













LM5160A, LM5160

SNVSA03D - OCTOBER 2014-REVISED NOVEMBER 2017

LM5160A, LM5160 Wide Input 65-V, 2-A Synchronous Buck / Fly-Buck™ Converter

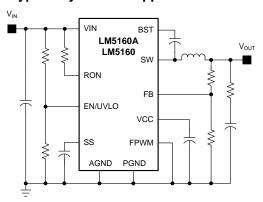
Features

- Wide 4.5-V to 65-V Input Voltage Range
- Integrated High-Side and Low-Side Switches
 - No Schottky Diode Required
- 2-A Maximum Load Current
- Constant ON-Time Control
 - No External Loop Compensation
 - Fast Transient Response
- Selectable Forced CCM or DCM Operation
- CCM Option Supports Multi-Output Fly-Buck™
- **Nearly Constant Switching Frequency**
- Frequency Adjustable Up to 1 MHz
- Programmable Soft-Start Time
- Prebiased Start-Up
- **Peak Current Limiting Protection**
- Adjustable Input UVLO and Hysteresis
- ±1% Feedback Voltage Reference
- LM5160A Allows External V_{CC} Bias
- Thermal Shutdown Protection
- Create a Custom Design Using the LM5160A With the WEBENCH® Power Designer

Applications

- Industrial Programmable Logic Controller
- **IGBT Gate Drive Bias Supply**
- Telecom Primary and Secondary Side Bias
- E-Meter Power Line Communication
- Low-Power Isolated DC-DC (Fly-Buck)

Typical Sync-Buck Application Circuit



3 Description

The LM516x device is a 65-V, 2-A synchronous stepdown converter with integrated high-side and low-side MOSFETs. The constant ON-time control scheme requires no loop compensation and supports high step-down ratios with fast transient response. An internal feedback amplifier maintains ±1% output regulation over the entire operating temperature range. The ON-time varies inversely with input voltage resulting in nearly constant switching frequency. Peak and valley current limit circuits protect against overload conditions. The undervoltage lockout (EN/UVLO) circuit provides independently adiustable input undervoltage threshold hysteresis. The LM5160 is programmed through the FPWM pin to operate in continuous conduction mode (CCM) from no load to full load or to automatically switch to discontinuous conduction mode (DCM) at light load for higher efficiency. Forced CCM operation supports multiple output and isolated Fly-Buck applications using a coupled inductor.

The LM5160A shares the same features and pin configuration as the LM5160. An external bias supply can be connected to the VCC pin of the LM5160A in either Buck or Fly-Buck applications. This additional capability can improve efficiency at high input voltages.

Device Information⁽¹⁾

PART NUMBER	PACKAGE	BODY SIZE (NOM)
LM5160A	\\\CON (42\)	4.00 mm × 4.00 mm
LM5160	WSON (12)	4.00 mm x 4.00 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.

Typical Fly-Buck Application Circuit

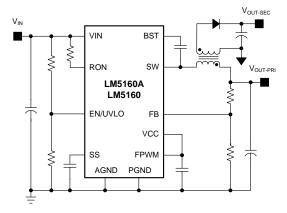




Table of Contents

1	Features 1	8 Applications and Implementation	16
2	Applications 1	8.1 Application Information	16
3	Description 1	8.2 Typical Applications	17
4	Revision History2	8.3 Do's and Don'ts	26
5	Pin Configuration and Functions 4	9 Power Supply Recommendations	26
6	Specifications5	10 Layout	27
٠	6.1 Absolute Maximum Ratings	10.1 Layout Guidelines	
	6.2 ESD Ratings	10.2 Layout Example	27
	6.3 Recommended Operating Conditions	11 Device and Documentation Support	28
	6.4 Thermal Information6	11.1 Device Support	
	6.5 Electrical Characteristics	11.2 Documentation Support	28
	6.6 Switching Characteristics	11.3 Related Links	28
	6.7 Typical Characteristics8	11.4 Receiving Notification of Documentation Update	es <mark>28</mark>
7	Detailed Description	11.5 Community Resources	28
•	7.1 Overview	11.6 Trademarks	29
	7.2 Functional Block Diagram	11.7 Electrostatic Discharge Caution	29
	7.3 Feature Description	11.8 Glossary	29
	7.4 Device Functional Modes	12 Mechanical, Packaging, and Orderable Information	29

4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

С	hanges from Revision C (August 2016) to Revision D	Page
•	Added WEBENCH links to the data sheet	
•	Deleted the lead temperature from the Absolute Maximum Ratings table	!
•	Changed the Ripple Configuration section to the Application Information section	16
•	Changed the Application Performance Plots title to Application Curves in both typical application sections	<u>2</u> 1
•	Changed the Electrostatic Discharge Caution statement	28

CI	hanges from Revision B (July 2015) to Revision C	Page
•	Changed full load rating in title from 1.5-A to 2-A	1
•	Changed full load rating from 1.5-A to 2-A	
•	Changed full load rating from 1.5-A to 2-A	1
•	Updated data sheet text to the latest documentation and translations standards	1
•	Changed recommended output current rating from 1.5-A to 2-A	5
•	Changed full load rating from 1.5 A to 2 A	11
•	Changed minimum ripple injection equation	17
•	Deleted 'maximum' from the sentence	17
•	Deleted 'maximum' from the sentence	
•	Deleted 'maximum' from the sentence	19
•	Changed equation for the required primary output voltage	24
•	Changed equation to add the isolated output voltage detail	
•	Changed Full Load Rating from 1.5 A to 2-A	26

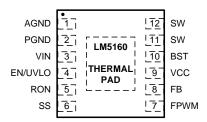


Cr	hanges from Revision A (January 2015) to Revision B	Page
<u>.</u>	Changed the input capacitor calculation equation	20
Cł	hanges from Original (October 2014) to Revision A	Page
•	Added Family to data sheet	1
•	Added 'A' to part number in graphic	1
•	5. a g. a a g a g a	
•	Added Ext VCC recommended operating data for LM5160A	5
•	Added conditions for LM5160A	
•	Added Ext- VCC description for LM5160A	12
•	Added Application circuit with LM5160A	26
•	Added Don'ts with LM5160	
•	Added updated layout guidelines with LM5160A	27
•	Added updated layout diagram	27
•	Added Related Documentation	28



5 Pin Configuration and Functions

DNT Package 12-Pin WSON With Exposed Thermal Pad Top View



Pin Functions

	PIN	1/0	DECODINE
NO.	NAME	1/0	DESCRIPTION
1	AGND	_	Analog Ground. Ground connection of internal control circuits.
2	PGND	_	Power Ground. Ground connection of the internal synchronous rectifier FET.
3	VIN	I	Input supply connection. Operating input range is 4.5 V to 65 V.
4	EN/UVLO	I	Precision enable. Input pin of undervoltage lockout (UVLO) comparator.
5	RON	I	ON-time programming pin. A resistor between this pin and VIN sets the switch ON-time as a function of input voltage.
6	SS	I	Soft start. Connect a capacitor from SS to AGND to control output rise time and limit overshoot.
7	FPWM	1	Forced PWM logic input pin. Connect to AGND for discontinuous conduction mode (DCM) with light loads. Connect to VCC for continuous conduction mode (CCM) at all loads and Fly-Buck configuration.
8	FB	I	Feedback input of voltage regulation comparator.
9	VCC	0	Internal high voltage start-up regulator bypass capacitor pin.
10	BST	I	Bootstrap capacitor pin. Connect a capacitor between BST and SW to bias gate driver of high-side buck FET.
11,12	SW	0	Switch node. Source connection of high-side buck FET and drain connection of low-side synchronous rectifier FET.
_	NC		No Connection.
_	EP		Exposed Pad. Connect to AGND and printed-circuit board ground plane to improve power dissipation.

Submit Documentation Feedback

Copyright © 2014–2017, Texas Instruments Incorporated



6 Specifications

6.1 Absolute Maximum Ratings

See (1)(2)

		MIN	MAX	UNIT	
	VIN to AGND	-0.3	70		
	EN/UVLO to AGND	-0.3	70		
	RON to AGND	-0.3	70		
lament valta as	BST to AGND	-0.3	84	.,,	
Input voltage	VCC to AGND	-0.3	14	V	
	FPWM to AGND	-0.3	14		
	SS to AGND	-0.3	7		
	FB to AGND	-0.3	7		
	BST to SW	-0.3	14		
Outrot valta aa	BST to VCC		70	1	
Output voltage	SW to AGND	-1.5	70	V	
	SW to AGND (20 ns transient)	-3		1	
Maximum junction temperature (3)		-40	150	°C	
Storage temperature, T _{stg}		-65	150	°C	

⁽¹⁾ Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

6.2 ESD Ratings

			VALUE	UNIT
V/EOD)	Electrostatic	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 (1)	±2000	V
	discharge	Charged-device model (CDM), per JEDEC specification JESD22-C101 ⁽²⁾	±750	V

⁽¹⁾ JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

Over operating free-air temperature range (unless otherwise noted)⁽¹⁾

1			
	MIN	MAX	UNIT
V _{IN} input voltage	4.5	65	V
I _O output current		2	Α
External V _{CC} bias voltage (LM5160A only)	9	13	V
Operating junction temperature ⁽²⁾ (LM5160 and LM5160A)	-40	125	°C

Recommended Operating Ratings are conditions under the device is intended to be functional. For specifications and test conditions, see Electrical Characteristics

(2) High junction temperatures degrade operating lifetimes. Operating lifetime is de-rated for junction temperatures greater than 125°C.

Copyright © 2014–2017, Texas Instruments Incorporated

⁽²⁾ If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/ Distributors for availability and specifications.

⁽³⁾ High junction temperatures degrade operating lifetimes. Operating lifetime is de-rated for junction temperatures greater than 125°C.

⁽²⁾ JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.



