

# TRF7964A 多协议全集成式 13.56MHz RFID 读写器 IC

## 1 器件概述

### 1.1 特性

- 完全集成了以下标准的协议处理：ISO/IEC 15693、ISO/IEC 18000-3、ISO/IEC 14443 A 和 B 以及 FeliCa™
- 通过集成的状态机实现 ISO/IEC 14443 A 防撞（破坏的字节）
- 输入电压范围：2.7VDC 至 5.5VDC
- 可编程输出功率：+20dBm (100mW)，+23dBm (200mW)
- 从 1.8VDC 至 5.5 VDC 的可编程 I/O 电压电平
- 来自 13.56MHz 或者 27.12MHz 晶振或者振荡器的可编程系统时钟频率输出 (RF, RF/2, RF/4)
- 针对其它系统组件（微控制器 (MCU)，外设，指示器）的集成电压稳压器输出，20mA（最大值）
- 可编程调制深度
- 具有针对“读取漏洞”消除和邻近读取器系统或者周围环境频带内噪声检测的具有接收信号强度指示器 (RSSI) 的双接收器架构
- 针对超低功耗系统设计的可编程功率模式（断电时 < 1μA）
- 并行或 SPI 接口（带有 127 字节 FIFO）
- 温度范围：-40°C 至 110°C
- 32 引脚 QFN 封装 (5mm x 5mm)

### 1.2 应用范围

- 公共运输或者赛事票务
- 护照或者付费 (POS) 读取器系统
- 产品识别或者认证
- 医疗设备或者消耗品
- 访问控制、数字门锁

### 1.3 说明

TRF7964A 器件是集成式模拟前端 (AFE) 和多协议数据组帧器件，适用于 13.56MHz NFC/RFID 读写器系统，支持 ISO/IEC 14443 A 和 B、Sony FeliCa 以及 ISO/IEC 15693。与超集器件 TRF7970A 之间实现了引脚到引脚兼容以及固件兼容。该器件具有内置的编程选项，因此适合于接近和邻近识别系统的广泛应用。

通过在控制寄存器内选择所需的协议可对此器件进行配置。通过对所有控制寄存器进行直接存取，可根据需要对不同的读取器参数进行微调。

TRF7964A 器件针对所有符合板载 ISO 协议的组帧和同步任务，支持高达 848kbps 的数据速率。可通过使用该器件提供的直接模式之一来实现其他标准甚至自定义协议。这些直接模式可让用户完全控制 AFE，并且还可以访问原始子载波数据或者未组帧但已经是 ISO 格式的数据和相关（提取的）时钟信号。

接收器系统具有双输入接收器架构，可最大程度实现通信稳定。接收器还包括多种自动和手动增益控制选项。在 RSSI 寄存器中可获取从应答器、周围信号源或者内部电平接收到的信号强度。

可使用 SPI 或并行接口进行 MCU 和 TRF7964A 器件间的通信。当使用内置的硬件编码器和解码器时，发送和接收功能使用一个 127 字节的 FIFO 寄存器。对于直接发送或接收功能，由于编码器或解码器可被旁路绕开，所以 MCU 可实时地处理数据。

TRF7964A 器件支持 2.7V 至 5.5V 的宽电源电压范围以及 MCU I/O 接口的 1.8V 至 5.5V 数据通信电平。

当使用 5V 电源时，发送器对于 50Ω 负载具有 100mW (+20dBm) 或 200mW (+23dBm) 等效值的可选输出功率电平，并支持可选调制深度的 OOK 和 ASK 调制。

内置的可编程辅助稳压器为 MCU 和读取器系统内的其他外部电路提供高达 20mA 的电源。

要评估 TRF7964A 多协议收发器 IC，可使用该超集器件的 TRF7970AEVM、TRF7970ATB 或 DLP-7970ABP。

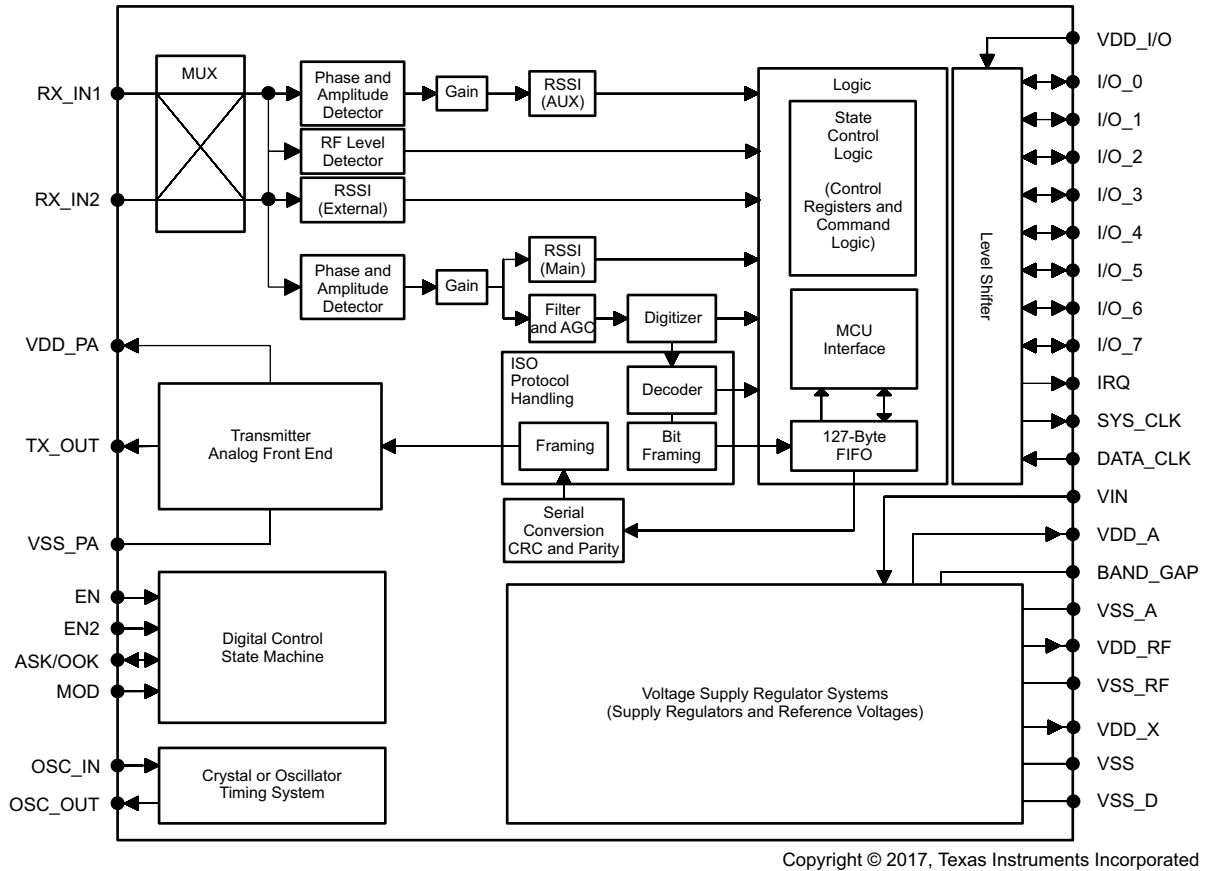


器件信息

器件型号	封装	封装尺寸
TRF7964ARHB	VQFN (32)	5mm x 5mm

1.4 功能方框图

图 1-1 显示了方框图。



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图 1-1. 方框图

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## 2 修订历史记录

注：之前版本的页码可能与当前版本有所不同。

Changes from April 18, 2014 to March 27, 2017	Page
• 更改了以下部分的内容：节 1.3 - 说明 .....	<a href="#">1</a>
• Added Section 3.1, <i>Related Products</i> .....	<a href="#">5</a>
• Moved T <sub>STG</sub> from Section 5.2 to Section 5.1, <i>Absolute Maximum Ratings</i> .....	<a href="#">8</a>
• Moved Section 5.2 and changed title from <i>Handling Ratings</i> to <i>ESD Ratings</i> .....	<a href="#">8</a>
• Added V <sub>OL</sub> and V <sub>OH</sub> to Section 5.4, <i>Electrical Characteristics</i> .....	<a href="#">9</a>
• Changed the TYP value of the f <sub>D,CLKmax</sub> parameter from 8 to 4 MHz in Section 5.4, <i>Electrical Characteristics</i> .....	<a href="#">9</a>
• Throughout document, removed support for application control of Automatic Gain Control (AGC) and Receiver Gain Adjust, because these features were designed for test functionality and not for production use .....	<a href="#">11</a>
• Added the sentence that starts "For applications in which the TRF7964A may be subjected..." in the second paragraph of Section 6.3, <i>Power Supplies</i> .....	<a href="#">12</a>
• Changed V <sub>DD,A</sub> to V <sub>DD,X</sub> in the last sentence that reads "The V <sub>DD,X</sub> output current should not exceed 20 mA." in the NOTE in <i>Analog Supply Regulator: V<sub>DD,A</sub></i> .....	<a href="#">13</a>
• Removed the paragraph that started "The RF power amplifier regulator..." from <i>Digital Supply Regulator: V<sub>DD,X</sub></i> .....	<a href="#">13</a>
• Changed 250 mV to 400 mV in "...a "Delta Voltage" of 400 mV below V <sub>IN</sub> ..." .....	<a href="#">13</a>
• Added the paragraph that starts "As V <sub>DD,RF</sub> is increased, the system..." in Section 6.3.2, <i>Supply Regulator Settings</i> .....	<a href="#">15</a>
• Removed the paragraphs that started "The main receiver also has..." and "By default, the AGC window comparator..." from Section 6.4.2, <i>Receiver Gain and Filter Stages</i> .....	<a href="#">18</a>
• Changed Table 6-5 to match Table 6-31 .....	<a href="#">19</a>
• Updated Section 6.5, <i>Receiver – Digital Section</i> , to clarify and remove duplicate content .....	<a href="#">19</a>
• Updated the description in Section 6.5.1.2, <i>External RSSI</i> .....	<a href="#">23</a>
• Removed "Equivalent Series Resistance" from Table 6-8, <i>Minimum Crystal Recommendations</i> .....	<a href="#">25</a>
• Removed mention of 3-wire SPI and replaced "IRQ" with "Slave Select" in the first paragraph of Section 6.10.1, <i>General Introduction</i> .....	<a href="#">27</a>
• Updated the description of FIFO level interrupts in Section 6.10.1.4, <i>FIFO Operation</i> .....	<a href="#">31</a>
• Added "but recommended" to "It is optional but recommended to read the FIFO Status register..." in Section 6.10.3, <i>Reception of Air Interface Data</i> .....	<a href="#">33</a>
• Changed the title of Section 6.10.4, <i>Data Transmission From MCU to TRF7964A</i> .....	<a href="#">34</a>
• Removed the sentence that started "The choice of one of these modes over another..." from Section 6.10.5, <i>Serial Interface Communication (SPI)</i> .....	<a href="#">34</a>
• Updated the paragraph that starts "TI recommends resetting the FIFO after receiving data..." in Section 6.10.5.1, <i>Serial Interface Mode With Slave Select (SS)</i> .....	<a href="#">39</a>
• Added the NOTE that starts "An additional direct mode..." in Section 6.10.6, <i>Direct Mode</i> .....	<a href="#">40</a>
• Added Section 6.11, <i>TRF7964A Initialization</i> .....	<a href="#">45</a>
• Changed the application report that is referenced in Section 6.12, <i>Special Direct Mode for Improved MIFARE™ Compatibility</i> .....	<a href="#">46</a>
• Added and updated comments in Table 6-14, <i>Address and Command Word Bit Distribution</i> .....	<a href="#">46</a>
• Added the sentence that starts "This command should be sent after a Software Initialization command..." in Section 6.13.1.1, <i>Idle (0x00)</i> .....	<a href="#">46</a>
• Removed unsupported registers (addresses 0x15 to 0x19) in Table 6-16, <i>Register Values After Sending Software Initialization (0x03)</i> .....	<a href="#">47</a>
• Added "This is used by the ISO/IEC 15693 protocol" to Section 6.13.1.8, <i>Transmit Next Time Slot (0x14)</i> .....	<a href="#">48</a>
• Corrected description of B1 Irq_col in Table 6-37, <i>IRQ Status Register (0x0C)</i> : changed from "(as defined in register 0x01)" to "(as defined in register 0x10)" .....	<a href="#">60</a>
• Changed the description of B5:B3 in Table 6-40 from "...Auxiliary RSSI represents the signal level at RX_IN2" to "...Auxiliary RSSI represents the signal level at RX_IN1" .....	<a href="#">62</a>
• Removed former Section 7.1, <i>TRF7964A Reader System Using Parallel Microcontroller Interface</i> .....	<a href="#">67</a>
• Updated the description in Section 7.1.2, <i>Schematic</i> .....	<a href="#">67</a>
• 添加了节 8.1“入门和后续步骤” .....	<a href="#">70</a>
• 添加了节 8.2“器件命名规则” .....	<a href="#">70</a>
• 添加了节 8.3“工具和软件” .....	<a href="#">71</a>
• 更新了节 8.4“文档支持” .....	<a href="#">71</a>

### 3 Device Characteristics

[Table 3-1](#) lists the supported modes of operation for the TRF7964A device.

**Table 3-1. Supported Protocols**

SUPPORTED PROTOCOLS					
ISO/IEC 14443 A and B				ISO/IEC 15693, ISO/IEC 18000-3 (Mode 1)	FeliCa
106 kbps	212 kbps	424 kbps	848 kbps		212 kbps, 424 kbps
✓	✓	✓	✓	✓	✓

#### 3.1 Related Products

For information about other devices in this family of products or related products, see the following links.

**Products for TI Wireless Connectivity** Connect more with the industry's broadest wireless connectivity portfolio.

**Products for NFC / RFID** TI provides one of the industry's most differentiated NFC and RFID product portfolios and is your solution to meet a broad range of NFC connectivity and RFID identification needs.

**Companion Products for TRF7964A** Review products that are frequently purchased or used with this product.

**Reference Designs for TRF7964A** The TI Designs Reference Design Library is a robust reference design library that spans analog, embedded processor, and connectivity. Created by TI experts to help you jump start your system design, all TI Designs include schematic or block diagrams, BOMs, and design files to speed your time to market. Search and download designs at [ti.com/tidesigns](http://ti.com/tidesigns).

## 4 Terminal Configuration and Functions

### 4.1 Pin Diagram

Figure 4-1 shows the pinout for the 32-pin RHB package.

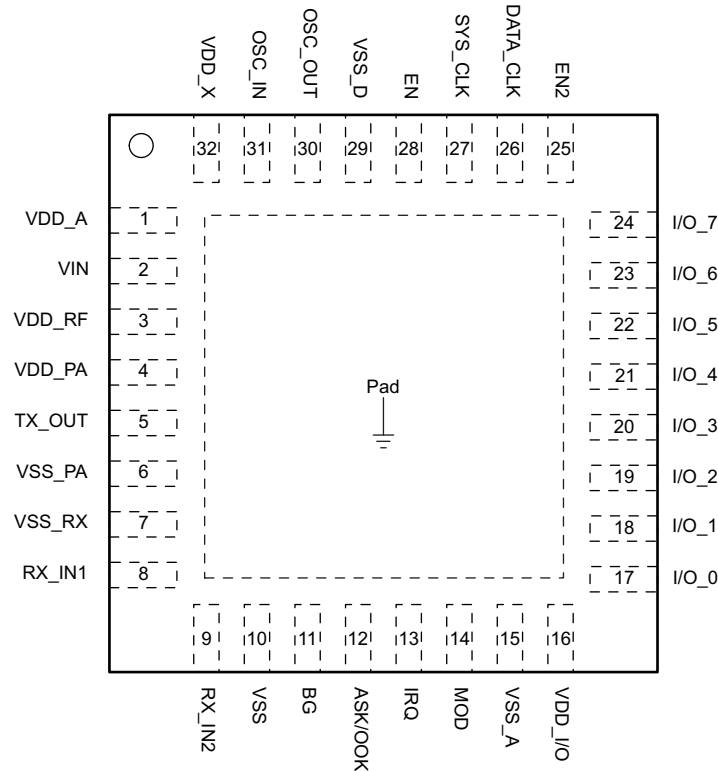


Figure 4-1. 32-Pin RHB Package (Top View)

### 4.2 Signal Descriptions

Table 4-1 describes the signals.

Table 4-1. Terminal Functions

TERMINAL		TYPE (1)	DESCRIPTION
NAME	NO.		
V <sub>DD_A</sub>	1	OUT	Internal regulated supply (2.7 V to 3.4 V) for analog circuitry
V <sub>IN</sub>	2	SUP	External supply input to chip (2.7 V to 5.5 V)
V <sub>DD_RF</sub>	3	OUT	Internal regulated supply (2.7 V to 5 V), normally connected to V <sub>DD_PA</sub> (pin 4)
V <sub>DD_PA</sub>	4	INP	Supply for PA; normally connected externally to V <sub>DD_RF</sub> (pin 3)
TX_OUT	5	OUT	RF output (selectable output power, 100 mW or 200 mW, with V <sub>DD</sub> = 5 V)
V <sub>SS_PA</sub>	6	SUP	Negative supply for PA; normally connected to circuit ground
V <sub>SS_RX</sub>	7	SUP	Negative supply for RX inputs; normally connected to circuit ground
RX_IN1	8	INP	Main RX input
RX_IN2	9	INP	Auxiliary RX input
V <sub>SS</sub>	10	SUP	Chip substrate ground
BAND_GAP	11	OUT	Bandgap voltage (V <sub>BG</sub> = 1.6 V); internal analog voltage reference
ASK/OOK	12	BID	Selection between ASK and OOK modulation (0 = ASK, 1 = OOK) for direct mode 0 or 1. Can be configured as an output to provide the received analog signal output.

(1) SUP = Supply, INP = Input, BID = Bidirectional, OUT = Output

**Table 4-1. Terminal Functions (continued)**

TERMINAL		TYPE <sup>(1)</sup>	DESCRIPTION
NAME	NO.		
IRQ	13	OUT	Interrupt request
MOD	14	INP	External data modulation input for direct mode 0 or 1
		OUT	Subcarrier digital data output (see registers 0x1A and 0x1B)
V <sub>SS_A</sub>	15	SUP	Negative supply for internal analog circuits; connected to GND
V <sub>DD_I/O</sub>	16	INP	Supply for I/O communications (1.8 V to V <sub>IN</sub> ) level shifter. V <sub>IN</sub> should be never exceeded.
I/O_0	17	BID	I/O pin for parallel communication
I/O_1	18	BID	I/O pin for parallel communication
I/O_2	19	BID	I/O pin for parallel communication TX enable (in special direct mode)
I/O_3	20	BID	I/O pin for parallel communication TX data (in special direct mode)
I/O_4	21	BID	I/O pin for parallel communication Slave select signal in SPI mode
I/O_5	22	BID	I/O pin for parallel communication Data clock output in direct mode 1 and special direct mode
I/O_6	23	BID	I/O pin for parallel communication
			MISO for serial communication (SPI) Serial bit data output in direct mode 1 or subcarrier signal in direct mode 0
I/O_7	24	BID	I/O pin for parallel communication.
			MOSI for serial communication (SPI)
EN2	25	INP	Selection of power down mode. If EN2 is connected to V <sub>IN</sub> , then V <sub>DD_X</sub> is active during power down mode 2 (for example, to supply the MCU).
DATA_CLK	26	INP	Data clock input for MCU communication (parallel and serial)
SYS_CLK	27	OUT	If EN = 1 (EN2 = don't care) the system clock for MCU is configured. Depending on the crystal that is used, options are as follows (see register 0x09): 13.56-MHz crystal: Off, 3.39 MHz, 6.78 MHz, or 13.56 MHz 27.12-MHz crystal: Off, 6.78 MHz, 13.56 MHz, or 27.12 MHz If EN = 0 and EN2 = 1, then system clock is set to 60 kHz
EN	28	INP	Chip enable input (If EN = 0, then chip is in sleep or power-down mode).
V <sub>SS_D</sub>	29	SUP	Negative supply for internal digital circuits
OSC_OUT	30	OUT	Crystal or oscillator output
OSC_IN	31	INP	Crystal or oscillator input
		OUT	Crystal oscillator output
V <sub>DD_X</sub>	32	OUT	Internally regulated supply (2.7 V to 3.4 V) for digital circuit and external devices (for example, an MCU)
Thermal Pad	PAD	SUP	Chip substrate ground

## 5 Specifications

### 5.1 Absolute Maximum Ratings<sup>(1) (2)</sup>

over operating free-air temperature range (unless otherwise noted)

		MIN	MAX	UNIT	
$V_{IN}$	Input voltage range	-0.3	6	V	
$I_{IN}$	Maximum current $V_{IN}$		150	mA	
$T_J$	Maximum operating virtual junction temperature	Any condition		140	°C
		Continuous operation, long-term reliability <sup>(3)</sup>		125	°C
$T_{STG}$	Storage temperature	-55	150	°C	

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions* are not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) All voltage values are with respect to substrate ground terminal  $V_{SS}$ .
- (3) The maximum junction temperature for continuous operation is limited by package constraints. Operation above this temperature may result in reduced reliability or lifetime of the device.

### 5.2 ESD Ratings

		VALUE	UNIT	
$V_{(ESD)}$	Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins <sup>(1)</sup>	±2000	V
		Charged-device model (CDM), per JEDEC specification JESD22-C101, all pins <sup>(2)</sup>	±500	V
		Machine model (MM)	±200	V

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process. Pins listed as ±2000 V may actually have higher performance.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process. Pins listed as ±500 V may actually have higher performance.

### 5.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	TYP	MAX	UNIT
$V_{IN}$	Operating input voltage	2.7	5	5.5	V
$T_A$	Operating ambient temperature	-40	25	110	°C
$T_J$	Operating virtual junction temperature	-40	25	125	°C
$V_{IL}$	Input voltage, logic low	I/O lines, IRQ, SYS_CLK, DATA_CLK, EN, EN2, ASK/OOK, MOD		$0.2 \times V_{DD\_I/O}$	V
$V_{IH}$	Input voltage threshold, logic high	I/O lines, IRQ, SYS_CLK, DATA_CLK, EN, EN2, ASK/OOK, MOD		$0.8 \times V_{DD\_I/O}$	V



## 5.4 Electrical Characteristics

TYP operating conditions are  $T_A = 25^\circ\text{C}$ ,  $V_{IN} = 5\text{ V}$ , full-power mode (unless otherwise noted)

MIN and MAX operating conditions are over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{OL}$	Low-level output voltage			$0.2 \times V_{DD\_I/O}$		V
$V_{OH}$	High-level output voltage			$0.8 \times V_{DD\_I/O}$		V
$I_{PD1}$	Supply current in power down mode 1	All building blocks disabled, including supply-voltage regulators; measured after 500-ms settling time ( $EN = 0$ , $EN2 = 0$ )		0.5	5	$\mu\text{A}$
$I_{PD2}$	Supply current in power down mode 2 (sleep mode)	The $SYS\_CLK$ generator and $V_{DD\_X}$ remain active to support external circuitry; measured after 100-ms settling time ( $EN = 0$ , $EN2 = 1$ )		120	200	$\mu\text{A}$
$I_{STBY}$	Supply current in stand-by mode	Oscillator running, supply-voltage regulators in low-consumption mode ( $EN = 1$ , $EN2 = x$ )		1.9	3.5	mA
$I_{ON1}$	Supply current without antenna driver current	Oscillator, regulators, RX and AGC active, TX is off		10.5	14	mA
$I_{ON2}$	Supply current, TX (half power)	Oscillator, regulators, RX and AGC and TX active, $P_{OUT} = 100\text{ mW}$		70	78	mA
$I_{ON3}$	Supply current, TX (full power)	Oscillator, regulators, RX and AGC and TX active, $P_{OUT} = 200\text{ mW}$		130	150	mA
$V_{POR}$	Power-on-reset voltage	Input voltage at $V_{IN}$	1.4	2	2.6	V
$V_{BG}$	Bandgap voltage (pin 11)	Internal analog reference voltage	1.5	1.6	1.7	V
$V_{DD\_A}$	Regulated output voltage for analog circuitry (pin 1)	$V_{IN} = 5\text{ V}$	3.1	3.4	3.8	V
$V_{DD\_X}$	Regulated supply for external circuitry	Output voltage pin 32, $V_{IN} = 5\text{ V}$	3.1	3.4	3.8	V
$I_{VDD\_Xmax}$	Maximum output current of $V_{DD\_X}$	Output current pin 32, $V_{IN} = 5\text{ V}$			20	mA
$R_{RFOUT}$	Antenna driver output resistance <sup>(1)</sup>	Half-power mode, $V_{IN} = 2.7\text{ V to }5.5\text{ V}$		8	12	$\Omega$
		Full-power mode, $V_{IN} = 2.7\text{ V to }5.5\text{ V}$		4	6	
$R_{RFIN}$	RX_IN1 and RX_IN2 input resistance		4	10	20	k $\Omega$
$V_{RF\_INmax}$	Maximum RF input voltage at RX_IN1 and RX_IN2	$V_{RF\_INmax}$ should not exceed $V_{IN}$		3.5		$V_{pp}$
$V_{RF\_INmin}$	Minimum RF input voltage at RX_IN1 and RX_IN2 (input sensitivity) <sup>(2)</sup>	$f_{SUBCARRIER} = 424\text{ kHz}$		1.4	2.5	m $V_{pp}$
		$f_{SUBCARRIER} = 848\text{ kHz}$		2.1	3	
$f_{SYS\_CLK}$	$SYS\_CLK$ frequency	In power mode 2, $EN = 0$ , $EN2 = 1$	25	60	120	kHz
$f_C$	Carrier frequency	Defined by external crystal		13.56		MHz
$t_{CRYSTAL}$	Crystal run-in time	Time until oscillator stable bit is set (register 0x0F) <sup>(3)</sup>		3		ms
$f_{D\_CLKmax}$	Maximum DATA_CLK frequency <sup>(4)</sup>	Depends on capacitive load on the I/O lines, TI recommends 2 MHz <sup>(4)</sup>	2	4	10	MHz
$R_{OUT}$	Output resistance I/O_0 to I/O_7			500	800	$\Omega$
$R_{SYS\_CLK}$	Output resistance $R_{SYS\_CLK}$			200	400	$\Omega$

(1) Antenna driver output resistance

(2) Measured with subcarrier signal at RX\_IN1 or RX\_IN2 and measured the digital output at MOD pin with register 0x1A bit 6 = 1.

(3) Depends on the crystal parameters and components

(4) TI recommends a DATA\_CLK speed of 2 MHz. Higher data clock depends on the capacitive load. Maximum SPI clock speed should not exceed 10 MHz. This clock speed is acceptable only when external capacitive load is less than 30 pF. MISO driver has a typical output resistance of 400  $\Omega$  (12-ns time constant when 30-pF load used).

