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# Voltage-Output, 12-Bit Multiplying DACs

## **General Description**

The MAX501/MAX502 are 12-bit, 4-quadrant, voltageoutput, multiplying digital-to-analog converters (DACs) with an output amplifier. Thin-film resistors, laser trimmed at the wafer level, maintain accuracy over the full operating temperature range.

The MAX501/MAX502 have buffered latches that are easily interfaced with microprocessors. Data is transferred into the input register in either a right-justified 8+4-bit format (MAX501) or with a 12-bit-wide data path (MAX502). In the MAX501, an LDAC signal transfers data from the Input register to the DAC register. In the MAX502, the input registers are controlled by standard CHIP SELECT (CS) and WRITE (WR) signals. For standalone operation, the CS and WR inputs are grounded, making all latches transparent. All logic inputs are level triggered and compatible with TTL and +5V CMOS logic

The internally compensated, low-input offset-voltage output amplifier provides an output voltage from +10V to -10V while sourcing and sinking up to 5mA.

## Applications

**Digital Attenuators** Programmable-Gain Amplifiers Servo Controls Digital to 4mA-to-20mA Converters **Automatic Test Equipment** Programmable Power Supplies

## 12-Bit Voltage Output DAC

- ±10V and 5mA Output Drive
- Monotonic Over Temperature
- Four Range-Scaling Resistors
- 8+4 (MAX501) and 12-Bit (MAX502) interface
- ♦ 24-Pin DIP and Wide SO Packages

## Ordering Information

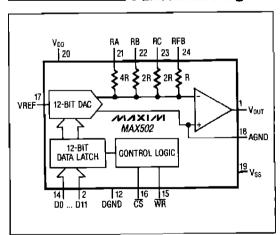
**Features** 

PART	TEMR RANGE	PIN- PACKAGE	ERROR (LSBs)
MAX501ACNG	0°C to +70°C	24 Narrow Plastic DIP	±1/2
MAX501BCNG	0°C to +70°C	24 Narrow Plastic DIP	±3/4
MAX501ACWG	0°C to +70°C	24 Wide SO	±1/2
MAX501BCWG	0°C to +70°C	24 Wide SO	±3/4
MAX501BC/D	0°C to +70°C	Dice*	±3/4
MAX501AENG	-40° C to +85° C	24 Narrow Plastic DIP	±1/2
MAX501BENG	-40° C to +85° C	24 Narrow Plastic DIP	±3/4
MAX501AEWG	-40°C to +85°C	24 Wide SO	±1/2
MAX501BEWG	-40°C to +85°C	24 Wide SO	±3/4
MAX501AMRG	-55°C to +125°C	24 Narrow CERDIP**	±1/2
MAX501BMRG	-55°C to +125°C	24 Narrow CERDIP**	±3/4

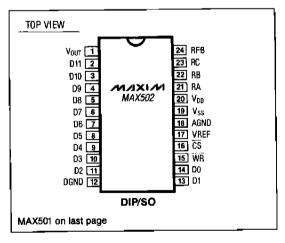
## Ordering information continued on last page

Contact factory for dica specifications. Contact factory for availability and processing to MIL-STD-883.

## Functional Diagram



## Pin Configurations



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# **ABSOLUTE MAXIMUM RATINGS**

VREF to AGND       ±25V         RFB to AGND       ±25V         RA to AGND       ±25V         RB to AGND       ±25V         RC to AGND       ±25V         VOUT to AGND (Note 1)       VDD +0.3V, VSS -0.3V         VDD to AGND       -0.3V, +17V	Digital Input Voltage to DGND         -0.3V, VDD           Continuous Power Dissipation (any package)         650mW           to +75°C         650mW           derate above +75°C         10mW/°C           Operating Temperature Ranges:         0°C to +70°C           MAX501_C, MAX502_C         -40°C to +86°C           MAX501_E, MAX502_E         -55°C to +125°C           Storage Temperature Range         -65°C to +150°C           Lead Temperature (soldering, 10 sec)         +300°C
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Note 1: Vour may be shorted to AGND, VDD, or VSS if the power dissipation of the package is not exceeded.

