

STT-MRAM Datasheet

PM002MN1A



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Shanghai Siproin Microelectronics

<http://www.siproin.com>

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1 Features

The PM002M is Mbit of SPI/QPI (serial/quad parallel interface) MRAM device. This device is configurable as 1 bit I/O separate or 4 bits I/O common interface. The PM002M has MRAM technology in memory array. The data in the memory array will be sustained with data retention greater than 20 years.

Density

- 2Mbits

Fast SPI interface

- Up to 50MHz clock frequency @SPI SDR
- Up to 50MHz clock frequency @QPI SDR
- Support standard SPI, Quad SPI mode
- Write no delay
- Support SPI mode0 and mode3

Single voltage operation

- Typical Voltage: 3.3V Vcc=2.7V~3.6V

Data protection

- Software protection mode with BP0,BP1 in mode register#1

Power consumption

- Sleep current 2uA (Typical value)
- Standby current 2mA (Typical value)
- Active current 4.3mA (Typical value @SPI 50MHz)

Reliability

- Data retention >20years @85°C
- P/E cycle up to 10⁸

Package

- SOP8_150MIL

Temperature range

- Junction temperature: -40°C~85°C

2 Pin Information

2.1 SOP8

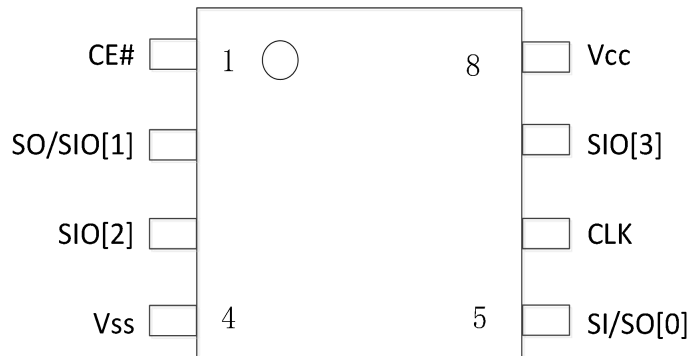


Figure 1: Package Information

3 Pin Description

Table1: Pin Description

| Symbol | Signal Type | SPI Mode | QPI Mode |
|-----------|-------------|--|----------|
| CE# | Input | Chip select signal,Active low.When CE input is high ,Memory will be in standby state | |
| SO/SIO[1] | I/O | Serial output | I/O[1] |
| SIO[2] | I/O | I/O[2]* | I/O[2] |
| Vss | Ground | Core Supply | Ground |
| SI/SO[0] | I/O | Serial input | I/O[0] |
| CLK | Input | Clock Signal | |
| SIO[3] | I/O | I/O[3]* | I/O[3] |
| Vcc | Power | Core Power Supply | |

*Fast read Quad access and Quad write access in SPI Mode use SIO[2] and SIO[3];

Recommend to pull down Vcc or to GND if no use of SIO[2] and SIO[3] in SPI Mode;

4 Operation Flow

According SPI protocol, the first 8 bits of DI is COMMAND (op_code), which define which operation the memory will do. The following 24bits (3 bytes) are address phase, which defined the memory array row address and column address. According current array density, PM002M use 17 of 24 address to feed in memory address, and left spare MSB bit with '0'.

Every command sequence starts with a one-byte command code. Depending on the command, this might be followed by 3-byte (24-bit) address plus dummy cycles and data byte(s).

All commands, addresses, and dummy bits are shifted in of the PM002M device with the most significant bit first. The data bits are also shifted in or out of the PM002M with the most significant bit.

The figure below explains relation between internal memory array organization and external I/O. This device has 16 internal I/O plates. Once memory read or write operation starts, these 16 internal I/O plates works parallelly. Because of this internal memory plates organization, the minimum burst access for read or write operation becomes 2 Bytes access.

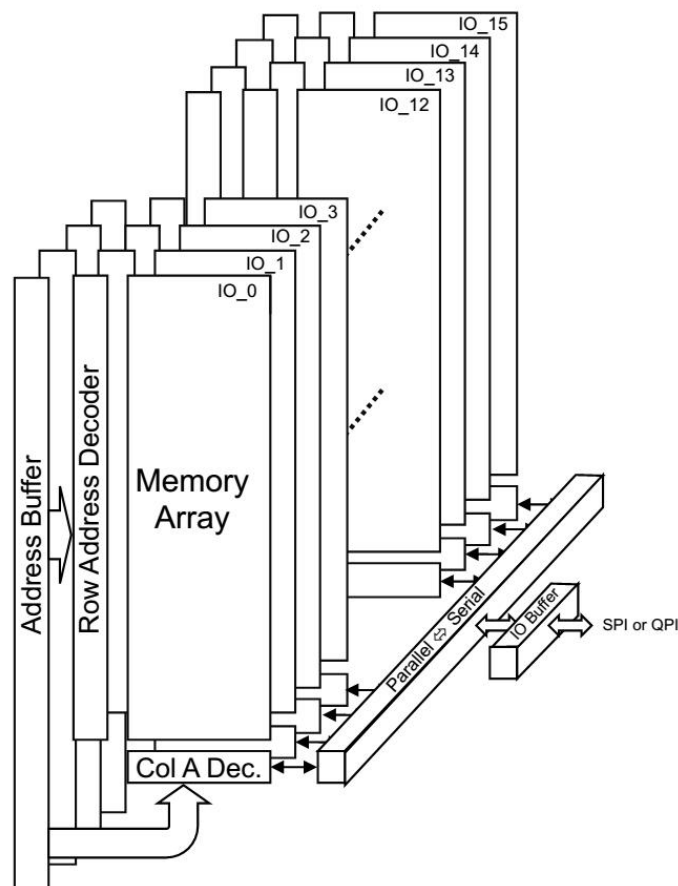


Figure 2: Operation Flow

5 SPI mode commands

Table 2: SPI Mode Commands

| Command | SPI Mode | | | | | | |
|-----------------------------|----------|---------|---------|---------|-------------|---------|---------|
| | Byte1 | Byte2 | Byte3 | Byte4 | Byte5 | Byte6 | Byte7 |
| Number of Clocks | 8 | 8(or 2) | 8(or 2) | 8(or 2) | 8(or 2) | 8(or 2) | 8(or 2) |
| Mode Register Write | B1H | A23-A16 | A16-A8 | A7-A0 | Value#n | | |
| Mode Register Read | B5H | A23-A16 | A16-A8 | A7-A0 | Value#n | | |
| Write | 02H | A23-A16 | A16-A8 | A7-A0 | D15-D8 | D7-D0 | |
| Quad Write | 38H | A23-A16 | A16-A8 | A7-A0 | D15-D8 | D7-D0 | |
| Read | 03H | A23-A16 | A16-A8 | A7-A0 | Dummy(0~12) | D15-D8 | D7-D0 |
| Quad Read | EBH | A23-A16 | A16-A8 | A7-A0 | Dummy(0~12) | D15-D8 | D7-D0 |
| Write Enable | 06H | | | | | | |
| Write Disable | 04H | | | | | | |
| Entry To Deep PowerDown | B9H | | | | | | |
| Exit From Deep PowerDown | ABH | | | | | | |
| Read Unique ID Register | 9FH | 0H | 0H | 0H | 16 Bytes | | |
| Enter QPI Mode | 35H | | | | | | |
| Reset Enable | 66H | | | | | | |
| Reset | 99H | | | | | | |

5.1 Control Command Operation

Control command include WriteEnable,WriteDisable,Entry To Sleep,Exit From Sleep,

Enter QPI Mode. For example Enter QPI Mode:

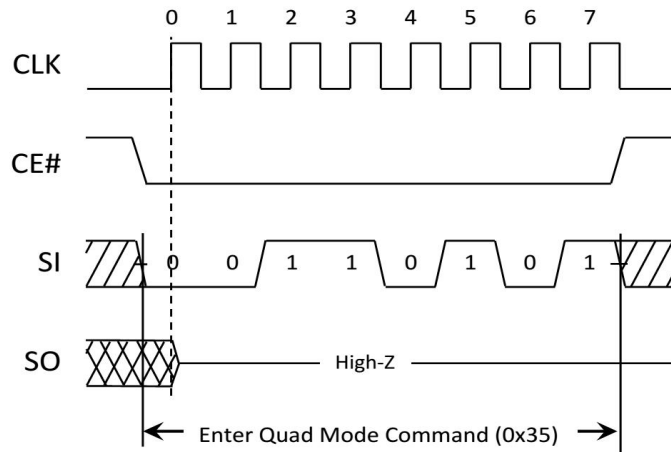


Figure 3: Enter QPI Command Timing

5.2 Reset Operation

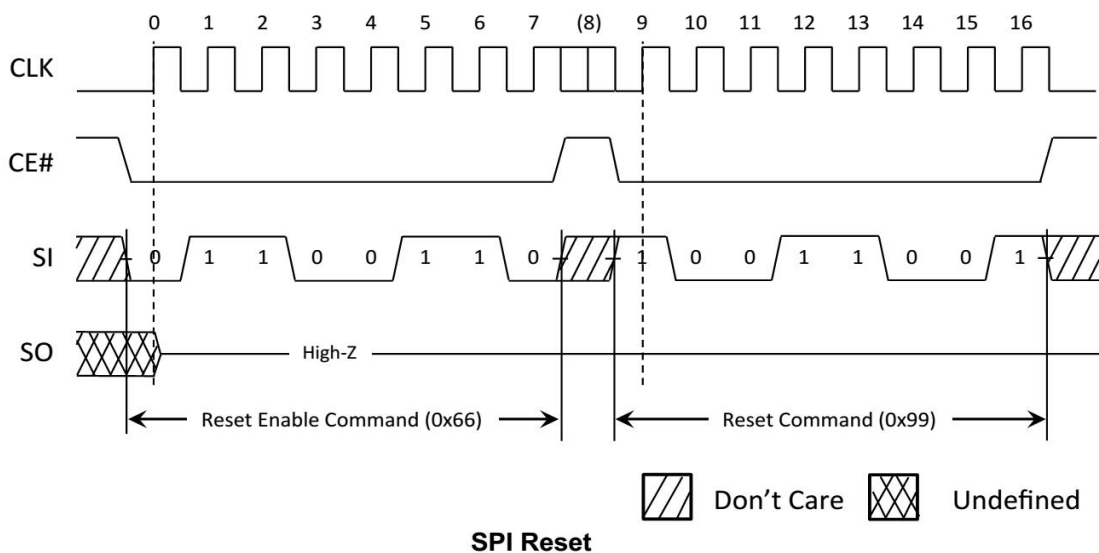


Figure 4: SPI Reset Operation Timing

5.3 Mode Register Write Command Timing

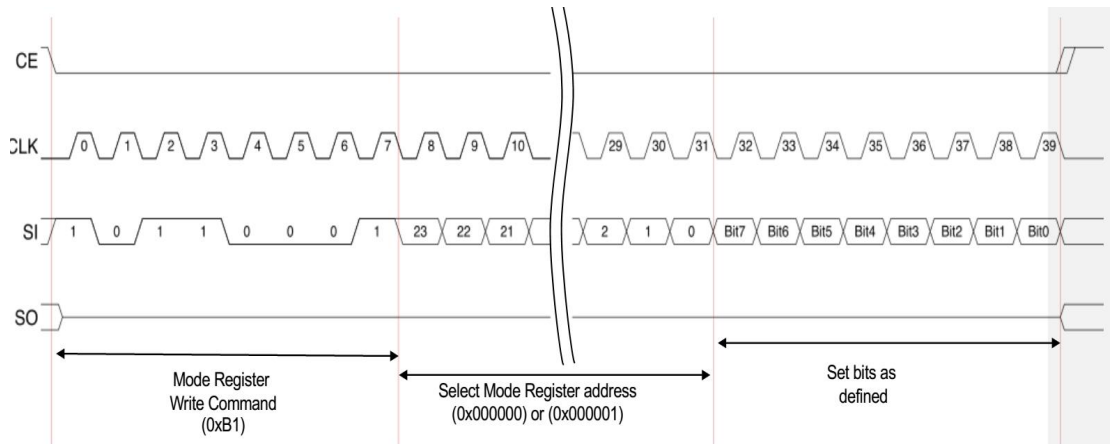


Figure 5: SPI Mode Register Write Command Timing

5.4 Mode Register Read Command Timing

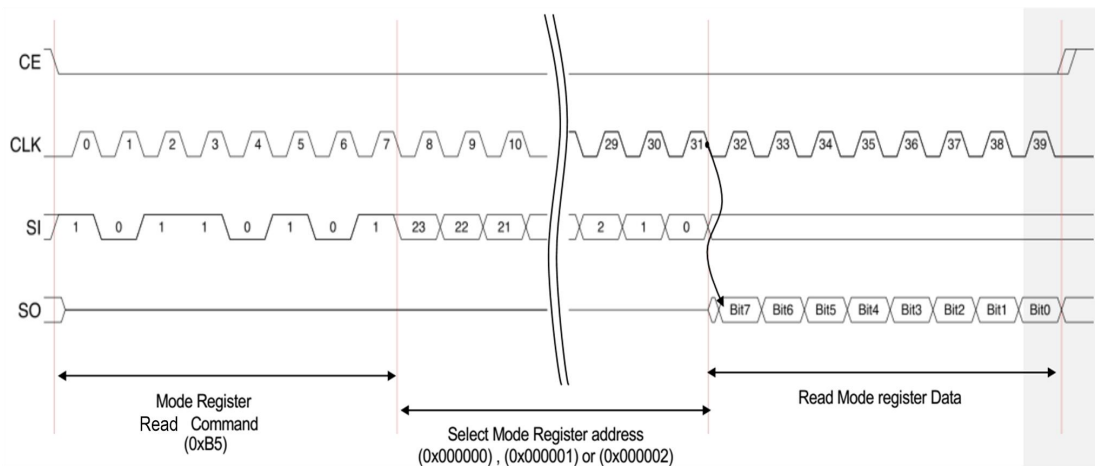


Figure 6: SPI Mode Register Read Command Timing

5.5 SPI Write Command Timing

The first byte(Bit7~Bit0) means IO_15~IO_8, the followed byte(Bit7~Bit0) means IO_7~IO_0.

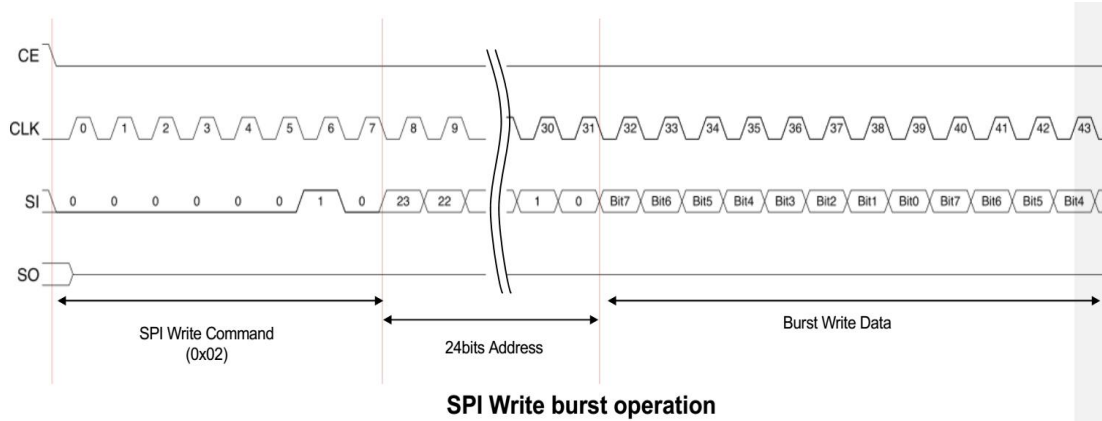


Figure 7: SPI Write Command Timing

5.6 SPI Read Command Timing

The first byte(Bit7~Bit0) means IO_15~IO_8, the followed byte(Bit7~Bit0) means IO_7~IO_0 .