## 5.5 Thermal Resistance Characteristics

PACKAGE	$\theta_{JC}$	$\theta_{JA}^{(1)}$	POWER RATING <sup>(2)</sup>	
			$T_A \leq 25^\circ\text{C}$	$T_A \leq 85^\circ\text{C}$
RHB (32 pin)	31°C/W	36.4°C/W	2.7 W	1.1 W

(1) This data was taken using the JEDEC standard high-K test PCB.

(2) Power rating is determined with a junction temperature of 125°C. This is the temperature at which distortion starts to increase substantially. Thermal management of the final PCB should strive to keep the junction temperature at or below 125°C for best performance and long-term reliability.

## 5.6 Switching Characteristics

TYP operating conditions are  $T_A = 25^\circ\text{C}$ ,  $V_{IN} = 5\text{ V}$ , full-power mode (unless otherwise noted)

MIN and MAX operating conditions are over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$t_{LO/HI}$	DATA_CLK time high or low, one half of DATA_CLK at 50% duty cycle	Depends on capacitive load on the I/O lines <sup>(1)</sup>	250	62.5	50	ns
$t_{STE,LEAD}$	Slave select lead time, slave select low to clock			200		ns
$t_{STE,LAG}$	Slave select lag time, last clock to slave select high			200		ns
$t_{STE,DIS}$	Slave select disable time, slave select rising edge to next slave select falling edge		300			ns
$t_{SU,SI}$	MOSI input data setup time		15			ns
$t_{HD,SI}$	MOSI input data hold time		15			ns
$t_{SU,SO}$	MISO input data setup time		15			ns
$t_{HD,SO}$	MISO input data hold time		15			ns
$t_{VALID,SO}$	MISO output data valid time	DATA_CLK edge to MISO valid, $C_L \leq 30\text{ pF}$	30	50	75	ns

(1) TI recommends a DATA\_CLK speed of 2 MHz. Higher data clock depends on the capacitive load. Maximum SPI clock speed should not exceed 10 MHz. This clock speed is acceptable only when external capacitive load is less than 30 pF. MISO driver has a typical output resistance of 400  $\Omega$  (12-ns time constant when 30-pF load used).

## 6 Detailed Description

### 6.1 Overview

#### 6.1.1 RFID – Reader and Writer

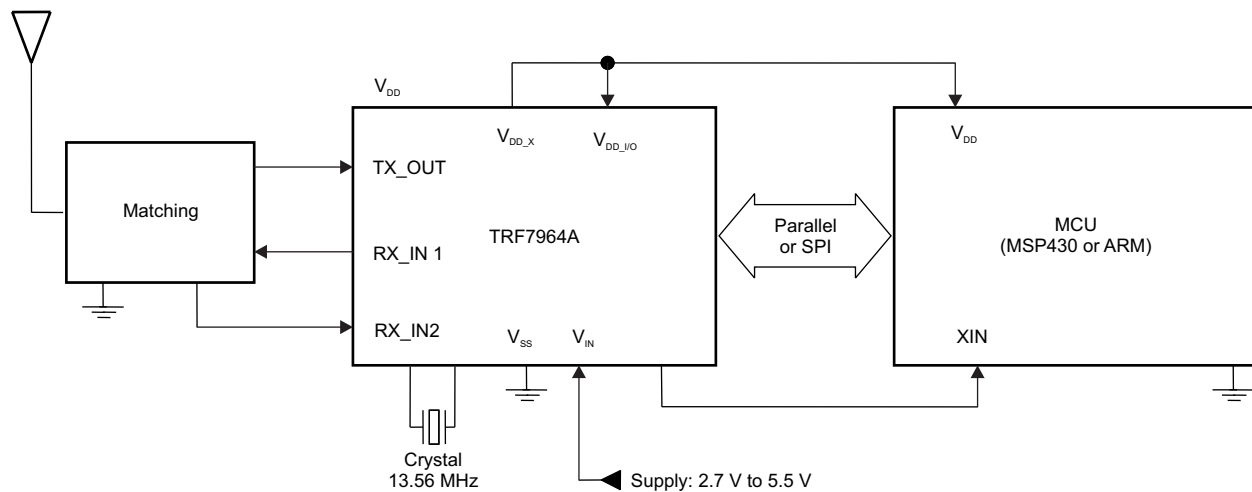
The is a high-performance 13.56-MHz HF RFID transceiver IC composed of an integrated analog front end (AFE) and a built-in data framing engine for ISO/IEC 15693, ISO/IEC 14443 A and B, and FeliCa. This includes data rates up to 848 kbps for ISO/IEC 14443 with all framing and synchronization tasks on board (in default mode). This architecture lets the customer build a complete cost-effective yet high-performance multiprotocol 13.56-MHz RFID system together with a low-cost microcontroller.

Other standards and even custom protocols can be implemented by using either of the direct modes that the device offers. These direct modes (0 and 1) allow the user to fully control the analog front end (AFE) and also gain access to the raw subcarrier data or the unframed but already ISO formatted data and the associated (extracted) clock signal.

The receiver system has a dual input receiver architecture. The receivers also include various automatic and manual gain control options. The received input bandwidth can be selected to cover a broad range of input subcarrier signal options.

The received signal strength from transponders, ambient sources, or internal levels is available through the RSSI register. The receiver output is selectable among a digitized subcarrier signal and any of the integrated subcarrier decoders. The selected subcarrier decoder delivers the data bit stream and the data clock as outputs.

The TRF7964A also includes a receiver framing engine. This receiver framing engine performs the CRC or parity check, removes the EOF and SOF settings, and organizes the data in bytes for ISO/IEC 14443 A and B, ISO/IEC 15693, and FeliCa protocols. Framed data is then accessible to the microcontroller (MCU) through a 127-byte FIFO register.



**Figure 6-1. Application Block Diagram**

A parallel or serial interface (SPI) can be used for the communication between the MCU and the TRF7964A reader. When the built-in hardware encoders and decoders are used, transmit and receive functions use a 127-byte FIFO register. For direct transmit or receive functions, the encoders and decoders can be bypassed so that the MCU can process the data in real time. The TRF7964A supports data communication voltage levels from 1.8 V to 5.5 V for the MCU I/O interface. The transmitter has selectable output-power levels of 100 mW (+20 dBm) or 200 mW (+23 dBm) equivalent into a 50-Ω load when using a 5-V supply.

The transmitter supports OOK and ASK modulation with selectable modulation depth. The TRF7964A also includes a data transmission engine that comprises low-level encoding for ISO/IEC 15693, ISO/IEC 14443 A and B, and FeliCa. Included with the transmit data coding is the automatic generation of Start Of Frame (SOF), End Of Frame (EOF), Cyclic Redundancy Check (CRC), and parity bits.

Several integrated voltage regulators ensure a proper power-supply noise rejection for the complete reader system. The built-in programmable auxiliary voltage regulator  $V_{DD\_X}$  (pin 32), is able to deliver up to 20 mA to supply a microcontroller and additional external circuits within the reader system.

## 6.2 System Block Diagram

Figure 6-2 shows a block diagram of the TRF7964A.

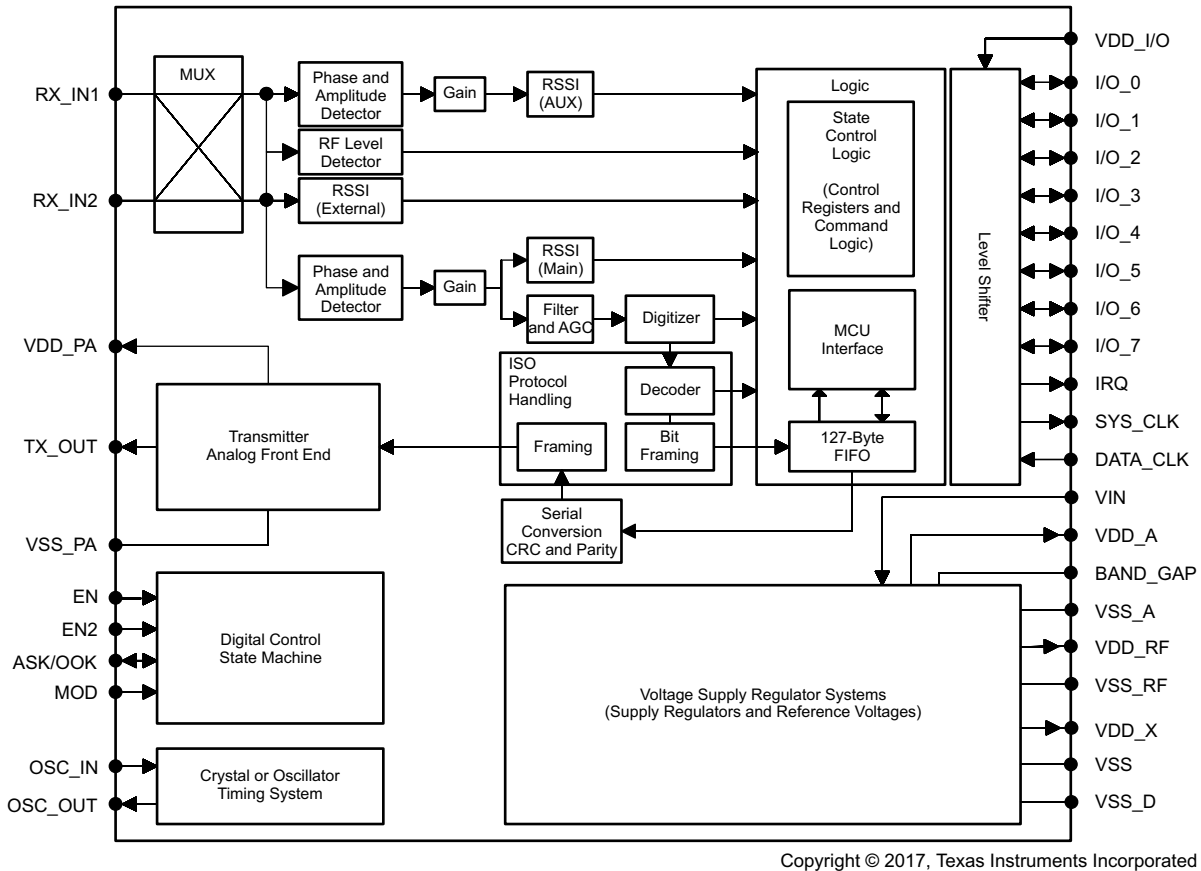


Figure 6-2. System Block Diagram

## 6.3 Power Supplies

The TRF7964A positive supply input  $V_{IN}$  (pin 2) sources three internal regulators with output voltages  $V_{DD\_RF}$ ,  $V_{DD\_A}$  and  $V_{DD\_X}$ . All regulators use external bypass capacitors for supply noise filtering and must be connected as indicated in reference schematics. These regulators provide a high power supply reject ratio (PSRR) as required for RFID reader systems. All regulators are supplied by  $V_{IN}$  (pin 2).

The regulators are not independent and have common control bits in register 0x0B for output voltage setting. The regulators can be configured to operate in either automatic or manual mode (register 0x0B, bit 7). The automatic regulator setting mode ensures an optimal compromise between PSRR and the highest possible supply voltage for RF output (to ensure maximum RF power output). The manual mode allows the user to manually configure the regulator settings. For applications in which the TRF7964A may be subjected to external noise, manually reducing the regulator settings can improve RF performance.

### 6.3.1 Supply Arrangements

#### Regulator Supply Input: $V_{IN}$

The positive supply at  $V_{IN}$  (pin 2) has an input voltage range of 2.7 V to 5.5 V.  $V_{IN}$  provides the supply input sources for three internal regulators with the output voltages  $V_{DD\_RF}$ ,  $V_{DD\_A}$ , and  $V_{DD\_X}$ . External bypass capacitors for supply noise filtering must be used (per reference schematics).

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#### NOTE

$V_{IN}$  must be the highest voltage supplied to the TRF7964A.

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#### RF Power Amplifier Regulator: $V_{DD\_RF}$

The  $V_{DD\_RF}$  (pin 3) regulator is supplying the RF power amplifier. The voltage regulator can be set for either 5-V or 3-V operation. External bypass capacitors for supply noise filtering must be used (per reference schematics). When configured for 5-V manual-operation, the  $V_{DD\_RF}$  output voltage can be set from 4.3 V to 5 V in 100-mV steps. In 3-V manual-operation, the output can be programmed from 2.7 V to 3.4 V in 100-mV steps. The maximum output current capability for 5-V operation is 150 mA and for 3-V operation is 100 mA.

#### Analog Supply Regulator: $V_{DD\_A}$

Regulator  $V_{DD\_A}$  (pin 1) supplies the analog circuits of the device. The output voltage setting depends on the input voltage and can be set for 5-V and 3-V operation. When configured for 5-V manual-operation, the output voltage is fixed at 3.4 V. External bypass capacitors for supply noise filtering must be used (per reference schematics). When configured for 3-V manual-operation, the  $V_{DD\_A}$  output can be set from 2.7 V to 3.4 V in 100-mV steps (see [Table 6-2](#)).

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#### NOTE

The configuration of  $V_{DD\_A}$  and  $V_{DD\_X}$  regulators are not independent from each other. The  $V_{DD\_X}$  output current should not exceed 20 mA.

---

#### Digital Supply Regulator: $V_{DD\_X}$

The digital supply regulator  $V_{DD\_X}$  (pin 32) provides the power for the internal digital building blocks and can also be used to supply external electronics within the reader system. When configured for 3-V operation, the output voltage can be set from 2.7 to 3.4 V in 100-mV steps. External bypass capacitors for supply noise filtering must be used (per reference schematics).

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#### NOTE

The configuration of the  $V_{DD\_A}$  and  $V_{DD\_X}$  regulators are not independent from each other. The  $V_{DD\_X}$  output current should not exceed 20 mA.

---

By default, the regulators are set in automatic regulator setting mode. In this mode, the regulators are automatically set every time the system is activated by setting EN input High or each time the automatic regulator setting bit, B7 in register 0x0B is set to a 1. The action is started on the 0 to 1 transition. This means that, if the user wants to rerun the automatic setting from a state in which the automatic setting bit is already high, the automatic setting bit (B7 in register 0x0B) should be changed: 1-0-1.

By default, the regulator setting algorithm sets the regulator outputs to a "Delta Voltage" of 400 mV below  $V_{IN}$ , but not higher than 5 V for  $V_{DD\_RF}$  and 3.4 V for  $V_{DD\_A}$  and  $V_{DD\_A}$ .

**Power Amplifier Supply:  $V_{DD\_PA}$** 

The power amplifier of the TRF7964A is supplied through  $V_{DD\_PA}$  (pin 4). The positive supply pin for the RF power amplifier is externally connected to the regulator output  $V_{DD\_RF}$  (pin 3).

**I/O Level Shifter Supply:  $V_{DD\_I/O}$** 

The TRF7964A has a separate supply input  $V_{DD\_I/O}$  (pin 16) for the built-in I/O level shifter. The supported input voltage ranges from 1.8 V to  $V_{IN}$ , not exceeding 5.5 V. Pin 16 is used to supply the I/O interface pins (I/O\_0 to I/O\_7), IRQ, SYS\_CLK, and DATA\_CLK pins of the reader. In typical applications,  $V_{DD\_I/O}$  is directly connected to  $V_{DD\_X}$ , while  $V_{DD\_X}$  also supplies the MCU. This ensures that the I/O signal levels of the MCU match the logic levels of the TRF7964A.

**Negative Supply Connections:  $V_{SS}$ ,  $V_{SS\_TX}$ ,  $V_{SS\_RX}$ ,  $V_{SS\_A}$ ,  $V_{SS\_PA}$** 

The negative supply connections  $V_{SS\_X}$  of each functional block are all externally connected to GND.

The substrate connection is  $V_{SS}$  (pin 10), the analog negative supply is  $V_{SS\_A}$  (pin 15), the logic negative supply is  $V_{SS\_D}$  (pin 29), the RF output stage negative supply is  $V_{SS\_PA}$  (pin 6), and the negative supply for the RF receiver  $V_{SS\_RX}$  (pin 7).

### 6.3.2 Supply Regulator Settings

The input supply voltage mode of the reader needs to be selected. This is done in the Chip Status Control register (0x00). Bit 0 in register 0x00 selects between 5-V or 3-V input supply voltage. The default configuration is 5 V, which reflects an operating supply voltage range of 4.3 V to 5.5 V. If the supply voltage is below 4.3 V, the 3-V configuration should be used.

As  $V_{DD\_RF}$  is increased, the system can become more susceptible to noise coupling on the RX lines. For minimum noise coupling, TI recommends using the value of 0x00. For improved range, higher  $V_{DD\_RF}$  voltages may be set, but complete system testing is required to determine the value which provides optimal performance.

The various regulators can be configured to operate in automatic or manual mode. This is done in the Regulator and I/O Control register (0x0B), as shown in [Table 6-1](#) and [Table 6-2](#).

**Table 6-1. Supply Regulator Setting: 5-V System**

REGISTER ADDRESS (hex)	OPTION BITS SETTING IN REGULATOR CONTROL REGISTER <sup>(1)</sup>								COMMENTS
	B7	B6	B5	B4	B3	B2	B1	B0	
<b>Automatic Mode (default)</b>									
0B	1	x	x	x	x	x	0	0	Automatic regulator setting 400-mV difference
<b>Manual Mode</b>									
0B	0	x	x	x	x	1	1	1	$V_{DD\_RF} = 5\text{ V}$ , $V_{DD\_A} = 3.4\text{ V}$ , $V_{DD\_X} = 3.4\text{ V}$
0B	0	x	x	x	x	1	1	0	$V_{DD\_RF} = 4.9\text{ V}$ , $V_{DD\_A} = 3.4\text{ V}$ , $V_{DD\_X} = 3.4\text{ V}$
0B	0	x	x	x	x	1	0	1	$V_{DD\_RF} = 4.8\text{ V}$ , $V_{DD\_A} = 3.4\text{ V}$ , $V_{DD\_X} = 3.4\text{ V}$
0B	0	x	x	x	x	1	0	0	$V_{DD\_RF} = 4.7\text{ V}$ , $V_{DD\_A} = 3.4\text{ V}$ , $V_{DD\_X} = 3.4\text{ V}$
0B	0	x	x	x	x	0	1	1	$V_{DD\_RF} = 4.6\text{ V}$ , $V_{DD\_A} = 3.4\text{ V}$ , $V_{DD\_X} = 3.4\text{ V}$
0B	0	x	x	x	x	0	1	0	$V_{DD\_RF} = 4.5\text{ V}$ , $V_{DD\_A} = 3.4\text{ V}$ , $V_{DD\_X} = 3.4\text{ V}$
0B	0	x	x	x	x	0	0	1	$V_{DD\_RF} = 4.4\text{ V}$ , $V_{DD\_A} = 3.4\text{ V}$ , $V_{DD\_X} = 3.4\text{ V}$
0B	0	x	x	x	x	0	0	0	$V_{DD\_RF} = 4.3\text{ V}$ , $V_{DD\_A} = 3.4\text{ V}$ , $V_{DD\_X} = 3.4\text{ V}$

(1) x = Don't care

**Table 6-2. Supply Regulator Setting: 3-V System**

REGISTER ADDRESS (hex)	OPTION BITS SETTING IN REGULATOR CONTROL REGISTER <sup>(1)</sup>								COMMENTS
	B7	B6	B5	B4	B3	B2	B1	B0	
<b>Automatic Mode (default)</b>									
0B	1	x	x	x	x	x	0	0	Automatic regulator setting 400-mV difference
<b>Manual Mode</b>									
0B	0	x	x	x	x	1	1	1	$V_{DD\_RF} = 3.4\text{ V}$ , $V_{DD\_A} = 3.4\text{ V}$ , $V_{DD\_X} = 3.4\text{ V}$
0B	0	x	x	x	x	1	1	0	$V_{DD\_RF} = 3.3\text{ V}$ , $V_{DD\_A} = 3.3\text{ V}$ , $V_{DD\_X} = 3.3\text{ V}$
0B	0	x	x	x	x	1	0	1	$V_{DD\_RF} = 3.2\text{ V}$ , $V_{DD\_A} = 3.2\text{ V}$ , $V_{DD\_X} = 3.2\text{ V}$
0B	0	x	x	x	x	1	0	0	$V_{DD\_RF} = 3.1\text{ V}$ , $V_{DD\_A} = 3.1\text{ V}$ , $V_{DD\_X} = 3.1\text{ V}$
0B	0	x	x	x	x	0	1	1	$V_{DD\_RF} = 3.0\text{ V}$ , $V_{DD\_A} = 3.0\text{ V}$ , $V_{DD\_X} = 3.0\text{ V}$
0B	0	x	x	x	x	0	1	0	$V_{DD\_RF} = 2.9\text{ V}$ , $V_{DD\_A} = 2.9\text{ V}$ , $V_{DD\_X} = 2.9\text{ V}$
0B	0	x	x	x	x	0	0	1	$V_{DD\_RF} = 2.8\text{ V}$ , $V_{DD\_A} = 2.8\text{ V}$ , $V_{DD\_X} = 2.8\text{ V}$
0B	0	x	x	x	x	0	0	0	$V_{DD\_RF} = 2.7\text{ V}$ , $V_{DD\_A} = 2.7\text{ V}$ , $V_{DD\_X} = 2.7\text{ V}$

(1) x = Don't care

The regulator configuration function adjusts the regulator outputs by default to 400 mV below  $V_{IN}$  level, but not higher than 5 V for  $V_{DD\_RF}$ , 3.4 V for  $V_{DD\_A}$  and  $V_{DD\_X}$ . This ensures the highest possible supply voltage for the RF output stage while maintaining an adequate PSRR (power supply rejection ratio).

### 6.3.3 Power Modes

The chip has several power states, which are controlled by two input pins (EN and EN2) and several bits in the chip status control register (0x00) (see [Table 6-3](#) and [Table 6-4](#)).

**Table 6-3. 3.3-V Operation Power Modes<sup>(1)</sup>**

MODE	EN2	EN	CHIP STATUS CONTROL REGISTER (0x00)	REGULATOR CONTROL REGISTER (0x0B)	TRANSMITTER	RECEIVER	SYS_CLK (13.56 MHz)	SYS_CLK (60 kHz)	V <sub>DD,X</sub>	TYPICAL CURRENT (mA)	TYPICAL POWER OUT (dBm)
Power down	0	0	XX	XX	OFF	OFF	OFF	OFF	OFF	<0.001	-
Sleep mode	1	0	XX	XX	OFF	OFF	OFF	ON	ON	0.120	-
Standby mode at +3.3 VDC	X	1	80	00	OFF	OFF	ON	X	ON	2	-
Mode 1 at +3.3 VDC	X	1	00	00	OFF	OFF	ON	X	ON	3	-
Mode 2 at +3.3 VDC	X	1	02	00	OFF	ON	ON	X	ON	9	-
Mode 3 (half power) at +3.3 VDC	X	1	30	07	ON	ON	ON	X	ON	53	14.5
Mode 4 (full power) at +3.3 VDC	X	1	20	07	ON	ON	ON	X	ON	67	17

(1) X = Don't care

**Table 6-4. 5-V Operation Power Modes<sup>(1)</sup>**

MODE	EN2	EN	CHIP STATUS CONTROL REGISTER (0x00)	REGULATOR CONTROL REGISTER (0x0B)	TRANSMITTER	RECEIVER	SYS_CLK (13.56 MHz)	SYS_CLK (60 kHz)	V <sub>DD,X</sub>	TYPICAL CURRENT (mA)	TYPICAL POWER OUT (dBm)
Power down	0	0	XX	XX	OFF	OFF	OFF	OFF	OFF	<0.001	-
Sleep mode	1	0	XX	XX	OFF	OFF	OFF	ON	ON	0.120	-
Standby mode at +5 VDC	X	1	81	07	OFF	OFF	ON	X	ON	3	-
Mode 1 at +5 VDC	X	1	01	07	OFF	OFF	ON	X	ON	5	-
Mode 2 at +5 VDC	X	1	03	07	OFF	ON	ON	X	ON	10.5	-
Mode 3 (half power) at +5 VDC	X	1	31	07	ON	ON	ON	X	ON	70	20
Mode 4 (full power) at +5 VDC	X	1	21	07	ON	ON	ON	X	ON	130	23

(1) X = Don't care

[Table 6-3](#) and [Table 6-4](#) show the configuration for the different power modes when using a 3.3-V or 5-V system supply, respectively. The main reader enable signal is pin EN. When EN is set high, all of the reader regulators are enabled, the 13.56-MHz oscillator is running and the SYS\_CLK (output clock for external microcontroller) is also available.

The input pin EN2 has two functions:

- A direct connection from EN2 to V<sub>IN</sub> to ensure the availability of the regulated supply V<sub>DD,X</sub> and an auxiliary clock signal (60 kHz, SYS\_CLK) for an external MCU. This mode (EN = 0, EN2 = 1) is intended for systems in which the MCU is also being supplied by the reader supply regulator (V<sub>DD,X</sub>) and the MCU clock is supplied by the SYS\_CLK output of the reader. This allows the MCU supply and clock to be available during sleep mode.
- EN2 enables the start-up of the reader system from complete power down (EN = 0, EN2 = 0). In this case the EN input is being controlled by the MCU (or other system device) that is without supply voltage during complete power down (thus unable to control the EN input). A rising edge applied to the EN2 input (which has an approximately 1-V threshold level) starts the reader supply system and 13.56-MHz oscillator (identical to condition EN = 1).

When user MCU is controlling EN and EN2, a delay of 1 ms between EN and EN2 must be used. If the MCU controls only EN, TI recommends connecting EN2 to either V<sub>IN</sub> or GND, depending on the application MCU requirements for V<sub>DD,X</sub> and SYS\_CLK.



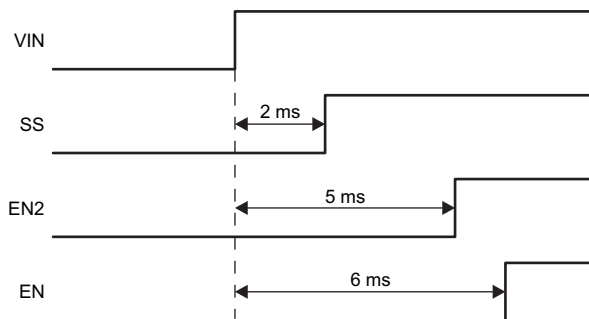


Figure 6-3. Nominal Start-up Sequence Using SPI With SS (MCU Controls EN2)

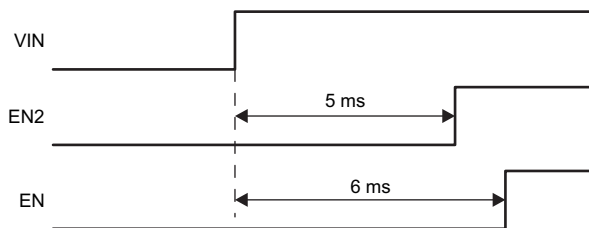


Figure 6-4. Nominal Start-up Sequence Using Parallel (MCU Controls EN2)

This start-up mode lasts until all of the regulators have settled and the 13.56-MHz oscillator has stabilized. If the EN input is set high (EN = 1) by the MCU (or other system device), the reader stays active. If the EN input is not set high (EN = 0) within 100  $\mu$ s after the SYS\_CLK output is switched from auxiliary clock (60 kHz) to high-frequency clock (derived from the crystal oscillator), the reader system returns to complete Power-Down Mode 1. This option can be used to wake-up the reader system from complete Power Down (PD Mode 1) by using a pushbutton switch or by sending a single pulse.