Stresses beyond those under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## **ELECTRICAL CHARACTERISTICS**

Dual Supply ( $V_{DD}$  = +11.4V to +15.75V,  $V_{SS}$  = -11.4V to -15.75V, VREF = +10V, AGND = DGND = 0V,  $R_L$  = 2k $\Omega$ ,  $C_L$  = 100pF, all grades,  $T_A$  =  $T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted.) (Note 2)

PARAMETER	SYMBOL	CON	DITIONS	MIN	TYP	MAX	UNITS
STATIC PERFORMANCE				Milit			UNITS
Resolution	N			12			Bits
		T <sub>A</sub> = +25° C	MAX501/502A	7		±1/2	1
Relative Accuracy	INL	1A - 125 C	MAX501/502B			±3/4	1
,	""	TA = TMIN to TMAX MAX501/502A			±3/4	LSB	
		TA - TMIN TO TMAX	MAX501/502B			±1	1
Differential Nonlinearity	DNL					±1	LSB
	1	T <sub>A</sub> = +25°C				±1	†  —
Zero-Code Offset Error	TA = TMIN to TMAX	MAX501/502_C/E			±2	m∨	
		TA TMIN TO TMAX	MAX501/502_M			±3	1
Offset Temperature Coefficient	ΔV <sub>OS</sub> / ΔTemp				±5		µV/°C
		RFB, Vout connecte	ed				
Gain Error		RC or RB connected VREF = 5V	to V <sub>OUT</sub> ,	_		±4½	LSB
		RA, VOUT connected	, VREF = 2.5V	T -			1
Gain Temperature Coefficient	ΔGain/ ΔTemp				±1		ppm/°C
Reference Input Resistance	T	RFB		8	12	16	kΩ
Application Resistor Ratio Matching		RA to RB to RC mate	 h	† <del>-</del>		0.5	%

## **ELECTRICAL CHARACTERISTICS (continued)**

Dual Supply (V<sub>DD</sub> = +11.4V to +15.75V, V<sub>SS</sub> = -11.4V to -15.75V, VREF = +10V, AGND = DGND = 0V, R<sub>L</sub> =  $2k\Omega$ , C<sub>L</sub> = 100pF, all grades, T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted.) (Note 2)

PARAMETER	SYMBOL	CON	IDITIONS	MIN	TYP	MAX	UNITS
DIGITAL INPUTS		<u> </u>				_	1
Indust Customet	1	V 014 and 14	T <sub>A</sub> = +25°C			±1	Ι.
Input Current	JIM	VIN = 0V and VDD	TA = TMIN to TMAX			±10	μA
Input Low Voltage	VIL					8.0	V
Input High Voltage	ViH			2.4			V
Input Capacitance	Cin				7		рF
POWER SUPPLIES							
Supply Voltage	Voo			11.40		15.75	v
ouppiy voltage	VSS			-11.40		-15.75	] <b>"</b>
Supply Current	lpb	Vour unloaded				10	4
Cuppiy Curtent	Iss	Vour unloaded				4	mA
		_	VREF ≈ -10V V <sub>DD</sub> = 15V ± 5%				
Daving Grands Balantina	200	ΔGain/ΔV <sub>DD</sub>	VREF = -8.9V V <sub>DD</sub> = 12V ± 5%			±0.02	
Power-Supply Rejection	PSR		VREF = 10V Vss = -15V ± 5%				%/%
		ΔGain/ΔV <sub>SS</sub>	VREF = 8.9V § Vss = -12V ± 5%			±0.02	
DYNAMIC PERFORMANCE (Not	e 3)	<u> </u>	II.				1
Output-Voltage Settling Time	ts	To ±0.01% of full sca	ale			5	μв
Slew Rate	SR				5		V/µs
DAC Glitch Impulse		Major carry transition	on -		450		nV-s
Multiplying Feedthrough Error		VREF = ±10V at 10k	Hz, DAC = all 0s		5		mVp₋p
Unity-Gain Small-Signal Bandwidth				-	3		MHz
Full-Power Bandwidth		-			250		kHz
Total Harmonic Distortion	THD	VREF = 6VRMS at 1k	:Hz	-	-90		dB
OUTPUT CHARACTERISTICS		<u> </u>		•			
Open-Loop Gain	Avo	RFB not connected,	V <sub>OUT</sub> = ±10V, R <sub>L</sub> = 2kΩ	90			dB
Output Resistance	Ro				0.2		Ω
Short-Circuit Current		T <sub>A</sub> = +25°C			20		mA
Output Maine Maltana		0.1Hz to 10Hz, T <sub>A</sub> =	+25° C		2		µVRMS
Output Noise Voltage		f = 1kHz, T <sub>A</sub> = +25°(	;		25		nV√Hz

