UTRS3085 Preliminary CMOS IC

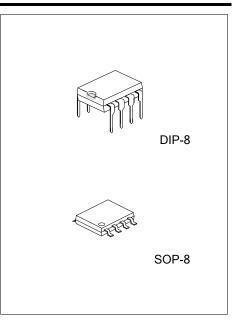
# FAIL-SAFE, 2.5MBPS, RS-485 / RS-422 TRANSCEIVERS WITH ±12KV ESD-PROTECTED

#### ■ DESCRIPTION

The UTC **UTRS3085** high-speed transceivers for RS-485/RS-422 communication contain one driver and one receiver. The device features fail-safe circuitry, which guarantees a logic-high receiver output when the receiver inputs are open or shorted. This means that the receiver output will be logic high if all transmitters on a terminated bus are disabled (high impedance). The UTC **UTRS3085** offer higher driver output slew-rate limits, allowing transmission up to 2.5Mbps.

The transceiver typically draws 375µA of supply current when unloaded or when fully loaded with the drivers disabled.

A device has a 1/8-unit-load receiver input impedance that allows up to 256 transceivers on the bus.

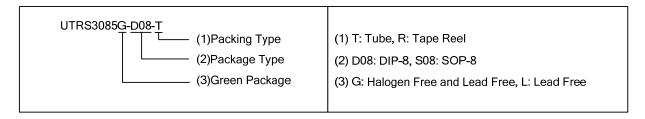


#### **■** FEATURES

- \* True fail-safe receiver while maintaining EIA/TIA-485 compatibility.
- \* Enhanced slew-rate limiting facilitates Error-Free data transmission.
- \* 5.0V single power supply.
- \* 1µA low-current shutdown mode.
- \* Allow up to 256 transceivers on the Bus.
- \* HBM ±12kV ESD-protected.
- \* Driver short circuit current limit.
- \* Thermal shutdown for overload protection.

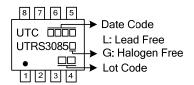
#### ORDERING INFORMATION

Ordering	Number	Dookogo	Dooking
Lead Free	Halogen Free	Package	Packing
UTRS3085L-D08-T	UTRS3085G-D08-T	DIP-8	Tube
UTRS3085L-S08-R	UTRS3085G-S08-R	SOP-8	Tape Reel

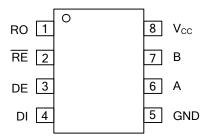


<u>www.unisonic.com.tw</u> 1 of 8

# ■ MARKING



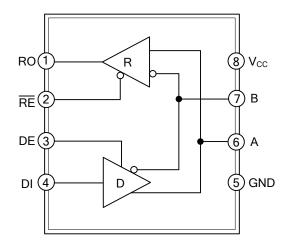
# **■ PIN CONFIGURATION**



#### **■ PIN DESCRIPTION**

PIN NO.	PIN NAME	DESCRIPTION			
1	RO	Receiver output.			
2	RE	Receiver output enable. Drive $\overline{RE}$ low to enable RO; RO is high impedance when $\overline{RE}$ is high. Drive $\overline{RE}$ high and DE low to enter low-power shutdown mode.			
3	DE	Driver output enable. Drive DE high to enable driver outputs. These outputs are high impedance when DE is low. Drive $\overline{\text{RE}}$ high and DE low to enter low-power shutdown mode.			
4	DI	Driver input. With DE high, a low on DI forces non-inverting output low and inverting output high. Similarly, a high on DI forces non-inverting output high and inverting output low.			
5	GND	Ground			
6	Α	Non-inverting receiver input and non-inverting driver output			
7	В	Inverting receiver input and inverting driver output			
8	V <sub>CC</sub>	Positive supply, 4.75V≤V <sub>CC</sub> ≤5.25V			