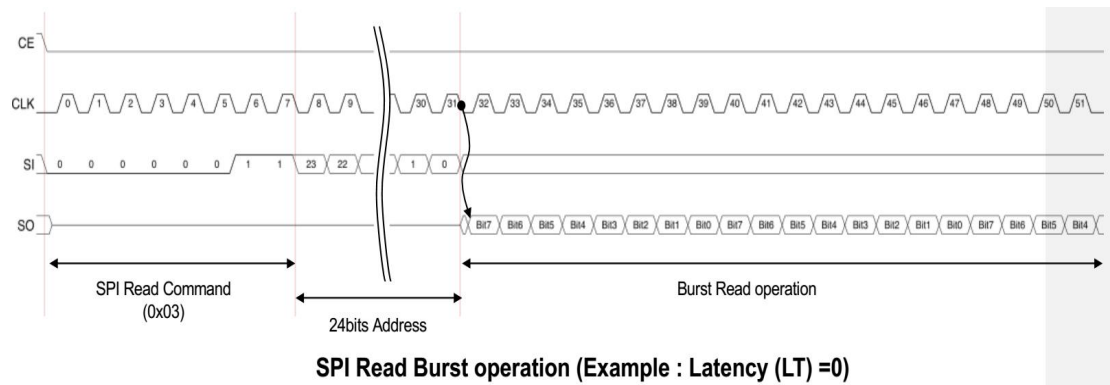


Figure 8: SPI Read Command Timing (Example: Latency(LT)=0)

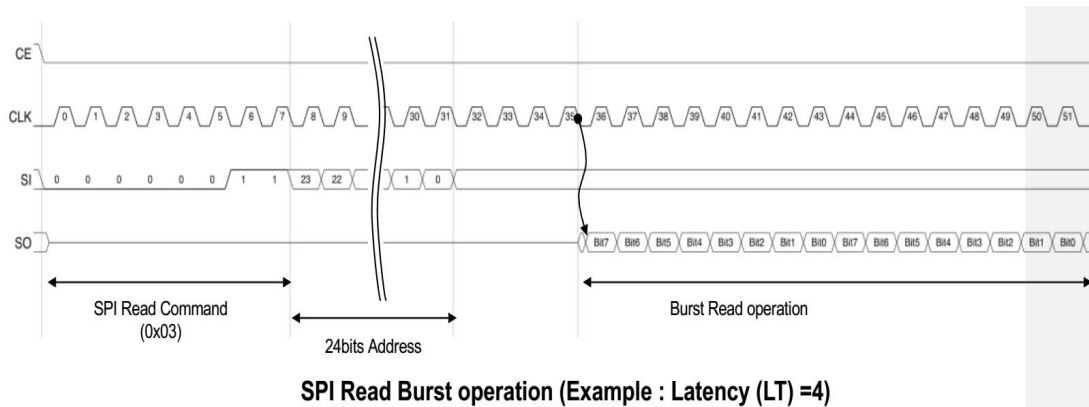
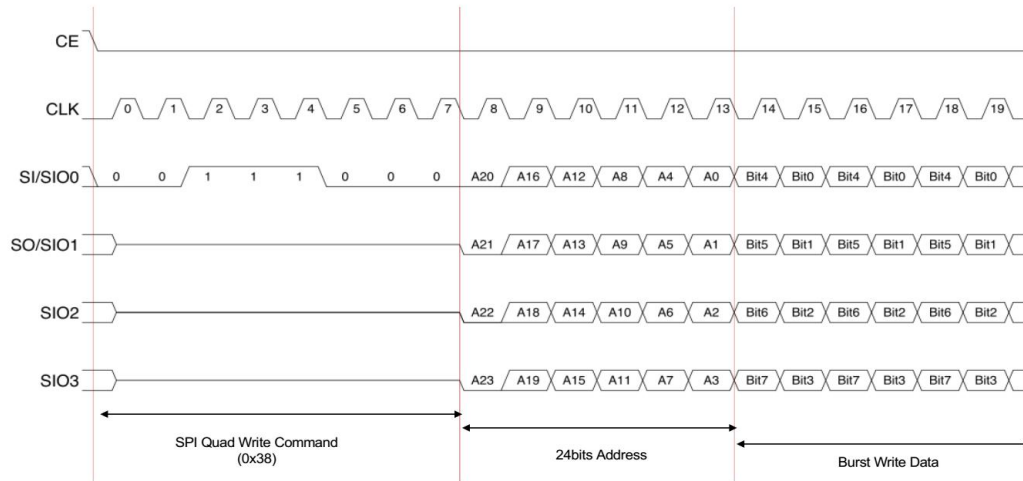


Figure 9: SPI Read Command Timing (Example: Latency(LT)=4)

5.7 SPI QuadWrite Command Timing

The first byte(Bit7~Bit0) means IO_15~IO_8, the followed byte(Bit7~Bit0) means IO_7~IO_0.



SPI Quad Write burst operation

Figure 10: SPI QuadWrite Command Timing

5.8 SPI QuadRead Command Timing

The first byte(Bit7~Bit0) means IO_15~IO_8, the followed byte(Bit7~Bit0) means IO_7~IO_0.

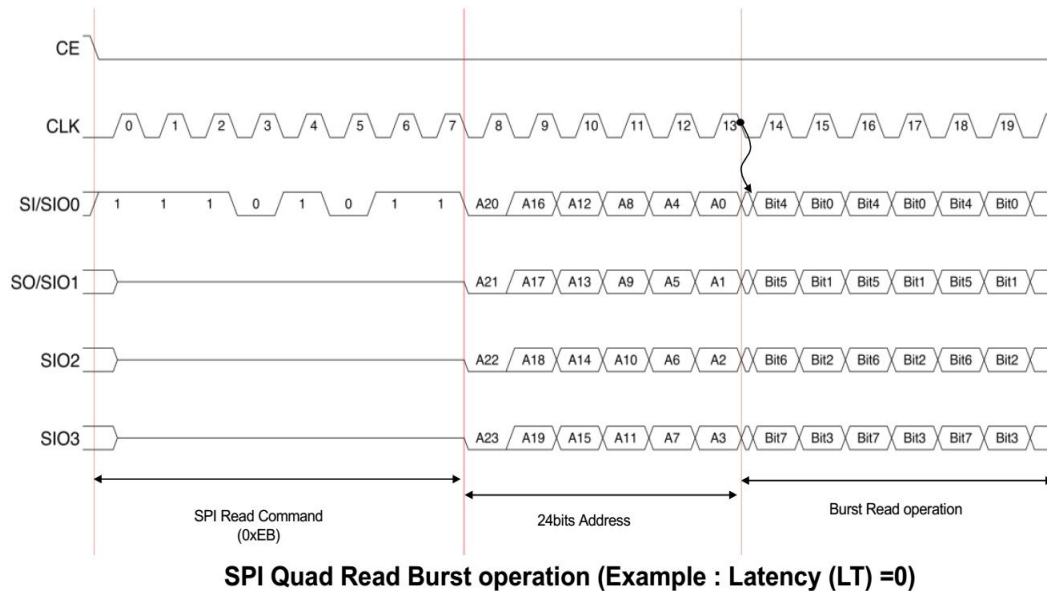
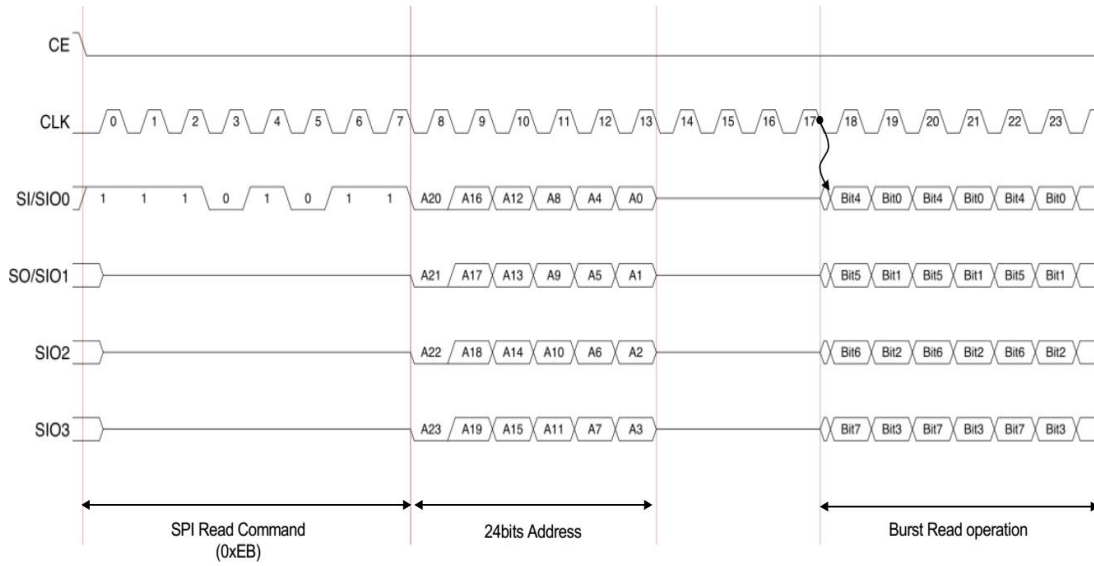


