



16-BIT, 4-MSPS, PSEUDO-BIPOLAR, FULLY DIFFERENTIAL INPUT, MICROPOWER SAMPLING ANALOG-TO-DIGITAL CONVERTER WITH PARALLEL INTERFACE, REFERENCE

FEATURES

- Fully Differential Input with Pseudo-Bipolar Input Range -4 V to +4 V
- 16-Bit NMC at 4 MSPS
- 1 LSB INL Typ
- 92dB SNR, -102dB THD Typ with 100-kHz Input
- Internal 4.096-V Reference and Reference Buffer
- REFIN/2 Available for Setting Analog Input Common-Mode Voltage
- Zero Latency
- High-Speed Parallel Interface
- Single Supply Operation Capability
- Low Power: 155 mW at 4 MHz Typ, Flexible Power-Down Scheme
- Pin-Out Similar to ADS8412/8402
- 48-Pin 9×9 TQFP Package

APPLICATIONS

- DWDM
- Instrumentation
- High-Speed, High-Resolution, Zero Latency Data Acquisition Systems
- Transducer Interface
- Medical Instruments
- Spectrum Analysis
- ATE

DESCRIPTION

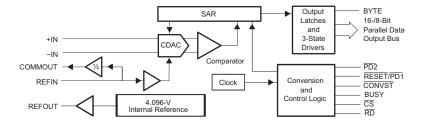
The ADS8422 is a 16-bit, 4-MHz A/D converter with an internal 4.096-V reference. The device includes a 16-bit capacitor-based multi-bit SAR A/D converter with inherent sample and hold. This converter includes a full 16-bit interface and an 8-bit option where data is read using two 8-bit read cycles if necessary.

The ADS8422 has a fully differential, pseudo-bipolar input. It is available in a 48-lead TQFP package and is characterized over the industrial -40°C to +85°C temperature range.

HIGH-SPEED SAR CONVERTER FAMILY(1)

TYPE/SPEED	500 kHz	~600 kHz	750 kHz	1 MHz	1.25 MHz	2 MHz	3 MHz	4MHz
18-Bit Pseudo-Diff	ADS8383	ADS8381		ADS8481				
10-Bit FSeudo-Dill		ADS8380 (s)						
18-Bit Pseudo-Bipolar, Fully Diff		ADS8382 (s)		ADS8482				
16-Bit Pseudo-Diff		ADS8370 (s)	ADS8371	ADS8471	ADS8401	ADS8411		
то-ык Pseudo-ыш	ADS8327/28 (s)	ADS8372 (s)		ADS8329/30 (s)	ADS8405	ADS8410 (s)		
4C Dit Decude Dineles Fully Diff				ADS8472	ADS8402	ADS8412		ADS8422
16-Bit Pseudo-Bipolar, Fully Diff					ADS8406	ADS8413 (s)		
14-Bit Pseudo-Diff					ADS7890 (s)		ADS7891	
12-Bit Pseudo-Diff				ADS7886		ADS7883		ADS7881

(1) S: Serial





Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.





These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

ORDERING INFORMATION(1)

MODEL	MAXIMUM INTEGRAL LINEARITY (LSB)	MAXIMUM DIFFERENTIAL LINEARITY (LSB)	NO MISSING CODES RESOLUTION (BIT)	PACKAGE TYPE	PACKAGE DESIGNATOR	TEMPERATURE RANGE	ORDERING INFORMATION	TRANSPORT MEDIA QTY.
ADS8422I	ADS8422I ±6 ±2	15	9×9 48-Pin	PFB	–40°C to 85°C	ADS8422IPFBT	Small tape and reel 250	
AD304221		± z	13	TQFP	FID	-40 C 10 65 C	ADS8422IPFBR	Tape and reel 1000
ADS8422IB	000400ID 10 14.5/4		16	9×9 48-Pin	PFB	–40°C to 85°C	ADS8422IBPFBT	Small tape and reel 250
AUS8422IB	±2	+1.5/-1	10	TQFP	FIFD	-40 C 10 65 C	ADS8422IBPFBR	Tape and reel 1000

⁽¹⁾ For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI website at www.ti.com.

ABSOLUTE MAXIMUM RATINGS(1)

over operating free-air temperature range (unless otherwise noted)

			VALUE	UNIT
		+IN to AGND	-0.4 to +VA + 0.1	V
	Valtana	-IN to AGND	-0.4 to +VA + 0.1	V
	Voltage	+VA to AGND	-0.3 to 7	V
		+VBD to BDGND	-0.3 to 7	V
	Digital input voltage to BDGND		-0.3 to +VBD + 0.3	V
	Digital output voltage to BDGN	D	-0.3 to +VBD + 0.3	V
T _A	Operating free-air temperature	range	-40 to 85	°C
T _{stg}	Storage temperature range		-65 to 150	°C
	Junction temperature (T _J max)		150	°C
	TOED 40 nin nockogo	Power dissipation	$(T_{J}Max - T_{A})/\theta_{JA}$	
	TQFP 48-pin package	θ_{JA} thermal impedance	86	°C/W
	l and to see a set up a caldesis a	Vapor phase (60 sec)	215	°C
	Lead temperature, soldering	Infrared (15 sec)	220	°C

⁽¹⁾ Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.



SPECIFICATIONS

 $T_A = -40^{\circ}\text{C}$ to 85°C, +VA = 5 V, +VAREG = 5 V to 3 V, +VBD = 5 V to 2.7 V, $f_{SAMPLE} = 4$ MSPS, $V_{ref} = 4.096$ V (measured with internal reference buffer) (unless otherwise noted)

