## 用于电池供电系统的 TPS65217x 单芯片 PMIC

1 特性

- 充电器和电源路径
- 电源路径上的 2 A 输出电流
- 线性充电器；最大充电电流 700 mA
- 耐压达 20 V 的 USB 和交流输入
- 热调节，安全定时器
- 温度感测输入
- 降压转换器（DCDC1，DCDC2 和 DCDC3）
- 具有集成开关 FET 的三个降压转换器
- 2.25 MHz 固定频率运行
- 轻负载电流下的省电模式
- PWM 模式下输出电压精度为 $\pm 2 \%$
- 针对最低压降的 $100 \%$ 占空比
- 每转换器的静态电流典型值为 $15 \mu \mathrm{~A}$
- 当被禁用时对地被动放电
- LDO 稳压器（LDO1 和 LDO2）
- 两个可调式 LDO
- LDO2 可配置为跟踪 DCDC3
- 静态电流典型值为 $15 \mu \mathrm{~A}$
- 负载开关（LDO3 和 LDO4）
- 两个可配置为 LDO 的独立负载开关
- WLED 驱动器
- 具有内部生成的 PWM，支持调光控制
- 38V 开路 LED 保护
- 支持两个 LED 灯串（每串多达 10 个 LED，每个 LED 的电流为 25 mA ）
- 内部低侧灌电流
- 保护
- 低压锁定和电池故障比较器
- 常开按钮监视器
- 硬件复位引脚
- 受密码保护的 $\mathrm{I}^{2} \mathrm{C}$ 寄存器
- 接口
- $I^{2} C$ 接口（地址 $0 \times 24$ ）
- 受密码保护的 $I^{2} C$ 寄存器


## 2 应用

- Sitara ${ }^{\text {TM }} A M 335 x$ 处理器电源
- 便携式导航系统
- 平板电脑
- 5V 工业用设备


## 3 说明

TPS65217x 是一款单芯片电源管理 IC（PMIC），专门设计用来为便携式设备和 5 V 线路供电应用中的 AM335x ARM ${ }^{\circledR}$ Cortex $^{\circledR}$－A8 处理器供电。该PMIC器件包含一个线性电池充电器（支持单节锂离子电池和锂聚合物电池），双输入电源路径，三个降压转化器，四个低压降（LDO）稳压器以及一个高效升压转换器，可为两个分别由多达 10 个 LED 组成的灯串供电。此系统可由 USB 端口，5V 交流适配器或锂离子电池的任意组合供电。此器件的额定运行温度范围为 $-40^{\circ} \mathrm{C}$ 至 $+105^{\circ} \mathrm{C}$ ，非常适合工业应用。三个高效 2.25 MHz 降压转换器可为系统提供内核电压，存储器和 I／O 电压。 TPS65217x 采用间距为 0.4 mm 的 48 引脚无引线封装 （ $6 \mathrm{~mm} \times 6 \mathrm{~mm}$ VQFN）。

器件信息 ${ }^{(1)}$

| 器件型号 | 封装 | 封装尺寸（标称值） |
| :--- | :---: | :--- |
| TPS65217A |  |  |
| TPS65217B | VQFN（48） | $6.00 \mathrm{~mm} \times 6.00 \mathrm{~mm}$ |
| TPS65217C |  |  |
| TPS65217D |  |  |

（1）如需了解所有可用封装，请参阅数据表末尾的可订购产品附录。

简化应用示意图


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## 4 修订历史记录

注：之前版本的页码可能与当前版本有所不同。
Changes from Revision H（June 2017）to Revision I Page
－已更改了说明部分中的方框图 ..... 1
－Changed the lists in the Power－Up Sequencing section to logical sentences for simplicity ..... 20
－Added a description of the always－on power supply in the Push－Button Monitor（PB＿IN）section ..... 23
－Changed the Global State Diagram． ..... 39
－Fixed typos in the Register Address Map section ..... 44
－Changed the list of access types to be more simple and added a note for reserved bits in the Access Type Codes table ..... 44
－已更改 the first paragraph in the 5－V Operation Without a Battery section． ..... 77
－已添加 文档支持 部分 ..... 83
Changes from Revision G（January 2015）to Revision H ..... Page
－在第一页顶部添加了＂参考设计＂按钮 ..... 1
－Revised Figure 4 ..... 20
－Reversed STROBE 14 and STROBE 15 in the second paragraph of Special Strobes（STROBE 14 and 15） ..... 22
－Changed PFMENx bit value required to force PWM operation at light loads from 0 to 1 ..... 34
－Changed Figure 24 ..... 39
－Changed text in RESET paragraph ..... 41
－Added a row to 表 37 ..... 78
－添加了＂接收通知＂和＂社区资源＂部分83

## Changes from Revision F（April 2013）to Revision G

－已添加 添加了 ESD 额定值 表，特性 说明部分，器件功能模式，应用和实施部分，电源相关建议部分，布局部分，器件和文档支持部分以及机械，封装和可订购信息部分

## 5 Device Comparison Table ${ }^{(1)}$

The device comparison table summarizes the default regulator output voltages and sequencing order settings for the four available variants of the TPS65217 device. For details on the preprogrammed register map values that determine these voltage and strobe sequence settings, refer to Register Maps. For details on specific applications, refer to the Powering the AM335x with the TPS65217x user's guide.