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TIMING CHARACTERISTICS (See Figures 1a, 1b) Dual Supply ( $V_{DD}$  = +11.4V to +15.75V,  $V_{SS}$  = -11.4V to -15.75V, VREF = +10V, AGND = DGND = 0V,  $R_L$  = 2k $\Omega$ ,  $C_L$  = 100pF, all grades,  $T_A$  =  $T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted.) (Note 2)

PARAMETER	SYMBOL	CON	CONDITIONS		TYP	MAX	UNITS	
MAX501		•	_				1	
Chip Select to Write-Setup Time	tcs						ns	
Write Pulse Width		T <sub>A</sub> = +25°C		55				
Write Pulse Wigth	twn	TA = TMIN to TMAX		70			ns	
Data Satura Time	1.	MAX501_C/E	_	50				
Data-Setup Time	tos	MAX501_M		60	-		ns	
Data-Hold Time	tDH			10	0	_	ns	
LDAC Pulse Width	tLDAC			70			ns	
CLR Pulse Width	tcla	_		70			ns	
SET Pulse Width	tset .		<u> </u>	200			ns	
MAX502	·			•		_		
Chip Select to Write-Setup Time	tcs	_		0			ns	
		T <sub>A</sub> = +25°C		40				
Write Pulse Width	twn	twn	MAX502_C/E	50	_		ns	
		TA = TMIN to TMAX	MAX502_M	60			1	
Data-Setup Time	•	MAX502_C/E		50				
Data-Soluh Hills	tos	MAX502_M		60			ns	
Data-Hold Time	t <sub>DH</sub>			10	0		ns	

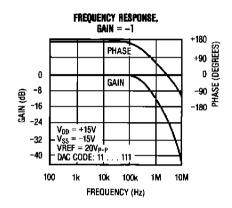
Note 2: V<sub>OUT</sub> must be less than V<sub>DD</sub> - 2.5V and greater than V<sub>SS</sub> + 2.5V to ensure correct operation. Performance at supplies other than V<sub>DD</sub> = +15V and V<sub>SS</sub> = -15V is guaranteed by PSRR tests. Leave unused feedback resistors floating.

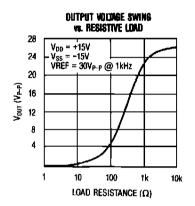
Note 3: Dynamic Performance and Output Characteristics are included for design guidance and are not subject to test.