PARAMETE	R	TEST CONDITIONS	MIN	TYP	MAX	UNIT	
ANALOG INPUT							
Full-scale input voltage(1)		+IN - (-IN)	-V _{ref}		V_{ref}	V	
Abaduta input valtaga		+IN	-0.2		V _{ref} + 0.2	V	
Absolute input voltage		-IN	-0.2		V _{ref} + 0.2	V	
Common-mode input range			(V _{ref})/2 - 0.2	(V _{ref})/2	$(V_{ref})/2 + 0.2$	V	
Input capacitance				30		pF	
Input leakage current					1	nA	
SYSTEM PERFORMANCE							
Resolution				16		Bits	
No missing codes	ADS8422I		15			Bits	
no missing codes	ADS8422IB		16			DIIS	
Integral linearity (2)(3)	ADS8422I		-6	±2	6	LSB	
Integral linearity (2)(3)	ADS8422IB		-2	±1	2	(16 bit) ⁽²⁾	
Differential linearity	ADS8422I		-2	±0.7	2	LSB	
Differential linearity	ADS8422IB		-1	±0.7	1.5	(16 bit)	
Offset error			-0.5	±0.25	0.5	mV	
Offset error drift				±0.2		ppm/°C	
Gain error ⁽⁴⁾⁽⁵⁾		V _{ref} = 4.096 V	-0.1	±0.05	0.1	%FS	
Gain error drift		V _{ref} = 4.096 V		±2		ppm/°C	
		At dc		81			
Common-mode rejection ratio		At code 0000h with $[+IN + (-IN)]/2 =$ 512 mV _{pp} at 500 kHz,	78			dB	
Noise		At 0000h output code		40		μV RMS	
Power supply rejection ratio		At 8000h output code		78		dB	
SAMPLING DYNAMICS							
Conversion time					0.180	μs	
Acquisition time			0.070			μs	
Throughput rate					4	MHz	
Aperture delay				3		ns	
Aperture jitter				7		ps RMS	
Step response				70		ns	
Overvoltage recovery				140		ns	

- (1) Ideal input span, does not include gain or offset error.
 (2) LSB means least significant bit and is equal to 2V_{REF}/65536.
- (3) This is endpoint INL, not best fit.
- (4) Measured relative to an ideal full-scale input [+IN (–IN)] of 8.192 V.
- (5) This specification does not include the internal reference voltage error and drift.



SPECIFICATIONS (Continued)

 $T_A = -40^{\circ}\text{C}$ to 85°C, +VA = 5 V, +VAREG = 5.25 V to 3 V, +VBD = 5 V to 2.7 V, $f_{SAMPLE} = 4$ MSPS, $V_{ref} = 4.096$ V (measured with internal reference buffer) (unless otherwise noted)

IESI	CONDITIONS	MIN	TYP	MAX	UNIT
	10 kHz		-114		
$V_{IN} = 8 V_{pp}$	100 kHz		-102		dB
	500 kHz		-100		
	10 kHz		93		
$V_{IN} = 8 V_{pp}$	100 kHz		92		dB
	500 kHz		90		
	10 kHz		92.5		
$V_{IN} = 8 V_{pp}$	100 kHz		91.5		dB
	500 kHz		89.5		
	10 kHz		116		
$V_{IN} = 8 V_{pp}$	100 kHz		109		dB
	500 kHz		106		
			30		MHz
$V_{IN} = 8 V_{pp}$		2			MHz
		3.9	4.096	4.15	V
			1000		ΜΩ
From 95% (+VA), with	ı 1-μF capacitor on REFOUT			25	ms
I _O = 0, T _A = 25°C		4.088	4.096	4.104	V
Static load				10	μΑ
+VA = 4.75 V to 5.25	V		±1		mV
I _O = 0		±6			PPM/°C
I _O = 0		V _{REF} /2 - 0.016	V _{REF} /2	V _{REF} /2 + 0.016	V
Static load			200		μΑ
	$V_{IN} = 8 \ V_{pp}$ From 95% (+VA), with I _O = 0, T _A = 25°C Static load +VA = 4.75 V to 5.25 I _O = 0 $I_{O} = 0$	$V_{IN} = 8 \text{ V}_{pp}$ V_{I	$V_{IN} = 8 \text{ V}_{pp}$ $I00 \text{ kHz}$ 100 kHz 500 kHz 100 kHz 100 kHz 500 kHz 100 kHz 500 kHz 100 kHz 500 kHz $100 $	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$

⁽¹⁾ Calculated on the first nine harmonics of the input frequency.

⁽²⁾ ADC Sampling circuit is optimized to accept inputs until Nyquist frequency. Dynamic performance may degrade rapidly above f_{i(max)}.



SPECIFICATIONS (Continued)

 $T_A = -40^{\circ}\text{C}$ to 85°C, +VA = 5 V, +VAREG = 5 V to 3 V, +VBD = 5 V to 2.7 V, $f_{SAMPLE} = 4$ MSPS, $V_{ref} = 4.096$ V (measured with internal reference buffer) (unless otherwise noted)

PARAME	ETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
DIGITAL INPUT/OUTPUT						
Logic family – CMOS						
	V _{IH}	$I_{IH} = 5 \mu A$	0.75×(+VBD)		+VBD + 0.3	
Logic level	V _{IL}	I _{IL} = 5 μA	-0.3		0.8	V
Logic level	V _{OH}	I _{OH} = 2 TTL loads	+VBD - 0.6			V
	V _{OL}	I _{OL} = 2 TTL loads			0.4	
Data format – Twos complen	nent					
POWER SUPPLY REQUIRE	MENTS				·	
	+VA		4.75	5	5.25	
Power supply voltage	+VAREG		2.85	2.85 3.0		V
	+VBD		2.7	3.0	5.25	
	+VA	+VA = 5 V, <u>PD1</u> = 1, <u>PD2</u> = 1		24		mA
	WAREC	+VAREG = 5 V, PD1 = 1, PD2 = 1		12 14		mA
Supply current	+VAREG	+VAREG = 3 V, <u>PD1</u> = 1, <u>PD2</u> = 1		12 14		ША
	+VBD ⁽¹⁾	+VBD = 3 V, 10 pF/pin	0.55		mA	
	+۷60(1)	+VBD = 5 V, 20 pF/pin			mA	
POWER DOWN ⁽²⁾	<u>.</u>					
Supply current	+VA	PD1 = 0, PD2 = 1, +VA = 5 V		2.5	3.4	mA
Supply current	+VAREG	PD1 = 0, PD2 = 1, +VA = 5 V		5		μΑ
Power					17	mW
Power-up time		$(\overline{PD1}, \overline{PD2}) : (0,1) \rightarrow (1,1)$			5	μs
Cumply ourrant	+VA	PD1 = 0. PD2 = 0		5		^
Supply current	+VAREG	PD1 = 0, PD2 = 0			μΑ	
Power				40		μW
Power-up time		$(\overline{PD1}, \overline{PD2})$: $(0,0) \rightarrow (1,1)$, 1-µF Storage capacitor from REFOUT to AGND			25	ms
TEMPERATURE RANGE			-		-	
Operating free-air			-40		85	°C

This includes the current required for charging the external load capacitance on the digital outputs and is measured with four digital outputs toggling at the same time. $(\overline{PD}_1$, \overline{PD}_2) = (1,0) is reserved. Do not use this power-down pins combination.



