















Software

LP8556

ZHCSD61L - JULY 2012 - REVISED MAY 2019

# 适用于平板电脑的 LP8556 高效 LED 背光驱动器

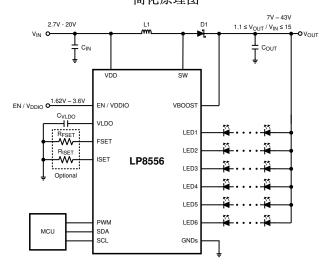
# 特性

- 高效直流/直流升压转换器,具有集成式 0.19Ω 功 率 MOSFET 和三个开关频率选项: 312kHz、 625kHz 和 1250kHz
- 2.7V 至 36V 升压开关输入电压范围支持多节锂离 子电池
  - (2.7V 至 20V V<sub>DD</sub> 输入范围)
- 7V 至 43V 升压开关输出电压范围可支持低至 3 个、高至 12 个每通道串联 WLED
- 可配置通道数(1至6个)
- 每通道高达 50mA
- PWM 和/或 I<sup>2</sup>C 亮度控制
- 相移 PWM 模式降低了可闻噪声
- 自适应调光,可获得更高的 LED 驱动光学效率
- 可编程边沿速率控制和扩频方案可最大限度减少开 关噪声并提升 EMI 性能
- LED 故障(短路和开路)检测、UVLO、TSD、 OCP和OVP(多达6个阈值选项)
- 采用小型 20 引脚、0.4mm 间距 DSBGA 封装和 24 引脚、0.5mm 间距 WQFN 封装

# 2 应用

用于平板电脑 LCD 的 LED 背光

# 简化原理图



### 3 说明

LP8556 器件是具有异步升压转换器和可由 PWM 信号 或 I<sup>2</sup>C 主器件控制的六路高精度电流阱的白色 LED 驱 动器。

升压转换器采用自适应输出电压控制,可为 LED 驱动 器在 7V 至 43V 之间设置最佳电压。这一特性可将输 出电压调整为满足所有条件的最低级别,从而最大限度 地减少功耗。转换器可以在三个开关频率下工 作: 312kHz、625kHz 和 1250kHz, 开关频率可以使

用外部电阻器进行设置或通过 EPROM 进行预配置。 可编程转换率控制和扩展频谱方案最大限度地减小了开 关噪声并提高了 EMI 性能。

PWM 调光分辨率高达 15 位,可用于设定 LED 灌 流。专有自适应调光模式,能够更大程度地节省系统能 耗。此外,相移 LED PWM 调光功能减小了可闻噪声 并且允许采用更小的升压输出电容。

LP8556 器件还具有完整的故障保护 特性, 确保器件 和外部组件可靠运行。其中包括输入欠压锁定 (UVLO)、热关断 (TSD)、过流保护 (OCP)、最高 6 级 过压保护 (OVP)、LED 开路和短路检测。

LP8556 的工作环境温度范围为 -30°C 至 +85°C。它 采用节省空间的 20 引脚 DSBGA 封装和 24 散热垫 WQFN 封装。

器件信息(1)

器件型号	封装	封装尺寸				
I DOFFE	DSBGA (20)	2.401mm x 1.74mm(最大 值)				
LP8556	WQFN (24)	4.00mm x 4.00mm(标称 值)				

(1) 如需了解所有可用封装,请参阅数据表末尾的可订购产品附 录。



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• A	dded content in VBOOST_RANGE description of Co	FG9E		Page
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• C	added content in VBOOST_RANGE description of Content of	on I Q rows, E09, I		Page 3
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# Changes from Revision E (August 2013) to Revision G

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•	Changed Description of "1=" for OCP row in Fault table, STATUS Register Section	34
•	Changed A7h values for E02, E03, E04, E06, E07, E09, E11 DSGBA EPROM Bit Explanations tables	36
•	Deleted E00, E01, E08, E10, E12, E13 columns and A8H row from 3 EPROM Bit Explanations table	36
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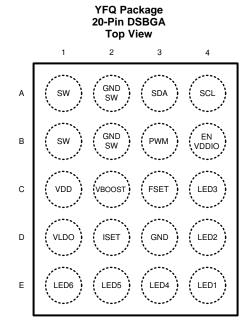
# 5 Device Options

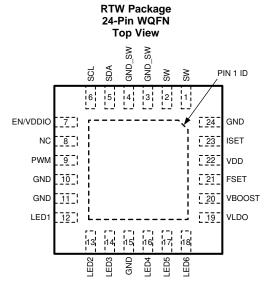
ORDERABLE DEVICE <sup>(1)</sup>	PACKAGE TYPE	DEVICE OPTION	LED CHANNEL COUNT	MAXIMUM LED CURRENT	BOOST OUTPUT VOLTAGE RANGE
LP8556SQ-E00/NOPB LP8556SQE-E00/NOPB LP8556SQX-E00/NOPB			5		
LP8556SQ-E08/NOPB LP8556SQE-E08/NOPB LP8556SQX-E08/NOPB	WQFN	"PWM Only" – Recommended for systems without an I <sup>2</sup> C master.	4	23 mA	16 V to 34.5 V
LP8556SQ-E09/NOPB LP8556SQE-E09/NOPB LP8556SQX-E09/NOPB			6		
LP8556TME-E02/NOPB LP8556TMX-E02/NOPB		"PWM and I <sup>2</sup> C" - Recommended for systems with an I <sup>2</sup> C master.	6	25 mA	16 V to 30 V
LP8556TME-E03/NOPB LP8556TMX-E03/NOPB		"PWM Only" – Recommended for	5	20 mA	16 V to 34.5 V
LP8556TME-E04/NOPB LP8556TMX-E04/NOPB		systems without an I <sup>2</sup> C master.	6	20 mA	16 V to 25 V
LP8556TME-E05/NOPB LP8556TMX-E05/NOPB	DSBGA	"Non-programmed" – This option is for evaluation purposes only.	Can be programmed to any available.	25 mA	Can be programmed to any available.
LP8556TME-E06/NOPB LP8556TMX-E06/NOPB			5	25 mA	16 V to 39 V
LP8556TME-E07/NOPB LP8556TMX-E07/NOPB		"PWM Only" – Recommended for systems without an I <sup>2</sup> C master.	4	20 mA	12.88 V to 30 V
LP8556TME-E09/NOPB LP8556TMX-E09/NOPB			6	23 mA	16 V to 34.5 V
LP8556TME-E11/NOPB LP8556TMX-E11/NOPB		"PWM and I <sup>2</sup> C" - Recommended for systems with an I <sup>2</sup> C master.	3	23 mA	7 V to 21 V

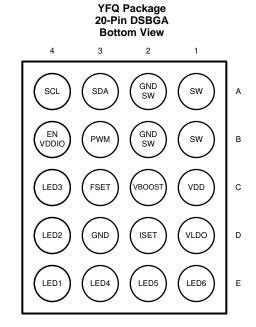
<sup>(1)</sup> For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI website at www.ti.com.

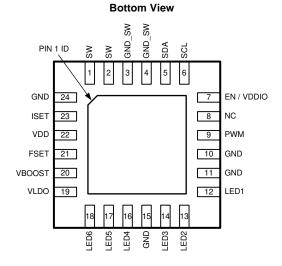


# 6 Pin Configuration and Functions









RTW Package

24-Pin WQFN



# **Pin Functions**

	PIN		(1)	
DSBGA	WQFN	NAME	TYPE <sup>(1)</sup>	DESCRIPTION
A1, B1	1, 2	SW	А	A connection to the drain terminal of the integrated power MOSFET.
A2, B2	3, 4	GND_SW	G	A connection to the source terminal of the integrated power MOSFET.
A3	5	SDA	I/O	I <sup>2</sup> C data input/output pin
A4	6	SCL	I	I <sup>2</sup> C clock input pin
В3	9	PWM	I	PWM dimming input. Supply a 75-Hz to 25-kHz PWM signal to control dimming. This pin must be connected to GND if unused.
B4	7	EN / VDDIO	Р	Dual-purpose pin serving both as a chip enable and as a power supply reference for PWM, SDA, and SCL inputs. Drive this pin with a logic gate capable of sourcing a minimum of 1 mA.
C1	22	VDD	Р	Device power supply pin. Provide 2.7-V to 20-V supply to this pin. This pin is an input of the internal LDO regulator. The output of the internal LDO is what powers the device.
C2	20	VBOOST	А	Boost converter output pin. The internal feedback (FB) and overvoltage protection (OVP) circuitry monitors the voltage on this pin. Connect the converter output capacitor bank close to this pin.
С3	21	FSET	A	A connection for setting the boost frequency and PWM output dimming frequency by using an external resistor. Connect a resistor, $R_{\text{FSET}}$ , between this pin and the ground reference (see Table 5). This pin may be left floating if PWM_FSET_EN = 0 AND BOOST_FSET_EN = 0 (see Table 10).
C4	14	LED3	А	LED driver - current sink terminal. If unused, it may be left floating.
D1	19	VLDO	Р	Internal LDO output pin. Connect a capacitor, $C_{VLDO}$ , between this pin and the ground reference.
D2	23	ISET	А	A connection for the LED current set resistor. Connect a resistor, R <sub>ISET</sub> , between this pin and the ground reference. This pin may be left floating if ISET_EN = 0 (see Table 10).
D3	10, 11, 15, 24, DAP	GND	I	Ground pin.
D4	13	LED2	А	LED driver - current sink pin. If unused, it may be left floating.
E1	18	LED6	Α	LED driver - current sink pin. If unused, it may be left floating.
E2	17	LED5	Α	LED driver - current sink pin. If unused, it may be left floating.
E3	16	LED4	Α	LED driver - current sink pin. If unused, it may be left floating.
E4	12	LED1	Α	LED driver - current sink pin. If unused, it may be left floating.
_	8	NC	_	No Connect pin.

<sup>(1)</sup> A: Analog Pin, G: Ground Pin, P: Power Pin, I: Digital Input Pin, I/O: Digital Input/Output Pin



# 7 Specifications

# 7.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted) (1)(2)

	MIN	MAX	UNIT
$V_{DD}$	-0.3	24	
Voltage on Logic Pins (SCL, SDA, PWM)	-0.3	6	
Voltage on Analog Pins (VLDO, EN / VDDIO)	-0.3	6	V
Voltage on Analog Pins (FSET, ISET)	-0.3	VLDO + 0.3	
V (LED1LED6, SW, VBOOST)	-0.3	50	
Junction Temperature (T <sub>J-MAX</sub> ) <sup>(3)</sup>		125	°C
Maximum Lead Temperature (Soldering)		260	°C
Storage temperature, T <sub>stg</sub>	-65	150	°C

- (1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability, see the Electrical Characteristics tables.
- (2) If Military/Aerospace specified devices are required, contact the Texas Instruments Sales Office/ Distributors for availability and specifications.
- (3) In applications where high power dissipation and/or poor package thermal resistance is present, the maximum ambient temperature may have to be de-rated. Maximum ambient temperature (T<sub>A-MAX</sub>) is dependent on the maximum operating junction temperature (T<sub>J-MAX-OP</sub> = 125°C), the maximum power dissipation of the device in the application (P<sub>D-MAX</sub>), and the junction-to ambient thermal resistance of the part/package in the application (R<sub>θJA</sub>), as given by the following equation: T<sub>A-MAX</sub> = T<sub>J-MAX-OP</sub> (R<sub>θJA</sub> × P<sub>D-MAX</sub>).

# 7.2 ESD Ratings

			VALUE	UNIT
		Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001, DSBGA Package <sup>(1)</sup>	±2000	
$V_{(ESD)}$	Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001, WQFN Package <sup>(1)</sup>	±1000	V
		Charged-device model (CDM), per JEDEC specification JESD22-C101 (2)	±500	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

## 7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)(1)

	MIN	MAX	UNIT
VDD	2.7	20	V
EN / VDDIO	1.62	3.6	V
V (LED1LED6, SW, VBOOST)	0	48	V
Junction temperature, T <sub>J</sub>	-30	125	°C
Ambient temperature, T <sub>A</sub>	-30	85	°C

(1) All voltages are with respect to the potential at the GND pins.



## 7.4 Thermal Information

		LP8	3556	
	THERMAL METRIC <sup>(1)</sup>	YFQ (DSBGA)	RTW (WQFN)	UNIT
		20 PINS	24 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	66.2	35.0	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	0.5	32.2	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	15.1	13.7	°C/W
ΨЈТ	Junction-to-top characterization parameter	1.9	0.3	°C/W
ΨЈВ	Junction-to-board characterization parameter	15.0	13.8	°C/W
$R_{\theta JC(bot)}$	Junction-to-case (bottom) thermal resistance	n/a	3.3	°C/W

<sup>(1)</sup> For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report (SPRA953).

# 7.5 Electrical Characteristics

Unless otherwise specified: VDD = 12 V, EN / VDDIO = 1.8 V,  $T_A$  = 25°C  $^{(1)(2)}$ 

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT	
$V_{DDIO}$	Supply voltage for digital I/Os		1.62		3.6	V	
$V_{DD}$	Input voltage for the internal LDO		2.7		20	V	
	Standby supply current	EN / VDDIO = 0 V, LDO disabled, $-30^{\circ}$ C $\leq$ T <sub>A</sub> $\leq$ 85 $^{\circ}$ C			1.6	μΑ	
I <sub>DD</sub>	Normal mode supply current	LDO enabled, boost disabled		0.9	1.5	A	
		LDO enabled, boost enabled, no load		2.2	3.65	mA	
	Internal oscillator frequency accuracy		-4%		4%		
tosc		-30°C ≤ T <sub>A</sub> ≤ 85°C	-7%		7%		
	LDO soutest scalle as	V <sub>DD</sub> ≥ 3.1 V	2.95	3.05	3.15		
$V_{LDO}$	LDO output voltage	2.7 V ≤ V <sub>DD</sub> < 3.1 V		V <sub>DD</sub> – 0.05		V	
T <sub>TSD</sub>	Thermal shutdown threshold	See <sup>(3)</sup>		150		°C	
T <sub>TSD_hyst</sub>	Thermal shutdown hysteresis	See		20		°C	

<sup>(1)</sup> All voltages are with respect to the potential at the GND pins.

<sup>(2)</sup> Minimum (MIN) and Maximum (MAX) limits are verified by design, test, or statistical analysis. Typical numbers are for information only.

<sup>3)</sup> Verified by design and not tested in production.



