

TPS62090, TPS62091 TPS62092, TPS62093

ZHCS208A -MARCH 2012-REVISED MARCH 2012

# 带有 DCS™ 控制的 3A 高效同步降压转换器

查询样品: TPS62090, TPS62091, TPS62092, TPS62093

## 特性

- 2.5 V 至 6 V 输入电压范围
- DCS™ 控制
- 转换器效率 95%
- 省电模式
- 20 µA 运行静态电流
- 针对最低压降的 100% 占空比
- 2.8 MHz/1.4 MHz 典型开关频率
- 0.8 V 至 V<sub>IN</sub> 的可调输出电压
- 固定输出电压版本
- 输出放电功能
- 可调节软启动
- 两级短路保护
- 输出电压跟踪

Vin 2.5V to 6V O

C1

10µF

C3 10nF

10nF

- 宽输出电容值选择
- 采用 3mm x 3mm 16 引脚四方扁平无引线 (QFN) 封装

TPS62090

sw

sw

vos

FB

PG

FREQ

AGND

PGND PGND

2

12 PVIN

11

10

13 EN

PVIN

A\/IN

СР

CN

SS

14 15

L1 470nH

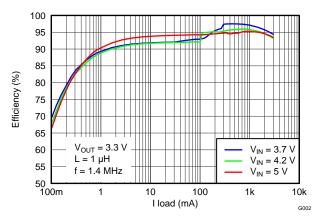
## 应用

- 分布式电源
- 笔记本、笔记本电脑
- 硬盘驱动器
- 处理器电源
- 电池供电型应用

说明

TPS6209x 器件是一款高效同步降压转换器,此转换器 针对小外形尺寸、高效应用进行了优化并适合于电池供 电类应用。为了最大限度地提升效率,此转换器运行 在 2.8 MHz/1.4 MHz 的标称开关频率的脉宽调制 (PWM)模式下并在轻负载时自动进入省电运行模式。 当被用于分布式电源和负载点调制时,此器件允许到其 它电源轨的电压跟踪并可耐受范围在 10 μF 到高达 150 μF 甚至更高的输出电容。通过使用 DCS™ 控制 技术,此器件可实现出色的负载静态性能以及精确的输 出电压调制。

此输出电压启动斜波由软启动引脚控制,从而使器件可 作为独立电源运行或运行在跟踪配置下。通过配置使 能和开漏电源正常引脚也有可能实现电源排序。在省 电模式下,此器件运行在典型值为 20 μA 静态电流 下。在全部负载电流范围内,自动进入省电模式并且 无缝保持高效。



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Vout

1.8V/3A

C2

22uF

-0

Power Good

R3 500k

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These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

T <sub>A</sub>	VOUT	ORDERING	PACKAGE	PACKAGE MARKING		
	adjustable	TPS62090	RGT	SBW		
4000 1- 0500	3.3 V	TPS62091	RGT	SBX		
-40°C to 85°C	2.5 V	TPS62092	RGT	SBY		
	1.8 V	TPS62093	RGT	SBZ		

#### **ORDERING INFORMATION**<sup>(1)</sup>

(1) For detailed ordering information please see the PACKAGE OPTION ADDENDUM section at the end of the datasheet.

## ABSOLUTE MAXIMUM RATINGS<sup>(1)</sup>

over operating free-air temperature range (unless otherwise noted)

		VALUE		UNIT
		MIN	MIN MAX	
	PVIN, AVIN, FB, SS, EN, FREQ, VOS <sup>(2)</sup>	-0.3	7	V
Voltage range	SW, PG	-0.3	V <sub>IN</sub> +0.3	V
Power Good sink current	PG		1	mA
CCD roting	Human Body Model		2	kV
ESD rating	Charged Device Model		500	V
Continuous total power diss	ipation	See t	he Thermal Ta	ble
Operating junction temperature range, T <sub>J</sub>		-40	150	°C
Operating ambient temperat	ture range, T <sub>A</sub>	-40	85	°C
Storage temperature range, T <sub>stg</sub> –65 15		150	°C	

(1) Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) All voltage values are with respect to network ground terminal.

#### THERMAL INFORMATION

	THERMAL METRIC <sup>(1)</sup>		
		QFN (16 PINS)	UNITS
$\theta_{JA}$	Junction-to-ambient thermal resistance	47	
θ <sub>JCtop</sub>	Junction-to-case (top) thermal resistance	60	
$\theta_{JB}$	Junction-to-board thermal resistance	20	°C/W
$\Psi_{JT}$	Junction-to-top characterization parameter	1.5	C/VV
Ψ <sub>JB</sub>	Junction-to-board characterization parameter	20	
$\theta_{JCbot}$	Junction-to-case (bottom) thermal resistance	5.3	

# (1) For more information about traditional and new thermal metrics, see the *IC Package Thermal Metrics* application report, SPRA953. **RECOMMENDED OPERATING CONDITIONS**<sup>(1)</sup>

		MIN	TYP MAX	UNIT
VIN	Input voltage range V <sub>IN</sub>	2.5	6	V
T <sub>A</sub>	Operating ambient temperature	-40	85	°C
TJ	Operating junction temperature	-40	125	°C

(1) See the application section for further information



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## **ELECTRICAL CHARACTERISTICS**