| RAIL | TPS65217A(TARGETED AT AM335x - ZCE) |  | TPS65217B(TARGETED AT AM335x-ZCZ) |  | TPS65217C <br> (TARGETED AT AM335x - ZCZ) |  | TPS65217D(TARGETED AT AM335x - ZCZ) |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | VOLTAGE (V) | SEQUENCE (STROBE) | VOLTAGE (V) | SEQUENCE (STROBE) | VOLTAGE (V) | SEQUENCE (STROBE) | VOLTAGE (V) | SEQUENCE (STROBE) |
| DCDC1 | 1.8 | 1 | 1.8 | 1 | 1.5 | 1 | 1.35 | 1 |
| DCDC2 | 3.3 | 2 | 1.1 | 5 | 1.1 | 5 | 1.1 | 5 |
| DCDC3 | 1.1 | 3 | 1.1 | 5 | 1.1 | 5 | 1.1 | 5 |
| LDO1 $^{(1)}$ | 1.8 | 15 | 1.8 | 15 | 1.8 | 15 | 1.8 | 15 |
| LDO2 | 3.3 | 2 | 3.3 | 2 | 3.3 | 3 | 3.3 | 3 |
| LS1 or LDO3 | Load switch | 1 | $\begin{gathered} 3.3 \\ (\mathrm{LDO}, 200 \mathrm{~mA}) \end{gathered}$ | 3 | $\begin{gathered} 1.8 \\ (\mathrm{LDO}, 400 \mathrm{~mA}) \end{gathered}$ | 2 | $\begin{gathered} 1.8 \\ (\mathrm{LDO}, 400 \mathrm{~mA}) \end{gathered}$ | 2 |
| $\begin{aligned} & \text { LS2 or } \\ & \text { LDO } \end{aligned}$ | Load switch | 4 | $\begin{gathered} 3.3 \\ (\mathrm{LDO}, 200 \mathrm{~mA}) \end{gathered}$ | 4 | $\begin{gathered} 3.3 \\ (\mathrm{LDO}, 400 \mathrm{~mA}) \end{gathered}$ | 4 | $\begin{gathered} 3.3 \\ (\mathrm{LDO}, 400 \mathrm{~mA}) \end{gathered}$ | 4 |

(1) For more information, see RESET in the PMIC States section.
(1) Strobe 15 (LDO1) is the first rail to be enabled in a sequence, followed by strobe 1 through strobe 7 . For more information, see the Wake-Up and Power-Up Sequencing section.

## 6 Pin Configuration and Functions



NC - No internal connection

## Pin Functions

| PIN |  | I/O |  |
| :--- | :---: | :---: | :--- |
| NAME | NO. |  | DESCRIPTION |
| AC | 10 | I | AC-adapter input to power path. Connect this pin to an external dc supply. |
| AGND | 41 | - | Analog ground (GND). Connect the AGND pin to the ground plane. |
| BAT | 4,5 | I/O | Battery charger output. Connect these pins to the battery. |
| BAT_SENSE | 6 | I | Battery-voltage sense input. Connect the BAT_SENSE pin to the BAT pin directly at the battery <br> terminal. |
| BYPASS | 47 | O | Internal bias voltage (2.25 V). TI does not recommend connecting any external load to this pin. <br> FB_WLED$\quad 38$ |
| I | Feedback pin for the WLED boost converter. This pin is also connected to the anode of the <br> WLED strings. |  |  |
| INT_LDO | 48 | O | Internal bias voltage (2.3 V). TI does not recommend connecting any external load to this pin. |
| ISET1 | 36 | I | Low-level WLED current set. Connect this pin to a resistor to ground to set the WLED low-level <br> current value. |
| ISET2 | I | High-level WLED current set. Connect this pin to a resistor to ground to set the WLED high-level <br> current value. |  |