## 7.6 Electrical Characteristics — Boost Converter

over operating free-air temperature range (unless otherwise noted)(1)

	PARAMETER	TEST CON	IDITIONS	MIN	TYP	MAX	UNIT
R <sub>DS_ON</sub>	Switch ON resistance	I <sub>SW</sub> = 0.5A			0.19		Ω
V <sub>BOOST_MIN</sub>	Boost minimum output voltage	VBOOST_RANGE = 0 VBOOST_RANGE = 1			7 16		V
		VBOOST_MAX = 100, \ VBOOST_MAX = 101, \ VBOOST_MAX = 110, \ VBOOST_MAX = 111, \	/BOOST_RANGE = 0 /BOOST_RANGE = 0	19 24.0 28.0 32	21 25 30 34	22 27 32 37	V
V <sub>BOOST_MAX</sub>	Boost maximum output voltage	VBOOST_MAX = 010, VBOOST_MAX = 011, VBOOST_MAX = 100, VBOOST_MAX = 101, VBOOST_MAX = 111, VBOOST_MAX =	/BOOST_RANGE = 1 /BOOST_RANGE = 1 /BOOST_RANGE = 1 /BOOST_RANGE = 1	17.9 22.8 27.8 32.7 37.2 41.8	21 25 30 34.5 39 43	23.1 27.2 31.5 36.6 40.8 44.2	V
		V <sub>IN</sub> = 3 V, V <sub>OUT</sub> = 18 V			220		
I <sub>LOAD_MAX</sub>	Maximum continuous output load current	V <sub>IN</sub> = 3 V, V <sub>OUT</sub> = 24 V			160		mA
_	load current	V <sub>IN</sub> = 3 V, V <sub>OUT</sub> = 30 V			120	7 16 21 22 25 27 30 32 34 37 21 23.1 25 27.2 30 31.5 4.5 36.6 39 40.8 43 44.2 20 60 m 20 15 12 112 112 112 112 115 10 116 1.16 1.16 1.16 1.16 1.16 1.16 1.	
	(2)	f <sub>SW</sub> = 625 kHz				15	
$V_{OUT}/V_{IN}$	Conversion ratio (2)	f <sub>SW</sub> = 1250 kHz				12	
$f_{\sf SW}$	Switching frequency	BOOST_FREQ = 00 BOOST_FREQ = 01 BOOST_FREQ = 10		312 625 1250		kHz	
V <sub>OVP</sub>	Overvoltage protection voltage	VBOOST_RANGE = 1		V	<sub>BOOST</sub> + 1.6		V
	\/ undervolte as le skout	UVLO_EN = 1					
$V_{UVLO}$	V <sub>IN</sub> undervoltage lockout threshold	UVLO_TH = 0, falling UVLO_TH = 1, falling			2.5 5.2		V
\/	\/ hystoresis	BOOST_FREQ = 01   625   1250		m)/			
$V_{UVLO\_hyst}$	V <sub>UVLO</sub> hysteresis		UVLO_TH = 1		100		mV
t <sub>PULSE</sub>	Switch minimum pulse width	No load			50		ns
tSTARTUP	Start-up time	See <sup>(3)</sup>			8		ms
I <sub>SW_LIM</sub>	SW pin current limit <sup>(4)</sup>	IBOOST_LIM_2X = 0	IBOOST_LIM = 00 IBOOST_LIM = 01 IBOOST_LIM = 10 IBOOST_LIM = 11	0.66 0.88 1.12 1.35	0.9 1.2 1.5 1.8	1.40 1.73	Α
OW_LIM		IBOOST_LIM_2X = 1	IBOOST_LIM = 00 IBOOST_LIM = 01 IBOOST_LIM = 10		1.6 2.1 2.6		Α
$\Delta V_{SW}$ / $t_{ m off\_on}$	SW pin slew rate during OFF to ON transition	EN DDV/2 0 AND EN DDV/2 0			3.7 5.3 7.5		V/ns
$\Delta V_{SW}$ / $t_{ m on\_off}$	SW pin slew rate during ON to OFF transition	EN_DRV3 = 0 AND EN EN_DRV3 = 0 AND EN EN_DRV3 = 1 AND EN	_DRV2 = 1		1.9 4.4 4.8		V/ns
Δt <sub>ON</sub> / t <sub>SW</sub>	Peak-to-peak switch ON time deviation to SW period ratio (spread spectrum feature)	SSCLK_EN = 1			1%		

Minimum (MIN) and Maximum (MAX) limits are verified by design, test, or statistical analysis. Typical numbers are for information only.

Verified by design and not tested in production.

 <sup>(3)</sup> Start-up time is measured from the moment boost is activated until the V<sub>BOOST</sub> crosses 90% or its target value.
 (4) 1.8 A is the maximum I<sub>SW\_LIM</sub> supported with the DSBGA package. For applications requiring the I<sub>SW\_LIM</sub> to be greater than 1.8 A and up to 2.6 A, WQFN package should be considered.



#### 7.7 Electrical Characteristics — LED Driver

over operating free-air temperature range (unless otherwise noted)(1)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
I <sub>LED_LEAKAGE</sub>	Leakage current	Outputs LED1LED6, V <sub>OUT</sub> = 48 V		0.1	1	μΑ
I <sub>LED_MAX</sub>	Maximum sink current LED1LED6			50		mA
		Output current set to 23 mA	-3%	1%	3%	
I <sub>LED</sub>	LED current accuracy (2)	Output current set to 23 mA, $-30^{\circ}$ C $\leq T_A \leq 85^{\circ}$ C	-4%	1%	4%	
I <sub>MATCH</sub>	Matching	Output current set to 23 mA		0.5%		
		100 Hz < f <sub>PWM</sub> ≤ 200 Hz	0.02%		100%	
		200 Hz < f <sub>PWM</sub> ≤ 500 Hz	0.02%		100%	
		500 Hz < f <sub>PWM</sub> ≤ 1 kHz	0.02%		100%	
		1 kHz < f <sub>PWM</sub> ≤ 2 kHz	0.04%		100%	
PWM <sub>DUTY</sub>	LED PWM output pulse duty cycle <sup>(3)</sup>	2 kHz < f <sub>PWM</sub> ≤ 5 kHz	0.1%		100%	
	Cycle	5 kHz < f <sub>PWM</sub> ≤ 10 kHz	0.2%		100%	
		10 kHz < f <sub>PWM</sub> ≤ 20 kHz	0.4%		100%	
	20 kHz < f <sub>PWM</sub> ≤ 30 kHz	0.6%		100%		
		30 kHz < f <sub>PWM</sub> ≤ 39 kHz	0.8%		100%	
f <sub>LED</sub>	PWM output frequency	PWM_FREQ = 1111		38.5		kHz
V <sub>SAT</sub>	Saturation voltage (4)	Output current set to 23 mA		200		mV

- (1) Minimum (MIN) and Maximum (MAX) limits are specified by design, test, or statistical analysis. Typical numbers are not verified, but do represent the most likely norm.
- (2) Output Current Accuracy is the difference between the actual value of the output current and programmed value of this current. Matching is the maximum difference from the average. For the constant current sinks on the part (OUT1 to OUT6), the following are determined: the maximum output current (MAX), the minimum output current (MIN), and the average output current of all outputs (AVG). Two matching numbers are calculated: (MAX-AVG)/AVG and (AVG-MIN/AVG). The largest number of the two (worst case) is considered the matching figure. The typical specification provided is the most likely norm of the matching figure for all parts. Note that some manufacturers have different definitions in use.
- (3) Verified by design and not tested in production.
- (4) Saturation voltage is defined as the voltage when the LED current has dropped 10% from the value measured at 1 V.

# 7.8 Electrical Characteristics — PWM Interface<sup>(1)</sup>

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
f <sub>PWM</sub>	PWM frequency range (2)		75		25 000	Hz
t <sub>MIN_ON</sub>	Minimum pulse ON time			1		
t <sub>MIN_OFF</sub>	Minimum pulse OFF time			1		μS
t <sub>STARTUP</sub>	Turnon delay from standby to backlight on	PWM input active, VDDIO pin transitions from 0 V to 1.8 V		10		ms
t <sub>STBY</sub>	Turnoff delay	PWM input low time for turnoff		50		ms
PWM <sub>RES</sub>	PWM input resolution	f <sub>IN</sub> < 9 kHz		10		bits

- (1) Minimum (MIN) and Maximum (MAX) limits are specified by design, test, or statistical analysis. Typical numbers are for information only.
- (2) Verified by design and not tested in production.



# 7.9 Electrical Characteristics — Logic Interface (1)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
LOGIC INPUTS (PWM, SDA, SCL)						
$V_{IL}$	Input low level	$-30$ °C $\leq$ T <sub>A</sub> $\leq$ 85°C			0.3 × VDDIO	V
V <sub>IH</sub>	Input high level	$-30$ °C $\leq$ T <sub>A</sub> $\leq$ 85°C	0.7 × VDDIO			V
l <sub>l</sub>	Input current	$(V_{DDIO} = 0 \text{ V or } 3.6 \text{ V}), (V_I = 0 \text{ V or } 3.6 \text{ V}), -30^{\circ}\text{C} \le T_A \le 85^{\circ}\text{C}$	-1		1	μΑ
LOG	IC OUTPUTS (SDA)					
		I <sub>OUT</sub> = 3 mA (pull-up current)		0.3		
$V_{OL}$	Output low level	$I_{OUT} = 3$ mA (pull-up current), -30°C $\leq T_A \leq 85$ °C		0.3	0.4	V
IL	Output leakage current	V <sub>OUT</sub> = 5 V, −30°C ≤ T <sub>A</sub> ≤ 85°C	-1		1	μΑ

<sup>(1)</sup> Minimum (MIN) and Maximum (MAX) limits are specified by design, test, or statistical analysis. Typical numbers are for information only.

# 7.10 I<sup>2</sup>C Serial Bus Timing Parameters (SDA, SCL)<sup>(1)</sup>

		MIN	MAX	UNIT
$f_{SCL}$	Clock frequency		400	kHz
1	Hold time (repeated) START condition	0.6		μs
2	Clock low time	1.3		μs
3	Clock high time	600		ns
4	Setup time for a repeated START condition	600		ns
5	Data hold time	50		ns
6	Data set-up time	100		ns
7	Rise time of SDA and SCL	20 + 0.1C <sub>b</sub>	300	ns
8	Fall time of SDA and SCL	15 + 0.1C <sub>b</sub>	300	ns
9	Setup time for STOP condition	600		ns
10	Bus-free time between a STOP and a START condition	1.3		μs
C <sub>b</sub>	Capacitive load parameter for each bus line load of 1 pF corresponds to 1 ns.	10	200	ns

(1) Verified by design and not tested in production.

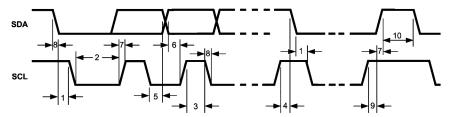
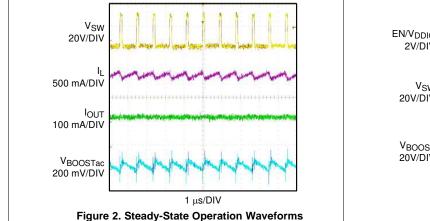


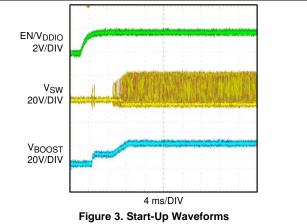
Figure 1. I<sup>2</sup>C-Compatible Timing



# 7.11 Typical Characteristics

Unless otherwise specified:  $V_{IN} = 3.8 \text{ V}$ ,  $C_{VLDO} = 10 \text{ }\mu\text{F}$ ,  $L1 = 4.7 \text{ }\mu\text{H}$ ,  $C_{IN} = 2.2 \text{ }\mu\text{F}$ ,  $C_{OUT} = 4.7 \text{ }\mu\text{F}$ ,  $f_{SW} = 1.25 \text{ MHz}$ .







# 8 Detailed Description

#### 8.1 Overview

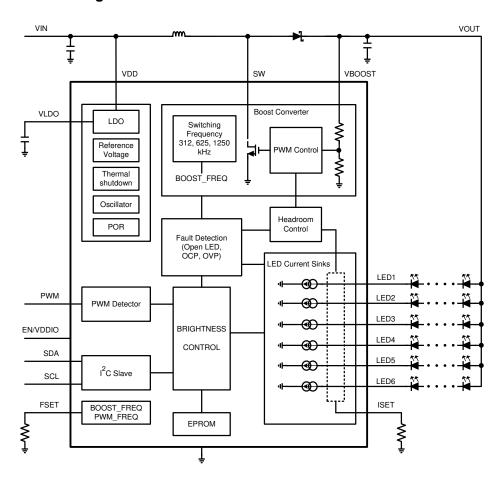
LP8556 is a white LED driver featuring an asynchronous boost converter and six high-precision current sinks that can be controlled by a PWM signal or an I<sup>2</sup>C master.

The boost converter uses adaptive output voltage control for setting the optimal LED driver voltages as high as 43 V. This feature minimizes the power consumption by adjusting the voltage to the lowest sufficient level under all conditions. The converter can operate at three switching frequencies: 312, 625, and 1250 kHz pre-configured via EPROM or can be set through an external resistor. Programmable slew rate control and spread spectrum scheme minimize switching noise and improve EMI performance.

LED current sinks can be set with the PWM dimming resolution of up to 15 bits. Proprietary adaptive dimming mode allows higher system power saving. In addition, phase shifted LED PWM dimming allows reduced audible noise and smaller boost output capacitors.

The LP8556 device has a full set of safety features that ensure robust operation of the device and external components. The set consists of input undervoltage lockout, thermal shutdown, overcurrent protection, up to six levels of overvoltage protection, LED open, and short detection.

## 8.2 Functional Block Diagram





### 8.3 Feature Description

#### 8.3.1 Boost Converter

#### 8.3.1.1 Boost Converter Operation

The LP8556 boost DC-DC converter generates a 7-V to approximately 43-V of boost output voltage from a 2.7-V to 36-V boost input voltage. The boost output voltage minimum, maximum value and range can be set digitally by pre-configuring EPROM memory (VBOOST\_RANGE, VBOOST\_and VBOOST\_MAX fields).

The converter is a magnetic switching PWM mode DC-DC boost converter with a current limit. It uses CPM (current programmed mode) control, where the inductor current is measured and controlled with the feedback. During start-up, the soft-start function reduces the peak inductor current. The LP8556 has an internal 20-MHz oscillator which is used for clocking the boost. Figure 4 shows the boost block diagram.

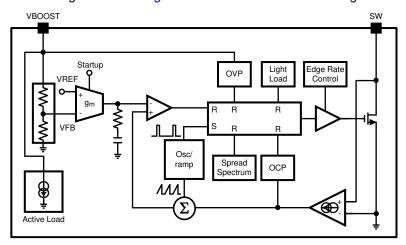


Figure 4. LP8556 Boost Converter Block Diagram

### 8.3.1.2 Setting Boost Switching Frequency

The LP8556 boost converter switching frequency can be set either by an external resistor (BOOST\_FSET\_EN = 1 selection),  $R_{FSET}$ , or by pre-configuring EPROM memory with the choice of boost frequency (BOOST\_FREQ field). Table 1 summarizes setting of the switching frequency. Note that the  $R_{FSET}$  is shared for setting the PWM dimming frequency in addition to setting the boost switching frequency. Setting the boost switching frequency and PWM dimming frequency using an external resistor is separately shown in Table 5.

Table 1. Configuring Bo	oost Switching Frequency via	EPROM
-------------------------	------------------------------	-------

R <sub>FSET</sub> [Ω]	BOOST_FSET_EN	BOOST_FREQ[1:0]	$f_{SW}\left[kHz\right]$
don't care	0	00	312
don't care	0	01	625
don't care	0	10	1250
don't care	0	11	undefined
See (1)	1	don't care	See <sup>(1)</sup>

(1) See Table 5.



### 8.3.1.3 Output Voltage Control

The LP8556 device supports two modes of controlling the boost output voltage: Adaptive Boost Voltage Control (see *Adaptive Control*) and Manual Boost Output Control (see *Manual Control*).

### 8.3.1.3.1 Adaptive Control

LP8556 supports a mode of output voltage control called Adaptive Boost Control mode. In this mode, the voltage at the LED pins is periodically monitored by the control loop and adaptively adjusted to the optimum value based on the comparator thresholds set using LED DRIVER\_HEADROOM, LED\_COMP\_HYST, BOOST\_STEP\_UP, BOOST\_STEP\_DOWN fields in the EPROM. Settings under LED DRIVER\_HEADROOM along with LED\_COMP\_HYST fields determine optimum boost voltage for a given condition. Boost voltage is raised if the voltage measured at any of the LED strings falls below the threshold setting determined with LED DRIVER\_HEADROOM field. Likewise, boost voltage is lowered if the voltage measured at any of the LED strings is above the combined setting determined under LED DRIVER\_HEADROOM and LED\_COMP\_HYST fields. LED\_COMP\_HYST fields serves to fine tune the headroom voltage for a given peak LED current. The boost voltage up/down step size can be controlled with the BOOST\_STEP\_UP and BOOST\_STEP\_DN fields.