After the reader EN line is high, the other power modes are selected by control bits within the chip status control register (0x00). The power mode options and states are listed in [Table 6-3](#).

When EN is set high (or on rising edge of EN2 and then confirmed by EN = 1) the supply regulators are activated and the 13.56-MHz oscillator is started. When the supplies are settled and the oscillator frequency is stable, the SYS\_CLK output is switched from the auxiliary frequency of 60 kHz to the 13.56-MHz frequency derived from the crystal oscillator. At this point, the reader is ready to communicate and perform the required tasks. When this occurs, osc\_ok (B6) of the RSSI Level and Oscillator Status register is set. The MCU can then program the Chip Status Control register 0x00 and select the operation mode by programming the additional registers.

- Standby Mode (bit 7 = 1 of register 0x00), the reader is capable of recovering to full operation in 100  $\mu$ s.
- Mode 1 (active mode with RF output disabled, bit 5 = 0 and bit 1 = 0 of register 0x00) is a low power mode which allows the reader to recover to full operation within 25  $\mu$ s.
- Mode 2 (active mode with only the RF receiver active, bit 1 = 1 of register 0x00) can be used to measure the external RF field (as described in RSSI measurements paragraph) if reader-to-reader anticollision is implemented.
- Modes 3 and 4 (active modes with the entire RF section active, bit 5 = 1 of register 0x00) are the normal modes used for normal transmit and receive operations.

## 6.4 Receiver – Analog Section

### 6.4.1 Main and Auxiliary Receivers

The TRF7964A has two receiver inputs: RX\_IN1 (pin 8) and RX\_IN2 (pin 9). Each of the input is connected to an external capacitive voltage divider to ensure that the modulated signal from the tag is available on at least one of the two inputs. This architecture eliminates any possible communication holes that may occur from the tag to the reader.

The two RX inputs (RX\_IN1 and RX\_IN2) are multiplexed into two receivers - the main receiver and the auxiliary receiver. Only the main receiver is used for reception, the auxiliary receiver is used for signal quality monitoring. Receiver input multiplexing is controlled by bit B3 in the Chip Status Control register (address 0x00).

After start-up, RX\_IN1 is multiplexed to the main receiver which is composed of an RF envelope detection, first gain and band-pass filtering stage, second gain and filtering stage with AGC. Only the main receiver is connected to the digitizing stage which output is connected to the digital processing block. The main receiver also has an RSSI measuring stage, which measures the strength of the demodulated signal (subcarrier signal).

The primary function of the auxiliary receiver is to monitor the RX signal quality by measuring the RSSI of the demodulated subcarrier signal (internal RSSI). After start-up, RX\_IN2 is multiplexed to the auxiliary receiver. The auxiliary receiver has an RF envelope detection stage, first gain and filtering with AGC stage and finally the auxiliary RSSI block.

The default MUX setting is RX\_IN1 connected to the main receiver and RX\_IN2 connected to the auxiliary receiver. To determine the signal quality, the response from the tag is detected by the "main" (pin RX\_IN1) and "auxiliary" (pin RX\_IN2) RSSI. Both values measured and stored in the RSSI Levels and Oscillator Status register (address 0x0F). The MCU can read the RSSI values from the TRF7964A RSSI register and make the decision if swapping the input- signals is preferable or not. Setting B3 in Chip Status Control register (address 0x00) to 1 connects RX\_IN1 (pin 8) to the auxiliary receiver and RX\_IN2 (pin 9) to the main receiver.

The main and auxiliary receiver input stages are RF envelope detectors. The RF amplitude at RX\_IN1 and RX\_IN2 should be approximately 3 V<sub>PP</sub> for a V<sub>IN</sub> supply level greater than 3.3 V. If the V<sub>IN</sub> level is lower, the RF input peak-to-peak voltage level should not exceed the V<sub>IN</sub> level.

### 6.4.2 Receiver Gain and Filter Stages

The first gain and filtering stage has a nominal gain of 15 dB with an adjustable band-pass filter. The band-pass filter has programmable 3-dB corner frequencies between 110 kHz to 450 kHz for the high-pass filter and 570 kHz to 1500 kHz for the low-pass filter. After the band-pass filter, there is another gain-and-filtering stage with a nominal gain of 8 dB and with frequency characteristics identical to the first band-pass stage.

The internal filters are configured automatically depending on the selected ISO communication standard in the ISO Control register (address 0x01). If required, additional fine tuning can be done by writing directly to the RX Special Setting registers (address 0x0A).

[Table 6-5](#) shows the various settings for the receiver analog section. Setting B4, B5, B6, and B7 to 0 results in a band-pass characteristic of 240 kHz to 1.4 MHz, which is appropriate for ISO/IEC 14443 B 106 kbps, ISO/IEC 14443 A and B data rates of 212 kbps and 424 kbps, and FeliCa 424 kbps.

**Table 6-5. RX Special Setting Register (0x0A)**

<b>Function:</b> Sets the gains and filters directly			
<b>Default:</b> 0x40 at POR = H or EN = L, and at each write to the ISO Control register (0x01). When bits B7, B6, B5 and B4 are all zero, the filters are set for ISO/IEC 14443 B (240 kHz to 1.4 MHz).			
Bit	Name	Function	Description
B7	C212	Band-pass 110 kHz to 570 kHz	Appropriate for 212-kHz subcarrier system (FeliCa)
B6	C424	Band-pass 200 kHz to 900 kHz	Appropriate for 424-kHz subcarrier used in ISO/IEC 15693
B5	M848	Band-pass 450 kHz to 1.5 MHz	Appropriate for Manchester-coded 848-kHz subcarrier used in ISO/IEC 14443 A and B
B4	hbt	Band-pass 100 kHz to 1.5 MHz Gain reduced for 18 dB	Appropriate for highest bit rate (848 kbps) used in high-bit-rate ISO/IEC 14443
B3	gd1	00 = Gain reduction 0 dB 01 = Gain reduction for 5 dB 10 = Gain reduction for 10 dB 11 = Gain reduction for 15 dB	Sets the RX gain reduction and reduces sensitivity
B2	gd2		
B1	Reserved		
B0	Reserved		

## 6.5 Receiver – Digital Section

The output of the TRF7964A analog receiver block is a digitized subcarrier signal and is the input to the digital receiver block, which consists of two sections that partly overlap. The digitized subcarrier signal is a digital representation of the modulation signal on the RF envelope. The two sections of the digital receiver block are the *protocol bit decoder* section and the *framing logic* section.

The protocol bit decoder section converts the subcarrier coded signal into a serial bit stream and a data clock. The decoder logic is designed for maximum error tolerance. This tolerance lets the decoder section successfully decode even partly corrupted subcarrier signals that would otherwise be lost due to noise or interference.

The framing logic section formats the serial bit stream data from the protocol bit decoder stage into data bytes. During the formatting process, special signals such as the start of frame (SOF), end of frame (EOF), start of communication, and end of communication are automatically removed. The parity bits and CRC bytes are also checked and removed. The end result is "clean or raw" data that is sent to the 127-byte FIFO register where it can be read by the external microcontroller system. Providing the data this way, in conjunction with the timing register settings of the TRF7964A, means that the firmware developer does not need to know the finer details of the ISO protocols to create a very robust application, especially in low-cost platforms in which code space is at a premium and high performance is still required.

The start of the receive operation (successfully received SOF) sets the IRQ flags in the IRQ Status register (0x0C). The end of the receive operation is signaled to the external system MCU by setting pin 13 (IRQ) to high. When data is received in the FIFO, an interrupt is sent to the MCU to signal that there is data to be read from the FIFO. The FIFO Status register (0x1C) should be used to provide the number of bytes that should be clocked out during the actual FIFO read. Additionally, an interrupt is sent to the MCU when the received data occupies 75% of the FIFO capacity to signal that the data should be removed from the FIFO. By default, that interrupt is triggered once the received data packet is longer than 124 bytes. This setting can be modified in the Adjustable FIFO IRQ Levels register (0x14).

Any error in the data format, parity, or CRC is detected and notified to the external system by setting pin 13 (IRQ) to high. The source condition of the interrupt is available in the IRQ Status register (0x0C). [Section 6.14.3.3.1](#) describes the bit coding description of this register.

The framing section also supports bit-collision detection as specified in ISO/IEC 14443 A and ISO/IEC 15693. When a bit collision is detected, an interrupt request is sent and a flag is set in the IRQ Status register (0x0C). For ISO/IEC 14443 A specifically, the position of the bit collision is written in two registers: partly in the Collision Position register (0x0E) and partly in the Collision Position and Interrupt Mask register (0x0D) (bits B6 and B7).

This collision position is presented as sequential bit number, where the count starts immediately after the start bit. This means a collision in the first bit of a UID would give the value 00 0001 0000 in these registers when their contents are combined after being read (the count starts with 0 and the first 16 bits are the command code and the number of valid bits [NVB] byte).

The receive section also contains two timers.

The RX wait time timer is controlled by the value in the RX Wait Time register (0x08). This timer defines the time interval after the end of the transmit operation during which the receive decoders are not active (held in reset state). This prevents false detections resulting from transients following the transmit operation. The value of the RX Wait Time register (0x08) defines the time in increments of 9.44  $\mu$ s. This register is preset at every write to the ISO Control register (0x01) according to the minimum tag response time defined by each standard.

The RX no response timer is controlled by the RX No Response Wait Time register (0x07). This timer measures the time from the start of the slot in the anticollision sequence until the start of tag response. If there is no tag response in the defined time, an interrupt request is sent and a flag is set in the IRQ Status register (0x0C). This enables the external controller to be relieved of the task of detecting empty slots. The wait time is stored in the register in increments of 37.76  $\mu$ s. This register is also preset automatically for every new protocol selection.

The main register controlling the digital part of the receiver is the ISO Control register (0x01). By writing to this register, the user selects the protocol to be used. With each new write in this register, all related registers are preset to their defaults for the protocol, so no further adjustments in other registers are needed for proper operation. [Table 6-6](#) describes the bit fields of the ISO Control register (0x01).

---

#### NOTE

If changes to other registers are needed to fine-tune the system, those changes must be made after setting the ISO Control register (0x01).

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**Table 6-6. Coding of the ISO Control Register**

BIT	SIGNAL NAME	FUNCTION	COMMENTS
B7	rx_crc_n	Receiving without CRC	1 = No RX CRC 0 = RX CRC
B6	dir_mode	Direct mode type	0 = Output is subcarrier data 1 = Output is bit stream and clock from decoder selected by ISO bits
B5	rfd	RFID mode	0 = RFID reader mode 1 = Reserved (should be set to 0)
B4	iso_4	RFID	See <a href="#">Table 6-7</a> for B0:B4 settings based on ISO protocol used by application.
B3	iso_3	RFID	See <a href="#">Table 6-7</a> for B0:B4 settings based on ISO protocol used by application.
B2	iso_2	RFID	See <a href="#">Table 6-7</a> for B0:B4 settings based on ISO protocol used by application.
B1	iso_1	RFID	See <a href="#">Table 6-7</a> for B0:B4 settings based on ISO protocol used by application.
B0	iso_0	RFID	See <a href="#">Table 6-7</a> for B0:B4 settings based on ISO protocol used by application.

**Table 6-7. Coding of the ISO Control Register For RFID Mode (B5 = 0)**

Iso_4	Iso_3	Iso_2	Iso_1	Iso_0	PROTOCOL	REMARKS
0	0	0	0	0	ISO/IEC 15693 low bit rate, one subcarrier, 1 out of 4	
0	0	0	0	1	ISO/IEC 15693 low bit rate, one subcarrier, 1 out of 256	
0	0	0	1	0	ISO/IEC 15693 high bit rate, one subcarrier, 1 out of 4	Default for RFID IC
0	0	0	1	1	ISO/IEC 15693 high bit rate, one subcarrier, 1 out of 256	
0	0	1	0	0	ISO/IEC 15693 low bit rate, double subcarrier, 1 out of 4	
0	0	1	0	1	ISO/IEC 15693 low bit rate, double subcarrier, 1 out of 256	
0	0	1	1	0	ISO/IEC 15693 high bit rate, double subcarrier, 1 out of 4	
0	0	1	1	1	ISO/IEC 15693 high bit rate, double subcarrier, 1 out of 256	
0	1	0	0	0	ISO/IEC 14443 A, bit rate 106 kbps	
0	1	0	0	1	ISO/IEC 14443 A high bit rate 212 kbps	RX bit rate when TX rate different from RX rate (see register 0x03)
0	1	0	1	0	ISO/IEC 14443 A high bit rate 424 kbps	
0	1	0	1	1	ISO/IEC 14443 A high bit rate 848 kbps	
0	1	1	0	0	ISO/IEC 14443 B, bit rate 106 kbps	
0	1	1	0	1	ISO/IEC 14443 B high bit rate 212 kbps	RX bit rate when TX rate different from RX rate (see register 0x03)
0	1	1	1	0	ISO/IEC 14443 B high bit rate 424 kbps	
0	1	1	1	1	ISO/IEC 14443 B high bit rate 848 kbps	
1	0	0	1	1	Reserved	
1	0	1	0	0	Reserved	
1	1	0	1	0	FeliCa 212 kbps	
1	1	0	1	1	FeliCa 424 kbps	

### 6.5.1 Received Signal Strength Indicator (RSSI)

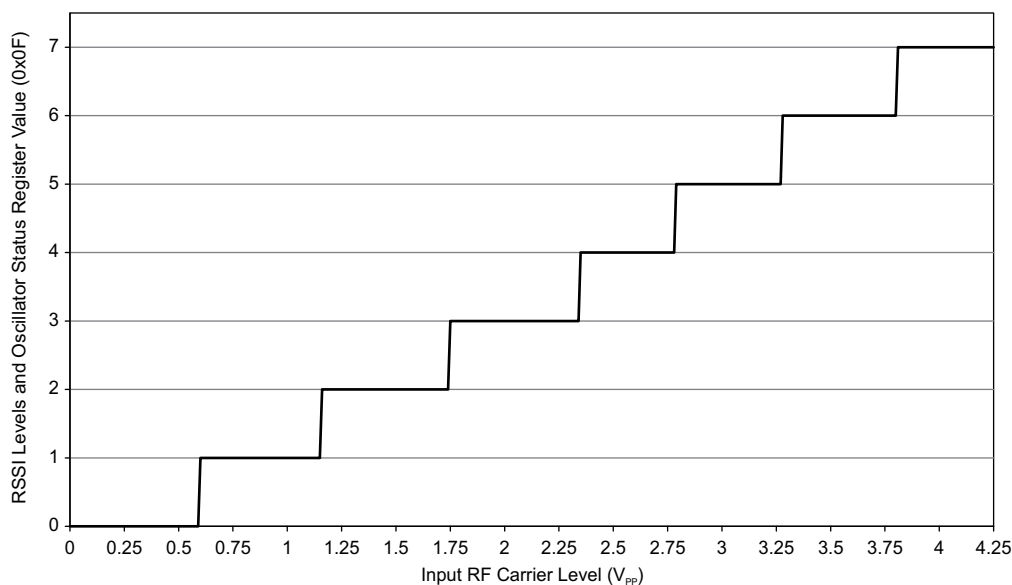
The TRF7964A incorporates in total three independent RSSI building blocks: Internal Main RSSI, Internal Auxiliary RSSI, and External RSSI. The internal RSSI blocks measure the amplitude of the subcarrier signal, and the external RSSI block measures the amplitude of the RF carrier signal at the receiver input.

#### 6.5.1.1 Internal RSSI – Main and Auxiliary Receivers

Each receiver path has its own RSSI block to measure the envelope of the demodulated RF signal (subcarrier). Internal Main RSSI and Internal Auxiliary RSSI are identical however connected to different RF input pins. The Internal RSSI is intended for diagnostic purposes to set the correct RX path conditions.

The internal RSSI values can be used to adjust the RX gain settings or determine which RX path (main or auxiliary) provides the greater amplitude and, hence, to determine if the MUX may need to be reprogrammed to swap the RX input signal. The measuring system latches the peak value, so the RSSI level can be read after the end of each receive packet. The RSSI register values are reset with every transmission (TX) by the reader. This ensures an updated RSSI measurement for each new tag response.

The Internal RSSI has 7 steps (3 bit) with a typical increment of approximately 4 dB. The operating range is between 600 mV<sub>PP</sub> and 4.2 V<sub>PP</sub> with a typical step size of approximately 600 mV. Both Internal Main and Internal Auxiliary RSSI values are stored in the RSSI Levels and Oscillator Status register (0x0F). The nominal relationship between the input RF peak level and the RSSI value is shown in [Figure 6-5](#).

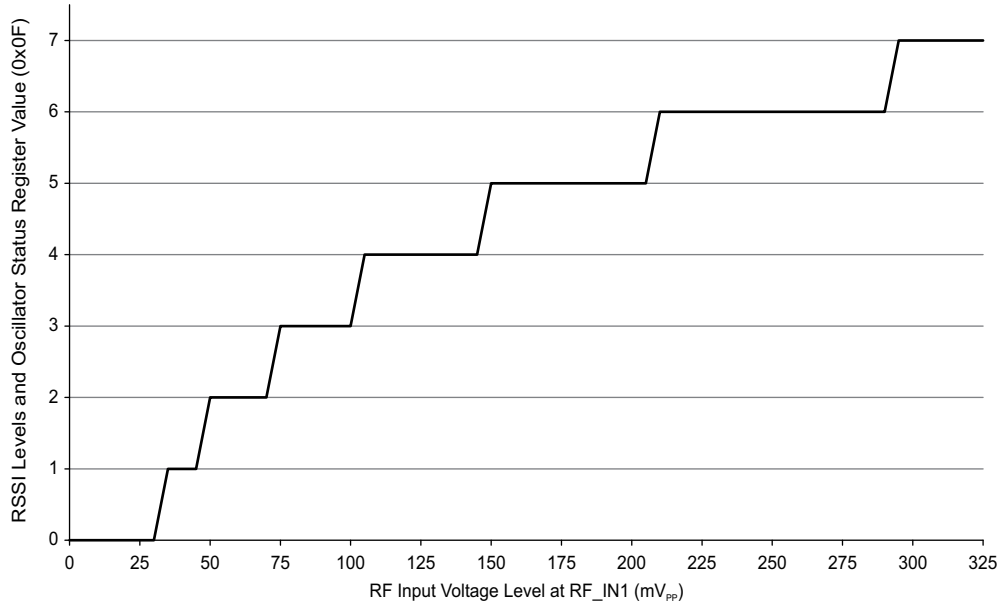


**Figure 6-5. Digital Internal RSSI (Main and Auxiliary) Value vs RF Input Level in V<sub>PP</sub> (V)**

This RSSI measurement is done during the communication to the Tag; this means the TX must be on. Bit 1 in the Chip Status Control register (0x00) defines if Internal RSSI or the External RSSI value is stored in the RSSI Levels and Oscillator Status register (0x0F). Direct command 0x18 is used to trigger an Internal RSSI measurement.

#### 6.5.1.2 External RSSI

The external RSSI is mainly used to check for any external 13.56-MHz signals at the receiver RX\_IN1 input. The external RSSI measurement should be used before turning on the transmitter to prevent RF field collisions. This is especially important for active mode, when both devices emit their own RF field. The level of the RF signal received at the antenna is measured and stored in the RSSI Levels and Oscillator Status register (0x0F). [Figure 6-6](#) shows the relationship between the voltage at the RX\_IN1 input and the 3-bit code.



**Figure 6-6. Digital External RSSI Value vs RF Input Level in V<sub>PP</sub> (mV)**

The relation between the 3-bit code and the external RF field strength (A/m) sensed by the antenna must be determined by calculation or by experiments for each antenna design. The antenna Q-factor and connection to the RF input influence the result. Direct command 0x19 is used to trigger an external RSSI measurement.

For clarity, to check the internal or external RSSI value independent of any other operation, the user must:

1. Set transmitter to desired state (on or off) using Bit 5 of Chip Status Control register (0x00) and enable receiver using Bit 1.
2. Check internal or external RSSI using direct commands 0x18 or 0x19, respectively. This action places the RSSI value in the RSSI register.
3. Delay at least 50  $\mu$ s.
4. Read the RSSI register using direct command 0x0F; values range from 0x40 to 0x7F.
5. Repeat steps 1 to 4 as needed. The register is reset when it is read.

## 6.6 Oscillator Section

The 13.56-MHz or 27.12-MHz crystal (or oscillator) is controlled by the Chip Status Control register (0x00) and the EN and EN2 terminals. The oscillator generates the RF frequency for the RF output stage as well as the clock source for the digital section. The buffered clock signal is available at pin 27 (SYS\_CLK) for any other external circuits. B4 and B5 inside the Modulation and SYS\_CLK register (0x09) can be used to divide the external SYS\_CLK signal at pin 27 by 1, 2, or 4.

Typical start-up time from complete power down is in the range of 3.5 ms.

During Power Down Mode 2 (EN = 0, EN2 = 1) the frequency of SYS\_CLK is switched to 60 kHz (typical).

The crystal needs to be connected between pin 30 and pin 31. The external shunt capacitors values for C<sub>1</sub> and C<sub>2</sub> must be calculated based on the specified load capacitance of the crystal being used. The external shunt capacitors are calculated as two identical capacitors in series plus the stray capacitance of the TRF7964A and parasitic PCB capacitance in parallel to the crystal.

The parasitic capacitance (C<sub>S</sub>, stray and parasitic PCB capacitance) can be estimated at 4 to 5 pF (typical).

As an example, using a crystal with a required load capacitance (C<sub>L</sub>) of 18 pF, the calculation is shown in [Equation 1](#).



$$C_1 = C_2 = 2 \times (C_L - C_S) = 2 \times (18 \text{ pF} - 4.5 \text{ pF}) = 27 \text{ pF} \quad (1)$$

A 27-pF capacitor must be placed on pins 30 and 31 to ensure proper crystal oscillator operation.

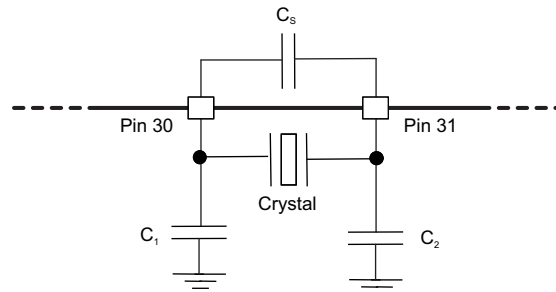


Figure 6-7. Crystal Block Diagram

Any crystal used with TRF7964A should meet the minimum characteristics in [Table 6-8](#).

Table 6-8. Minimum Crystal Recommendations

PARAMETER	SPECIFICATION
Frequency	13.56 MHz or 27.12 MHz
Mode of operation	Fundamental
Type of resonance	Parallel
Frequency tolerance	±20 ppm
Aging	< 5 ppm/year
Operation temperature range	–40°C to 85°C

As an alternative, an external clock oscillator source can be connected to pin 31 to provide the system clock; pin 30 can be left open.

## 6.7 Transmitter – Analog Section

The 13.56-MHz oscillator generates the RF signal for the PA stage. The power amplifier consists of a driver with selectable output resistance of nominal 4 Ω or 8 Ω. The transmit power level is set by bit B4 in the Chip Status Control register (0x00). The transmit power levels are selectable between 100 mW (half power) or 200 mW (full power) when configured for 5-V automatic operation. The transmit power levels are selectable between 33 mW (half power) or 70 mW (full power) when configured for 3-V automatic operation.

The ASK modulation depth is controlled by bits B0, B1, and B2 in the Modulator and SYS\_CLK Control register (0x09). The ASK modulation depth range can be adjusted between 7% to 30% or 100% (OOK).

External control of the transmit modulation depth is possible by setting the ISO Control register (0x01) to direct mode. While operating the TRF7964A in direct mode, the transmit modulation is made possible by selecting the modulation type ASK or OOK at pin 12. External control of the modulation type is made possible only if enabled by setting B6 in the Modulator and SYS\_CLK Control register (0x09) to 1.

In normal operation mode, the length of the modulation pulse is defined by the protocol selected in the ISO Control register (0x01). With a high-Q antenna, the modulation pulse is typically prolonged, and the tag detects a longer pulse than intended. For such cases, the modulation pulse length needs to be corrected by using the TX Pulse Length Control register (0x06).

If the register contains all zeros, then the pulse length is governed by the protocol selection. If the register contains a value other than 0x00, the pulse length is equal to the value of the register multiplied by 73.7 ns; therefore, the pulse length can be adjusted between 73.7 ns and 18.8 μs in 73.7-ns increments.

## 6.8 Transmitter – Digital Section

The digital part of the transmitter is a mirror of the receiver. The settings controlled the ISO Control register (0x01) are applied to the transmitter just like the receiver. In the TRF7964A default mode the TRF7964A automatically adds these special signals: start of communication, end of communication, SOF, EOF, parity bits, and CRC bytes.

The data is then coded to modulation pulse levels and sent to the RF output stage modulation control unit. Similar to working with the receiver, this means that the external system MCU must only load the FIFO with data, and all the microcoding is done automatically, again saving the firmware developer code space and time. Additionally, all of the registers used for transmit parameter control are automatically preset to optimum values when a new selection is entered into the ISO Control register (0x01).

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### NOTE

The FIFO must be reset before starting any transmission with direct command 0x0F.

---

There are two ways to start the transmit operation:

- Send the transmit command and the number of bytes to be transmitted first, and then start to send the data to the FIFO. The transmission starts when first data byte is written into the FIFO.
- Load the number of bytes to be sent into registers 0x1D and 0x1E and load the data to be sent into the FIFO (address 0x1F), followed by sending a transmit command (see Direct Commands section). The transmission then starts when the transmit command is received.

---

### NOTE

If the data length is longer than the FIFO, the TRF7964A notifies the external system MCU when most of the data from the FIFO has been transmitted by sending an interrupt request with a flag in the IRQ register to indicate a FIFO low or high status. The external system should respond by loading the next data packet into the FIFO.

---

At the end of a transmit operation, the external system MCU is notified by interrupt request (IRQ) with a flag in IRQ register (0x0C) indicating TX is complete (example value = 0x80).

The TX Length registers also support incomplete byte transmission. The high two nibbles in register 0x1D and the nibble composed of bits B4 through B7 in register 0x1E store the number of complete bytes to be transmitted. Bit B0 in register 0x1E is a flag indicating that there are also additional bits to be transmitted that do not form a complete byte. The number of bits is stored in bits B1 through B3 of the same register (0x1E).

