



54121/DM54121/DM74121 One-Shot with Clear and Complementary Outputs

General Description

The DM54/74121 is a monostable multivibrator featuring both positive and negative edge triggering with complementary outputs. An internal $2k\Omega$ timing resistor is provided for design convenience minimizing component count and layout problems. This device can be used with a single external capacitor. Inputs (A) are active-low trigger transition inputs and input (B) is an active-high transition Schmitt-trigger input that allows jitter-free triggering from inputs with transition rates as slow as 1 volt/second. A high immunity to V_{CC} noise of typically 1.5V is also provided by internal circuitry at the input stage.

To obtain optimum and trouble free operation please read operating rules and NSC one-shot application notes carefully and observe recommendations.

Features

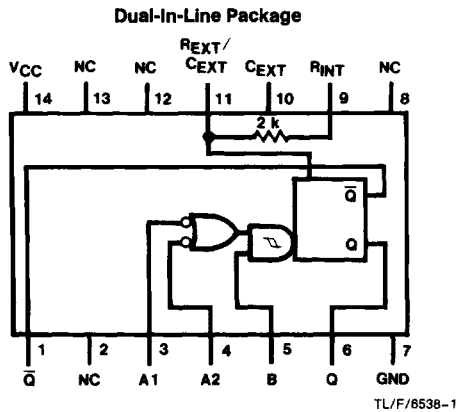
- Triggered from active-high transition or active-low transition inputs
- Variable pulse width from 30 ns to 28 seconds

- Jitter free Schmitt-trigger input
- Excellent noise immunity typically 1.2V
- Stable pulse width up to 90% duty cycle
- TTL, DTL compatible
- Compensated for V_{CC} and temperature variations
- Input clamp diodes
- Alternate Military/Aerospace device (54121) is available. Contact a National Semiconductor Sales Office/Distributor for specifications.

Functional Description

The basic output pulse width is determined by selection of an internal resistor R_{INT} or an external resistor (R_X) and capacitor (C_X). Once triggered the output pulse width is independent of further transitions of the inputs and is a function of the timing components. Pulse width can vary from a few nano-seconds to 28 seconds by choosing appropriate R_X and C_X combinations. There are three trigger inputs from the device, two negative edge-triggering (A) inputs, one positive edge Schmitt-triggering (B) input.

Connection Diagram



Order Number 54121DMQB, 54121FMQB,
DM54121J, DM54121W or DM74121N
See NS Package Number J14A, N14A or W14B

Function Table

| Inputs | | | Outputs | |
|--------|----|---|---------|-----------|
| A1 | A2 | B | Q | \bar{Q} |
| L | X | H | L | H |
| X | L | H | L | H |
| X | X | L | L | H |
| H | H | X | L | H |
| H | ↓ | H | ⌋ | ⌋ |
| ↓ | H | H | ⌋ | ⌋ |
| ↓ | ↓ | H | ⌋ | ⌋ |
| L | X | ↑ | ⌋ | ⌋ |
| X | L | ↑ | ⌋ | ⌋ |

- H = High Logic Level
L = Low Logic Level
X = Can Be Either Low or High
↑ = Positive Going Transition
↓ = Negative Going Transition
⌋ = A Positive Pulse
⌋ = A Negative Pulse

Absolute Maximum Ratings (Note)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/Distributors for availability and specifications.

| | |
|--------------------------------------|-----------------|
| Supply Voltage | 7V |
| Input Voltage | 5.5V |
| Operating Free Air Temperature Range | |
| DM54 | -55°C to +125°C |
| DM74 | 0°C to +70°C |
| Storage Temperature Range | -65°C to +150°C |

Note: The "Absolute Maximum Ratings" are those values beyond which the safety of the device cannot be guaranteed. The device should not be operated at these limits. The parametric values defined in the "Electrical Characteristics" table are not guaranteed at the absolute maximum ratings. The "Recommended Operating Conditions" table will define the conditions for actual device operation.