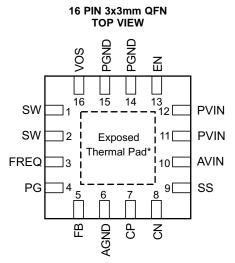
 $V_{IN}$  = 3.6V,  $T_A$  = -40°C to 85°C, typical values are at  $T_A$  = 25°C (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
SUPPLY	r					
V <sub>IN</sub>	Input voltage range		2.5		6	V
I <sub>QIN</sub>	Quiescent current	Not switching, FB = FB +5 %, Into PVIN and AVIN		20		μA
I <sub>sd</sub>	Shutdown current	Into PVIN and AVIN		0.6	5	μA
UVLO	Undervoltage lockout threshold	V <sub>IN</sub> falling	2.1	2.2	2.3	V
UVLO	Undervoltage lockout hysteresis			200		mV
	Thermal shutdown	Temperature rising		150		°C
	Thermal shutdown hysteresis			20		°C
Control	SIGNALS EN, FREQ					
V <sub>H</sub>	High level input voltage	$V_{IN} = 2.5 V \text{ to } 6 V$	1			V
VL	Low level input voltage	V <sub>IN</sub> = 2.5 V to 6 V			0.4	V
l <sub>lkg</sub>	Input leakage current	EN, FREQ = GND or $V_{IN}$		10	100	nA
R <sub>PD</sub>	Pull down resistance			400		kΩ
Softstar	rt				I	
I <sub>SS</sub>	Softstart current		6.3	7.5	8.7	μA
POWER	GOOD					
.,	5	Output voltage rising		95%		
V <sub>th</sub>	Power good threshold	Output voltage falling		90%		
VL	Low level voltage	I <sub>(sink)</sub> = 1mA			0.4	V
I <sub>PG</sub>	PG sinking current				1	mA
l <sub>lkg</sub>	Leakage current	V <sub>PG</sub> = 3.6V		10	100	nA
0	SWITCH	+	1			
	High side FET on-resistance	I <sub>SW</sub> = 500 mA		50		mΩ
R <sub>DS(on)</sub>	Low side FET on-resistance	I <sub>SW</sub> = 500 mA		40		mΩ
1	High side FET switch current		2.7	4.6	<b>F F</b>	^
I <sub>LIM</sub>	limit		3.7	4.6	5.5	A
f <sub>s</sub>	Switching frequency	FREQ = GND, I <sub>OUT</sub> = 3 A		2.8		MHz
's		FREQ = VIN, I <sub>OUT</sub> = 3 A		1.4		MHz
OUTPU	Т					
Vs	Output voltage range		0.8		V <sub>IN</sub>	V
R <sub>od</sub>	Output discharge resistor	$EN = GND, V_{OUT} = 1.8 V$		200		Ω
V <sub>FB</sub>	Feedback regulation voltage			0.8		V
		$V_{IN} \ge V_{OUT}$ + 1 V, TPS62090 adjustable output version				
		I <sub>OUT</sub> = 1 A, PWM mode	-1.4%		+1.4%	
V <sub>FB</sub>	Feedback voltage accuracy <sup>(1)</sup> (2)(3)	$I_{OUT}$ = 0 mA, FREQ = 2.8 MHz, $V_{OUT} \ge$ 0.8 V, PFM mode	-1.4%		+3%	
		$I_{OUT}$ = 0 mA, FREQ = 1.4 MHz, $V_{OUT} \ge$ 1.2 V, PFM mode	-1.4%		+3%	
		$I_{OUT}$ = 0 mA, FREQ = 1.4 MHz, $V_{OUT}$ < 1.2V, PFM mode	-1.4%		+3.7%	
I <sub>FB</sub>	Feedback input bias current	V <sub>FB</sub> = 0.8V, TPS62090 adjustable output version		10	100	nA
		$V_{IN} \ge V_{OUT} + 1 V$ , Fixed output voltage				
V <sub>OUT</sub>	Output voltage accuracy (2)(3)	I <sub>OUT</sub> = 1 A, PWM mode	-1.4%		+1.4%	
		<sub>OUT</sub> = 0 mA, FREQ = High and Low, PFM mode	-1.4%		+2.5%	
	Line regulation	V <sub>OUT</sub> = 1.8 V, PWM operation		0.016		%/V
	Load regulation	$V_{OUT} = 1.8 \text{ V}, \text{PWM operation}$		0.04		%/A

For output voltages < 1.2 V, use a 2 x 22 μF output capacitance to achieve +3% output voltage accuracy.</li>
 Conditions: f = 2.8 MHz, L = 0.47 μH, C<sub>OUT</sub> = 22 μF or f = 1.4 MHz, L = 1 μH, C<sub>OUT</sub> = 22 μF.
 For more information, see the Power Save Mode Operation section of this data sheet.



#### **DEVICE INFORMATION**



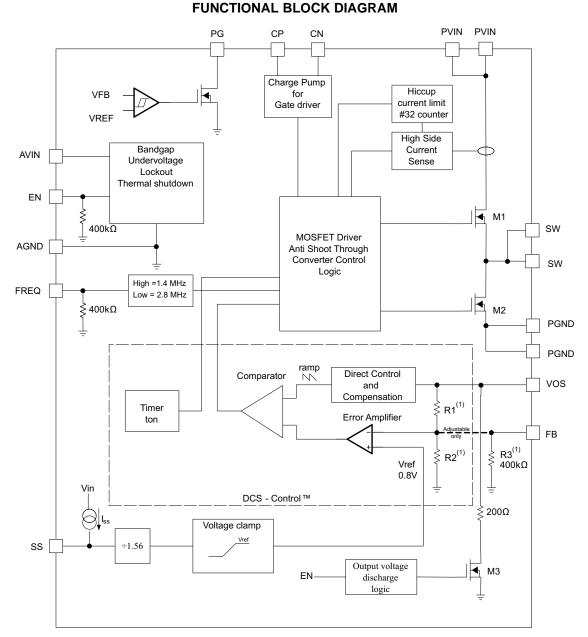
NOTE: \*The exposed Thermal Pad is connected to AGND.