6.4 Thermal Information⁽¹⁾

		LM5160, LM5160A	
	THERMAL METRIC	DNT (WSON)	UNIT
		12 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance (1)	33.4	°C/W
$R_{\theta JCbot}$	Junction-to-case (bottom) thermal resistance (1)	1.9	°C/W
ΨЈВ	Junction-to-board thermal characteristic parameter	11.3	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	11.1	°C/W
$R_{\theta JCtop}$	Junction-to-case (top) thermal resistance	24.7	°C/W
ΨЈТ	Junction-to-top thermal characteristic parameter	0.2	°C/W

⁽¹⁾ For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application

6.5 Electrical Characteristics

Typical values correspond to T_J = 25°C. Minimum and maximum limits apply over T_J = -40°C to 125°C⁽¹⁾⁽²⁾ for the LM5160, LM5160A . Unless otherwise stated, V_{IN} = 24 V.

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
SUPPLY CUI	RRENT					
I _{SD}	Input shutdown current	V _{IN} = 24 V, EN/UVLO = 0 V		50	90.7	μΑ
I _{OP}	Input operating current	V _{IN} = 24 V, FB = 3 V, non-switching		2.3	2.84	mA
VCC SUPPL	Y				<u>.</u>	
V _{CC}	Bias regulator output	V _{IN} = 24 V, I _{CC} = 20 mA	6.47	7.5	8.52	V
V _{CC}	Bias regulator current limit	V _{IN} = 24 V	30			mA
V _{CC(UV)}	VCC undervoltage threshold	V _{CC} rising		3.98	4.1	V
V _{CC(HYS)}	VCC undervoltage hysteresis	V _{CC} falling		185		mV
V _{CC(LDO)}	VIN – VCC dropout voltage	V _{IN} = 4.5 V, I _{CC} = 20 mA		165	260	mV
HIGH-SIDE F	ET				•	
R _{DS(ON)}	High-side ON-resistance	V _(BST - SW) = 7 V, I _{SW} = 1 A		0.29		Ω
BST _(UV)	Bootstrap gate drive UV	V _(BST - SW) rising		2.93	3.6	V
BST _(HYS)	Gate drive UV hysteresis	V _(BST - SW) falling		200		mV
LOW-SIDE F	ET					
R _{DS(ON)}	Low-side ON-resistance	I _{SW} = 1 A		0.13		Ω
HIGH-SIDE C	URRENT LIMIT				<u>.</u>	
I _{LIM (HS)}	High-side current limit threshold		2.125	2.5	2.875	Α
T _{RES}	Current limit response time	I _{LIM (HS)} threshold detect to FET turnoff		100		ns
T _{OFF1}	Current limit forced OFF-time	FB = 0 V, VIN = 65 V	17.31	29	39.8	μs
T _{OFF2}	Current limit forced OFF-time	FB = 1 V, VIN = 24 V	2.18	3.5	5.12	μs
LOW-SIDE C	URRENT LIMIT				<u>.</u>	
I _{SOURCE(LS)}	Sourcing current limit		1.9	2.5	3	Α
I _{SINK(LS)}	Sinking current limit			5.4		Α
DIODE EMUI	ATION					
$V_{FPWM(LOW)}$	FPWM input logic low	V _{IN} = 24 V			1	V
V _{FPWM(HIGH)}	FPWM input logic high	V _{IN} = 24 V	3			V
I _{ZX}	Zero cross detect current	FPWM = 0 (diode emulation)		0		mA
REGULATIO	N COMPARATOR					
V _{REF}	FB regulation level	V _{IN} = 24 V (12-pin WSON)	1.977	2	2.017	٧
I _(Bias)	FB input bias current	V _{IN} = 24 V			100	nA



Electrical Characteristics (continued)

Typical values correspond to $T_J = 25^{\circ}C$. Minimum and maximum limits apply over $T_J = -40^{\circ}C$ to $125^{\circ}C^{(1)(2)}$ for the LM5160, LM5160A. Unless otherwise stated, $V_{IN} = 24 \text{ V}$.

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
ERROR CO	RRECTION AMPLIFIER & SOFT-ST	ART				
G _M	Error amp transconductance	FB = V _{REF} (+/–) 10 mV		105		μΑ/V
I _{EA(Source)}	Error amp source current	FB = 1 V, SS = 1 V	7.62	10.2	12.51	μΑ
I _{EA(Sink)}	Error amp sink current	FB = 5 V, SS = 2.25 V	7.46	10	12.2	μΑ
V _(SS-FB)	V _{SS} – V _{FB} clamp voltage	FB = 1.75 V, C _{SS} = 1 nF		135		mV
I _{SS}	Soft-start charging current	SS = 0.5 V	7.63	10.2	12.5	μA
ENABLE/UV	'LO				*	
V _{UVLO (TH)}	UVLO threshold	EN/UVLO rising	1.213	1.24	1.277	V
I _{UVLO(HYS)}	UVLO hysteresis current	EN/UVLO = 1.4 V	15	20	25	μΑ
V _{SD(TH)}	Shutdown mode threshold	EN/UVLO falling	0.28	0.35		V
V _{SD(HYS)}	Shutdown threshold hysteresis	EN/UVLO rising		47		mV
THERMAL S	HUTDOWN				*	
T _{SD}	Thermal shutdown threshold			175		°C
T _{SD(HYS)}	Thermal shutdown hysteresis			20		°C

6.6 Switching Characteristics (1)

Typical values correspond to T_J = 25°C. Minimum and maximum limits apply over T_J = -40°C to 125°C for the LM5160, LM5160A. Unless otherwise stated, V_{IN} = 24 V.

		MIN	TYP	MAX	UNIT
MINIMUM OFF	F-TIME				
T _{OFF-MIN}	Minimum OFF-Time, FB = 0 V		170		ns
ON-TIME GEN	IERATOR				
T _{ON} Test 1	VIN = 24 V, RON = 100 kΩ	312	428	520	ns
T _{ON} Test 2	VIN = 24 V, RON = 200 kΩ	625	818	1040	ns
T _{ON} Test 3	VIN = 8 V, RON = 100 kΩ	937	1247	1563	ns
T _{ON} Test 4	VIN = 65 V, RON = 100 kΩ	132	176	220	ns

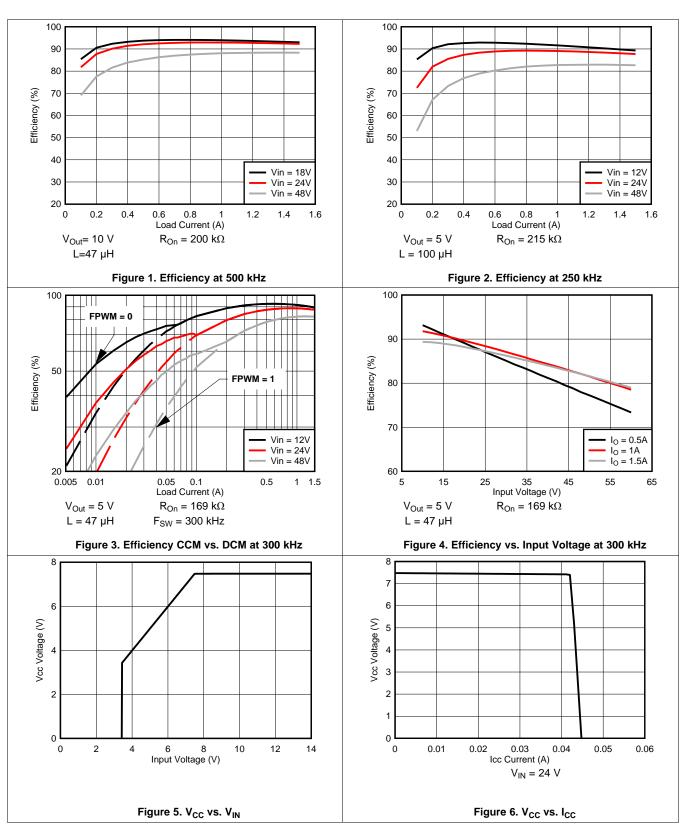
⁽¹⁾ All minimum and maximum limits are specified by correlating the electrical characteristics to process and temperature variations and applying statistical process control.

Product Folder Links: LM5160A LM5160



6.7 Typical Characteristics

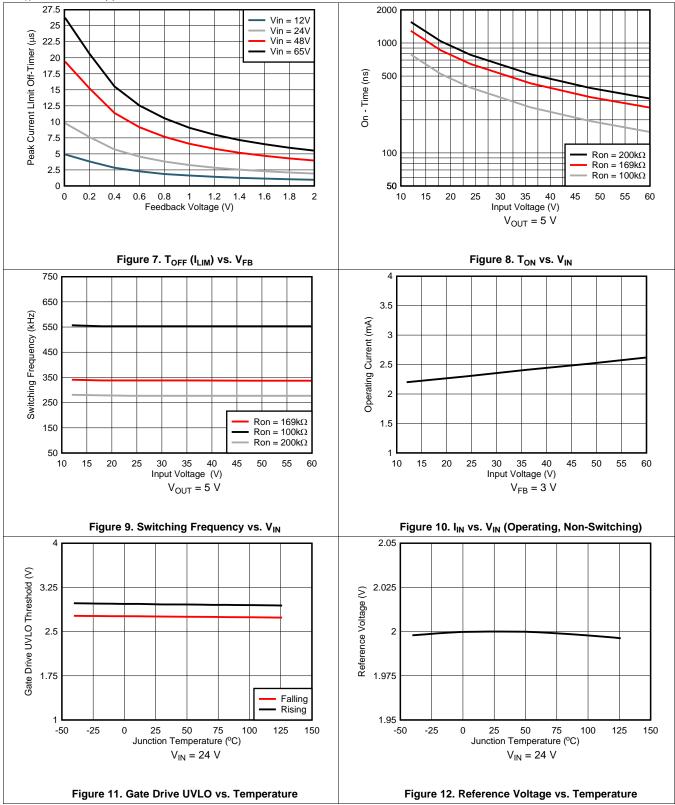
At $T_A = 25$ °C and applicable to both LM5160 and LM5160A, unless otherwise noted.