TIMING CHARACTERISTICS FROM DIGITAL INPUTS

All specifications typical at -40° C to 85° C, +VBD = 2.7 V to 5.25 V (1)(2)

		PARAMETER	MIN	TYP MAX	UNIT
CONV	ERSION AND AC				
t _(ACQ)	Acquisition time	, internal to device, not externally visible	70		ns
t _{w1}	Pulse duration,	CONVST low	20		ns
t _{w2}	Pulse duration,	CONVST high	100		ns
t _{p1}	Period, CONVS	T	250		ns
t _{q1}	Quiet time, last	toggle of interface input signals during acquisition before CONVST falling (3)	30		ns
t _{q2}	Quiet time, CON	NVST falling to first toggle of interface input signals (3)	10		ns
POWE	R DOWN				
		PD1 low for only ADC reset (no powerdown)	20	500	
t _{w3}	w3 Pulse duration	PD1 low for ADC reset and also ADC powerdown	1500		ns
		PD2 low pulse duration for REFOUT and COMMOUT buffers powerdown	1500		1
	Pulse duration,	10		ns	

- (1) All input signals are specified with t_r = t_f = 5 ns (10% to 90% of V_{DD}) and timed from after 90% of transition.
 (2) All digital output signals loaded with 10-pF capacitors at +VBD = 2.7 V and 20-pF capacitor at +VBD = 5.25 V and timed to reaching 90% of transition.
- Quiet time zones are for meeting performance and not functionality.

TIMING CHARACTERISTICS OF DIGITAL OUTPUTS

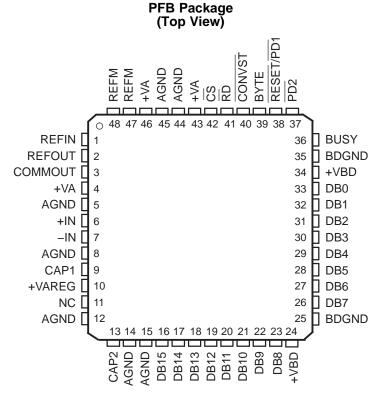
All specifications typical at -40° C to 85° C, +VBD = 2.7 V to 5.25 V (1)(2)

	PARAMETER	MIN TYP	MAX	UNIT
CONVE	RSION AND ACQUISITION	-1	'	
t _(CONV)	Conversion time, internal to device, not externally visible		180	ns
t _{d1}	Delay time, CONVST fall to conversion start (aperture delay)	3		ns
DATA R	EAD OPERATION			
t _{d2}	Delay time, \overline{CONVST} low to data valid if $\overline{CS} = \overline{RD} = 0$		225	ns
t _{d3}	Delay time, data valid to BUSY low if $\overline{CS} = \overline{RD} = 0$	5		ns
t _{d4}	Delay time, $\overline{\text{RD}}$ (or $\overline{\text{CS}}$) low to data valid		17	ns
t _{d5}	Delay time, BYTE toggle to data valid		20	ns
t _{d6}	Delay time, data three-state after $\overline{\text{RD}}$ (or $\overline{\text{CS}}$) high		12	ns
POWER	DOWN	-1	'	
t _{d7}	Delay time, PD1 low to BUSY rising		20	ns
	Delay time, PD1 high to device operational (with PD2 held high)		5	μs
t _{d8}	Delay time, PD2 high to REFOUT/COMMOUT valid		25	ms
	Delay time, power up (after AV _{DD} = 4.75 V)		25	ms
t _{d9}	Delay time, data three-state after PD1 low		1.5	μs

- (1) All input signals are specified with t_r = t_f = 5 ns (10% to 90% of V_{DD}) and timed from after 90% of transition.
 (2) All digital output signals loaded with 10-pF capacitors at +VBD = 2.7 V and 20-pF capacitor at +VBD = 5.25 V and timed to reaching 90% of transition.



PIN ASSIGNMENTS



- A. NC No connection
- B. Pins 9 and 13 are internally regulated 3-V outputs and are externally to be connected to decoupling capacitors only.
- C. +VAREG can be connected to a 3-V to 5-V supply.
- D. Pin 3 outputs REFIN/2
- E. Pin 38 can be used for ADC powerdown and pin 37 for analog output powerdown.

TERMINAL FUNCTIONS

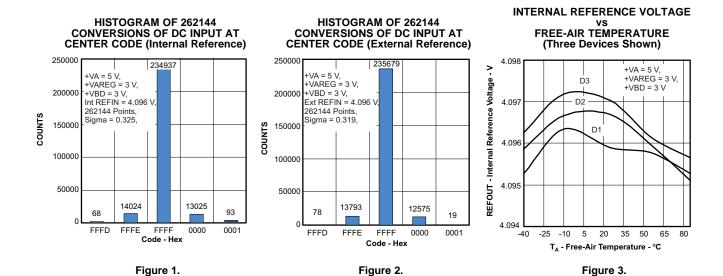
NAME	NO	I/O		DESCRIPTION						
AGND	5, 8, 12, 14, 15, 44, 45	-	Analog ground	Analog ground						
BDGND	25, 35	-	Digital ground for bus	interface digital supply						
BUSY	36	0	Status output. High wh	en a conversion is in progr	ess.					
BYTE	39	I	0: No fold back	select input. Used for 8-bit bus reading.						
COMMOUT	3	0	This pin outputs REFII –IN)/2.	oin outputs REFIN/2 and can be used to set the common-mode voltage of the differential analog input, (+IN +						
CONVST	40	I	Convert start. This inp	onvert start. This input is low true and can act independent of the CS input.						
CS	42	I	Chip select.							
CAP1, CAP2	9, 13	0	Decoupling of internall	y generated 3-V supply. Ad	d 1-μF capacitor from these pins to AGND.					
Dete Due			8-E	BIT BUS	16-BIT BUS					
Data Bus			BYTE = 0	BYTE = 1	BYTE = 0					
DB15	16	0	D15 (MSB)	D7	D15 (MSB)					
DB14	17	0	D14	D6	D14					
DB13	18	0	D13	D5	D13					
DB12	19	0	D12	D4	D12					
DB11	20	0	D11	D3	D11					
DB10	21	0	D10	D2	D10					