The initial boost voltage is configured with the VBOOST field. This field also sets the minimum boost voltage. The VBOOST\_MAX field sets the maximum boost voltage. When an LED pin is open, the monitored voltage never has enough headroom, and the adaptive mode control loop keeps raising the boost voltage. The VBOOST\_MAX field allows the boost voltage to be limited to stay under the voltage rating of the external components.

#### **NOTE**

Only LED strings that are enabled are monitored and PS\_MODE field determines which LED strings are enabled.

The adaptive mode is selected using ADAPTIVE bit set to 1 (CFGA EPROM Register) and is the recommended mode of boost control.

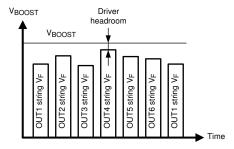


Figure 5. Boost Adaptive Control Principle

#### 8.3.1.3.2 Manual Control

User can control the boost output voltage with the VBOOST EPROM field when adaptive mode is not used. Equation 1 shows the relationship between the boost output voltage and the VBOOST field.

$$V_{BOOST} = V_{BOOST\_MIN} + 0.42 \times VBOOST[dec]$$
 (1)

The expression is only valid when the calculated values are between the minimum boost output voltage and the maximum boost output voltage. The minimum boost output voltage is set with the VBOOST\_RANGE field. The maximum boost output voltage is set with the VBOOST\_MAX EPROM field.



#### 8.3.1.4 EMI Reduction

The LP8556 device features two EMI reduction schemes.

The first scheme, Programmable Slew Rate Control, uses a combination of three drivers for boost switch. Enabling all three drivers allows boost switch on/off transition times to be the shortest. On the other hand, enabling just one driver allows boost switch on/off transition times to be the longest. The longer the transition times, the lower the switching noise on the SW pin. Note that the shortest transition times bring the best efficiency as the switching losses are the lowest.

EN\_DRV2 and EN\_DRV3 bits in the EPROM determine the boost switch driver configuration. Refer to the SW pin slew rate parameter listed under *Electrical Characteristics* — *Boost Converter* for the slew rate options.

The second EMI reduction scheme is the spread spectrum. This scheme deliberately spreads the frequency content of the boost switching waveform, which inherently has a narrow bandwidth, makes the bandwidth of the switching waveform wider, and ultimately reduces its EMI spectral density.

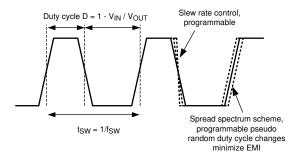


Figure 6. Principles of EMI Reduction Scheme

### 8.3.2 Brightness Control

LP8556 enables various methods of brightness control. The brightness can be controlled using an external PWM signal or the Brightness register accessible by users via an  $I^2$ C interface or both. How these two input sources are selected and combined is set by the BRT\_MODE EPROM bits and described in  $BRT_MODE = 00$  through  $BRT_MODE = 11$ , Figure 7, and Table 2. The LP8556 can also be preconfigured via EPROM memory to allow direct and unaltered brightness control by an external PWM signal. This mode of operation is obtained by setting PWM\_DIRECT EPROM bit to 1 (CFG5[7] = 1).

#### 8.3.2.1 BRT MODE = 00

With BRT\_MODE = 00, the LED output is controlled by the PWM input duty cycle. The PWM detector block measures the duty cycle at the PWM pin and uses this 16-bit value to generate an internal to the device PWM data. Before the output is generated, the PWM data goes through the PWM curve-shaper block. Then, the data goes into the adaptive dimming function which determines the range of the PWM and Current control as described in *Output Dimming Schemes*. The outcome of the adaptive dimming function is 12-bit current and/or up to 6 PWM output signals. The current is then passed through the non-linear compensation block while the output PWM signals are channeled through the dither block.

### 8.3.2.2 BRT MODE = 01

With BRT\_MODE = 01, the PWM output is controlled by the PWM input duty cycle and the Brightness register. The PWM detector block measures the duty cycle at the PWM pin and uses this 16-bit value to generate the PWM data. Before the output is generated, the PWM data is first multiplied with BRT[7:0] register, then it goes through the PWM Curve Shaper block. Then, the data goes into the Adaptive Dimming function which determines the range of the PWM and Current control as described in *Output Dimming Schemes*. The outcome of the Adaptive Dimming function is 12-bit current and/or up to 6 PWM output signals. The current is then passed through the non-linear compensation block while the output PWM signals are channeled through the Dither block.



### 8.3.2.3 $BRT_MODE = 10$

With BRT\_MODE = 10, the PWM output is controlled only by the Brightness register. From BRT[7:0] register, the data goes through the PWM Curve Shaper block. Then, the data goes into the Adaptive Dimming function which determines the range of the PWM and Current control as described in *Output Dimming Schemes*. The outcome of the Adaptive Dimming function is 12-bit Current and / or up to 6 PWM output signals. The current is then passed through the non-linear compensation block while the output PWM signals are channeled through the Dither block.

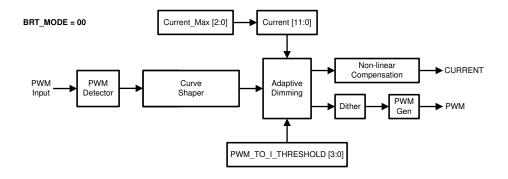
## 8.3.2.4 BRT\_MODE = 11

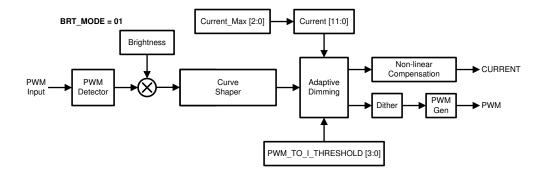
With BRT\_MODE = 11, the PWM control signal path is similar to the path when BRT\_MODE = 01 except that the PWM input signal is multiplied with BRT[7:0] data after the Curve-Shaper block.

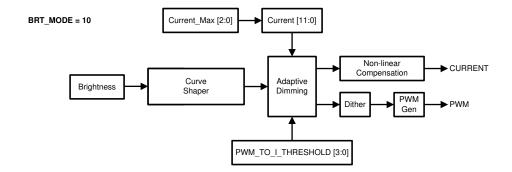
**Table 2. Brightness Control Methods Truth Table** 

PWM_DIRECT	BRT_MODE [1:0]	BRIGHTNESS CONTROL SOURCE	OUTPUT ILED FORM
0	00	External PWM signal	
0	01	External PWM signal and Brightness Register (multiplied before Curve Shaper)	Adaptive. See <i>Output</i>
0	10	Brightness Register	Dimming Schemes
0	11	External PWM signal and Brightness Register (multiplied after Curve Shaper)	
1	don't care	External PWM signal	Same as the external PWM input









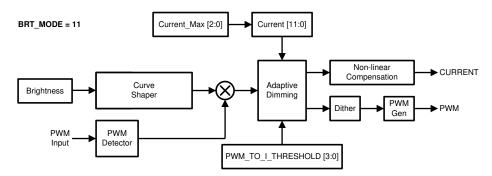


Figure 7. Brightness Control Signal Path Block Diagrams



### 8.3.2.5 Output Dimming Schemes

The LP8556 device supports three types of output dimming control methods: PWM Control, Pure Current Control and Adaptive Dimming (Hybrid PWM and Current) Control.

#### 8.3.2.5.1 PWM Control

PWM control is the traditional way of controlling the brightness using PWM of the outputs with the same LED current across the entire brightness range. Brightness control is achieved by varying the duty cycle proportional to the input PWM. PWM frequency is set either using an external set fesistor (R<sub>FSET</sub>) or using the PWM\_FREQ EPROM field. The maximum LED current is set by using an external set Resistor (R<sub>ISET</sub>), CURRENT, and CURRENT\_MAX EPROM bits. PWM frequency can also be set by simply using the CURRENT and CURRENT MAX EPROM bits.

#### NOTE

The output PWM signal is de-coupled and generated independent of the input PWM signal eliminating display flicker issues and allowing better noise immunity.

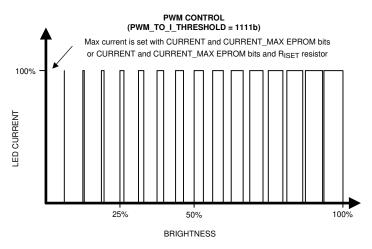


Figure 8. PWM Only Output Dimming Scheme

### 8.3.2.5.2 Pure Current Control

In Pure Current Control mode, brightness control is achieved by changing the LED current proportionately from maximum value to a minimum value across the entire brightness range. Like in PWM Control mode, the maximum LED current is set by using an external set Resistor (R<sub>ISET</sub>), CURRENT, and CURRENT\_MAX EPROM bits. The maximum LED current can also be set by just using the CURRENT and CURRENT\_MAX EPROM bits. Current resolution in this mode is 12 bits.

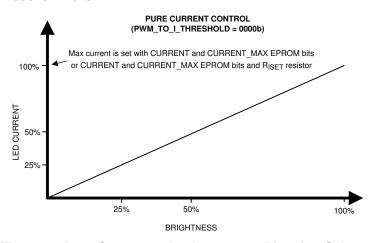


Figure 9. Pure Current or Analog Output Dimming Scheme



### 8.3.2.5.3 Adaptive Control

Adaptive dimming control combines PWM Control and Pure Current Control dimming methods. With the adaptive dimming, it is possible to achieve better optical efficiency from the LEDs compared to pure PWM control while still achieving smooth and accurate control at low brightness levels. Current resolution in this mode is 12 bits. Switch point from Current to PWM control can be set with the PWM\_TO\_I\_THRESHOLD EPROM field from 0% to 100% of the brightness range to get good compromise between good matching of the LEDs brightness/white point at low brightness and good optical efficiency.

PWM frequency is set either using an external set Resistor ( $R_{FSET}$ ) or using the PWM\_FREQ EPROM bits. The maximum LED current is set either by using an external set Resistor ( $R_{ISET}$ ), CURRENT, and CURRENT\_MAX EPROM bits. Or the maximum LED current may be set using the CURRENT and CURRENT\_MAX EPROM bits.

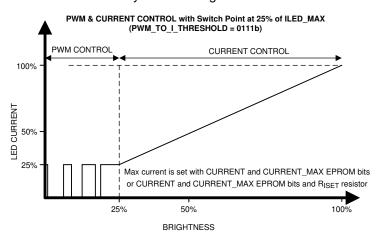


Figure 10. Adaptive Output Dimming Scheme

### 8.3.2.6 Setting Full-Scale LED Current

The maximum or full-scale LED current is set either using an external set Resistor (R<sub>ISET</sub>), CURRENT, and CURRENT\_MAX EPROM bits or just by using the CURRENT and CURRENT\_MAX EPROM bits. Table 3 summarizes setting of the full-scale LED current.

Tubic of Setting Fun Setting Les Surfeix				
R <sub>ISET</sub> [Ω]	ISET_EN	CURRENT_MAX	CURRENT[11:0]	FULL-SCALE ILED [mA]
don't care	0	000	FFFh	5
don't care	0	001	FFFh	10
don't care	0	010	FFFh	15
don't care	0	011	FFFh	20
don't care	0	100	FFFh	23
don't care	0	101	FFFh	25
don't care	0	110	FFFh	30
don't care	0	111	FFFh	50
don't care	0	000 - 111	001h - FFFh	See <sup>(1)</sup>
24k	1	000	FFFh	5
24k	1	001	FFFh	10
24k	1	010	FFFh	15
24k	1	011	FFFh	20
24k	1	100	FFFh	23
24k	1	101	FFFh	25

**FFFh** 

**FFFh** 

001h - FFFh

110

111

000 - 111

Table 3. Setting Full-Scale LED Current

24k

24k

12k - 100k

1

1

50 See<sup>(1)</sup>

<sup>(1)</sup> See CFG0.



# 8.3.2.7 Setting PWM Dimming Frequency

LP8556 PWM dimming frequency can be set by an external resistor,  $R_{\text{FSET}}$ , or by pre-configuring EPROM Memory (CFG5 register, PWM\_FREQ[3:0] bits). Table 4 summarizes setting of the PWM dimming frequency. Note that .

## **NOTE**

The  $R_{\text{FSET}}$  is shared for setting the boost switching frequency, too. Setting the boost switching frequency and PWM dimming frequency using an external resistor is shown in Table 5.

Table 4. Configuring PWM Dimming Frequency via EPROM

R <sub>FSET</sub> [kΩ]	PWM_FSET_EN	PWM_FREQ[3:0]	f <sub>PWM</sub> [Hz] (Resolution)
		0000	4808 (11-bit)
		0001	6010 (10-bit)
		0010	7212 (10-bit)
		0011	8414 (10-bit)
		0100	9616 (10-bit)
		0101	12020 (9-bit)
		0110 132	13222 (9-bit)
don't care	0	0111	14424 (9-bit)
dont care	0	1000	15626 (9-bit)
		1001	16828 (9-bit)
		1010	18030 (9-bit)
		1011	19232 ((9-bit)
		1100	24040 (8-bit)
		1101	28848 (8-bit)
		1110	33656 (8-bit)
		1111	38464 (8-bit)
See <sup>(1)</sup>	1	don't care	See <sup>(1)</sup>

<sup>(1)</sup> See Table 5.



Table 5. Setting Switching and PWM Dimming Frequency With an External Resistor

R <sub>FSET</sub> [Ω] (Tolerance)	$f_{SW}\left[kHz\right]$	f <sub>PWM</sub> [Hz] (Resolution)
Floating or FSET pin pulled HIGH	1250	9616 (10-bit)
470k - 1M (±5%)	312	2402 (12-bit)
300k, 330k (±5%)	312	4808 (11-bit)
200k (±5%)	312	6010 (10-bit)
147k, 150k, 154k, 158k (±1%)	312	9616 (10-bit)
121k (±1%)	312	12020 (9-bit)
100k (±1%)	312	14424 (9-bit)
86.6k (±1%)	312	16828 (9-bit)
75.0k (±1%)	312	19232 (9-bit)
63.4k (±1%)	625	2402 (12-bit)
52.3k, 53.6k (±1%)	625	4808 (11-bit)
44.2k, 45.3k (±1%)	625	6010 (10-bit)
39.2k (±1%)	625	9616 (10-bit)
34.0k (±1%)	625	12020 (9-bit)
30.1k (±1%)	625	14424 (9-bit)
26.1k (±1%)	625	16828 (9-bit)
23.2k (±1%)	625	19232 (9-bit)
20.5k (±1%)	1250	2402 (12-bit)
18.7k (±1%)	1250	4808 (11-bit)
16.5k (±1%)	1250	6010 (10-bit)
14.7k (±1%)	1250	9616 (10-bit)
13.0k (±1%)	1250	12020 (9-bit)
11.8k (±1%)	1250	14424 (9-bit)
10.7k (±1%)	1250	16828 (9-bit)
9.76k (±1%)	1250	19232 (9-bit)
FSET pin shorted to GND	1250	Same as PWM input



#### 8.3.2.8 Phase Shift PWM Scheme

Phase shift PWM scheme allows delaying the time when each LED driver is active. When the LED drivers are not activated simultaneously, the peak load current from the boost output is greatly decreased. This reduces the ripple seen on the boost output and allows smaller output capacitors. Reduced ripple also reduces the output ceramic capacitor audible ringing. PSPWM scheme also increases the load frequency seen on the boost output six times and therefore transfers the possible audible noise to the frequencies outside of the audible range.