Typical Characteristics (continued)

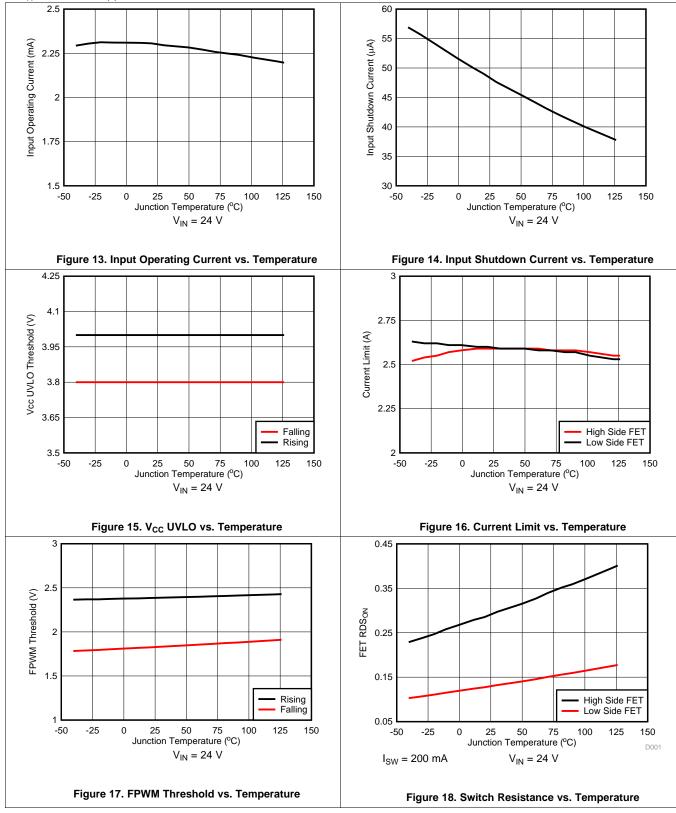
At T_A = 25°C and applicable to both LM5160 and LM5160A, unless otherwise noted.





Typical Characteristics (continued)

At T_A = 25°C and applicable to both LM5160 and LM5160A, unless otherwise noted.





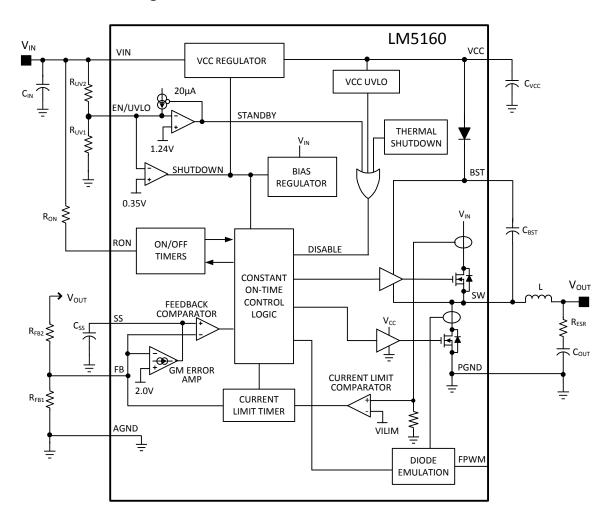
7 Detailed Description

7.1 Overview

The LM5160 family of step-down switching regulators features all the functions needed to implement a low-cost, efficient buck converter capable of supplying 2 A to the load. This high voltage regulator contains 65-V N-channel buck and synchronous rectifier switches and is available in the 12-pin WSON package. The regulator operation is based on constant ON-time control where the ON-time is inversely proportional to input voltage V_{IN} . This feature maintains a relatively constant operating frequency with load and input voltage variations. A constant ON-time switching regulator requires no loop compensation resulting in fast load transient response. Peak current limit detection circuit is implemented with a forced OFF-time during current limiting which is inversely proportional to voltage at the feedback pin, V_{FB} and directly proportional to V_{IN} . Varying the current limit OFF-time with V_{FB} and V_{IN} ensures short-circuit protection with minimal current limit foldback. The LM5160 can be applied in numerous end equipment systems requiring efficient step-down regulation from higher input voltages. This regulator is well-suited for 24-V industrial systems as well as 48-V Telecom and PoE voltage ranges. The LM5160 integrates an undervoltage lockout (EN/UVLO) circuit to prevent faulty operation of the device at low input voltages and features intelligent current limit and thermal shutdown to protect the device during overload or short circuit.

The LM5160 device name is used generically throughout this document and represents both the LM5160 and LM5160A unless stated otherwise. The only difference between the two is the ability to connect an external voltage source to the VCC pin of the LM5160A.

7.2 Functional Block Diagram



Copyright © 2014–2017, Texas Instruments Incorporated



7.3 Feature Description

7.3.1 Control Circuit

The LM5160 step-down switching regulator employs a control principle based on a comparator and a one-shot ON-timer, with the output voltage feedback (FB) compared to the voltage at the Soft-Start (SS) pin (V_{SS}). If the FB voltage is below V_{SS} , the internal buck switch is turned on for a time period determined by the input voltage and one-shot programming resistor R_{ON}). Following the ON-time, the buck switch must remain off for the minimum OFF-time forced by the minimum OFF-time one-shot. The buck switch remains off until the FB voltage falls below the soft start again, when it turns back on for another ON-time one-shot period.

During a rapid start-up or when the load current increases suddenly, the regulator operates with minimum OFF-time per cycle. When regulating the output in steady-state operation, the OFF-time automatically adjusts to produce the SW pin duty cycle required for output voltage regulation.

When in regulation, the LM5160 operates in continuous conduction mode at heavy load currents. If the FPWM pin is connected to ground or left floating, the regulator operates in discontinuous conduction mode at light load with the synchronous rectifier FET in diode emulation. With sufficient load, the LM5160 operates in continuous conduction mode with the inductor current never reaching zero during the OFF-time of the high-side FET. In this mode the operating frequency remains relatively constant with load and line variations. The minimum load current for continuous conduction mode is one-half the inductor's ripple current amplitude. The operating frequency is programmed by the R_{ON} pin resistor and can be calculated from Equation 1 with R_{ON} expressed in ohms.

$$F_{sw} = \frac{V_{OUT}}{R_{ON} \times 1 \times 10^{-10}} \, Hz \tag{1}$$

In discontinuous conduction mode, current through the inductor ramps up from zero to a peak value during the ON-time, then ramps back to zero before the end of the OFF-time. The next ON-time period starts when the voltage at FB falls below V_{SS} . When the inductor current is zero during the high-side FET OFF-time, the load current is supplied by the output capacitor. In this mode, the operating switching frequency is lower than the continuous conduction mode switching frequency and the frequency varies with load. The discontinuous conduction mode maintains conversion efficiency at light loads because the switching losses decrease with the decrease in load and frequency.

The output voltage is set by two external resistors (R_{FB1} , R_{FB2}). The regulated output voltage is calculated from Equation 2.

$$V_{OUT} = \frac{V_{REF} \times (R_{FB2} + R_{FB1})}{R_{FB1}} V$$

where

7.3.2 VCC Regulator

The LM5160 contains an internal high voltage linear regulator with a nominal output voltage of 7.5 V (typical). The VCC regulator is internally current limited to 30 mA (minimum). This regulator supplies power to internal circuit blocks including the synchronous FET gate driver and the logic circuits. When the voltage on the VCC pin reaches the undervoltage lockout ($V_{CC(UV)}$) threshold of 3.98 V (typical), the IC is enabled. An external capacitor at the VCC pin stabilizes the regulator and supplies transient VCC current to the gate drivers. An internal diode connected from VCC to the BST pin replenishes the charge in the high-side gate drive bootstrap capacitor when the SW pin is low.

In high input voltage applications, the power dissipated in the regulator is significant and can limit the efficiency and maximum achievable output power. The LM5160A allows the internal VCC regulator power loss to be reduced by supplying the VCC voltage through a diode from an external voltage source regulated between 9 V and 13 V. The external VCC bias can be supplied from the LM5160A converter output rail if the regulation voltage is within this range. When the VCC pin of the LM5160A is raised above the regulation voltage (7.5 V typical), the internal regulator is disabled and the power dissipation in the IC is reduced. The only difference between the LM5160 and LM5160A is wide operating V_{CC} voltage range of the LM5160A.



Feature Description (continued)

7.3.3 Regulation Comparator

The feedback voltage at the FB pin is compared to the SS pin voltage V_{SS} . In normal operation when the output voltage is in regulation, an ON-time period is initiated when the voltage at FB pin falls below V_{SS} . The high-side buck switch stays on for the ON-time one-shot period causing the FB voltage to rise. After the ON-time period expires, the high-side switch remains off until the FB voltage falls below V_{SS} . During the start-up, the FB voltage is below V_{SS} at the end of each ON-time period and the high-side switch turns on again after the minimum forced OFF-time of 170 ns (typical). When the output is shorted to ground (FB = 0 V), the high-side peak current limit is triggered, the high-side FET is turned off, and remains off for a period determined by the current limit OFF-timer. See the *Current Limit* section for additional information.

7.3.4 Soft Start

The soft-start feature of the LM5160 allows the converter to gradually reach a steady-state operating point, thereby reducing start-up stresses and current surges. When the EN/UVLO pin is above the EN/UVLO standby threshold $V_{UVLO(TH)} = 1.24$ V (typical) and the VCC exceeds the VCC undervoltage $V_{CC(UV)} = 3.98$ V (typical) threshold, an internal 10-µA current source charges the external capacitor at the SS pin C_{SS} from 0 V to 2 V. The voltage at the SS pin is the noninverting input of the internal FB comparator. The soft-start interval ends when the SS capacitor is charged to the 2-V reference level. The ramping voltage at the SS pin produces a controlled, monotonic output voltage start-up. A minimum 1-nF soft-start capacitor must be used in all applications.

7.3.5 Error Transconductance (G_M) Amplifier

The LM5160 provides a trans-conductance (G_M) error amplifier that minimizes the difference between the reference voltage (V_{REF}) and the average feedback (FB) voltage. This amplifier reduces the load and line regulation errors that are common in constant ON-time regulators. The soft-start capacitor C_{SS}) provides compensation for this error correction loop. The soft-start capacitor must be greater than 1 nF to ensure stability.

