











LMX2491

ZHCSFL5A - OCTOBER 2016-REVISED JANUARY 2017

LMX2491 具有斜坡/线性调频生成功能的 6.4GHz 低噪声 RF PLL

特性

- -227dBc/Hz 标准化锁相环 (PLL) 噪声
- 500MHz 至 6.4GHz 宽带 PLL
- 3.15V 至 5.25V 电荷泵 PLL 电源
- 多用途斜坡/超宽带信号源生成功能
- 200MHz 最大相位检测器频率
- 频移键控/相移键控 (FSK/PSK) 调制引脚
- 数字锁检测
- 3.3V 单电源供电

应用

- 调频连续波 (FMCW) 雷达
- 军用雷达
- 微波回程
- 测试和测量
- 卫星通信
- 无线基础设施
- 适用于高速模数转换器/数模转换器 (ADC/DAC) 的 采样时钟

3 说明

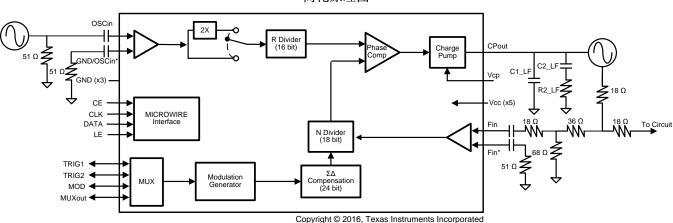
LMX2491 器件是一款具有斜坡/线性调频生成功能的低 噪声 6.4GHz 宽带 Δ - Σ 分数 N PLL。它由一个相位频 率检测器、可编程电荷泵以及适用于外部 VCO 的高频 输入组成。LMX2491 广泛支持各类灵活的斜坡功能, 包括 FSK、PSK 和多达 8 段的可配置分段线性 FM 调 制配置文件。该器件具有精密 PLL 分辨率和快速斜升 功能,相位检测器速率高达 200MHz。LMX2491 允许 读回其任一寄存器。LMX2491 可由 3.3V 单电源供电 运行。此外,该器件支持电压高达 5.25V 的电荷泵, 无需使用外部放大器即可提供相位噪声性能得到改善的 简易解决方案。

器件信息

器件编号	封装	封装尺寸 (标称值)
LMX2491	WQFN (24)	4.00mm x 4.00mm

(1) 要了解所有可用封装,请见数据表末尾的可订购产品附录。

简化原理图





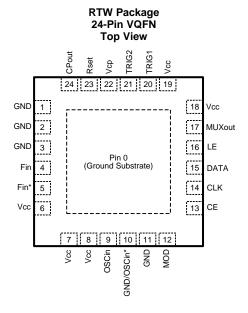
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4 修订历史记录

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Deleted Charge pump output pin from the table	4
Changed to Supply voltage	
Changed to I/O input voltage	4
Changed to Power down current	5
Changed DATA field bit description	6
Added new plots in Typical Characteristics	7
Changed Table 1 title	9
Added CMP0 and CMP1 definition. Changed Equation 1 description.	12
Added Register Readback	13
Added MSB bit description	14
Changed the format in Window and f _{PD} Frequency column	21
Changed to correct register bits location	23
Changed to correct value	25
Added correct start time	26
Added design details and plots in Typical Application	27



5 Pin Configuration and Functions



Pin Functions

TERMINAL		TVDE	DECODINE	
NO.	NAME	TYPE	DESCRIPTION	
0	DAP	GND	Die Attach Pad. Connect to PCB ground plane.	
1	GND	GND	Ground for charge pump.	
2, 3	GND	GND	round for Fin Buffer	
4, 5	Fin Fin*	Input	complimentary high frequency input pins. Should be AC-coupled. If driving single-ended, inpedance as seen from Fin and Fin* pins looking outwards from the part should be roughly the lame.	
6	Vcc	Supply	Power Supply for Fin Buffer	
7	Vcc	Supply	Supply for On-chip LDOs	
8	Vcc	Supply	Supply for OSCin Buffer	
9	OSCin	Input	Reference Frequency Input	
10	GND/ OSCin*	GND/Input	Complimentary input for OSCin. If not used, it is recommended to match the termination as seen from the OSCin terminal looking outwards. However, this may also be grounded as well.	
11	GND	GND	Ground for OSCin Buffer	
12	MOD	Input/Output	Multiplexed Input/Output Pins for Ramp Triggers, FSK/PSK Modulation, FastLock, and Diagnostics	
13	CE	Input	Chip Enable	
14	CLK	GND	Serial Programming Clock.	
15	DATA	GND	Serial Programming Data	
16	LE	Input	Serial Programming Latch Enable	
17	MUXout	Input/Output	Multiplexed Input/Output Pins for Ramp Triggers, FSK/PSK Modulation, FastLock, and Diagnostics	
18	Vcc	Supply	Supply for delta sigma engine.	
19	Vcc	Supply	Supply for general circuitry.	
20	TRIG1	Input/Output	Multiplexed Input/Output Pins for Ramp Triggers, FSK/PSK Modulation, FastLock, and Diagnostics	
21	TRIG2	Input/Output	Multiplexed Input/Output Pins for Ramp Triggers, FSK/PSK Modulation, FastLock, and Diagnostics	
22	Vcp	Supply	Power Supply for the charge pump.	
23	Rset	NC	No connect.	
24	CPout	Output	Charge Pump Output	



6 Specifications

6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted) (1)

		MIN	MAX	UNIT
V _{CP}	Supply voltage for charge pump	V _{CC}	5.5	V
V _{CC}	Supply voltage	-0.3	3.6	V
V _{IN}	I/O input voltage	-0.3	V _{CC} + 0.3	V
T _{Solder}	Lead temperature (solder 4 seconds)		260	°C
T _{Junction}	Junction temperature		150	°C

⁽¹⁾ Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

6.2 Storage Conditions

applicable before the DMD is installed in the final product

		MIN	MAX	UNIT
T _{stg}	DMD storage temperature	-65	150	°C
T_{DP}	Storage dew point		3	٥°

6.3 ESD Ratings

			VALUE	UNIT
\/	Floatroatatia diaaharaa	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 (1)	±2500	V
V _(ESD)	Electrostatic discharge	Charged-device model (CDM), per JEDEC specification JESD22-C101 (2)	±1500	V

¹⁾ JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

6.4 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

	PARAMETER	MIN	NOM	MAX	UNIT
V _{CC}	Supply voltage	3.15	3.3	3.45	V
V_{CP}	Charge pump supply voltage	V _{CC}		5.25	V
T _A	Ambient temperature	-40		85	°C
T_{J}	Junction temperature	-40		125	°C

6.5 Thermal Information

		LMX2491	
	THERMAL METRIC ⁽¹⁾	RTW (VQFN)	UNIT
		24 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	39.4	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	7.1	°C/W
ΨЈВ	Junction-to-board characterization parameter	20	°C/W

For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.

⁽²⁾ JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.



6.6 Electrical Characteristics

 $3.15~\text{V} \leq \text{V}_{\text{CC}} \leq 3.45~\text{V},~\text{V}_{\text{CC}} \leq \text{V}_{\text{CP}} \leq 5.25~\text{V},~-40~\text{°C} \leq \text{T}_{\text{A}} \leq 85~\text{°C},~\text{except as specified}.~\text{Typical values are at V}_{\text{CC}} = \text{V}_{\text{CP}} = 3.3~\text{V},~\text{V}_{\text{CC}} \leq \text{V}_{\text{CP}} \leq 5.25~\text{V},~\text{C}_{\text{CP}} \leq 5.25~\text{V},~\text{C}_{\text{CP}} \leq 85~\text{°C},~\text{except as specified}.$

	PARAMETER	TEST CO	ONDITIONS	MIN	TYP	MAX	UNIT
			f _{PD} = 10 MHz		45		
		All Vcc pins	f _{PD} = 100 MHz		50		
	Current consumption		f _{PD} = 200 MHz		55		mA
I _{CC}			$K_{PD} = 0.1 \text{ mA}$		2		
		Vcp pin	K _{PD} = 1.6 mA		10		
			K _{PD} = 3.1 mA		19		
I _{CC} PD	Power down current	POWERDOWN			3		
		OSC_DIFFR = 0,	doubler disabled	10		600	
	Frequency for OSCin	OSC_DIFFR = 0,	doubler enabled	10		300	
f _{OSCin}	terminal	OSC_DIFFR = 1,	doubler disabled	10		1200	MHz
		OSC_DIFFR = 1,	doubler enabled	10		600	
V _{OSCin}	Voltage for OSCin pin ⁽¹⁾			0.5		V _{CC} - 0.5	V _{PP}
f _{Fin}	Frequency for Fin pin			500		6400	MHz
P _{Fin}	Power for Fin pin	Single-ended ope	Single-ended operation			5	dBm
f _{PD}	Phase detector frequency					200	MHz
PN1Hz	PLL figure of merit ⁽²⁾				-227		dBc/Hz
PN10kHz	Normalized PLL 1/f noise ⁽²⁾	Normalized to 10 GHz carrier.	Normalized to 10-kHz offset for a 1-GHz carrier.		-120		dBc/Hz
I _{CPout} TRI	Charge pump leakage tri- state leakage					10	nA
I _{CPout} MM	Charge pump mismatch (3)	V _{CPout} = V _{CP} / 2			5%		
			CPG = 1X		0.1		
I _{CPout}	Charge pump current	$V_{CPout} = V_{CP} / 2$					mA
			CPG = 31X		3.1		
LOGIC OU	TPUT TERMINALS (MUXout,	TRIG1, TRIG2, MO	DD)			<u> </u>	
V _{OH}	Output high voltage			0.8 × V _{CC}	V _{CC}		V
V _{OL}	Output low voltage				0	0.2 × V _{CC}	V
LOGIC INP	UT TERMINALS (CE, CLK, DA	ATA, LE, MUXout	TRIG1, TRIG2, MO	D)		*	
V _{IH}	Input high voltage			1.4		V _{CC}	V
V _{IL}	Input low voltage					0.6	V
I _{IH}	Input leakage current			-5	1	5	μA
t _{CE} LOW	Chip enable low time			5			μs

⁽¹⁾ For optimal phase noise performance, higher input voltage and a slew rate of at least 3 V/ns is recommended

PLL Noise Metrics are measured with a clean OSCin signal with a high slew rate using a wide loop bandwidth. The noise metrics model the PLL noise for an infinite loop bandwidth as:

PLL_Total = 10 × log(10^{PLL_Flat / 10} + 10^{PLL_Flicker(Offset) / 10})

PLL_Flat = PN1Hz + 20 × log(N) + 10 × log(f_{PD} / 1 Hz)

PLL_Flicker = PN10kHz - 10 × log(Offset / 10 kHz) + 20 × log(f_{VCO} / 1 GHz)

(3) Charge pump mismatch varies as a function of charge pump voltage. Consult typical performance characteristics to see this variation.