#### **PIN FUNCTIONS**

PIN	PIN I/O		DESCRIPTION	
NAME	NO.	1/0	DESCRIPTION	
SW	1, 2	Ι	Switch pin of the power stage.	
FREQ	3	I	This pin selects the switching frequency of the device. FREQ=low sets the typical switching frequency to 2.8 MHz. FREQ=high sets the typical switching frequency to 1.4 MHz. This pin has an active pull down resistor of typically 400 k $\Omega$ and can be left floating for 2.8 MHz operation.	
PG	4	0	Power good open drain output. This pin is high impedance if the output voltage is within regulation. This pin is pulled low if the output is below its nominal value. The pull up resistor can not be connected to any voltage higher than the input voltage of the device.	
FB	5		Feedback pin of the device. For the fixed output voltage versions this pin needs to be connected to GND for improved thermal performance. If, desired then this pin can also be left floating since it is internally connected with 400 k $\Omega$ to GND for fixed output voltage versions.	
AGND	6		Analog ground.	
CP	7		Internal charge pump flying capacitor. Connect a 10 nF capacitor between CP and CN.	
CN	8		Internal charge pump flying capacitor. Connect a 10 nF capacitor between CP and CN.	
SS	9	Т	Soft-start control pin. A capacitor is connected to this pin and sets the softstart time. Leaving this pin floating sets the minimum start-up time.	
AVIN	10		Bias supply input voltage pin.	
PVIN	11,12		Power supply input voltage pin.	
EN	13		Device enable. To enable the device this pin needs to be pulled high. Pulling this pin low disables the device. This pin has an active pull down resistor of typically 400 k $\Omega$ .	
PGND	14,15		Power ground connection.	
VOS	16		Output voltage sense pin. This pin needs to be connected to the output voltage.	
Thermal Pa	d		The exposed thermal pad is connected to AGND.	



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#### (1) R1, R2, R3 are implemented in the fixed output voltage version only.

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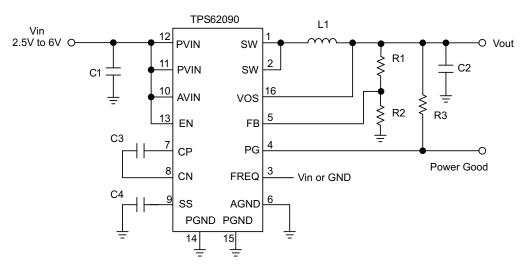
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NSTRUMENTS

ÈXAS

REFERENCE	DESCRIPTION	MANUFACTURER
TPS62090	High efficient step down converter	Texas Instruments
L1	Inductor: 1uH, 0.47uH, 0.4uH	Coilcraft XFL4020-102, XAL4020-401, TOKO DEF252012-R47
C1	Ceramic capacitor: 10uF, 22uF	(6.3V, X5R, 0603), (6.3V, X5R, 0805)
C2	Ceramic capacitor: 22uF	(6.3V, X5R, 0805)
C3, C4	Ceramic capacitor	Standard
R1, R2, R3	Resistor	Standard

Table 1. List of components



#### Figure 1. Parametric Measurement Circuit



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## **TYPICAL CHARACTERISTICS**

		FIGURE
Efficiency	vs load current ( $V_0$ = 3.3 V, f = 1.4 MHz, f = 2.8 MHz)	Figure 2, Figure 3
Efficiency	vs load current ( $V_0$ = 1.8 V, f = 1.4 MHz, f = 2.8 MHz)	Figure 4, Figure 5
Efficiency	vs load current ( $V_0$ = 1.05 V, f = 1.4 MHz, f = 2.8 MHz)	Figure 6, Figure 7
Output voltage	vs load current ( $V_0$ = 1.8 V, f = 1.4 MHz, f = 2.8 MHz)	Figure 8, Figure 9
High Side FET on-resistance	vs input voltage	Figure 10
Switching frequency	vs load current ( $V_0$ = 1.8 V, f = 1.4 MHz)	Figure 11
Switching frequency	vs input voltage (V <sub>O</sub> = 1.8 V, f = 1.4 MHz)	Figure 12
Switching frequency	vs load current (V <sub>O</sub> = 1. 8 V, f = 2.8 MHz)	Figure 13
Switching frequency	vs input voltage (V <sub>O</sub> = 1.8 V, f = 2.8 MHz)	Figure 14
Quiescent current	vs input voltage ( $V_O = 1.8 V$ , f = 1.4 MHz)	Figure 15
PWM operation	V <sub>O</sub> = 1.8 V, f = 1.4 MHz	Figure 16
PFM operation	V <sub>O</sub> = 1.8 V, f = 1.4 MHz	Figure 17
PFM operation	V <sub>O</sub> = 1.8 V, f = 2.8 MHz	Figure 18
Load sweep	V <sub>O</sub> = 1.8 V, f = 1.4 MHz	Figure 19
Load sweep	V <sub>O</sub> = 1.8 V, f = 2.8 MHz	Figure 20
Start-up	V <sub>O</sub> = 1.8 V, f = 2.8 MHz, C <sub>SS</sub> = 10 nF	Figure 21
Shutdown	V <sub>O</sub> = 1.8 V, f = 2.8 MHz	Figure 22
Hiccup short circuit protection	V <sub>O</sub> = 1.8 V, f = 1.4 MHz	Figure 23
Hiccup Short circuit protection	$V_{O}$ = 1.8 V, f = 1.4 MHz, recovery after short circuit	Figure 24
Load transient response	V <sub>O</sub> = 1.8 V, f = 1.4 MHz, 300 mA to 2.5 A	Figure 25
Load transient response	V <sub>O</sub> = 1.8 V, f = 1.4 MHz, 300 mA to 2.5 A	Figure 26
Load transient response	V <sub>O</sub> = 1.8 V, f = 1.4 MHz, 20 mA to 1 A	Figure 27

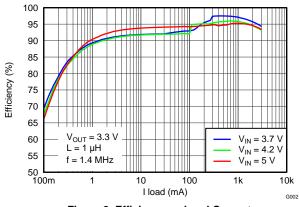
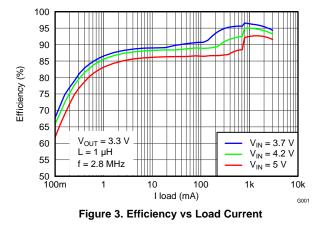