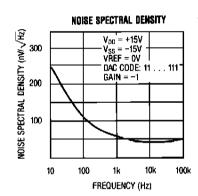
# MAX501/MAX502

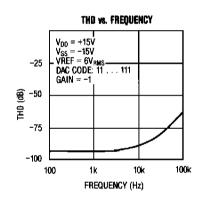
# Voltage-Output, 12-Bit Multiplying DACs

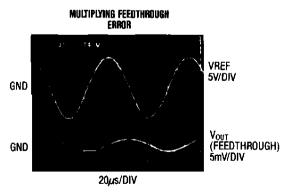
## Typical Operating Characteristics

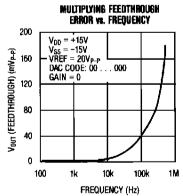












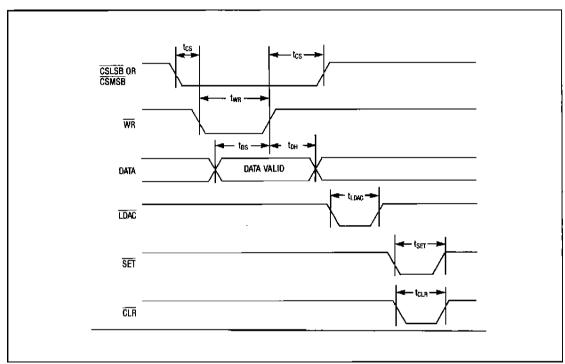


Figure 1a. MAX501 Timing Diagram

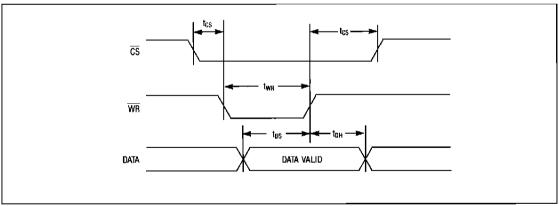


Figure 1b. MAX502 Timing Diagram

- NOTES: 1. All input signal rise and fall times measured from 10% to 90% of +5V,  $t_R=t_F=$  20ns.
- 2. Timing measurement reference level is  $\frac{V_{IH}+V_{JL}}{2}$

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MAX50	ı	<u></u>
PIN	NAME	FUNCTION
1	<b>Υ</b> ουτ	Voltage Output
2	LDAC	Asynchronous Load DAC Input is active low
3	SET	Sets DAC register to all 1s
4	CLR	Sets DAC register to all 0s
5-8	D7-D4	Data Bits 7 to 4
9	D3/D11	Data Bit 3 or 11
10	D2/D10	Data Bit 2 or 10
11	D1/D9	Data Bit 1 or 9
12	DGND	Digital Ground
13	D0/D8	Data Bit 0 or 8 (LSB)
14	CSLSB	LSB Chip-Select Input is active low
15	WR	Write Input is active low
16	CSMSB	MSB Chip-Select Input is active low
17	VREF	Reference Input to DAC
18	AGND	Analog Ground
19	Vss	-12V to -15V Supply Voltage Input
20	V <sub>DD</sub>	+12V to +15V Supply Voltage Input
21	RA	Scaling Resistor: RA = 4RFB
22	RB	Scaling Resistor: RB = 2RFB
23	RC	Scaling Resistor: RC = 2RFB
24	RFB	Feedback Resistor

AX50:	2	
PIN	NAME	FUNCTION
1	Vout	Voltage Output
2–11	D11-D2	Data Bits 2 to 11 (MSB)
12	DGND	Digital Ground
3,14	D1, D0	Data Bits 0 to 1 (LSB)
15	WR	Write Input is active low
16	CS	Chip-Select Input is active low
17	VREF	Reference Input to DAC
18	AGND	Analog Ground
19	Vss	-12V to -15V Supply Voltage input
20	VDD	+12V to +15V Supply Voltage Input
21	RA	Scaling Resistor: RA = 4RFB
22	RB	Scaling Resistor: RB = 2RFB
23	RC	Scaling Resistor: RC = 2RFB
24	RFB	Feedback Resistor