## Pin Functions (continued)

| PIN |  | I/O | DESCRIPTION |
| :---: | :---: | :---: | :---: |
| NAME | NO. |  |  |
| ISINK1 | 34 | I | Input to the WLED current SINK1. Connect this pin to the cathode of the WLED string. Current through the SINK1 pin equals current through the ISINK2 pin. If only one WLED string is used, short the ISINK1 and ISINK2 pins together. |
| ISINK2 | 33 | I | Input to the WLED current SINK2. Connect this pin to the cathode of the WLED string. Current through the SINK1 pin equals current through the ISINK2 pin. If only one WLED string is used, short the ISINK1 and ISINK2 pins together. |
| L1 | 20 | 0 | Switch pin for DCDC1. Connect this pin to the respective inductor. |
| L2 | 23 | O | Switch pin for DCDC2. Connect this pin to the respective inductor. |
| L3 | 31 | 0 | Switch pin for DCDC3. Connect this pin to the respective inductor. |
| L4 | 37 | O | Switch pin of the WLED boost converter. Connected this pin to the respective inductor. |
| LDO_PGOOD | 46 | O | Power-good signal for the LDO regulator (LDO1 and LDO2 only). This pin is a push-pull output. This pin is pulled low when either the LDO1 or LDO2 regulator is out of regulation. |
| LS1_IN | 39 | 1 | Input voltage pin for load switch 1 (LS1) or LDO3 |
| LS1_OUT | 40 | O | Output voltage pin for load switch 1 (LS1) or LDO3 |
| LS2_IN | 42 | 1 | Input voltage pin for load switch 2 (LS2) or LDO4 |
| LS2_OUT | 43 | O | Output voltage pin for load switch 2 (LS2) or LDO4 |
| MUX_IN | 14 | O | Input to analog multiplexer |
| MUX_OUT | 16 | O | Output pin of analog multiplexer |
| NC | 15, 17 |  | Not used |
| nINT | 45 | O | Interrupt output. This pin is an active-low, open-drain output. This pin is pulled low if an interrupt bit is set. The output goes high after the bit causing the interrupt in the INT register is read. The interrupt sources can be masked in the INT register, such that no interrupt is generated when the corresponding interrupt bit is set. |
| nRESET | 44 | 1 | Reset pin. This pin is an active-low input. Pulling this pin low causes the PMIC to shut down. When this pin returns to a high voltage level, the PMIC powers up in its default state after a 1-s delay. |
| nWAKEUP | 13 | O | Signal to the host to indicate a power-on event. This pin is an active-low, open-drain output. |
| PB_IN | 25 | I | Push-button monitor input. This pin is typically connected to a momentary switch to ground. This pin is an active-low input. |
| PGND | 30 |  | Power ground. Connect this pin to the ground plane. |
| PGOOD | 26 | O | Power-good output. This pin is a push-pull output. This pin is pulled low when any of the power rails are out of regulation. |
| PWR_EN | 9 | I | Enable input for the DCDC1, DCDC2, and DCDC3 converters, and the LDO1, LDO2, LDO3, and LDO4 regulators. Pull this pin high to start the power-up sequence. |
| SCL | 28 | 1 | Clock input for the $\mathrm{I}^{2} \mathrm{C}$ interface |
| SDA | 27 | I/O | Data line for the $\mathrm{I}^{2} \mathrm{C}$ interface |
| SYS | 7, 8 | O | System voltage pin and output of the power path. All voltage regulators are typically powered from this output. |
| TS | 11 | 1 | Temperature sense input. Connect this pin to the NTC thermistor to sense the battery temperature. This pin works with $10-\mathrm{k} \Omega$ and $100-\mathrm{k} \Omega$ thermistors. For more information, see the Battery-Pack Temperature Monitoring section. |
| USB | 12 | I | USB voltage input to power path. Connect this pin to an external voltage from a USB port. |
| VDCDC1 | 19 | I | DCDC1 output and feedback voltage-sense input |
| VDCDC2 | 24 | 1 | DCDC2 output and feedback voltage-sense input |
| VDCDC3 | 29 | I | DCDC3 output and feedback voltage-sense input |
| VINLDO | 2 | I | Input voltage for LDO1 and LDO2 |
| VIN_DCDC1 | 21 | I | Input voltage for DCDC1. This pin must be connected to the SYS pin. |
| VIN_DCDC2 | 22 | I | Input voltage for DCDC2. This pin must be connected to the SYS pin. |
| VIN_DCDC3 | 32 | 1 | Input voltage for DCDC3. This pin must be connected to the SYS pin. |
| VIO | 18 | 1 | Output-high supply for output buffers |
| VLDO1 | 3 | O | Output voltage of LDO1 |

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## Pin Functions (continued)

| PIN |  | I/O |  |
| :--- | :---: | :---: | :--- |
| NAME | NO. |  |  |
| VLDO2 | 1 | O | Output voltage of LDO2 |
| Thermal pad |  | - | Power-ground connection for the PMIC. Connect the thermal pad to the ground plane. |

## 7 Specifications

### 7.1 Absolute Maximum Ratings

over operating ambient temperature range (unless otherwise noted) ${ }^{(1)(2)}$

|  |  |  | MIN | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | BAT | -0.3 | 7 |  |
|  | Supply voltage (with respect to | USB, AC | -0.3 | 20 | V |
|  |  | All pins unless specified separately | -0.3 | 7 |  |
|  | Input/output voltage (with respect to PGND) | ISINK | -0.3 | 20 | V |
|  |  | L4, FB_WLED | -0.3 | 44 |  |
|  | Absolute voltage difference between S | and any VIN_DCDCx pin or SYS and VINLDO | 0.3 | 0.3 | V |
|  | Terminal current | SYS, USB, BAT | 3000 | 3000 | mA |
|  | Source or Sink current | PGOOD, LDO_PGOOD | 6 | 6 | mA |
|  | Sink current | nWAKEUP, nINT | 2 | 2 | mA |
|  | Operating junction temperature |  | 125 | 125 | ${ }^{\circ} \mathrm{C}$ |
|  | Operating ambient temperature |  | -40 | 105 | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{T}_{\text {stg }}$ | Storage temperature |  | -65 | 150 | ${ }^{\circ} \mathrm{C}$ |

(1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
(2) All voltage values are with respect to network ground terminal.