6.7 Timing Requirements, Programming Interface (CLK, DATA, LE)

		MIN	TYP	MAX	UNIT
t _{CE}	Clock to LE low time	10			ns
t _{CS}	Data to clock setup time	4			ns
t _{CH}	Data to clock hold time	4			ns
t _{CWH}	Clock pulse width high	10			ns
t _{CWL}	Clock pulse width low	10			ns
t _{CES}	Enable to clock setup time	10			ns
t _{EWH}	Enable pulse width high	10			ns

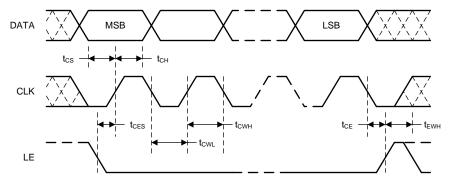
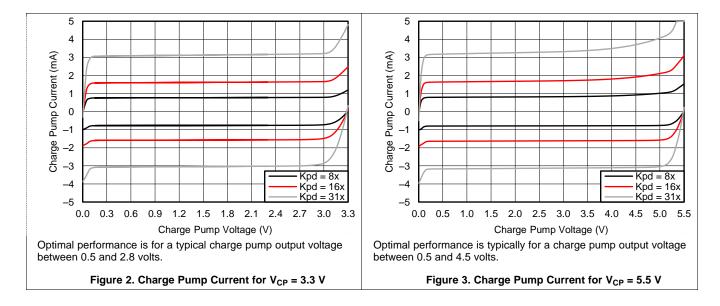


Figure 1. Serial Data Input Timing

There are several other considerations for programming:

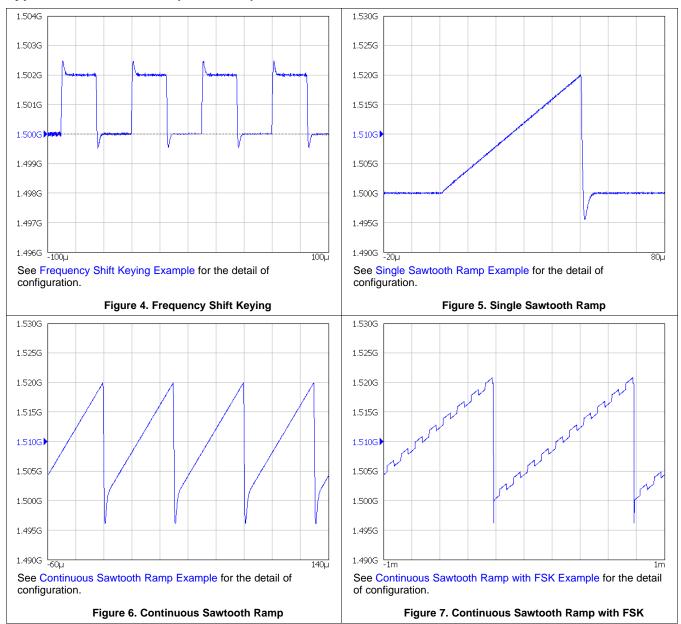
- The DATA is clocked into a shift register on each rising edge of the CLK signal. On the rising edge of the LE signal, the data is sent from the shift register to an actual counter.
- If no LE signal is given after the last data bit and the clock is kept toggling, then these bits are read into the next lower register. This eliminates the need to send the address each time.
- A slew rate of at least 30 V/µs is recommended for the CLK, DATA, and LE signals
- Timing specs also apply to readback. Readback can be done through the MUXout, TRIG1, TRIG2, or MOD terminals.

6.8 Typical Characteristics



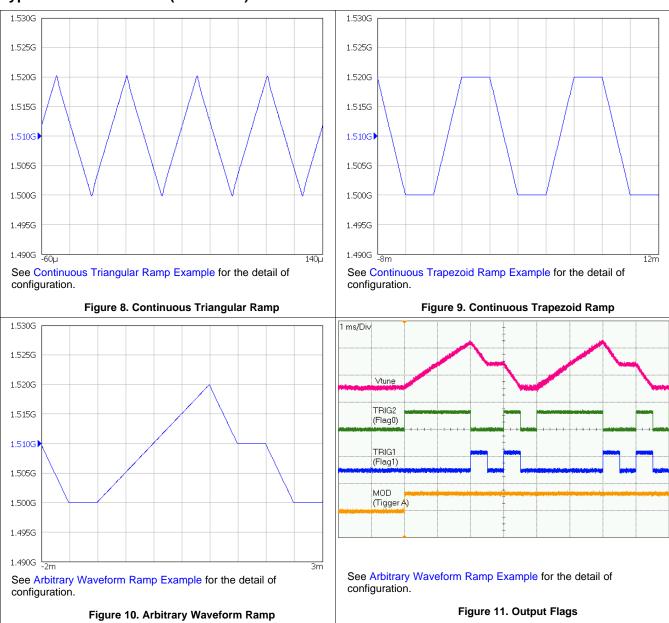


Typical Characteristics (continued)



TEXAS INSTRUMENTS

Typical Characteristics (continued)



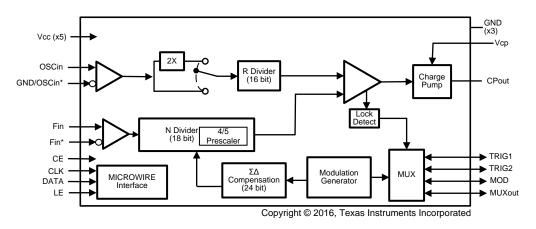


7 Detailed Description

7.1 Overview

The LMX2491 is a microwave PLL, consisting of a reference input and divider, high frequency input and divider, charge pump, ramp generator, and other digital logic. The Vcc power supply pins run at a nominal 3.3 volts, while the charge pump supply pin, Vcp, operates anywhere from V_{CC} to 5 volts. The device is designed to operate with an external loop filter and VCO. Modulation is achieved by manipulating the MASH engine.

7.2 Functional Block Diagram



7.3 Feature Description

7.3.1 OSCin Input

The reference can be applied in several ways. If using a differential input, this must be terminated differentially with a $100-\Omega$ resistance and AC-coupled to the OSCin and GND/OSCin* terminals. If driving this single-ended, then the GND/OSCin* terminal may be grounded, although better performance is attained by connecting the GND/OSCin* terminal through a series resistance and capacitance to ground to match the OSCin terminal impedance.

7.3.2 OSCin Doubler

The OSCin doubler allows the input signal to the OSCin to be doubled to have higher phase detector frequencies. This works by clocking on both the rising and falling edges of the input signal, so it therefore requires a 50% input duty cycle.

7.3.3 R Divider

The R counter is 16 bits divides the OSCin signal from 1 to 65535. If DIFF_R = 0, then any value can be chosen in this range. If DIFF_R = 1, then the divide is restricted to 2, 4, 8, and 16, but allows for higher OSCin frequencies.

7.3.4 PLL N Divider

The 16-bit N divider divides the signal at the Fin terminal down to the phase detector frequency. It contains a 4/5 prescaler that creates minimum divide restrictions, but allows the N value to increment in values of one.

Table 1. Allowable Minimum N Divider Values

MODULATOR ORDER	MINIMUM N DIVIDE
Integer Mode, 1st-Order Modulator	16
2nd-Order Modulator	17
3rd-Order Modulator	19
4th-Order Modulator	25



7.3.5 Fractional Circuitry

The fractional circuitry controls the N divider with delta sigma modulation that supports a programmable first, second, third, and fourth-order modulator. The fractional denominator is a fully programmable 24-bit denominator that can support any value from 1, 2, ..., 2^{24} , with the exception when the device is running one of the ramps, and in this case it is a fixed size of 2^{24} .

7.3.6 PLL Phase Detector and Charge Pump

The phase detector compares the outputs of the R and N dividers and generates a correction voltage corresponding to the phase error. This voltage is converted to a correction current by the charge pump. The phase detector frequency, f_{PD} , can be calculated as follows: $f_{PD} = f_{OSC_{in}} \times OSC_{2X} / R$.

The charge pump supply voltage on this device, V_{CP} , can be either run at the V_{CC} voltage, or up to 5.25 volts to get higher tuning voltages to present to the VCO.

7.3.7 External Loop Filter

The loop filter is external to the device and is application specific. Texas Instruments website has details on this at www.ti.com.

7.3.8 Fastlock and Cycle Slip Reduction

This PLL has a Fastlock and a cycle slipping reduction feature. The user can enable these two features by programming FL_TOC to a non-zero value. Every time PLL_N (the feedback divider, register R17 and R16) is written, the Fastlock feature engages for the prescribed time set in FL_TOC. There are 3 actions that can be enabled while the counter is running:

- 1. Change the charge pump current to the desired higher value FL_CPG. Typically this value would be set to the maximum at 31x. This increases the loop bandwidth and hence reduces lock time.
- 2. Change the phase detector frequency with FL_CSR to reduce cycle slipping. The phase detector frequency can be reduced by a factor 2 or 4 to reduce cycle slipping.
- 3. The loop filter can be configured to have a switchable R2 resistor to increase loop bandwidth and hence reduce lock time. A resistor R2pLF is added in parallel to R2_LF and connected to the a terminal on the PLL to use the internal switch. Any of the terminal MUXout, MOD, TRIG1,or TRIG2 can be configured for the function. The terminal configuration is set as *Output TOC Running*. Also set the terminal as *output inverted OD* (OD for open-drain) so the output will be high impedance in normal operation and act as ground in Fastlock. The suggested schematic for that feature is shown in Figure 12.

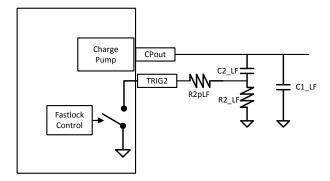


Figure 12. Suggested Schematic to Enable the Variable Loop Bandwidth Filter In Fastlock Mode

 Table 2. Fastlock Settings: Charge Pump Gain and Fastlock Pin Status

PARAMETER	NORMAL OPERATION	FASTLOCK OPERATION
Charge Pump Gain	CPG	FL_CPG
Device Pin (TRIG1, TRIG2, MOD, or MUXout)	High Impedance	Grounded



The resistor and the charge pump current are changed simultaneously so that the phase margin remains the same while the loop bandwidth is by a factor of K as shown in the following table:

Table 3. Suggested Equations to Calculate R2pLF

	PARAMETER	CALCULATION
FL_CPG	Charge Pump Gain in Fastlock	Typically use the highest value.
K	Loop Bandwidth Multiplier	K = sqrt(FL_CPG / CPG)
R2pLF	External Resistor	R2 / (K - 1)

Cycle slip reduction is another method that can also be used to speed up lock time by reducing cycle slipping. Cycle slipping typically occurs when the phase detector frequency exceeds about 100x the loop bandwidth of the PLL. Cycle slip reduction works in a different way than fastlock. To use this, the phase detector frequency is decreased while the charge pump current is simultaneously increased by the same factor. Although the loop bandwidth is unchanged, the ratio of the phase detector frequency to the loop bandwidth is, and this is helpful for cases when the phase detector frequency is high. Because cycle slip reduction changes the phase detector rate, it also impacts other things that are based on the phase detector rate, such as the fastlock timeout-counter and ramping controls.

7.3.9 Lock Detect and Charge Pump Voltage Monitor

The LMX2491 offers two methods to determine if the PLL is in lock: charge pump voltage monitoring and digital lock detect. These features can be used individually or in conjunction to give a reliable indication of when the PLL is in lock. The output of this detection can be routed to the TRIG1, TRIG2, MOD, or MUXout terminals.

7.3.9.1 Charge Pump Voltage Monitor

The charge pump voltage monitor allows the user to set low (CMP_THR_LOW) and high (CMP_THR_HIGH) thresholds for a comparator that monitors the charge pump output voltage.

Table 4. Desired Comparator Threshold Register Settings for Two Charge Pump Supplies

V _{CP}	THRESHOLD	SUGGESTED LEVEL	
3.3 V	CPM_THR_LOW = (Vthresh + 0.08) / 0.085	6 for 0.5-V limit	
3.3 V	CPM_THR_HIGH = (Vthresh - 0.96) / 0.044	42 for 2.8-V limit	
5.0 V	CPM_THR_LOW = (Vthresh + 0.056) / 0.137	4 for 0.5-V limit	
5.0 V	CPM_THR_HIGH = (Vthresh -1.23) / 0.071	46 for 4.5-V limit	

7.3.9.2 Digital Lock Detect

Digital lock detect works by comparing the phase error as presented to the phase detector. If the phase error plus the delay as specified by the PFD_DLY bit is outside the tolerance as specified by DLD_TOL, then this comparison would be considered to be an error, otherwise passing. The DLD_ERR_CNT specifies how may errors are necessary to cause the circuit to consider the PLL to be unlocked. The DLD_PASS_CNT specifies how many passing comparisons are necessary to cause the PLL to be considered to be locked and also resets the count for the errors. The DLD_TOL value should be set to no more than half of a phase detector period plus the PFD_DLY value. The DLD_ERR_CNT and DLD_PASS_CNT values can be decreased to make the circuit more sensitive. If the circuit is too sensitive, then chattering can occur and the DLD_ERR_CNT, DLD_PASS_CNT, or DLD_TOL values should be increased.