#### ■ BLOCK DIAGRAM



# ■ ABSOLUTE MAXIMUM RATING

PARAMETER		SYMBOL	RATINGS	UNIT
Supply Voltage	Supply Voltage		+7.0	V
Control Input Voltage (RE, DE)			-0.3 ~ (V <sub>CC</sub> +0.3)	V
Driver Input Voltage		DI	-0.3 ~ (V <sub>CC</sub> +0.3)	V
Receiver Input Voltage (A, B)			±12.5	V
Receiver Output Voltage (RO)			-0.3 ~ (V <sub>CC</sub> +0.3)	V
Continuous Power Dissipation DIP-8		Б	550	mW
(Derate 5.88mW/°C above +70°C) SOP-8		P <sub>D</sub>	471	mW
Operating Temperature Ranges		T <sub>OPR</sub>	-40 ~ +85	°C
Storage Temperature Range		T <sub>STG</sub>	-65 ~ +150	°C

Note: Absolute maximum ratings are only stress ratings and it is not implied for functional device operation. Absolute maximum ratings are the values beyond which the device will be damaged permanently.

# ■ DC ELECTRICAL CHARACTERISTICS

 $(V_{CC}=+5.0V \pm 5\%, T_A=T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } V_{CC}=+5.0V \text{ and } T_A=+25^{\circ}C) \text{ (Note 1)}$ 

(100 0:01 =070; 1A 1WIII 10 1	1017-000	otherwide noted. Typical values are c				(11010 1)
PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
DRIVER						
Differential Driver Output (No Load)	V <sub>OD1</sub>	Fig.1			5.0	V
Differential Driver Output	\/	Fig.1, R=50Ω (RS-422)	1.8			V
Differential Driver Output	$V_{OD2}$	Fig.1, R=27Ω (RS-485)	1.4			V
Change in Magnitude of Differential Output Voltage (Note 2)	$\Delta V_{OD}$	Fig.1, R=50Ω or R=27Ω			0.2	V
Driver Common-Mode Output Voltage	V <sub>OC</sub>	Fig.1, R=50Ω or R=27Ω			3.0	V
Change In Magnitude of Common-Mode Voltage (Note 2)	$\Delta V_{OC}$	Fig.1, R=50Ω or R=27Ω			0.2	V
Input High Voltage	$V_{IH1}$	DE, DI, RE	2.0			V
Input Low Voltage	V <sub>IL1</sub>	DE, DI, RE			0.8	V
DI Input Hysteresis	$V_{HYS}$			100		mV
Input Current	I <sub>IN1</sub>	DE, DI, RE			±2.0	μA
la and Orange to (A and D)	I <sub>IN2</sub>	DE=GND, V <sub>IN</sub> =12V			125	μA
Input Current (A and B)		V <sub>CC</sub> =GND or 5.25V V <sub>IN</sub> =-7V			-75	μA
Driver Short Circuit Output		-7V≤V <sub>OUT</sub> ≤V <sub>CC</sub>	-250			mA
Driver Short-Circuit Output Current (Note 4)	$V_{\text{OD1}}$	0V≤V <sub>OUT</sub> ≤12V			250	mA
Current (Note 4)		0V≤V <sub>OUT</sub> ≤V <sub>CC</sub>	±25			mA
RECEIVER						
Receiver Differential Threshold Voltage	$V_{TH}$	-7V≤V <sub>CM</sub> ≤+12V	-300		+300	mV
Receiver Input Hysteresis	$\Delta V_{TH}$			25		mV
Receiver Output High Voltage	$V_{OH}$	I <sub>O</sub> =-4mA, V <sub>ID</sub> =-50mV	V <sub>CC</sub> -1.5			V
Receiver Output Low Voltage	$V_{OL}$	I <sub>O</sub> =4mA, V <sub>ID</sub> =-200mV			0.4	V
Three-State Output Current at Receiver	I <sub>OZR</sub>	0.4V≤V <sub>0</sub> ≤2.4V			±1.0	μA
Receiver Input Resistance	R <sub>IN</sub>	-7V≤V <sub>CM</sub> ≤+12V	96			kΩ
Receiver Output Short-Circuit Current	I <sub>OSR</sub>	0V≤V <sub>RO</sub> ≤V <sub>CC</sub>	±7		±95	mA

# ■ DC ELECTRICAL CHARACTERISTICS (Cont.)

PARAMETER	SYMBOL	TEST CONDITIONS			TYP	MAX	UNIT
SUPPLY CURRENT							
Supply Current		No Load,	DE=V <sub>CC</sub>		430	900	μΑ
Supply Current	Icc	RE =DI= V <sub>CC</sub> or GND	DE=GND		375	600	μΑ
Supply Current in Shutdown Mode	I <sub>SHDN</sub>	DE=GND, $V_{\overline{RE}} = V_{CC}$			1.0	10	μA

Notes: 1. All currents into the device are positive; all currents out of the device are negative. All voltages are referred to device ground unless otherwise noted.