Figure 11: SPI QuadRead Command Timing (Example: Latency(LT)=0)

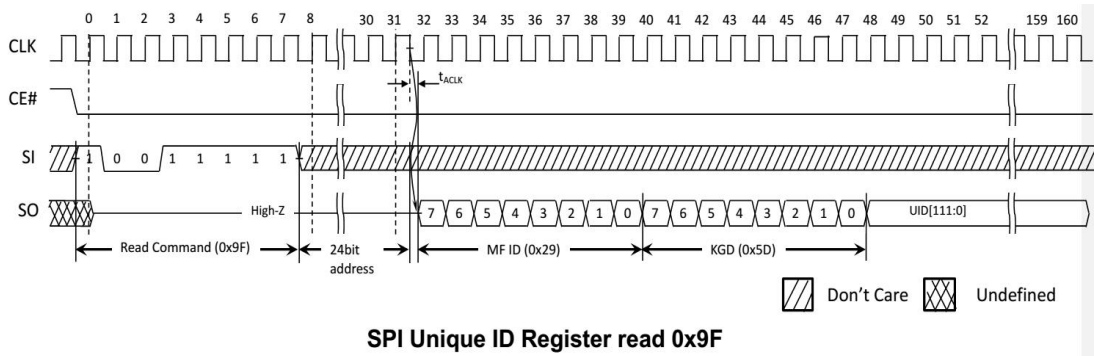


SPI Quad Read Burst operation (Example : Latency (LT) =4)

Figure 12: SPI QuadRead Command Timing (Example: Latency(LT)=4)

5.9 SPI Unique ID Operation

The two bytes are used for Manufacture ID (0x29, 0x55) and the two bytes can be read by SPI instruction.



SPI Unique ID Register read 0x9F

Figure 13: SPI Unique ID Read Command Timing

6 QPI mode commands

Table 3: QPI Mode Commands

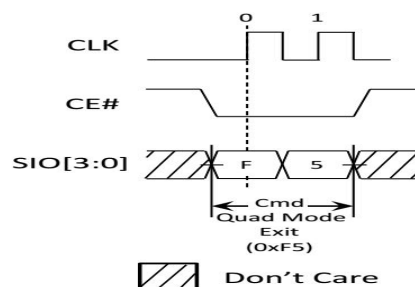
| Command | QPI Mode | | | | | | |
|--------------------------|----------|---------|--------|-------|-------------|---------|-------|
| | Byte1 | Byte2 | Byte3 | Byte4 | Byte5 | Byte6 | Byte7 |
| Number of Clocks | 2 | 2 | 2 | 2 | 2 | 2 | 2 |
| Mode Register Write | B1H | A23-A16 | A16-A8 | A7-A0 | Value#n | | |
| Mode Register Read | B5H | A23-A16 | A16-A8 | A7-A0 | Dummy(2) | Value#n | |
| Write | 02H | A23-A16 | A16-A8 | A7-A0 | D15-D8 | D7-D0 | |
| Read | 03H | A23-A16 | A16-A8 | A7-A0 | Dummy(0~12) | D15-D8 | D7-D0 |
| Write Enable | 06H | | | | | | |
| Write Disable | 04H | | | | | | |
| Entry To Deep PowerDown | B9H | | | | | | |
| Exit From Deep PowerDown | ABH | | | | | | |
| Read Unique ID Register | 9FH | 0H | 0H | 0H | 16 Bytes | | |
| Exit QPI Mode | F5H | | | | | | |
| Reset Enable | 66H | | | | | | |
| Reset | 99H | | | | | | |

At power up, QPI mode is disabled.

6.1 Control Command Operation

Control command include Write Enable, Write Disable, Entry To Sleep, Exit From Sleep,

Exit QPI Mode. For example Exit QPI Mode:


Figure 14: Exit QPI Command Timing

6.2 Reset Operation

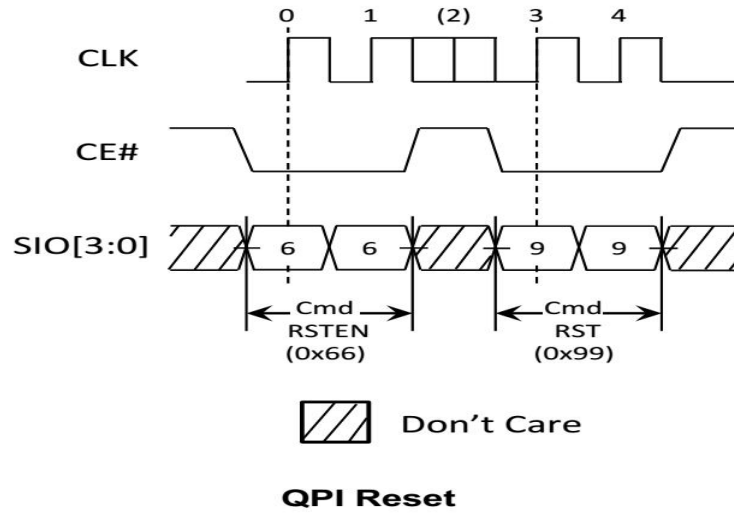


Figure 15: QPI Reset Operation Timing

6.3 Mode Register Write Command Timing

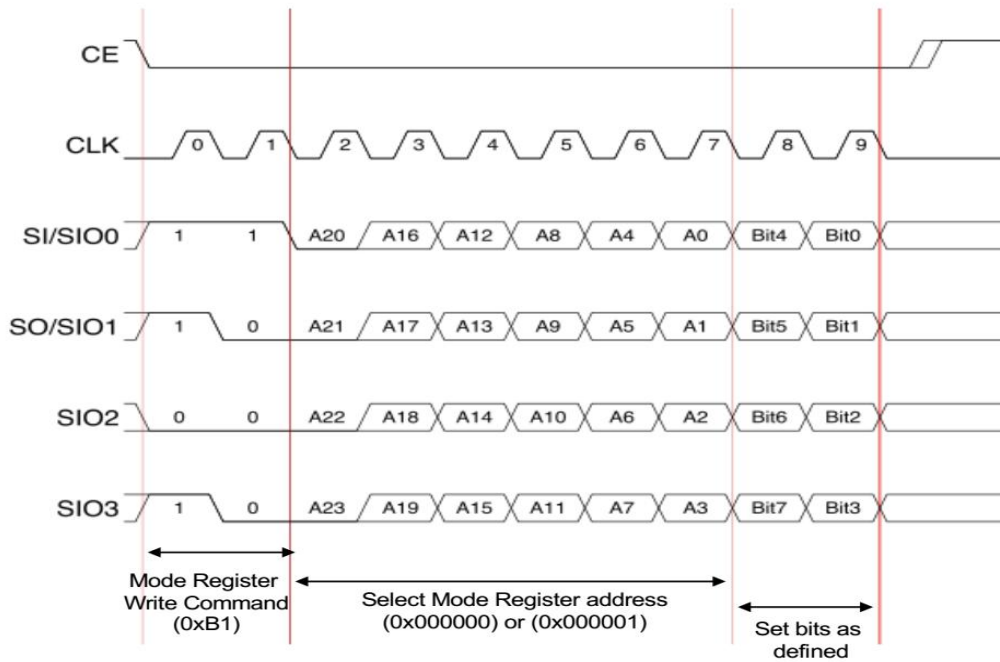


Figure 16: QPI Mode Register Write Command Timing

6.4 Mode Register Read Command Timing

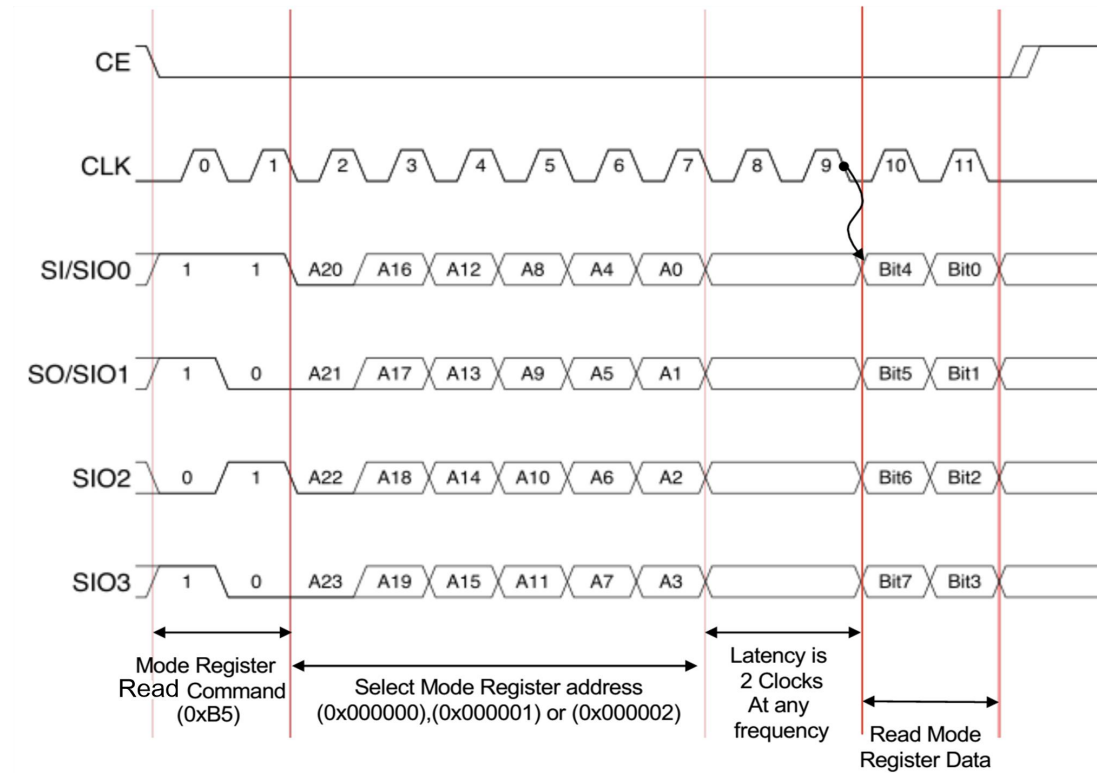


Figure 17: QPI Mode Register Read Command Timing

6.5 QPI Write Command Timing

The first byte(Bit7~Bit0) means IO_15~IO_8, the followed byte(Bit7~Bit0) means IO_7~IO_0 .

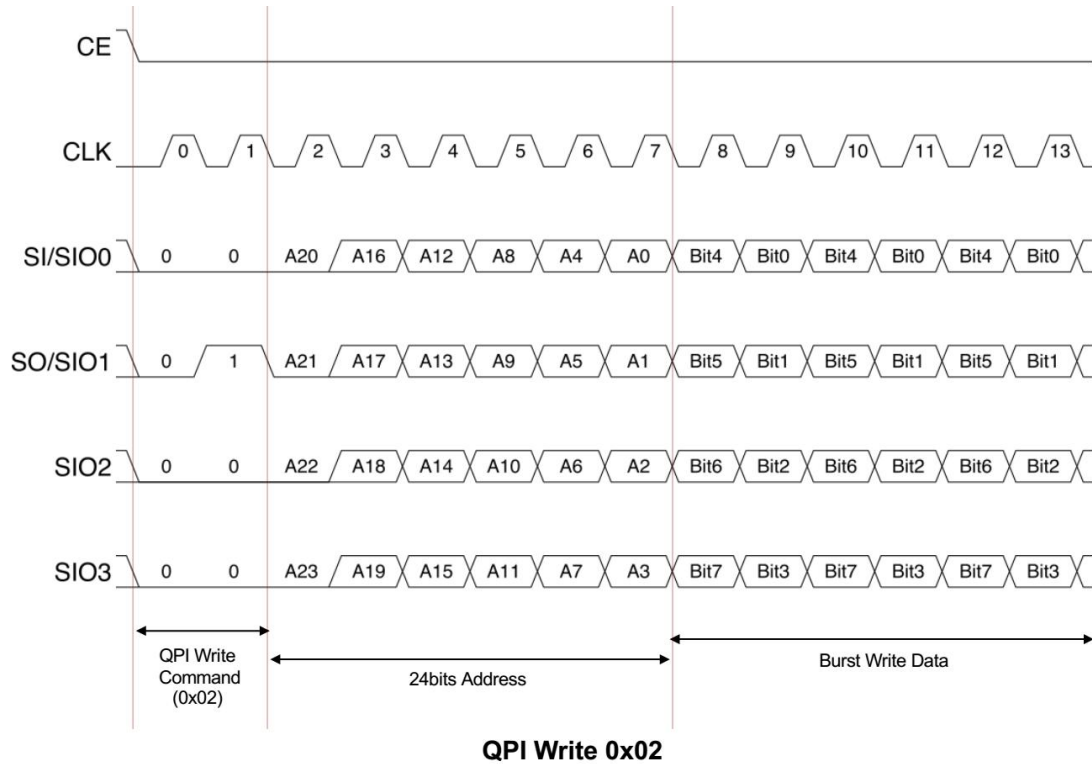


Figure 18: QPI Write Command Timing

6.6 QPI Read Command Timing

The first byte(Bit7~Bit0) means IO_15~IO_8, the followed byte(Bit7~Bit0) means IO_7~IO_0 .

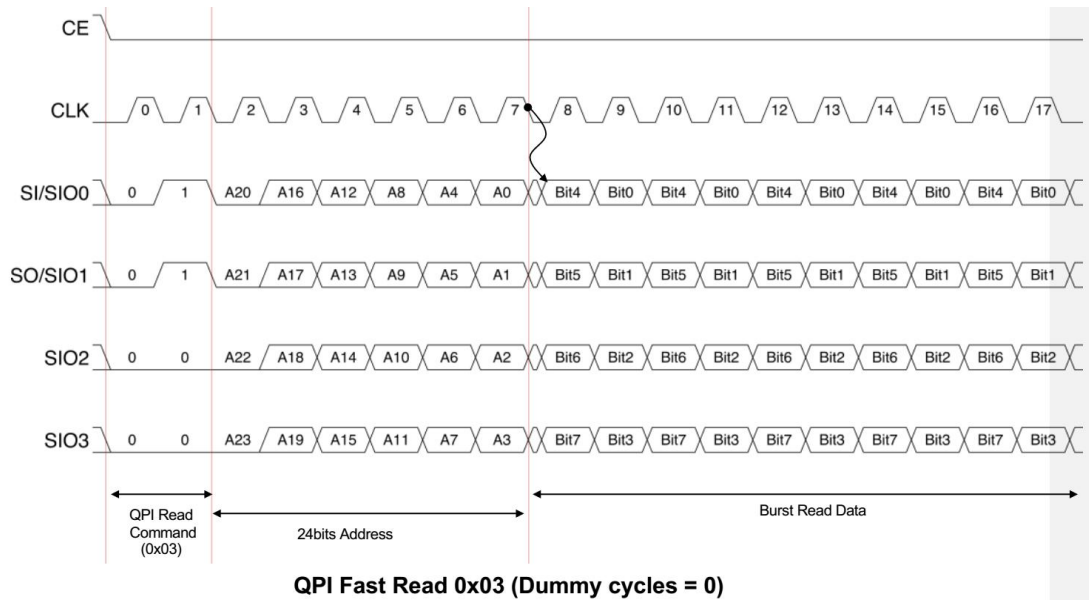


Figure 19: QPI Read Command Timing (Example: Dummy cycles=0)

6.7 QPI Unique ID Operation

The two bytes are used for Manufacture ID (0x29, 0x55) and the two bytes can be read by SPI instruction.