NOTE

If the OSCin signal goes away and there is no noise or self-oscillation at the OSCin pin, then it is possible for the digital lock detect to indicate a locked state when the PLL really is not in lock. If this is a concern, then digital lock detect can be combined with charge pump voltage monitor to detect this situation.



7.3.10 FSK/PSK Modulation

Two-level FSK or PSK modulation can be created whenever a trigger event, as defined by the FSK_TRIG field is detected. This trigger can be defined as a transition on a terminal (TRIG1, TRIG2, MOD, or MUXout) or done purely in software. The RAMP_PM_EN bit defines the modulation to be either FSK or PSK and the FSK_DEV register determines the amount of the deviation. Remember that the FSK_DEV[32:0] field is programmed as the 2's complement of the actual desired FSK_DEV value. This modulation can be added to the modulation created from the ramping functions as well.

Table 5. How to Obtain Deviation for Two Types of Modulation

RAMP_PM_EN	MODULATION TYPE	DEVIATION
0	2 Level FSK	f _{PD} × FSK_DEV / 2 ²⁴
1	2 Level PSK	360° × FSK_DEV / 2 ²⁴

7.3.11 Ramping Functions

The LMX2491 supports a broad and flexible class of FMCW modulation formed by up to 8 linear ramps. When the ramping function is running, the denominator is fixed to a forced value of $2^{24} = 16777216$. The waveform always starts at RAMP0 when the LSB of the PLL_N (R16) is written to. After it is set up, it starts at the initial frequency and have piecewise linear frequency modulation that deviates from this initial frequency as specified by the modulation. Each of the eight ramps can be individually programmed. Various settings are as follows:

Table 6. Register Descriptions of the Ramping Function

RAMP CHARACTERISTIC	PROGRAMMING FIELD NAME	DESCRIPTION				
Ramp Length	RAMPx_LEN RAMPx_DLY	The user programs the length of the ramp in phase detector cycles. If RAMPx_DLY = 1, then each count of RAMPx_LEN is actually two phase detector cycles.				
Ramp Slope	RAMPx_LEN RAMPx_DLY RAMPx_INC	The user does not directly program slope of the line, but rather this is done by defining how long the ramp is and how much the fractional numerator is increased per phase detector cycle. The value for RAMPx_INC is calculated by taking the total expected increase in the frequency, expressed in terms of how much the fractional numerator increases, and dividing it by RAMPx_LEN. The value programmed into RAMPx_INC is actually the two's complement of the desired mathematical value.				
Trigger for Next Ramp	RAMPx_NEXT_TRIG	The event that triggers the next ramp can be defined to be the ramp finishing or can wait for a trigger as defined by Trigger A, Trigger B, or Trigger C.				
Next Ramp	RAMPx_NEXT	This sets the ramp that follows. Waveforms are constructed by defining a charamp segments. To make the waveform repeat, make RAMPx_NEXT point the first ramp in the pattern.				
Ramp Fastlock	RAMPx_FL	This allows the ramp to use a different charge pump current or use Fastlock				
Ramp Flags	RAMPx_FLAG	This allows the ramp to set a flag that can be routed to external terminals to trigger other devices.				

7.3.11.1 Ramp Count

If it is desired that the ramping waveform keep repeating, then all that is needed is to make the RAMPx_NEXT of the final ramp equal to the first ramp. This runs until the RAMP_EN bit is set to zero. If this is not desired, then one can use the RAMP_COUNT to specify how may times the specified pattern is to repeat.

7.3.11.2 Ramp Comparators and Ramp Limits

The ramp comparators and ramp limits use programable thresholds to allow the device to detect whenever the modulated waveform frequency crosses a limit as set by the user. The difference between these is that comparators set a flag to alert the user while a ramp limits prevent the frequency from going beyond the prescribed threshold. In either case, these thresholds are expressed by programming the Extended_Fractional_Numerator. CMP0 and CMP1 are two separated comparators but they work in the same fashion.

Extended Fractional Numerator = Fractional Numerator + (N - N*) x 2²⁴

(1)



In Equation 1, N* is the PLL feedback value without ramping. Fractional Numerator and N are the new values as defined by the threshold frequency. The actual value programmed is the 2's complement of Extended Fractional Numerator.

Table 7 Register Descriptions of Ramp Comparators and Limits

	rabio i regioto	- Boodingtions of Kamp Comparators and Ellinto
PE	PROGRAMMING BIT	THRESHOLD
	DAMP LIMIT LOW	Lawrent Carlo

TYPE	PROGRAMMING BIT	THRESHOLD
Down Limite	RAMP_LIMIT_LOW	Lower Limit
Ramp Limits	RAMP_LIMIT_HIGH	Upper Limit
Ramp Comparators	RAMP_CMP0 RAMP_CMP1	For the ramp comparators, if the ramp is increasing and exceeds the value as specified by RAMP_CMPx, then the flag goes high, otherwise it is low. If the ramp is decreasing and goes below the value as specified by RAMP_CMPx, then the flag goes high, otherwise it is low.

7.3.12 Power-on-reset (POR)

The power-on-reset circuitry sets all the registers to a default state when the device is powered up. This same reset can be done by programming SWRST = 1. In the programming section, the power on reset state is given for all the programmable fields.

7.3.13 Register Readback

The LMX2491 allows any of its registers to be read back, MOD, MUXout, TRIG1 or TRIG2 pin can be programmed to support register-readback serial-data output. To read back a certain register value, follow the following steps:

- 1. Set the R/W bit to 1; the data field contents are ignored.
- 2. Send the register to the device; readback serial data will be output starting at the 17th clock cycle.

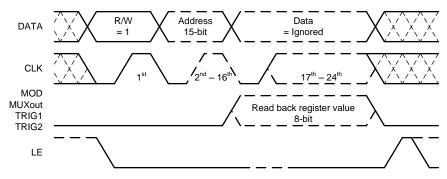


Figure 13. Register Readback Timing Diagram

7.4 Device Functional Modes

The two primary ways to use the LMX2491 are to run it to generate a set of frequencies

7.4.1 Continuous Frequency Generator

In this mode, the LMX2491 generates a single frequency that only changes when the N divider is programmed to a new value. In this mode, the RAMP EN bit is set to 0 and the ramping controls are not used. The fractional denominator can be programmed to any value from 1 to 16777216. In this kind of application, the PLL is tuned to different channels, but at each channel, the goal is to generate a stable fixed frequency.

7.4.1.1 Integer Mode Operation

In integer mode operation, the VCO frequency needs to be an integer multiple of the phase detector frequency. This can be the case when the output frequency or frequencies are nicely related to the input frequency. As a rule of thumb, if this an be done with a phase detector of as high as the lesser of 10 MHz or the OSCin frequency, then this makes sense. To operate the device in integer mode, disable the fractional circuitry by programming the fractional order (FRAC_ORDER), dithering (FRAC_DITH), and numerator (FRAC_NUM) to zero.



Device Functional Modes (continued)

7.4.1.2 Fractional Mode Operation

In fractional mode, the output frequency does not need to be an integer multiple of the phase detector frequency. This makes sense when the channel spacing is more narrow or the input and output frequencies are not nicely related. There are several programmable controls for this such as the modulator order, fractional dithering, fractional numerator, and fractional denominator. There are many trade-offs with choosing these, but here are some guidelines

Table 8. Fractional Mode Register Descriptions and Recommendations

PARAMETER	FIELD NAME	HOW TO CHOOSE
Fractional Numerator and Denominator	FRAC_NUM FRAC_DEN	The first step is to find the fractional denominator. To do this, find the frequency that divides the phase detector frequency by the channel spacing. For instance, if the output ranges from 5000 to 5050 in 5-MHz steps and the phase detector is 100 MHz, then the fractional denominator is 100 MHz / $5 = 20$. So for a an output of 5015 MHz, the N divider would be $50 + 3/20$. In this case, the fractional numerator is 3 and the fractional denominator is 20. Sometimes when dithering is used, it makes sense to express this as a larger equivalent fraction. Note that if ramping is active, the fractional denominator is forced to 2^{24} .
Fractional Order	FRAC_ORDER	There are many trade-offs, but in general try either the 2nd or 3rd-order modulator as starting points. The 3rd-order modulator may give lower main spurs, but may generate others. Also if dithering is involved, it can generate phase noise.
Dithering	FRAC_DITH	Dithering can reduce some fractional spurs, but add noise. Consult application note AN-1879 Fractional N Frequency Synthesis for more details on this.

7.4.2 Modulated Waveform Generator

In this mode, the device can generate a broad class of frequency sweeping waveforms. The user can specify up to 8 linear segments to generate these waveforms. When the ramping function is running, the denominator is fixed to a forced value of $2^{24} = 16777216$

In addition to the ramping functions, there is also the capability to use a terminal to add phase or frequency modulation that can be done by itself or added on top of the waveforms created by the ramp generation functions.

7.5 Programming

7.5.1 Loading Registers

The device is programmed using several 24-bit registers. Each register consists of a data field, an address field, and a R/W bit. The MSB is the R/W bit. 0 means register write while 1 means register read. The following 15 bits of the register are the address, followed by the next 8 bits of data. The user has the option to pull the LE terminal high after this data, or keep sending data and it applies this data to the next lower register. So instead of sending three registers of 24 bits each, one could send a single 40-bit register with the 16 bits of address and 24 bits of data. For that matter, the entire device could be programmed as a single register if desired.

7.6 Register Maps

Registers are programmed in REVERSE order from highest to lowest. Registers NOT shown in this table or marked as reserved can be written as all 0s unless otherwise stated. The POR value is the power on reset value that is assigned when the device is powered up or the SWRST bit is asserted.

