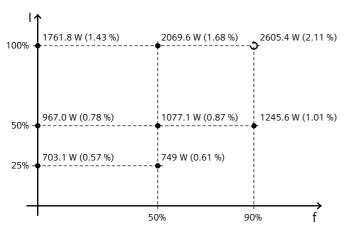
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Figure similar

## Converter losses to EN 50598-2\*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	-51.40 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

## Standards

Compliance with standards

UL, cUL, CE, C-Tick (RCM), EAC, KCC, SEMI F47, REACH

**CE** marking

EMC Directive 2004/108/EC, Low-Voltage Directive 2006/95/EC

<sup>\*</sup>converted values