TERMINAL FUNCTIONS (continued)

NAME	NO	I/O			DESCRIPTION			
DB9	22	0	D9	D1	D9			
DB8	23	0	D8 D0 (LSB)		D8			
DB7	26	0	D7	All ones	D7			
DB6	27	0	D6	All ones D6				
DB5	28	0	D5	All ones	D5			
DB4	29	0	D4	All ones	D4			
DB3	30	0	D3	All ones	D3			
DB2	31	0	D2	All ones	D2			
DB1	32	0	D1	All ones	D1			
DB0	33	0	D0 (LSB)	All ones	D0 (LSB)			
-IN	7	I	Inverting input channel					
+IN	6	I	Noninverting input cha	nnel				
NC	11	-	No connection					
PD2	37	I			pplied to this pin powers down only the analog outputs that include tition PD1 = 1, PD2 = 0 is reserved. Do not use this combination.)			
REFIN	1	ı	Reference input. Add 0).1-μF decoupling capacito	or between REFIN and REFM.			
REFOUT	2	0	Reference output. Add	1-μF capacitor between t	he REFOUT pin and REFM pin when internal reference is used.			
REFM	47, 48	I	Reference ground					
RESET/PD1	38	ı	than 0.5 µs only resets		esets the ADC; the ongoing conversion is aborted. A low pulse shorter μ s resets and also powers down the ADC. Note that analog outputs μ by $\overline{PD2}$, if necessary.			
RD	41	ı	Synchronization pulse	for the parallel output.				
+VA	4, 46	-	Analog power supplies	, 4.75 V to 5.25 VDC				
+VAREG	10	-	Regulator supply, 2.85	V to 5.25 VDC				
+VBD	24, 34	-	Digital power supply fo	r bus				

TYPICAL CHARACTERISTICS





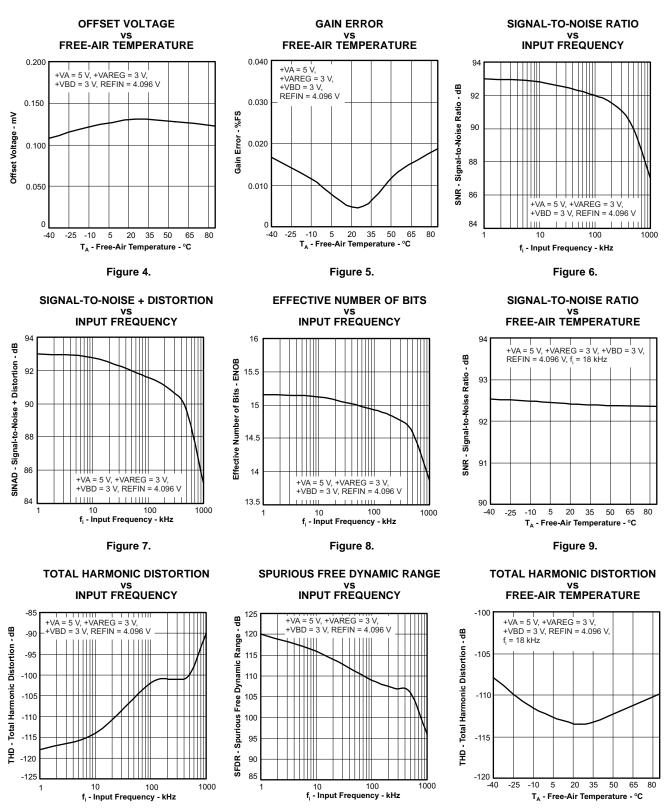
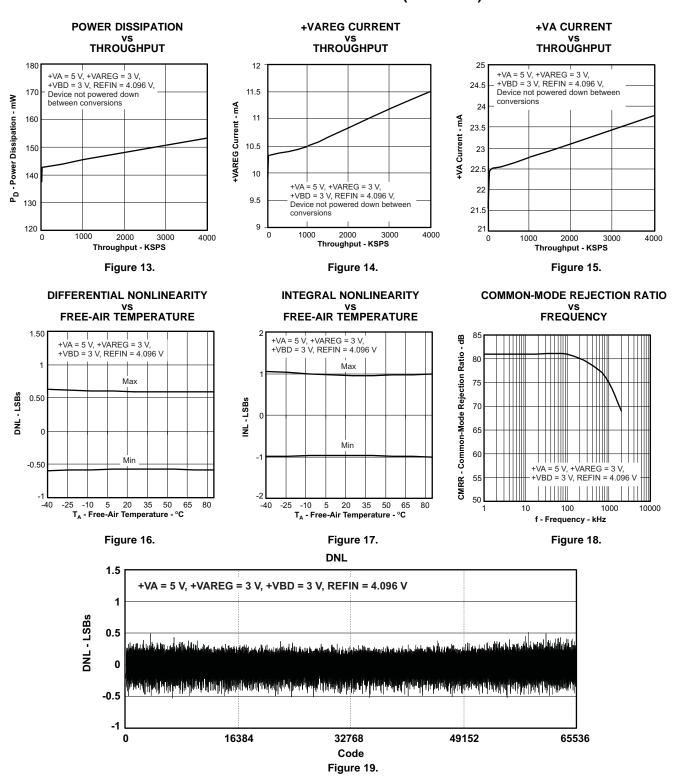


Figure 12.

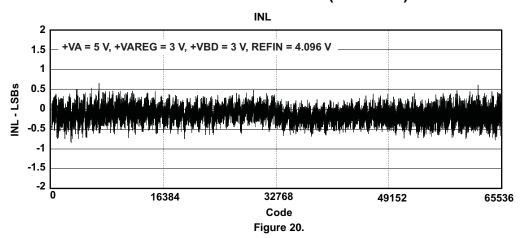
Figure 11.

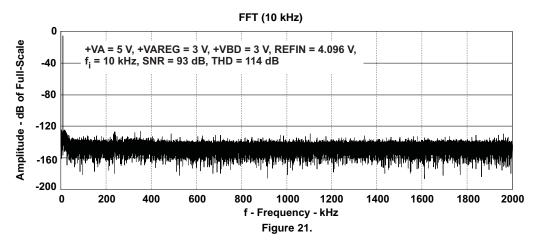
Figure 10.