Some protocols have options, and there are two sublevel configuration registers to select the TX protocol options.

- ISO/IEC 14443 B TX Options register (0x02). This register controls the SOF and EOF selection and EGT selection for the ISO/IEC 14443 B protocol.
- ISO/IEC 14443 A High Bit Rate Options and Parity register (0x03). This register enables the use of different bit rates for RX and TX operations in the ISO/IEC 14443 high bit rate protocol and also selects the parity method in the ISO/IEC 14443 A high bit rate protocol.

The digital section also has a timer. The timer can be used to start the transmit operation at a specified time in accordance with a selected event.

## 6.9 Transmitter – External Power Amplifier and Subcarrier Detector

The TRF7964A can be used in conjunction with an external TX power amplifier or external subcarrier detector for the receiver path. In this case, certain registers must be programmed as shown here:

- Bit B6 of the Regulator and I/O Control register (0x0B) must be set to 1. This setting has two functions: first, to provide a modulated signal for the transmitter if needed, and second, to configure the TRF7964A receiver inputs for an external demodulated subcarrier input.
- Bit B3 of the Modulation and SYS\_CLK Control register (0x09) must be set to 1 (see [Section 6.14.3.2.8](#)). This function configures the ASK/OOK pin for either a digital or analog output (B3 = 0 enables a digital output, B3 = 1 enables an analog output). The design of an external power amplifier requires detailed RF knowledge. There are also readily designed and certified high-power HF reader modules on the market.

## 6.10 TRF7964A IC Communication Interface

### 6.10.1 General Introduction

The communication interface to the reader can be configured in two ways: with a eight line parallel interface (D0:D7) plus DATA\_CLK, or with a 4-wire Serial Peripheral Interface (SPI). The SPI interface uses traditional Master Out/Slave In (MOSI), Master In/Slave Out (MISO), Slave Select, and DATA\_CLK lines.

These communication modes are mutually exclusive; that is, only one mode can be used at a time in the application.

When the SPI interface is selected, the unused I/O\_2, I/O\_1, and I/O\_0 pins must be hard-wired as shown in [Table 6-9](#). At power up, the TRF7964A samples the status of these three pins and then enters one of the possible SPI modes.

The TRF7964A always behaves as the slave device, and the microcontroller (MCU) behaves as the master device. The MCU initiates all communications with the TRF7964A, and the TRF7964A makes use of the Interrupt Request (IRQ) pin in both parallel and SPI modes to prompt the MCU for servicing attention.

**Table 6-9. Pin Assignment in Parallel and Serial Interface Connection or Direct Mode**

PIN	PARALLEL	PARALLEL (DIRECT MODE)	SPI WITH SS	SPI WITHOUT SS <sup>(1)</sup>
DATA_CLK	DATA_CLK	DATA_CLK	DATA_CLK from master	DATA_CLK from master
I/O_7	A/D[7]	Not used	MOSI <sup>(2)</sup> = data in (reader in)	MOSI <sup>(2)</sup> = data in (reader in)
I/O_6	A/D[6]	Direct mode, data out (subcarrier or bit stream)	MISO <sup>(3)</sup> = data out (MCU out)	MISO <sup>(3)</sup> = data out (MCU out)
I/O_5 <sup>(4)</sup>	A/D[5]	Direct mode, strobe – bit clock out	See <sup>(4)</sup> .	See <sup>(4)</sup> .
I/O_4	A/D[4]	Not used	SS – slave select <sup>(5)</sup>	Not used
I/O_3	A/D[3]	Not used	Not used	Not used
I/O_2	A/D[2]	Not used	At VDD	At VDD
I/O_1	A/D[1]	Not used	At VDD	At V <sub>SS</sub>
I/O_0	A/D[0]	Not used	At V <sub>SS</sub>	At V <sub>SS</sub>
IRQ	IRQ interrupt	IRQ interrupt	IRQ interrupt	IRQ interrupt

(1) FIFO is not accessible in SPI without SS mode. See the [TRF7970A Silicon Errata](#) for detailed information.

(2) MOSI = master out, slave in

(3) MISO = master in, slave out

(4) I/O\_5 pin is used only for information when data is put out of the chip (for example, reading 1 byte from the chip). It is necessary first to write in the address of the register (8 clocks) and then to generate another 8 clocks for reading out the data. The I/O\_5 pin goes high during the second 8 clocks. But for normal SPI operations, I/O\_5 pin is not used.

(5) Slave select pin is active low

Communication is initialized by a start condition, which is expected to be followed by an Address/Command word (Adr/Cmd). The Adr/Cmd word is 8 bits long, and [Table 6-10](#) shows its format.

**Table 6-10. Address and Command Word Bit Distribution**

BIT	DESCRIPTION	BIT FUNCTION	ADDRESS	COMMAND
B7	Command control bit	0 = Address 1 = Command	0	1
B6	Read/Write	0 = Write 1 = Read	R/W	0
B5	Continuous address mode	1 = Continuous mode	R/W	0
B4	Address/Command bit 4		Adr 4	Cmd 4
B3	Address/Command bit 3		Adr 3	Cmd 3
B2	Address/Command bit 2		Adr 2	Cmd 2
B1	Address/Command bit 1		Adr 1	Cmd 1
B0	Address/Command bit 0		Adr 0	Cmd 0

The MSB (bit 7) determines if the word is to be used as a command or as an address. The last two columns of [Table 6-10](#) show the function of the separate bits if either address or command is written. Data is expected once the address word is sent. In continuous-address mode (Cont. mode = 1), the first data that follows the address is written (or read) to (from) the given address. For each additional data, the address is incremented by one. Continuous mode can be used to write to a block of control registers in a single stream without changing the address; for example, setup of the predefined standard control registers from the MCU nonvolatile memory to the reader. In noncontinuous address mode (simple addressed mode), only one data word is expected after the address.

Address Mode is used to write or read the configuration registers or the FIFO. When writing more than 12 bytes to the FIFO, the Continuous Address Mode should be set to 1.

Command Mode is used to enter a command resulting in reader action (for example, initialize transmission, enable reader, and turn reader on or off).

The following sections give examples of the expected communications between an MCU and the TRF7964A.

6.10.1.1 Continuous Address Mode

Figure 6-8 summarizes the continuous address mode communication. Figure 6-8 and Figure 6-9 show the signals between the MCU and the TRF7964A.

Table 6-11. Continuous Address Mode

Start	Adr x	Data(x)	Data(x+1)	Data(x+2)	Data(x+3)	Data(x+4)	...	Data(x+n)	StopCont
-------	-------	---------	-----------	-----------	-----------	-----------	-----	-----------	----------

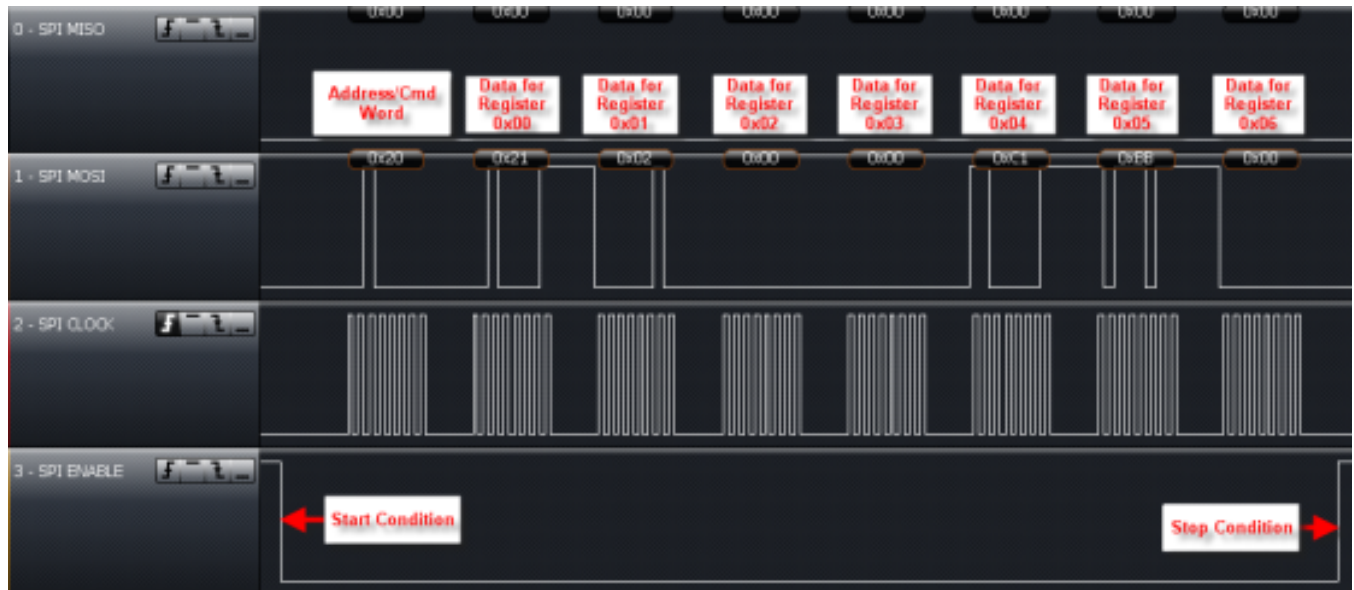


Figure 6-8. Continuous Address Register Write Example Starting With Register 0x00 Using SPI With SS

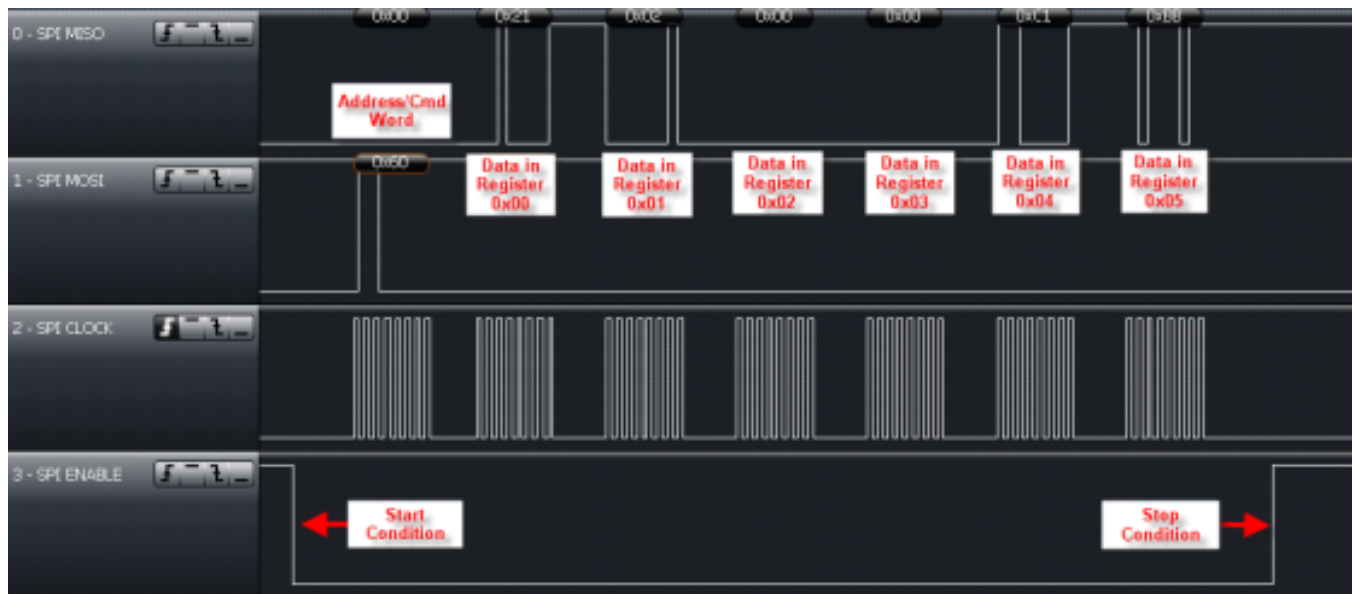


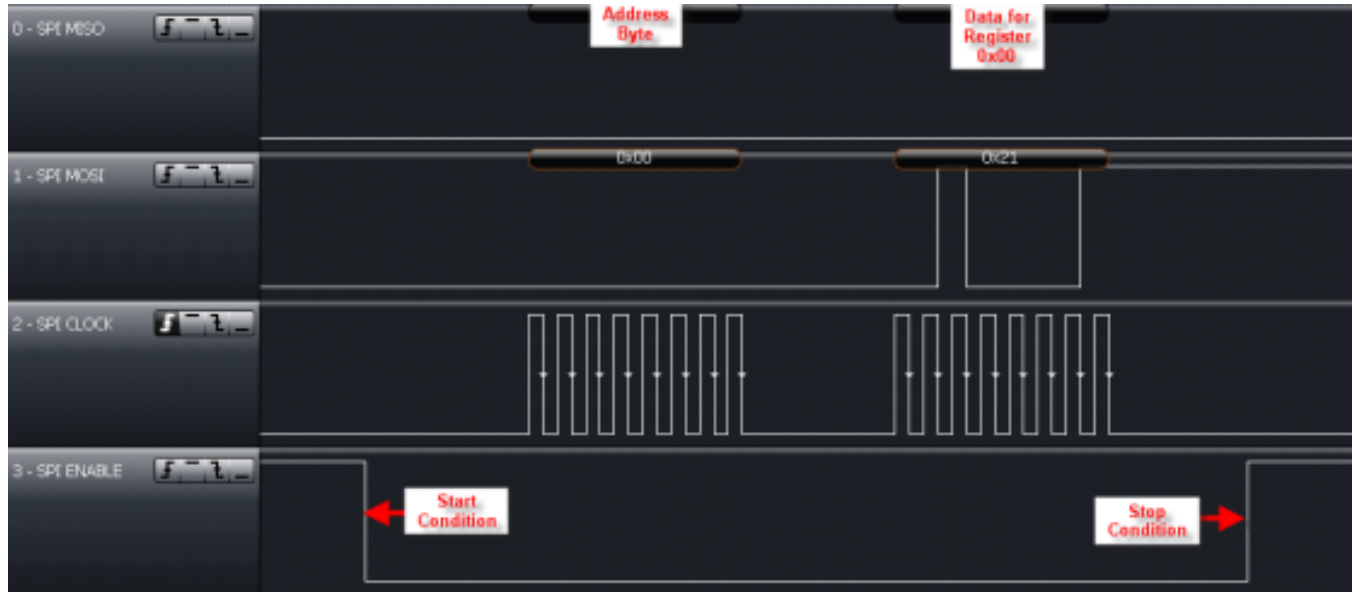
Figure 6-9. Continuous Address Register Read Example Starting With Register 0x00 Using SPI With SS

### 6.10.1.2 Noncontinuous Address Mode (Single Address Mode)

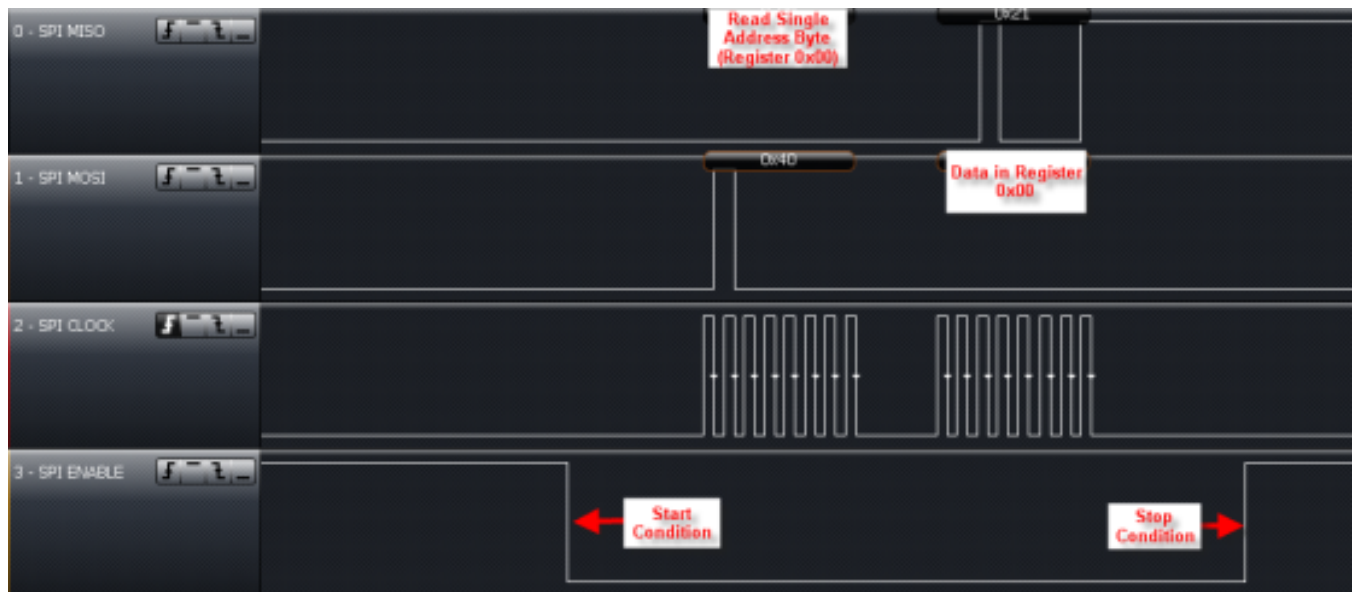
Table 6-12 summarizes the noncontinuous address (single address) mode communication. Figure 6-10 and Figure 6-11 show the signals between the MCU and the TRF7964A.

**Table 6-12. Noncontinuous Address Mode (Single Address Mode)**

Start	Adr x	Data(x)	Adr y	Data(y)	...	Adr z	Data(z)	StopSgl
-------	-------	---------	-------	---------	-----	-------	---------	---------



**Figure 6-10. Single Address Register Write Example of Register 0x00 Using SPI With SS**



**Figure 6-11. Single Address Register Read Example of Register 0x00 Using SPI With SS**

6.10.1.3 Direct Command Mode

Table 6-13 summarizes the direct command mode communication. Figure 6-12 shows the signals between the MCU and the TRF7964A.

Table 6-13. Direct Command Mode

Start	Cmd x	(Optional data or command)	Stop
-------	-------	----------------------------	------

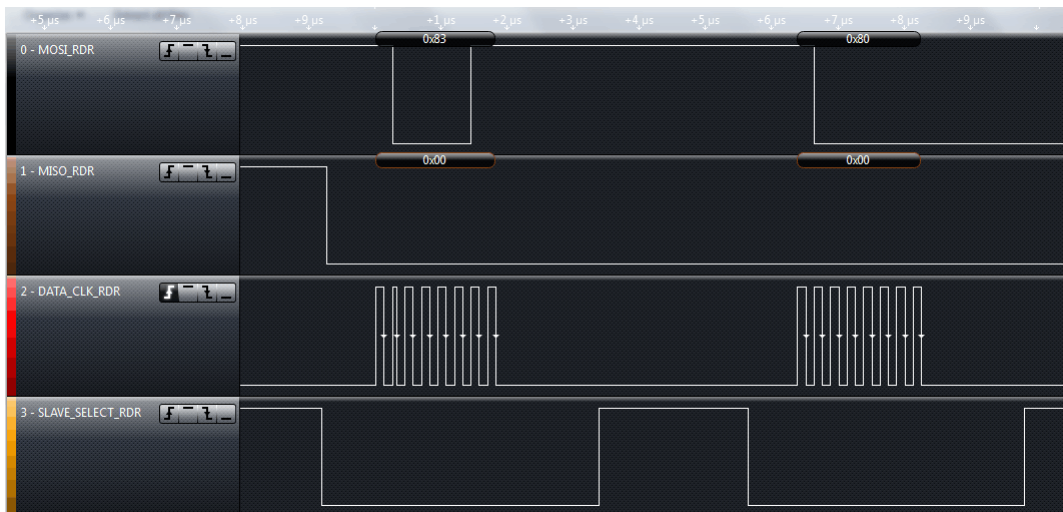


Figure 6-12. Direct Command Example of Sending 0x0F (Reset) Using SPI With SS

Section 6.13 describes the other direct command codes from the MCU to the TRF7964A IC.

6.10.1.4 FIFO Operation

The FIFO is a 127-byte register at address 0x1F with byte storage locations 0 to 126. FIFO data is loaded in a cyclical manner and can be cleared by a reset command (0x0F) (see Figure 6-12 showing this direct command).

Associated with the FIFO are two counters and three FIFO status flags. The first counter is a 7-bit FIFO byte counter (bits B0 to B6 in register 0x1C) that tracks the number of bytes loaded into the FIFO. If the number of bytes in the FIFO is n, the register value is n (number of bytes in FIFO register). For example, if 8 bytes are in the FIFO, the FIFO counter (Register 0x1C) has the hexadecimal value of 0x08 (binary value of 00001000).

A second counter (12 bits wide) indicates the number of bytes being transmitted (registers 0x1D and 0x1E) in a data frame. An extension to the transmission-byte counter is a 4-bit broken-byte counter also provided in register 0x1E (bits B0 to B3). Together these counters make up the TX length value that determines when the reader generates the EOF byte.

During transmission, the FIFO is checked for an almost-empty condition, and during reception for an almost-full condition. The maximum number of bytes that can be loaded into the FIFO in a single sequence is 127 bytes.

**NOTE**

The number of bytes in a frame, transmitted or received, can be greater than 127 bytes.

During transmission, the MCU loads the TRF7964A FIFO (or during reception the MCU removes data from the FIFO), and the FIFO counter counts the number of bytes being loaded into the FIFO. Meanwhile, the byte counter keeps track of the number of bytes being transmitted. An interrupt request is generated if the number of bytes in the FIFO triggers the watermark levels, which are configured in the Adjustable FIFO IRQ Levels register (0x14). The default setting is for the interrupt to be triggered when receiving 124 bytes during RX or having 4 bytes remaining during TX. These watermark levels are used so that MCU can send new data or read the data as necessary. The MCU must also validate the number of data bytes to be sent, so as to not surpass the value defined in the TX Length Byte registers (0x1D and 0x1E). The MCU also signals the transmit logic when the last byte of data is sent or was removed from the FIFO during reception.

Figure 6-13 shows an example of checking the FIFO Status register using SPI with SS.

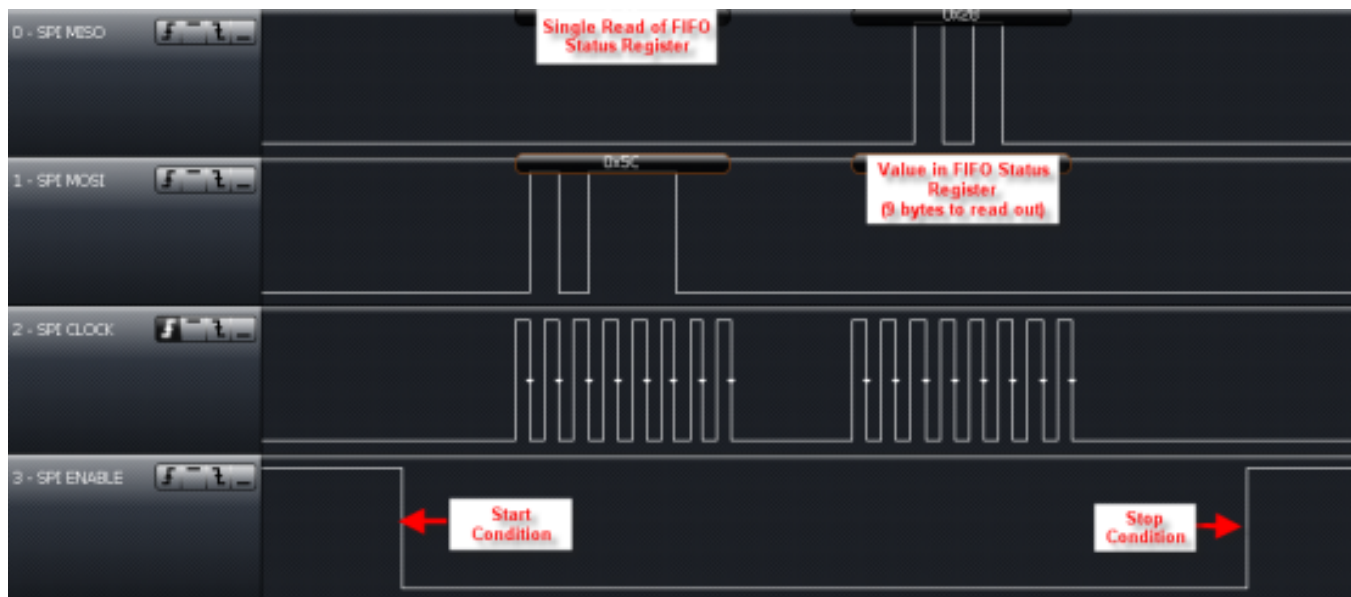


Figure 6-13. Example of Checking the FIFO Status Register Using SPI With SS

### 6.10.2 Parallel Interface Mode

In parallel mode, the start condition is generated on the rising edge of the I/O\_7 pin while the CLK is high.

This is used to reset the interface logic. Figure 6-14, Figure 6-15, and Figure 6-16 show the sequence of the data, with an 8-bit address word first, followed by data.

Communication is ended by:

- The StopSmpl condition, where a falling edge on the I/O\_7 pin is expected while CLK is high.
- The StopCont condition, where the I/O\_7 pin must have a successive rising and falling edge while CLK is low to reset the parallel interface and be ready for the new communication sequence.
- The StopSmpl condition is also used to terminate the direct mode.