### 7.2 ESD Ratings

|  |  |  | VALUE | UNIT |
| :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {(ESD) }}$ | Electrostatic discharge | Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 ${ }^{(1)}$ | $\pm 2000$ | V |
|  |  | Charged-device model (CDM), per JEDEC specification JESD22-C101 ${ }^{(2)}$ | $\pm 500$ |  |

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 7.3 Recommended Operating Conditions

over operating ambient temperature range (unless otherwise noted)

|  | MIN | NOM |
| :--- | ---: | ---: |
| Supply voltage, USB, AC | 4.3 | MAX |
| UNIT |  |  |
| Supply voltage, BAT | 2.75 | 5.8 |
| Input current from AC |  | 5.5 |
| Input current from USB |  | V |
| Battery current |  | 2.5 |
| Input voltage range for DCDC1, DCDC2, and DCDC3 | 2.7 | 1.3 |
| Input voltage range for LDO1, LDO2 | 1.8 | A |
| Input voltage range for LS1 or LDO3, LS2, or LDO4 configured as LDOs | 2.7 | A |
| Input voltage range for LS1 or LDO3, LS2, or LDO4 configured as load switches | 1.8 | 5.8 |
| Output voltage range for LDO1 | 1 | V |
| Output voltage range for LDO2 | 0.9 | V |
| Output voltage range for LS1 or LDO3, LS2, or LDO4 | 1.8 | 5.8 |

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## Recommended Operating Conditions (continued)

over operating ambient temperature range (unless otherwise noted)

|  |  | MIN | NOM | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Output current DCDC1 |  | 0 |  | 1.2 | A |
| Output current DCDC2 |  | 0 |  | 1.2 | A |
| Output current DCDC3 |  | 0 |  | 1.2 | A |
| Output current LDO1, LDO2 |  | 0 |  | 100 | mA |
| Output current LS1 or LDO3, LS2, or LDO4 configured as LDOs | TPS65217A | 0 |  | 200 | mA |
|  | TPS65217B | 0 |  | 200 |  |
|  | TPS65217C | 0 |  | 400 |  |
|  | TPS65217D | 0 |  | 400 |  |
| Output current LS1 or LDO, LS2 or LDO4 configured as load switches |  | 0 |  | 200 | mA |

### 7.4 Thermal Information

| THERMAL METRIC ${ }^{(1)}$ |  | $\begin{gathered} \text { TPS65217 } \\ \hline \text { RSL (VQFN) } \end{gathered}$ | UNIT |
| :---: | :---: | :---: | :---: |
|  |  |  |  |
|  |  | 48 PINS |  |
| $\mathrm{R}_{\theta \mathrm{JA}}$ | Junction-to-ambient thermal resistance | 30.4 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |
| $\mathrm{R}_{\theta \mathrm{JC} \text { (top) }}$ | Junction-to-case (top) thermal resistance | 16.4 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |
| $\mathrm{R}_{\theta \mathrm{JB}}$ | Junction-to-board thermal resistance | 5.6 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |
| \%JT | Junction-to-top characterization parameter | 0.2 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |
| $\psi_{\text {JB }}$ | Junction-to-board characterization parameter | 5.6 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |
| $\mathrm{R}_{\text {өJC(bot) }}$ | Junction-to-case (bottom) thermal resistance | 1.3 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.

### 7.5 Electrical Characteristics

$\mathrm{V}_{\mathrm{BAT}}=3.6 \mathrm{~V} \pm 5 \%, \mathrm{~T}_{\mathrm{J}}=27^{\circ} \mathrm{C}$ (unless otherwise noted)