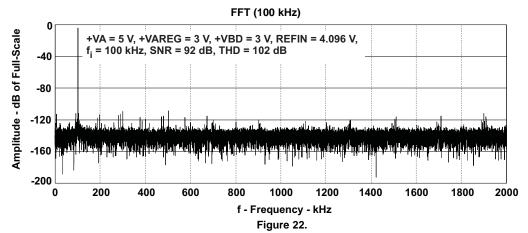




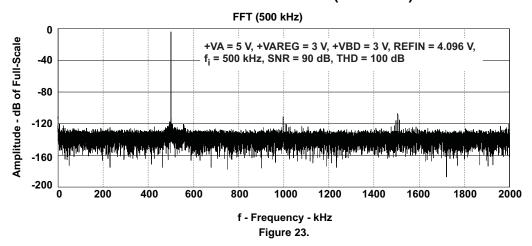




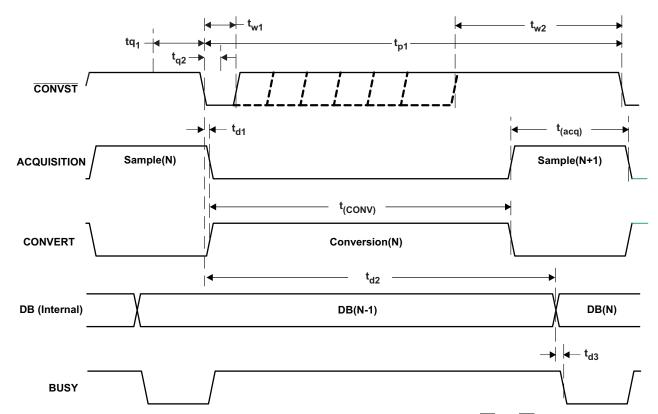








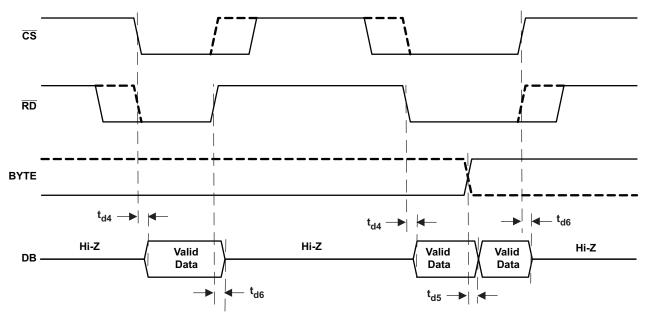
TIMING DIAGRAMS



Note: The DB shown here is internal to the device and output on the pins only if and when \overline{CS} and \overline{RD} are both low (after t_{d4} ns). This is shown in Figure 25.

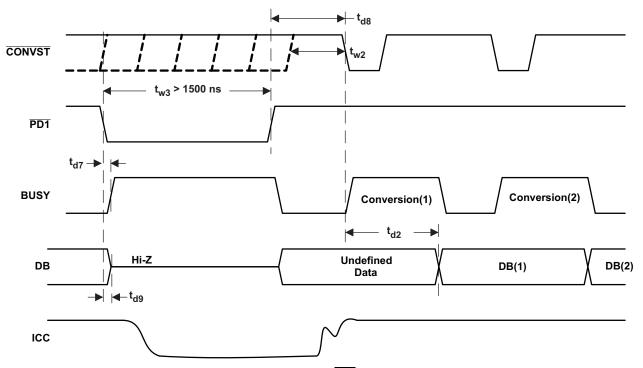
Figure 24. Conversion Control Timing





Note: Data is output on the pins only if $\overline{\text{CS}}$ and $\overline{\text{RD}}$ are both low, t_{d4} ns after this condition is satisfied.

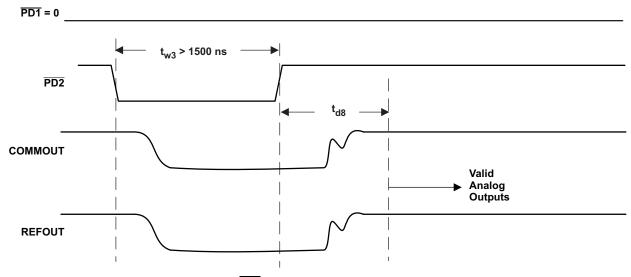
Figure 25. Data Read Timing



Note: Data is valid from the first conversion initiated 5 μs after $\overline{PD1}$ is pulled high.

Figure 26. ADC Power-Down Timing

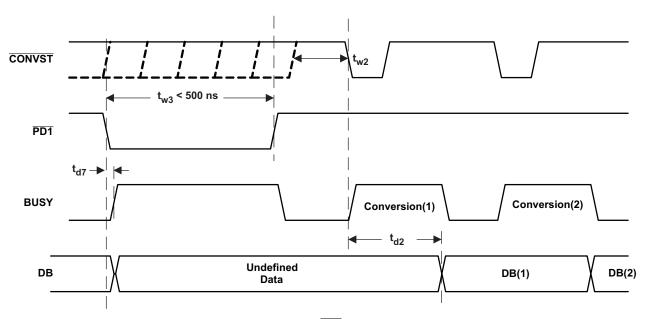




Note: Analog outputs are valid 25 ms after $\overline{\text{PD2}}$ is pulled high.

Figure 27. Analog Output Power-Down Timing

RESET TIMING



Note: Data valid from first conversion initiated 100 ns after PD1 is pulled high.

Figure 28. ADC Reset



PRINCIPLES OF OPERATION

The ADS8422 is a member of a family of high-speed multi-bit successive approximation register (SAR) analog-to-digital converters (ADC). The architecture is based on charge redistribution, which inherently includes a sample/hold function. See Figure 34 for the application circuit for the ADS8422.

The conversion clock is generated internally. The conversion time is a maximum of 180 ns that is capable of sustaining a 4-MHz throughput.

The analog input is provided to two input pins: +IN and -IN. When a conversion is initiated, the differential input on these pins is sampled on the internal capacitor array. While a conversion is in progress, both inputs are disconnected from any internal function.

REFERENCE

The ADS8422 has a built-in 4.096-V reference but can operate with an external 4.096-V reference. When internal reference is used, pin 2 (REFOUT) should be connected to pin 1 (REFIN) with a 0.1- μ F decoupling capacitor and a 1- μ F storage capacitor between pin 2 (REFOUT) and pins 47 and 48 (REFM). The internal reference of the converter is double buffered. If an external reference is used, the second buffer provides isolation between the external reference and the CDAC. This buffer is also used to recharge all of the capacitors of the CDAC during conversion. Pin 2 (REFOUT) can be left unconnected (floating) if an external reference is used.