Recommended Operating Conditions

| Symbol | Parameter | DM54121 | | | DM74121 | | | Units |
|------------------|---|---|-----|------|---------|-----|------|-------|
| | | Min | Nom | Max | Min | Nom | Max | |
| V _{CC} | Supply Voltage | 4.5 | 5 | 5.5 | 4.75 | 5 | 5.25 | V |
| V _{T+} | Positive-Going Input Threshold Voltage at the A Input (V _{CC} = Min) | | 1.4 | 2 | | 1.4 | 2 | V |
| V _{T-} | Negative-Going Input Threshold Voltage at the A Input (V _{CC} = Min) | 0.8 | 1.4 | | 0.8 | 1.4 | | V |
| V _{T+} | Positive-Going Input Threshold Voltage at the B Input (V _{CC} = Min) | | 1.5 | 2 | | 1.5 | 2 | V |
| V _{T-} | Negative-Going Input Threshold Voltage at the B Input (V _{CC} = Min) | 0.8 | 1.3 | | 0.8 | 1.3 | | V |
| I _{OH} | High Level Output Current | | | -0.4 | | | -0.4 | mA |
| I _{OL} | Low Level Output Current | | | 16 | | | 16 | mA |
| t _w | Input Pulse Width (Note 1) | 40 | | | 40 | | | ns |
| dV/dt | Rate of Rise or Fall of Schmidt Input (B) (Note 1) | | | 1 | | | 1 | V/s |
| dV/dt | Rate of Rise or Fall of Logic Input (A) (Note 1) | | | 1 | | | 1 | V/μs |
| R _{EXT} | External Timing Resistor (Note 1) | 1.4 | | 30 | 1.4 | | 40 | kΩ |
| C _{EXT} | External Timing Capacitance (Note 1) | 0 | | 1000 | 0 | | 1000 | μF |
| DC | Duty Cycle (Note 1) | R _T = 2 kΩ | | 67 | | | 67 | % |
| | | R _T = R _{EXT} (Max) | | 90 | | | 90 | |
| T _A | Free Air Operating Temperature | -55 | | 125 | 0 | | 70 | °C |

Note 1: T_A = 25°C and V_{CC} = 5V.

Electrical Characteristics over recommended operating free air temperature range (unless otherwise noted)

| Symbol | Parameter | Conditions | Min | Typ (Note 1) | Max | Units |
|-----------------|-----------------------------------|--|-----------|--------------|------|-------|
| V _I | Input Clamp Voltage | V _{CC} = Min, I _I = -12 mA | | | -1.5 | V |
| V _{OH} | High Level Output Voltage | V _{CC} = Min, I _{OH} = Max, V _{IL} = Max, V _{IH} = Min | 2.4 | 3.4 | | V |
| V _{OL} | Low Level Output Voltage | V _{CC} = Min, I _{OL} = Max, V _{IH} = Min, V _{IL} = Max | | 0.2 | 0.4 | V |
| I _I | Input Current @ Max Input Voltage | V _{CC} = Max, V _I = 5.5V | | | 1 | mA |
| I _{IH} | High Level Input Current | V _{CC} = Max V _I = 2.4V | A1, A2 | | 40 | μA |
| | | | B | | 80 | |
| I _{IL} | Low Level Input Current | V _{CC} = Max V _I = 0.4V | A1, A2 | | -1.6 | mA |
| | | | B | | -3.2 | |
| I _{OS} | Short Circuit Output Current | V _{CC} = Max (Note 2) | DM54 | -20 | -55 | mA |
| | | | DM74 | -18 | -55 | |
| I _{CC} | Supply Current | V _{CC} = Max | Quiescent | 13 | 25 | mA |
| | | | Triggered | 23 | 40 | |

Note 1: All typicals are at V_{CC} = 5V, T_A = 25°C.

Note 2: Not more than one output should be shorted at a time.

Switching Characteristics at $V_{CC} = 5V$ and $T_A = 25^\circ C$ (See Section 1 for Test Waveforms and Output Load)

| Symbol | Parameter | From (Input) To (Output) | Conditions | Min | Max | Units |
|--------------|---|--------------------------------|--|-----|-----|-------|
| t_{PLH} | Propagation Delay Time Low to High Level Output | A1, A2 to Q | $C_{EXT} = 80 \text{ pF}$ $R_{INT} \text{ to } V_{CC}$ $C_L = 15 \text{ pF}$ $R_L = 400\Omega$ | | 70 | ns |
| t_{PLH} | Propagation Delay Time Low to High Level Output | B to Q | | | 55 | ns |
| t_{PHL} | Propagation Delay Time High to Low Level Output | A1, A2 to \bar{Q} | | | 80 | ns |
| t_{PHL} | Propagation Delay Time High to Low Level Output | B to \bar{Q} | | | 65 | ns |
| $t_{W(OUT)}$ | Output Pulse Width Using the Internal Timing Resistor | A1, A2 or B to Q, \bar{Q} | $C_{EXT} = 80 \text{ pF}$ $R_{INT} \text{ to } V_{CC}$ $R_L = 400\Omega$ $C_L = 15 \text{ pF}$ | 70 | 150 | ns |
| $t_{W(OUT)}$ | Output Pulse Width Using Zero Timing Capacitance | A1, A2 to Q, \bar{Q} | $C_{EXT} = 0 \text{ pF}$ $R_{INT} \text{ to } V_{CC}$ $R_L = 400\Omega$ $C_L = 15 \text{ pF}$ | | 50 | ns |
| $t_{W(OUT)}$ | Output Pulse Width Using External Timing Resistor | A1, A2 to Q, \bar{Q} | $C_{EXT} = 100 \text{ pF}$ $R_{INT} = 10 \text{ k}\Omega$ $R_L = 400\Omega$ $C_L = 15 \text{ pF}$ | 600 | 800 | ns |
| | | A1, A2 to Q, \bar{Q} | $C_{EXT} = 1 \mu\text{F}$ $R_{INT} = 10 \text{ k}\Omega$ $R_L = 400\Omega$ $C_L = 15 \text{ pF}$ | 6 | 8 | ms |