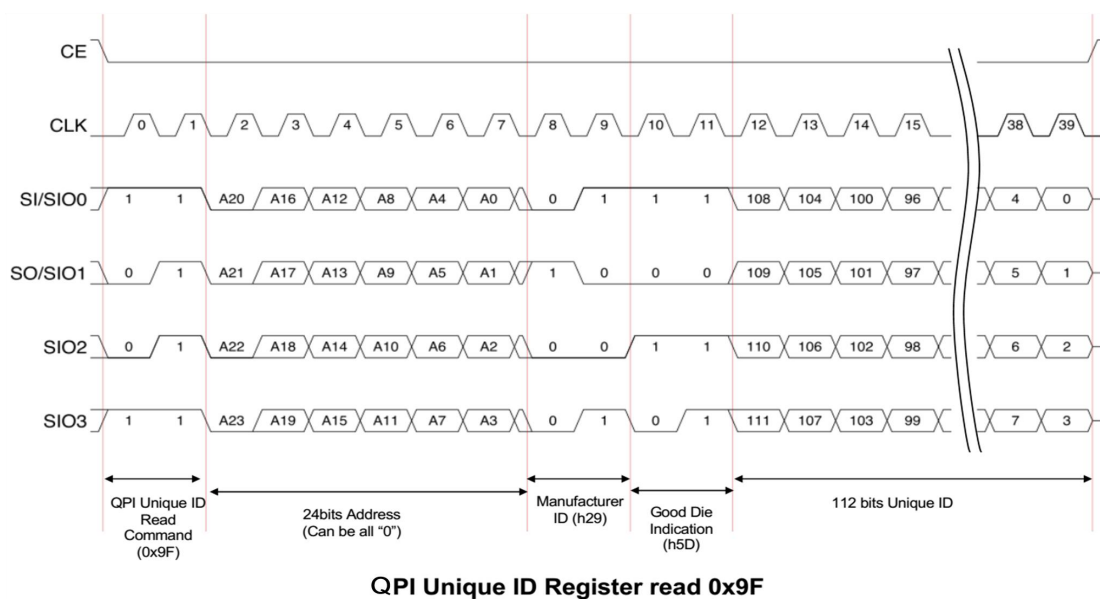


Figure 20: QPI Unique ID Read Command Timing

7 Mode Register Definition

For PM002M chip, three Mode Registers are provided, that are, MR1, MR2,MR3. Each register is accessed by MRWR and MRRD commands combined with 3-Bytes Register Address and 1-Byte Value respectively.

Table 4: Mode Register Definition

| | Address | Feature Data Bits Definition | | | | | | | | Note |
|------|---------|------------------------------|----|----|------|------|-----|-----|----|------|
| | | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
| MR#1 | 0x0000 | MRWD | -- | -- | -- | BP1 | BP0 | WEC | -- | RW |
| MR#2 | 0x0001 | -- | -- | -- | LT1 | LT0 | -- | -- | -- | RW |
| MR#3 | 0x0002 | -- | D1 | D0 | REV1 | REV0 | -- | -- | -- | R |

7.1 Mode Register#1 (MR#1)

This register defines Write protection function. When this device will be used as partial nonvolatile memory. There are protected area and unprotected area which are defined by BP1(Bit3) and BP0 (Bit2). The combination of MRWD(Bit7) and WEC(Bit1) defines how write protection applies to those protected area, unprotected area and Mode Register.

Table 5: Write Protection Combination

| WEC | MRWD | Protected area | Unprotected area | Mode Register | Note |
|-----|------|----------------|------------------|---------------|---------|
| 0 | 0 | Writable | Writable | Writable | Default |
| 0 | 1 | Protected | Writable | Protected | |
| 1 | 0 | Protected | Writable | Writable | |
| 1 | 1 | Protected | Protected | Protected | |

Table 6: Protected and unprotected area

| BP1 | BP0 | Protected area | Unprotected area | Note |
|-----|-----|----------------|------------------|---------|
| 0 | 0 | None | ALL | Default |
| 0 | 1 | Upper 1/4 | Lower 3/4 | |
| 1 | 0 | Upper 1/2 | Lower 1/2 | |
| 1 | 1 | ALL | None | |

Note : Lower half is h[00FFFF]~h[000000], and Higher half is h[01FFFF]~h[010000]

Lower 1/4 means h[007FFF]~h[000000]. Lower 3/4 means h[017FFF]~h[000000]

7.2 Mode Register#2 (MR#2)

MR#2 defines Read operation. Especially, the latency (number of dummy cycles) between the end of read address input to the first data output in Bit4 and Bit3.

The default value of other RFU bits in MR#2 are “0”.

Table 7: Read Latency definition

| LT1 | LT0 | Number of Dummy Clock | Max Clock Frequency (SPI Mode) | Max Clock Frequency (QPI Mode) | Note |
|-----|-----|-----------------------|--------------------------------|--------------------------------|---------|
| 0 | 0 | 0 | 50Mhz | 50Mhz | Default |
| 0 | 1 | 4 | 50Mhz | 50Mhz | |
| 1 | 0 | 8 | 50Mhz | 50Mhz | |
| 1 | 1 | 12 | 50Mhz | 50Mhz | |

7.3 Mode Register#3 (MR#3)

MR#3 defines density of the products and revision of the products.

D1 and D0 bits in Bit6 and 5 in MR#3 define memory density of this device. Bit4 and 3 in MR#3 define revision of the device. The default value of other RFU bits in MR#3 are “0”.

Table 8: Density Bits

| D1 | D0 | Density | Note |
|----|----|---------|---------|
| 0 | 0 | 2Mbit | Default |
| 0 | 1 | RFU | |
| 1 | 0 | RFU | |
| 1 | 1 | RFU | |

Table 9: Revision

| Rev1 | Rev0 | Revision | Note |
|------|------|----------|---------|
| 0 | 0 | 0 | Default |

8 Power Mode

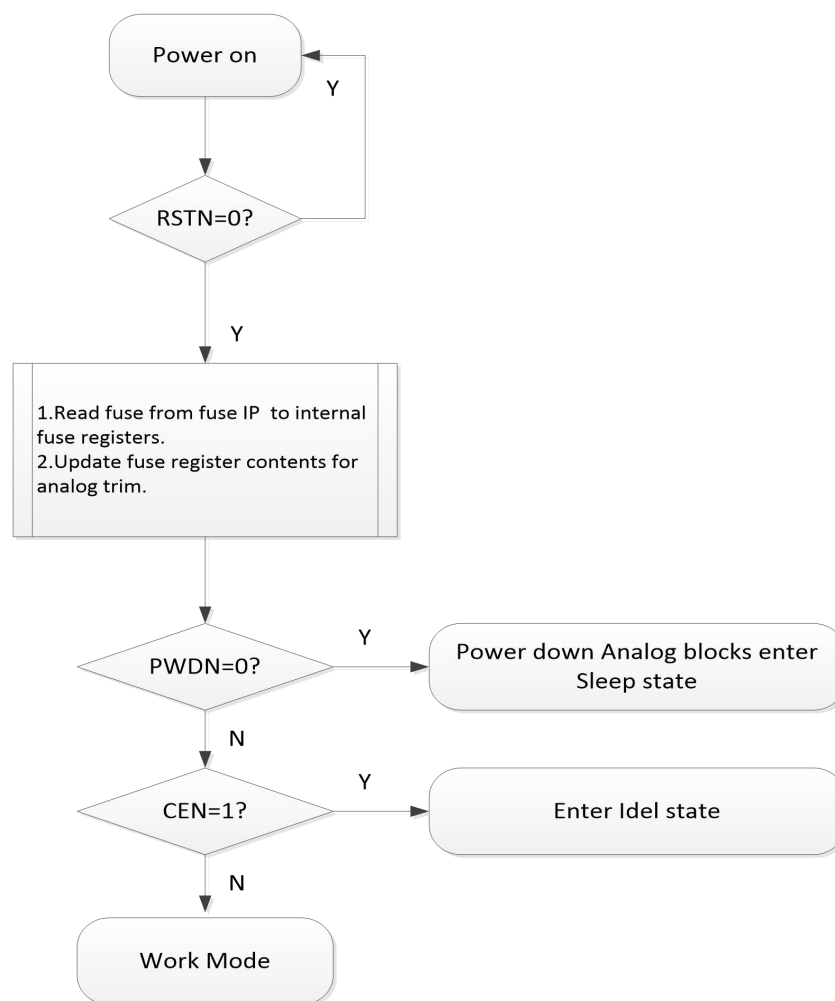
This device provides four kind of low power mode, Read, Write, Standby, Sleep.