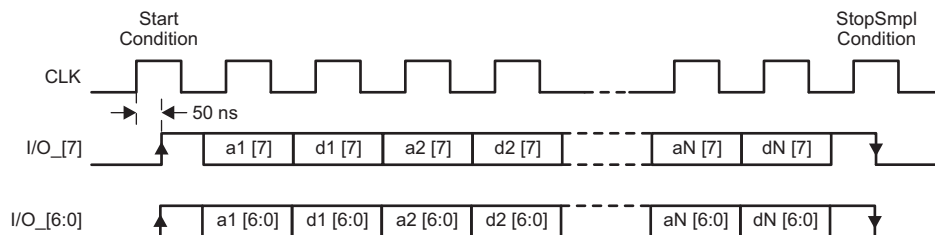


Figure 6-14. Parallel Interface Communication With Simple Stop Condition (StopSmpl)



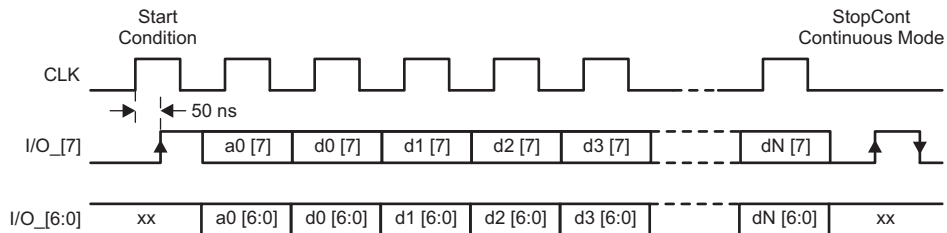


Figure 6-15. Parallel Interface Communication With Continuous Stop Condition (StopCont)



Figure 6-16. Example of Parallel Interface Communication With Continuous Stop Condition

### 6.10.3 Reception of Air Interface Data

At the start of a receive operation (when SOF is successfully detected), B6 is set in the IRQ Status register. An RX complete interrupt request is sent to the MCU at the end of the receive operation if the receive data string is shorter than or equal to the number of bytes configured in the Adjustable FIFO IRQ Levels register (0x14). An IRQ\_FIFO interrupt request is sent to the MCU during the receive operation if the data string is greater than the level set in the Adjustable FIFO IRQ Levels register (0x14). After receiving an IRQ\_FIFO or RX complete interrupt, the MCU must read the FIFO Status register (0x1C) to determine the number of bytes to be read from the FIFO. Next, the MCU must read the data in the FIFO. It is optional but recommended to read the FIFO Status register (0x1C) after reading FIFO data to determine if the receive is complete. In the case of an IRQ\_FIFO, the MCU should expect either another IRQ\_FIFO or RX complete interrupt. This is repeated until an RX complete interrupt is generated. The MCU receives the interrupt request, then checks to determine the reason for the interrupt by reading the IRQ Status register (0x0C), after which the MCU reads the data from the FIFO.

If the reader detects a receive error, the corresponding error flag is set (framing error, CRC error) in the IRQ Status register, indicating to the MCU that reception was not completed correctly.

#### 6.10.4 Data Transmission From MCU to TRF7964A

Before beginning data transmission, the FIFO should always be cleared with a reset command (0x0F). Data transmission is initiated with a selected command (see [Section 6.13](#)). The MCU then commands the reader to do a continuous write command (0x3D) starting from register 0x1D. Data written into register 0x1D is the TX Length Byte 1 (upper and middle nibbles), while the following byte in register 0x1E is the TX Length Byte 2 (lower nibble and broken byte length) (see [Table 6-47](#) and [Table 6-48](#)). Note that the TX byte length determines when the reader sends the end of frame (EOF) byte. After the TX length bytes are written, FIFO data is loaded in register 0x1F with byte storage locations 0 to 127. Data transmission begins automatically after the first byte is written into the FIFO. The loading of TX length bytes and the FIFO can be done with a continuous-write command, as the addresses are sequential.

At the start of transmission, the flag B7 (IRQ\_TX) is set in the IRQ Status register, and at the end of the transmit operation, an interrupt is sent to inform the MCU that the task is complete.

#### 6.10.5 Serial Interface Communication (SPI)

When an SPI interface is used, I/O pins I/O\_2, I/O\_1, and I/O\_0 must be hard wired according to [Table 6-9](#). On power up, the TRF7964A looks for the status of these pins and then enters into the corresponding mode.

The serial communications work in the same manner as the parallel communications with respect to the FIFO, except for the following condition. On receiving an IRQ from the reader, the MCU reads the TRF7964A IRQ Status register to determine how to service the reader. After this, the MCU must do a dummy read to clear the reader's IRQ status register. The dummy read is required in SPI mode because the reader's IRQ status register needs an additional clock cycle to clear the register. This is not required in parallel mode because the additional clock cycle is included in the Stop condition. When first establishing communications with the TRF7964A, the SOFT\_INIT (0x03) and IDLE (0x00) commands should be sent first from the MCU (see [Table 6-14](#)).

The procedure for a dummy read is as follows (see [Figure 6-17](#) and [Figure 6-18](#)):

1. Start the dummy read:
  1. When using slave select (SS): set SS bit low.
  2. When not using SS: start condition is when Data Clock is high (see [Table 6-9](#)).
2. Send address word to IRQ status register (0x0C) with read and continuous address mode bits set to 1 (see [Table 6-9](#)).
3. Read 1 byte (8 bits) from IRQ status register (0x0C).
4. Dummy-read 1 byte from register 0x0D (collision position and interrupt mask).
5. Stop the dummy read:
  1. When using slave select (SS): set SS bit high.
  2. When not using SS: stop condition when Data Clock is high.

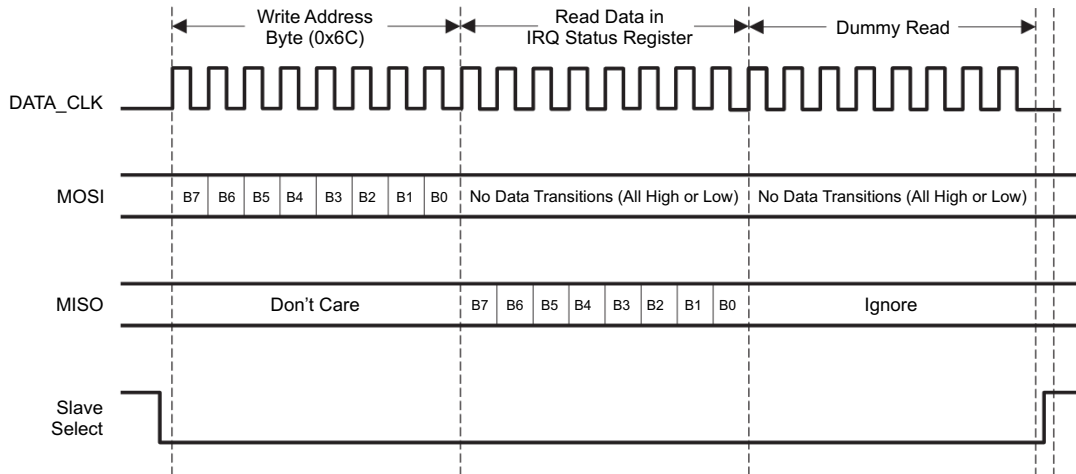


Figure 6-17. Procedure for Dummy Read

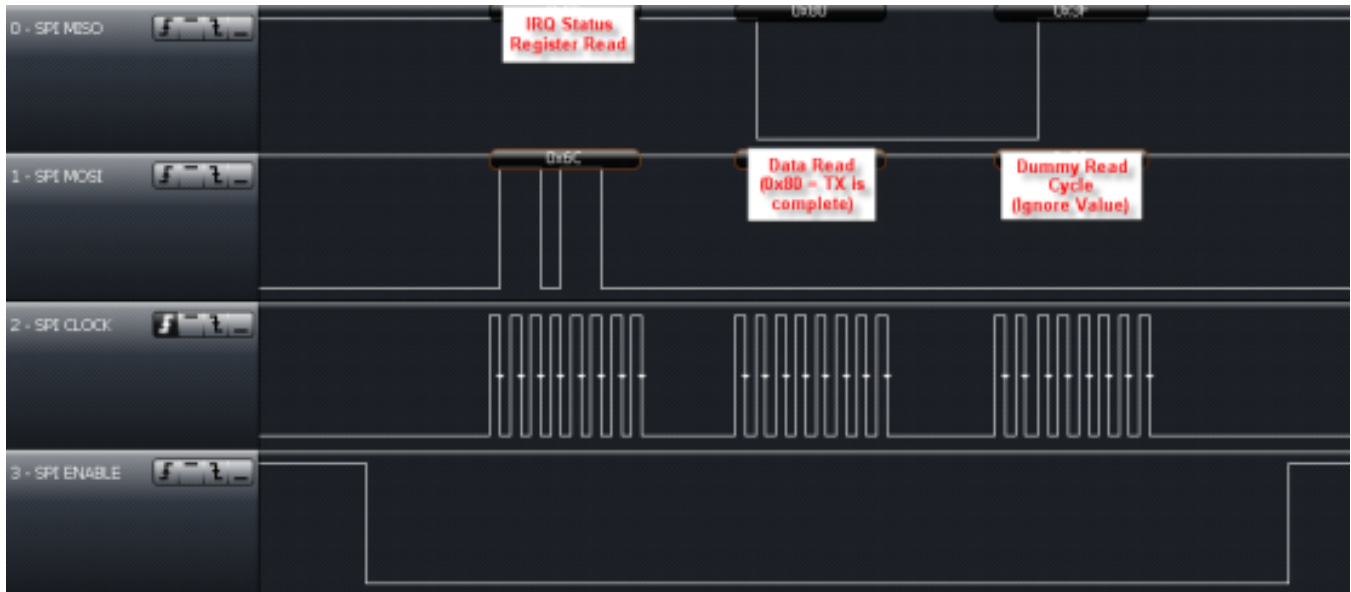
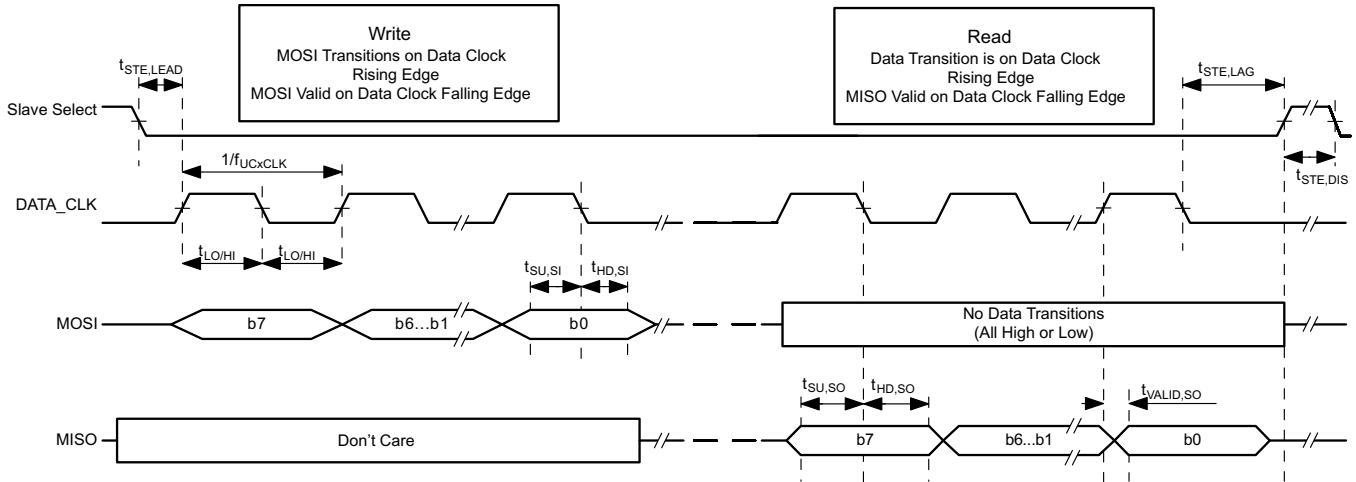


Figure 6-18. Example of Dummy Read Using SPI With SS

### 6.10.5.1 Serial Interface Mode With Slave Select (SS)

The serial interface is in reset while the Slave Select signal is high. Serial data in (MOSI) changes on the rising edge, and is validated in the reader on the falling edge, as shown in Figure 6-19. Communication is terminated when the Slave Select signal goes high.

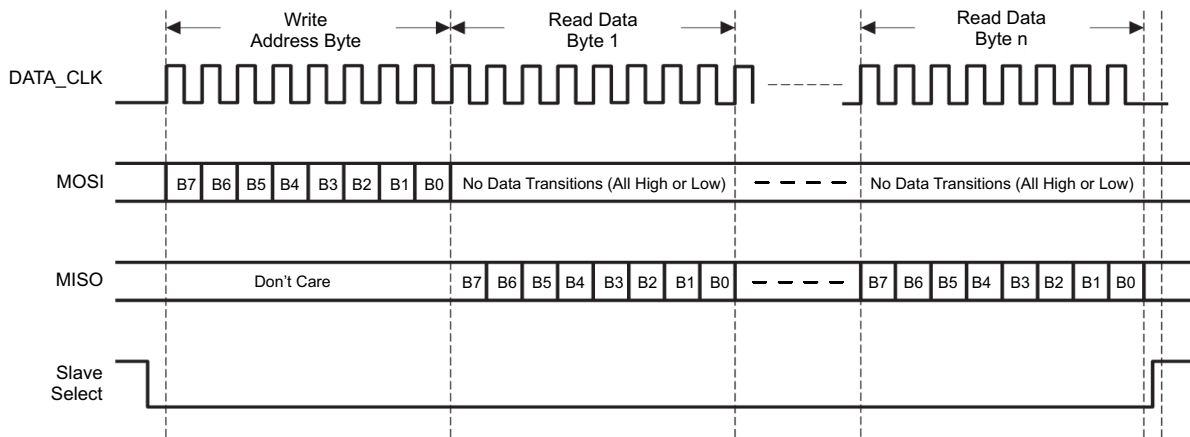
All words must be 8 bits long with the MSB transmitted first.



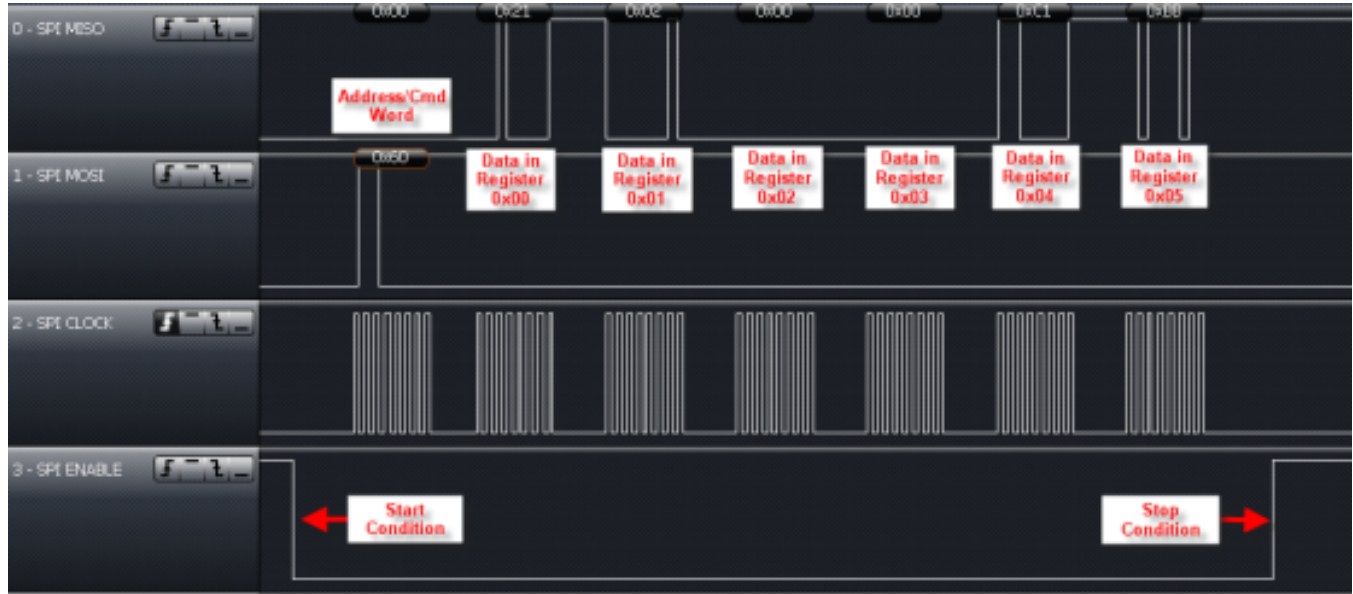
**Figure 6-19. SPI With Slave Select Timing Diagram**

The read command is sent out on the MOSI pin, MSB first, in the first eight clock cycles. MOSI data changes on the rising edge, and is validated in the reader on the falling edge, as shown in Figure 6-19. During the write cycle, the serial data out (MISO) is not valid. After the last read command bit (B0) is validated at the eighth falling edge of SCLK, valid data can be read on the MISO pin at the falling edge of SCLK. It takes eight clock edges to read out the full byte (MSB first). See Section 5.4 for electrical specifications related to Figure 6-19.

Figure 6-20 and Figure 6-21 show the continuous read operation.



**Figure 6-20. Continuous Read Operation Using SPI With Slave Select**



**Figure 6-21. Continuous Read of Registers 0x00 to 0x05 Using SPI With SS**

Figure 6-22 shows an example of performing a single slot inventory command. Reader registers (in this example) are configured for 5 VDC in and default operation.



**Figure 6-22. Inventory Command Sent From MCU to TRF7964A**

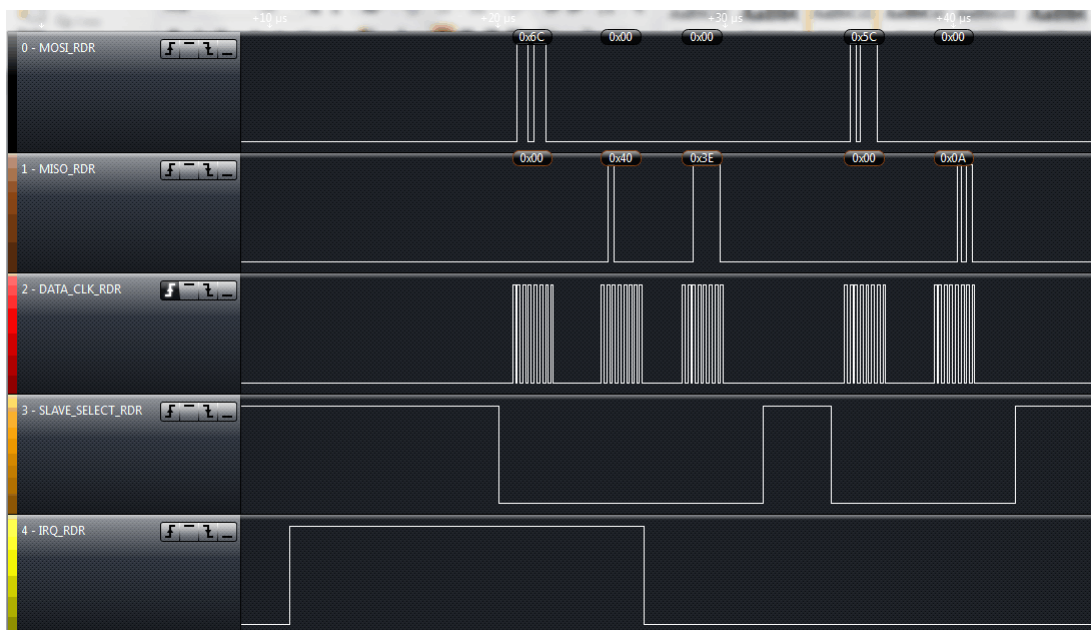
The TRF7964A takes these bytes from the MCU and then send out Request Flags, Inventory Command, and Mask over the air to the ISO/IEC 15693 transponder. After these three bytes have been transmitted, an interrupt occurs to indicate back to the reader that the transmission has been completed. In the example in Figure 6-23, this IRQ occurs approximately 1.6 ms after the SS line goes high after the Inventory command is sent out.



**Figure 6-23. IRQ After Inventory Command**

The IRQ status register read (0x6C) yields 0x80, which indicates that TX is indeed complete. This is followed by a dummy clock. Then, if a tag is in the field and no error is detected by the reader, a second interrupt is expected and occurs (in this example) approximately 4 ms after first IRQ is read and cleared.

In the continuation of the example (see [Figure 6-24](#)), the IRQ Status Register is read using method previously recommended, followed by a single read of the FIFO Status register, which indicates that there are 10 bytes to be read out.



**Figure 6-24. Read IRQ Status Register After Inventory Command**

This is then followed by a continuous read of the FIFO (see [Figure 6-25](#)). The first byte is (and should be) 0x00 for no error. The next byte is the DSFID (usually shipped by manufacturer as 0x00), then the UID, shown here up to the next most significant byte, the MFG code [shown as 0x07 (TI silicon)].

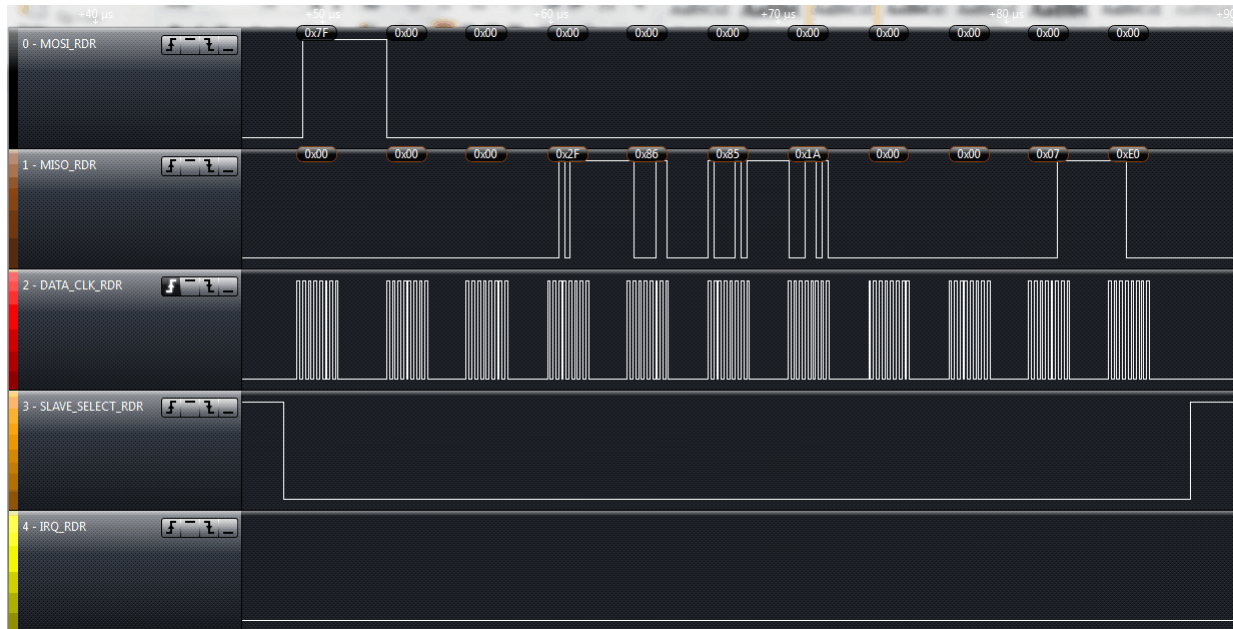


Figure 6-25. Continuous Read of FIFO After Inventory Command

TI recommends resetting the FIFO after receiving data. Additionally, the RSSI value of the tag can be read out at this point. In the example in Figure 6-26, the transponder is very close to the antenna, so value of 0x7F is recovered.



Figure 6-26. Reset FIFO and Read RSSI

### 6.10.6 Direct Mode

Direct mode allows the user to configure the reader in one of two ways. Direct mode 0 (bit 6 = 0, as defined in ISO Control register) allows the user to use only the front-end functions of the reader, bypassing the protocol implementation in the reader. For transmit functions, the user has direct access to the transmit modulator through the MOD pin (pin 14). On the receive side, the user has direct access to the subcarrier signal (digitized RF envelope signal) on I/O\_6 (pin 23).

Direct mode 1 (bit 6 = 1, as defined in ISO Control register) uses the subcarrier signal decoder of the selected protocol (as defined in ISO Control register). This means that the receive output is not the subcarrier signal but the decoded serial bit stream and bit clock signals. The serial data is available on I/O\_6 (pin 23) and the bit clock is available on I/O\_5 (pin 22). The transmit side is identical; the user has direct control over the RF modulation through the MOD input. This mode is provided so that the user can implement a protocol that has the same bit coding as one of the protocols implemented in the reader, but needs a different framing format.

To select direct mode, the user must first choose which direct mode to enter by writing B6 in the ISO Control register. This bit determines if the receive output is the direct subcarrier signal (B6 = 0) or the serial data of the selected decoder. If B6 = 1, then the user must also define which protocol should be used for bit decoding by writing the appropriate setting in the ISO Control register.

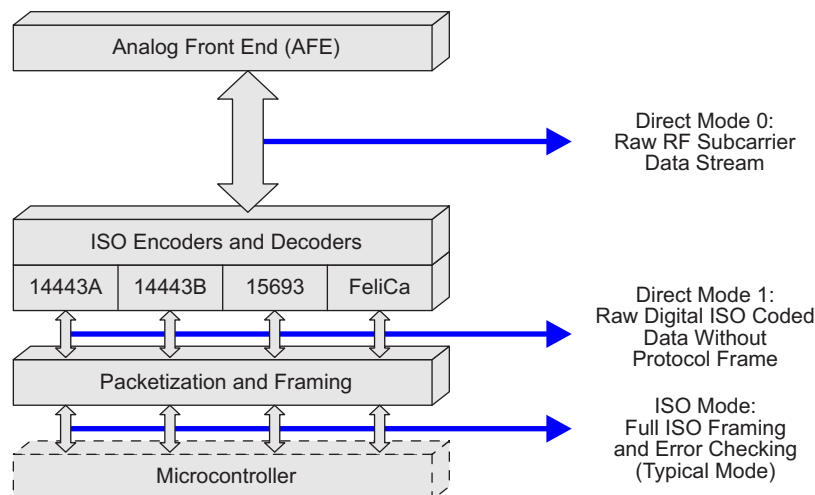
The reader actually enters the direct mode when B6 (direct) is set to 1 in the chip status control register. Direct mode starts immediately. The write command should not be terminated with a stop condition (see communication protocol), because the stop condition terminates the direct mode and clears B6. This is necessary as the direct mode uses one or two I/O pins (I/O\_6, I/O\_5). Normal parallel communication is not possible in direct mode. Sending a stop condition terminates direct mode.

#### NOTE

An additional direct mode known as special direct mode can be used to communicate with certain tags not compliant with ISO standards. For full details on how to use this feature, see [Using Special Direct Mode With the TRF7970A](#).

Figure 6-27 shows the different configurations available in direct mode.

- In mode 0, the reader is used as an AFE only, and protocol handling is bypassed.
- In mode 1, framing is not done, but SOF and EOF are present. This allows for a user-selectable framing level based on an existing ISO standard.
- In mode 2, data is ISO-standard formatted. SOF, EOF, and error checking are removed, so the microprocessor receives only bytes of raw data through a 127-byte FIFO.



**Figure 6-27. User-Configurable Modes**



The steps to enter direct mode are listed below, using SPI with SS communication method only as one example, as direct modes are also possible with parallel and SPI without SS. The must enter direct mode 0 to accommodate card type communications that are not compliant with ISO standards. Direct mode can be entered at any time, so if a card type started with ISO standard communications, then deviated from the standard after being identified and selected, the ability to go into direct mode 0 is very useful.

**Step 1: Configure Pins I/O\_0 to I/O\_2 for SPI with SS**

**Step 2: Set Pin 12 of the TRF7964A (ASK/OOK pin) to 0 for ASK or 1 for OOK**

**Step 3: Program the TRF7964A registers**

The following registers must be explicitly set before going into the direct mode.