Table 9. Register Map

REGI	STER	D7	D7 D6 D5 D4 D3 D2 D1 D0				POR			
0	0	0	0	0	1	1	0	0	0	0x18
1	0x1		Reserved							
2	0x2	0	0 0 0 0 SWRST POWERDOWN[1:0]							0x00
3 - 15	0x3 - 0xF		Reserved							
16	0x10		PLL_N[7:0]							



Register Maps (continued)

Table 9. Register Map (continued)

			510 01 1108	jiotoi iliap	(OOIIIIII	<i>-</i>			
ISTER	D7	D6	D5	D4	D3	D2	D1	D0	POR
0x11				PLL_N	l[15:8]				0x00
0x12	0	FRA	AC_ORDER[2:0]	FRAC_DI	THER[1:0]	PLL_N	I[17:16]	0x00
0x13				FRAC_N	IUM[7:0]				0x00
0x14				FRAC_N	UM[15:8]				0x00
0x15				FRAC_NU	JM[23:16]				0x00
0x16				FRAC_D	DEN[7:0]				0x00
0x17				FRAC_D	EN[15:8]				0x00
0x18				FRAC_DE	EN[23:16]				0x00
0x19				PLL_I	R[7:0]				0x04
0x1A				PLL_F	R[15:8]				0x00
0x1B	0	FL_CS	R[1:0]	PFD_D	LY[1:0]	PLL_R_ DIFF	0	OSC_2X	0x08
0x1C	0	0	CPPOL			CPG[4:0]			0x00
0x1D	ı	FL_TOC[10:8]]			FL_CPG[4:0]		0x00
0x1E	0	CPM_ FLAGL		1	CPM_THR	R_LOW[5:0]			0x0A
0x1F	0	CPM_ FLAGH			CPM_THR	_HIGH[5:0]			0x32
0x20		-		FL_TC	C[7:0]				0x00
0x21				DLD_PASS	S_CNT[7:0]				0x0F
0x22	[DLD_TOL[2:0]]		DLD	_ERR_CNTF	R[4:0]		0x00
0x23	MOD_ MUX[5]	1	MUXout _MUX[5]	TRIG2 _MUX[5]	TRIG1 _MUX[5]	0	0	1	0x41
0x24		TR				Т	RIG1_PIN[2:	0]	0x08
0x25									0x10
0x26		М	OD_MUX[4:	0]			MOD_PIN[2:0	0]	0x18
0x27		MU	IXout_MUX[4	1:0]		М	UXout_PIN[2	2:0]	0x38
0x28 - 0x39				Rese	erved				-
0x3A		RAMP_TR	RIG_A[3:0]		0	RAMP_ PM_EN	RAMP_ CLK	RAMP_EN	0x00
0x3B		RAMP_TR	IG_C[3:0]			RAMP_TI	RIG_B[3:0]		0x00
0x3C				RAMP_C	MP0[7:0]				0x00
0x3D				RAMP_CI	MP0[15:8]				0x00
0x3E				RAMP_CN	/IP0[23:16]				0x00
0x3F				RAMP_CN	/IP0[31:24]				0x00
0x40				RAMP_CM	P0_EN[7:0]				0x00
0x41				RAMP_C	MP1[7:0]				0x00
0x42				RAMP_CI	MP1[15:8]				0x00
0x43				RAMP_CN	/P1[23:16]				0x00
0x44	RAMP_CMP1[31:24]								0x00
OX II	RAMP_CMP1_EN[7:0]						0x00		
0x45				RAMP_CM	P1_EN[7:0]				UXUU
	0	FSK_TF	RIG[1:0]	RAMP_CM RAMP_ LIMH[32]	P1_EN[7:0] RAMP_ LIML[32]	FSK_ DEV[32]	RAMP_ CMP1[32]	RAMP_ CMP0[32]	0x00
0x45	0	FSK_TF	RIG[1:0]	RAMP_	RAMP_ LIML[32]				
0x45 0x46	0	FSK_TF	RIG[1:0]	RAMP_ LIMH[32]	RAMP_ LIML[32] EV[7:0]				0x08
0x45 0x46 0x47	0	FSK_TF	RIG[1:0]	RAMP_ LIMH[32] FSK_D	RAMP_ LIML[32] EV[7:0] EV[15:8]				0x08 0x00
	0x11 0x12 0x13 0x14 0x15 0x16 0x17 0x18 0x19 0x1A 0x1B 0x1C 0x1D 0x1E 0x1F 0x20 0x21 0x22 0x23 0x24 0x25 0x26 0x27 0x28 0x26 0x27 0x28 0x38 0x3B 0x3C 0x3B 0x3C 0x3B 0x40 0x41 0x42	0x11 0x12 0x13 0x14 0x15 0x16 0x17 0x18 0x19 0x1A 0x1B 0x1C 0x1D 0x1E 0 0x1F 0x20 0x21 0x22 0x23 0x23 0x24 0x25 0x26 0x27 0x28 0x38 0x3A 0x3B 0x3C 0x3D 0x3E 0x40 0x41 0x42 0x43	0x11 0x12 0 FRA 0x13 0x14 0x15 0x16 0x17 0x18 0x19 0x19 0x1A 0x19 0x1A 0x1B 0 FL_CS 0x1C 0 0 0x1D FL_TOC[10:8 0x1E 0 CPM_FLAGL 0x1E 0x1E 0 CPM_FLAGH 0x20 0x21 0x20 0x21 0x22 DLD_TOL[2:0 0x21 0x22 DLD_TOL[2:0 0x23 MUX[5] 1 0x24 TF 0x26 MUX[5] 1 0x28 0x32 0x32 0x32 0x32 0x32 0x32 0x39 0x3A RAMP_TR 0x3B 0x3A RAMP_TR 0x3B 0x3B 0x3F 0x40 0x41 0x42 0x43 0x43 0x42 0x43 0x42 0x43 0x43 0x42 0x43	D7 D6 D5	STER	STER	DX11	STER	STER



Register Maps (continued)

Table 9. Register Map (continued)

REG	ISTER	D7	D6	D5	D4 D3	D2	D1 D0	POR	
75	0x4B	RAMP_LIMIT_LOW[7:0]							
76	0x4C				RAMP_LIMIT_LOW[15:8	8]		0x00	
77	0x4D				RAMP_LIMIT_LOW[23:1	6]		0x00	
78	0x4E				RAMP_LIMIT_LOW[31:2	24]		0x00	
79	0x4F				RAMP_LIMIT_HIGH[7:0)]		0xFF	
80	0x50				RAMP_LIMIT_HIGH[15:	8]		0xFF	
81	0x51				RAMP_LIMIT_HIGH[23:1	[6]		0xFF	
82	0x52				RAMP_LIMIT_HIGH[31:2	24]		0xFF	
83	0x53				RAMP_COUNT[7:0]			0x00	
84	0x54	RAMP_TRI	G_INC[1:0]	RAMP_ AUTO	RA	MP_COUNT[12:8]	0x00	
85	0x55				Reserved			0x00	
86	0x56				RAMP0_INC[7:0]			0x00	
87	0x57				RAMP0_INC[15:8]			0x00	
88	0x58				RAMP0_INC[23:16]			0x00	
89	0x59	RAMP0_ DLY	RAMP0_ FL		RAMP0_	_INC[29:24]		0x00	
90	0x5A				RAMP0_LEN[7:0]			0x00	
91	0x5B				RAMP0_LEN[15:8]			0x00	
92	0x5C	RA	MP0_NEXT[2	2:0]	RAMP0_ NEXT_TRIG[1:0]	RAMP0_ RST	RAMP0_FLAG[1:0]	0x00	
93	0x5D				RAMP1_INC[7:0]			0x00	
94	0x5E		RAMP1_INC[15:8]						
95	0x5F		RAMP1_INC[23:16]						
96	0x60	RAMP1_ DLY	RAMP1_ FL		RAMP1_	_INC[29:24]		0x00	
97	0x61			RAMP1_LEN[7:0]					
98	0x62				RAMP1_LEN[15:8]			0x00	
99	0x63	RA	MP1_NEXT[2	2:0]	RAMP1_ NEXT_TRIG[1:0]	RAMP1_ RST	RAMP1_FLAG[1:0]	0x00	
100	0x64				RAMP2_INC[7:0]	+	 	0x00	
101	0x65				RAMP2_INC[15:8]			0x00	
102	0x66				RAMP2_INC[23:16]			0x00	
103	0x67	RAMP2 DLY	RAMP2_ FL		RAMP2_	_INC[29:24]		0x00	
104	0x68		1		RAMP2_LEN[7:0]			0x00	
105	0x69				RAMP2_LEN[15:8]			0x00	
106	0x6A	RA	RAMP2_NEXT[2:0]					0x00	
107	0x6B		RAMP3_INC[7:0]						
108	0x6C				RAMP3_INC[15:8]			0x00	
109	0x6D				RAMP3_INC[23:16]			0x00	
110	0x6E	RAMP3_ DLY	RAMP3_ FL		RAMP3_	_INC[29:24]		0x00	
111	0x6F				RAMP3_LEN[7:0]			0x00	
112	0x70				RAMP3_LEN[15:8]			0x00	
113	0x71	RA	MP3_NEXT[2	2:0]	RAMP3_ NEXT_TRIG[1:0]	RAMP3_ RST	RAMP3_FLAG[1:0]	0x00	



Register Maps (continued)

Table 9. Register Map (continued)

REG	ISTER	D7	D6	D5	D4	D3	D2 D1 D0			POR
114	0x72				RAMP4	_INC[7:0]				0x00
115	0x73				RAMP4_	INC[15:8]				0x00
116	0x74				RAMP4_	NC[23:16]				0x00
117	0x75	RAMP4_ DLY	RAMP4_ FL			RAMP4_I	NC[29:24]			0x00
118	0x76				RAMP4_	_LEN[7:0]				0x00
119	0x77				RAMP4_	LEN[15:8]				0x00
120	0x78	RA	MP4_NEXT[2:0]		/IP4_ TRIG[1:0]	RAMP4_ RST	RAMP4_	FLAG[1:0]	0x00
121	0x79				RAMP5	_INC[7:0]				0x00
122	0x7A				RAMP5_	INC[15:8]				0x00
123	0x7B				RAMP5_	NC[23:16]				0x00
124	0x7C	RAMP5_ DLY	RAMP5_ FL			RAMP5_I	NC[29:24]			0x00
125	0x7D		Į.	!	RAMP5_	LEN[7:0]				0x00
126	0x7E				RAMP5_	LEN[15:8]				0x00
127	0x7F	RA	MP5_NEXT[2:0]		/IP5_ TRIG[1:0]	RAMP5_ RST	RAMP5_	FLAG[1:0]	0x00
128	0x80				RAMP6	_INC[7:0]				0x00
129	0x81				RAMP6_	INC[15:8]				0x00
130	0x82				RAMP6_	NC[23:16]				0x00
131	0x83	RAMP6_ DLY	RAMP6_ FL			RAMP6_I	NC[29:24]			0x00
132	0x84		I.		RAMP6_	_LEN[7:0]				0x00
133	0x85				RAMP6_	LEN[15:8]				0x00
134	0x86	RA	MP6_NEXT[2:0]		/IP6_ TRIG[1:0]	RAMP6_ RST	RAMP6_	FLAG[1:0]	0x00
135	0x87				RAMP7	_INC[7:0]				0x00
136	0x88				RAMP7_	INC[15:8]				0x00
137	0x89				RAMP7_	NC[23:16]				0x00
138	0x8A	RAMP7_ DLY	RAMP7_ FL			RAMP7_I	NC[29:24]			0x00
139	0x8B		RAMP7_LEN[7:0]						0x00	
140	0x8C				RAMP7_	LEN[15:8]				0x00
141	0x8D	RA	MP7_NEXT[2:0]		//P7_ TRIG[1:0]	RAMP7_ RST	RAMP7_	FLAG[1:0]	0x00
142 - 32767	0x8E - 0x7FFF				Res	erved				0x00



7.6.1 Register Field Descriptions

The following sections go through all the programmable fields and their states. Additional information is also available in the applications and feature descriptions sections as well. The POR column is the power on reset state that this field assumes if not programmed.