During normal work mode, there are read and write. when CE# high, the arrays enter into the Standby mode, which internal regular are still on, but the device cannot receive the command and the data in SI/SO will be not available. When host issue EntryToSleep command, the device will enter into the Sleep mode, in this situation, the internal logic and voltage regular will be off, when host issue the ExitFromSleep command, the device will execute the wake-up sequence to the Standby mode.

This device has four states, that is power-on sequence, normal work mode, sleep mode and wake-up sequence

8.1 Power-on

When powering on, the power-on sequence begins, it is composed of three stage as below:



Analog block active

Fuse-recall

During this stage, the device internal logic loads the fuse bits form EFUSE to trim registers..

Analog block ready

In Fuse-recall stage, the analog blocks' trim bits are updated by fuse registers, and it takes some times to stable..

8.2 Sleep

Sleep is a low power mode. During this mode, all internal regulators were closed to saving the power consumption. Host can issue command EntryTo Sleep to make device enter into this stage.

8.3 Wake-up

Wake-up make the internal analog blocks active It doesn't need do initialization like fuse-recall, only need analog modules stable stage.

9 Input/Output Timing

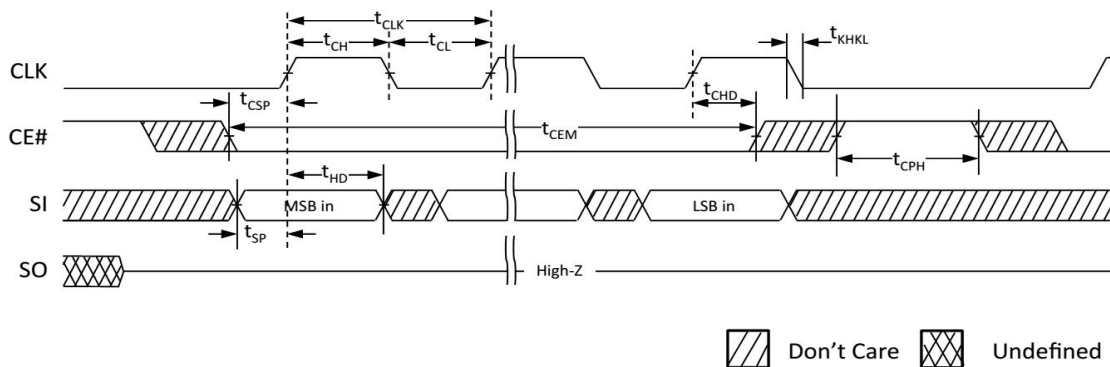


Figure 22: Input Timing

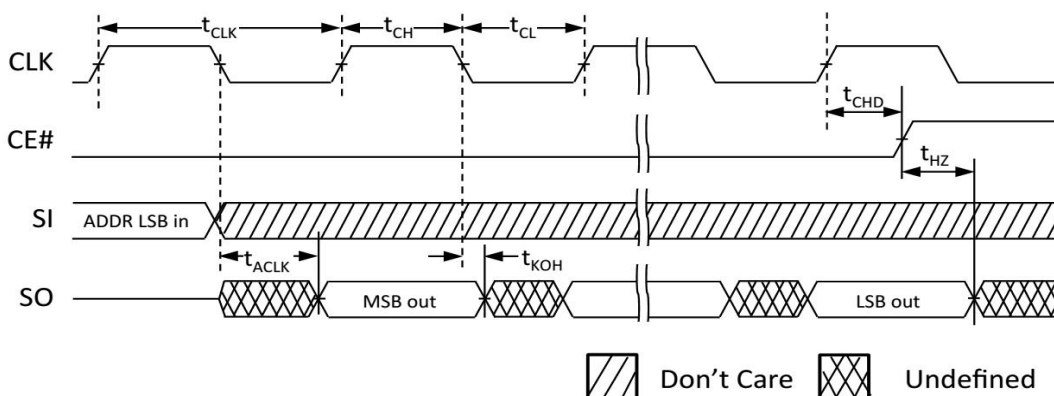


Figure 23: Output Timing

10 Electrical Specifications

This device contains circuitry to protect the inputs against damage caused by high static voltages or electric fields. However, it is advised that normal precautions be taken to avoid application of any voltage greater than maximum rated voltages to these high-impedance (Hi-Z) circuits.

The device also contains protection against external magnetic fields. Precautions should be taken to avoid application of any magnetic field more intense than the maximum field intensity specified in the maximum ratings.

Table 10: Electrical Specifications

| Symbol | Parameter | Conditions | Value | Unit |
|---------------|--|------------------|-------------|------|
| Vcc | Supply Voltage | | -0.5 to 4 | V |
| Vin | Voltage on any pin | | -0.5 to Vcc | V |
| Iout | Output current per pin | | ±4 | mA |
| Tbias | Temperature under bias | Commercial Grade | -40 to 85 | °C |
| Tstg | Storage Temperature | | -55 to 125 | °C |
| Tlead | Lead temperature during solder(3mins max)(note1) | | 260 | °C |
| Hmax_write | Maximum magnetic field during write | Write | 4,000 | A/m |
| Hmax_read | Maximum magnetic field during read or standby | Read or Standby | 40,000 | A/m |
| Hmax_poweroff | Maximum magnetic field during power off | Power off | 40,000 | A/m |

*Note1: We recommend programming of the device after reflow. Data written before reflow cannot be guaranteed

WARNING: Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, magnetic etc.) in excess of absolute maximum ratings. Do not exceed these ratings. Always use semiconductor devices within their recommended operating condition ranges. Operation outside these ranges may adversely affect reliability and could result in device failure. No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet.

11 DC/AC characteristic

This section presents the DC and AC characteristics of the device. The values for the DC and AC parameters indicated in the following tables are derived from tests under the operating and measurement conditions also indicated in the relevant tables. Designers should be aware that the operating conditions in their circuit match the measurement conditions when relying on the quoted parameters.

11.1 Operating Conditions

Table 11: Operating Conditions

| Symbol | Parameter | Min | Max | Unit |
|-----------------|-----------------------------------|-----|-----|------|
| V _{CC} | Voltage Supply | 2.7 | 3.6 | V |
| T _{ax} | Operating Temperature(commercial) | -40 | 85 | °C |

11.2 DC Characteristics

Table 12: DC Characteristics

| Symbol | Parameter | Test Conditions | Min | Typ. | Max | Uni | |
|------------------|------------------------|------------------------|-------------|------|----------------------|-----|----|
| I _{LI} | Input leakage current | | | | ±1 | μA | |
| I _{LO} | Output Leakage current | | | | ±1 | μA | |
| I _{SLP} | Sleep Current | | | 2 | 13 | uA | |
| I _{SBY} | Standby current | | | 2 | 2.7 | mA | |
| I _{CC} | Active Current | SPI Write/Read | CLK = 1MHz | | 2.25 | | mA |
| | | | CLK = 10MHz | | 2.5 | | mA |
| | | | CLK = 20MHz | | 3 | 4.8 | mA |
| | | | CLK = 50MHz | | 4.3 | 6.9 | mA |
| | | QPI Write/Read | CLK = 1MHz | | 2.5 | | mA |
| | | | CLK = 10MHz | | 4 | | mA |
| | | | CLK = 20MHz | | 5 | 7 | mA |
| | | | CLK = 50MHz | | 7 | 9 | mA |
| V _{IL} | Input low voltage | | -0.3 | | 0.8 | V | |
| V _{IH} | Input high voltage | | 2.0 | | V _{CC} +0.3 | V | |
| V _{OL} | Output low voltage | I _{OL} = 4mA | | | 0.4 | V | |
| V _{OH} | Output high voltage | I _{OH} = -4mA | 2.4 | | | V | |

11.3 Pin Capacitance

Table 13: Pin Capacitance

| Symbol | Parameter | Typical | Max | Unit |
|-------------------|------------------------------------|---------|-----|------|
| Cp* | VCC/VSS power external capacitance | | 10 | uF |
| C _{IN} | Control input capacitance | - | 8 | pF |
| C _{IO} | IO capacitance | - | 12 | pF |
| C _{LOAD} | Load capacitance | - | 32 | pF |

*Note: The external capacitor Cp at the Vcc/Vss is recommended $\leq 10\mu\text{F}$; If Cp > 10 μF , reading datas may be unstable when Vcc return to the normal operating voltage from power down. In this case, for the datas are read reliably, suggest to operate the highest address to write ID(0x29, 0x55) data within the specified working voltage range, and then confirm this ID data before operating on the chip. If the ID data is wrong, need to send 0xB9 (sleep) and 0xAB (wake-up),so the chip will be read reliably; Otherwise, when power up and down frequently, the hardware circuit ensures that the chip starting voltage is lower than Vs (0.3V), when Vcc up from down.