7.3.6 ON-Time Generator

The ON-time of the LM5160 high-side FET is determined by the R_{ON} resistor and is inversely proportional to the input voltage (V_{IN}). The inverse relationship with V_{IN} results in a nearly constant frequency as V_{IN} is varied. The ON-time can be calculated from Equation 3 with R_{ON} expressed in ohms.

$$T_{ON} = \frac{R_{ON} \times 1 \times 10^{-10}}{V_{IN}} s$$
(3)

To set a specific continuous conduction mode switching frequency (F_{SW} expressed in Hz), the R_{ON} resistor is determined from Equation 4:

$$R_{ON} = \frac{V_{OUT}}{F_{SW} \times 1 \times 10^{-10}} \Omega \tag{4}$$

 R_{ON} must be selected for a minimum ON-time (at maximum V_{IN}) greater than 150 ns for proper operation. This minimum ON-time requirement limits the maximum switching frequency of applications with relatively high V_{IN} and low V_{OUT} .

7.3.7 Current Limit

The LM5160 provides an intelligent current limit OFF-timer that adjusts the OFF-time to reduce the foldback in the current limit. If the peak value of the current in the buck switch exceeds 2.5 A (typical) the present ON-time period is immediately terminated, and a non-resettable OFF-timer is initiated. The length of the OFF-time is controlled by the FB voltage and the input voltage V_{IN} . As an example, when $V_{FB} = 0$ V and $V_{IN} = 24$ V, the OFF-time is set to 10 μ s. This condition would occur if the output is shorted or during the initial phase of start-up. In cases of output overload where the FB voltage is greater than zero volts (a soft short), the current limit OFF-time is reduced. Reducing the OFF-time during less severe overloads reduces the current limit foldback, overload recovery time, and start-up time. The current limit OFF-time, $T_{OFF(CL)}$ is calculated from Equation 5:

$$T_{OFF(CL)} = \frac{5V_{IN}}{24V_{FB} + 12} \,\mu\text{s} \tag{5}$$



Feature Description (continued)

7.3.8 N-Channel Buck Switch and Driver

The LM5160 integrates an N-channel buck switch and associated floating high-side gate driver. The gate driver circuit works in conjunction with an external bootstrap capacitor and an internal high voltage bootstrap diode. A 10-nF or larger ceramic capacitor connected between the BST pin and the SW pin provides the voltage to the high-side driver during the buck switch ON-time. During the OFF-time, the SW node is pulled down to approximately 0 V and the bootstrap capacitor charges from VCC through the internal bootstrap diode. The minimum OFF-time of 170 ns (typical) provides a minimum time each cycle to recharge the bootstrap capacitor.

7.3.9 Synchronous Rectifier

The LM5160 provides an internal low-side synchronous rectifier N-channel FET. This low-side FET provides a low resistance path for the inductor current when the high-side FET is turned off.

With the FPWM pin connected to ground or left floating, the LM5160 synchronous rectifier operates in diode emulation mode. Diode emulation enables the pulse-skipping during light load conditions. This leads to a reduction in the average switching frequency at light loads. Switching losses and FET gate driver losses, both of which are proportional to switching frequency, are significantly reduced and efficiency is improved. This pulse-skipping mode also reduces the circulating inductor currents and losses associated with a continuous conduction mode (CCM).

When the FPWM pin is pulled high, diode emulation is disabled. The inductor current can flow in either direction through the low-side FET resulting in CCM operation with nearly constant switching frequency. A negative sink current limit circuit limits the current that can flow into the SW pin and through the low-side FET to ground. In a buck regulator application, large negative current only flows from V_{OUT} to the SW pin if V_{OUT} is lifted above the output regulation setpoint.

7.3.10 Enable / Undervoltage Lockout (EN/UVLO)

The LM5160 contains a dual-level undervoltage lockout (EN/UVLO) circuit. When the EN/UVLO pin voltage is below 0.35 V, the regulator is in a low-current shutdown mode. When the EN/UVLO pin voltage is greater than 0.35 V (typical) but less than 1.24 V (typical), the regulator is in standby mode. In standby mode, the VCC bias regulator is active but converter switching remains disabled. When the voltage at the VCC pin exceeds the VCC rising threshold $V_{CC(UV)} = 3.98 \text{ V}$ (typical) and the EN/UVLO pin voltage is greater than 1.24 V, normal switching operation begins. An external resistor voltage divider from VIN to GND can be used to set the minimum operating voltage of the regulator.

EN/UVLO hysteresis is accomplished with an internal 20 μ A (typical) current source (I_{UVLO(HYS)}) that is switched on or off into the impedance of the EN/UVLO pin resistor divider. When the EN/UVLO threshold is exceeded, the current source is activated to effectively raise the voltage at the EN/UVLO pin. The hysteresis is equal to the value of this current times the upper resistance of the resistor divider, R_{UV2}) (See *Functional Block Diagram*).

7.3.11 Thermal Protection

The LM5160 must be operated such that the junction temperature does not exceed 150°C during normal operation. An internal thermal shutdown circuit is provided to protect the LM5160 in the event of a higher than normal junction temperature. When activated, typically at 175°C, the controller is forced into a low-power reset state, disabling the high-side buck switch and the VCC regulator. This feature prevents catastrophic failures from accidental device overheating. When the junction temperature falls below 155°C (typical hysteresis = 20°C), the VCC regulator is enabled, and operation resumes.

Product Folder Links: LM5160A LM5160



7.4 Device Functional Modes

7.4.1 Forced Pulse Width Modulation (FPWM) Mode

The *Synchronous Rectifier* section gives a brief introduction to the LM5160 diode emulation feature. The FPWM pin allows the power supply designer to select either CCM or DCM mode of operation at light loads. When the FPWM pin is connected to ground or left floating (FPWM = 0), a pulse-skipping mode is enabled and a zero-cross current detector circuit is enabled. The zero-cross detector turns off the low-side FET when the inductor current falls to zero (I_{ZX} , see *Electrical Characteristics*). This feature allows the LM5160 regulator to operate in DCM mode at light loads. In the DCM state, the switching frequency decreases with lighter loads.

If the FPWM pin is pulled high (FPWM connected to VCC), the LM5160 operates in CCM mode even at light loads. This option allows the synchronous rectifier FET to conduct continuously until the start of the next high-side switch cycle. The inductor current drops to zero and then reverse direction (negative direction through inductor), passing from drain to source of low-side FET. The current flows continuously until the FB comparator initiates another high-side switch ON-time. CCM operation reduces efficiency at light load but improves the output transient response to step load changes and provides nearly constant switching frequency.

Table 1. FPWM Pin Mode Summary

FPWM PIN CONNECTION	LOGIC STAGE	DESCRIPTION
GND or Floating (High Z)	0	The FPWM pin is grounded or left floating. DCM enabled at light loads.
V _{CC}	1	The FPWM pin is connected to VCC. The LM5160 then operates in CCM mode at light loads.

7.4.2 Undervoltage Detector

The following table summarizes the dual threshold levels of the undervoltage lockout (EN/UVLO) circuit explained in *Enable / Undervoltage Lockout (EN/UVLO)*.

Table 2. UVLO Pin Mode Summary

EN/UVLO PIN VOLTAGE	VCC REGULATOR	MODE	DESCRIPTION
< 0.35 V	Off	Shutdown	V _{CC} regulator disabled. High-side and low-side FETs disabled.
0.35 V to 1.24 V	On	Standby	V _{CC} regulator enabled. High-side and low-side FETs disabled.
> 1.24 V	V _{CC} < V _{CC(UV)}	Standby	V _{CC} regulator enabled. High-side and low-side FETs disabled.
	$V_{CC} > V_{CC(UV)}$	Operating	V _{CC} regulator enabled. Switching enabled.

If an EN/UVLO setpoint is not required, the EN/UVLO pin can be driven by a logic signal as an enable input or connected directly to the VIN pin. If the EN/UVLO is directly connected to the VIN pin, the regulator begins switching when the $V_{CC(UV)} = 3.98 \text{ V}$ (typical) is satisfied.

Product Folder Links: LM5160A LM5160

Copyright © 2014-2017, Texas Instruments Incorporated



8 Applications and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

The LM5160 family is a synchronous-buck regulator converter designed to operate over a wide input voltage and output current range. Spreadsheet based Quick-Start Calculator tools, available on the www.ti.com product website, can be used to design a single output synchronous buck converter or an isolated dual output Fly-Buck converter using both the LM5160 and LM5160A. For a detailed design guide for the Fly-Buck converter, refer to the AN-2292 Designing an Isolated Buck (Fly-Buck) Converter application report. Alternatively, online WEBENCH software can be used to create a complete buck or Fly-Buck designs and generate the bill of materials, estimated efficiency, solution size, and cost of the complete solution.

Typical Applications describes a few application circuits using the LM5160 or LM5160A with detailed, step-by-step design procedures.

8.1.1 Ripple Configuration

LM5160 and LM5160A uses a Constant ON-Time (COT) control scheme, in which the ON-time is terminated by a one-shot, and the OFF-time is terminated by the feedback voltage (V_{FB}) falling below the reference voltage. Therefore, for stable operation, the feedback voltage must decrease monotonically in phase with the inductor current during the OFF-time. Furthermore, this change in feedback voltage (V_{FB}) during OFF-time must be large enough to dominate any noise present at the feedback node.

Table 3 presents three different methods for generating appropriate voltage ripple at the feedback node. Type 1 and Type 2 ripple circuits couple the ripple from the output of the converter to the feedback node (FB). The output voltage ripple has two components:

- 1. Capacitive ripple caused by the inductor current ripple charging or discharging the output capacitor.
- 2. Resistive ripple caused by the inductor current ripple flowing through the ESR of the output capacitor and R3.

The capacitive ripple is out-of-phase with the inductor current. As a result, the capacitive ripple does not decrease monotonically during the OFF-time. The resistive ripple is in phase with the inductor current and decreases monotonically during the OFF-time. The resistive ripple must exceed the capacitive ripple at output (V_{OUT}) for stable operation. If this condition is not satisfied unstable switching behavior is observed in COT converters, with multiple ON-time bursts in close succession followed by a long OFF-time.

Type 3 ripple method uses a ripple injection circuit with R_A, C_A and the switch node (SW) voltage to generate a triangular ramp. This triangular ramp is then AC-coupled into the feedback node (FB) using the capacitor C_B. Because this circuit does not use the output voltage ripple, it is suited for applications where low output voltage ripple is imperative. For more information on each ripple generation method, refer to the *AN-1481 Controlling Output Ripple & Achiev ESR Indep Constant On-Time Reg Designs* application note.