# Detailed Description Digital Circuit

Figures 2a and 2b are simplified circuit diagrams of the MAX501 and MAX502 input control logic. For the MAX501, a low on CSLSB and WR with CSMSB high loads the least significant bit (LSB) byte into the input register. The LSB byte is then latched into the input register on the rising edge of either a WR or a CSLSB. Similarly, a low on CSMSB and WR with CSLSB high

loads the most significant bit (MSB) nibble into the input register. The MSB nibble is then latched into the input register on the rising edge of either a  $\overline{\text{WR}}$  or a CSMSB pulse. With all 12 bits loaded, a low on LDAC transfers the data to the DAC register. For the MAX502, a low on CS and WR transfers the data on the input registers to the DAC latch. Both parts' digital inputs are TTL and CMOS compatible, providing easy microprocessor ( $\mu$ P) interfacing. Tables 1 and 2 are MAX501 and MAX502 truth tables.

Table 1. MAX501 Truth Table

WR	CSMSB	CSLSB	LDAC	CLR	SET	OPERATION
x	х	х	Х	х	0	DAC Register overridden by 1's Input Register unaffected
X	Х	×	х	0	1	DAC Register overridden by 0's Input Register unaffected
0	_0	1	_ 1	1	1	Load MSB nibble into Input Register
0	1	0	1	1	1	Load LSB byte into Input Register
Х	_x	х	_ 0	1	1	Transfer Input Register to DAC Register
1	X	_ x	_1	1	1	No Operation
0	11	1	1	1	1	No Operation
0	R	1	1	1	1	Latching MSB nibble into Input Register
R	0	1 1	1	1	1	Latching MSB nibble into Input Register
O	1	R	1	1	1	Latching LSB byte Into Input Register
A_	1	0	1	1	1	Latching LSB byte into Input Register

H = High State, L = Low State, R = Rising Edge, X = Don't Care

Table 2. MAX502 Truth Table

WR	<u>cs</u>	OPERATION
Н	х	No Operation
Х	Н	No Operation
L	L	Input Register is Transparent
L	R	Input Register is Latched
R	L	Input Register is Latched

H = High State, L = Low State, R = Rising Edge, X = Don't Care

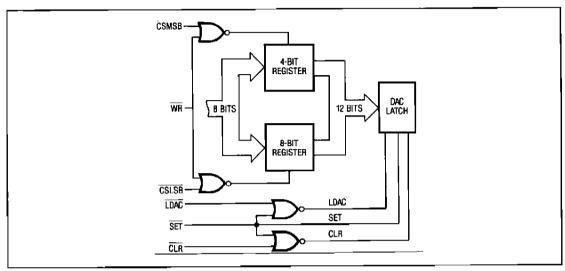


Figure 2a. MAX501 Input Control Logic

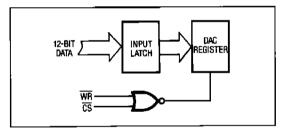


Figure 2b. MAX502 Input Control Logic

## Digital-to-Analog Converter

The MAX501/MAX502 have a 12-bit, binary-weighted, current-output DAC with standard R-2R ladder (Figure 3). Binarily weighted currents are switched between AGND and the inverting input of the internal output amplifier. The output amplifier, typically connected to the feedback resistor RFB, converts the output current to a voltage. With RFB connected to VOUT,

where D is the fractional expression of the digital input code divided by full scale. D can vary from 0 to 4095/4096 in unipolar mode.

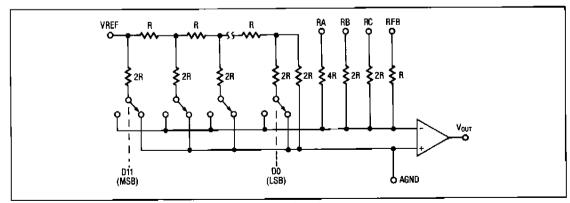


Figure 3. MAX501/MAX502 Simplified DAC and Amplifier Circuit

### Output-Buffer Amplifier

The output amplifier is an internally compensated, non-inverting, gain-scalable amplifier that can develop  $\pm 10V$  across a  $2k\Omega$  load. Maximum settling time is less than 5µs (to within 0.01% FSR). Input offset voltage is laser trimmed at the wafer level. Slew rate is typically  $7V/\mu s$ . The gain-setting resistors (RA, RB, and RC) connect to the amplifier inverting terminal. Float unused gain-setting resistors.