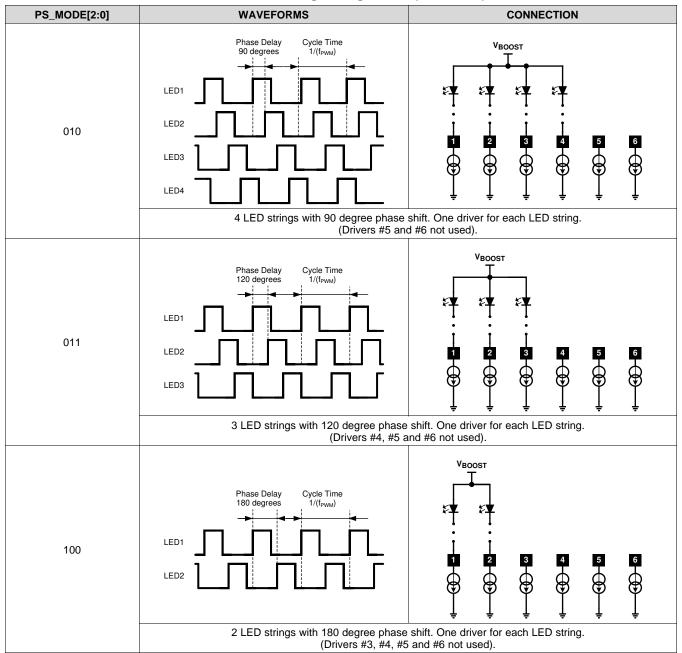
Description of the PSPWM mode is seen inTable 6. PSPWM mode is set with <PS MODE[2:0]> bits.

PS\_MODE[2:0] **WAVEFORMS** CONNECTION Phase Delay Cycle Time 60 degrees  $1/(f_{PWM})$ **V**BOOST LED1 LED2 000 LED3 LED4 LED5 LED6 6 LED strings with 60 degree phase shift. One driver for each LED string. Phase Delay Cycle Time 72 degrees  $1/(f_{PWM})$ **VBOOST** LED1 LED2 001 LED3 LED4 LED5 5 LED strings with 72 degree phase shift. One driver for each LED string. (Driver #6 not used).

**Table 6. LED String Configuration** 

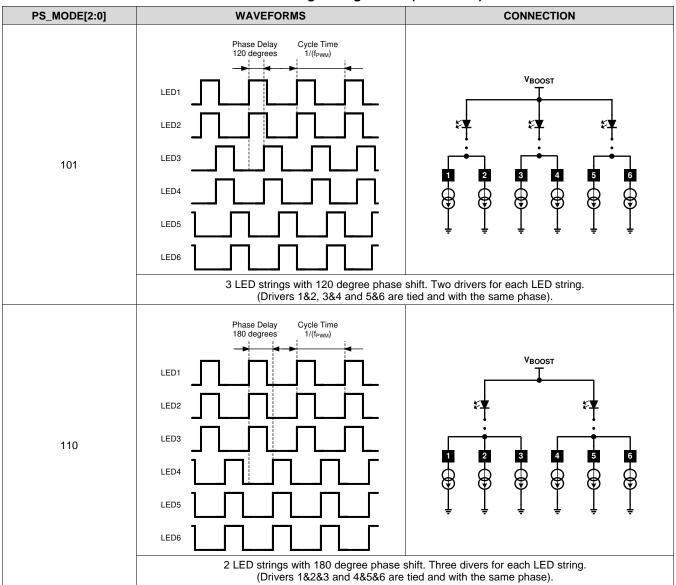


# **Table 6. LED String Configuration (continued)**



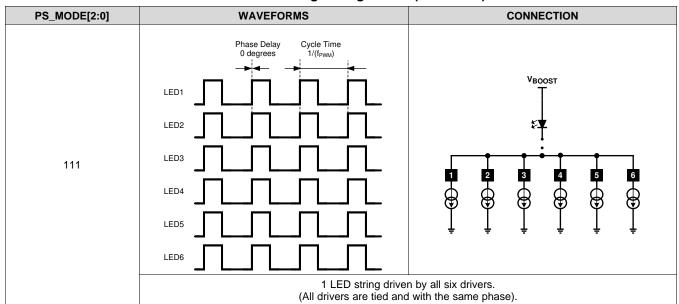


# **Table 6. LED String Configuration (continued)**





# **Table 6. LED String Configuration (continued)**





## 8.3.2.9 Slope and Advanced Slope

Transition time between two brightness values can be programmed with EPROM bits <PWM\_SLOPE[2:0]> from 0 to 500 ms. Same slope time is used for sloping up and down. With advanced slope the brightness changes can be made more pleasing to a human eye.

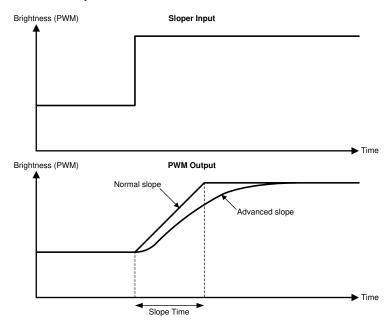


Figure 11. Sloper Operation

### 8.3.2.10 Dithering

Special dithering scheme can be used during brightness changes and in steady state condition. It allows increased resolution and smaller average steps size during brightness changes. Dithering can be programmed with EPROM bits <DITHER[1:0]> from 0 to 3 bits. <STEADY\_DITHER> EPROM bit sets whether the dithering is used also in steady state or only during slopes. Example below is for 1-bit dithering. For 3-bit dithering, every 8th pulse is made 1 LSB longer to increase the average value by 1/8th.

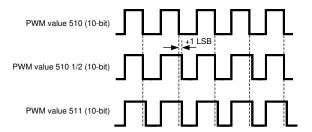


Figure 12. Example of the Dithering, 1-bit Dither, 10-bit Resolution



#### 8.3.3 Fault Detection

LP8556 has fault detection for LED open and short conditions, UVLO, overcurrent, and thermal shutdown. The cause for the fault can be read from status register. Reading the fault register also resets the fault.

#### 8.3.3.1 LED Fault Detection

With LED fault detection, the voltages across the LED drivers are constantly monitored. Shorted or open LED strings are detected.

### 8.3.3.1.1 Open Detect

The logic uses the LOW comparators and the requested boost voltage to detect the OPEN condition. If the logic is asking the boost for the maximum allowed voltage and a LOW comparator is asserted, then the OPEN bit is set in the STATUS register (ADDR = 02h). In normal operation, the adaptive headroom control loop raises the requested boost voltage when the LOW comparator is asserted. If it has raised it as high as it can and an LED string still needs more voltage, then it is assumed to be disconnected from the boost voltage (open or grounded). The actual boost voltage is not part of the OPEN condition decision; only the requested boost voltage and the LOW comparators.

#### 8.3.3.1.2 Short Detect

The logic uses all three comparators (HIGH, MID and LOW) to detect the SHORT condition. When the MID and LOW comparators are de-asserted, the headroom control loop considers that string to be optimized - enough headroom, but not excessive. If at least one LED string is optimized and at least one other LED string has its HIGH comparator asserted, then the SHORT condition is detected. It is important to note that the SHORT condition requires at least two strings for detection: one in the optimized headroom zone (LOW/MID/HIGH comparators all de-asserted) and one in the excessive headroom zone (HIGH comparator asserted).

Fault is cleared by reading the fault register.

### 8.3.3.2 Undervoltage Detection

The LP8556 device has detection for too-low  $V_{IN}$  voltage. Threshold level for the voltage is set with EPROM register bits as shown in Table 7.

	UVLO_EN	UVLO_TH	THRESHOLD (V)
	0	don't care	OFF
	1	0	2.5
	1	1	5.2

Table 7. UVLO Truth Table

When undervoltage is detected the LED outputs and the boost shuts down, and the corresponding fault bit is set in the fault register. The LEDs and the boost start again when the voltage has increased above the threshold level. Hysteresis is implemented to threshold level to avoid continuous triggering of fault when threshold is reached.

Fault is cleared by setting the EN / VDDIO pin low or by reading the fault register.

#### 8.3.3.3 Overcurrent Protection

LP8556 has detection for too-high loading on the boost converter. When overcurrent fault is detected, the boost shuts down and the corresponding fault bit is set in the fault register. The boost starts again when the current has dropped below the OCP threshold.

Fault is cleared by reading the fault register.

# 8.3.3.4 Thermal Shutdown

If the LP8556 reaches thermal shutdown temperature (150°C) the LED outputs and boost shut down to protect it from damage. The device re-activates when temperature drops below 130°C.

Fault is cleared by reading the fault register.

#### 8.4 Device Functional Modes

#### 8.4.1 Shutdown Mode

The device is in shutdown mode when the EN/VDDIO input is low. Current consumption in this mode from VDD pin is < 1.6 μA.

#### 8.4.2 Active Mode

In active mode the backlight is enabled either with setting the ON register bit high (BRTMODE = 0 1, 10, 11) or by activating PWM input (BRTMODE=00). The powers supplying the VDD and EN/VDDIO pins must be present. Brightness is controlled with I<sup>2</sup>C writes to brightness registers or by changing PWM input duty cycle (operation without I<sup>2</sup>C control). Configuration registers are not accessible in Active mode to prevent damage to the device by accidental writes. Current consumption from VDD pin this mode is typically 2.2 mA when boost is enabled and LEDs are not drawing any current.

### 8.5 Programming

### 8.5.1 I<sup>2</sup>C-Compatible Serial Bus Interface

#### 8.5.1.1 Interface Bus Overview

The I<sup>2</sup>C-compatible synchronous serial interface provides access to the programmable functions and registers on the device. This protocol uses a two-wire interface for bidirectional communications between the ICs connected to the bus. The two interface lines are the Serial Data Line (SDA) and the Serial Clock Line (SCL). These lines must be connected to a positive supply via a pull-up resistor and remain HIGH even when the bus is idle.

Every device on the bus is assigned a unique address and acts as either a Master or a Slave depending on whether it generates or receives the SCL. The LP8556 can operate as an I<sup>2</sup>C slave.

### 8.5.1.2 Data Transactions

One data bit is transferred during each clock pulse. Data is sampled during the high state of the serial clock SCL. Consequently, throughout the clock's high period, the data should remain stable. Any changes on the SDA line during the high state of the SCL and in the middle of a transaction, aborts the current transaction. New data should be sent during the low SCL state. This protocol permits a single data line to transfer both command/control information and data using the synchronous serial clock.

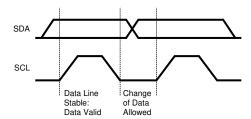


Figure 13. Bit Transfer

Each data transaction is composed of a Start Condition, a number of byte transfers (set by the software) and a Stop Condition to terminate the transaction. Every byte written to the SDA bus must be 8 bits long and is transferred with the most significant bit first. After each byte, an Acknowledge signal must follow. The following sections provide further details of this process.



# **Programming (continued)**

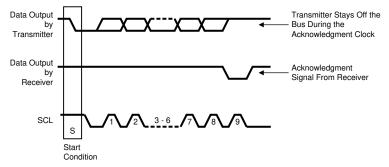


Figure 14. Start and Stop

The Master device on the bus always generates the Start and Stop Conditions (control codes). After a Start Condition is generated, the bus is considered busy and it retains this status until a certain time after a Stop Condition is generated. A high-to-low transition of the data line (SDA) while the clock (SCL) is high indicates a Start Condition. A low-to-high transition of the SDA line while the SCL is high indicates a Stop Condition.

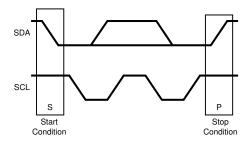


Figure 15. Start and Stop Conditions

In addition to the first Start Condition, a repeated Start Condition can be generated in the middle of a transaction. This allows another device to be accessed, or a register read cycle.

### 8.5.1.3 Acknowledge Cycle

The Acknowledge Cycle consists of two signals: the acknowledge clock pulse the master sends with each byte transferred, and the acknowledge signal sent by the receiving device.

The master generates the acknowledge clock pulse on the ninth clock pulse of the byte transfer. The transmitter releases the SDA line (permits it to go high) to allow the receiver to send the acknowledge signal. The receiver must pull down the SDA line during the acknowledge clock pulse and ensure that SDA remains low during the high period of the clock pulse, thus signaling the correct reception of the last data byte and its readiness to receive the next byte.

### 8.5.1.4 Acknowledge After Every Byte Rule

The master generates an acknowledge clock pulse after each byte transfer. The receiver sends an acknowledge signal after every byte received.

There is one exception to the *acknowledge after every byte* rule. When the master is the receiver, it must indicate to the transmitter an end of data by not-acknowledging ("negative acknowledge") the last byte clocked out of the slave. This *negative acknowledge* still includes the acknowledge clock pulse (generated by the master), but the SDA line is not pulled down.



# **Programming (continued)**

### 8.5.1.5 Addressing Transfer Formats

Each device on the bus has a unique slave address. The LP8556 operates as a slave device with 7-bit address combined with data direction bit. Slave address is 2Ch as 7-bit or 58h for write and 59h for read in 8-bit format.

Before any data is transmitted, the master transmits the slave I.D. The slave device should send an acknowledge signal on the SDA line, once it recognizes its address.

The slave address is the first seven bits after a Start Condition. The direction of the data transfer (R/W) depends on the bit sent after the slave address — the 8th bit.

When the slave address is sent, each device in the system compares this slave address with its own. If there is a match, the device considers itself addressed and sends an acknowledge signal. Depending upon the state of the R/W bit (1:read, 0:write), the device acts as a transmitter or a receiver.



Figure 16. I<sup>2</sup>C Chip Address (0x2C)

### 8.5.1.6 Control Register Write Cycle

- Master device generates start condition.
- Master device sends slave address (7 bits) and the data direction bit (r/w = 0).
- · Slave device sends acknowledge signal if the slave address is correct.
- Master sends control register address (8 bits).
- Slave sends acknowledge signal.
- Master sends data byte to be written to the addressed register.
- Slave sends acknowledge signal.
- If master sends further data bytes the control register address is incremented by one after acknowledge signal.
- Write cycle ends when the master creates stop condition.

#### 8.5.1.7 Control Register Read Cycle

- · Master device generates a start condition.
- Master device sends slave address (7 bits) and the data direction bit (r/w = 0).
- Slave device sends acknowledge signal if the slave address is correct.
- Master sends control register address (8 bits).
- · Slave sends acknowledge signal.
- · Master device generates repeated start condition.
- Master sends the slave address (7 bits) and the data direction bit (r/w = 1).
- Slave sends acknowledge signal if the slave address is correct.
- Slave sends data byte from addressed register.
- If the master device sends acknowledge signal, the control register address is incremented by one. Slave device sends data byte from addressed register.
- Read cycle ends when the master does not generate acknowledge signal after data byte and generates stop condition.