- 2.  $\Delta V_{OD}$  and  $\Delta V_{OC}$  are the changes in  $V_{OD}$  and  $V_{OC}$ , respectively, when the DI input changes state.
- 3. Maximum current level applies to peak current just prior to foldback-current limiting; minimum current level applies during current limiting.

#### **■ SWITCHING CHARACTERISTICS**

 $(V_{CC}$ =+5.0V ±5%,  $T_A$ = $T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $V_{CC}$ =+5.0V and  $T_A$ =+25°C)

(VCC-10.0V ±070, 1A-1MIN to	MAX, unicoo	otherwise noted. Typical values are at v <sub>CC</sub> -	· 0.0 v a	na r <sub>A</sub>	20 0)	
PARAMETER	SYMBOL	TEST CONDITIONS		TYP	MAX	UNIT
Driver Input to Output	t <sub>DPLH</sub>	Fig.3 and 5, $R_{DIFF}$ =54 $\Omega$ , $C_{L1}$ = $C_{L2}$ =100pF		100		ns
Driver input to Output	t <sub>DPHL</sub>			100		ns
Driver Output Skew	t <sub>DSKEW</sub>	Fig.3 and 5, R <sub>DIFF</sub> =54Ω, C <sub>L1</sub> =C <sub>L2</sub> =100pF		5	200	ns
Driver Rise or Fall Time	t <sub>DR</sub> , t <sub>DF</sub>	Fig.3 and 5, R <sub>DIFF</sub> =54Ω, C <sub>L1</sub> =C <sub>L2</sub> =100pF		200		ns
Maximum Data Rate	f <sub>MAX</sub>	. 19.0 0.10 0, 110   1 0 121, 0   1 0   2	2.5			Mbps
Driver Enable to Output High	t <sub>DZH</sub>	Fig.4 and 6, C <sub>L</sub> =100pF, S2 Closed			3500	ns
Driver Enable to Output Low	t <sub>DZL</sub>	Fig.4 and 6, C <sub>L</sub> =100pF, S1 Closed			3500	ns
Driver Disable Time from Low	t <sub>DLZ</sub>	Fig.4 and 6, C <sub>L</sub> =15pF, S1 Closed			200	ns
Driver Disable Time from High		Fig.4 and 6, C <sub>L</sub> =15pF, S2 Closed			200	ns
Receiver Input to Output	t <sub>RPLH</sub> ,	Fig.7 and 9, $ V_{ID}  \ge 2.0V$ ; Rise and Fall Time of $V_{ID} \le 15$ ns		200	200	ns
t <sub>RPLH</sub> - t <sub>RPHL</sub>   Differential Receiver Skew	t <sub>RSKD</sub>	Fig.7 and 9,  V <sub>ID</sub>  ≥2.0V; Rise and Fall Time of V <sub>ID</sub> ≤15ns		50		ns
Receiver Enable to Output Low	t <sub>RZL</sub>	Fig.2 and 8, C <sub>L</sub> =100pF, S1 Closed		50		ns
Receiver Enable to Output High	t <sub>RZH</sub>	Fig.2 and 8, C <sub>L</sub> =100pF, S2 Closed		50		ns
Receiver Disable Time from Low	t <sub>RLZ</sub>	Fig.2 and 8, C <sub>L</sub> =100pF, S1 Closed		50		ns
Receiver Disable Time from High	t <sub>RHZ</sub>	Fig.2 and 8, C <sub>L</sub> =100pF, S2 Closed		50		ns
Time to Shutdown	t <sub>SHDN</sub>	Note 1		200		ns
Driver Enable from Shutdown to Output High	t <sub>DZH(SHDN)</sub>	Fig.4 and 6, C <sub>L</sub> =15pF, S2 Closed			4500	ns
Driver Enable from Shutdown to Output Low	t <sub>DZL(SHDN)</sub>	Fig.4 and 6, C <sub>L</sub> =15pF, S1 Closed			4500	ns
Receiver Enable from Shutdown to Output High	t <sub>RZH(SHDN)</sub>	Fig.2 and 8, C <sub>L</sub> =100pF, S2 Closed			3500	ns
Receiver Enable from Shutdown to Output Low	t <sub>RZL(SHDN)</sub>	Fig.2 and 8, C <sub>L</sub> =100pF, S1 Closed			3500	ns