Figure 2. Efficiency vs Load Current



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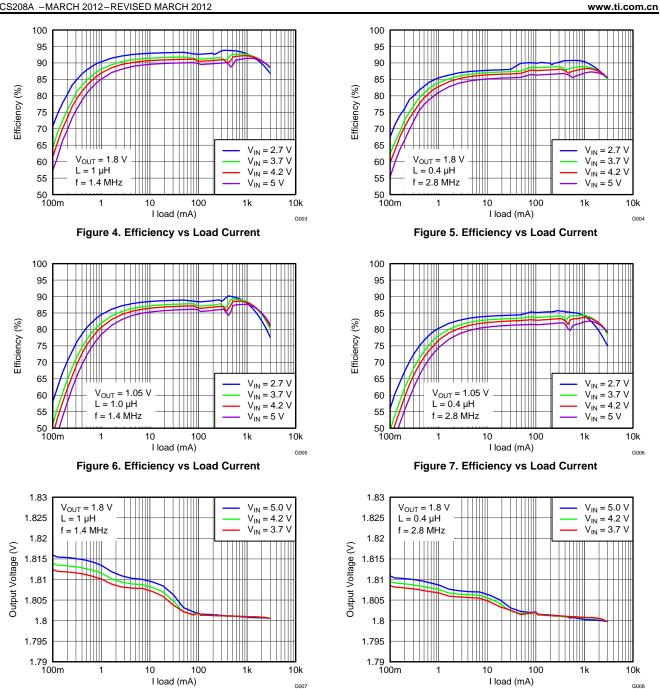


Figure 8. Output Voltage vs Load Current

Figure 9. Output Voltage vs Load Current

**EXAS** 

**NSTRUMENTS** 



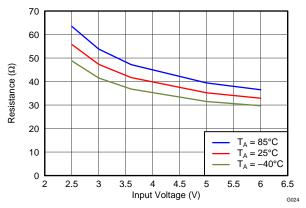


Figure 10. High Side FET On-Resistance vs Input Voltage

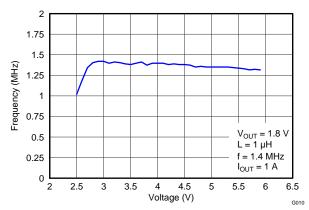


Figure 12. Switching Frequency vs Input Voltage

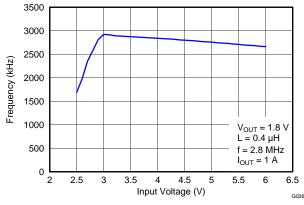


Figure 14. Frequency vs Input Voltage

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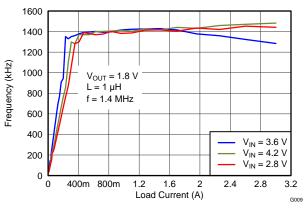


Figure 11. Switching Frequency vs Load Current

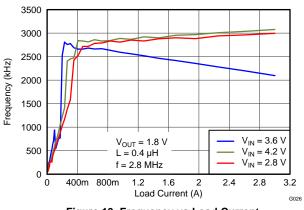


Figure 13. Frequency vs Load Current

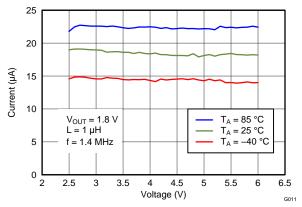
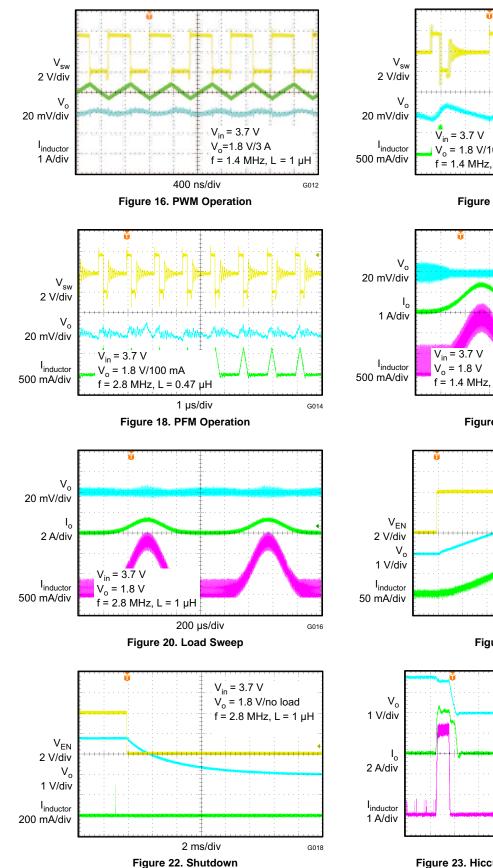


Figure 15. Quiescent Current vs Input Voltage

TEXAS INSTRUMENTS

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 $V_{sw}$ 2 V/div  $V_{o}$ 20 mV/div  $I_{inductor}$ 500 mA/div  $I_{inductor}$   $I_{inductor}$ 500 mA/div  $I_{inductor}$   $I_{$ 

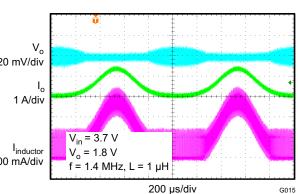


Figure 19. Load Sweep

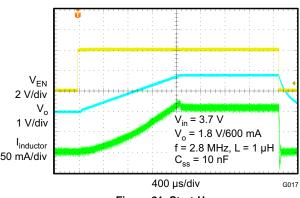
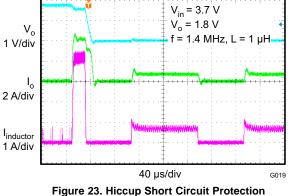
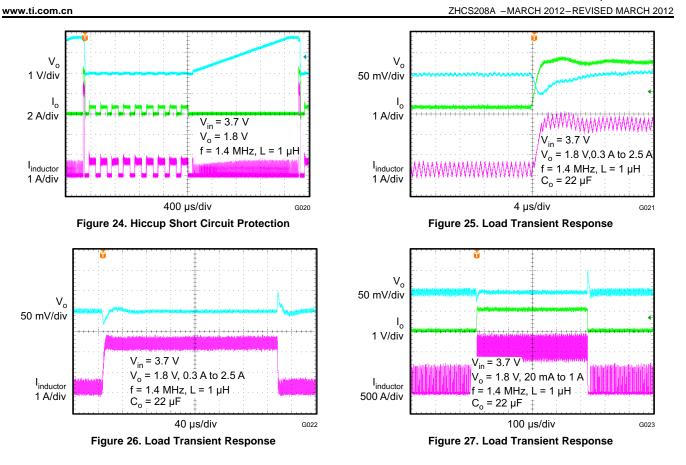


Figure 21. Start-Up



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## DETAILED DESCRIPTION

#### Operation

The TPS6209x synchronous switched mode converters are based on DCS<sup>™</sup> Control (Direct Control with Seamless transition into Power Save Mode). This is an advanced regulation topology that combines the advantages of hysteretic and voltage mode control.