|  | PARAMETER | TEST CONDITIONS |  | MIN | TYP | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| INPUT VOLTAGE AND CURRENTS |  |  |  |  |  |  |  |
| $\mathrm{V}_{\text {BAT }}$ | Battery input voltage range | USB or AC supply connected |  | 0 |  | 5.5 | V |
|  |  | USB and AC not connected |  | 2.75 |  | 5.5 |  |
| $\mathrm{V}_{\text {AC }}$ | AC adapter input voltage range | Valid range for charging |  | 4.3 |  | 5.8 | V |
| $V_{\text {USB }}$ | USB input voltage range | Valid range for charging |  | 4.3 |  | 5.8 | V |
| $\mathrm{V}_{\text {UVLO }}$ | Undervoltage lockout | Measured in respect to $V_{\text {BAT }}$; supply falling;$\mathrm{V}_{\mathrm{AC}}=\mathrm{V}_{\mathrm{USB}}=0 \mathrm{~V}$ | UVLO[1:0] = 00b |  | 2.73 |  | V |
|  |  |  | UVLO[1:0] = 01b |  | 2.89 |  |  |
|  |  |  | UVLO[1:0] = 10b |  | 3.18 |  |  |
|  |  |  | UVLO[1:0] = 11b |  | 3.3 |  |  |
|  | UVLO accuracy |  |  | -2\% |  | 2\% |  |
|  | UVLO deglitch time ${ }^{(1)}$ |  |  | 4 |  | 6 | ms |
| $\mathrm{V}_{\text {OFFSET }}$ | AC and USB UVLO offset | $\mathrm{V}_{\mathrm{BAT}}<\mathrm{V}_{\text {UVLO }}$; Device shuts down when $\mathrm{V}_{\mathrm{AC}}$, <br> $\mathrm{V}_{\text {USB }}$ drop below $\mathrm{V}_{\text {UVLO }}+\mathrm{V}_{\text {OFFSET }}$ |  |  | 200 |  | mV |
| Ioff | OFF current, <br> Total current into VSYS, VINDCDCx, VINLDO | All rails disabled, $\mathrm{T}_{\mathrm{A}}=27^{\circ} \mathrm{C}$ |  |  | 6 |  | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\text {SLEEP }}$ | Sleep current, <br> Total current into VSYS, VINDCDCx, VINLDO | LDO1 and LDO2 enabled, no load. All other rails disabled.$\mathrm{V}_{\mathrm{SYS}}=4 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=0.105^{\circ} \mathrm{C}$ |  |  | 80 | 106 | $\mu \mathrm{A}$ |

[^0]
## Electrical Characteristics (continued)

$\mathrm{V}_{\mathrm{BAT}}=3.6 \mathrm{~V} \pm 5 \%, \mathrm{~T}_{\mathrm{J}}=27^{\circ} \mathrm{C}$ (unless otherwise noted)

|  | PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\mathrm{IN}(\mathrm{DT})}$ | AC and USB voltage-detection threshold | $\begin{aligned} & V_{\text {BAT }}>V_{\text {UVLO }}, A C \text { and USB valid when } V_{A C-} \\ & \text { USB }-V_{B A T}>V_{I N(D T)} \end{aligned}$ | 190 |  |  | mV |
|  |  | $\mathrm{V}_{\text {BAT }}<\mathrm{V}_{\text {UVLO }}, \mathrm{AC}$ and USB valid when $\mathrm{V}_{\text {AC-USB }}$ $>\mathrm{V}_{\text {IN(DT) }}$ | 4.3 |  |  | V |
| $\mathrm{V}_{\text {IN(NDT }}$ | AC and USB voltage-removal detection threshold | $\mathrm{V}_{\text {BAT }}>\mathrm{V}_{\text {UVLO }}, \mathrm{AC}$ and USB invalid when $\mathrm{V}_{\mathrm{AC} / \mathrm{USB}}-\mathrm{V}_{\mathrm{BAT}}<\mathrm{V}_{\mathrm{IN}(\mathrm{DT})}$ |  |  | 125 | mV |
|  |  | $\mathrm{V}_{\mathrm{BAT}}<\mathrm{V}_{\mathrm{UVLO}}$, AC and USB invalid when $\mathrm{V}_{\mathrm{AC}}$ USB < $\mathrm{V}_{\text {IN(DT) }}$ |  | $\mathrm{V}_{\text {UVLO }}+$ <br> VOFFSET |  | V |
| $\mathrm{t}_{\text {RISE }}$ | $\mathrm{V}_{\mathrm{AC}}, \mathrm{V}_{\text {USB }}$ rise time | Voltage rising from 100 mV to 4.5 V . If rise time is exceeded, device may not power up. |  |  | 50 | ms |
| $\mathrm{t}_{\mathrm{DG}(\mathrm{DT})}$ | Power detected deglitch ${ }^{(1)}$ | AC or USB voltage increasing |  | 22.5 |  | ms |
| $\mathrm{V}_{\text {IN(OVP }}$ | Input overvoltage detection threshold | USB and AC input | 5.8 | 6 | 6.4 | V |
| POWER PATH TIMING |  |  |  |  |  |  |
| $\mathrm{t}_{\text {SW(PSEL) }}$ | Switching from AC to USB ${ }^{(1)}$ |  |  |  | 150 | $\mu \mathrm{s}$ |
| POWER PATH MOSFET CHARACTERISTICS |  |  |  |  |  |  |
| $\mathrm{V}_{\mathrm{DO}, \mathrm{AC}}$ | AC input switch dropout voltage | $\mathrm{IAC}[1: 0]=11 \mathrm{~b}(2.5 \mathrm{~A}), \mathrm{I}$ SYS $=1 \mathrm{~A}$ |  | 150 |  | mV |
| $\mathrm{V}_{\text {DO, USB }}$ | USB input switch dropout voltage | IUSB[1:0] = 01b ( 500 mA ), $\mathrm{I}_{\text {SYS }}=500 \mathrm{~mA}$ |  | 100 |  | mV |
|  |  | IUSB[1:0] = 10b (1300 mA), $\mathrm{I}_{\mathrm{SYS}}=800 \mathrm{~mA}$ |  | 160 |  |  |
| $\mathrm{V}_{\text {DO, BAT }}$ | Battery switch dropout voltage | $\mathrm{V}_{\mathrm{BAT}}=3 \mathrm{~V}, \mathrm{I}_{\mathrm{BAT}}=1 \mathrm{~A}$ |  | 60 |  | mV |
| POWER PATH INPUT CURRENT LIMITS |  |  |  |  |  |  |
| $\mathrm{I}_{\text {ACLMT }}$ | Input current limit; AC pin | IAC[1:0] = 00b | 90 |  | 130 | mA |
|  |  | IAC[1:0] = 01b | 480 |  | 580 |  |
|  |  | IAC[1:0] = 10b | 1000 | 1500 |  |  |
|  |  | IAC [1:0] = 11b | 2000 | 2500 |  |  |
| IUSBLMT | Input current limit; USB pin | IUSB[1:0] = 00b | 90 |  | 100 | mA |
|  |  | IUSB[1:0] = 01b | 460 |  | 500 |  |
|  |  | IUSB[1:0] = 10b | 1000 | 1300 |  |  |
|  |  | IUSB[1:0] = 11b | 1500 | 1800 |  |  |
| $\mathrm{I}_{\text {BAT }}$ | Battery load current ${ }^{(1)}$ |  |  |  | 2 | A |