7.6.1.1 POWERDOWN and Reset Fields

Table 10. POWERDOWN and Reset Fields

FIELD	LOCATION	POR	DESCRIPTION AND STATES					
				Value	POWERDOWN State			
			POWERDOWN Control	0	Power Down, ignore CE			
POWERDOWN	R2[1:0]	0		1	Power Up, ignore CE			
[1:0]				2	Power State Defined by CE terminal state			
				3	Reserved			
		0		Value	Reset State			
SWRST	R2[2]		Software Reset. Setting this bit sets all registers to their POR default values.	0	Normal Operation			
			regionals to them? Off deladit values.	1	Register Reset			



7.6.1.2 Dividers and Fractional Controls

Table 11. Dividers and Fractional Controls

FIELD	LOCATION	POR	DESCRIPTION AND STATES			
PLL_N [17:0]	R18[1] to R16[0]	16	Feedback N counter Divide value. Minimum the register R16 begins any ramp execution			
				Value	Dither	
				0	Weak	
FRAC_ DITHER [1:0]	R18[3:2]	0	Dither used by the fractional modulator	1	Medium	
[1.0]				2	Strong	
				3	Disabled	
				Value	Modulator Order	
				0	Integer Mode	
				1	1st Order Modulator	
FRAC_ ORDER [2:0]	R18[6:4]	0	Fractional Modulator order	2	2nd Order Modulator	
[2.0]				3	3rd Order Modulator	
				4	4th Order Modulator	
				5-7	Reserved	
FRAC_NUM [23:0]	R21[7] to R19[0]	0	Fractional Numerator. This value should denominator.	be less that	an or equal to the fractional	
FRAC_DEN [23:0]	R24[7] to R22[0]	0	Fractional Denominator. If RAMP_EN = 1, fixed to 2^{24} .	this field is i	gnored and the denominator is	
PLL_R [15:0]	R26[7] to R25[0]	1	Reference Divider value. Selecting 1 bypasses counter.			
			Enables the Doubler before the Reference divider	Value	Doubler	
OSC_2X	R27[0]	0		0	Disabled	
				1	Enabled	
			Enables the Differential R counter. This allows for higher OSCin frequencies, but restricts PLL_R to divides of 2, 4, 8 or 16.	Value	R Divider	
PLL_R _DIFF	R27[2]	0		0	Single-Ended	
				1	Differential	
			Sets the charge pump minimum pulse width. This could potentially be a trade-off between fractional spurs and phase noise. Setting 1 is recommended for general use.	Value	Pulse Width	
				0	Reserved	
PFD_DLY [1:0]	R27[4:3]	1		1	860 ps	
[1.0]				2	1200 ps	
				3	1500 ps	
				Value	Charge Pump State	
				0	Tri-State	
CPG	D. 0.1 / 0.1	_		1	100 μΑ	
[4:0]	R28[4:0]	0	Charge pump gain	2	200 μΑ	
				31	3100 µA	
			Charge pump polarity is used to	Value	Charge Pump Polarity	
			accommodate VCO with either polarity so	0	Positive	
CPPOL	R28[5] 0	that feedback of the PLL is always correct. IF reference (R) output is faster than feedback (N) output, R28[5]==0 THEN charge pump will source current R28[5]==1 THEN charge pump will sink current	1	Negative		



7.6.1.2.1 Speed Up Controls (Cycle Slip Reduction and Fastlock)

Table 12. FastLock and Cycle Slip Reduction

Table 12. Facilities of the control						
FIELD	LOCATION	POR	DESCRIPTION	AND STATE	≣S	
			Cycle Slip Reduction (CSR) reduces the	Value	CSR Value	
			phase detector frequency by multiplying both the R and N counters by the CSR	0	Disabled	
			value while either the FastLock Timer is	1	x 2	
FL_ CSR	R27[6:5]	0	counting or the RAMPx_FL = 1 and the part is ramping. Care must be taken that	2	x 4	
[1:0]			the R and N divides remain inside the range of the counters. Cycle slip reduction is generally not recommended during ramping.	3	Reserved	
				Value	Fastlock Charge Pump Gain	
	R29[4:0]	0	Charge pump gain only when Fast Lock Timer is counting down or a ramp is running with RAMPx_FL = 1	0	Tri-State	
FL_ CPG				1	100 μΑ	
[4:0]				2	200 μΑ	
				•••		
				31	3100 μΑ	
			Fast Lock Timer. This counter starts	Value	Fastlock Timer Value	
			counting when the user writes the PLL_N(Register R16). During this time the	0	Disabled	
FL_ TOC	R29[7:5]		FL_CPG gain is sent to the charge pump,	1	1 x 32 = 32	
[10:0]	and R32[7:0]	0	and the FL_CSR shifts the R and N counters if enabled. When the counter			
1.1.9			terminates, the normal CPG is presented and the CSR undo's the shifts to give a normal PFD frequency.	2047	2047 x 32 = 65504	



7.6.2 Lock Detect and Charge Pump Monitoring

Table 13. Lock Detect and Charge Pump Monitor

FIELD	LOCATION	POR	DESCRIPTION AND STATES		
				Value	Threshold
CPM_THR _LOW	D20[E.0]	0x0A	Charge pump voltage low threshold value. When the charge pump voltage is below	0	Lowest
[5:0]	R30[5:0]	UXUA	this threshold, the LD goes low.		•••
			·	63	Highest
				Value	Flag Indication
CPM_FLAGL	R30[6]	-	This is a read only bit. Low indicates the charge pump voltage is	0	Charge pump is below CPM_THR_LOW threshold
			below the minimum threshold.	1	Charge pump is above CPM_THR_LOW threshold
				Value	Threshold
CPM_THR _HIGH	D24[E.0]	0.20	Charge pump voltage high threshold value.	0	Lowest
[5:0]	R31[5:0]	0x32	When the charge pump voltage is above this threshold, the LD goes low.		•••
				63	Highest
			This is a read only bit. Charge pump voltage high comparator reading. High indicates the charge pump voltage is above the maximum threshold.	Value	Threshold
CPM_FLAGH	R31[6]	-		0	Charge pump is below CPM_THR_HIGH threshold
				1	Charge pump is above CPM_THR_HIGH threshold
DLD_ PASS_CNT [7:0]	R33[7:0]	0xFF	Digital Lock Detect Filter amount. There must be at least DLD_PASS_CNT god and less than DLD_ERR edges before the DLD is considered in lock. Making this smaller speeds the detection of lock, but also allows a higher chance of DLD chat		ered in lock. Making this number
DLD_ ERR_CNT [4:0]	R34[4:0]	0	Digital Lock Detect error count. This is th DLD_TOL that are allowed before DLD is recommended value is 4.		
				Value	Window and f _{PD} Frequency
				0	1 ns (f _{PD} > 130 MHz)
			Digital Lock detect edge window. If both N and R edges are within this window, it is considered a "good" edge. Edges that are	1	1.7 ns (80 MHz < f _{PD} ≤ 130 MHz)
DLD _TOL	R34[7:5]	0	farther apart in time are considered "error"	2	3 ns (60 MHz < f _{PD} ≤ 80 MHz)
[2:0]	134[1.0]	U	edges. Window choice depends on phase	3	6 ns (45 MHz < f _{PD} ≤ 60 MHz)
			detector frequency, charge pump minimum pulse width, fractional modulator order and the users desired margin.	4	10 ns (30 MHz < f _{PD} ≤ 45 MHz)
				5	18 ns (f _{PD} ≤ 30 MHz)
				6 and 7	Reserved



7.6.3 TRIG1, TRIG2, MOD, and MUXout Pins

Table 14. TRIG1, TRIG2, MOD, and MUXout Terminal States

FIELD	LOCATION	POR	DESCRIPTION AND STATES			
				Value	Pin Drive State	
TRIG1 _PIN	D26[2.0]	0		0	TRISTATE (default)	
[2:0]	R36[2:0]	U		1	Open Drain Output	
				2	Pullup / Pulldown Output	
TRIG2 _PIN [2:0]	R37[2:0]	0	This is the terminal drive state for the	3	Reserved	
MOD_ PIN [2:0]	R38[2:0]	0	TRIG1, TRIG2, MOD, and MUXout Pins	4	GND	
			0	5	Inverted Open Drain Output	
MUXout_ PIN [2:0]	R39[2:0]	0		6	Inverted Pullup / Pulldown Output	
				7	Input	



Table 15. TRIG1, TRIG2, MOD, and MUXout Selections

FIELD	LOCATION	POR	DESCRIPTION	AND STATE	≣S .
				Value	MUX State
				0	GND
				1	Input TRIG1
				2	Input TRIG2
				3	Input MOD
				4	Output TRIG1 after synchronizer
				5	Output TRIG2 after synchronizer
				6	Output MOD after synchronizer
				7	Output Read back
				8	Output CMP0
				9	Output CMP1
				10	Output LD (DLD good AND CPM good)
				11	Output DLD
				12	Output CPMON good
				13	Output CPMON too High
			These fields central what signal is moved	14	Output CPMON too low
TRIG1_MUX [5:0]	R36[7:3], R35[3]	1	These fields control what signal is muxed to or from the TRIG1, TRIG2, MOD, and MUXout pins.	15	Output RAMP LIMIT EXCEEDED
TRIG2_MUX	R37[7:3],	2	Some of the abbreviations used are:	16	Output R Divide/2
[5:0]	R35[4]		COMP0, COMP1: Comparators 0 and 1 LD, DLD: Lock Detect, Digital Lock Detect	17	Output R Divide/4
MOD_MUX [5:0]	R38[7:3], R35[7]	3	CPM: Charge Pump Monitor	18	Output N Divide/2
			CPG: Charge Pump Gain	19	Output N Divide/4
MUXout_MUX [5:0]	R39[7:3], R35[5]	7	CPUP: Charge Pump Up Pulse	20	Reserved
. ,			CPDN: Charge Pump Down Pulse	21	Reserved
				22	Output CMP0RAMP
				23	Output CMP1RAMP
				24	Reserved
				25	Reserved
				26	Reserved
				27	Reserved
				28	Output Faslock
				29	Output CPG from RAMP
				30	Output Flag0 from RAMP
				31	Output Flag1 from RAMP
				32	Output TRIGA
				33	Output TRIGB
				34	Output TRIGC
				35	Output R Divide
				36	Output CPUP
				37	Output CPDN
				38	Output RAMP_CNT Finished
				39 to 63	Reserved



7.6.4 Ramping Functions

Table 16. Ramping Functions

FIELD LOCATION POR DESCRIPTION AND STATES							
TILLD	LOCATION	1 OK	Enables the RAMP functions. When this bit	Value	Ramp		
	N R58[0]				is set, the Fractional Denominator is fixed	0	Disabled
RAMP_EN	R58[0]	0	to 2 ²⁴ . RAMP execution begins at RAMP0 upon the PLL_N[7:0] write. The Ramp should be set up before RAMP_EN is set.	1	Enabled		
			RAMP clock input source. The ramp can	Value	Source		
RAMP_CLK	R58[1]	0	be clocked by either the phase detector clock or the MOD terminal based on this	0	Phase Detector		
			selection.	1	MOD Terminal		
				Value	Modulation Type		
RAMP_PM_EN	R58[2]	0	Phase modulation enable.	0	Frequency Modulation		
				1	Phase Modulation		
				Value	Source		
				0	Never Triggers (default)		
				1	TRIG1 terminal rising edge		
				2	TRIG2 terminal rising edge		
				3	MOD terminal rising edge		
				4	DLD Rising Edge		
RAMP_TRIGA	DE0[7:4]			5	CMP0 detected (level)		
[3:0]	R58[7:4]			6	RAMPx_CPG Rising edge		
RAMP_TRIGB	R59[3:0]	0	Trigger A, B, and C Sources	7	RAMPx_FLAG0 Rising edge		
[3:0]				8	Always Triggered (level)		
RAMP_TRIGC [3:0]	R59[7:4]			9	TRIG1 terminal falling edge		
[0.0]				10	TRIG2 terminal falling edge		
				11	MOD terminal falling edge		
				12	DLD Falling Edge		
				13	CMP1 detected (level)		
				14	RAMPx_CPG Falling edge		
				15	RAMPx_FLAG0 Falling edge		
RAMP_CMP0 [32:0]	R70[0], R63[7] to R60[0]	0	Twos compliment of Ramp Comparator 0 va R70.	alue. Be aware			
RAMP_CMP0_EN [7:0]	R64[7:0]	0	Comparator 0 is active during each RAMP c is active in and 0 for ramps it should be ignoreresponds to R64[7]				
RAMP_CMP1 [32:0]	R70[1], R68[7] to R65[0]	0	Twos compliment of Ramp Comparator 1 va R70.	alue. Be aware	e of that the MSB is in Register		
RAMP_CMP1_EN [7:0]	R69[7:0]	0	Comparator 1 is active during each RAMP corresponding to the bit. Place a 1 for ramps is active in and 0 for ramps it should be ignored. RAMP0 corresponds to R64[0], RAMP corresponds to R64[7].				
				Value	Trigger		
FOIX TO: 0	D70111		Deviation trigger source. When this trigger	0	Always Triggered		
FSK_TRIG [1:0]	R76[4] to R75[3]	0	source specified is active, the FSK_DEV	1	Trigger A		
			value is applied.	2	Trigger B		
				3	Trigger C		
FSK_DEV [32:0]	R70[2], R74[7] to R71[0]	0	Twos compliment of the deviation value for frequency modulation and phase modulation This value should be written with 0 when not used. Be aware that the MSB is in Registe R70.				