Table 3. Ripple Configuration

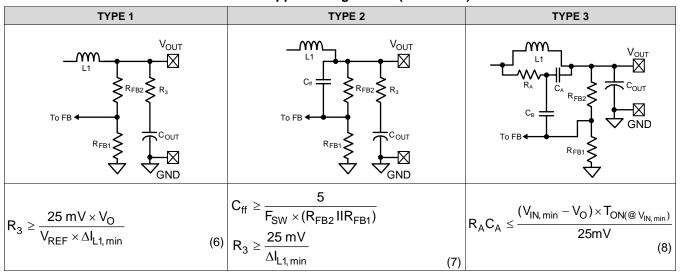
TYPE 1	TYPE 2	TYPE 3
Lowest Cost	Reduced Ripple	Minimum Ripple

Product Folder Links: LM5160A LM5160



Application Information (continued)

Table 3. Ripple Configuration (continued)



8.2 Typical Applications

8.2.1 LM5160 Synchronous Buck (10-V to 60-V Input, 5-V Output, 1.5-A Load)

A typical application example is a synchronous buck converter operating from a wide input voltage range of 10 V to 65 V and providing a stable 5-V output voltage with output current capability of 1.5 A. The complete schematic for a typical synchronous buck application circuit is shown in Figure 19. In the application schematic below, the components are labeled by numbers instead of the descriptive name used in the previous sections. For example, R3 represents R_{ON} and so on.

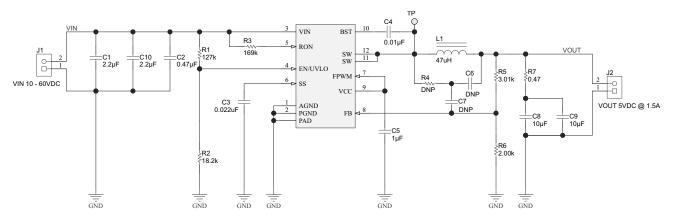


Figure 19. Synchronous Buck Application Circuit



Typical Applications (continued)

8.2.1.1 Design Requirements

A typical synchronous-buck application introduced in *LM5160 Synchronous Buck (10-V to 60-V Input, 5-V Output, 1.5-A Load)*, Table 4 summarizes the operating parameters:

Table 4. Design Parameters

DESIGN PARAMETER	EXAMPLE VALUE		
Input voltage range	10 V to 65 V		
Output	5 V		
Load current	1.5 A		
Nominal switching frequency	300 kHz		
Light load operating mode	CCM, FPWM=1		

8.2.1.2 Detailed Design Procedure

8.2.1.2.1 Custom Design With WEBENCH® Tools

Click here to create a custom design using the LM5160A device with the WEBENCH® Power Designer.

- 1. Start by entering the input voltage (V_{IN}), output voltage (V_{OUT}), and output current (I_{OUT}) requirements.
- 2. Optimize the design for key parameters such as efficiency, footprint, and cost using the optimizer dial.
- 3. Compare the generated design with other possible solutions from Texas Instruments.

The WEBENCH Power Designer provides a customized schematic along with a list of materials with real-time pricing and component availability.

In most cases, these actions are available:

- Run electrical simulations to see important waveforms and circuit performance
- Run thermal simulations to understand board thermal performance
- Export customized schematic and layout into popular CAD formats
- Print PDF reports for the design, and share the design with colleagues

Get more information about WEBENCH tools at www.ti.com/WEBENCH.

8.2.1.2.2 Output Resistor Divider Selection

With the required output voltage set point at 5 V and $V_{FB} = 2 \text{ V}$ (typical), the ratio of R6 R_{FB1}) to R5 R_{FB2}) can be calculated using Equation 9:

$$\frac{R_{FB2}}{R_{FB1}} = \frac{V_{OUT}}{V_{REF}} - 1 \tag{9}$$

The resistor ratio calculates to be 3:2. Standard values of R6 R_{FB1}) = 2 k Ω and R5 R_{FB2}) =3.01 k Ω are chosen. Higher or lower values could be used as long as the ratio of the 3:2 is maintained.

8.2.1.2.3 Frequency Selection

The duty cycle required to maintain output regulation at the minimum input voltage restricts the maximum switching frequency of LM5160. The maximum value of the minimum forced OFF-time $T_{OFF,min}$ (maximum), limits the duty cycle and therefore the switching frequency. The maximum frequency that avoids output dropout at minimum input voltage can be calculated from Equation 10.

$$F_{SW, \max(@V_{IN, \min})} = \frac{V_{IN, \min} - V_{OUT}}{V_{IN, \min} \times T_{OFF, \min}(ns)}$$
(10)

For this design example, the maximum frequency based on the minimum OFF-time limitation for $T_{OFF,min}$ (typical) = 170 ns is calculated to be $F_{SW,max(@VIN,min)}$ = 2.9 MHz. This value is well above 1 MHz, the maximum possible operating frequency of the LM5160. Therefore, the minimum OFF-time parameter cannot be used further for the maximum achievable switching frequency calculation in this application.

Submit Documentation Feedback

Copyright © 2014–2017, Texas Instruments Incorporated



At the maximum input voltage, the maximum switching frequency of LM5160 is restricted by the minimum ON-time, T_{ON,min} which limits the minimum duty cycle of the converter. The maximum frequency at maximum input voltage can be calculated using Equation 11.

$$F_{SW, \max(@V_{IN, \max})} = \frac{V_{OUT}}{V_{IN, \max} \times T_{ON, \min}(ns)}$$
(11)

Using Equation 11 and $T_{ON,min}$ (typical) = 150 ns, the maximum achievable switching frequency is $F_{SW,max(@VIN,min)}$ = 514 kHz. Taking this value as the maximum possible operational switching frequency over the input voltage range in this application, a nominal switching frequency of F_{SW} = 300 kHz is chosen for this design.

The value of the resistor, R_{ON} sets the nominal switching frequency based on Equation 12.

$$R_{ON} = \frac{V_{OUT}}{F_{SW} \times 1 \times 10^{-10}} \Omega \tag{12}$$

For this particular application with $F_{SW}=300$ kHz, R_{ON} calculates to be 167 k Ω . Selecting a standard value for R3 R_{ON}) = 169 k Ω (±1%) results in an ideal nominal frequency of 296 kHz. The resistor value may need to adjusted further in order to achieve the required switching frequency as the switching frequency in COTs varies slightly(±10%) with input voltage and/or output current. Operation at a lower nominal switching frequency results in higher efficiency but increase in the inductor and capacitor values leading to a larger total solution size.

8.2.1.2.4 Inductor Selection

The inductor is selected to limit the inductor ripple current between 20 and 40 percent of the maximum load current. The minimum value of the inductor required in this application can be calculated from Equation 13:

$$L_{min} = \frac{V_O \times (V_{IN, max} - V_O)}{V_{IN, max} \times F_{SW} \times I_{O, max} \times 0.4}$$
(13)

Based on Equation 13, the minimum value of the inductor is calculated to be 26 μ H for V_{IN} = 65 V (maximum) and inductor current ripple equal to 40 percent of the maximum load current. Allowing some margin for inductance variation and inductor saturation, a higher standard value of L1 (L) = 47 μ H is selected for this design.

The peak inductor current at maximum load must be smaller than the minimum current limit threshold of the highside FET as given in *Electrical Characteristics* table. The inductor current ripple at any input voltage is given by:

$$\Delta I_{L} = \frac{V_{O} \times (V_{IN} - V_{O})}{V_{IN} \times F_{SW} \times L}$$
(14)

The peak-to-peak inductor current ripple is calculated to be 180 mA and 332 mA at the minimum and maximum input voltages respectively. The maximum peak inductor current in the buck FET is given by:

$$I_{L(peak)} = I_{O, max} + \frac{\Delta I_{L, max}}{2}$$
(15)

In this design with output current of 1.5 A, the maximum peak inductor current is calculated to be approximately 1.67 A which is less than the minimum high-side FET current limit threshold.

The saturation current of the inductor must also be carefully considered. The peak value of the inductor current is bound by the high-side FET current limit during overload or short circuit conditions. Based on the high-side FET current limit specification in the *Electrical Characteristics*, an inductor with saturation current rating above 2.875 A (maximum) must be selected.

8.2.1.2.5 Output Capacitor Selection

The output capacitor is selected to limit the capacitive ripple at the output of the regulator. Maximum capacitive ripple is observed at maximum input voltage. The output capacitance required for a ripple voltage ΔV_O across the capacitor is given by Equation 16.

$$C_{OUT} = \frac{\Delta I_{L, max}}{8 \times F_{SW} \times \Delta V_{O, ripple}}$$
(16)



Substituting $\Delta V_{O, ripple} = 10$ mV gives $C_{OUT} = 14$ μF . Two standard 10- μF ceramic capacitors in parallel (C8, C9) are selected. An X7R type capacitor with a voltage rating 16 V or higher must be used for C_{OUT} (C8, C9) to limit the reduction of capacitance due to DC bias voltage.

8.2.1.2.6 Series Ripple Resistor - R_{ESR}

The series resistor is selected such that sufficient ripple injection is ensured at the feedback node FB. The ripple produced by R_{ESR} is proportional to the inductor current ripple, and therefore, R_{ESR} must be chosen for minimum inductor current ripple which occurs at minimum input voltage. The R_{ESR} is calculated by Equation 17.

$$R_{ESR} \ge \frac{25 \text{ mV} \times V_{O}}{V_{REF} \times \Delta I_{L, min}}$$
(17)

With $V_O = 5$ V, $V_{REF} = 2$ V and $\Delta I_{L, min} = 180$ mA (at $V_{IN, min} = 10$ V) as calculated in Equation 14, Equation 17 requires an R_{ESR} greater than or equal to 0.35 Ω . Selecting R7 R_{ESR}) = 0.47 Ω results in approximately 150 mV of maximum output voltage ripple at $V_{IN,max}$. For applications requiring lower output voltage ripple, Type II or Type III ripple injection circuits should be used as described in *Ripple Configuration*.