1. ISO Control register (0x01) to the appropriate standard
  - 0x02 for ISO/IEC 15693 High Data Rate
  - 0x08 for ISO/IEC 14443 A (106 kbps)
  - 0x1A for FeliCa 212 kbps
  - 0x1B for FeliCa 424 kbps
2. Modulator and SYS\_CLK register (0x09) to the appropriate clock speed and modulation
  - 0x21 for 6.78 MHz Clock and OOK (100%) modulation
  - 0x20 for 6.78 MHz Clock and ASK 10% modulation
  - 0x22 for 6.78 MHz Clock and ASK 7% modulation
  - 0x23 for 6.78 MHz Clock and ASK 8.5% modulation
  - 0x24 for 6.78 MHz Clock and ASK 13% modulation
  - 0x25 for 6.78 MHz Clock and ASK 16% modulation
 (See register 0x09 definition for all other possible values)

Example register setting for ISO/IEC 14443 A at 106 kbps:

- ISO Control register (0x01) to 0x08
- RX No Response Wait Time register (0x07) to 0x0E
- RX Wait Time register (0x08) to 0x07
- Modulator control register (0x09) to 0x21 (or any custom modulation)
- RX Special Settings register (0x0A) to 0x20

### Step 4: Entering Direct Mode 0

The following registers must be programmed to enter direct mode 0:

1. Set bit B6 of the Modulator and SYS\_CLK Control register (0x09) to 1.
2. Set bit B6 of the ISO Control (Register 01) to 0 for direct mode 0 (default its 0)
3. Set bit B6 of the Chip Status Control register (0x00) to 1 to enter direct mode
4. Send extra eight clock cycles (see [Figure 6-28](#), this step is TRF7964A specific)

#### NOTE

- It is important that the last write is not terminated with a stop condition. For SPI, this means that Slave Select (I/O\_4) stays low.
- Sending a Stop condition terminates the direct mode and clears bit B6 in the Chip Status Control register (0x00).

#### NOTE

Access to Registers, FIFO, and IRQ is not available during direct mode 0.

The reader enters the direct mode 0 when bit 6 of the Chip Status Control register (0x00) is set to a 1 and stays in direct mode 0 until a stop condition is sent from the microcontroller.

#### NOTE

The write command should not be terminated with a stop condition (for example, in SPI mode this is done by bringing the Slave Select line high after the register write), because the stop condition terminates the direct mode and clears bit 6 of the Chip Status Control register (0x00), making it a 0.

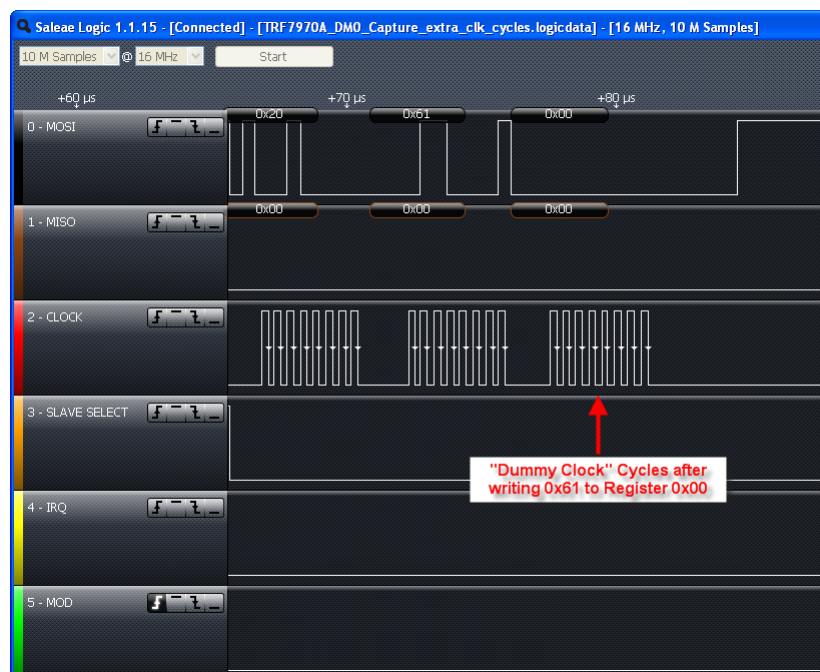


Figure 6-28. Entering Direct Mode 0



- $128/f_c = 9.435 \mu s = t_b$  (106-kbps data rate)
- $64/f_c = 4.719 \mu s = t_x$  time
- $32/f_c = 2.359 \mu s = t_1$  time

Table 7 — Parameters for sequences

Parameter	Bit rate			
	fc/128	fc/64	fc/32	fc/16
$t_b$	128/fc	64/fc	32/fc	16/fc
$t_x$	64/fc	32/fc	16/fc	8/fc
$t_1$	see $t_1$ of Table 3		see $t_1$ of Table 5	

Figure 10 together with the timing parameters in Table 7 illustrate sequences X, Y and Z.

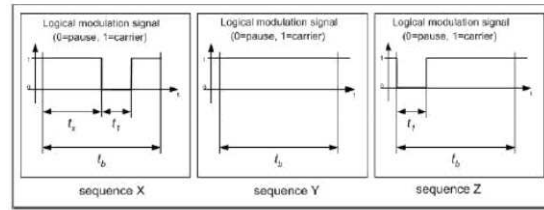
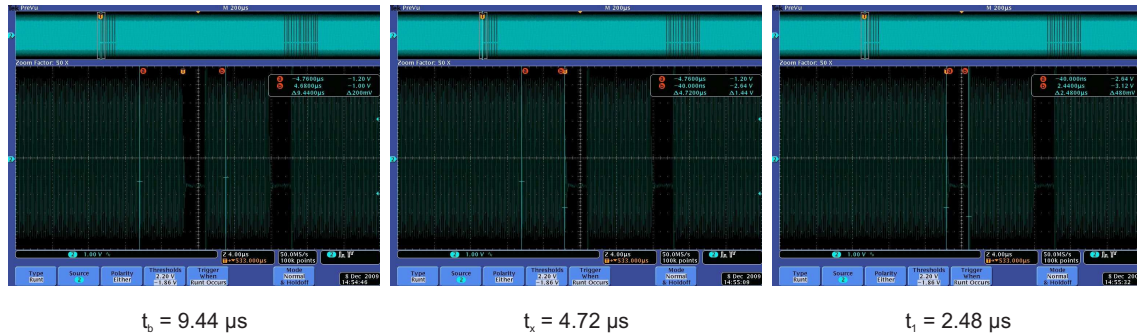


Figure 10 — Sequences for Type A communication PCD to PICC

The above sequences shall be used to code the following information:

- logic "1": sequence X.
- logic "0": sequence Y with the following two exceptions:
  - i) If there are two or more contiguous "0"s, sequence Z shall be used from the second "0" on.
  - ii) If the first bit after a "start of frame" is "0", sequence Z shall be used to represent this and any "0"s which follow directly thereafter.
- start of communication: sequence Z.
- end of communication: logic "0" followed by sequence Y.
- no information: at least two sequences Y.



Sequence Y = Carrier for 9.44 μs

Sequence Z = Pause for 2 to 3 μs, Carrier for Remainder of 9.44 μs

Figure 6-31. Receive Data Bits and Framing Level

Figure 6-32 shows an example of what the developer should expect on the I/O\_6 line during the RX process while in direct mode 0.

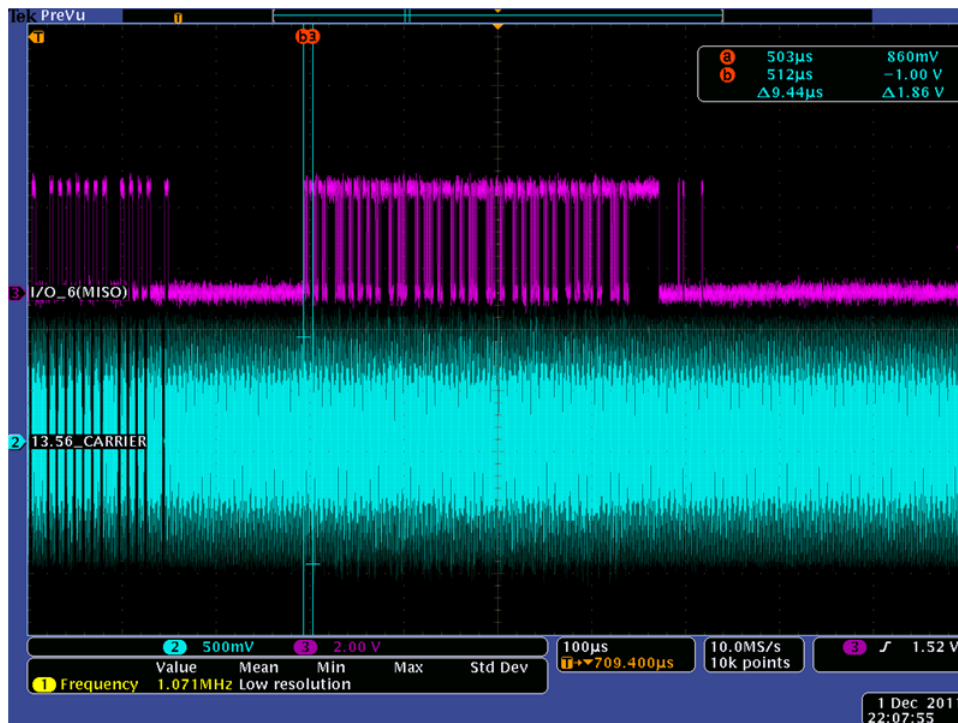


Figure 6-32. RX Sequence on I/O\_6 in DM0 (Analog Capture)

### Step 7: Terminating Direct Mode 0

After the EOF is received, data transmission is over, and direct mode 0 can be terminated by sending a Stop Condition (in the case of SPI, make the Slave Select go high). The TRF7964A is returned to default state.

## 6.11 TRF7964A Initialization

To properly initialize the TRF7964A, perform these steps:

1. Raise the EN, EN2, and SS lines at the correct intervals after power up (for timing diagrams, see [Figure 6-3](#) and [Figure 6-4](#)).
2. Issue a Software Initialization direct command (0x03), followed by an Idle direct command (0x00) to soft reset the TRF7964A.

### NOTE

[Table 6-16](#) lists the initial register settings for the TRF7964A after the Software Initialization command.

3. Delay 1 ms to allow the TRF7964A to fully process the soft reset.
4. Issue a Reset FIFO direct command (0x0F).
5. Write the Modulator and SYS\_CLK Control register (0x09) with the appropriate application-specific setting for the crystal and system clock settings.
6. (Optional) Write the Regulator and I/O Control register (0x0B) with the appropriate application-specific setting.

## 6.12 Special Direct Mode for Improved MIFARE™ Compatibility

See [Using Special Direct Mode With the TRF7970A](#).

## 6.13 Direct Commands from MCU to Reader

### 6.13.1 Command Codes

Table 6-14 summarizes the command codes.

**Table 6-14. Address and Command Word Bit Distribution**

COMMAND CODE	COMMAND	COMMENTS
0x00	Idle	
0x03	Software initialization	Same as Power on Reset
0x0F	Reset FIFO	
0x10	Transmission without CRC	
0x11	Transmission with CRC	
0x12	Delayed transmission without CRC	
0x13	Delayed transmission with CRC	
0x14	End of frame and transmit next time slot	Used for ISO/IEC 15693 only
0x16	Block receiver	
0x17	Enable receiver	
0x18	Test internal RF (RSSI at RX input with TX off)	
0x19	Test external RF (RSSI at RX input with TX on)	

The command code values from Table 6-14 are substituted in Table 6-15, bits 0 through 4. Also, the most-significant bit (MSB) in Table 6-15 must be set to 1. (Table 6-15 is same as Table 6-10, shown here again for easy reference).

**Table 6-15. Address and Command Word Bit Distribution**

BIT	DESCRIPTION	BIT FUNCTION	ADDRESS	COMMAND
B7	Command control bit	0 = Address 1 = Command	0	1
B6	Read/Write	0 = Write 1 = Read	R/W	0
B5	Continuous address mode	1 = Continuous mode	R/W	0
B4	Address/Command bit 4		Adr 4	Cmd 4
B3	Address/Command bit 3		Adr 3	Cmd 3
B2	Address/Command bit 2		Adr 2	Cmd 2
B1	Address/Command bit 1		Adr 1	Cmd 1
B0	Address/Command bit 0		Adr 0	Cmd 0

The MSB determines if the word is to be used as a command or address. The last two columns of Table 6-15 show the function of each bit, depending on whether address or command is written. Command mode is used to enter a command resulting in reader action (initialize transmission, enable reader, and turn reader on or off).

#### 6.13.1.1 Idle (0x00)

This command issues dummy clock cycles. In parallel mode, one cycle is issued. In SPI mode, eight cycles are issued. This command should be sent after a Software Initialization command to allow the command to finish operation.

### 6.13.1.2 Software Initialization (0x03)

This command starts a power-on reset. After sending this command, the register values change as shown in [Table 6-16](#).

**Table 6-16. Register Values After Sending Software Initialization (0x03)**

ADDRESS	REGISTER	VALUE
0x00	Chip status control	0x01
0x01	ISO control	0x21 <sup>(1)</sup>
0x02	ISO/IEC 14443 B TX options	0x00
0x03	ISO/IEC 14443 A high bit rate options	0x00
0x04	TX timer high byte control	0xC1 <sup>(1)</sup>
0x05	TX timer low byte control	0xC1 <sup>(1)</sup>
0x06	TX pulse length control	0x00
0x07	RX no response wait time	0x0E
0x08	RX wait time	0x07 <sup>(1)</sup>
0x09	Modulator and SYS_CLK control	0x91
0x0A	RX special setting	0x10 <sup>(1)</sup>
0x0B	Regulator and I/O control	0x87
0x0C	IRQ status	0x00
0x0D	Collision position and interrupt mask	0x3E
0x0E	Collision position	0x00
0x0F	RSSI levels and oscillator status	0x40
0x10	Special function	0x00
0x11	Special function	0x00
0x12	RAM	0x00
0x13	RAM	0x00
0x14	Adjustable FIFO IRQ levels	0x00
0x1A	Test	0x00
0x1B	Test	0x00
0x1C	FIFO status	0x00

(1) Differs from default at POR

### 6.13.1.3 Reset FIFO (0x0F)

The reset command clears the FIFO contents and FIFO Status register (0x1C). It also clears the register storing the collision error location (0x0E).

### 6.13.1.4 Transmission With CRC (0x11)

The transmission command must be sent first, followed by transmission length bytes, and FIFO data. The reader starts transmitting after the first byte is loaded into the FIFO. The CRC byte is included in the transmitted sequence.

### 6.13.1.5 Transmission Without CRC (0x10)

Same as [Section 6.13.1.4](#) with CRC excluded.

### 6.13.1.6 Delayed Transmission With CRC (0x13)

The transmission command must be sent first, followed by the transmission length bytes, and FIFO data.

The reader transmission is triggered by the TX timer.

### 6.13.1.7 Delayed Transmission Without CRC (0x12)

Same as [Section 6.13.1.6](#) with CRC excluded.

### 6.13.1.8 Transmit Next Time Slot (0x14)

When this command is received, the reader transmits the next slot command. The next slot sign is defined by the protocol selection. This is used by the ISO/IEC 15693 protocol.

### 6.13.1.9 Block Receiver (0x16)

The block receiver command puts the digital part of receiver (bit decoder and framer) in reset mode. This is useful in an extremely noisy environment, where the noise level could otherwise cause a constant switching of the subcarrier input of the digital part of the receiver. The receiver (if not in reset) would try to catch a SOF signal, and if the noise pattern matched the SOF pattern, an interrupt would be generated, falsely signaling the start of an RX operation. A constant flow of interrupt requests can be a problem for the external system (MCU), so the external system can stop this by putting the receive decoders in reset mode. The reset mode can be terminated in two ways. The external system can send the enable receiver command. The reset mode is also automatically terminated at the end of a TX operation. The receiver can stay in reset after end of TX if the RX wait time register (0x08) is set. In this case, the receiver is enabled at the end of the wait time following the transmit operation.

### 6.13.1.10 Enable Receiver (0x17)

This command clears the reset mode in the digital part of the receiver if the reset mode was entered by the block receiver command.

### 6.13.1.11 Test Internal RF (RSSI at RX Input With TX ON) (0x18)

The level of the RF carrier at RF\_IN1 and RF\_IN2 inputs is measured. Operating range between 300 mV<sub>P</sub> and 2.1 V<sub>P</sub> (step size is 300 mV). The two values are displayed in the RSSI Levels and Oscillator Status register (0x0F). The command is intended for diagnostic purposes to set correct RF\_IN levels. Optimum RFIN input level is approximately 1.6 V<sub>P</sub> or code 5 to 6. The nominal relationship between the RF peak level and RSSI code is shown in [Table 6-17](#) and in [Section 6.5.1.1](#).

#### NOTE

If the command is executed immediately after power-up and before any communication with a tag is performed, the command must be preceded by Enable RX command. The Check RF commands require full operation, so the receiver must be activated by Enable RX or by a normal Tag communication for the Check RF command to work properly.

**Table 6-17. Test Internal RF Peak Level to RSSI Codes**

<b>RF_IN1 [mV<sub>PP</sub>]</b>	300	600	900	1200	1500	1800	2100
<b>Decimal Code</b>	1	2	3	4	5	6	7
<b>Binary Code</b>	001	010	011	001	101	011	111

### 6.13.1.12 Test External RF (RSSI at RX Input with TX OFF) (0x19)

This command can be used in active mode when the RF receiver is switched on but RF output is switched off. This means bit B1 = 1 in Chip Status Control Register. The level of RF signal received on the antenna is measured and displayed in the RSSI Levels and Oscillator Status register (0x0F). The relation between the 3 bit code and the external RF field strength [A/m] must be determinate by calculation or by experiments for each antenna type as the antenna Q and connection to the RF input influence the result. The nominal relation between the RF peak to peak voltage in the RF\_IN1 input and RSSI code is shown in [Table 6-18](#) and in [Section 6.5.1.2](#).



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**NOTE**

If the command is executed immediately after power-up and before any communication with a tag is performed, the command must be preceded by an Enable RX command. The Check RF commands require full operation, so the receiver must be activated by Enable RX or by a normal Tag communication for the Check RF command to work properly.

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**Table 6-18. Test External RF Peak Level to RSSI Codes**

<b>RF_IN1 [mV<sub>PP</sub>]</b>	40	60	80	100	140	180	300
<b>Decimal Code</b>	1	2	3	4	5	6	7
<b>Binary Code</b>	001	010	011	001	101	011	111

## 6.14 Register Description

### 6.14.1 Register Preset

After power up and the EN pin low-to-high transition, the reader is in the default mode. The default configuration is ISO/IEC 15693, single subcarrier, high data rate, 1-out-of-4 operation. The low-level option registers (0x02 to 0x0B) are automatically set to adapt the circuitry optimally to the appropriate protocol parameters. When entering another protocol (by writing to the ISO Control register 0x01), the low-level option registers (0x02 to 0x0B) are automatically configured to the new protocol parameters. After selecting the protocol, it is possible to change some low-level register contents if needed. However, changing to another protocol and then back, reloads the default settings, and so then the custom settings must be reloaded.

The Clo0 and Clo1 register (0x09) bits, which define the microcontroller frequency available on the SYS\_CLK pin, are the only 2 bits in the configuration registers that are not cleared during protocol selection.

## 6.14.2 Register Overview

Table 6-19 lists the registers.

**Table 6-19. Register Definitions**

ADDRESS	REGISTER	READ/WRITE	SECTION
<b>Main Control Registers</b>			
0x00	Chip status control	R/W	<a href="#">Section 6.14.3.1.1</a>
0x01	ISO Control	R/W	<a href="#">Section 6.14.3.1.2</a>
<b>Protocol Subsetting Registers</b>			
0x02	ISO/IEC 14443 B TX options	R/W	<a href="#">Section 6.14.3.2.1</a>
0x03	ISO/IEC 14443 A high bit rate options	R/W	<a href="#">Section 6.14.3.2.2</a>
0x04	TX timer high byte control	R/W	<a href="#">Section 6.14.3.2.3</a>
0x05	TX timer low byte control	R/W	<a href="#">Section 6.14.3.2.4</a>
0x06	TX pulse length control	R/W	<a href="#">Section 6.14.3.2.5</a>
0x07	RX no response wait time	R/W	<a href="#">Section 6.14.3.2.6</a>
0x08	RX wait time	R/W	<a href="#">Section 6.14.3.2.7</a>
0x09	Modulator and SYS_CLK control	R/W	<a href="#">Section 6.14.3.2.8</a>
0x0A	RX special setting	R/W	<a href="#">Section 6.14.3.2.9</a>
0x0B	Regulator and I/O control	R/W	<a href="#">Section 6.14.3.2.10</a>
0x10	Special function register (preset 0x00)	R/W	<a href="#">Section 6.14.3.3.4</a>
0x11	Special function register (preset 0x00)	R/W	<a href="#">Section 6.14.3.3.5</a>
0x14	Adjustable FIFO IRQ levels	R/W	<a href="#">Section 6.14.3.3.6</a>
<b>Status Registers</b>			
0x0C	IRQ status	R	<a href="#">Section 6.14.3.3.1</a>
0x0D	Collision position and interrupt mask register	R/W	<a href="#">Section 6.14.3.3.2</a>
0x0E	Collision position	R	<a href="#">Section 6.14.3.3.2</a>
0x0F	RSSI levels and oscillator status	R	<a href="#">Section 6.14.3.3.3</a>
<b>Test Registers</b>			
0x1A	Test (preset 0x00)	R/W	<a href="#">Section 6.14.3.4.1</a>
0x1B	Test (preset 0x00)	R/W	<a href="#">Section 6.14.3.4.2</a>
<b>FIFO Registers</b>			
0x1C	FIFO status	R	<a href="#">Section 6.14.3.5.1</a>
0x1D	TX length byte 1	R/W	<a href="#">Section 6.14.3.5.2</a>
0x1E	TX length byte 2	R/W	<a href="#">Section 6.14.3.5.2</a>
0x1F	FIFO I/O register	R/W	N/A

### 6.14.3 Detailed Register Description

#### 6.14.3.1 Main Configuration Registers

##### 6.14.3.1.1 Chip Status Control Register (0x00)

Table 6-20 describes the Chip Status Control register.

**Table 6-20. Chip Status Control Register (0x00)**

<b>Function:</b> Control of Power mode, RF on or off, Active or Passive mode, Direct mode			
<b>Default:</b> 0x01, preset at EN = L or POR = H			
Bit	Name	Function	Description
B7	stby	1 = Standby mode	Standby mode keeps all supply regulators and the 13.56-MHz SYS_CLK oscillator running. (Typical start-up time to full operation is 100 $\mu$ s.)
		0 = Active mode	Active mode (default)
B6	direct	1 = Direct mode 0 or 1	Provides user direct access to AFE (direct mode 0) or allows user to add custom framing (direct mode 1). Bit 6 of the ISO Control register must be set by user before entering direct mode 0 or 1.
		0 = Direct I 2 (default)	Uses SPI or parallel communication with automatic framing and ISO decoders
B5	rf_on	1 = RF output active	Transmitter on, receivers on
		0 = RF output not active	Transmitter off
B4	rf_pwr	1 = Half output power	TX_OUT (pin 5) = 8- $\Omega$ output impedance P = 100 mW (20 dBm) at 5 V, P = 33 mW (+15 dBm) at 3.3 V
		0 = Full output power	TX_OUT (pin 5) = 4- $\Omega$ output impedance P = 200 mW (+23 dBm) at 5 V, P = 70 mW (+18 dBm) at 3.3 V
B3	pm_on	1 = Selects aux RX input	RX_IN2 input is used
		0 = Selects main RX input	RX_IN1 input is used
B2	Reserved		
B1	rec_on	1 = Receiver activated for external field measurement	Forced enabling of receiver and TX oscillator. Used for external field measurement.
		0 = Automatic enable	Allows enable of the receiver by bit 5 of this register (0x00)
B0	vrs5_3	1 = 5-V operation 0 = 3-V operation	Selects the V <sub>IN</sub> voltage range

##### 6.14.3.1.2 ISO Control Register (0x01)

Table 6-21 describes the ISO Control register.

**Table 6-21. ISO Control Register (0x01)**

<b>Function:</b> Controls the selection of ISO standard protocol, direct mode and receive CRC			
<b>Default:</b> 0x02 (ISO/IEC 15693 high bit rate, one subcarrier, 1 out of 4); it is preset at EN = L or POR = H			
Bit	Name	Function	Description
B7	rx_crc_n	CRC Receive selection	0 = RX CRC (CRC is present in the response) 1 = no RX CRC (CRC is not present in the response) <sup>(1)</sup>
B6	dir_mode	Direct mode type selection	0 = Direct Mode 0 1 = Direct mode 1
B5	rfid	RFID / Reserved	0 = RFID mode 1 = Reserved (should be set to 0)
B4	iso_4	RFID	RFID: See Table 6-22 for B0:B4 settings based on ISO protocol in application
B3	iso_3	RFID	RFID: See Table 6-22 for B0:B4 settings based on ISO protocol in application
B2	iso_2	RFID	RFID: See Table 6-22 for B0:B4 settings based on ISO protocol in application
B1	iso_1	RFID	RFID: See Table 6-22 for B0:B4 settings based on ISO protocol in application

(1) Only applicable to ISO/IEC 14443 A and ISO/IEC 15693

**Table 6-21. ISO Control Register (0x01) (continued)**

B0	iso_0	RFID	RFID: See <a href="#">Table 6-22</a> for B0:B4 settings based on ISO protocol in application
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**Table 6-22. ISO Control Register ISO\_x Settings, RFID Mode**

ISO_4	ISO_3	ISO_2	ISO_1	ISO_0	PROTOCOL	REMARKS
0	0	0	0	0	ISO/IEC 15693 low bit rate, 6.62 kbps, one subcarrier, 1 out of 4	
0	0	0	0	1	ISO/IEC 15693 low bit rate, 6.62 kbps, one subcarrier, 1 out of 256	
0	0	0	1	0	ISO/IEC 15693 high bit rate, 26.48 kbps, one subcarrier, 1 out of 4	Default for reader
0	0	0	1	1	ISO/IEC 15693 high bit rate, 26.48 kbps, one subcarrier, 1 out of 256	
0	0	1	0	0	ISO/IEC 15693 low bit rate, 6.67 kbps, double subcarrier, 1 out of 4	
0	0	1	0	1	ISO/IEC 15693 low bit rate, 6.67 kbps, double subcarrier, 1 out of 256	
0	0	1	1	0	ISO/IEC 15693 high bit rate, 26.69 kbps, double subcarrier, 1 out of 4	
0	0	1	1	1	ISO/IEC 15693 high bit rate, 26.69 kbps, double subcarrier, 1 out of 256	
0	1	0	0	0	ISO/IEC 14443 A RX bit rate, 106 kbps	RX bit rate <sup>(1)</sup>
0	1	0	0	1	ISO/IEC 14443 A RX high bit rate, 212 kbps	
0	1	0	1	0	ISO/IEC 14443 A RX high bit rate, 424 kbps	
0	1	0	1	1	ISO/IEC 14443 A RX high bit rate, 848 kbps	
0	1	1	0	0	ISO/IEC 14443 B RX bit rate, 106 kbps	RX bit rate <sup>(1)</sup>
0	1	1	0	1	ISO/IEC 14443 B RX high bit rate, 212 kbps	
0	1	1	1	0	ISO/IEC 14443 B RX high bit rate, 424 kbps	
0	1	1	1	1	ISO/IEC 14443 B RX high bit rate, 848 kbps	
1	0	0	1	1	Reserved	
1	0	1	0	0	Reserved	
1	1	0	1	0	FeliCa 212 kbps	
1	1	0	1	1	FeliCa 424 kbps	

(1) For ISO/IEC 14443 A or B, when bit rate of TX is different from RX, settings can be done in register 0x02 or 0x03.