The DCS<sup>™</sup> Control topology operates in PWM (Pulse Width Modulation) mode for medium to heavy load conditions and in Power Save Mode at light load currents. In PWM, the converter operates with its nominal switching frequency of 2.8 MHz/1.4 MHz having a controlled frequency variation over the input voltage range. As the load current decreases, the converter enters Power Save Mode, reducing the switching frequency and minimizing the IC quiescent current to achieve high efficiency over the entire load current range. DCS<sup>™</sup> Control supports both operation modes (PWM and PFM) using a single building block having a seamless transition from PWM to Power Save Mode without effects on the output voltage. Fixed output voltage versions provide smallest solution size combined with lowest quiescent current. The TPS6209x family offers excellent DC voltage regulation and load transient regulation, combined with low output voltage ripple, minimizing interference with RF circuits.

#### **PWM Operation**

At medium to heavy load currents, the device operates with pulse width modulation (PWM) at a nominal switching frequency of 2.8 MHz or 1.4 MHz depending on the setting of the FREQ pin. As the load current decreases, the converter enters the Power Save Mode operation reducing its switching frequency. The device enters Power Save Mode at the boundary to discontinuous conduction mode (DCM).

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As the load current decreases, the converter enters Power Save Mode operation. During Power Save Mode the converter operates with reduced switching frequency in PFM mode and with a minimum quiescent current while maintaining high efficiency. The Power Save Mode is based on a fixed on-time architecture following Equation 1. When operating at 1.4 MHz the on-time is twice as long as the on-time for 2.8 MHz operation. This results in larger output voltage ripple, as shown in Figure 17 and Figure 18, and slightly higher output voltage at no load, as shown in Figure 8 and Figure 9. To have the same output voltage ripple at 1.4 MHz during PFM mode, either the output capacitor or the inductor value needs to be increased. As an example, operating at 2.8 MHz using 0.47 µH inductor gives the same output voltage ripple as operating with 1.4 MHz using 1 µH inductor.

$$ton_{2.8MHz} = \frac{V_{OUT}}{V_{IN}} \times 360 \text{ ns}$$
$$ton_{1.4MHz} = \frac{V_{OUT}}{V_{IN}} \times 360 \text{ ns} \times 2$$
$$f = \frac{2 \times I_{OUT}}{ton^2 \left(1 + \frac{V_{IN} - V_{OUT}}{V_{OUT}}\right) \times \frac{V_{IN} - V_{OUT}}{L}$$

In Power Save Mode the output voltage rises slightly above the nominal output voltage in PWM mode, as shown in Figure 8 and Figure 9. This effect can be reduced by increasing the output capacitance or the inductor value. This effect can also be reduced by programming the output voltage of the TPS62090 lower than the target value. As an example, if the target output voltage is 3.3 V, then the TPS62090 can be programmed to 3.3 V - 0.8%. As a result the output voltage accuracy is now -2.2% to +2.2% instead of -1.4% to 3%. The output voltage accuracy in PFM operation is reflected in the electrical specification table and given for a 22 µF output capacitance.

#### Low Dropout Operation (100% Duty Cycle)

The device offers low input to output voltage difference by entering 100% duty cycle mode. In this mode the high side MOSFET switch is constantly turned on. This is particularly useful in battery powered applications to achieve longest operation time by taking full advantage of the whole battery voltage range. The minimum input voltage where the output voltage falls below its nominal regulation value is given by:

$$V_{IN(min)} = V_{OUT(max)} + I_{OUT} x (R_{DS(on)} + R_L)$$

Where

R<sub>DS(on)</sub> = High side FET on-resistance

 $R_L = DC$  resistance of the inductor

V<sub>OUT(max)</sub> = nominal output voltage plus maximum output voltage tolerance

#### Softstart (SS)

To minimize inrush current during start up, the device has an adjustable softstart depending on the capacitor value connected to the SS pin. The device charges the softstart capacitor with a constant current of typically 7.5  $\mu$ A. The feedback voltage follows this voltage with a fraction of 1.56 until the internal reference voltage of 0.8 V is reached. The softstart operation is completed once the voltage at the softstart capacitor has reached typically 1.25 V. The soft-start time can be calculated using Equation 3. The larger the softstart capacitor the longer the softstart time. The relation between softstart voltage and feedback voltage can be estimated using Equation 4.

$$t_{SS} = C_{SS} \times \frac{1.25V}{7.5\mu A}$$

$$V_{FB} = \frac{V_{SS}}{1.56}$$
(3)

This is also the case for the fixed output voltage option having the internal regulation voltage. Leaving the softstart pin floating sets the minimum start-up time.

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(2)

(1)





## Start-up Tracking (SS)

The softstart pin can also be used to implement output voltage tracking with other supply rails. The internal reference voltage follows the voltage at the softstart pin with a fraction of 1.56 until the internal reference voltage of 0.8 V is reached. The softstart pin can be used to implement output voltage tracking as shown in Figure 28.

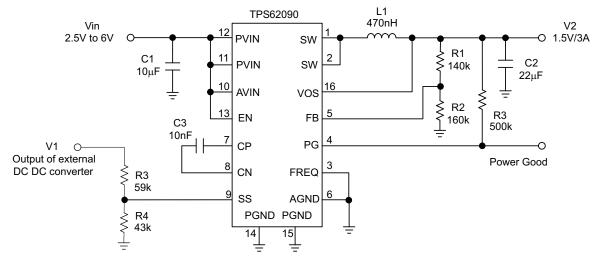


Figure 28. Output Voltage Tracking

In Figure 28, the output V2 will track the voltage applied to V1. The voltage will track simultaneously when following conditions are met:

$$\frac{R3}{R4} = \frac{R1}{R2} \times 1.56$$
(5)

As the fraction of R3/R4 becomes larger the voltage V1 will ramp up faster than V2 and if it gets smaller than the ramp will be slower than V2. R4 needs to be determined first using Equation 6.

$$R4 = \frac{1.25V}{300\mu A}$$
(6)

In the calculation of R4, 300  $\mu$ A current is used to achieve sufficient accuracy by taking into account the typical 7.5  $\mu$ A soft-start current. After determining R4, R3 can be calculated using Equation 5.