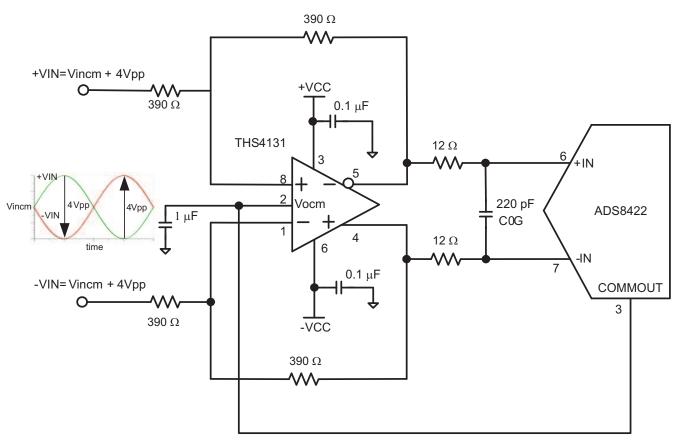
ANALOG INPUT

The ADS8422 has a pseudo-bipolar, fully differential input. When the input is differential, the amplitude of the input equals the difference between +IN and -IN. The peak-to-peak amplitude of each input is V_{REF} . However since the two inputs are 180° out of phase, the peak-to-peak amplitude of the difference voltage [+IN - (-IN)] is equal to $2V_{REF}$. The common-mode input range is from $V_{REF}/2 - 0.2 \text{ V}$ to $V_{REF}/2 + 0.2 \text{ V}$.

In order to avoid additional external circuitry on the board, the ADS8422 outputs reference input on REFIN divided by 2 on pin 3 (COMMOUT). This voltage can be used to set the common-mode of the output from the input driver.

Figure 29, Figure 30, Figure 31, Figure 32, and Figure 33 show the recommended circuits to interface an analog input signal to the ADS8422.

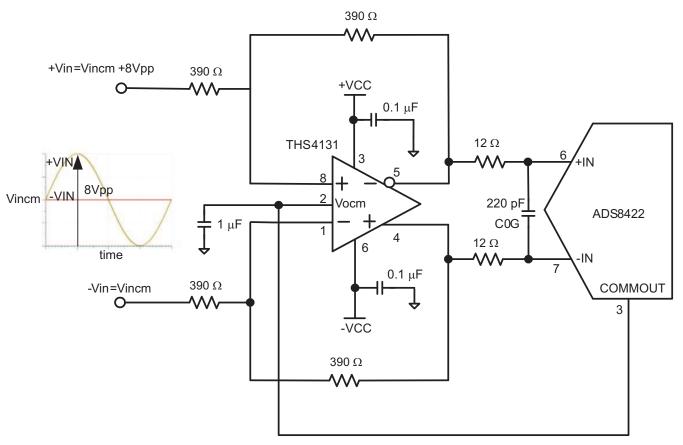




A. Input common-mode voltage (Vincm) range is restricted by the amplifier. Refer to the amplifier data sheet for more information. Output common mode of the THS4131 is set by the voltage at pin 2. The COMMOUT pin of the ADS8422 is designed to source pin 2 of the THS4131. However to use this feature both the positive supply and negative supply rails must equal (|-VCC| = |+VCC|), absolutely.

Figure 29. Fully Differential Input Driver Circuit for Unipolar or Bipolar Signals





A. Input common-mode voltage (Vincm) range is restricted by the amplifier. Refer to the amplifier data sheet for more information. Output common mode of the THS4131 is set by the voltage at pin 2. The COMMOUT pin of the ADS8422 is designed to source pin 2 of the THS4131. However to use this feature both the positive supply and negative supply rails must equal (|-VCC| = |+VCC|), absolutely.

Figure 30. Single-Ended Input Driving Circuit for When Input is Unipolar or Bipolar



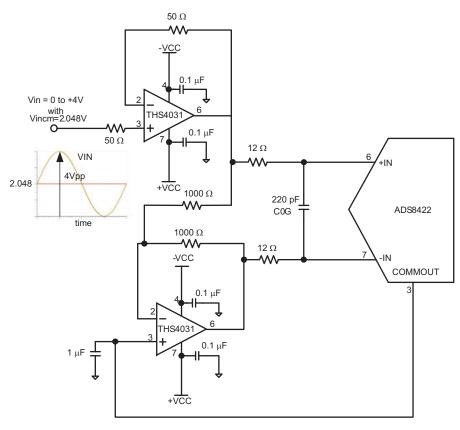
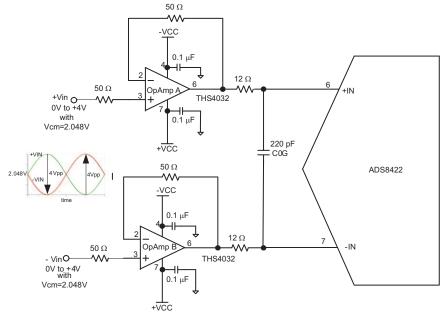


Figure 31. Single-Ended Driving Circuit for When Input is Single-Ended Unipolar and has Common-Mode of 2.048 V



A. This circuit is used to specify ADS8422 performance parameters listed in the data sheet.

Figure 32. Driver Circuit for When Input is Fully Differential Riding on Common-Mode of 2.048 V



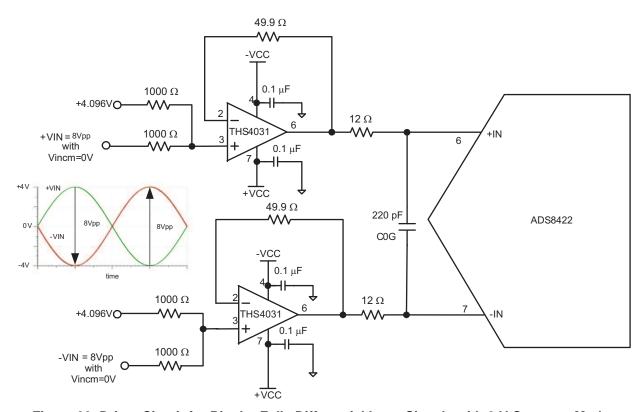


Figure 33. Driver Circuit for Bipolar Fully Differential Input Signals with 0-V Common-Mode

The input current on the analog inputs depends upon a number of factors: sample rate, input voltage, and source impedance. Essentially, the current into the ADS8422 charges the internal capacitor array during the sample period. After this capacitance has been fully charged, there is no further input current. The source of the analog input voltage must be able to charge the input capacitance (30 pF) to a 16-bit settling level within the 70 ns acquisition time of the device. When the converter goes into hold mode, the input impedance is greater than $1 \text{ G}\Omega$.