### 6.14.3.2 Control Registers – Sublevel Configuration Registers

#### 6.14.3.2.1 ISO/IEC 14443 TX Options Register (0x02)

Table 6-23 describes the ISO/IEC 14443 TX Options register.

**Table 6-23. ISO/IEC 14443 TX Options Register (0x02)**

<b>Function:</b> Selects the ISO subsets for ISO/IEC 14443 – TX			
<b>Default:</b> 0x00 at POR = H or EN = L			
Bit	Name	Function	Description
B7	egt2	TX EGT time select MSB	Three bit code defines the number of etu (0-7) which separate two characters. ISO/IEC 14443 B TX only.
B6	egt1	TX EGT time select	
B5	egt0	TX EGT time select LSB	
B4	eof_l0	1 = EOF→ 0 length 11 etu 0 = EOF→ 0 length 10 etu	ISO/IEC 14443 B TX only
B3	sof_l1	1 = SOF→ 1 length 03 etu 0 = SOF→ 1 length 02 etu	
B2	sof_l0	1 = SOF→ 0 length 11 etu 0 = SOF→ 0 length 10 etu	
B1	l_egt	1 = EGT after each byte 0 = EGT after last byte is omitted	
B0	Reserved		

#### 6.14.3.2.2 ISO/IEC 14443 High-Bit-Rate and Parity Options Register (0x03)

Table 6-24 describes the ISO/IEC 14443 High-Bit-Rate and Parity Options register.

**Table 6-24. ISO/IEC 14443 High-Bit-Rate and Parity Options Register (0x03)**

<b>Function:</b> Selects the ISO subsets for ISO/IEC 14443 – TX			
<b>Default:</b> 0x00 at POR = H or EN = L, and at each write to ISO Control register			
Bit	Name	Function	Description
B7	dif_tx_br	TX bit rate different from RX bit rate enable	Valid for ISO/IEC 14443 A or B high bit rate
B6	tx_br1	TX bit rate	tx_br1 = 0, tx_br = 0 → 106 kbps tx_br1 = 0, tx_br = 1 → 212 kbps tx_br1 = 1, tx_br = 0 → 424 kbps tx_br1 = 1, tx_br = 1 → 848 kbps
B5	tx_br0		
B4	parity-2tx	1 = parity odd except last byte which is even for TX	For ISO/IEC 14443 A high bit rate, coding and decoding
B3	parity-2rx	1 = parity odd except last byte which is even for RX	
B2			Unused
B1			Unused
B0			Unused

### 6.14.3.2.3 TX Timer High Byte Control Register (0x04)

Table 6-25 describes the TX Timer High Byte Control register.

**Table 6-25. TX Timer High Byte Control Register (0x04)**

<b>Function:</b> For Timings			
<b>Default:</b> 0xC2 at POR = H or EN = L, and at each write to ISO Control register			
Bit	Name	Function	Description
B7	tm_st1	Timer Start Condition	tm_st1 = 0, tm_st0 = 0 → beginning of TX SOF tm_st1 = 0, tm_st0 = 1 → end of TX SOF tm_st1 = 1, tm_st0 = 0 → beginning of RX SOF tm_st1 = 1, tm_st0 = 1 → end of RX SOF
B6	tm_st0	Timer Start Condition	
B5	tm_lengthD	Timer Length MSB	
B4	tm_lengthC	Timer Length	
B3	tm_lengthB	Timer Length	
B2	tm_lengthA	Timer Length	
B1	tm_length9	Timer Length	
B0	tm_length8	Timer Length LSB	

### 6.14.3.2.4 TX Timer Low Byte Control Register (0x05)

Table 6-26 describes the TX Timer Low Byte Control register.

**Table 6-26. TX Timer Low Byte Control Register (0x05)**

<b>Function:</b> For Timings			
<b>Default:</b> 0x00 at POR = H or EN = L, and at each write to ISO Control register			
Bit	Name	Function	Description
B7	tm_length7	Timer Length MSB	Defines the time when delayed transmission is started. RX wait range is 590 ns to 9.76 ms (1 to 16383) Step size is 590 ns All bits low = timer disabled (0x00) Preset 0x00 for all other protocols
B6	tm_length6	Timer Length	
B5	tm_length5	Timer Length	
B4	tm_length4	Timer Length	
B3	tm_length3	Timer Length	
B2	tm_length2	Timer Length	
B1	tm_length1	Timer Length	
B0	tm_length0	Timer Length LSB	

### 6.14.3.2.5 TX Pulse Length Control Register (0x06)

The length of the modulation pulse is defined by the protocol selected in the ISO Control register 0x01. With a high Q antenna, the modulation pulse is typically prolonged, and the tag detects a longer pulse than intended. For such cases, the modulation pulse length can be corrected by using the TX Pulse Length Control register (0x06). If the register contains all zeros, then the pulse length is governed by the protocol selection. If the register contains a value other than 0x00, the pulse length is equal to the value of the register in 73.7-ns increments. This means the range of adjustment can be 73.7 ns to 18.8  $\mu$ s.

Table 6-27 describes the TX Pulse Length Control register.

**Table 6-27. TX Pulse Length Control Register (0x06)**

<b>Function:</b> Controls the length of TX pulse			
<b>Default:</b> 0x00 at POR = H or EN = L and at each write to ISO Control register.			
Bit	Name	Function	Description
B7	Pul_p2	Pulse length MSB	The pulse range is 73.7 ns to 18.8 $\mu$ s (1...255), step size 73.7 ns.
B6	Pul_p1		
B5	Pul_p0	Pulse length LSB	All bits low (00): pulse length control is disabled.
B4	Pul_c4		
B3	Pul_c3		
B2	Pul_c2		
B1	Pul_c1		
B0	Pul_c0	Pulse length LSB	The following default timings are preset by the ISO Control register (0x01):
			9.44 $\mu$ s → ISO/IEC 15693 (TI Tag-It HF-I)
			11 $\mu$ s → Reserved
			2.36 $\mu$ s → ISO/IEC 14443 A at 106 kbps
			1.4 $\mu$ s → ISO/IEC 14443 A at 212 kbps
			737 ns → ISO/IEC 14443 A at 424 kbps
			442 ns → ISO/IEC 14443 A at 848 kbps; pulse length control disabled

### 6.14.3.2.6 RX No Response Wait Time Register (0x07)

The RX No Response timer is controlled by the RX NO Response Wait Time Register 0x07. This timer measures the time from the start of slot in the anticollision sequence until the start of tag response. If there is no tag response in the defined time, an interrupt request is sent and a flag is set in IRQ status control register 0x0C. This enables the external controller to be relieved of the task of detecting empty slots. The wait time is stored in the register in increments of 37.76  $\mu$ s. This register is also preset, automatically, for every new protocol selection. Sending a Reset FIFO (0x0F) direct command after a TX Complete interrupt will disable this feature.

Table 6-28 describes the RX No Response Wait Time register.

**Table 6-28. RX No Response Wait Time Register (0x07)**

<b>Function:</b> Defines the time when "no response" interrupt is sent; only for ISO/IEC 15693			
<b>Default:</b> 0x0E at POR = H or EN = L and at each write to ISO Control register			
Bit	Name	Function	Description
B7	NoResp7	No response MSB	Defines the time when "no response" interrupt is sent. It starts from the end of TX EOF. RX no response wait range is 37.76 $\mu$ s to 9628 $\mu$ s (1 to 255), step size is: 37.76 $\mu$ s.
B6	NoResp6		
B5	NoResp5	No response LSB	The following default timings are preset by the ISO Control register (0x01):
B4	NoResp4		
B3	NoResp3		
B2	NoResp2		
B1	NoResp1		
B0	NoResp0	No response LSB	390 $\mu$ s → Reserved
			529 $\mu$ s → for all protocols supported, but not listed here
			604 $\mu$ s → Reserved
			755 $\mu$ s → ISO/IEC 15693 high data rate (TI Tag-It HF-I)
			1812 $\mu$ s → ISO/IEC 15693 low data rate (TI Tag-It HF-I)

### 6.14.3.2.7 RX Wait Time Register (0x08)

The RX-wait-time timer is controlled by the value in the RX wait time register 0x08. This timer defines the time after the end of the transmit operation in which the receive decoders are not active (held in reset state). This prevents incorrect detections resulting from transients following the transmit operation. The value of the RX wait time register defines this time in increments of 9.44  $\mu$ s. This register is preset at every write to ISO Control register 0x01 according to the minimum tag response time defined by each standard.

Table 6-29 describes the RX Wait Time register.

**Table 6-29. RX Wait Time Register (0x08)**

<b>Function:</b> Defines the time after TX EOF when the RX input is disregarded for example, to block out electromagnetic disturbance generated by the responding card.			
<b>Default:</b> 0x1F at POR = H or EN = L and at each write to ISO control register.			
Bit	Name	Function	Description
B7	Rxw7	RX wait time	Defines the time after the TX EOF during which the RX input is ignored. Time starts from the end of TX EOF.  RX wait range is 9.44 $\mu$ s to 2407 $\mu$ s (1 to 255), Step size 9.44 $\mu$ s.  The following default timings are preset by the ISO Control register (0x01):  9.44 $\mu$ s → FeliCa  66 $\mu$ s → ISO/IEC 14443 A and B  180 $\mu$ s → Reserved  293 $\mu$ s → ISO/IEC 15693 (TI Tag-It HF-I)
B6	Rxw6		
B5	Rxw5		
B4	Rxw4		
B3	Rxw3		
B2	Rxw2		
B1	Rxw1		
B1	Rxw0		



### 6.14.3.2.8 Modulator and SYS\_CLK Control Register (0x09)

The frequency of SYS\_CLK (pin 27) is programmable by the bits B4 and B5 of this register. The frequency of the TRF7964A system clock oscillator is divided by 1, 2 or 4 resulting in available SYS\_CLK frequencies of 13.56 MHz or 6.78 MHz or 3.39 MHz.

The ASK modulation depth is controlled by bits B0, B1 and B2. The range of ASK modulation is 7% to 30% or 100% (OOK). The selection between ASK and OOK (100%) modulation can also be done using direct input OOK (pin 12). The direct control of OOK/ASK using OOK pin is only possible if the function is enabled by setting B6 = 1 (en\_ook\_p) in this register (0x09) and the ISO Control Register (0x01, B6 = 1). When configured this way, the MOD (pin 14) is used as input for the modulation signal.

Table 6-30 describes the Modulator and SYS\_CLK Control register.

**Table 6-30. Modulator and SYS\_CLK Control Register (0x09)**

<b>Function:</b> Controls the modulation input and depth, ASK / OOK control and clock output to external system (MCU)				
<b>Default:</b> 0x91 at POR = H or EN = L, and at each write to ISO control register, except Clo1 and Clo0.				
Bit	Name	Function	Description	
B7	27MHz	Enables 27.12-MHz crystal	Default = 1 (enabled)	
B6	en_ook_p	1 = Enables external selection of ASK or OOK modulation 0 = Default operation as defined in B0 to B2 (0x09)	Enable ASK/OOK pin (pin 12) for "on the fly change" between any preselected ASK modulation as defined by B0 to B2 and OOK modulation: If B6 is 1, pin 12 is configured as follows: 1 = OOK modulation 0 = Modulation as defined in B0 to B2 (0x09)	
B5	Clo1	SYS_CLK output frequency MSB	<b>Clo1</b>	<b>Clo0</b> <b>SYS_CLK Output</b> (if 13.56-MHz crystal is used) <b>SYS_CLK Output</b> (if 27.12-MHz crystal is used)
			0	0 Disabled
			0	1 3.39 MHz
B4	Clo0	SYS_CLK output frequency LSB	1	0 6.78 MHz
			1	1 13.56 MHz
B3	en_ana	1 = Sets pin 12 (ASK/OOK) as an analog output 0 = Default	For test and measurement purpose. ASK/OOK pin 12 can be used to monitor the analog subcarrier signal before the digitizing with DC level equal to AGND.	
B2	Pm2	Modulation depth MSB	<b>Pm2</b>	<b>Pm1</b> <b>Pm0</b> <b>Mod Type and %</b>
			0	0 ASK 10%
			0	1 OOK (100%)
B1	Pm1	Modulation depth	0	1 ASK 7%
			1	0 ASK 8.5%
			1	0 ASK 13%
B0	Pm0	Modulation depth LSB	1	1 ASK 16%
			1	0 ASK 22%
			1	1 ASK 30%

### 6.14.3.2.9 RX Special Setting Register (0x0A)

Table 6-31 describes the RX Special Setting register.

**Table 6-31. RX Special Setting Register (0x0A)**

<b>Function:</b> Sets the gains and filters directly			
<b>Default:</b> 0x40 at POR = H or EN = L, and at each write to the ISO Control register 0x01. When bits B7, B6, B5 and B4 are all zero, the filters are set for ISO/IEC 14443 B (240 kHz to 1.4 MHz).			
Bit	Name	Function	Description
B7	C212	Band-pass 110 kHz to 570 kHz	Appropriate for 212-kHz subcarrier system (FeliCa)
B6	C424	Band-pass 200 kHz to 900 kHz	Appropriate for 424-kHz subcarrier used in ISO/IEC 15693
B5	M848	Band-pass 450 kHz to 1.5 MHz	Appropriate for Manchester-coded 848-kHz subcarrier used in ISO/IEC 14443 A and B
B4	hbt	Band-pass 100 kHz to 1.5 MHz Gain reduced for 18 dB	Appropriate for highest bit rate (848 kbps) used in high-bit-rate ISO/IEC 14443
B3	gd1	00 = Gain reduction 0 dB 01 = Gain reduction for 5 dB	Sets the RX gain reduction and reduces sensitivity
B2	gd2	10 = Gain reduction for 10 dB 11 = Gain reduction for 15 dB	
B1	Reserved		
B0	Reserved		

#### NOTE

The setting of bits B4, B5, B6 and B7 to 0 selects bandpass characteristic of 240 kHz to 1.4 MHz. This is appropriate for ISO/IEC 14443 B, FeliCa protocol, and ISO/IEC 14443 A higher bit rates of 212 kbps and 424 kbps.

### 6.14.3.2.10 Regulator and I/O Control Register (0x0B)

Table 6-32 describes the Regulator and I/O Control register.

**Table 6-32. Regulator and I/O Control Register (0x0B)**

Function: Control the three voltage regulators			
Default: 0x87 at POR = H or EN = L			
Bit	Name	Function	Description
B7	auto_reg	0 = Manual settings; see B0 to B2 in Table 6-33 and Table 6-34 1 = Automatic setting (see Table 6-35 and Table 6-36)	Auto system sets $V_{DD\_RF} = V_{IN} - 250$ mV and $V_{DD\_A} = V_{IN} - 250$ mV and $V_{DD\_X} = V_{IN} - 250$ mV, but not higher than 3.4 V.
B6	en_ext_pa	Support for external power amplifier	Internal peak detectors are disabled, receiver inputs (RX_IN1 and RX_IN2) accept externally demodulated subcarrier. At the same time ASK/OOK pin 12 becomes modulation output for external TX amplifier.
B5	io_low	1 = enable low peripheral communication voltage	When B5 = 1, maintains the output driving capabilities of the I/O pins connected to the level shifter under low voltage operation. Should be set 1 when $V_{DD\_I/O}$ voltage is between 1.8 V to 2.7 V.
B4	Unused	No function	Default is 0.
B3	Unused	No function	Default is 0.
B2	vrs2	Voltage set MSB voltage set LSB	Vrs3_5 = L: $V_{DD\_RF}$ , $V_{DD\_A}$ , $V_{DD\_X}$ range 2.7 V to 3.4 V; see Table 6-33 and Table 6-34
B1	vrs1		
B0	vrs0		

**Table 6-33. Supply-Regulator Setting – Manual 5-V System**

REGISTER	OPTION BITS SETTING IN CONTROL REGISTER								ACTION
	B7	B6	B5	B4	B3	B2	B1	B0	
00								1	5-V system
0B	0								Manual regulator setting
0B	0					1	1	1	$V_{DD\_RF} = 5$ V, $V_{DD\_A} = 3.4$ V, $V_{DD\_X} = 3.4$ V
0B	0					1	1	0	$V_{DD\_RF} = 4.9$ V, $V_{DD\_A} = 3.4$ V, $V_{DD\_X} = 3.4$ V
0B	0					1	0	1	$V_{DD\_RF} = 4.8$ V, $V_{DD\_A} = 3.4$ V, $V_{DD\_X} = 3.4$ V
0B	0					1	0	0	$V_{DD\_RF} = 4.7$ V, $V_{DD\_A} = 3.4$ V, $V_{DD\_X} = 3.4$ V
0B	0					0	1	1	$V_{DD\_RF} = 4.6$ V, $V_{DD\_A} = 3.4$ V, $V_{DD\_X} = 3.4$ V
0B	0					0	1	0	$V_{DD\_RF} = 4.5$ V, $V_{DD\_A} = 3.4$ V, $V_{DD\_X} = 3.4$ V
0B	0					0	0	1	$V_{DD\_RF} = 4.4$ V, $V_{DD\_A} = 3.4$ V, $V_{DD\_X} = 3.4$ V
0B	0					0	0	0	$V_{DD\_RF} = 4.3$ V, $V_{DD\_A} = 3.4$ V, $V_{DD\_X} = 3.4$ V

**Table 6-34. Supply-Regulator Setting – Manual 3-V System**

REGISTER	OPTION BITS SETTING IN CONTROL REGISTER								ACTION
	B7	B6	B5	B4	B3	B2	B1	B0	
00								0	3-V system
0B	0								Manual regulator setting
0B	0					1	1	1	$V_{DD\_RF} = 3.4$ V, $V_{DD\_A}$ and $V_{DD\_X} = 3.4$ V
0B	0					1	1	0	$V_{DD\_RF} = 3.3$ V, $V_{DD\_A}$ and $V_{DD\_X} = 3.3$ V
0B	0					1	0	1	$V_{DD\_RF} = 3.2$ V, $V_{DD\_A}$ and $V_{DD\_X} = 3.2$ V
0B	0					1	0	0	$V_{DD\_RF} = 3.1$ V, $V_{DD\_A}$ and $V_{DD\_X} = 3.1$ V
0B	0					0	1	1	$V_{DD\_RF} = 3.0$ V, $V_{DD\_A}$ and $V_{DD\_X} = 3.0$ V
0B	0					0	1	0	$V_{DD\_RF} = 2.9$ V, $V_{DD\_A}$ and $V_{DD\_X} = 2.9$ V
0B	0					0	0	1	$V_{DD\_RF} = 2.8$ V, $V_{DD\_A}$ and $V_{DD\_X} = 2.8$ V
0B	0					0	0	0	$V_{DD\_RF} = 2.7$ V, $V_{DD\_A}$ and $V_{DD\_X} = 2.7$ V

**Table 6-35. Supply-Regulator Setting – Automatic 5-V System**

REGISTER	OPTION BITS SETTING IN CONTROL REGISTER								ACTION
	B7	B6	B5	B4	B3	B2	B1	B0	
00								1	5-V system
0B	1					x <sup>(1)</sup>	0	0	Automatic regulator setting 400-mV difference

(1) x = don't care

**Table 6-36. Supply-Regulator Setting – Automatic 3-V System**

REGISTER	OPTION BITS SETTING IN CONTROL REGISTER								ACTION
	B7	B6	B5	B4	B3	B2	B1	B0	
00								0	3-V system
0B	1					x <sup>(1)</sup>	0	0	Automatic regulator setting 400-mV difference

(1) x = don't care

### 6.14.3.3 Status Registers

#### 6.14.3.3.1 IRQ Status Register (0x0C)

Table 6-37 describes the IRQ Status register.

**Table 6-37. IRQ Status Register (0x0C)**

Function: Information available about TRF7964A IRQ and TX/RX status			
Default: 0x00 at POR = H or EN = L, and at each write to the ISO Control Register 0x01. It is also automatically reset at the end of a read phase. The reset also removes the IRQ flag.			
Bit	Name	Function	Description
B7	Irq_tx	IRQ set due to end of TX	Signals that TX is in progress. The flag is set at the start of TX but the interrupt request (IRQ = 1) is sent when TX is finished.
B6	Irq_srx	IRQ set due to RX start	Signals that RX SOF was received and RX is in progress. The flag is set at the start of RX but the interrupt request (IRQ = 1) is sent when RX is finished.
B5	Irq_fifo	Signals the FIFO level	Signals FIFO high or low as set in the Adjustable FIFO IRQ Levels (0x14) register
B4	Irq_err1	CRC error	Indicates receive CRC error only if B7 (no RX CRC) of ISO Control register is set to 0.
B3	Irq_err2	Parity error	Indicates parity error for ISO/IEC 14443 A
B2	Irq_err3	Byte framing or EOF error	Indicates framing error
B1	Irq_col	Collision error	Collision error for ISO/IEC 14443 A and ISO/IEC 15693 single subcarrier. Bit is set if more than 6 or 7 (as defined in register 0x10) are detected in 1 bit period of ISO/IEC 14443 A 106 kbps. Collision error bit can also be triggered by external noise.
B0	Irq_noresp	No response time interrupt	No response within the "No-response time" defined in RX No Response Wait Time register (0x07). Signals the MCU that the next slot command can be sent. Only for ISO/IEC 15693.

To reset (clear) the register 0x0C and the IRQ line, the register must be read. During Transmit the decoder is disabled, only bits B5 and B7 can be changed. During Receive only bit B6 can be changed, but does not trigger the IRQ line immediately. The IRQ signal is set at the end of Transmit and Receive phase.

### 6.14.3.3.2 Interrupt Mask Register (0x0D) and Collision Position Register (0x0E)

Table 6-38 describes the Interrupt Mask register. Table 6-39 describes the Collision Position register.

**Table 6-38. Interrupt Mask Register (0x0D)**

Default: 0x3E at POR = H and EN = L. Collision bits reset automatically after read operation.			
Bit	Name	Function	Description
B7	Col9	Bit position of collision MSB	Supports ISO/IEC 14443 A
B6	Col8	Bit position of collision	
B5	En_irq_fifo	Interrupt enable for FIFO	Default = 1
B4	En_irq_err1	Interrupt enable for CRC	Default = 1
B3	En_irq_err2	Interrupt enable for Parity	Default = 1
B2	En_irq_err3	Interrupt enable for Framing error or EOF	Default = 1
B1	En_irq_col	Interrupt enable for collision error	Default = 1
B0	En_irq_noresp	Enables no-response interrupt	Default = 0

**Table 6-39. Collision Position Register (0x0E)**

Function: Displays the bit position of collision or error			
Default: 0x00 at POR = H and EN = L. Automatically reset after read operation.			
Bit	Name	Function	Description
B7	Col7	Bit position of collision MSB	ISO/IEC 14443 A mainly supported, in the other protocols this register shows the bit position of error. Frame, SOF, EOF, parity, or CRC error.
B6	Col6		
B5	Col5		
B4	Col4		
B3	Col3		
B2	Col2		
B1	Col1		
B0	Col0	Bit position of collision LSB	

### 6.14.3.3.3 RSSI Levels and Oscillator Status Register (0x0F)

Table 6-40 describes the RSSI Levels and Oscillator Status register.

**Table 6-40. RSSI Levels and Oscillator Status Register (0x0F)**

Bit	Name	Function	Description
B7	Unused		
B6	osc_ok	Crystal oscillator stable indicator	13.56-MHz frequency stable (approximately 200 $\mu$ s)
B5	rss_i_x2	MSB RSSI value of auxiliary RX (RX_IN2)	Auxiliary channel is by default RX_IN2. The input can be swapped by B3 = 1 (Chip Status Control register 0x00). If "swapped", the Auxiliary channel is connected to RX_IN1 and, hence, the Auxiliary RSSI represents the signal level at RX_IN1.
B4	rss_i_x1	Auxiliary channel RSSI	
B3	rss_i_x0	MSB RSSI value of auxiliary RX (RX_IN2)	
B2	rss_i_2	MSB RSSI value of main RX (RX_IN1)	Active channel is default and can be set with option bit B3 = 0 of Chip Status Control register 0x00.
B1	rss_i_1	Main channel RSSI	
B0	rss_i_0	LSB RSSI value of main RX (RX_IN1)	

RSSI measurement block is measuring the demodulated envelope signal (except in case of direct command for RF amplitude measurement described later in direct commands section). The measuring system is latching the peak value, so the RSSI level can be read after the end of receive packet. The RSSI value is reset during next transmit action of the reader, so the new tag response level can be measured. The RSSI levels calculated to the RF\_IN1 and RF\_IN2 are presented in [Section 6.5.1.1](#) and [Section 6.5.1.2](#). The RSSI has 7 steps (3 bits) with 4-dB increment. The input level is the peak-to-peak modulation level of RF signal measured on one side envelope (positive or negative).

### 6.14.3.3.4 Special Functions Register (0x10)

Table 6-41 describes the Special Functions register at address 0x10.

**Table 6-41. Special Functions Register (0x10)**

Function: User configurable options for ISO/IEC 14443 A specific operations			
Bit	Name	Function	Description
B7		Reserved	Reserved
B6		Reserved	Reserved
B5	par43	Disables parity checking for ISO/IEC 14443 A	
B4	next_slot_37us	0 = 18.88 $\mu$ s 1 = 37.77 $\mu$ s	Sets the time grid for next slot command in ISO/IEC 15693
B3	Sp_dir_mode	Bit stream transmit for MIFARE at 106 kbps	Enables direct mode for transmitting ISO/IEC 14443 A data, bypassing the FIFO and feeding the data bit stream directly onto the encoder.
B2	4_bit_RX	0 = normal receive 1 = 4-bit receive	Enable 4-bit replay for example, ACK, NACK used by some cards; for example, MIFARE Ultralight
B1	14_anticoll	0 = anticollision framing (0x93, 0x95, 0x97) 1 = normal framing (no broken bytes)	Disable anticollision frames for ISO/IEC 14443 A (this bit should be set to 1 after anticollision is finished)
B0	col_7_6	0 = 7 subcarrier pulses 1 = 6 subcarrier pulses	Selects the number of subcarrier pulses that trigger collision error in ISO/IEC 14443 A at 106 kbps

### 6.14.3.3.5 Special Functions Register (0x11)

Table 6-42 describes the Special Functions register at address 0x11.