Operating Rules

- To use the internal $2 \text{ k}\Omega$ timing resistor, connect the R_{INT} pin to V_{CC} .
- An external resistor (R_X) or the internal resistor ($2 \text{ k}\Omega$) and an external capacitor (C_X) are required for proper operation. The value of C_X may vary from 0 to any necessary value. For small time constants use high-quality mica, glass, polypropylene, polycarbonate, or polystyrene capacitors. For large time constants use solid tantalum or special aluminum capacitors. If the timing capacitors have leakages approaching 100 nA or if stray capacitance from either terminal to ground is greater than 50 pF the timing equations may not represent the pulse width the device generates.
- The pulse width is essentially determined by external timing components R_X and C_X . For $C_X < 1000 \text{ pF}$ see *Figure 1* design curves on T_W as function of timing components value. For $C_X > 1000 \text{ pF}$ the output is defined as:

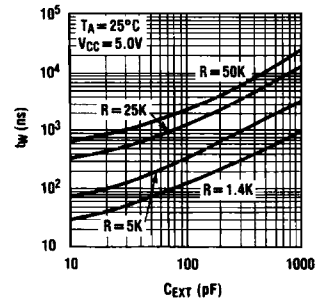
$$t_W = K R_X C_X$$

where [R_X is in Kilo-ohm]

[C_X is in pico Farad]

[T_W is in nano second]

[$K \approx 0.7$]



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FIGURE 1

- If C_X is an electrolytic capacitor a switching diode is often required for standard TTL one-shots to prevent high inverse leakage current (*Figure 2*).

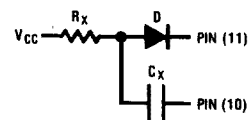


FIGURE 2

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Operating Rules (Continued)

5. Output pulse width versus V_{CC} and operation temperatures: *Figure 3* depicts the relationship between pulse width variation versus V_{CC} . *Figure 4* depicts pulse width variation versus ambient temperature.

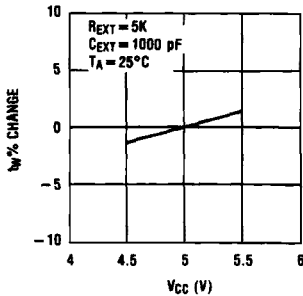


FIGURE 3

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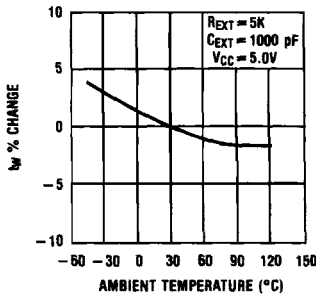


FIGURE 4

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6. The "K" coefficient is not a constant, but varies as a function of the timing capacitor C_X . *Figure 5* details this characteristic.

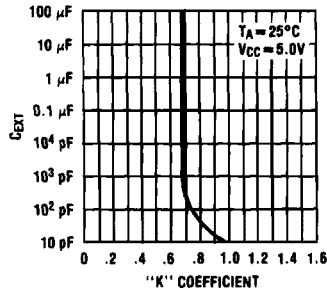


FIGURE 5

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- Under any operating condition C_X and R_X must be kept as close to the one-shot device pins as possible to minimize stray capacitance, to reduce noise pick-up, and to reduce $I \times R$ and $L di/dt$ voltage developed along their connecting paths. If the lead length from C_X to pins (10) and (11) is greater than 3 cm, for example, the output pulse width might be quite different from values predicted from the appropriate equations. A non-inductive and low capacitive path is necessary to ensure complete discharge of C_X in each cycle of its operation so that the output pulse width will be accurate.
- V_{CC} and ground wiring should conform to good high-frequency standards and practices so that switching transients on the V_{CC} and ground return leads do not cause interaction between one-shots. A 0.01 μF to 0.10 μF bypass capacitor (disk ceramic or monolithic type) from V_{CC} to ground is necessary on each device. Furthermore, the bypass capacitor should be located as close to the V_{CC} -pin as space permits.

For further detailed device characteristics and output performance please refer to the NSC one-shot application note, AN-366.