Table 16. Ramping Functions (continued)

FIELD	LOCATION	POR	DESCRIPTION AND STATES				
RAMP_LIMIT_LOW [32:0]	R70[3], R78[7] to R75[0]	0	Twos compliment of the ramp lower limit that the ramp can not go below . The ramp limit occurs before any deviation values are included. Care must be taken if the deviation is used and the ramp limit must be set appropriately. Be aware that the MSB is in Register R70.				
RAMP_LIMIT_HIGH [32:0]	R70[4], R82[7] to R79[0]	0x1FF FFFF FF	Twos compliment of the ramp higher limit that the ramp can not go above. The ramp limit occurs before any deviation values are included. Care must be taken if the deviation is used and the ramp limit must be set appropriately. Be aware that the MSB is in Register R70.				
RAMP_COUNT [12:0]	R84[4] to R83[0]	0	Number of RAMPs that is executed before a trigger or ramp enable is brought down. Load zero if this feature is not used. Counter is automatically reset when RAMP_EN goes from 0 to 1.				
				Value	Ramp		
RAMP_AUTO	R84[5]	0	Automatically clear RAMP_EN when	0	RAMP_EN unaffected by ramp counter (default)		
10 tivil _7.010	ारु ग् ।		RAMP Count hits terminal count.	1	RAMP_EN automatically brought low when ramp counter terminal counts		
				Value	Source		
RAMP_TRIG_INC		_	Increment Trigger source for RAMP	0	Increments occur on each ramp transition		
[1:0]	R84[7:6]	0	Counter. To disable ramp counter, load a count value of 0.	1	Increment occurs on Trigger A		
			Count value of 0.	2	Increment occurs on Trigger B		
				3	Increment occurs on Trigger C		



7.6.5 Individual Ramp Controls

These bits apply for all eight ramp segments. For the field names, x can be 0, 1, 2, 3, 4, 5, 6, or 7.

Table 17. Individual Ramp Controls

FIELD	LOCATI ON	POR	DESCRIPTION AND STATES						
RAMPx _INC[29:0]	Varies	0	Signed ramp increment.						
				Value	CPG				
RAMPx _FL	Varies	0	This enables fastlock and cycle slip reduction for ramp x.	0	Disabled				
				1	Enabled				
				Value	Clocks				
RAMPx _DLY	Varies	0	During this ramp, each increment takes 2 f _{PD} cycles per LEN clock instead of the normal 1 f _{PD} cycle. Slows the ramp by a factor of 2.	0	1 f _{PD} clock per RAMP tick.(default)				
			ramp by a lactor of E.	1	2 f _{PD} clocks per RAMP tick.				
RAMPx _LEN	Varies	0	Number of f_{PD} clocks (if DLY is 0) to continue to increme Maximum of 65536 cycles.	Number of f_{PD} clocks (if DLY is 0) to continue to increment RAMP. 1 = 1 cycle, 2 = 2 cycles Maximum of 65536 cycles.					
				Value	Flag				
			General purpose FLAGs sent out of RAMP at the start of a ramp pattern.	0	Both FLAG1 and FLAG0 are zero. (default)				
RAMPx _FLAG[1:0]	Varies	0		1	FLAG0 is set, FLAG1 is clear				
_1 L/(0[1:0]	_FLAG[1.0]		Tump pattern.	2	FLAG0 is clear, FLAG1 is set				
				3	Both FLAG0 and FLAG1 are set.				
			Forces a clear of the ramp accumulator at the start of a	Value	Reset				
RAMPx RST	Varies	0	ramp pattern. This is used to erase any accumulator creep	0	Disabled				
			that can occur depending on how the ramps are defined.	1	Enabled				
				Value	Operation				
RAMPx_			Determines what event is necessary to cause the state	0	RAMPx_LEN				
NEXT TRIG Varies	0	machine to go to the next ramp. It can be set to when the RAMPx LEN counter reaches zero or one of the events for	1	Trigger A					
[1:0]			Triggers A, B, or C.	2	Trigger B				
			3	Trigger C					
RAMPx _NEXT[2:0]	Varies	0	The next RAMP to execute when the length counter times out						



8 Applications and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

The LMX2491 can be used in a broad class of applications such as generating a single frequency for a high frequency clock, generating a tunable range of frequencies, or generating swept waveforms that can be used in applications such as radar.

8.2 Typical Application

Figure 14 is an example that could be used in a typical application.

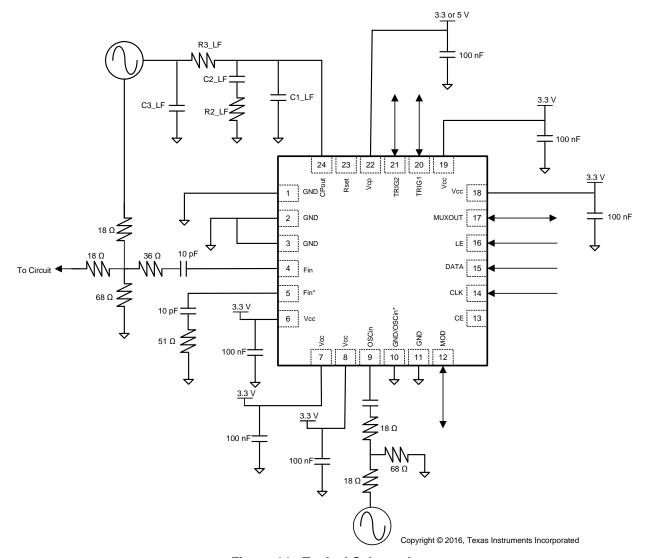


Figure 14. Typical Schematic



Typical Application (continued)

8.2.1 Design Requirements

For these examples, it will be assumed that there is a 100 MHz input signal and the output frequency is between 1500 and 1520 MHz with various modulated waveforms.

Table 18. Design Requirements

PARAMETER	SYMBOL	VALUE	COMMENTS
Input frequency	f _{OSCin}	100 MHz	
Phase detector frequency	f _{PD}	50 MHz	There are many possibilities, but this choice gives good performance.
VCO frequency	f _{vco}	1500 - 1520 MHz	In the different examples, the VCO frequency is actually changing. However, the same loop filter design can be used for all examples. Unmodulated VCO frequency or steady state VCO frequency without ramp is 1500 MHz.
VCO gain	K _{VCO}	65 MHz/V	This parameter has nothing to do with the LMX2491, but is rather set by the external VCO choice.

8.2.2 Detailed Design Procedure

The first step is to calculate the reference divider (PLL_R) and feedback divider (PLL_N) values as shown in the table that follows.

Table 19. Detailed Design Procedure

PARAMETE R	SYMBOL AND CALCULATIONS	VALUE	COMMENTS
Average VCO frequency	$f_{VCOavg} = (f_{VCOmax} + f_{VCOmin}) / 2$	1510 MHz	To design a loop filter, one designs for a fixed VCO value, although it is understood that the VCO will tune around. This typical value is usually chosen as the average VCO frequency
VCO gain	K _{vco}	65 MHz/V	This parameter has nothing to do with LMX2491, but is rather set by the external VCO choice. In this case, it was the CVCO55BE-1400-1624 VCO.
VCO input capacitance	C_{VCO}	120 pF	This parameter has nothing to do with LMX2491, but is rather set by the external VCO choice.
PLL loop bandwidth	LBW	380 kHz	This bandwidth is very wide to allow the VCO frequency to be modulated.
Charge pump gain	CPG	3.1 mA	Using the larger gain allows a wider loop bandwidth and gives good phase performance.
R-divider	$PLL_R = f_{OSCin} / f_{PD}$	2	
N-divider	$PLL_N = f_{VCO} / f_{PD}$	96	
	C1_LF	68 pF	
	C2_LF	3.9 nF	
Loop filter components	C3_LF	150 pF	These were calculated by TI PLLatinum Simulator Tool.
	R2_LF	390 Ω	
	R3_LF	150 Ω	

Once a loop filter bandwidth is chosen, the external loop filter component values can be calculated with a tool such as PLLatinum Simulator Tool. It is also highly recommended to look at the EVM User's Guide. TICS Pro software is an excellent starting point and example to see how to program this device.

8.2.3 TICS Pro Basic Setup

In the following application examples, TICS Pro is used to program the device to implement different ramp profiles. The following procedure shows how to setup TICS Pro to put the device to lock to 1500 MHz without modulation or ramp.



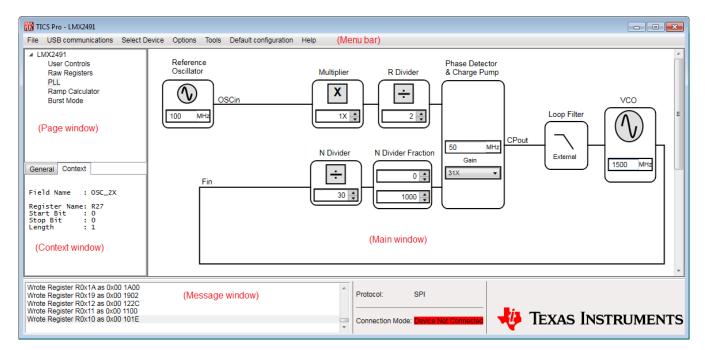


Figure 15. TICS Pro

- 1. In the Menu bar, click Select Device and then select LMX2491.
- 2. In the Menu bar, click Default Configuration and then select Default Mode.
- 3. In the Page window, click PLL.
- 4. In the Main window, change R Divider value to 2 and VCO value to 1500.
- 5. In the Menu bar, click USB Communications and then click Write All Registers. The device is now locked to 1500 MHz.

Other TICS Pro fundamentals:

- When a particular content in the Main window is moused-over, the Context window will show a brief description of that content.
- An alternative method to write all registers is press the Ctrl key and L key from the keyboard.
- Whenever a value is updated in the Main window, the Message window will show which register is being updated

8.2.4 Frequency Shift Keying Example

FSK operation requires an external input trigger signal at either MOD, TRIG1 or TRIG2 pin. In this example, MOD pin is selected as the Trigger A source. A 20 kHz square-wave clock will be applied to MOD pin to toggle the RF output to switch between 1500 MHz and 1502 MHz. That is, FSK frequency deviation is 2 MHz. The following register bits are required to set in order to initiate FSK operation.