POWER PATH BATTERY SUPPLEMENT DETECTION

| $V_{\text {BSUP }}$ | Battery supplement threshold | $\mathrm{V}_{\text {SYS }} \leq \mathrm{V}_{\mathrm{BAT}}-$ VBSUP1, <br> $\mathrm{V}_{\text {SYS }}$ falling IUSB[1:0] $=10 \mathrm{~b}$ | 40 |  |  | mV |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Battery supplement hysteresis | $\mathrm{V}_{\text {SYS }}$ rising |  | 20 |  |  |
| POWER PATH BATTERY PROTECTION |  |  |  |  |  |  |
| $\mathrm{V}_{\mathrm{BAT}(\mathrm{SC})}$ | BAT pin short-circuit detection threshold |  | 1.3 | 1.5 | 1.7 | V |
| $\mathrm{I}_{\text {BAT(SC) }}$ | Source current for BAT pin short-circuit detection |  |  | 7.5 |  | mA |
| INPUT BASED DYNAMIC POWER PATH MANAGEMENT (DPPM) |  |  |  |  |  |  |
| $V_{\text {DPPM }}$ | Threshold at which DPPM loop is enabled | $\mathrm{I}^{2} \mathrm{C}$ selectable | 3.5 |  | 4.25 | V |
| BATTERY CHARGER |  |  |  |  |  |  |
| $V_{\text {OREG }}$ | Battery charger voltage | $\mathrm{I}^{2} \mathrm{C}$ selectable | 4.1 |  | 4.25 | V |
|  | Battery charger accuracy |  | -2\% |  | 1\% |  |
| V Lowv | Precharge to fast-charge transition threshold | VPRECHG $=0 \mathrm{~b}$ |  | 2.9 |  | V |
|  |  | VPRECHG $=1 \mathrm{~b}$ |  | 2.5 |  |  |
| t DGL1(LOWV) | Deglitch time on precharge to fast-charge transition ${ }^{(1)}$ |  |  | 25 |  | ms |
| t ${ }_{\text {DGL2(LOWV) }}$ | Deglitch time on fast-charge to precharge transition ${ }^{(1)}$ |  |  | 25 |  | ms |
| $\mathrm{I}_{\text {CHG }}$ | Battery fast charge current range$\mathrm{V}_{\text {OREG }}>\mathrm{V}_{\text {BAT }}>\mathrm{V}_{\text {LOWV }}$$\mathrm{V}_{\mathrm{IN}}=\mathrm{V}_{\text {USB }}=5 \mathrm{~V}$ | ICHRG[1:0] = 00b |  | 300 |  | mA |
|  |  | ICHRG[1:0] = 01b |  | 400 |  |  |
|  |  | ICHRG[1:0] = 10b | 450 | 500 | 550 |  |
|  |  | ICHRG[1:0] = 11b |  | 700 |  |  |

## Electrical Characteristics (continued)

$\mathrm{V}_{\mathrm{BAT}}=3.6 \mathrm{~V} \pm 5 \%, \mathrm{~T}_{\mathrm{J}}=27^{\circ} \mathrm{C}$ (unless otherwise noted)