## **Unipolar Configuration**

Figure 4, a typical configuration for the MAX501/MAX502, provides for unipolar-bipolar operation or two-quadrant multiplication when VIN is an AC signal. R1 adjusts gain and R3 adjusts zero offset. For fixed-reference applications, trim the reference voltage and omit R1 and R2. If R1 and R2 are included, you must take into account their gain-temperature coefficient. The typical gain-temperature coefficient of the MAX502 is 1ppm/°C, which corresponds to a gain shift of ¹/2LSB over a +100°C temperature range. Table 3 is the code table for unipolar-binary operation.

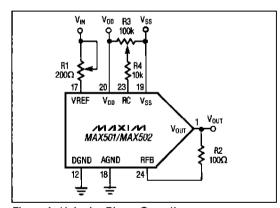


Figure 4. Unipolar-Binary Operation (2-Quadrant Multiplication)

Table 3. MAX501/MAX502 Unipolar-Binary Code Table

Dic	GITAL INF	TU	ANALOG OUTPUT
1111	1111	1111	(-V <sub>IN</sub> ) 4095 4096
1000	0000	0000	$(-V_{IN})\frac{2048}{4096} = -\frac{1}{2}V_{IN}$
0000	0000	0001	(-V <sub>IN</sub> ) 1/4096
0000	0000	0000	ov

## **Bipolar Operation**

Figure 5 shows a 4-quadrant, bipolar operation. Gain error may be adjusted by changing the R1 and R2 ratio. These resistors should be ratio-matched to 0.01% to stay within gain-error specifications and to eliminate trimming. The offset value is defined by matching the RB and RC internal resistors. Table 4 is the code table for bipolar-binary operation.

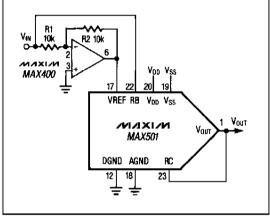


Figure 5. Bipolar Operation (4-Quadrant Multiplication)

Table 4. MAX501/MAX502 Bipolar-Binary Code Table

DIC	BITAL INF	7U°	ANALOG OUTPUT
1111	1111	1111	(+V <sub>IN</sub> ) 2047 2048
1000	0000	0001	(+V <sub>IN</sub> ) 1/2048
1000	0000	0000	ov
0111	1111	1111	(-VIN) 1/2048
0000	0000	0000	$(-V_{IN})\frac{2048}{2048} = V_{IN}$

# Applications information

AC or transient voltages between AGND and DGND can cause noise injection into the analog output. Tie the MAX502 AGND to DGND to ensure both pins are at the same potential. If these ground pins connect to separate backplanes, use two back-to-back diodes to tie the pins together. Also, decouple VDD and Vss to AGND, as µP-based systems generally have noisy grounds that couple into the power supplies.

## Digital Giltohes

Any digital word written into the DAC causes a glitch impulse. This impulse couples across the stray capacitance of the DAC switches to the output bus. A glitch impulse on this bus is converted to a voltage by RFB and the output amplifier. The output voltage glitch energy is the product of its duration and its average magnitude (the net area under the curve), and is expressed in (nV)(s). The energy is measured with VREF connected to analog ground and the DAC register alternately loaded with all 0s and all 1s.