Table 20. FSK Register Settings

PARAMETER	REGISTER BIT	SETTING	COMMENTS
Frequency deviation	FSK_DEV	671089 = 2 MHz	Frequency deviation = (f _{PD} x FSK_DEV) / 2 ²⁴
MOD pin characteristic	MOD_PIN	7 = Input	Set MOD pin as an input pin
FSK trigger source	FSK_DEV_TRIG	1 = Trigger A	Use Trigger A to trigger FSK
Trigger source definition	RAMP_TRIGA	3 = MOD Rising Edge	When there is a L-to-H transition at MOD pin, the set amount of frequency deviation will be added to the unmodulated carrier
Enable ramp	RAMP_EN	1 = Enabled	Activate FSK operation



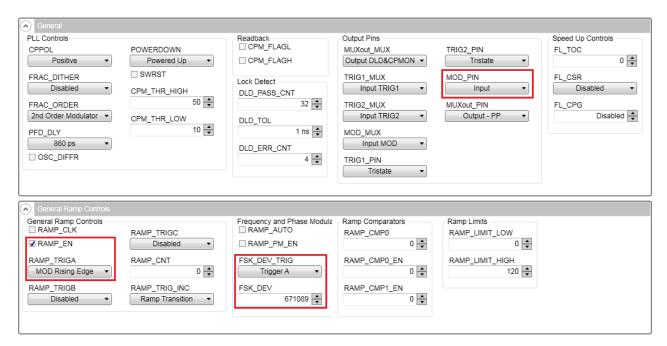


Figure 16. TICS Pro FSK Configuration

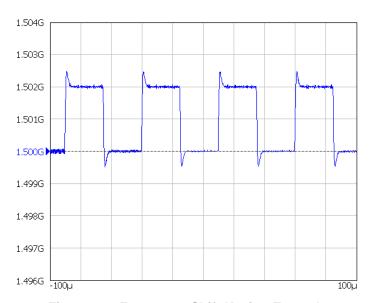


Figure 17. Frequency Shift Keying Example

8.2.5 Single Sawtooth Ramp Example

In this example, Trigger B is used to trigger the ramp generator of LMX2491 to general a single frequency ramp between 1500 MHz and 1520 MHz. Ramp duration is 50 µs. The ramp will finish and return back to 1500 MHz immediately when the output frequency reaches 1520 MHz. Trigger 1 pin is assigned as Trigger B source.

Two ramp segments are setup to create this one-time single ramp. RAMP0 is used to establish a trigger for the second ramp segment - RAMP1. When a trigger signal is received, RAMP1 will execute and bring the output frequency to 1520 MHz in $50 \mu s$.



Table 21. Single Sawtooth Ramp Register Settings

PARAMETER	REGISTER BIT	SETTING	COMMENTS
Set maximum ramp frequency threshold	RAMP_LIMIT_HIGH	16777216 = 1550 MHz	This threshold frequency can be anything above 1520 MHz. The fractional numerator is equal to 0 at 1550 MHz. The N-Divider difference between 1500 MHz and 1550 MHz is 1. From Equation 1, this threshold is equal to $0 + (1 \times 2^{24}) = 16777216$.
Set minimum ramp frequency threshold	RAMP_LIMIT_LOW	8573157376 = 1450 MHz	This threshold frequency can be anything below 1500 MHz. This threshold is equal to –16777216. This is a 33-bit long register, 2's complement is therefore equal to 8573157376.
Number of ramp in each ramp segment	RAMP0_LEN, RAMP1_LEN	2500 = for ramp duration equals 50 μs	The duration of RAMP0 is not matter, for demonstration convenience, it has the same ramp duration as RAMP1. During ramp, LMX2491 ramp generator will increment its output frequency once per phase detector cycle. For ramp duration of 50 μs and f_{PD} = 50 MHz, there are 2500 ramps [= 50 μs / (1 / 50 MHz)].
Frequency change per ramp in RAMP0	RAMP0_INC	0	Since the output frequency would not change in RAMP0, there is no frequency increment.
Set next ramp segment	RAMP0_NEXT	1 = RAMP1	Set RAMP1 as the next ramp segment following RAMP0.
Set next ramp segment trigger source	RAMP0_NEXT_TRIG	2 = Trigger B	Use Trigger B to trigger the execution of RAMP1.
Rest fractional numerator	RAMP0_RST	1 = Reset	RAMP0 will execute again after RAMP1 is finished but RAMP1 does not end at 1500 MHz, a reset to the fractional numerator is required before RAMP0 is executed.
Frequency change per ramp in RAMP1	RAMP1_INC	2684 = 8 kHz	Between 1500 MHz and 1520 MHz, there are 2500 ramps. For each ramp, the output frequency will increment by 20 MHz / 2500 = 8 kHz. For f_{PD} = 50 MHz and fractional denominator = 2^{24} , fractional numerator is incremented by a value of (8 kHz x 2^{24}) / 50 MHz ≈ 2684.
Set next ramp segment	RAMP1_NEXT	0 = RAMP0	Set RAMP0 as the next ramp segment following RAMP1.
Set next ramp segment trigger source	RAMP1_NEXT_TRIG	0 = TOC Timeout	After RAMP1 is finished, the next ramp segment will execute immediately.
Trigger source definition	RAMP_TRIGB	1 = TRIG1 Rising Edge	When there is a L-to-H transition at TRIG1 pin, RAMP1 will execute.
TRIG1 pin characteristic	TRIG1_PIN	7 = Input	Set TRIG1 pin as an input pin.



It is recommended to use the Ramp Calculator in TICS Pro to create the ramp profile. TICS Pro will calculate the ramp-related register values automatically.

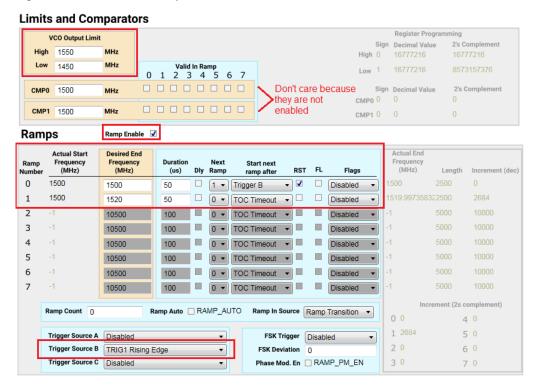


Figure 18. TICS Pro Ramp Calculator

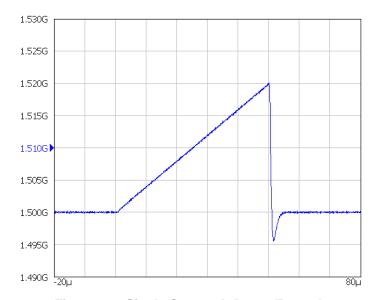


Figure 19. Single Sawtooth Ramp Example

8.2.6 Continuous Sawtooth Ramp Example

This example shows how to generate a continuous sawtooth ramp. Only one ramp segment is necessary as it will loop back to itself.



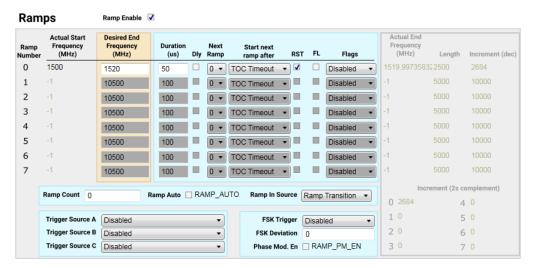


Figure 20. Continuous Sawtooth Ramp Configuration

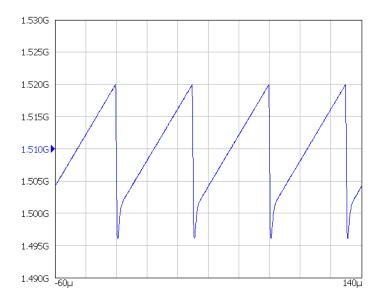


Figure 21. Continuous Sawtooth Ramp Example

8.2.7 Continuous Sawtooth Ramp with FSK Example

A ramp and FSK can coexist at the same time. Since the amount of FSK is added to the instantaneous carrier, the FSK will appear at the envelope of the ramp. Furthermore, a ramp and FSK are two independent operations, their register settings can be combined in a single configuration setting. That is, when RAMP_EN is enabled, both frequency ramp and FSK will be activated together.



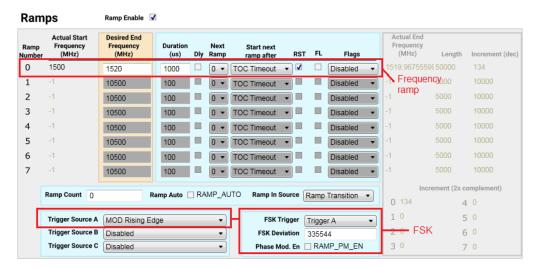


Figure 22. Continuous Sawtooth Ramp with FSK Configuration

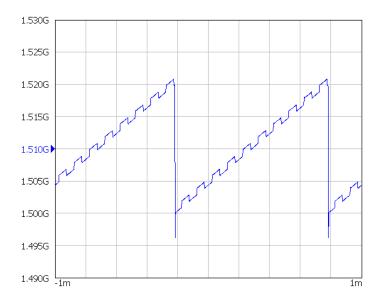


Figure 23. Continuous Sawtooth Ramp with FSK Example

8.2.8 Continuous Triangular Ramp Example

Two ramp segments are used to create this ramp pattern. RAMP0 ramps from 1500 MHz to 1520 MHz. RAMP1 brings the frequency back to 1500 MHz and then RAMP0 starts over again. Since RAMP1 already brought the frequency back to 1500 MHz, which is also the start frequency of RAMP0, a reset to fractional numerator is not required.



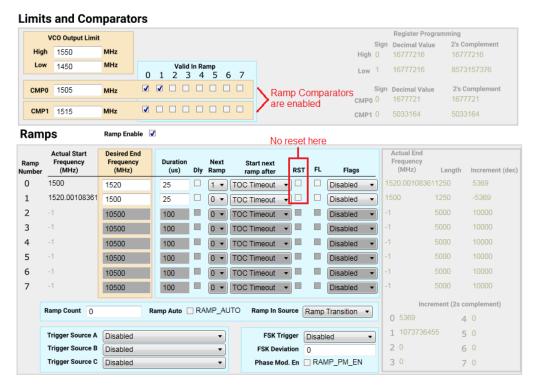


Figure 24. Continuous Triangular Ramp Configuration

Ramp comparators are enabled so as to output flag signals when the threshold frequencies are hit. MOD pin is assigned for CMP0 while TRIG1 pin is assigned for CMP1. RAMP_CMP0_EN is equal to 3 because ramp segment 0 and 1 are monitored.

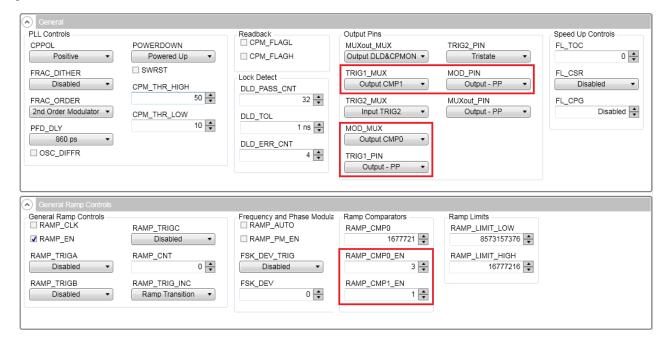


Figure 25. Ramp Comparators Configuration

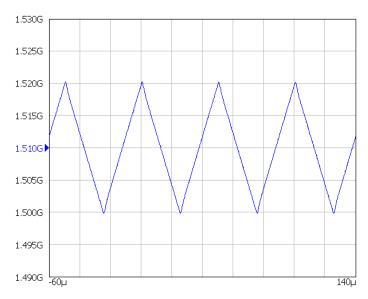


Figure 26. Continuous Triangular Ramp Example

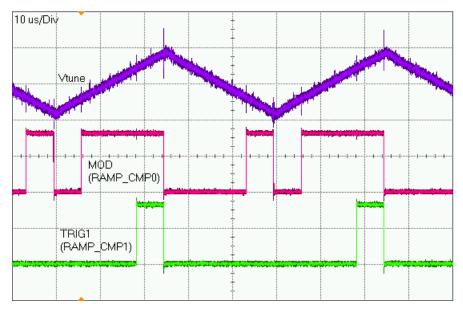


Figure 27. Ramp Comparators Output Flags

8.2.9 Continuous Trapezoid Ramp Example

This is a long-ramp example, the ramp duration is 2 ms. Since f_{PD} = 50 MHz, 100000 ramps are required for each ramp segment. However, LMX2491 supports up to a maximum ramp length (RAMPx_LEN) of 65536 only. There are two solutions to resolve this problem:

- 1. Reduce phase detector frequency. For example, reduce f_{PD} to 25 MHz, then the required RAMPx_LEN becomes 50000.
- 2. Enable RAMPx_DLY. When this register bit is set, the ramp generator will ramp every 2 phase detector cycles instead of the normal 1 f_{PD} cycle. In this example, this bit is set and as a result, RAMPx_LEN is 50000.