Note: The device is put into shutdown by bringing  $\overline{RE}$  high and DE low. If the enable inputs are in this state for less than 50ns, the device is guaranteed not to enter shutdown. If the enable inputs are in this state for at least 600ns, the device is guaranteed to have entered shutdown.

# **■ FUNCTION TABLE**

# **TRANSMITTING**

INPUTS			OUTPUTS		
RE	DE	DI	В	Α	
Х	1	1	0	1	
Х	1	0	1	0	
0	0	X	High-Z	High-Z	
1	0	X	Shutdown		

# **RECEIVING**

	INPUTS	OUTPUT	
RE	DE	A-B	RO
0	X	≥-0.05V	1
0	X	≤-0.2V	0
0	X	Open/Shorted	1
1	1	X	High-Z
1	0	X	Shutdown

X = Don't care

Shutdown mode, driver and receiver outputs high impedance

#### **■ TEST CIRCUIT**

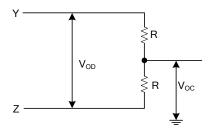


Fig. 1 Driver DC Test Circuit

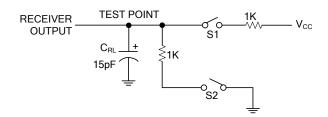


Fig. 2 Receiver Enable/Disable Timing Test Load

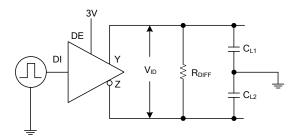


Fig. 3 Driver Timing Test Circuit

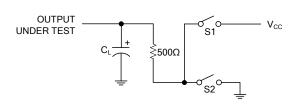


Fig. 4 Driver Enable/Disable Timing Test Load

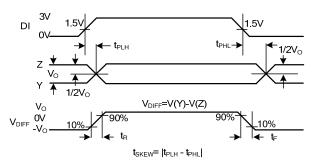


Fig. 5 Driver Propagation Delays

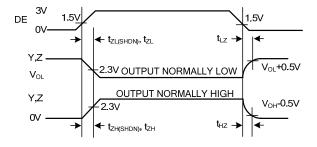


Fig. 6 Driver Enable and Disable Times

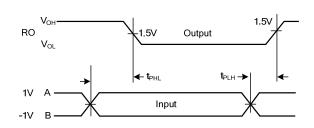


Fig. 7 Receiver Propagation Delays

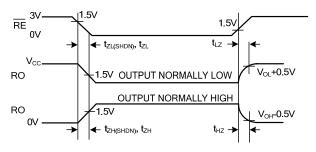


Fig. 8 Receiver Enable and Disable Times

### ■ TEST CIRCUIT (Cont.)

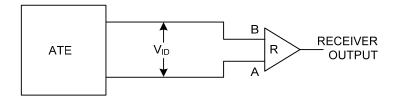
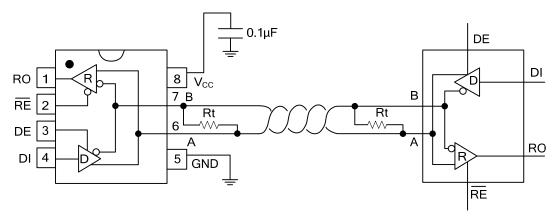


Fig. 9 Receiver Propagation Delay Test Circuit

#### **■ TYPICAL APPLICATION CIRCUIT**



Note: Pin labels Y and Z on timing, test, and waveform diagrams refer to pins A and B when DE is high.

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