Care must be taken regarding the absolute analog input voltage. To maintain the linearity of the converter, both -IN and +IN inputs should be within the limits specified. Outside of these ranges, the converter linearity may not meet specifications. To minimize noise, low bandwidth input signals with low pass filters should be used.

Care should be taken to ensure that the output impedances of the sources driving the +IN and -IN inputs are matched. If this is not observed, the two inputs could have different settling times. This may result in offset error, gain error, and linearity error which change with temperature and input voltage.

When the converter enters hold mode, the voltage difference between the +IN and -IN inputs is captured on the internal capacitor array.

DIGITAL INTERFACE

Timing and Control

See the timing diagrams for detailed information on timing signals and their requirements.

The ADS8422 uses an internal oscillator generated clock which controls the conversion rate and in turn the throughput of the converter. No external clock input is required.



Conversions are initiated by bringing the \overline{CONVST} pin low for a minimum of 20 ns (after the 20 ns minimum requirement has been met, the \overline{CONVST} pin can be brought high). The converter switches from sample to hold mode on the falling edge of the \overline{CONVST} command. A clean and low jitter falling edge of this signal is important to the performance of the converter. The BUSY pin is brought high immediately following \overline{CONVST} going low. BUSY stays high through the conversion process and returns low when the conversion has ended and data is available on the DB pins. Once the conversion is started, it cannot be stopped except with an asynchronous \overline{RESET} (or a logical $\overline{PD1}$).

If $\overline{\text{CONVST}}$ is detected high at the end of conversion, the device immediately enters sampling mode and the analog input is connected to the CDAC. Otherwise, the CDAC is connected to the analog input only when $\overline{\text{CONVST}}$ goes high. The high duration of $\overline{\text{CONVST}}$ should be at least 100 ns. There is no maximum high pulse duration specification for $\overline{\text{CONVST}}$.

Reading Data

The ADS8422 outputs full parallel data in 2's complement format as shown in Table 1. The parallel output is active when \overline{CS} and \overline{RD} are both low. There is a minimal quiet zone requirement around the falling edge of \overline{CONVST} . This is 30 ns prior to the falling edge of \overline{CONVST} and 10 ns after the falling edge. No data read should be attempted within this zone. Any other combination of \overline{CS} and \overline{RD} three-states the parallel output. BYTE is used for multi-word read operation. BYTE is used whenever lower bits on the bus are output on the higher byte of the bus. Refer to Table 1 for ideal output codes.

ANALOG VALUE DESCRIPTION **DIGITAL OUTPUT 2'S COMPLIMENT** Full scale range $2V_{ref}$ 2V_{ref})/65536 Least significant bit (LSB) **BINARY CODE HEX CODE** +Full scale $(+V_{ref})$ -0111 1111 1111 1111 7FFF Midscale 0000 0000 0000 0000 0000 0 V 0 V – Midscale - 1 LSB 1111 1111 1111 1111 **FFFF** -Full scale $-V_{ref}+$ 1000 0000 0000 0000 8000

Table 1. Ideal Input Voltages and Output Codes

The output data can be read as a full 16-bit word on pins DB15 - DB0 (MSB-LSB) if BYTE is low.

The result may also be read on an 8-bit bus for convenience. This is done by using only pins DB15-DB8. In this case two reads are necessary: the first as before, leaving BYTE low and reading the 8 most significant bits on pins DB15-DB8, then bringing BYTE high. When BYTE is high, the low bits (D7-D0) appear on pins DB15-DB8.

These multi-word read operations can be performed with a multiple active (toggling) \overline{RD} signal or with the \overline{RD} signal tied low for simplicity.

 DATA READ OUT

 BYTE
 PINS DB15-DB8
 PINS DB7-DB0

 High
 D7 - D0
 All One's

 Low
 D15 - D8
 D7 - D0

Table 2. Conversion Data Read Out

RESET

RESET/PD1 is an asynchronous active low input signal. Maximum RESET/PD1 low time is 0.5 μs to avoid ADC powerdown. Current conversion is aborted no later than 20 ns after the converter is in reset mode. The converter returns to normal operation mode no later than 20 ns after the RESET/PD1 input is brought high (see Figure 28).

The converter provides two power saving options: ADC powerdown (using pin 38, PD1) and analog output powerdown (PD2).



ADC powerdown is activated by asserting $\overline{PD1}$ to 0 for longer than 1.5 μ s. If the signal $\overline{PD1}$ is asserted 0 for less than 0.5 μ s, the ADC is only reset and any ongoing conversion aborted. See Figure 26. ADC operation can be resumed from ADC powerdown by de-asserting the $\overline{PD1}$ pin. In ADC power-down mode, the analog outputs from the ADC(COMMOUT, REFOUT) are not powered down thereby reducing the power-on time.

Full chip power-down is activated by turning off the power supply or by asserting both, $\overline{PD1} = 0$ and $\overline{PD2} = 0$ for longer than 1.5 µs (see Figure 27). In this mode, even the analog outputs of the ADC (COMMOUT, REFOUT) are powered down thereby giving maximum power saving. Device operation can be resumed from full chip power-down by turning on the power supply or by deasserting both, $\overline{PD1} = 1$ and $\overline{PD2} = 1$.

COMMAND **APPLICATION TIME POWER WHEN APPLIED RESUME TIME** $\overline{RESET/PD1} = 0$ 20 ns No change 20 ns $\overline{PD1} = 0, \overline{PD2} = 1$ 1.5 µs 17mW 5 μs $\overline{PD1} = \overline{PD2} = 0$ $1.5 \, \mu s$ $40 \mu W$ 25 ms $\overline{PD1} = 1, \overline{PD2} = 0$ Reserved - Do not use this combination

Table 3. Effects of RESET, PD1, and PD2

LAYOUT

For optimum performance, care should be taken with the physical layout of the ADS8422 circuitry.