#### Short Circuit Protection (Hiccup-Mode)

The device is protected against hard short circuits to GND and over-current events. This is implemented by a two level short circuit protection. During start-up and when the output is shorted to GND the switch current limit is reduced to 1/3 of its typical current limit of 4.6 A. Once the output voltage exceeds typically 0.6 V the current limit is released to its nominal value. The full current limit is implemented as a hiccup current limit. Once the internal current limits is triggered 32 times the device stops switching and starts a new start-up sequence after a typical delay time of 66  $\mu$ S passed by. The device will go through these cycles until the high current condition is released.

#### **Output Discharge Function**

To make sure the device starts up under defined conditions, the output gets discharged via the VOS pin with a typical discharge resistor of 200  $\Omega$  whenever the device shuts down. This happens when the device is disabled or if thermal shutdown, undervoltage lockout or short circuit hiccup-mode is triggered.

#### Power Good Output (PG)

The power good output is low when the output voltage is below its nominal value. The power good will become high impedance once the output is within 5% of regulation. The PG pin is an open drain output and is specified to typically sink up to 1 mA. This output requires a pull-up resistor to be monitored properly. The pull-up resistor cannot be connected to any voltage higher than the input voltage of the device.

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#### Frequency Set Pin (FREQ)

The FREQ pin is a digital logic input which sets the nominal switching frequency. Pulling this pin to GND sets the nominal switching frequency to 2.8 MHz and pulling this pin high sets the nominal switching frequency to 1.4 MHz. Since this pin changes the switching frequency it also changes the on-time during PFM mode. At 1.4 MHz the on-time is twice the on-time as operating at 2.8 MHz. This pin has an active pull-down resistor of typically 400 k $\Omega$ . For applications where efficiency is of highest importance, a lower switching frequency should be selected. A higher switching frequency allows the use of smaller external components, faster load transient response and lower output voltage ripple when using same L-C values.

#### Undervoltage Lockout (UVLO)

To avoid mis-operation of the device at low input voltages, an undervoltage lockout is included. UVLO shuts down the device at input voltages lower than typically 2.2 V with a 200 mV hysteresis.

#### **Thermal Shutdown**

The device goes into thermal shutdown once the junction temperature exceeds typically 150°C with a 20°C hysteresis.

#### APPLICATION INFORMATION

#### DESIGN PROCEDURE

The first step is the selection of the output filter components. To simplify this process, Table 2 and Table 3 outline possible inductor and capacitor value combinations.

		OUTPUT C	APACITOR V	ΑLUE [μF] <sup>(2)</sup>	
INDUCTOR VALUE [µH] <sup>(1)</sup>	10	22	47	100	150
0.47		√ <sup>(3)</sup>	$\checkmark$	$\checkmark$	$\checkmark$
1.0	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$
2.2					
3.3					

Table 2. Output Filter Selection (2.8 MHz Operation, FREQ = GND)

(1) Inductor tolerance and current de-rating is anticipated. The effective inductance can vary by +20% and -30%.

(2) Capacitance tolerance and bias voltage de-rating is anticipated. The effective capacitance can vary by +20% and -50%.

(3) Typical application configuration. Other check mark indicates alternative filter combinations

		OUTPUT C	APACITOR V	ΑLUE [μF] <sup>(2)</sup>	
INDUCTOR VALUE [µH] <sup>(1)</sup>	10	22	47	100	150
0.47		$\checkmark$	$\checkmark$	$\checkmark$	
1.0	$\checkmark$	√(3)	$\checkmark$	$\checkmark$	
2.2	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$
3.3					

Table 3. Output Filter Selection (1.4 MHz Operation, FREQ =  $V_{IN}$ )

(1) Inductor tolerance and current de-rating is anticipated. The effective inductance can vary by +20% and -30%.

(2) Capacitance tolerance and bias voltage de-rating is anticipated. The effective capacitance can vary by +20% and -50%.

(3) Typical application configuration. Other check mark indicates alternative filter combinations



#### Inductor Selection

The inductor selection is affected by several parameter like inductor ripple current, output voltage ripple, transition point into Power Save Mode, and efficiency. See Table 4 for typical inductors.

INDUCTOR VALUE	COMPONENT SUPPLIER	SIZE (LxWxH mm)	Isat/DCR
0.6 µH	Coilcraft XAL4012-601	4 x 4 x 2.1	7.1A/9.5 mΩ
1 µH	Coilcraft XAL4020-102	4 x 4 x 2.1	5.9A/13.2 mΩ
1 µH	Coilcraft XFL4020-102	4 x 4 x 2.1	5.1 A/10.8 mΩ
0.47 µH	TOKO DFE252012 R47	2.5 x 2 x 1.2	3.7A/39 mΩ
1 µH	TOKO DFE252012 1R0	2.5 x 2 x 1.2	3.0A/59 mΩ
0.68 µH	TOKO DFE322512 R68	3.2 x 2.5 x 1.2	3.5A/37 mΩ
1 µH	TOKO DFE322512 1R0	3.2 x 2.5 x 1.2	3.1A/45 mΩ

#### **Table 4. Inductor Selection**

In addition, the inductor has to be rated for the appropriate saturation current and DC resistance (DCR). The inductor needs to be rated for a saturation current as high as the typical switch current limit, of 4.6 A or according to Equation 7 and Equation 8 calculate the maximum inductor current under static load conditions. The formula takes the converter efficiency into account. The converter efficiency can be taken from the data sheet graph's or 80% can be used as a conservative approach. The calculation must be done for the maximum input voltage where the peak switch current is highest.

$$I_{L} = I_{OUT} + \frac{\frac{\Delta I_{L}}{2}}{\eta} x \left(1 - \frac{V_{OUT}}{V_{IN} x \eta}\right)$$

$$I_{L} = I_{OUT} + \frac{\frac{V_{OUT}}{\eta} x \left(1 - \frac{V_{OUT}}{V_{IN} x \eta}\right)}{2 x f x L}$$
(8)

where

f = Converter switching frequency (typical 2.8 MHz or 1.4 MHz)

L = Selected inductor value

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 $\eta$  = Estimated converter efficiency (use the number from the efficiency curves or 0.80 as an conservative assumption)

Note: The calculation must be done for the maximum input voltage of the application

Calculating the maximum inductor current using the actual operating conditions gives the minimum saturation current. A margin of 20% needs to be added to cover for load transients during operation.