8.2.1.2.7 VCC and Bootstrap Capacitor

The VCC capacitor charges the bootstrap capacitor during the OFF-time of the high-side switch and powers internal logic circuits and the low-side sync FET gate driver. The bootstrap capacitor biases the high-side gate driver during the high-side FET ON-time. A good value for C5 C_{VCC}) is 1 μ F. A good choice for C4 C_{BST}) is 10 nF. Both must be high-quality X7R ceramic capacitors.

8.2.1.2.8 Input Capacitor Selection

The input capacitor must be large enough to limit the input voltage ripple to an acceptable level. Equation 18 provides the input capacitance C_{IN} required for a worst-case input ripple of $\Delta V_{IN, ripple}$.

$$C_{IN} = \frac{I_{O, max} \times D \times (1 - D)}{\Delta V_{IN, ripple} \times F_{SW}}$$
(18)

 C_{IN} (C1, C10) supplies most of the switch current during the ON-time to limit the voltage ripple at the VIN pin. At maximum load current, when the buck switch turns on, the current into the VIN pin quickly increases to the valley current of the inductor ripple and then ramps up to the peak of the inductor ripple during the ON-time of the high-side FET. The average current during the ON-time is the output load current. For a worst-case calculation, C_{IN} must supply this average load current during the maximum ON-time, without letting the voltage at VIN drop more than the desired input ripple. For this design, the input voltage drop is limited to 0.5 V and the value of C_{IN} is calculated using Equation 18.

Based on Equation 18, the value of the input capacitor is calculated to be approximately 2.5 μ F at D = 0.5. Taking into account the decrease in capacitance over an applied voltage, two standard value ceramic capacitors of 2.2 μ F are selected for C1 and C10. The input capacitors must be rated for the maximum input voltage under all operating and transient conditions. A 100-V, X7R dielectric was selected for this design.

A third input capacitor C2 may be needed in this design as a bypass path for the high frequency component of the input switching current. The value of C2 is $0.47~\mu F$ and this bypass capacitor must be placed directly across VIN and PGND (pin 3 and 2) near the IC. The C_{IN} values and location are critical to reducing switching noise and transients.

8.2.1.2.9 Soft-Start Capacitor Selection

The capacitor at the SS pin determines the soft-start time, that is, the time for the output voltage to reach its final steady-state value. The capacitor value is determined from Equation 19:

$$C_{SS} = \frac{I_{SS} \times T_{Startup}}{V_{SS}}$$
(19)

With C3 C_{SS}) set at 22 nF and the Vss = 2 V, I_{SS} = 10 μ A, the $T_{Startup}$ must measure approximately 4 ms.

20



8.2.1.2.10 EN/UVLO Resistor Selection

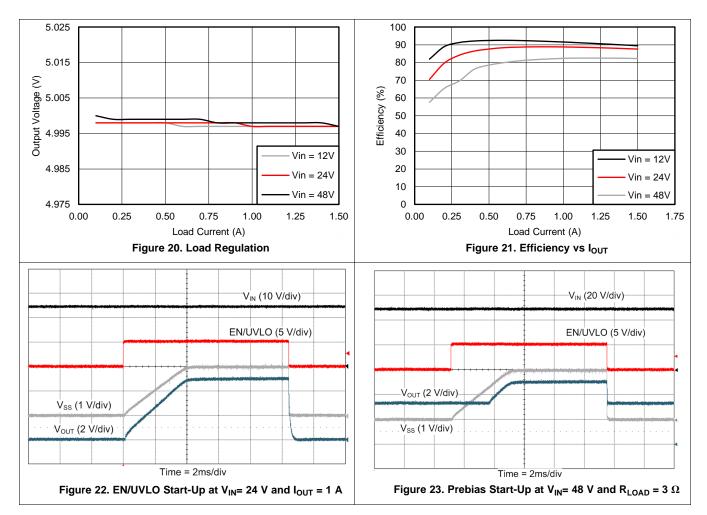
The UVLO resistors R1 R_{UV2}) and R2 R_{UV1}) set the input undervoltage lockout threshold and hysteresis according to Equation 20 and Equation 21:

$$V_{IN(HYS)} = I_{UVLO(HYS)} \times R_{UV2}$$
(20)

$$V_{IN, UVLO(rising)} = V_{UVLO(TH)} \left(1 + \frac{R_{UV2}}{R_{UV1}} \right)$$
(21)

From the *Electrical Characteristics* table, $I_{UVLO(HYS)}=20~\mu A$ (typical). To design for V_{IN} rising threshold ($V_{IN,UVLO(rising)}$) at 10 V and EN/UVLO hysteresis of 2.5 V, Equation 20 and Equation 21 yield $R_{UV1}=17.98~k\Omega$ and $R_{UV2}=125~k\Omega$. Selecting 1% sandard value of R2 $R_{UV1}=18.2~k\Omega$ and R1 $R_{UV2}=127~k\Omega$ results in UVLO thresholds and hysteresis of 9.89 V and 2.54 V respectively.

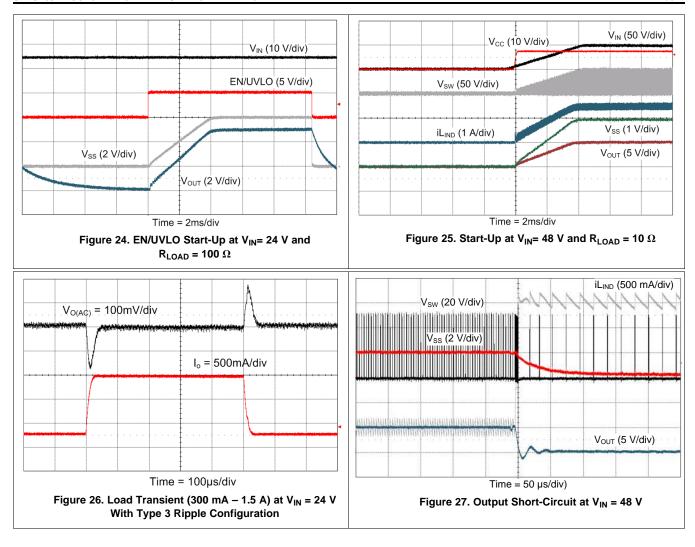
8.2.1.3 Application Curves



Copyright © 2014-2017, Texas Instruments Incorporated

Product Folder Links: LM5160A LM5160







8.2.2 LM5160 Isolated Fly-Buck (18-V to 32-V Input, 12-V, 4.5-W Isolated Output)

A typical application example for an isolated Fly-Buck converter operates over an input voltage range of 18 V to 32 V. It provides a stable 12-V isolated output voltage with output power capability of 4.5 W. The complete schematic of the Fly-Buck application circuit is shown in Figure 28.

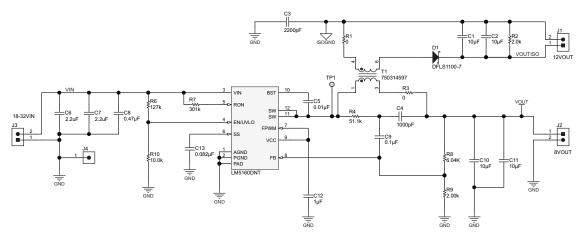


Figure 28. 12-V, 4.5-W Fly-Buck Schematic

8.2.2.1 LM5160 Fly-Buck Design Requirements

The LM5160 Fly-Buck application example is designed to operate from a 24-V DC supply with line variations from 18 V to 32 V. This example provides a space-optimized and efficient 12-V isolated output solution with secondary load current capability from 0 mA to 400 mA. The primary side remains unloaded in this application. The switching frequency is set at 300 kHz (nominal). This design achieves greater than 88% peak efficiency.

DESIGN PARAMETEREXAMPLE VALUEInput voltage range18 V - 32 VIsolated output12 VIsolated load current range0 mA to 400 mANominal switching frequency300 KHzPeak Efficiency88%

Table 5. Design Parameters



8.2.2.2 Detailed Design Procedure

The Fly-Buck converter design procedure closely follows the buck converter design outlined in *LM5160 Synchronous Buck (10-V to 60-V Input, 5-V Output, 1.5-A Load)*. The selection of primary output voltage, transformer turns ratio, rectifier diode, and output capacitors are covered here.

8.2.2.2.1 Selection of V_{OUT1} and Turns Ratio

The primary output voltage in a Fly-Buck converter must be no more than one half of the minimum input voltage. For a minimum V_{IN} of 18 V, the primary output voltage (V_{OUT}) must be no higher than 9 V. To generate an isolated output voltage of V_{OUT} (ISO) = 12 V, a transformer turns ratio (N1:N2) of 1:1.5 is selected. Using this turns ration, the required primary output voltage V_{OUT} is calculated in Equation 22:

$$V_{OUT} = \frac{V_{OUT(ISO)} + 0.7 \text{ V}}{1.5} = 8.47 \text{ V}$$
 (22)

The 0.7 V subtracted from $V_{OUT(ISO)}$ represents the forward voltage drop of the secondary rectifier diode. Fine tuning the primary side V_{OUT1} may be required to account for voltage errors due to the leakage inductance of the transformer and the resistance of the transformer windings and the low-side FET of LM5160.

8.2.2.2.2 Secondary Rectifier Diode

The secondary rectifier diode must block the maximum input voltage multiplied by the transformer turns ratio. The minimum diode reverse voltage $V_{R(diode)}$ rating is given by Equation 23:

$$V_{R(diode)} = V_{IN(max)} \times \frac{N2}{N1} + V_{OUT(ISO)} = 32 \text{ V} \times 1.5 + 12 \text{ V} = 60 \text{ V}$$
(23)

A diode of 60 V or higher reverse voltage rating must be selected in this application. If the input voltage (V_{IN}) has transients above the normal operating maximum input voltage of 32 V, then the worst-case transient input voltage must be used in the diode voltage calculation of Equation 23.

8.2.2.2.3 External Ripple Circuit

Type 3 ripple circuit is required for Fly-Buck applications. The design procedure for ripple components is identical to that in a buck converter. See *Ripple Configuration* for ripple design information.