**Table 6-42. Special Functions Register (0x11)**

<b>Function:</b> Indicate IRQ status for RX operations.			
Bit	Name	Function	Description
B7	Reserved		Reserved
B6	Reserved		Reserved
B5	Reserved		Reserved
B4	Reserved		Reserved
B3	Reserved		Reserved
B2	Reserved		Reserved
B1	Reserved		Reserved
B0	irg_srx	Copy of the RX start signal (Bit 6) of the IRQ Status register (0x0C)	Signals the RX SOF was received and the RX is in progress. IRQ when RX is completed.

### 6.14.3.3.6 Adjustable FIFO IRQ Levels Register (0x14)

Table 6-43 describes the Adjustable FIFO IRQ Levels register.

**Table 6-43. Adjustable FIFO IRQ Levels Register (0x14)**

<b>Function:</b> Adjusts level at which FIFO indicates status by IRQ					
<b>Default:</b> 0x00 at POR = H and EN = L					
Bit	Name	Function	Description		
B7	Reserved		Reserved		
B6	Reserved		Reserved		
B5	Reserved		Reserved		
B4	Reserved		Reserved		
B3	Wlh_1	FIFO high IRQ level (during RX)	<b>Wlh_1</b>	<b>Wlh_0</b>	<b>IRQ Level</b>
B2	Wlh_0		0	0	124
			0	1	120
			1	0	112
		1	1	96	
B1	Wll_1	FIFO low IRQ level (during TX)	<b>Wll_1</b>	<b>Wll_0</b>	<b>IRQ Level</b>
B0	Wll_0		0	0	4
			0	1	8
			1	0	16
		1	1	32	

### 6.14.3.4 Test Registers

#### 6.14.3.4.1 Test Register (0x1A)

Table 6-44 describes the Test register at address 0x1A.

**Table 6-44. Test Register (0x1A) (for Test or Direct Use)**

Default: 0x00 at POR = H and EN = L.			
Bit	Name	Function	Description
B7	OOK_Subc_In	Subcarrier input	OOK pin becomes decoder digital input
B6	MOD_Subc_Out	Subcarrier output	MOD pin becomes receiver digitized subcarrier output
B5	MOD_Direct	Direct TX modulation and RX reset	MOD pin becomes input for TX modulation control by the MCU
B4	o_sel	First stage output selection	o_sel = L: First stage output used for analog out and digitizing o_sel = H: Second Stage output used for analog out and digitizing
B3	low2	Second stage gain –6 dB, HP corner frequency / 2	
B2	low1	First stage gain –6 dB, HP corner frequency / 2	
B1	zun	Input followers test	
B0	Test_AGC	AGC test, AGC level is seen on rssi_210 bits	

#### 6.14.3.4.2 Test Register (0x1B)

Table 6-45 describes the Test register at address 0x1B.

**Table 6-45. Test Register (0x1B) (for Test or Direct Use)**

Default: 0x00 at POR = H and EN = L. When a test_dec or test_io is set IC is switched to test mode. Test Mode persists until a stop condition arrives. At stop condition the test_dec and test_io bits are cleared.			
Bit	Name	Function	Description
B7	test_rf_level	RF level test	
B6			
B5			
B4			
B3	test_io1	I/O test	Not implemented
B2	test_io0		
B1	test_dec	Decoder test mode	
B0	clock_su	Coder clock 13.56 MHz	For faster test of coders



### 6.14.3.5 FIFO Control Registers

Section 6.14.3.5.1 describes the FIFO Status register.

#### 6.14.3.5.1 FIFO Status Register (0x1C)

**Table 6-46. FIFO Status Register (0x1C)**

<b>Function:</b> Number of bytes available to be read from FIFO (= N number of bytes, in hexadecimal)			
<b>Bit</b>	<b>Name</b>	<b>Function</b>	<b>Description</b>
B7	Foverflow	FIFO overflow error	Bit is set when FIFO has more than 127 bytes presented to it
B6	Fb6	FIFO bytes fb[6]	Bits B0:B6 indicate how many bytes are in the FIFO to be read out (= N number of bytes, in hex)
B5	Fb5	FIFO bytes fb[5]	
B4	Fb4	FIFO bytes fb[4]	
B3	Fb3	FIFO bytes fb[3]	
B2	Fb2	FIFO bytes fb[2]	
B1	Fb1	FIFO bytes fb[1]	
B0	Fb0	FIFO bytes fb[0]	

### 6.14.3.5.2 TX Length Byte1 Register (0x1D), TX Length Byte2 Register (0x1E)

Table 6-47 describes the TX Length Byte1 register. Table 6-48 describes the TX Length Byte2 register.

**Table 6-47. TX Length Byte1 Register (0x1D)**

<b>Function:</b> High 2 nibbles of complete, intended bytes to be transferred through FIFO			
<b>Register default is set to</b> 0x00 at POR and EN = 0. It is also automatically reset at TX EOF			
Bit	Name	Function	Description
B7	Txl11	Number of complete byte bn[11]	High nibble of complete, intended bytes to be transmitted
B6	Txl10	Number of complete byte bn[10]	
B5	Txl9	Number of complete byte bn[9]	
B4	Txl8	Number of complete byte bn[8]	
B3	Txl7	Number of complete byte bn[7]	Middle nibble of complete, intended bytes to be transmitted
B2	Txl6	Number of complete byte bn[6]	
B1	Txl5	Number of complete byte bn[5]	
B0	Txl4	Number of complete byte bn[4]	

**Table 6-48. TX Length Byte2 Register (0x1E)**

<b>Function:</b> Low nibbles of complete bytes to be transferred through FIFO; Information about a broken byte and number of bits to be transferred from it			
<b>Default:</b> 0x00 at POR and EN = 0. It is also automatically reset at TX EOF			
Bit	Name	Function	Description
B7	Txl3	Number of complete byte bn[3]	Low nibble of complete, intended bytes to be transmitted
B6	Txl2	Number of complete byte bn[2]	
B5	Txl1	Number of complete byte bn[1]	
B4	Txl0	Number of complete byte bn[0]	
B3	Bb2	Broken byte number of bits bb[2]	Number of bits in the last broken byte to be transmitted. Valid only when broken byte flag is set.
B2	Bb1	Broken byte number of bits bb[1]	
B1	Bb0	Broken byte number of bits bb[0]	
B0	Bbf	Broken byte flag	B0 = 1 indicates that last byte is not complete 8 bits wide.



## 7.2 Layout Considerations

Keep all decoupling capacitors as close to the IC as possible, with the high-frequency decoupling capacitors (10 nF) closer than the low-frequency decoupling capacitors (2.2  $\mu$ F).

Place ground vias as close as possible to the ground side of the capacitors and reader IC pins to minimize possible ground loops.

TI recommends not using any inductor sizes smaller than 0603, as the output power can be compromised. If smaller inductors are necessary, output performance must be confirmed in the final application.

Pay close attention to the required load capacitance of the crystal, and adjust the two external shunt capacitors accordingly. Follow the recommendations of the crystal manufacturer for those values.

There should be a common ground plane for the digital and analog sections. The multiple ground sections or islands should have vias that tie the different sections of the planes together.

Ensure that the exposed thermal pad at the center of the reader IC is properly laid out. It should be tied to ground to help dissipate any heat from the package.

All trace line lengths should be made as short as possible, particularly the RF output path, crystal connections, and control lines from the reader to the microprocessor. Proper placement of the TRF7964A, microprocessor, crystal, and RF connection or connector help facilitate this.

Avoid crossing of digital lines under RF signal lines. Also, avoid crossing of digital lines with other digital lines when possible. If the crossings are unavoidable, 90° crossings should be used to minimize coupling of the lines.

Depending on the production test plan, consider possible implementations of test pads or test vias for use during testing. The necessary pads or vias should be placed in accordance with the proposed test plan to enable easy access to those test points.

If the system implementation is complex (for example, if the RFID reader module is a subsystem of a greater system with other modules (microprocessors and clocks), special considerations should be taken to ensure that there is no noise coupling into the supply lines. If needed, special filtering or regulator considerations should be used to minimize or eliminate noise in these systems.

For more information/details on layout considerations, see the [TRF796x HF-RFID Reader Layout Design Guide](#).

## 7.3 Impedance Matching TX\_Out (Pin 5) to 50 $\Omega$

The output impedance of the TRF7964A when operated at full power out setting is nominally  $4 + j0$  (4  $\Omega$  real). This impedance must be matched to a resonant circuit and TI recommends matching circuit from 4  $\Omega$  to 50  $\Omega$ , as commercially available test equipment (for example, spectrum analyzers, power meters, and network analyzers) are 50- $\Omega$  systems. [Figure 7-2](#) shows an impedance-matching reference circuit. [Figure 7-3](#) shows a Smith chart simulation based on this circuit. This section explains how the values were calculated.

Starting with the 4- $\Omega$  source, the process of going from 4  $\Omega$  to 50  $\Omega$  can be represented on a Smith Chart simulator (available from <http://www.fritz.dellsperger.net/>). The elements are combined where appropriate (see [Figure 7-2](#)).

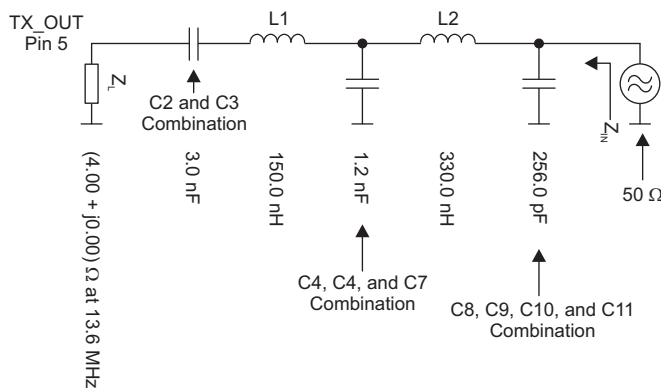


Figure 7-2. Impedance Matching Circuit

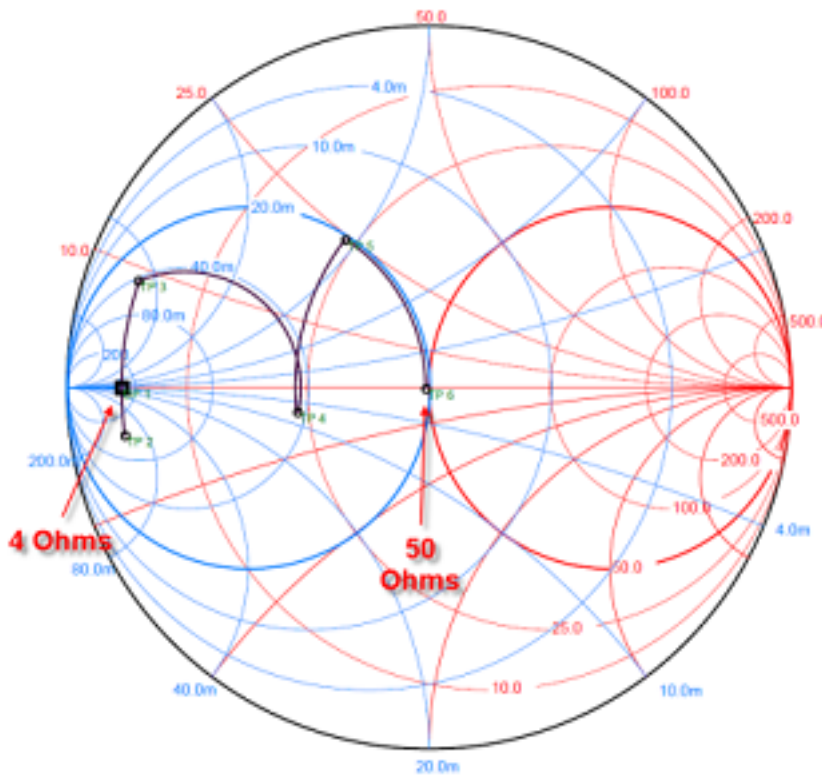


Figure 7-3. Smith Chart Simulation

Resulting power out can be measured with a power meter or spectrum analyzer with power meter function or other equipment capable of making a "hot" measurement. Observe maximum power input levels on test equipment and use attenuators whenever available to avoid damage to equipment. Expected output power levels under various operating conditions are shown in [Table 6-20](#).

#### 7.4 Reader Antenna Design Guidelines

For HF antenna design considerations using the TRF7964A, see these documents:

- [Antenna Matching for the TRF7960 RFID Reader](#)
- [TRF7960TB HF RFID Reader Module User's Guide](#)

## 8 器件和文档支持

### 8.1 入门和下一步

有关 TI NFC/RFID 器件以及有助于开发的工具和软件的更多信息，请访问 [NFC/RFID 概述](#)。

### 8.2 器件命名规则

为了标示产品开发周期所处的阶段，TI 为器件的部件号分配了前缀。每个商用系列产品成员都具有以下三个前缀之一：**x**、**p** 或无前缀。这些前缀代表了从工程原型（带有前缀 **x**）到完全合格的生产器件（无前缀）的产品开发进化阶段。

器件开发进化流程：

**xTRF...** – 实验器件，不一定代表最终器件的电气规格

**pTRF...** – 最终器件，符合最终产品的电气规格，但是未完成质量和可靠性验证

**TRF...** – 完全合格的生产器件

具有 **x** 或 **p** 前缀的器件供货时附带如下免责声明：

“开发的产品用于内部评估用途。”

生产器件已进行完全特性化，并且器件的质量和可靠性已经完全论证。TI 的标准保修证书适用。

预测显示原型器件的故障率大于标准生产器件。由于这些器件的预计最终使用故障率仍未定义，德州仪器 (TI) 建议不要将它们用于任何生产系统。只有合格的产品器件将被使用。

TI 器件的命名规则也包括一个带有器件系列名称的后缀。此后缀表示封装类型和可选的温度范围。图 8-1 提供了解读完整器件名称的图例。

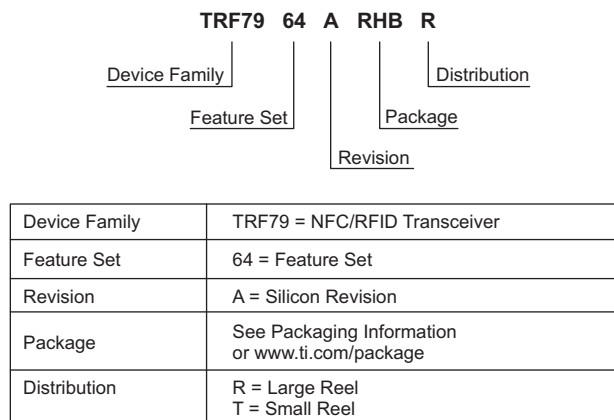


图 8-1. 器件命名规则

## 8.3 工具与软件

### 设计套件和评估模块

**NFC 收发器附加目标板模块** TRF7970ATB 评估模块让软件应用开发人员能够熟悉所选的德州仪器 (TI) 嵌入式微控制器平台上的 TRF7970A 多协议全集成 13.56MHz NFC/HF RFID IC 的功能，而无需担心射频部分。

**NFC 收发器 Booster Pack 插件模块** 第三方提供商 DLP Design 所提供的 NFC/RFID BoosterPack 插件模块 (DLP-7970ABP) 是一款附加电路板，旨在满足所有 TI MCU LaunchPad 开发套件的需求。此 BoosterPack 插件模块能够让软件应用开发人员熟悉所选的 TI 嵌入式微控制器平台上的 TRF7970A 多协议全集成式 13.56MHz NFC 和 HF RFID IC 的功能，而无需担心射频部分的开发。

**NFC 收发器评估模块** TRF7970AEVM 是一种自成一体的开发平台，可用于评估 NFC 收发器 TRF7970A 的性能。TRF7970A 是一款多协议全集成式 13.56MHz NFC/RFID 收发器 IC。该评估模块与这个 IC 一起可用于开发和评估自定义固件、客户设计的天线以及潜在应答器，适用于各种 NFC/RFID 应用。

## 8.4 文档支持

以下文档对 TRF7964A 器件进行了介绍。[www.ti.com.cn](http://www.ti.com.cn) 网站上提供了这些文档的副本。

### 接收文档更新通知

要接收文档更新通知（包括器件勘误表），请转至 [ti.com.cn](http://ti.com.cn) 上相关器件的产品文件夹（例如 [TRF7964A](#)）。单击右上角的“提醒我”(Alert me) 按钮。点击后，您将每周定期收到已更改的产品信息（如果有的话）。有关更改的详细信息，请查阅已修订文档的修订历史记录。

### 应用手册

《[在断电模式下最大限度减小 TRF79xx 电流使用量](#)》此应用报告为 TRF79xx 器件系列（TRF796x、TRF796xA 和 TRF7970A）提供了电路和固件设计建议，以便减少断电模式下的电流消耗。此手册考虑了各种设计，并根据这些设计的电流消耗进行了分析。此应用报告特别强调了由电池供电的双电压系统。

《[使用 TRF7970A 的 NFC/HF RFID 读/写器](#)》近场通信 (NFC) 市场正在涌入医疗、消费品、零售、工业、汽车和智能电网等多个领域。读/写器是 TRF7970A 支持的三种工作模式之一。使用读/写器模式时，用户可以配置 TRF7970A 以读取类型 2、类型 3、类型 4A、类型 4B 和类型 5 标签平台（也称为应答器）。标签可以存储 NFC 数据交换格式 (NDEF) 消息或事先定义的专有数据。此应用报告介绍了读/写器模式的基本概念以及如何针对每种支持的技术正确配置 TRF7970A 收发器。

《[TRF7970A NFC 读取器天线多路复用](#)》此应用报告介绍了使用单个 TRF7970A NFC 收发器 IC 实现多个读取器天线的情况。为了进行演示，此报告中使用了带有 TRF7970A BoosterPack 插件模块的 MSP430F5529 LaunchPad 开发套件。该演示支持 ISO/IEC 15693 以及 ISO/IEC 14443 A 和 B 通信协议。

《使用 MSP430 和 TRF79xxA 进行 NFC/RFID 读取器超低功耗卡存在检测》NFC 和 RFID 读取器电池供电型应用 必须具有事先定义和限定的能量消耗预算以及低成本才能实现产品。多年来，卡在检测领域已涌现多种技术和策略，试图解决这两个问题。此应用报告的目的是进一步优化这些技术和策略，方法是在现有设计中增加一个简单电路和小型固件控制逻辑环路，从而在原先确定的卡检测解决方案的基础上带来巨大改进。

## 8.5 社区资源

下列链接能连接到 TI 社区资源。链接的内容由各个分销商“按照原样”提供。这些内容并不构成 TI 技术规范，并且不一定反映 TI 的观点；请参阅 TI 的《使用条款》。

### TI E2E™ 社区

**TI 工程师间 (E2E) 社区。** 此社区的创建目的在于促进工程师之间的协作。在 [e2e.ti.com](http://e2e.ti.com) 中，您可以咨询问题、分享知识、拓展思路并与同行工程师一道帮助解决问题。

## 8.6 商标

E2E is a trademark of Texas Instruments.  
MIFARE is a trademark of NXP Semiconductors.  
FeliCa is a trademark of Sony Corporation.

## 8.7 静电放电警告



ESD 可能会损坏该集成电路。德州仪器 (TI) 建议通过适当的预防措施处理所有集成电路。如果不遵守正确的处理措施和安装程序，可能会损坏集成电路。

ESD 的损坏小至导致微小的性能降级，大至整个器件故障。精密的集成电路可能更容易受到损坏，这是因为非常细微的参数更改都可能会导致器件与其发布的规格不相符。

## 8.8 Glossary

[SLYZ022](#) — *TI Glossary*.



This glossary lists and explains terms, acronyms and definitions.



## 9 机械、封装和可订购信息

以下页面包含机械、封装和可订购信息。这些信息是指定器件的最新可用数据。这些数据如有变更，恕不另行通知和修订此文档。如欲获取此数据表的浏览器版本，请参阅左侧的导航。

**PACKAGING INFORMATION**

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
TRF7964ARHBR	ACTIVE	VQFN	RHB	32	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 110	TRF 7964A	
TRF7964ARHBT	ACTIVE	VQFN	RHB	32	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 110	TRF 7964A	

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green:** TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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**TAPE AND REEL INFORMATION**

**QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TRF7964ARHBR	VQFN	RHB	32	3000	330.0	12.4	5.3	5.3	1.5	8.0	12.0	Q2
TRF7964ARHBT	VQFN	RHB	32	250	180.0	12.4	5.3	5.3	1.5	8.0	12.0	Q2

**TAPE AND REEL BOX DIMENSIONS**


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TRF7964ARHBR	VQFN	RHB	32	3000	356.0	356.0	35.0
TRF7964ARHBT	VQFN	RHB	32	250	210.0	185.0	35.0

## GENERIC PACKAGE VIEW

**RHB 32**

**VQFN - 1 mm max height**

5 x 5, 0.5 mm pitch

PLASTIC QUAD FLATPACK - NO LEAD



Images above are just a representation of the package family, actual package may vary.  
Refer to the product data sheet for package details.

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NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

# EXAMPLE BOARD LAYOUT

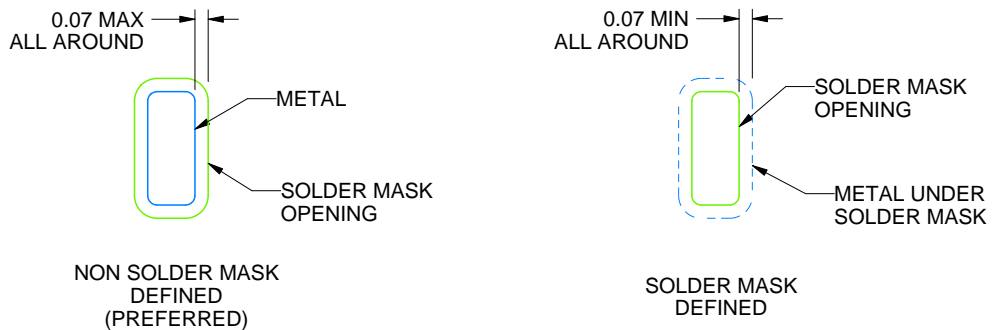
RHB0032E

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



LAND PATTERN EXAMPLE  
SCALE:18X



SOLDER MASK DETAILS

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NOTES: (continued)

- This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 ([www.ti.com/lit/sluea271](http://www.ti.com/lit/sluea271)).
- Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

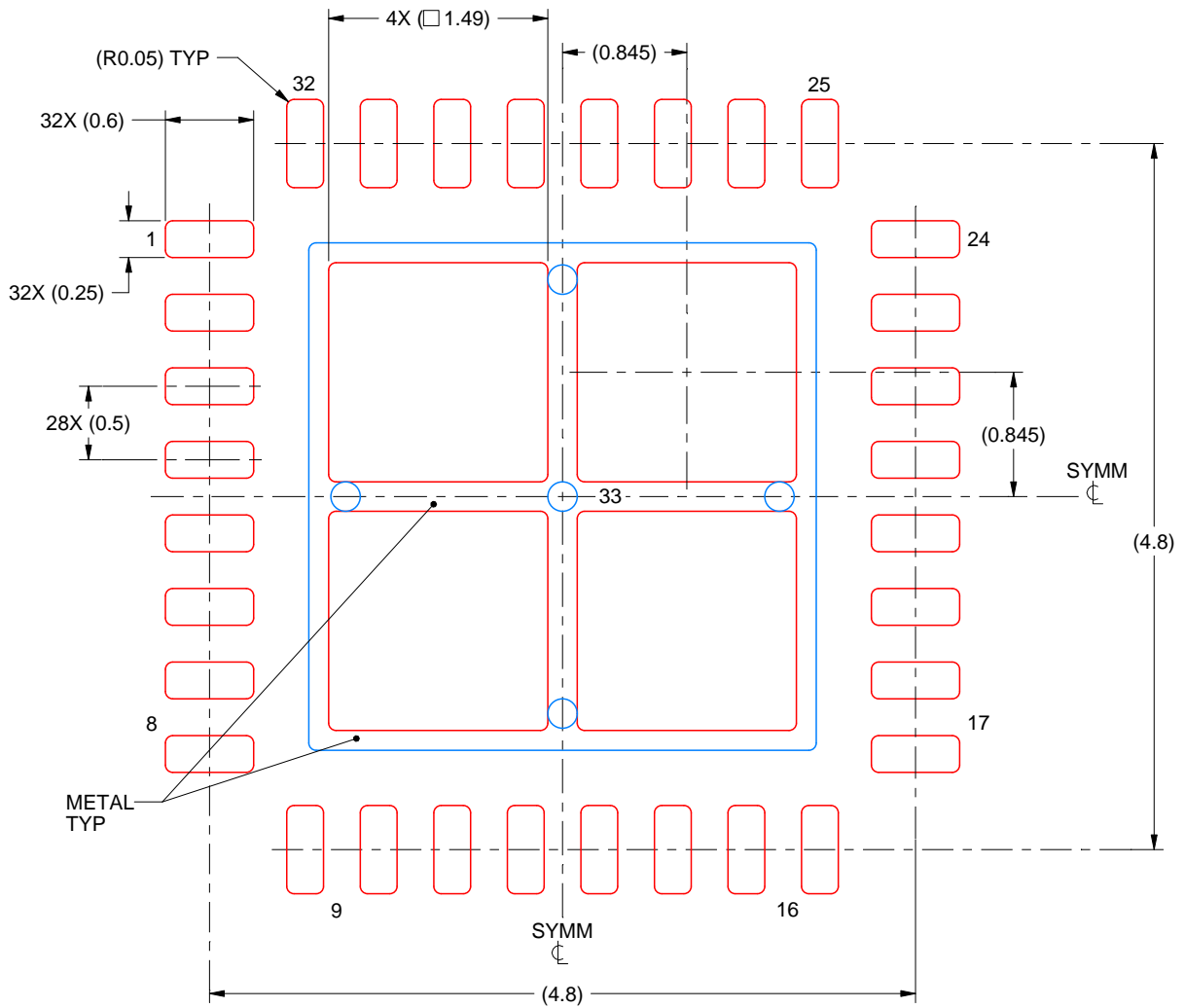


# EXAMPLE STENCIL DESIGN

RHB0032E

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



**SOLDER PASTE EXAMPLE**  
 BASED ON 0.125 mm THICK STENCIL

EXPOSED PAD 33:  
 75% PRINTED SOLDER COVERAGE BY AREA UNDER PACKAGE  
 SCALE:20X

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NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

## 重要声明和免责声明

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