As the ADS8422 offers single-supply operation, it is often used in close proximity with digital logic, microcontrollers, microprocessors, and digital signal processors. The more digital logic present in the design and the higher the switching speed, the more difficult it is to achieve good performance from the converter.

The basic SAR architecture is sensitive to glitches or sudden changes on the power supply, reference, ground connections, and digital inputs that occur just prior to latching the output of the analog comparator. Thus, driving any single conversion for an n-clock SAR converter, there are n *windows* in which large external transient voltages can affect the conversion result. Such glitches might originate from switching power supplies, nearby digital logic, or high power devices. The 50 ns period before BUSY falls should be kept free of supply glitches.

The degree of error in the digital output depends on the reference voltage, layout, and the exact timing of the external event.

On average, the ADS8422 draws very little current from an external reference as the reference voltage is internally buffered. If the reference voltage is external and originates from an op amp, make sure that it can drive the bypass capacitor or capacitors without oscillation. A 0.1- μ F bypass capacitor is recommended from pin 1 directly to REFM (pin 48). REFM and AGND should be shorted on the same ground plane underneath the device.

The AGND, BDGND, and AGND pins should be connected to a clean ground point. In all cases, this should be the *analog* ground. Avoid connections which are too close to the grounding point of a microcontroller or digital signal processor. If required, run a ground trace directly from the converter to the power supply entry point. The ideal layout consists of an analog ground plane dedicated to the converter and associated analog circuitry.

As with the AGND connections, +VA and +VAREG should be connected to their respective power supply planes or traces that are separate from the connection for digital logic, until they are connected at the power entry point. Power to the ADS8422 should be clean and well bypassed. A 0.1- μ F ceramic bypass capacitor should be placed as close to the device as possible. See Table 4 for capacitor placement. In addition, a 1- μ F to 10- μ F capacitor is recommended. In some situations, additional bypassing may be required, such as a 100- μ F electrolytic capacitor or even a Pi filter made up of inductors and capacitors — all designed to essentially low-pass filter the +5-V supply, thus removing the high frequency noise.

Table 4. Power Supply Decoupling Capacitor Placement

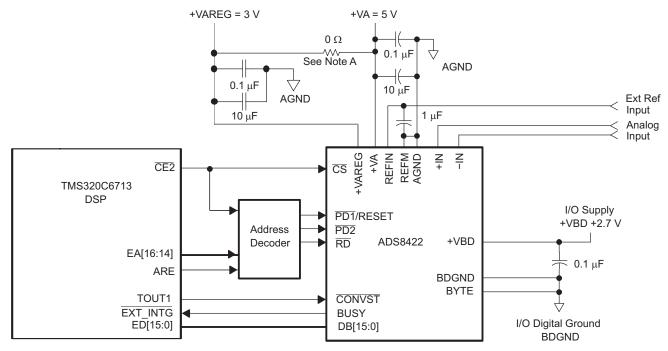
POWER SUPPLY PLANE	CONVERTER ANALOG SIDE	CONVERTER
SUPPLY PINS	CONVENTER ANALOG SIDE	DIGITAL SIDE
Pin pairs that require shortest path to decoupling capacitors	(4,5), (9,8), (10,12), (13,15), (43,44), (46,45)	(24,25), (34,35)



APPLICATION INFORMATION

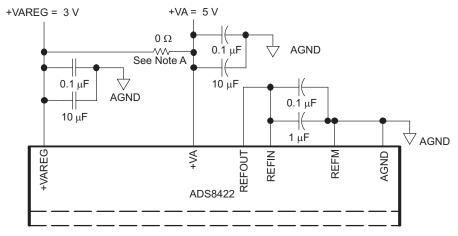
ADS8422 TO A HIGH PERFORMANCE DSP INTERFACE

Figure 34 shows a parallel interface between the ADS8422 and a Texas instruments high performance DSP such as the TMS320C6713 using the full 16-bit bus. The ADS8422 is mapped onto the CE2 memory space of the TMS320C6713 DSP. The read and reset signals are generated by using a 3-to-8 decoder. A read operation from the address 0xA000C000 generates a pulse on the RD pin of the data converter, wheras a read operation form word address 0xA0014000 generates a pulse on the RESET/PD1 pin. The CE2 signal of the DSP acts as CS (chip select) for the converter. As the TMS320C6713 features a 32-bit external memory interface, the BYTE input of the converter can be tied permanently low, disabling the foldback of the data bus. The BUSY signal of the ADS8422 is applied to the EXT_INT6 interrupt input of the DSP, enabling the EDMA controller to react on the falling edge of this signal and to collect the conversion result. The TOUT1 (timer out 1) pin of the TMS320C6713 is used to source the CONVST signal of the converter.



A. This resistor (0 Ω) can be installed to use the same 5-V supply.

Figure 34. ADS8422 Application Circuitry



A. This resistor (0 Ω) can be installed to use the same 5-V supply.

Figure 35. ADS8422 Using Internal Reference

14-Oct-2022 www.ti.com

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan	Lead finish/ Ball material	MSL Peak Temp	Op Temp (°C)	Device Marking (4/5)	Samples
ADS8422IBPFBR	ACTIVE	TQFP	PFB	48	1000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	ADS 8422I B	Samples
ADS8422IBPFBT	ACTIVE	TQFP	PFB	48	250	RoHS & Green	Call TI	Level-2-260C-1 YEAR	-40 to 85	ADS 8422I B	Samples
ADS8422IPFBR	ACTIVE	TQFP	PFB	48	1000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	ADS 8422I	Samples

(1) The marketing status values are defined as follows: **ACTIVE:** Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

- (3) MSL, Peak Temp. The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
- (4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
- (5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
- (6) Lead finish/Ball material Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and



PACKAGE OPTION ADDENDUM

www.ti.com 14-Oct-2022

continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

PFB (S-PQFP-G48)

PLASTIC QUAD FLATPACK



NOTES: A. All linear dimensions are in millimeters.

B. This drawing is subject to change without notice.

C. Falls within JEDEC MS-026

PFB (S-PQFP-G48)



NOTES: A. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
- C. Publication IPC-7351 is recommended for alternate designs.
- D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC-7525.
- E. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.



IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATA SHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to TI's Terms of Sale or other applicable terms available either on ti.com or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products.

TI objects to and rejects any additional or different terms you may have proposed.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2022, Texas Instruments Incorporated