8.2.2.2.4 Output Capacitor (COUT2)

The Fly-Buck output capacitor conducts higher ripple current than a buck converter output capacitor. The capacitive ripple for the isolated output capacitor is calculated based on the time the rectifier diode is off. During this time the entire output current is supplied by the output capacitor. The required capacitance for a worst-case V_{OUT} (V_{OUT} (ISO)) ripple voltage can be calculated using Equation 24.

$$C_{OUT2} = \frac{I_{OUT2}}{\Delta V_{OUT2}} \left(\frac{V_{OUT1}}{V_{IN(MIN)}} \right) \times \frac{1}{f_{sw}}$$

where

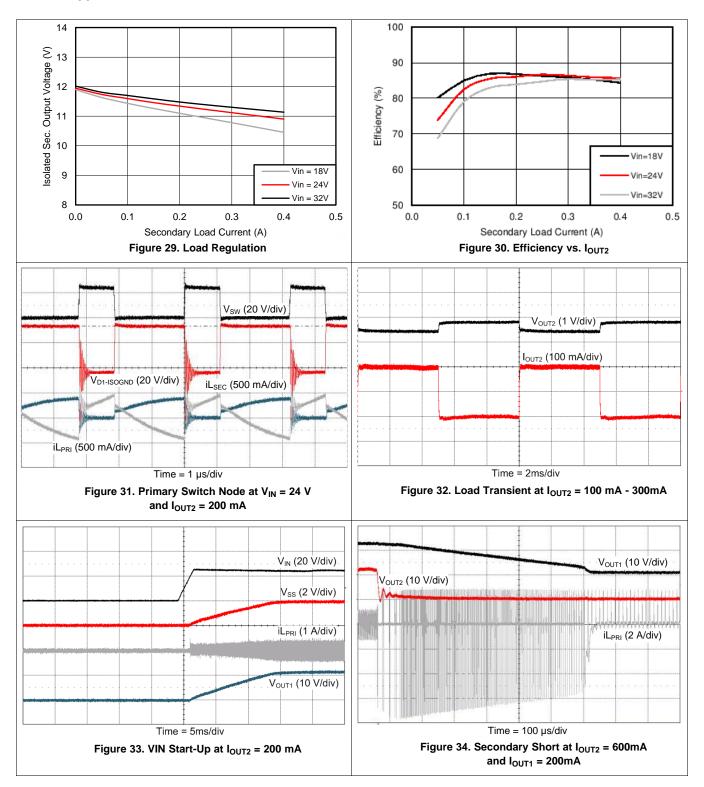
ΔV_{OUT2} is the target ripple at the secondary output.

(24)

Equation 24 is an approximation and ignores the ripple components associated with ESR and ESL of the output capacitor. For a ΔV_{OUT2} = 100 mV, Equation 24 requires C_{OUT2} = 6.5 μF . When selecting a capacitor, consider its DC bias to ensure sufficient capacitance over the output voltage.



8.2.2.3 Application Curves





8.2.3 LM5160A Isolated Fly-Buck (18-V to 32-V Input, 12-V, 4.5-W Isolated Output)

The LM5160A when used in either the buck or the Fly-Buck application, can also be biased by an external voltage source for improved efficiency requirements. The LM5160A, can be externally biased to VOUT by connecting VCC to VOUT through a diode as shown in the Fly-Buck application circuit in Figure 35. In this dual output rail Fly-Buck application circuit, the VCC pin is externally diode connected (D2) to VOUT (primary). The design procedure with LM5160A, for both Buck and the Fly-BuckTM, remain same as with LM5160. The voltage applied to the VCC pin, either from VOUT or an external supply must be between 9 V and 13 V.

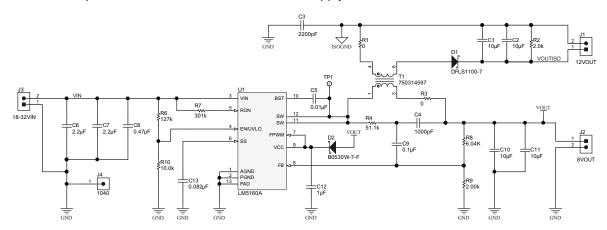


Figure 35. 12-V, 4.5-W Fly-Buck Schematic With LM5160A

8.3 Do's and Don'ts

As mentioned earlier in *Soft Start*, the SS capacitor C_{SS} , must always be more than 1 nF in both buck and Fly-Buck applications. Apart from determining the start-up time, this capacitor serves as the external compensation of the internal G_M error amplifier. A minimum value of 1 nF is necessary to maintain stability. The SS pin must not be left floating.

The VCC pin in the LM5160 must not be biased with an external voltage source. When improved efficiency requirement warrants an external V_{CC} bias, the LM5160A must be used.

9 Power Supply Recommendations

The LM5160 is designed to operate with an input power supply capable of supplying a voltage range between 4.5 V and 65 V. The power supply must be well regulated and capable of supplying sufficient current to the regulator during the sync buck mode or the isolated Fly-Buck mode of operation. As in all DC-DC applications, the power supply source impedance must be small compared to the converter input impedance in order to maintain the stability of the converter.

If the LM5160 is used in a buck topology with low input supply voltage (4.5 V) and large load current (2 A), it is prudent to add a large electrolytic capacitor, in parallel the C_{IN} capacitors. The electrolytic capacitor stabilizes the input voltage to the IC and prevent droop or oscillation, over the entire load range.



10 Layout

10.1 Layout Guidelines

A proper layout is essential for optimum performance of the circuit. In particular, observe the following guidelines:

- C_{IN}: The loop consisting of input capacitor (C_{IN}), VIN pin, and PGND pin carries the switching current. Therefore, in both the LM5160 and the LM5160A, the input capacitor must be placed close to the IC, directly across VIN and PGND pins, and the connections to these two pins must be direct to minimize the loop area. In general it is not possible to place all of input capacitances near the IC. A good layout practice includes placing the bulk capacitor as close as possible to the VIN pin (see Figure 36).
- C_{VCC} and C_{BST}: The VCC and bootstrap (BST) bypass capacitors supply switching currents to the high and low-side gate drivers. These two capacitors must also be placed as close to the IC as possible, and the connecting trace length and loop area must be minimized (see Figure 36).
- The feedback trace carries the output voltage information and a small ripple component that is necessary for
 proper operation of both the LM5160 and the LM5160A. Therefore, take care while routing the feedback trace
 to avoid coupling any noise into this pin. In particular, the feedback trace must be short and not run close to
 magnetic components, or parallel to any other switching trace.
- SW trace: The SW node switches rapidly between VIN and GND every cycle and is therefore a source of noise. The SW node area must be minimized. In particular, the SW node must not be inadvertently connected to a copper plane or pour.

10.2 Layout Example

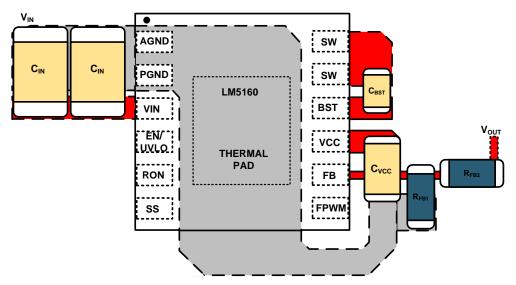


Figure 36. Placement of Bypass Capacitors



11 Device and Documentation Support

11.1 Device Support

11.1.1 Development Support

For design tools see the LM5160 PSpice Transient Model, LM5160 Unencrypted PSpice Transient Model, and LM5160 TINA-TI Flybuck Reference Design.

11.1.1.1 Custom Design With WEBENCH® Tools

Click here to create a custom design using the LM5160A device with the WEBENCH® Power Designer.

- 1. Start by entering the input voltage (V_{IN}) , output voltage (V_{OUT}) , and output current (I_{OUT}) requirements.
- 2. Optimize the design for key parameters such as efficiency, footprint, and cost using the optimizer dial.
- 3. Compare the generated design with other possible solutions from Texas Instruments.

The WEBENCH Power Designer provides a customized schematic along with a list of materials with real-time pricing and component availability.

In most cases, these actions are available:

- Run electrical simulations to see important waveforms and circuit performance
- Run thermal simulations to understand board thermal performance
- Export customized schematic and layout into popular CAD formats
- Print PDF reports for the design, and share the design with colleagues

Get more information about WEBENCH tools at www.ti.com/WEBENCH.

11.2 Documentation Support

11.2.1 Related Documentation

For related documentation see the following: For related documentation, see the following:

- Texas Instruments, AN-2292 Designing an Isolated Buck (Fly-Buck) Converter application report
- Texas Instruments, AN-1481 Controlling Output Ripple & Achieving ESR Independence in Constant ON-Time Regulator Designs application report
- Texas Instruments, LM5160A, LM5160 Buck EVM User's Guide
- Texas Instruments, LM5160 Fly-Buck (Isolated Buck) User's Guide

11.3 Related Links

The table below lists quick access links. Categories include technical documents, support and community resources, tools and software, and quick access to sample or buy.

Table 6. Related Links

PARTS	PRODUCT FOLDER	SAMPLE & BUY	TECHNICAL DOCUMENTS	TOOLS & SOFTWARE	SUPPORT & COMMUNITY
LM5160	Click here	Click here	Click here	Click here	Click here
LM5160A	Click here	Click here	Click here	Click here	Click here

11.4 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

11.5 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

Product Folder Links: LM5160A LM5160



Community Resources (continued)

TI E2E™ Online Community TI's Engineer-to-Engineer (E2E) Community. Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

Design Support TI's Design Support Quickly find helpful E2E forums along with design support tools and contact information for technical support.

11.6 Trademarks

Flv-Buck, E2E are trademarks of Texas Instruments. WEBENCH is a registered trademark of Texas Instruments. All other trademarks are the property of their respective owners.

11.7 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

11.8 Glossary

SLYZ022 — TI Glossary.

This glossary lists and explains terms, acronyms, and definitions.