Four ramp segments are used to construct the ramp pattern. Again there is no need to reset the fractional numerator because the last ramp end frequency is equal to the first ramp start frequency.



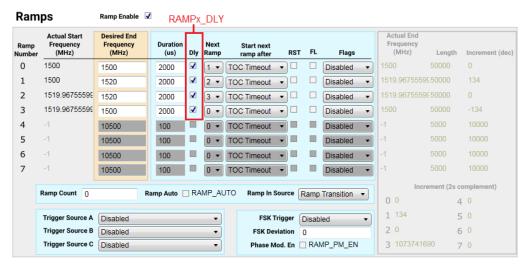


Figure 28. Continuous Trapezoid Ramp Configuration

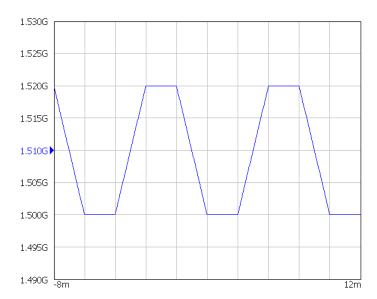


Figure 29. Continuous Trapezoid Ramp Example

8.2.10 Arbitrary Waveform Ramp Example

An arbitrary ramp waveform can be easily constructed with the 8 ramp segments provided in LMX2491. LMX2491 also provides flag signals output to indicate the start of a ramp. This example used the MOD pin to initiate the ramp and used TRIG1 and TRIG2 as the output flags to indicate the status of the ramp.



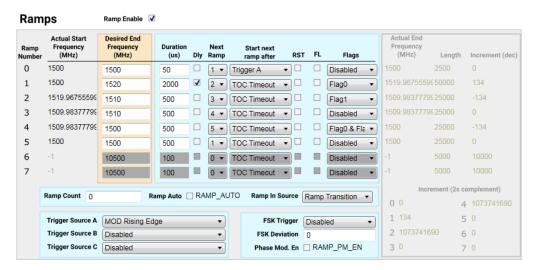


Figure 30. Arbitrary Waveform Ramp Configuration

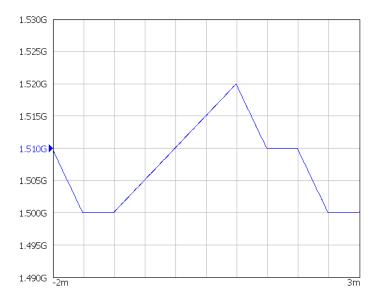


Figure 31. Arbitrary Waveform Ramp Example



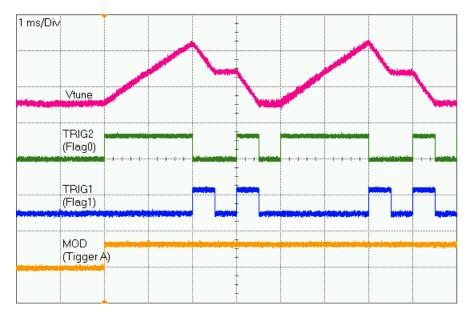


Figure 32. Arbitrary Waveform Ramp Timing

9 Power Supply Recommendations

For power supplies, TI recommends placing 100 nF close to each of the power supply pins. If fractional spurs are a large concern, using a ferrite bead to each of these power supply pins can reduce spurs to a small degree.

10 Layout

10.1 Layout Guidelines

For layout examples, the EVM instructions are the most comprehensive document. In general, the layout guidelines are similar to most other PLL devices. For the high frequency Fin pin, it is recommended to use 0402 components and match the trace width to these pad sizes. Also the same needs to be done on the Fin* pin. If layout is easier to route the signal to Fin* instead of Fin, then this is acceptable as well.



10.2 Layout Example

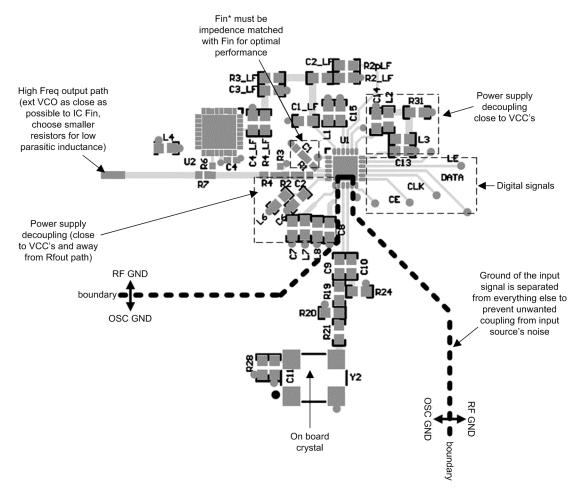


Figure 33. Layout Recommendation



11 器件和文档支持

11.1 器件支持

11.1.1 开发支持

德州仪器 (TI) 提供多款开发辅助软件工具,包括 TICS Pro 编程辅助工具、PLLatinum Simulator Tool 回路滤波器 设计辅助工具以及相位噪声/毛刺仿真辅助工具。所有这些工具均可从以下网址获得:www.ti.com。

11.2 文档支持

11.2.1 相关文档

相关文档如下:

- 《AN-1879 分数 N 频率合成》(文献编号: SNAA062)
- 《PLL 性能仿真和设计》

11.3 接收文档更新通知

要接收文档更新通知,请导航至德州仪器 Tl.com.cn 上的器件产品文件夹。请单击右上角的通知我进行注册,即可收到任意产品信息更改每周摘要。有关更改的详细信息,请查看任意已修订文档中包含的修订历史记录。

11.4 社区资源

下列链接提供到 TI 社区资源的连接。链接的内容由各个分销商"按照原样"提供。这些内容并不构成 TI 技术规范,并且不一定反映 TI 的观点;请参阅 TI 的 《使用条款》。

TI E2E™ 在线社区 TI 的工程师对工程师 (E2E) 社区。此社区的创建目的在于促进工程师之间的协作。在 e2e.ti.com 中,您可以咨询问题、分享知识、拓展思路并与同行工程师一道帮助解决问题。

设计支持 TI 参考设计支持 可帮助您快速查找有帮助的 E2E 论坛、设计支持工具以及技术支持的联系信息。

11.5 商标

E2E is a trademark of Texas Instruments.

All other trademarks are the property of their respective owners.

11.6 静电放电警告



ESD 可能会损坏该集成电路。德州仪器 (TI) 建议通过适当的预防措施处理所有集成电路。如果不遵守正确的处理措施和安装程序,可能会损坏集成电路。

ESD 的损坏小至导致微小的性能降级,大至整个器件故障。 精密的集成电路可能更容易受到损坏,这是因为非常细微的参数更改都可能会导致器件与其发布的规格不相符。

11.7 Glossary

SLYZ022 — TI Glossary.

This glossary lists and explains terms, acronyms, and definitions.

12 机械、封装和可订购信息

以下页中包括机械封装、封装和可订购信息。这些信息是针对指定器件可提供的最新数据。这些数据发生变化时,我们可能不会另行通知或修订此文档。如欲获取此产品说明书的浏览器版本,请参阅左侧的导航栏。



PACKAGE OPTION ADDENDUM

10-Dec-2020

PACKAGING INFORMATION

www.ti.com

Orderable Device	Status	Package Type	Package Drawing	Pins	Package Qty	Eco Plan	Lead finish/ Ball material	MSL Peak Temp	Op Temp (°C)	Device Marking (4/5)	Samples
LMX2491RTWR	ACTIVE	WQFN	RTW	24	1000	RoHS & Green	SN	Level-3-260C-168 HR	-40 to 85	X2491	Samples
LMX2491RTWT	ACTIVE	WQFN	RTW	24	250	RoHS & Green	SN	Level-3-260C-168 HR	-40 to 85	X2491	Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

- (3) MSL, Peak Temp. The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
- (4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
- (5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
- (6) Lead finish/Ball material Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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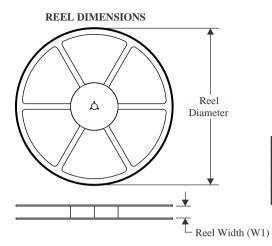


10-Dec-2020

PACKAGE MATERIALS INFORMATION

www.ti.com 9-Aug-2022

TAPE AND REEL INFORMATION





A0	Dimension designed to accommodate the component width
В0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LMX2491RTWR	WQFN	RTW	24	1000	178.0	12.4	4.3	4.3	1.3	8.0	12.0	Q1
LMX2491RTWT	WQFN	RTW	24	250	178.0	12.4	4.3	4.3	1.3	8.0	12.0	Q1

PACKAGE MATERIALS INFORMATION

www.ti.com 9-Aug-2022



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LMX2491RTWR	WQFN	RTW	24	1000	208.0	191.0	35.0
LMX2491RTWT	WQFN	RTW	24	250	208.0	191.0	35.0



PLASTIC QUAD FLATPACK - NO LEAD

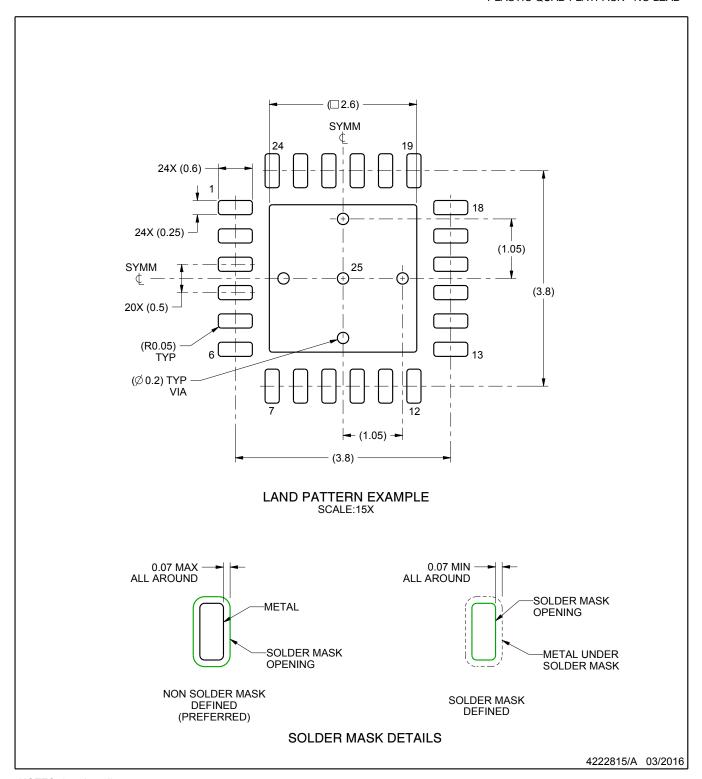


NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
 2. This drawing is subject to change without notice.
- 3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.



PLASTIC QUAD FLATPACK - NO LEAD



NOTES: (continued)

4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).



PLASTIC QUAD FLATPACK - NO LEAD



NOTES: (continued)

5. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



重要声明和免责声明

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