### Digital Foodthrough

Most of the MAX501/MAX502's digital inputs are directly connected to the  $\mu P$  bus. These inputs are constantly changing, even when the DAC is not selected. High-frequency logic activity on the data bus can feed through the DAC package capacitance as noise on the DAC output. Figure 6 shows an interface that minimizes digital feedthrough. All data inputs are latched from the busy by  $\overline{\text{CS}}$ . Alternatively, using peripheral interface devices reduces digital feedthrough.

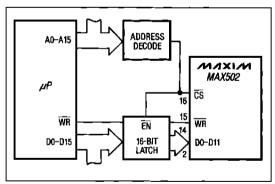


Figure 6. MAX502 Interface Circuit — Latches Minimize Digital Feedthrough

# MAX502 Microprocessor Interfacing 16-Bit Microprocessor Systems

Figures 7-9 show the MAX502 interfaced with the MC68000, the 8086, and the TMS32010. The MAX502 appears as a memory-mapped peripheral to the processors. In each case, a write instruction loads the MAX502 with the appropriate data. The particular instructions used are as follows:

MC68000: MOVE 8086: MOV TMS32010: OUT

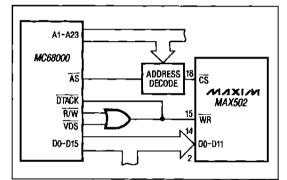


Figure 7. MAX502 to MC6800 Interface

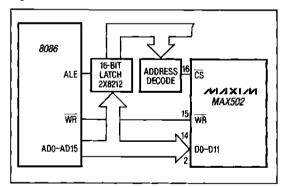


Figure 8. MAX502 to 8086 Interface

# **AX501/MAX502**

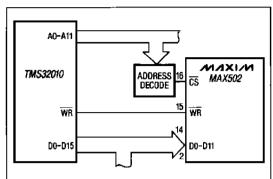


Figure 9. MAX502 to TMS32010 Interface

# MAX501 Microprocessor Interfacing 8-Bit Microprocessor Systems

Figure 10 shows an interface circuit for the MAX501 to the 8085A 8-bit  $\mu$ P. The software routine to load data to the device is given in Table 3. Note that transferring 12 data bits requires two write operations. The first of these loads the 4 MSBs into the 7475 latch. The second write operation loads the 8 LSBs plus the 4 MSBs (which are held by the latch) into the DAC.

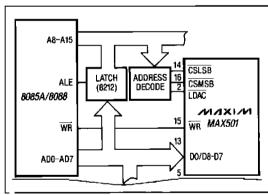
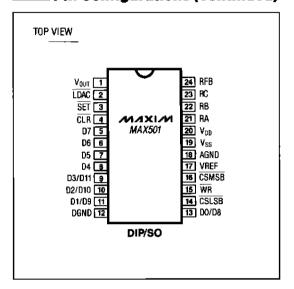


Figure 10. MAX501 to 8085A/8088 Interface

## Pin Configurations (continued)



## Ordering Information (continued)

PART	TEMP. RANGE	PIN- PACKAGE	ERROR (LSBe)
MAX502ACNG	0°C to +70°C	24 Narrow Plastic DIP	1/2
MAX502BCNG	0°C to +70°C	24 Narrow Plastic DIP	3/4
MAX502ACWG	0°C to +70°C	24 Wide SO	1/2
MAX502BCWG	0°C to +70°C	24 Wide SO	3/4
MAX502BC/D	0°C to +70°C	Dice*	3/4
MAX502AENG	-40°C to +85°C	24 Narrow Plastic DIP	1/2
MAX502BENG	-40°C to +85°C	24 Narrow Plastic DIP	3/4
MAX502AEWG	-40°C to +85°C	24 Wide SO	1/2
MAX502BEWG	-40°C to +85°C	24 Wide SO	3/4
MAX502AMRG	-55°C to +125°C	24 Narrow CERDIP**	1/2
MAX502BMRG	-55°C to +125°C	24 Narrow CERDIP**	3/4

- Contact factory for dice specifications.

  Contact factory for evallability and processing to MIL-STD-883.

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