12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical packaging and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

Copyright © 2014-2017, Texas Instruments Incorporated





20-Nov-2017

PACKAGING INFORMATION

Orderable Device	Status	Package Type	Package	Pins	Package	Eco Plan	Lead/Ball Finish	MSL Peak Temp	Op Temp (°C)	Device Marking	Samples
0.40.40.0	(1)	. acinge type	Drawing		Qty	(2)	(6)	(3)	op ::::::p (o)	(4/5)	
LM5160ADNTJ	ACTIVE	WSON	DNT	12	4500	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	LM5160A	Samples
LM5160ADNTR	ACTIVE	WSON	DNT	12	1000	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	LM5160A	Samples
LM5160ADNTT	ACTIVE	WSON	DNT	12	250	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	LM5160A	Samples
LM5160DNTJ	ACTIVE	WSON	DNT	12	4500	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	LM5160	Samples
LM5160DNTR	ACTIVE	WSON	DNT	12	1000	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	LM5160	Samples
LM5160DNTT	ACTIVE	WSON	DNT	12	250	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	LM5160	Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

- (3) MSL, Peak Temp. The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
- (4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
- (5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.



PACKAGE OPTION ADDENDUM

20-Nov-2017

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

OTHER QUALIFIED VERSIONS OF LM5160:

Automotive: LM5160-Q1

NOTE: Qualified Version Definitions:

Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects

PACKAGE MATERIALS INFORMATION

www.ti.com 20-Nov-2017

TAPE AND REEL INFORMATION





Α0	Dimension designed to accommodate the component width
	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LM5160ADNTJ	WSON	DNT	12	4500	330.0	12.4	4.3	4.3	1.3	8.0	12.0	Q1
LM5160ADNTR	WSON	DNT	12	1000	178.0	12.4	4.3	4.3	1.3	8.0	12.0	Q1
LM5160ADNTT	WSON	DNT	12	250	178.0	12.4	4.3	4.3	1.3	8.0	12.0	Q1
LM5160DNTJ	WSON	DNT	12	4500	330.0	12.4	4.3	4.3	1.3	8.0	12.0	Q1
LM5160DNTR	WSON	DNT	12	1000	178.0	12.4	4.3	4.3	1.3	8.0	12.0	Q1
LM5160DNTT	WSON	DNT	12	250	178.0	12.4	4.3	4.3	1.3	8.0	12.0	Q1

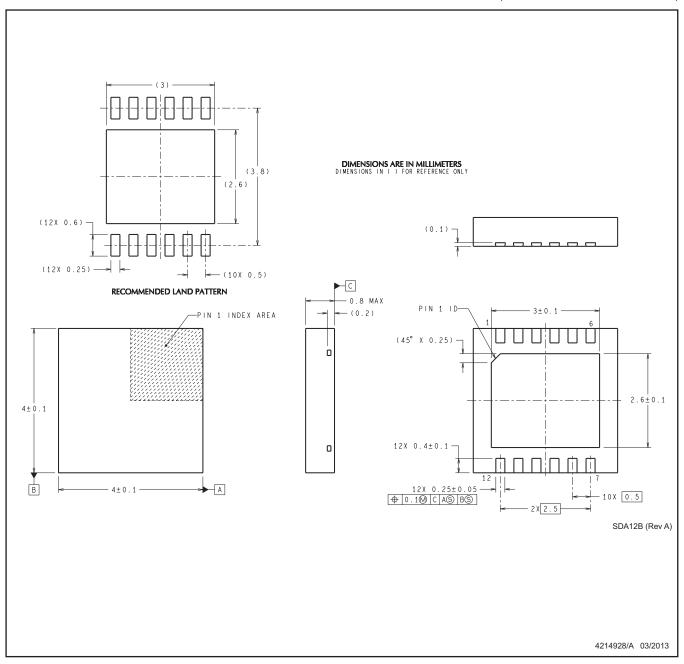
www.ti.com 20-Nov-2017



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LM5160ADNTJ	WSON	DNT	12	4500	367.0	367.0	35.0
LM5160ADNTR	WSON	DNT	12	1000	210.0	185.0	35.0
LM5160ADNTT	WSON	DNT	12	250	210.0	185.0	35.0
LM5160DNTJ	WSON	DNT	12	4500	367.0	367.0	35.0
LM5160DNTR	WSON	DNT	12	1000	210.0	185.0	35.0
LM5160DNTT	WSON	DNT	12	250	210.0	185.0	35.0

SON (PLASTIC SMALL OUTLINE - NO LEAD)



NOTES: 1. All linear dimensions are in millimeters. Dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

- 2. This drawing is subject to change without notice.
- 3. This package is designed to be soldered to a thermal pad on the board for thermal and mechanical performance. For more information, refer to QFN/SON PCB application note in literature No. SLUA271 (www.ti.com/lit/slua271).



IMPORTANT NOTICE

Texas Instruments Incorporated (TI) reserves the right to make corrections, enhancements, improvements and other changes to its semiconductor products and services per JESD46, latest issue, and to discontinue any product or service per JESD48, latest issue. Buyers should obtain the latest relevant information before placing orders and should verify that such information is current and complete.

TI's published terms of sale for semiconductor products (http://www.ti.com/sc/docs/stdterms.htm) apply to the sale of packaged integrated circuit products that TI has qualified and released to market. Additional terms may apply to the use or sale of other types of TI products and services.

Reproduction of significant portions of TI information in TI data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. TI is not responsible or liable for such reproduced documentation. Information of third parties may be subject to additional restrictions. Resale of TI products or services with statements different from or beyond the parameters stated by TI for that product or service voids all express and any implied warranties for the associated TI product or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Buyers and others who are developing systems that incorporate TI products (collectively, "Designers") understand and agree that Designers remain responsible for using their independent analysis, evaluation and judgment in designing their applications and that Designers have full and exclusive responsibility to assure the safety of Designers' applications and compliance of their applications (and of all TI products used in or for Designers' applications) with all applicable regulations, laws and other applicable requirements. Designer represents that, with respect to their applications, Designer has all the necessary expertise to create and implement safeguards that (1) anticipate dangerous consequences of failures, (2) monitor failures and their consequences, and (3) lessen the likelihood of failures that might cause harm and take appropriate actions. Designer agrees that prior to using or distributing any applications that include TI products, Designer will thoroughly test such applications and the functionality of such TI products as used in such applications.

TI's provision of technical, application or other design advice, quality characterization, reliability data or other services or information, including, but not limited to, reference designs and materials relating to evaluation modules, (collectively, "TI Resources") are intended to assist designers who are developing applications that incorporate TI products; by downloading, accessing or using TI Resources in any way, Designer (individually or, if Designer is acting on behalf of a company, Designer's company) agrees to use any particular TI Resource solely for this purpose and subject to the terms of this Notice.

TI's provision of TI Resources does not expand or otherwise alter TI's applicable published warranties or warranty disclaimers for TI products, and no additional obligations or liabilities arise from TI providing such TI Resources. TI reserves the right to make corrections, enhancements, improvements and other changes to its TI Resources. TI has not conducted any testing other than that specifically described in the published documentation for a particular TI Resource.

Designer is authorized to use, copy and modify any individual TI Resource only in connection with the development of applications that include the TI product(s) identified in such TI Resource. NO OTHER LICENSE, EXPRESS OR IMPLIED, BY ESTOPPEL OR OTHERWISE TO ANY OTHER TI INTELLECTUAL PROPERTY RIGHT, AND NO LICENSE TO ANY TECHNOLOGY OR INTELLECTUAL PROPERTY RIGHT OF TI OR ANY THIRD PARTY IS GRANTED HEREIN, including but not limited to any patent right, copyright, mask work right, or other intellectual property right relating to any combination, machine, or process in which TI products or services are used. Information regarding or referencing third-party products or services does not constitute a license to use such products or services, or a warranty or endorsement thereof. Use of TI Resources may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

TI RESOURCES ARE PROVIDED "AS IS" AND WITH ALL FAULTS. TI DISCLAIMS ALL OTHER WARRANTIES OR REPRESENTATIONS, EXPRESS OR IMPLIED, REGARDING RESOURCES OR USE THEREOF, INCLUDING BUT NOT LIMITED TO ACCURACY OR COMPLETENESS, TITLE, ANY EPIDEMIC FAILURE WARRANTY AND ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE, AND NON-INFRINGEMENT OF ANY THIRD PARTY INTELLECTUAL PROPERTY RIGHTS. TI SHALL NOT BE LIABLE FOR AND SHALL NOT DEFEND OR INDEMNIFY DESIGNER AGAINST ANY CLAIM, INCLUDING BUT NOT LIMITED TO ANY INFRINGEMENT CLAIM THAT RELATES TO OR IS BASED ON ANY COMBINATION OF PRODUCTS EVEN IF DESCRIBED IN TI RESOURCES OR OTHERWISE. IN NO EVENT SHALL TI BE LIABLE FOR ANY ACTUAL, DIRECT, SPECIAL, COLLATERAL, INDIRECT, PUNITIVE, INCIDENTAL, CONSEQUENTIAL OR EXEMPLARY DAMAGES IN CONNECTION WITH OR ARISING OUT OF TI RESOURCES OR USE THEREOF, AND REGARDLESS OF WHETHER TI HAS BEEN ADVISED OF THE POSSIBILITY OF SUCH DAMAGES.

Unless TI has explicitly designated an individual product as meeting the requirements of a particular industry standard (e.g., ISO/TS 16949 and ISO 26262), TI is not responsible for any failure to meet such industry standard requirements.

Where TI specifically promotes products as facilitating functional safety or as compliant with industry functional safety standards, such products are intended to help enable customers to design and create their own applications that meet applicable functional safety standards and requirements. Using products in an application does not by itself establish any safety features in the application. Designers must ensure compliance with safety-related requirements and standards applicable to their applications. Designer may not use any TI products in life-critical medical equipment unless authorized officers of the parties have executed a special contract specifically governing such use. Life-critical medical equipment is medical equipment where failure of such equipment would cause serious bodily injury or death (e.g., life support, pacemakers, defibrillators, heart pumps, neurostimulators, and implantables). Such equipment includes, without limitation, all medical devices identified by the U.S. Food and Drug Administration as Class III devices and equivalent classifications outside the U.S.

TI may expressly designate certain products as completing a particular qualification (e.g., Q100, Military Grade, or Enhanced Product). Designers agree that it has the necessary expertise to select the product with the appropriate qualification designation for their applications and that proper product selection is at Designers' own risk. Designers are solely responsible for compliance with all legal and regulatory requirements in connection with such selection.

Designer will fully indemnify TI and its representatives against any damages, costs, losses, and/or liabilities arising out of Designer's non-compliance with the terms and provisions of this Notice.