#### Input and Output Capacitor Selection

For best output and input voltage filtering, low ESR ceramic capacitors are recommended. The input capacitor minimizes input voltage ripple, suppresses input voltage spikes and provides a stable system rail for the device. A 22  $\mu$ F or larger input capacitor is recommended for 1.4 MHz operation frequency. For 2.8 MHz operation frequence a 10  $\mu$ F input capacitor or larger is recommended. The output capacitor value can range from 10  $\mu$ F up to 150  $\mu$ F and beyond. The recommended typical output capacitor value is 22  $\mu$ F and can vary over a wide range as outline in the output filter selection table.

INPUT CAPACITOR	COMMENT
10 µF	FREQ=low, f=2.8 MHz
22 µF	FREQ=high, f=1.4 MHz

Table 5. Input Ca	apacitor Selection
-------------------	--------------------

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The output voltage is set by an external resistor divider according to the following equations:

$$V_{OUT} = V_{FB} \times \left(1 + \frac{R1}{R2}\right) = 0.8 \text{ V} \times \left(1 + \frac{R1}{R2}\right)$$

$$R2 = \frac{V_{FB}}{I_{FB}} = \frac{0.8 \text{ V}}{5 \text{ µA}} \approx 160 \text{ k}\Omega$$
(9)

$$R1 = R2 \times \left(\frac{V_{OUT}}{V_{FB}} - 1\right) = R2 \times \left(\frac{V_{OUT}}{0.8V} - 1\right)$$
(10)  
(11)

When sizing R2, in order to achieve low quiescent current and acceptable noise sensitivity, use a minimum of 5  $\mu$ A for the feedback current I<sub>FB</sub>. Larger currents through R2 improve noise sensitivity and output voltage accuracy. Lowest quiescent current and best output voltage accuracy can be achieved with the fixed output voltage versions. For the fixed output voltage versions, the FB pin can be left floating or connected to GND to improve the thermal package performance.

## Layout Guideline

**TYPICAL APPLICATIONS** 

It is recommended to place all components as close as possible to the IC. The VOS connection is noise sensitive and needs to be routed as short and directly to the output terminal of the inductor. The exposed thermal pad of the package, analog ground (pin 6) and power ground (pin 14, 15) should have a single joint connection at the exposed thermal pad of the package. This minimizes switch node jitter. The charge pump capacitor connected to CP and CN should be placed close to the IC to minimize coupling of switching waveforms into other traces and circuits. Refer to the evaluation module User Guide (SLVU670) for an example of component placement, routing and thermal design.

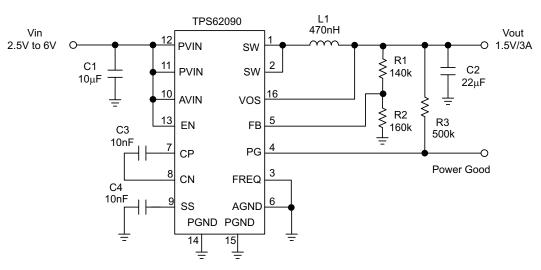
#### L1 TPS62090 470nH Vin Vout 2.5V to 6V O PVIN 1.2V/3A SW 0 R1 Ş C1 2 11 C2 **PVIN** SW 75k 10µF 22µF 10 AVIN VOS ÷ R2 Ş 13 R3 ΕN FB 150k C3 500k 10nF 7 CP PG O Power Good 8 CN FREQ C4 10nF SS AGNE PGND PGND Ξ 14 15

Figure 29. 1.2 V Adjustable Version Operating at 2.8 MHz

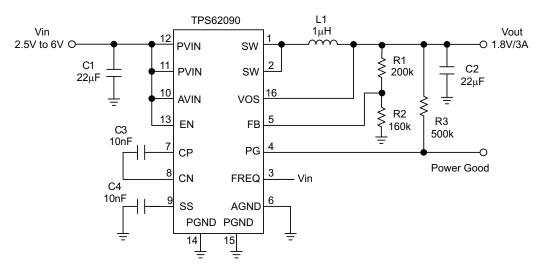
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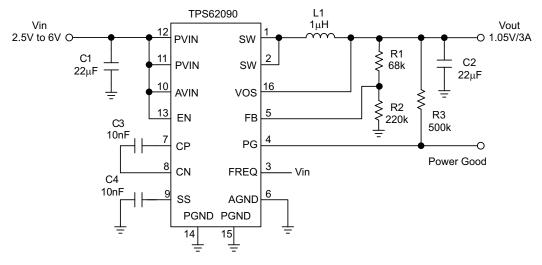


Figure 32. 1.05 V Adjustable Version Operating at 1.4 MHz



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## **REVISION HISTORY**

Changes from Original (March 2012) to Revision A							
•	Changed the FUNCTIONAL BLOCK DIAGRAM	5					
•	Changed R1, R2 and R4 values in Figure 28	13					
•	Changed R1 and R2 values in Figure 29	16					



# PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan	Lead finish/ Ball material	MSL Peak Temp	Op Temp (°C)	Device Marking (4/5)	Samples
	( )						(6)	(-)			
TPS62090RGTR	ACTIVE	VQFN	RGT	16	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	SBW	Samples
TPS62090RGTT	ACTIVE	VQFN	RGT	16	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	SBW	Samples
TPS62091RGTR	ACTIVE	VQFN	RGT	16	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	SBX	Samples
TPS62091RGTT	ACTIVE	VQFN	RGT	16	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	SBX	Samples
TPS62092RGTR	ACTIVE	VQFN	RGT	16	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	SBY	Samples
TPS62092RGTT	ACTIVE	VQFN	RGT	16	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	SBY	Samples
TPS62093RGTR	ACTIVE	VQFN	RGT	16	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	SBZ	Samples
TPS62093RGTT	ACTIVE	VQFN	RGT	16	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	SBZ	Samples

<sup>(1)</sup> The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW**: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

<sup>(3)</sup> MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

<sup>(4)</sup> There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

<sup>(5)</sup> Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.