# **Programming (continued)**

Table 8. Data Read and Write Cycles

	ADDRESS MODE
Data Read	<start condition=""> <slave address=""><r w="0">[Ack] <register addr.="">[Ack] <repeated condition="" start=""> <slave address=""><r w="1">[Ack] [Register Data]<ack nack="" or=""> additional reads from subsequent register address possible <stop condition=""></stop></ack></r></slave></repeated></register></r></slave></start>
Data Write	<start condition=""> <slave address=""><r w="0">[Ack] <register addr.="">[Ack] <register data="">[Ack] additional writes to subsequent register address possible <stop condition=""></stop></register></register></r></slave></start>

<>Data from master [ ] Data from slave

## 8.5.1.8 Register Read and Write Detail

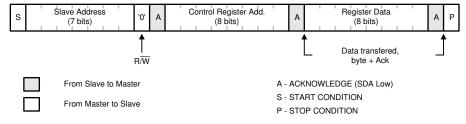


Figure 17. Register Write Format

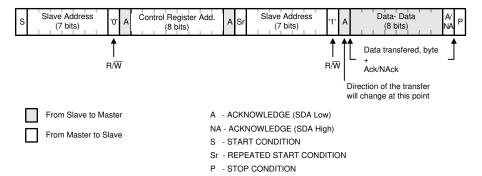


Figure 18. Register Read Format



# 8.6 Register Maps

# Table 9. Register Map

ADDR	REGISTER	D7	D6	D5	D4	D3	D2	D1	D0	RESET
00H	Brightness Control		BRT[7:0]							
01H	Device Control	FAST					BRT_MODE		BL_CTL	0000 0000
02H	Status	OPEN	SHORT	VREF_OK	VBOOST_OK	OVP	OCP	TSD	UVLO	0000 0000
04H	Direct Control			LED						0000 0000
16H	LED Enable					LE	D_EN			0011 1111

# **Table 10. EPROM Memory Map**

ADDR	REGISTER	D7	D6	D5	D4	D3	D2	D1	D0	
98H	CFG98	IBOOST_LIM_2X		RESERVED			RESERVED			
			-		RESERVED					
9EH	CFG9E	RESERVI	<u>:</u> υ	VBOOST_RANGE			HEADRO	OOM_OFFSET		
A0H	CFG0				C	URRENT LSB				
A1H	CFG1	PDET_STDBY		CURRENT_MAX			CUR	RENT MSB		
A2H	CFG2	RESERVI	D	UVLO_EN	UVLO_TH	BL_ON	ISET_EN	BOOST_FSET_EN	PWM_FSET_EN	
АЗН	CFG3	RESERVED		SLOPE		FII	TER	PWM_INPUT_	HYSTERESIS	
A4H	CFG4		PWM_TO_	PWM_TO_I_THRESHOLD			STEADY_DITHE R	DITI	HER	
A5H	CFG5	PWM_DIRECT		PS_MODE		PWM_FREQ				
A6H	CFG6	BOOST_FF	REQ				VBOOST			
A7H	CFG7	RESERVI	D	EN_DRV3	EN_DRV2	RES	ERVED	IBOOST_LIM		
A8H	CFG8	RESERVI	ED .	RESERV	ED	RESERVED		RESERVED		
A9H	CFG9		VBOOST_MA	AX	JUMP_EN	JUMP_THRESHOLD		JUMP_VOLTAGE		
AAH	CFGA	SSCLK_EN	RESERVE D	RESERV	ED	ADAPTIVE		DRIVER_HEADROOM	И	
ABH	CFGB					RESERVED				
ACH	CFGC		RES	SERVED			RE	SERVED		
ADH	CFGD		RESERVED							
AEH	CFGE	STEP_U	Р	STEP_D	LED_FAULT_TH LED_COMP_HYST		MP_HYST			
AFH	CFGF		REVISION							



# 8.6.1 Register Bit Explanations

# 8.6.1.1 Brightness Control

Address 00h

Reset value 0000 0000b

BRIGHTNESS CONTROL REGISTER										
7	6	5	4 3 2 1 0							
BRT[7:0]										
NAME	BIT	ACCESS	DESCRIPTION							
BRT	7:0	R/W	Backlight PWM 8-bit linear control.							

# 8.6.1.2 Device Control

Address 01h

Reset value 0000 0000b

DEVICE CONTR	OL REGISTE	R											
7	6	5	4	3	2	1	0						
FAST					BRT_	MODE[1:0]	BL_CTL						
NAME	BIT	ACCESS	DESCRIPTIO	N									
FAST	7		Skip refresh of trim and configuration registers from EPROMs when exiting the low power STANDBY mode.  0 = read EPROMs before returning to the ACTIVE state  1 = only read EPROMs once on initial power-up.										
BRT_MODE	2:1	2:1	2:1	2:1	2:1	:1 R/W	Brightness source mode Figure 7						
			00b = PWM input only										
			01b = PWM input and Brightness register (combined before shaper block)										
			10b = Brightness register only										
			11b = PWM input and Brightness register (combined after shaper block)										
BL_CTL	0	R/W	Enable backlight when Brightness Register is used to control brightness (BRT_MODE = 10).										
			0 = Backlight disabled and chip turned off 1 = Backlight enabled and chip turned on										
			This bit has no effect when PWM pin control is selected for brightness control (BRT_MODE = 00). In this mode the state of PWM pin enable or disables the chip.										



# 8.6.1.3 Status

Address 02h

Reset value 0000 0000b

FAULT REGIST	ER									
7	6	5	4	3	2	1	0			
OPEN	SHORT	VREF_OK	VBOOST_OK	OVP	OCP	TSD	UVLO			
NAME	BIT	ACCESS	DESCRIPTION							
OPEN	7	R	LED open fault detect	ion						
			0 = No fault							
			1 = LED open fault de	etected. The value is	s not latched.					
SHORT	6	R	LED short fault detect	ion						
			0 = No fault							
			1 = LED short fault de	etected. The value is	s not latched.					
VREF_OK	5	R	Internal VREF node n	nonitor status						
			1 = VREF voltage is OK.							
VBOOST_OK	4	R	Boost output voltage monitor status							
			0 = Boost output voltage has not reached its target (VBOOST < Vtarget – 2.5V)							
			1 = Boost output voltage is OK. The value is not latched.							
OVP	3	R	Overvoltage protection							
			0 = No fault							
			1 = Overvoltage condition occurred. Fault is cleared by reading the register 02h.							
OCP	2	R	Over current protection							
			0 = No fault							
			1 = Overcurrent condition occurred. Fault bit is cleared by reading this register.							
TSD	1	R	Thermal shutdown							
			0 = No fault							
			1 = Thermal fault gen disabled until the tem this register.							
UVLO	0	R	Undervoltage detection							
			0 = No fault							
			1 = Undervoltage dete disabled until V <sub>DD</sub> vol- set with EPROM bits.	tage is above the U	VLO threshold v	oltage. Thresho				

# 8.6.1.4 Direct Control

Address 04h

Reset value 0000 0000b

DIRECT CONTROL REGISTER										
7	6	5	4	3	2	1	0			
		OUT[5:0]								
NAME	BIT	ACCESS	DESCRIPTION							
OUT	5:0	R/W	Direct control of t	he LED outputs						
			0 = Normal opera	ition. LED output	are controlled with	n the adaptive	dimming block			
			1 = LED output is	forced to 100%	PWM.					



# 8.6.1.5 LED String Enable

Address 16h

Reset value 0011 1111b

TEMP LSB REGISTER										
7	6	5	4	3	2	1	0			
		LED_EN[5:0]								
NAME	BIT	ACCESS	CCESS DESCRIPTION							
LED_EN	5:0	R/W	Bits 5:0 correspond to LED Strings 6:1 respectively. Bit value 1 = LED String Enabled Bit value 0 = LED String Disabled Note: To disable string(s), it is recommended to disable higher order string(s). For example, for 5-string configuration, disable 6th String. For 4-string configuration, disable 6th and 5th string. These bits are ANDed with the internal LED enable bits that are generated with the PS_MODE logic.							



# 8.6.2 EPROM Bit Explanations

# 8.6.2.1 LP8556TM (DSBGA) Configurations and Pre-Configured EPROM Settings

ADDRESS	LP8556-E02	LP8556-E03	LP8556-E04	LP8556-E05 <sup>(1)</sup>
98h[7]	0b	0b	0b	0b
9Eh	22h	24h	24h	22h
A0h	FFh	FFh	FFh	
A1h	5Fh	BFh	3Fh	
A2h	20h	28h	2Fh	
A3h	5Eh	5Eh	5Eh	
A4h	72h	72h	72h	
A5h	04h	14h	04h	
A6h	80h	80h	80h	
A7h	F7h	F7h	F7h	
A9h	80h	A0h	60h	
AAh	0Fh	0Fh	0Fh	
ABh	00h	00h	00h	
ACh	00h	00h	00h	
ADh	00h	00h	00h	
AEh	0Fh	0Fh	0Fh	
AFh	05h	03h	03h	

<sup>(1)</sup> LP8556-E05 is a device option with un-configured EPROM settings. This option is for users that desire programming the device by themselves. Bits 98h[7] and 9Eh[5] are always pre-configured.

# 8.6.2.2 LP8556TM (DSBGA) Configurations and Pre-configured EPROM Settings Continued

ADDRESS	LP8556-E06	LP8556-E07	LP8556-E09	LP8556-E11
98h[7]	0b	0b	0b	0b
9Eh	22h	04h	22h	02h
A0h	FFh	FFh	FFh	FFh
A1h	DBh	BFh	CFh	4Fh
A2h	2Fh	0Dh	2Fh	20h
A3h	02h	02h	02h	03h
A4h	72h	72h	72h	12h
A5h	14h	20h	04h	3Ch
A6h	40h	4Eh	80h	40h
A7h	F7h	F6h	F7h	F4h
A9h	DBh	C0h	A0h	80h
AAh	0Fh	0Fh	0Fh	0Fh
ABh	00h	00h	00h	00h
ACh	00h	00h	00h	00h
ADh	00h	00h	00h	00h
AEh	0Fh	0Fh	0Eh	0Fh
AFh	05h	03h	05h	01h



# 8.6.2.3 LP8556SQ (WQFN) Configurations and Pre-configured EPROM Settings

ADDRESS	LP8556-E00	LP8556-E08	LP8556-E09
98h[7]	1b	1b	1b
9Eh	22h	22h	22h
A0h	FFh	FFh	FFh
A1h	CFh	CFh	CFh
A2h	2Fh	2Fh	2Fh
A3h	5Eh	5Eh	02h
A4h	72h	72h	<b>7</b> 2h
A5h	14h	24h	04h
A6h	80h	80h	80h
A7h	F6h	F6h	F6h
A9h	A0h	A0h	A0h
AAh	0Fh	0Fh	0Fh
ABh	00h	00h	00h
ACh	00h	00h	00h
ADh	00h	00h	00h
AEh	0Fh	0Fh	0Fh
AFh	01h	01h	01h

### 8.6.2.4 CFG98

Address 98h

CFG98 REGISTER											
7	6	5	4	3	2	1	0				
IBOOST_LIM_2X											
NAME	BIT	ACCESS	DESCRIPTION								
IBOOST_LIM_2X	7	R/W	A. When IBOOST_LIM	$_2X = 0$ , the ind $_2X = 1$ , the ind	ge. luctor current limit car luctor current limit car QFN package and not	n be set to 1.6 A, 2	2.1 A, or 2.6 A .				

<sup>(1) 1.8</sup> A is the maximum I<sub>SW\_LIM</sub> supported with the DSBGA package. For applications requiring the I<sub>SW\_LIM</sub> to be greater than 1.8 A and up to 2.6 A, WQFN package should be considered.



# 8.6.2.5 CFG9E

Address 9Eh

CFG9E REGISTER											
7	6	5	4	3	2	1	0				
		VBOOST_RANGE	HEADROOM_OFFSET								
NAME	BIT	ACCESS	DESCRIPTION								
VBOOST_RANGE	5	R/W	Select VBOOST range. When VBOOST_RANGE = 0, the output voltage range is from 7 V to 34 V When VBOOST_RANGE = 1, the output voltage range is from 16 V to 43 V In applications with an output voltage higher than 16 V, VBOOST_RANGE = 1 is preferred.								
HEADROOM_ OFFSET	3:0	R/W	preferred.  LED driver headroom offset. This adjusts the LOW comparator threshold together with LED_HEADROOM bits and contributes to the MID comparator threshold.  0000 = 460 mV  0001 = 390 mV  0010 = 320 mV  1000 = 250 mV  1000 = 180 mV								

### 8.6.2.6 CFG0

Address A0h

CFG0 REGISTER										
7	6	5	4	3	2	1	0			
			CURRE	NT LSB[7:0]						
NAME	BIT	ACCESS		DE	SCRIPTION					
CURRENT LSB	7:0	R/W	LED current to be current set using 0, the LED current	register (LSB) along the set in 12-bit fine steps CFG1 Register, CURRI t is defined with the bits connected to the ISET p	. These 12-bits ENT_MAX bits ( s as shown belo	further scale the m (denoted as IMAX ) bw. If ISET_EN = 1	aximum LED In the state of the			
			ISET_EN = 0 ISET_EN = 1							
			0000	0000 0000	0A	0A				
			0000	0000 0001	(1/4095) × I <sub>MAX</sub>	(1/4095) × I <sub>MAX</sub> × / R <sub>IS</sub>	20,000 <b>x</b> 1.2V			
			0000	0000 0010	(2/4095) <b>x</b> I <sub>MAX</sub>	(2/4095) x I <sub>MAX</sub> × / R <sub>IS</sub>				
			0111	1111 1111	(2047/4095) × I <sub>MAX</sub>	(2047/4095) × I <sub>N</sub> 1.2V / F				
			1111	1111 1101	(4093/4095) × I <sub>MAX</sub>	(4093/4095) × I <sub>N</sub> 1.2V / F	<sub>IAX</sub> × 20,000 × R <sub>ISET</sub>			
			1111	1111 1110	(4094/4095) × I <sub>MAX</sub>	, , , , , , ,				
			1111	1111 1111	(4095/4095) × I <sub>MAX</sub>	(4095/4095) × I <sub>N</sub> 1.2V / F				



# 8.6.2.7 CFG1

Address A1h

CFG1 REGISTER										
7	6	5	4	3	2	1	0			
PDET_STDBY	C	URRENT_MAX[	2:0]		CURRENT	MSB[11:8]				
NAME	BIT	ACCESS	DESCRIPTION	١						
PDET_STDBY	7	R/W	Enable Standby when PWM input is constant low (approx. 50 ms timeout).							
CURRENT_MAX	6:4	R/W		LED current as le <i>CFG0</i> Registo	shown below. This m er.	aximum current i	s scaled as			
CURRENT MSB	3:0	R/W	These bits form	n the 4 MSB bit	s for LED Current as	described in CFC	30 Register.			

# 8.6.2.8 CFG2

Address A2h

CFG2 REGISTER									
7	6	5	4	3	2	1	0		
RESERVED		UVLO_EN	UVLO_TH	BL_ON	ISET_EN	BOOST_ _FSET_EN	PWM_ _FSET_EN		
NAME	BIT	ACCESS	DESCRIPTION	١					
RESERVED	7:6	R/W							
UVLO_EN	5	R/W	Undervoltage I	ockout protection	on enable.				
UVLO_TH	4	R/W	UVLO threshold levels: 0 = 2.5 V 1 = 5.2 V						
BL_ON	3	R/W	Enable backlight. This bit must be set for PWM only control.  0 = Backlight disabled. This selection is recommended for systems with an I <sup>2</sup> C master. With an I <sup>2</sup> C master, the backlight can be controlled by writing to the register 01h.  1 = Backlight enabled. This selection is recommended for systems with PWM only control.						
ISET_EN	2	R/W	0 = Resistor is EPROM regist 1 = Resistor is	er bits. enabled and c		the R <sub>ISET</sub> resis	d CURRENT_MAX		
BOOST_FSET_EN	1	R/W	Enable configuration of the switching frequency via FSET pin.  0 = Configuration of the switching frequency via FSET pin is is disabled. The switching frequency is set with BOOST_FREQ EPROM register bits.  1 = Configuration of the switching frequency via FSET pin is is enabled.						
PWM_FSET_EN	0	R/W	Enable configuration of the PWM dimming frequency via FSET pin.  0 = Configuration of the switching frequency via FSET pin is is disabled. The switching frequency is set with PWM_FREQ EPROM register bits.  1 = Configuration of the PWM dimming frequency via FSET pin is is enabled.						