|  | PARAMETER | TEST CONDITIONS |  | MIN | TYP | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| IPRECHG | Precharge current | ICHRG[1:0] = 00b |  | 30 |  |  | mA |
|  |  | ICHRG[1:0] = 01b |  | 40 |  |  |  |
|  |  | ICHRG[1:0] = 10b |  | 25 | 50 | 75 |  |
|  |  | ICHRG[1:0] = 11b |  |  | 70 |  |  |
| $\mathrm{I}_{\text {TERM }}$ | Charge current value for termination detection threshold (fraction of $\mathrm{I}_{\mathrm{CHG}}$ ) | TERMIF[1:0] = 00b |  |  | 2.5\% |  |  |
|  |  | TERMIF[1:0] = 01b |  | 3\% | 7.5\% | 10\% |  |
|  |  | TERMIF[1:0] = 10b |  |  | 15\% |  |  |
|  |  | TERMIF[1:0] = 11b |  | 18\% |  |  |  |
| $\mathrm{t}_{\text {DGL(TERM) }}$ | Deglitch time, termination detected ${ }^{(1)}$ |  |  | 125 |  |  | ms |
| $\mathrm{V}_{\text {RCH }}$ | Recharge detection threshold | Voltage below $\mathrm{V}_{\text {OREG }}$ |  | 150 | 100 | 70 | mV |
| $\mathrm{t}_{\text {DGL(RCH) }}$ | Deglitch time, recharge threshold detected ${ }^{(1)}$ |  |  |  | 125 |  | ms |
| $\mathrm{I}_{\text {BAT(DET) }}$ | Sink current for battery detection | $\mathrm{T}_{\mathrm{J}}=27^{\circ} \mathrm{C}$ |  | 3 | 7.5 | 10 | mA |
| $t_{\text {det }}$ | Battery detection timer. $I_{\mathrm{BAT}(\mathrm{DET})}$ is pulled from the battery for $t_{\text {DET }}$. If BAT voltage stays above $\mathrm{V}_{\text {RCH }}$ threshold the battery is connected. ${ }^{(1)}$ | $\mathrm{V}_{\text {BAT }}<\mathrm{V}_{\text {RCH; }}$ |  |  | 250 |  | ms |
| $\mathrm{t}_{\text {CHG }}$ | Charge safety timer ${ }^{(1)}$ | Safety timer range, thermal and DPPM not active, selectable by $\mathrm{I}^{2} \mathrm{C}$ |  | 4 |  | 8 | h |
| trrechg | Precharge timer ${ }^{(1)}$ | Pre charge timer, thermal and DPPM loops not active, selectable by $\mathrm{I}^{2} \mathrm{C}$ | PCHRGT $=0 \mathrm{~b}$ |  | 30 | 60 | min |
|  |  |  | PCHRGT = 1b |  | 60 |  |  |

## BATTERY NTC MONITOR


(2) Contact factory for 3.3-V option.

## Electrical Characteristics (continued)

$\mathrm{V}_{\text {BAT }}=3.6 \mathrm{~V} \pm 5 \%, \mathrm{~T}_{\mathrm{J}}=27^{\circ} \mathrm{C}$ (unless otherwise noted)

| PARAMETER |  | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{r}_{\text {DS(on) }}$ | High-side MOSFET on-resistance | $\mathrm{V}_{\mathrm{IN}}=2.7 \mathrm{~V}$ |  | 170 |  | $\mathrm{m} \Omega$ |
|  | Low-side MOSFET on-resistance | $\mathrm{V}_{\mathrm{IN}}=2.7 \mathrm{~V}$ |  | 120 |  |  |
| $\mathrm{I}_{\text {LEAK }}$ | High-side MOSFET leakage current | $\mathrm{V}_{\mathrm{IN}}=5.8 \mathrm{~V}$ |  |  | 2 | $\mu \mathrm{A}$ |
|  | Low-side MOSFET leakage current | $\mathrm{V}_{\mathrm{DS}}=5.8 \mathrm{~V}$ |  |  | 1 |  |
| Ilimit | Current limit (high- and low-side MOSFET). | $2.7 \mathrm{~V}<\mathrm{V}_{\text {IN }}<5.8 \mathrm{~V}$ |  | 1.6 |  | A |
| $\mathrm{f}_{\text {SW }}$ | Switching frequency |  | 1.95 | 2.25 | 2.55 | MHz |
| $\mathrm{V}_{\mathrm{FB}}$ | Feedback voltage | XADJ $=1 \mathrm{~b}$ |  | 600 |  | mV |
| $\mathrm{t}_{\text {ss }}$ | Soft-start time | Time to ramp $\mathrm{V}_{\text {OUT }}$ from $5 \%$ to $95 \%$, no load |  | 750 |  | $\mu \mathrm{s}$ |
| $\mathrm{R}_{\text {DIS }}$ | Internal discharge resistor at L1 ${ }^{(3)}$ |  |  | 250 |  | $\Omega$ |
| L | Inductor |  | 1.5 | 2.2 |  | $\mu \mathrm{H}$ |
| Cout | Output capacitor | Ceramic | 10 | 22 |  | $\mu \mathrm{F}$ |
|  | ESR of output capacitor |  |  | 20 |  | $\mathrm{m} \Omega$ |

## DCDC2 (BUCK)

| $\mathrm{V}_{\text {IN }}$ | Input voltage range | VIN_DCDC2 pin | 2.7 | $\mathrm{V}_{\text {SYS }}$ | V |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{I}_{\mathrm{Q}, \mathrm{SLEEP}}$ | Quiescent current in SLEEP mode | No load, $\mathrm{V}_{\text {SYS }}=4 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ | 30 |  | $\mu \mathrm{A}$ |
|  | Output voltage range | External resistor divider (XADJ2 $=1 \mathrm{~b}$ ) | 0.6 | VIN | V |
|  |  | $1^{2} \mathrm{C}$ selectable in $25-\mathrm{mV}$ steps |  |  |  |