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(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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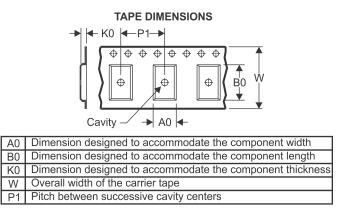
# PACKAGE MATERIALS INFORMATION

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## TAPE AND REEL INFORMATION





## QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



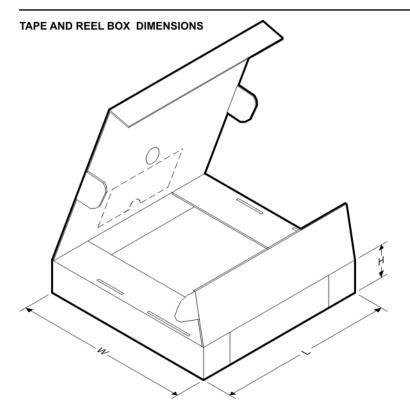
Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPS62090RGTR	VQFN	RGT	16	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
TPS62090RGTR	VQFN	RGT	16	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
TPS62090RGTT	VQFN	RGT	16	250	180.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
TPS62090RGTT	VQFN	RGT	16	250	180.0	12.5	3.3	3.3	1.1	8.0	12.0	Q2
TPS62091RGTR	VQFN	RGT	16	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
TPS62091RGTR	VQFN	RGT	16	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
TPS62091RGTT	VQFN	RGT	16	250	180.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
TPS62091RGTT	VQFN	RGT	16	250	180.0	12.5	3.3	3.3	1.1	8.0	12.0	Q2
TPS62092RGTR	VQFN	RGT	16	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
TPS62092RGTT	VQFN	RGT	16	250	180.0	12.5	3.3	3.3	1.1	8.0	12.0	Q2
TPS62093RGTR	VQFN	RGT	16	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
TPS62093RGTT	VQFN	RGT	16	250	180.0	12.5	3.3	3.3	1.1	8.0	12.0	Q2



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# PACKAGE MATERIALS INFORMATION

27-Oct-2021



*All dimensions are nominal							
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPS62090RGTR	VQFN	RGT	16	3000	338.0	355.0	50.0
TPS62090RGTR	VQFN	RGT	16	3000	367.0	367.0	35.0
TPS62090RGTT	VQFN	RGT	16	250	210.0	185.0	35.0
TPS62090RGTT	VQFN	RGT	16	250	338.0	355.0	50.0
TPS62091RGTR	VQFN	RGT	16	3000	338.0	355.0	50.0
TPS62091RGTR	VQFN	RGT	16	3000	367.0	367.0	35.0
TPS62091RGTT	VQFN	RGT	16	250	210.0	185.0	35.0
TPS62091RGTT	VQFN	RGT	16	250	338.0	355.0	50.0
TPS62092RGTR	VQFN	RGT	16	3000	338.0	355.0	50.0
TPS62092RGTT	VQFN	RGT	16	250	338.0	355.0	50.0
TPS62093RGTR	VQFN	RGT	16	3000	338.0	355.0	50.0
TPS62093RGTT	VQFN	RGT	16	250	338.0	355.0	50.0

# **GENERIC PACKAGE VIEW**

# VQFN - 1 mm max height PLASTIC QUAD FLATPACK - NO LEAD



Images above are just a representation of the package family, actual package may vary. Refer to the product data sheet for package details.



# **RGT0016C**



# **PACKAGE OUTLINE**

# VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



#### NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M. 2. This drawing is subject to change without notice.
- 3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

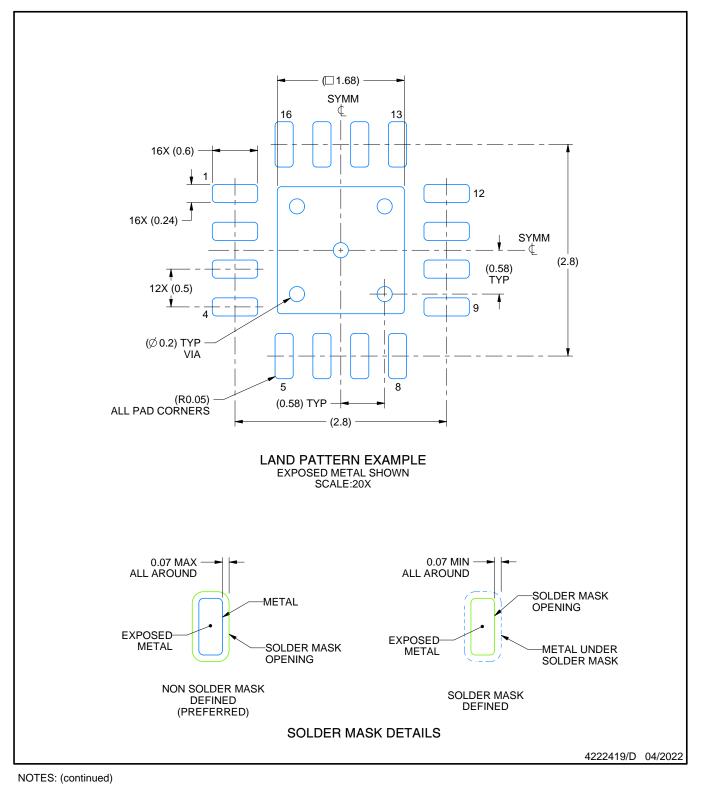


# **RGT0016C**

# **EXAMPLE BOARD LAYOUT**

# VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).

5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.



# **RGT0016C**

# **EXAMPLE STENCIL DESIGN**

# VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



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