### 8.6.2.9 CFG3

Address A3h

CFG3 REGISTER							
7	6	5	4	3	2	1	0
RESERVED		SLOPE[2:0]		FILTE	R[1:0]	PWM_INPUT_	_HYSTERESIS[1:0]
NAME	BIT	ACCESS	DESCRIPTION	N			
RESERVED	7	R/W					
SLOPE	6:4	R/W		ess change trans nmediate chang			
FILTER	3:2	R/W	Select brightness change transition filtering strength 00 = No filtering 01 = light smoothing 10 = medium smoothing 11 = heavy smoothing				
PWM_INPUT_ _HYSTERESIS	1:0	R/W	00 = OFF 01 = 1-bit hyst 10 = 1-bit hyst	steresis function eresis with 13-b eresis with 12-b eresis with 8-bit	it resolution it resolution		

# 8.6.2.10 CFG4

Address A4h

CFG4 REGISTER								
7	6	5	4	3	2	1	0	
PWM_TO	_I_THRES	SHOLD[3:0]		RESERVED STEADY_ DITHER[1:0]DITHER				
NAME	BIT	ACCESS	DESCRIPTIO	ON				
PWM_TO_I_THRESHOLD	7:4	R/W	Select switch point between PWM and pure current dimming 0000 = current dimming across entire range 0001 = switch point at 10% of the maximum LED current. 0010 = switch point at 12.5% of the maximum LED current. 0011 = switch point at 15% of the maximum LED current. 0100 = switch point at 17.5% of the maximum LED current. 0101 = switch point at 20% of the maximum LED current. 0110 = switch point at 22.5% of the maximum LED current. 0111 = switch point at 25.5% of the maximum LED current. This is a recommended selection. 1000 = switch point at 33.33% of the maximum LED current. 1001 = switch point at 41.67% of the maximum LED current. 1010 = switch point at 50% of the maximum LED current. 1011 = Switch point at 50% of the maximum LED current. 1011 = PWM dimming across entire range					
RESERVED	3	R/W						
STEADY_DITHER	2	R/W	Dither function method select: 0 = Dither only on transitions 1 = Dither at all times					
DITHER	1:0	R/W	Dither function control 00 = Dithering disabled 01 = 1-bit dithering 10 = 2-bit dithering 11 = 3-bit dithering					



# 8.6.2.11 CFG5

Address A5h

CFG5 REGISTER								
7	6	5	4	3	2	1	0	
PWM_DIRECT		PS_MODE[2:0]			PWM_	_FREQ[3:0]		
NAME	BIT	ACCESS	DESCRIPTION					
PWM_DIRECT	7	R/W	Intended for certain test mode purposes. When enabled, the entire pipeline is bypassed and PWM output is connected with PWM input.					
PS_MODE	6:4	R/W	Select PWM output phase configuration:  000 = 6-phase, 6 drivers (0°, 60°, 120°, 180°, 240°, 320°)  001 = 5-phase, 5 drivers (0°, 72°, 144°, 216°, 288°, OFF)  010 = 4-phase, 4 drivers (0°, 90°, 180°, 270°, OFF, OFF)  011 = 3-phase, 3 drivers (0°, 120°, 240°, OFF, OFF, OFF)  100 = 2-phase, 2 drivers (0°, 180°, OFF, OFF, OFF, OFF)  101 = 3-phase, 6 drivers (0°, 0°, 120°, 240°, 240°, 240°)  110 = 2-phase, 6 drivers (0°, 0°, 180°, 180°, 180°)  111 = 1-phase, 6 drivers (0°, 0°, 0°, 0°, 0°, 0°)					
PWM_FREQ	3:0	R/W	0h = 4,808 Hz 1h = 6,010 Hz 2h = 7,212 Hz 3h = 8,414 Hz 4h = 9,616 Hz 5h = 12,020 H 6h = 13,222 H 7h = 14,424 H 8h = 15,626 H 9h = 16,828 H Ah = 18,030 H Bh = 19,232 H Ch = 24,040 H Dh = 28,848 H Eh = 33,656 H Fh = 38,464 H	(10-bit) (10-bit) (10-bit) (10-bit) z (9-bit) z (9-bit) z (9-bit) z (9-bit) z (9-bit) z (9-bit) z (9-bit) z (8-bit) z (8-bit) z (8-bit)				



# 8.6.2.12 CFG6

# Address A6h

CFG6 REGISTER											
7	6	5	4 3 2 1 0								
BOOST_FREQ[	BOOST_FREQ[1:0] VBOOST[5:0]										
NAME	NAME BIT ACCESS DESCRIPTION										
BOOST_FREQ	7:6	R/W	Set boost switching frequency when BOOST_FSET_EN = 0.  00 = 312 kHz 01 = 625 kHz 10 = 1250 kHz 11 = undefined								
VBOOST	5:0	R/W	Boost output voltage. When ADAPTIVE = 1, this is the boost minimum and initial voltage.								

# 8.6.2.13 CFG7

### Address A7h

CFG7 REGISTER									
7	6	5	4	3	2	1	0		
RESERVED		EN_DRV3	EN_DRV2	RESE	RVED	IBOOS	ST_LIM[1:0]		
NAME	BIT	ACCESS	DESCRIPTION	N					
RESERVED	7:6								
EN_DRV3	5	R/W	Selects boost driver strength to set boost slew rate. See <i>EMI Reduction</i> for more detail.  0 = Driver3 disabled  1 = Driver3 enabled						
EN_DRV2	4	R/W	Selects boost more detail. 0 = Driver2 dis 1 = Driver2 en		o set boost slev	v rate. See <i>EM</i>	Reduction for		
RESERVED	3:2	R/W							
IBOOST_LIM	1:0	R/W	Select boost inductor current limit (IBOOST_LIM_2X = 0 / IBOOST_LIM_2X = 1) 00 = 0.9 A / 1.6 A 01 = 1.2 A / 2.1 A 10 = 1.5 A / 2.6 A 11 = 1.8 A / not permitted						



# 8.6.2.14 CFG9

### Address A9h

CFG9 REGISTER									
7	6	5	4	3	2	1	0		
VBOO	ST_MAX[2:0]		JUMP_EN	JUMP_THRE	SHOLD[1:0]	JUMP_\	OLTAGE[1:0]		
NAME	BIT	ACCESS	DESCRIPTION						
VBOOST_MAX	7:5	R/W	Select the maximum boost voltage (typ values) ( VBOOST_RANGE = 0 / VBOOST_RANGE = 1) 010 = NA / 21 V 011 = NA / 25 V 100 = 21 V / 30 V 101 = 25 V / 34.5 V 110 = 30 V / 39 V 111 = 34 V / 43 V						
JUMP_EN	4	R/W	Enable JUMP	detection on the	e PWM input.				
JUMP_THRESHOLD	3:2	R/W	Select JUMP threshold: 00 = 10% 01 = 30% 10 = 50% 11 = 70%						
JUMP_VOLTAGE	1:0	R/W	Select JUMP voltage: 00 = 0.5 V 01 = 1 V 10 = 2 V 11 = 4 V						

### 8.6.2.15 CFGA

# Address AAh

CFGA REGISTER							
7	6	5	4	3	2	1	0
SSCLK_EN	RESERVED	RESE	RVED	ADAPTIVE DRIVER_HEADROOM[2:0]			OOM[2:0]
NAME	BIT	ACCESS	DESCRIPTIO	N			
SSCLK_EN	7	R/W	Enable sprea	d spectrum fund	ction		
RESERVED	6	R/W					
RESERVED	5:4	R/W					
ADAPTIVE	3	R/W	Enable adapt	tive boost contro	ol		
DRIVER_HEADROOM	2:0	R/W	contributes to 000 = HEADI 001 = HEADI 010 = HEADI 011 = HEADI 100 = HEADI 101 = HEADI 110 = HEADI	eadroom control the MID compa ROOM_OFFSE ROOM_OFFSE ROOM_OFFSE ROOM_OFFSE ROOM_OFFSE ROOM_OFFSE ROOM_OFFSE ROOM_OFFSE ROOM_OFFSE	arator threshol F + 875 mV F + 750 mV F + 625 mV F + 500 mV F + 375 mV F + 250 mV F + 125 mV		or threshold and



# 8.6.2.16 CFGE

# Address AEh

CFGE REGISTER									
7	6	5	4	3	2	1	0		
STEP_UP[1:0]		STEP_I	DN[1:0]	LED_FAUL	T_TH[2:0]	LED_CO	MP_HYST[1:0]		
NAME	BIT	ACCESS	DESCRIPTION	N					
STEP_UP	7:6	R/W	Adaptive headroom UP step size 00 = 105 mV 01 = 210 mV 10 = 420 mV 11 = 840 mV						
STEP_DN	5:4	R/W	Adaptive headroom DOWN step size 00 = 105 mV 01 = 210 mV 10 = 420 mV 11 = 840 mV						
LED_FAULT_TH	3:2	R/W	LED headroom fault threshold. This sets the HIGH comparator threshold.  00 = 5 V  01 = 4 V  10 = 3 V  11 = 2 V						
LED_COMP_HYST	1:0	R/W	00 = DRIVER_ 01 = DRIVER_ 10 = DRIVER_	comparison hys _HEADROOM + _HEADROOM + _HEADROOM + _HEADROOM +	- 1000 mV - 750 mV - 500 mV	ets the MID co	mparator threshold.		

# 8.6.2.17 CFGF

### Address AFh

CFGF REGISTER									
7	6	5	4	3	2	1	0		
	REVISION								
NAME	BIT	ACCESS	DESCRIPTION						
REV	7:0	R/W	EPROM Settings F	Revision ID code					



### 9 Application and Implementation

#### **NOTE**

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

#### 9.1 Application Information

### 9.1.1 Using LP8556 With I<sup>2</sup>C Host

#### 9.1.1.1 Setting Boost Switching and PWM Dimming Frequencies

Boost switching and PWM dimming frequencies can be set via EEPROM when BOOST\_FSET\_EN = 0 and PWM\_FSET\_EN = 0. Available options are shown in Table 11 and Table 12.

Table 11. Configuring Boost Switching Frequency via EPROM

BOOST_FSET_EN	BOOST_FREQ[1:0]	$f_{SW}\left[kHz\right]$
0	00	312
0	01	625
0	10	1250
0	11	Reserved

Table 12. Configuring PWM Dimming Frequency via EPROM

PWM_FSET_EN	PWM_FREQ[3:0]	f <sub>PWM</sub> [Hz] (Resolution)
0	0000	4808 (11-bit)
0	0001	6010 (10-bit)
0	0010	7212 (10-bit)
0	0011	8414 (10-bit)
0	0100	9616 (10-bit)
0	0101	12020 (9-bit)
0	0110	13222 (9-bit)
0	0111	14424 (9-bit)
0	1000	15626 (9-bit)
0	1001	16828 (9-bit)
0	1010	18030 (9-bit)
0	1011	19232 (9-bit)
0	1100	24040 (8-bit)
0	1101	28848 (8-bit)
0	1110	33656 (8-bit)
0	1111	38464 (8-bit)

#### 9.1.1.2 Setting Full-Scale LED Current

The LED current per output is configured by programming the CURRENT\_MAX and CURRENT registers when ISET\_EN = 0. Available options are shown below.



Table 13. Setting Full-Scale LED Current with EEPROM

ISET_EN	CURRENT_MAX	CURRENT[11:0]	FULL-SCALE ILED [mA]
0	0	FFFh	5
0	1	FFFh	10
0	10	FFFh	15
0	11	FFFh	20
0	100	FFFh	23
0	101	FFFh	25
0	110	FFFh	30
0	111	FFFh	50
0	000 – 111	001h – FFFh	(CURRENT/4095) × CURRENT_IMAX

## 9.1.2 Using LP8556 With Configuration Resistors and IO Pins

#### 9.1.2.1 Setting Boost Switching and PWM Dimming Frequencies

Boost switching and PWM dimming frequencies can be set via resistor when BOOST\_FSET\_EN = 1 and PWM\_FSET\_EN = 1. Available options are shown in Table 14.

Table 14. Configuring PWM Dimming Frequency With an External Resistor

RFSET [kΩ] (TOLERANCE)	$f_{SW}$ [kHz] BOOST_FSET_EN = 1	f <sub>PWM</sub> [Hz] (RESOLUTION) PWM_FSET_EN = 1
Floating or FSET pin pulled HIGH	1250	9616 (10-bit)
470 k - 1 M (±5%)	312	2402 (12-bit)
300 k, 330 k (±5%)	312	4808 (11-bit)
200 k (±5%)	312	6010 (10-bit)
147 k, 150k, 154 k, 158k (±1%)	312	9616 (10-bit)
121 k (±1%)	312	12020 (9-bit)
100 k (±1%)	312	14424 (9-bit)
86.6 k (±1%)	312	16828 (9-bit)
75 k (±1%)	312	19232 (9-bit)
63.4 k (±1%)	625	2402 (12-bit)
52.3 k, 53.6 k (±1%)	625	4808 (11-bit)
44.2k, 45.3 k (±1%)	625	6010 (10-bit)
39.2 k (±1%)	625	9616 (10-bit)
34 k (±1%)	625	12020 (9-bit)
30.1k (±1%)	625	14424 (9-bit)
26.1 k (±1%)	625	16828 (9-bit)
23.2 k (±1%)	625	19232 (9-bit)
20.5 k (±1%)	1250	2402 (12-bit)
18.7 k (±1%)	1250	4808 (11-bit)
16.5k (±1%)	1250	6010 (10-bit)
14.7 k (±1%)	1250	9616 (10-bit)
13 k (±1%)	1250	12020 (9-bit)
11.8k (±1%)	1250	14424 (9-bit)
10.7 k (±1%)	1250	16828 (9-bit)
9.76 k (±1%)	1250	19232 (9-bit)
FSET pin shorted to GND	1250	Same as PWM input frequency

(CURRENT/4095) × IMAX × 20,000 × 1.2 V / RISET



#### 9.1.2.2 Setting Full-Scale LED Current

1

The LED current per output is configured by ISET resistor when ISET\_EN=1. In this mode the CURRENT\_IMAX and CURRENT registers can also further scale the LED current. Available options are shown in Table 15.

CURRENT\_MAX ISET\_EN CURRENT[11:0] **FULL-SCALE ILED [mA]** RISET  $[\Omega]$ 24 k FFFh 24 k 1 FFFh 10 24 k 1 10 FFFh 15 24 k 1 11 FFFh 20 24 k 100 FFFh 23 24 k 101 FFFh 25 24 k 1 110 FFFh 30 24 k 111 FFFh

001h-FFFh

000-111

Table 15. Setting Full-Scale LED Current with ISET Resistor

# 9.2 Typical Application

12 k – 100 k

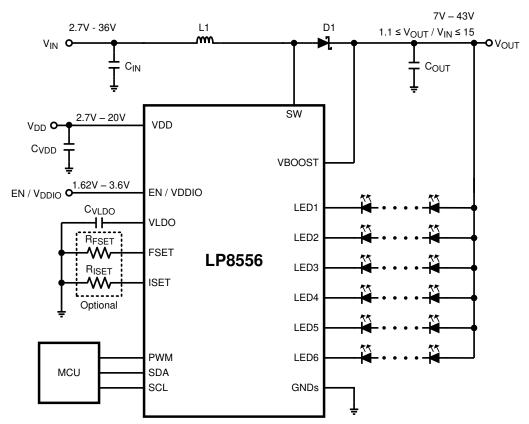


Figure 19. LP8556 Typical Application Schematic



### **Typical Application (continued)**

### 9.2.1 Design Requirements

#### **Table 16. Recommended Inductance**

$f_{SW}$	MIN	TYP MAX	UNIT
1250	3.3	22	μH
625	6.8	68	μH
312	10	100	μH

#### **Table 17. Recommended Output Capacitance**

fsw	MIN	TYP	MAX	UNIT
1250	4.7			μF
625	4.7			μF
312	10			μF

# 9.2.2 Detailed Design Procedure

#### 9.2.2.1 Recommended Inductance for the Boost Power Stage

Assumes 20 mA as the maximum LED current per string and 3.3 V as the maximum LED forward voltage.