11.4 AC Characteristics

Table 14: AC Characteristics

| Symbol | Parameter | 50Mhz | | Unit |
|---------|------------------------------------|-------|-----|------|
| | | Min | Max | |
| tCLK | CLK period | 20 | | ns |
| tCH/tCL | Clock high/low width | 1.5 | | ns |
| tKHKL | CLK rise or fall time | | 1.5 | ns |
| tCPH | CE# High between subsequent burst | 20 | | ns |
| tCSP | CE# Setup time to CLK rising edge | 3 | | ns |
| tCHD | CE# Hold time from CLK rising edge | 50 | | ns |
| tSP | Setup time to active CLK edge | 2 | | ns |
| tHD | Hold time from active CLK edge | 2 | | ns |
| tHZ | Chip disable to DQ output high-Z | | 6 | ns |

| | | | | |
|--------|---|-----|----|----|
| tACLK | CLK to output delay | 8 | 10 | ns |
| tKOH | Data hold time from clock falling edge | 1.5 | | ns |
| tRST | Reset recovery time after Operation command | 150 | | us |
| tESLP | Sleep entry time from Sleep command | | 40 | us |
| tRSLP | Recovery time from Sleep exit command | 1 | | ms |
| tERSLP | Sleep entry to exit command | 1 | | ms |

11.5 Power Up Timing

To provide protection for data during initial power up, power loss or brownout, when ever V_{cc} falls below $V_{CC}(\min)$ the device cannot be selected ($CE\#$ is restricted from going low) and the device is inhibited from Read or Write operations.

Power Up Delay Time

During initial power up or when recovering from brownout or power loss, a power up delay time (t_{PU}) must be added from their specified minimum voltages ($V_{cc}(\min)$) to normal operations may commence. This time is required to insure that the device internal voltages have stabilized.

t_{PU} is measured from the time that V_{cc} have reached their specified minimum voltages. and the device will finish fuse-recall and analog blocks are stable to work.

Table 15: Power-Up Initial Voltages and Delay Timing

| Symbol | Parameter | Min | Max | Unit |
|----------|-----------------------|-----|-----|------|
| V_s | Chip Starting Voltage | - | 0.3 | V |
| t_{PU} | Power Up delay time | 1.5 | - | ms |

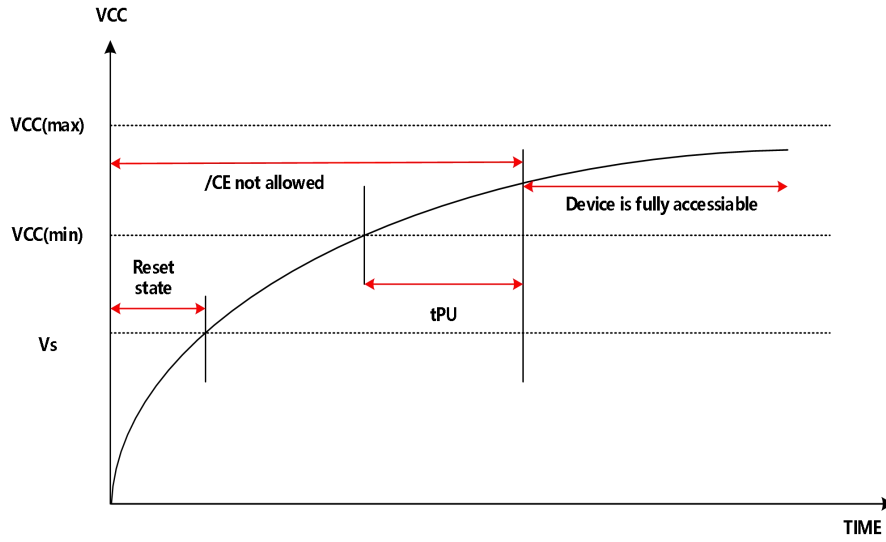


Figure 24: Power-Up Timing and Voltage Levels

12 Order Information

| Orderable Device | Density | Typical voltage | Interface | Package Type | Op Temp(°C) | Package Qty |
|------------------|---------|-----------------|-----------|--------------|-------------|-------------|
| PM002MNIATU | 2Mbits | 3.3V | SPI/QPI | SOP8_150mil | -40 to 85 | 100/Tube |
| PM002MNIATR | 2Mbits | 3.3V | SPI/QPI | SOP8_150mil | -40 to 85 | 2500/Reel |

Top Side Marking



Type: PM002MNI Version: A
 Y: Year WW:Week

13 Package Outline Drawing

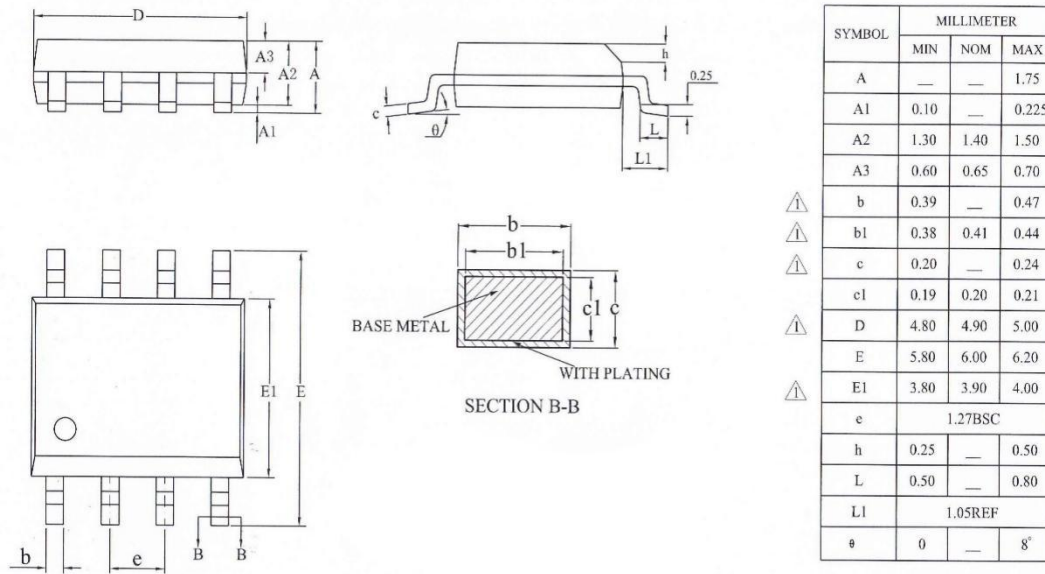


Figure 25: Package Outline for SOP8 150MIL

Document Revision History

| Version | Date | Author | Brief Description of Changes |
|---------|------------|--------|---|
| V1.0 | 2022-05-05 | Ding | Define Max Frequency, modify Feature/DC/AC, parameter, cancel ddr read/write timing |
| V1.1 | 2022-05-24 | Ding | modify Electrical Specifications, modify Note on Use, modify Package description |
| V1.2 | 2022-08-22 | Justin | modify Vin description in Table10, Delete Vccq description in Table11, modify Table15 and Figure24 |
| V1.3 | 2022-11-01 | Justin | Modify ID(0x29, 0x55) description in Chapter 5.9 and Chapter 5.9, Modify Hmax_read description in Table10, define tRST in Table14, modify Chapter 11.3, modify Chapter 11.5 |

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