NUMBER OF	NUMBER OF	BOOST INPUT	INPUT L1 INDUCTANCE						
LED STRINGS	LEDS PER STRING	VOLTAGE RANGE	f <sub>SW</sub> = 1250 kHz	f <sub>SW</sub> = 625 kHz	f <sub>SW</sub> = 312 kHz				
6	6	2.7 V - 4.4 V	3.3 μΗ - 6.8 μΗ	6.8 μΗ - 15 μΗ	10 μΗ - 33 μΗ				
б	6 6	5.4 V - 8.8 V	10 μΗ - 22 μΗ	22 μΗ - 47 μΗ	47 μΗ - 100 μΗ				
6	8	2.7 V - 4.4 V	4.7 μΗ - 10 μΗ	10 μΗ - 15 μΗ	22 μΗ - 33 μΗ				
б	0	5.4 V - 8.8 V	10 μΗ - 22 μΗ	22 μΗ - 68 μΗ	47 μΗ - 100 μΗ				
4	10	5.4 V - 8.8 V	6.8 μΗ - 22 μΗ	22 μΗ - 47 μΗ	47 μΗ - 100 μΗ				
4	12	5.4 V - 8.8 V	10 μΗ - 22 μΗ	22 μΗ - 47 μΗ	33 μΗ - 100 μΗ				

### 9.2.2.2 Recommended Capacitances for the Boost and LDO Power Stages (1)

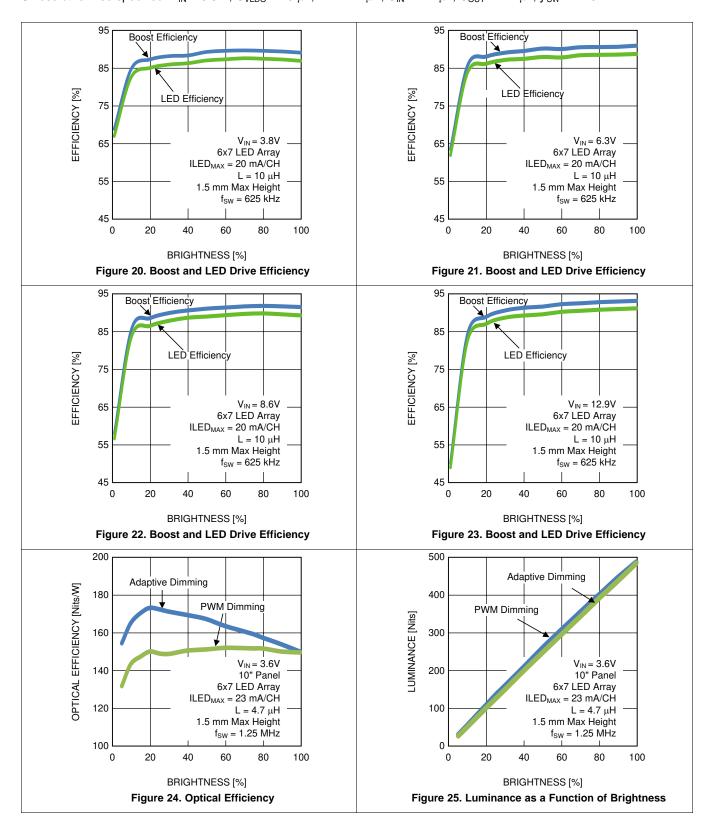
SWITCHING FREQUENCY [kHz]	C <sub>IN</sub> [μF]	C <sub>OUT</sub> [μF]	C <sub>VLDO</sub> [μF]
1250	2.2	4.7	10
625	2.2	4.7	10
312	4.7	10	10

<sup>(1)</sup> Capacitance of Multi-Layer Ceramic Capacitors (MLCC) can change significantly with the applied DC voltage. Use capacitors with good capacitance versus DC bias characteristics. In general, MLCC in bigger packages have lower capacitance de-rating than physically smaller capacitors.



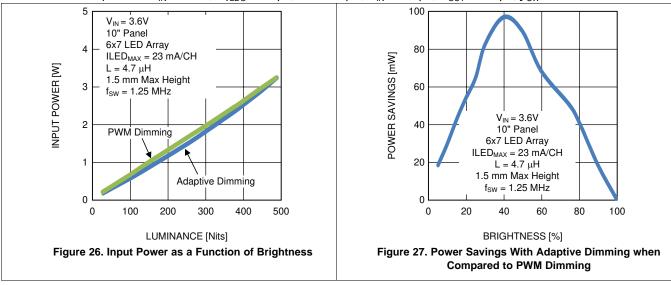
#### 9.2.3 Application Curves

Unless otherwise specified:  $V_{IN} = 3.8 \text{ V}$ ,  $C_{VLDO} = 10 \text{ }\mu\text{F}$ ,  $L1 = 4.7 \text{ }\mu\text{H}$ ,  $C_{IN} = 2.2 \text{ }\mu\text{F}$ ,  $C_{OUT} = 4.7 \text{ }\mu\text{F}$ ,  $f_{SW} = 1.25 \text{ MHz}$ 





Unless otherwise specified:  $V_{IN} = 3.8 \text{ V}, C_{VLDO} = 10 \text{ }\mu\text{F}, L1 = 4.7 \text{ }\mu\text{H}, C_{IN} = 2.2 \text{ }\mu\text{F}, C_{OUT} = 4.7 \text{ }\mu\text{F}, f_{SW} = 1.25 \text{ MHz}$ 





### 10 Power Supply Recommendations

The device is designed to operate from a VDD input voltage supply range from 2.7 V to 20 V. This input supply must be well regulated and able to withstand maximum input current and maintain stable voltage without voltage drop even at load transition condition (start-up or rapid brightness change). The resistance of the input supply rail must be low enough that the input current transient does not cause drop high enough in the LP8556 supply voltage that can cause false UVLO fault triggering.

If the input supply is located more than a few inches from the LP8556 device, additional bulk capacitance may be required in addition to the ceramic bypass capacitors. Depending on device EEPROM configuration and usage case the boost converter is configured to operate optimally with certain input voltage range.

#### 11 Layout

#### 11.1 Layout Guidelines

Figure 28 and Figure 29 follow proper layout guidelines and should be used as a guide for laying out the LP8556 circuit.

The LP8556 inductive boost converter has a high switched voltage at the SW pin, and a step current through the Schottky diode and output capacitor each switching cycle. The high switching voltage can create interference into nearby nodes due to electric field coupling ( $I = C \times dV/dt$ ). The large step current through the diode and the output capacitor can cause a large voltage spike at the SW and VBOOST pins due to parasitic inductance in the step current conducting path ( $V = L \times di/dt$ ). Board layout guidelines are geared towards minimizing this electric field coupling and conducted noise.

The following list details the main (layout sensitive) areas of the device inductive boost converter in order of decreasing importance:

#### 1. Boost Output Capacitor Placement

Because the output capacitor is in the path of the inductor current discharge path, there is a high-current step from 0 to IPEAK each time the switch turns off and the Schottky diode turns on. Any inductance along this series path from the diodes cathode, through COUT, and back into the LP8556 GND pin contributes to voltage spikes (VSPIKE = LP\_ x dl/dt) at SW and OUT. These spikes can potentially overvoltage the SW and VBOOST pins, or feed through to GND. To avoid this, COUT+ must be connected as close to the cathode of the Schottky diode as possible, and COUT- must be connected as close to the LP8556 GND bumps as possible. The best placement for COUT is on the same layer as the LP8556 to avoid any vias that can add excessive series inductance.

#### 2. Schottky Diode Placement

In the device boost circuit the Schottky diode is in the path of the inductor current discharge. As a result the Schottky diode has a high-current step from 0 to IPEAK each time the switch turns off and the diode turns on. Any inductance in series with the diode causes a voltage spike (VSPIKE = LP\_ x dl/dt) at SW and OUT. This can potentially over-voltage the SW pin, or feed through to VOUT and through the output capacitor, into GND. Connecting the anode of the diode as close to the SW pin as possible, and connecting the cathode of the diode as close to COUT+ as possible reduces the inductance (LP\_) and minimize these voltage spikes.

### 3. Boost Input/VDD Capacitor Placement

- The LP8556 input capacitor filters the inductor current ripple and the internal MOSFET driver currents. The inductor current ripple can add input voltage ripple due to any series resistance in the input power path. The MOSFET driver currents can add voltage spikes on the input due to the inductance in series with the VIN/VDD and the input capacitor. Close placement of the input capacitor to the VDD pin and to the GND pin is critical because any series inductance between VIN/VDD and CIN+ or CIN- and GND can create voltage spikes that could appear on the VIN/VDD supply line and GND.
- Close placement of the input capacitor at the input side of the inductor is also critical. The source impedance (inductance and resistance) from the input supply, along with the input capacitor of the LP8556, forms a series RLC circuit. If the output resistance from the source is low enough, the circuit is underdamped and will have a resonant frequency (typically the case).
- Depending on the size of LS, the resonant frequency could occur below, close to, or above the switching frequency of the LP8556. This can cause the supply current ripple to be:



### **Layout Guidelines (continued)**

- Approximately equal to the inductor current ripple when the resonant frequency occurs well above the LP8556 switching frequency.
- Greater than the inductor current ripple when the resonant frequency occurs near the switching frequency.
- Less than the inductor current ripple when the resonant frequency occurs well below the switching frequency.

# 11.2 Layout Examples

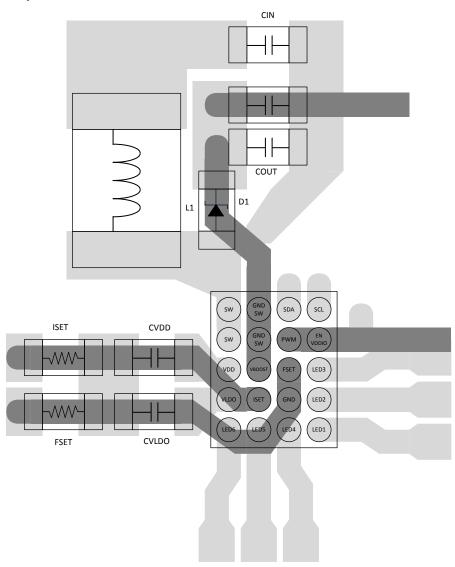


Figure 28. DSBGA Layout



# **Layout Examples (continued)**

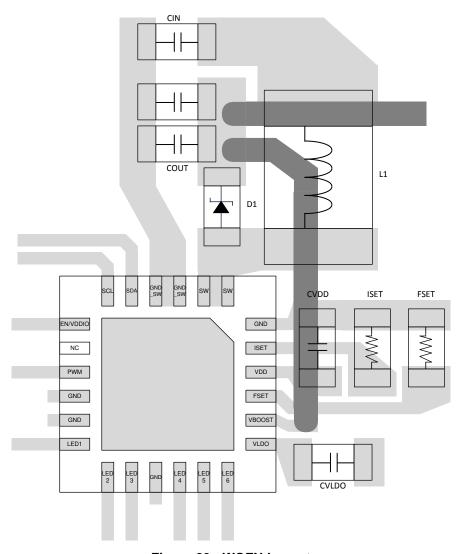


Figure 29. WQFN Layout



#### 12 器件和文档支持

#### 12.1 接收文档更新通知

要接收文档更新通知,请导航至 Tl.com.cn 上的器件产品文件夹。单击右上角的通知我进行注册,即可每周接收产品信息更改摘要。有关更改的详细信息,请查看任何已修订文档中包含的修订历史记录。

#### 12.2 社区资源

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

TI E2E™ Online Community *TI's Engineer-to-Engineer (E2E) Community.* Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

**Design Support** *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

#### 12.3 商标

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#### 12.4 静电放电警告



这些装置包含有限的内置 ESD 保护。 存储或装卸时,应将导线一起截短或将装置放置于导电泡棉中,以防止 MOS 门极遭受静电损伤。

# 12.5 Glossary

SLYZ022 — TI Glossary.

This glossary lists and explains terms, acronyms, and definitions.

### 13 机械、封装和可订购信息

以下页面包含机械、封装和可订购信息。这些信息是指定器件的最新可用数据。数据如有变更,恕不另行通知,且 不会对此文档进行修订。如需获取此数据表的浏览器版本,请查阅左侧的导航栏。





13-Dec-2020

### **PACKAGING INFORMATION**

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan	Lead finish/ Ball material	MSL Peak Temp	Op Temp (°C)	<b>Device Marking</b> (4/5)	Samples
LP8556SQ-E00/NOPB	ACTIVE	WQFN	RTW	24	1000	RoHS & Green	NIPDAU   SN	Level-1-260C-UNLIM	-30 to 85	L8556E0	Samples
LP8556SQ-E08/NOPB	ACTIVE	WQFN	RTW	24	1000	RoHS & Green	NIPDAU   SN	Level-1-260C-UNLIM	-30 to 85	L8556E8	Samples
LP8556SQ-E09/NOPB	ACTIVE	WQFN	RTW	24	1000	RoHS & Green	NIPDAU   SN	Level-1-260C-UNLIM	-30 to 85	L8556E9	Samples
LP8556SQE-E00/NOPB	ACTIVE	WQFN	RTW	24	250	RoHS & Green	NIPDAU   SN	Level-1-260C-UNLIM	-30 to 85	L8556E0	Samples
LP8556SQE-E08/NOPB	ACTIVE	WQFN	RTW	24	250	RoHS & Green	NIPDAU   SN	Level-1-260C-UNLIM	-30 to 85	L8556E8	Samples
LP8556SQE-E09/NOPB	ACTIVE	WQFN	RTW	24	250	RoHS & Green	NIPDAU   SN	Level-1-260C-UNLIM	-30 to 85	L8556E9	Samples
LP8556SQX-E00/NOPB	ACTIVE	WQFN	RTW	24	4500	RoHS & Green	NIPDAU   SN	Level-1-260C-UNLIM	-30 to 85	L8556E0	Samples
LP8556SQX-E08/NOPB	ACTIVE	WQFN	RTW	24	4500	RoHS & Green	NIPDAU   SN	Level-1-260C-UNLIM	-30 to 85	L8556E8	Samples
LP8556SQX-E09/NOPB	ACTIVE	WQFN	RTW	24	4500	RoHS & Green	NIPDAU   SN	Level-1-260C-UNLIM	-30 to 85	L8556E9	Samples
LP8556TME-E02/NOPB	ACTIVE	DSBGA	YFQ	20	250	RoHS & Green	SNAGCU	Level-1-260C-UNLIM	-30 to 85	56E2	Samples
LP8556TME-E03/NOPB	ACTIVE	DSBGA	YFQ	20	250	RoHS & Green	SNAGCU	Level-1-260C-UNLIM	-30 to 85	56E3	Samples
LP8556TME-E04/NOPB	ACTIVE	DSBGA	YFQ	20	250	RoHS & Green	SNAGCU	Level-1-260C-UNLIM	-30 to 85	56E4	Samples
LP8556TME-E05/NOPB	ACTIVE	DSBGA	YFQ	20	250	RoHS & Green	SNAGCU	Level-1-260C-UNLIM	-30 to 85	56E5	Samples
LP8556TME-E06/NOPB	ACTIVE	DSBGA	YFQ	20	250	RoHS & Green	SNAGCU	Level-1-260C-UNLIM	-30 to 85	56E6	Samples
LP8556TME-E09/NOPB	ACTIVE	DSBGA	YFQ	20	250	RoHS & Green	SNAGCU	Level-1-260C-UNLIM	-30 to 85	56E9	Samples
LP8556TME-E11/NOPB	ACTIVE	DSBGA	YFQ	20	250	RoHS & Green	SNAGCU	Level-1-260C-UNLIM	-30 to 85	6E11	Samples
LP8556TMX-E02/NOPB	ACTIVE	DSBGA	YFQ	20	3000	RoHS & Green	SNAGCU	Level-1-260C-UNLIM	-30 to 85	56E2	Samples
LP8556TMX-E03/NOPB	ACTIVE	DSBGA	YFQ	20	3000	RoHS & Green	SNAGCU	Level-1-260C-UNLIM	-30 to 85	56E3	Samples
LP8556TMX-E04/NOPB	ACTIVE	DSBGA	YFQ	20	3000	RoHS & Green	SNAGCU	Level-1-260C-UNLIM	-30 to 85	56E4	Samples
LP8556TMX-E05/NOPB	ACTIVE	DSBGA	YFQ	20	3000	RoHS & Green	SNAGCU	Level-1-260C-UNLIM	-30 to 85	56E5	Samples



# PACKAGE OPTION ADDENDUM

13-Dec-2020

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan	Lead finish/ Ball material	MSL Peak Temp	Op Temp (°C)	Device Marking (4/5)	Samples
LP8556TMX-E06/NOPB	ACTIVE	DSBGA	YFQ	20	3000	RoHS & Green	SNAGCU	Level-1-260C-UNLIM	-30 to 85	56E6	Samples
LP8556TMX-E09/NOPB	ACTIVE	DSBGA	YFQ	20	3000	RoHS & Green	SNAGCU	Level-1-260C-UNLIM	-30 to 85	56E9	Samples
LP8556TMX-E11/NOPB	ACTIVE	DSBGA	YFQ	20	3000	RoHS & Green	SNAGCU	Level-1-260C-UNLIM	-30 to 85	6E11	Samples

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green:** TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

- (3) MSL. Peak Temp. The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
- (4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
- (5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
- (6) Lead finish/Ball material Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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### TAPE AND REEL INFORMATION





A0	Dimension designed to accommodate the component width
В0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

#### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LP8556SQ-E00/NOPB	WQFN	RTW	24	1000	180.0	12.4	4.25	4.25	1.15	8.0	12.0	Q1
LP8556SQ-E00/NOPB	WQFN	RTW	24	1000	178.0	12.4	4.3	4.3	1.3	8.0	12.0	Q1
LP8556SQ-E08/NOPB	WQFN	RTW	24	1000	180.0	12.4	4.25	4.25	1.15	8.0	12.0	Q1
LP8556SQ-E08/NOPB	WQFN	RTW	24	1000	178.0	12.4	4.3	4.3	1.3	8.0	12.0	Q1
LP8556SQ-E09/NOPB	WQFN	RTW	24	1000	178.0	12.4	4.3	4.3	1.3	8.0	12.0	Q1
LP8556SQ-E09/NOPB	WQFN	RTW	24	1000	180.0	12.4	4.25	4.25	1.15	8.0	12.0	Q1
LP8556SQE-E00/NOPB	WQFN	RTW	24	250	180.0	12.4	4.25	4.25	1.15	8.0	12.0	Q1
LP8556SQE-E00/NOPB	WQFN	RTW	24	250	178.0	12.4	4.3	4.3	1.3	8.0	12.0	Q1
LP8556SQE-E08/NOPB	WQFN	RTW	24	250	180.0	12.4	4.25	4.25	1.15	8.0	12.0	Q1
LP8556SQE-E08/NOPB	WQFN	RTW	24	250	178.0	12.4	4.3	4.3	1.3	8.0	12.0	Q1
LP8556SQE-E09/NOPB	WQFN	RTW	24	250	180.0	12.4	4.25	4.25	1.15	8.0	12.0	Q1
LP8556SQE-E09/NOPB	WQFN	RTW	24	250	178.0	12.4	4.3	4.3	1.3	8.0	12.0	Q1
LP8556SQX-E00/NOPB	WQFN	RTW	24	4500	330.0	12.4	4.3	4.3	1.3	8.0	12.0	Q1
LP8556SQX-E00/NOPB	WQFN	RTW	24	4500	330.0	12.4	4.25	4.25	1.15	8.0	12.0	Q1
LP8556SQX-E08/NOPB	WQFN	RTW	24	4500	330.0	12.4	4.3	4.3	1.3	8.0	12.0	Q1
LP8556SQX-E08/NOPB	WQFN	RTW	24	4500	330.0	12.4	4.25	4.25	1.15	8.0	12.0	Q1



# PACKAGE MATERIALS INFORMATION

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Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LP8556SQX-E09/NOPB	WQFN	RTW	24	4500	330.0	12.4	4.3	4.3	1.3	8.0	12.0	Q1
LP8556SQX-E09/NOPB	WQFN	RTW	24	4500	330.0	12.4	4.25	4.25	1.15	8.0	12.0	Q1
LP8556TME-E02/NOPB	DSBGA	YFQ	20	250	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1
LP8556TME-E02/NOPB	DSBGA	YFQ	20	250	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1
LP8556TME-E03/NOPB	DSBGA	YFQ	20	250	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1
LP8556TME-E03/NOPB	DSBGA	YFQ	20	250	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1
LP8556TME-E04/NOPB	DSBGA	YFQ	20	250	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1
LP8556TME-E04/NOPB	DSBGA	YFQ	20	250	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1
LP8556TME-E05/NOPB	DSBGA	YFQ	20	250	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1
LP8556TME-E05/NOPB	DSBGA	YFQ	20	250	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1
LP8556TME-E06/NOPB	DSBGA	YFQ	20	250	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1
LP8556TME-E06/NOPB	DSBGA	YFQ	20	250	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1
LP8556TME-E09/NOPB	DSBGA	YFQ	20	250	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1
LP8556TME-E09/NOPB	DSBGA	YFQ	20	250	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1
LP8556TME-E11/NOPB	DSBGA	YFQ	20	250	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1
LP8556TME-E11/NOPB	DSBGA	YFQ	20	250	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1
LP8556TMX-E02/NOPB	DSBGA	YFQ	20	3000	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1
LP8556TMX-E02/NOPB	DSBGA	YFQ	20	3000	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1
LP8556TMX-E03/NOPB	DSBGA	YFQ	20	3000	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1
LP8556TMX-E03/NOPB	DSBGA	YFQ	20	3000	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1
LP8556TMX-E04/NOPB	DSBGA	YFQ	20	3000	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1
LP8556TMX-E04/NOPB	DSBGA	YFQ	20	3000	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1
LP8556TMX-E05/NOPB	DSBGA	YFQ	20	3000	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1
LP8556TMX-E05/NOPB	DSBGA	YFQ	20	3000	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1
LP8556TMX-E06/NOPB	DSBGA	YFQ	20	3000	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1
LP8556TMX-E06/NOPB	DSBGA	YFQ	20	3000	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1
LP8556TMX-E09/NOPB	DSBGA	YFQ	20	3000	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1
LP8556TMX-E09/NOPB	DSBGA	YFQ	20	3000	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1
LP8556TMX-E11/NOPB	DSBGA	YFQ	20	3000	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1
LP8556TMX-E11/NOPB	DSBGA	YFQ	20	3000	178.0	8.4	1.83	2.49	0.76	4.0	8.0	Q1



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\*All dimensions are nominal

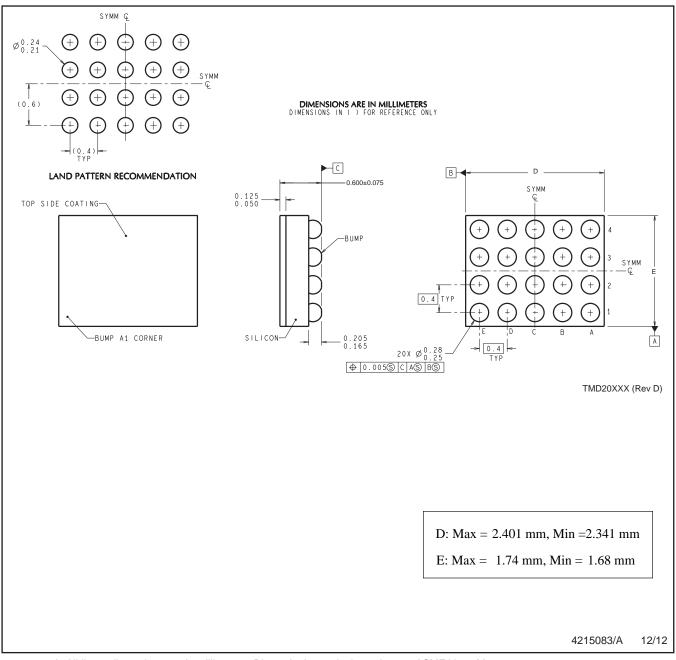
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LP8556SQ-E00/NOPB	WQFN	RTW	24	1000	210.0	185.0	35.0
LP8556SQ-E00/NOPB	WQFN	RTW	24	1000	208.0	191.0	35.0
LP8556SQ-E08/NOPB	WQFN	RTW	24	1000	210.0	185.0	35.0
LP8556SQ-E08/NOPB	WQFN	RTW	24	1000	208.0	191.0	35.0
LP8556SQ-E09/NOPB	WQFN	RTW	24	1000	208.0	191.0	35.0
LP8556SQ-E09/NOPB	WQFN	RTW	24	1000	210.0	185.0	35.0
LP8556SQE-E00/NOPB	WQFN	RTW	24	250	210.0	185.0	35.0
LP8556SQE-E00/NOPB	WQFN	RTW	24	250	208.0	191.0	35.0
LP8556SQE-E08/NOPB	WQFN	RTW	24	250	210.0	185.0	35.0
LP8556SQE-E08/NOPB	WQFN	RTW	24	250	208.0	191.0	35.0
LP8556SQE-E09/NOPB	WQFN	RTW	24	250	210.0	185.0	35.0
LP8556SQE-E09/NOPB	WQFN	RTW	24	250	208.0	191.0	35.0
LP8556SQX-E00/NOPB	WQFN	RTW	24	4500	367.0	367.0	35.0
LP8556SQX-E00/NOPB	WQFN	RTW	24	4500	367.0	367.0	35.0
LP8556SQX-E08/NOPB	WQFN	RTW	24	4500	367.0	367.0	35.0
LP8556SQX-E08/NOPB	WQFN	RTW	24	4500	367.0	367.0	35.0
LP8556SQX-E09/NOPB	WQFN	RTW	24	4500	367.0	367.0	35.0
LP8556SQX-E09/NOPB	WQFN	RTW	24	4500	367.0	367.0	35.0



# **PACKAGE MATERIALS INFORMATION**

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Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LP8556TME-E02/NOPB	DSBGA	YFQ	20	250	220.0	220.0	35.0
LP8556TME-E02/NOPB	DSBGA	YFQ	20	250	208.0	191.0	35.0
LP8556TME-E03/NOPB	DSBGA	YFQ	20	250	208.0	191.0	35.0
LP8556TME-E03/NOPB	DSBGA	YFQ	20	250	220.0	220.0	35.0
LP8556TME-E04/NOPB	DSBGA	YFQ	20	250	208.0	191.0	35.0
LP8556TME-E04/NOPB	DSBGA	YFQ	20	250	220.0	220.0	35.0
LP8556TME-E05/NOPB	DSBGA	YFQ	20	250	208.0	191.0	35.0
LP8556TME-E05/NOPB	DSBGA	YFQ	20	250	220.0	220.0	35.0
LP8556TME-E06/NOPB	DSBGA	YFQ	20	250	208.0	191.0	35.0
LP8556TME-E06/NOPB	DSBGA	YFQ	20	250	220.0	220.0	35.0
LP8556TME-E09/NOPB	DSBGA	YFQ	20	250	208.0	191.0	35.0
LP8556TME-E09/NOPB	DSBGA	YFQ	20	250	220.0	220.0	35.0
LP8556TME-E11/NOPB	DSBGA	YFQ	20	250	220.0	220.0	35.0
LP8556TME-E11/NOPB	DSBGA	YFQ	20	250	208.0	191.0	35.0
LP8556TMX-E02/NOPB	DSBGA	YFQ	20	3000	208.0	191.0	35.0
LP8556TMX-E02/NOPB	DSBGA	YFQ	20	3000	220.0	220.0	35.0
LP8556TMX-E03/NOPB	DSBGA	YFQ	20	3000	208.0	191.0	35.0
LP8556TMX-E03/NOPB	DSBGA	YFQ	20	3000	220.0	220.0	35.0
LP8556TMX-E04/NOPB	DSBGA	YFQ	20	3000	208.0	191.0	35.0
LP8556TMX-E04/NOPB	DSBGA	YFQ	20	3000	220.0	220.0	35.0
LP8556TMX-E05/NOPB	DSBGA	YFQ	20	3000	208.0	191.0	35.0
LP8556TMX-E05/NOPB	DSBGA	YFQ	20	3000	220.0	220.0	35.0
LP8556TMX-E06/NOPB	DSBGA	YFQ	20	3000	208.0	191.0	35.0
LP8556TMX-E06/NOPB	DSBGA	YFQ	20	3000	220.0	220.0	35.0
LP8556TMX-E09/NOPB	DSBGA	YFQ	20	3000	208.0	191.0	35.0
LP8556TMX-E09/NOPB	DSBGA	YFQ	20	3000	220.0	220.0	35.0
LP8556TMX-E11/NOPB	DSBGA	YFQ	20	3000	220.0	220.0	35.0
LP8556TMX-E11/NOPB	DSBGA	YFQ	20	3000	208.0	191.0	35.0



NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994. B. This drawing is subject to change without notice.



PLASTIC QUAD FLATPACK - NO LEAD

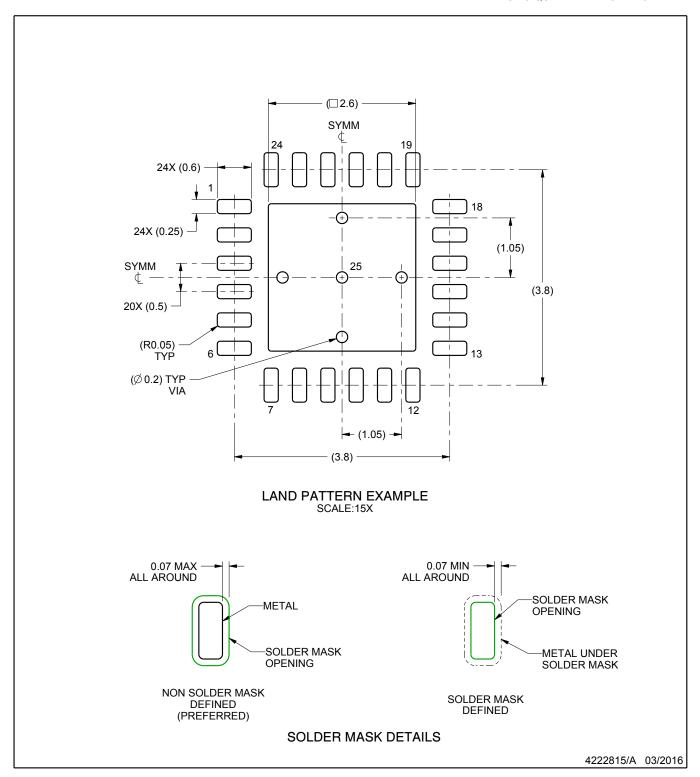


#### NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
  2. This drawing is subject to change without notice.
- 3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.



PLASTIC QUAD FLATPACK - NO LEAD



NOTES: (continued)

4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).



PLASTIC QUAD FLATPACK - NO LEAD



NOTES: (continued)

5. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



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