## DCDC3 (BUCK)

| $\mathrm{V}_{\mathrm{IN}}$ | Input voltage range | VIN_DCDC3 pin | 2.7 | $\mathrm{V}_{\text {SYS }}$ | V |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{I}_{\mathrm{Q}, \text { SLEEP }}$ | Quiescent current in SLEEP mode | No load, $\mathrm{V}_{\text {SYS }}=4 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ | 30 |  | $\mu \mathrm{A}$ |
| $\mathrm{V}_{\text {OUT }}$ | Output voltage range | External resistor divider (XADJ3 = 1b) | 0.6 | $\mathrm{V}_{\text {IN }}$ | V |
|  |  | $1^{2} \mathrm{C}$ selectable in $25-\mathrm{mV}$ steps (XADJ3 = 0b) | 0.9 | $1.5{ }^{(2)}$ |  |
|  | DC output voltage accuracy | $\begin{aligned} & \mathrm{V}_{\text {IN }}=\mathrm{V}_{\text {OUT }}+0.3 \mathrm{~V} \text { to } 5.8 \mathrm{~V} ; \\ & 0 \mathrm{~mA} \leq \mathrm{I}_{\text {OUT }} \leq 1.2 \mathrm{~A} \end{aligned}$ | -2\% | 3\% |  |
|  | Power save mode (PSM) ripple voltage | $\mathrm{I}_{\text {OUT }}=1 \mathrm{~mA}$, PFM mode $\mathrm{L}=2.2 \mu \mathrm{H}, \mathrm{C}_{\text {OUT }}=20 \mu \mathrm{~F}$ | 40 |  | $m \mathrm{~V}_{\mathrm{pp}}$ |
| Iout | Output current range |  | 0 | 1.2 | A |
| $\mathrm{r}_{\text {DS(on) }}$ | High-side MOSFET on-resistance | $\mathrm{V}_{\mathrm{IN}}=2.7 \mathrm{~V}$ | 170 |  | $\mathrm{m} \Omega$ |
|  | Low side MOSFET on-resistance | $\mathrm{V}_{\mathrm{IN}}=2.7 \mathrm{~V}$ | 120 |  |  |

[^1]
## Electrical Characteristics (continued)

$\mathrm{V}_{\mathrm{BAT}}=3.6 \mathrm{~V} \pm 5 \%, \mathrm{~T}_{\mathrm{J}}=27^{\circ} \mathrm{C}$ (unless otherwise noted)


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## Electrical Characteristics (continued)

$\mathrm{V}_{\text {BAT }}=3.6 \mathrm{~V} \pm 5 \%, \mathrm{~T}_{\mathrm{J}}=27^{\circ} \mathrm{C}$ (unless otherwise noted)

| PARAMETER |  | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Cout | Output capacitor | Ceramic | 8 | 10 | 12 | $\mu \mathrm{F}$ |
|  | ESR of output capacitor |  |  | 20 |  | $\mathrm{m} \Omega$ |
| LS1 OR LDO3, AND LS2 OR LDO4, CONFIGURED AS LOAD SWITCHES |  |  |  |  |  |  |
| $\mathrm{V}_{\text {IN }}$ | Input voltage range | LS1_VIN, LS2_VIN pins | 1.8 |  | 5.8 | V |
| $\mathrm{R}_{\mathrm{DS}(\mathrm{ON})}$ | P-channel MOSFET on-resistance | $\mathrm{V}_{\mathrm{IN}}=1.8 \mathrm{~V}$, over full temperature range |  | 300 | 650 | $\mathrm{m} \Omega$ |
| $\mathrm{I}_{\text {SC }}$ | Short circuit current limit | Output shorted to GND | 200 | 280 |  | mA |
| $\mathrm{R}_{\mathrm{DIS}}$ | Internal discharge resistor at output |  |  | 375 |  | $\Omega$ |
| $\mathrm{C}_{\text {OUT }}$ | Output capacitor | Ceramic | 1 | 10 | 12 | $\mu \mathrm{F}$ |
|  | ESR of output capacitor |  |  | 20 |  | $\mathrm{m} \Omega$ |

## WLED BOOST

| $\mathrm{V}_{\text {IN }}$ | Input voltage range |  | 2.7 | 5.8 | V |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {OUT }}$ | Max output voltage | $\mathrm{I}_{\text {SINK }}=20 \mathrm{~mA}$ | 32 |  | V |
| $\mathrm{V}_{\text {OVP }}$ | Output overvoltage protection |  | $37 \quad 38$ | 39 | V |
| $\mathrm{R}_{\mathrm{DS}(\mathrm{ON})}$ | N-channel MOSFET on-resistance | $\mathrm{V}_{\mathrm{IN}}=3.6 \mathrm{~V}$ | 0.6 |  | $\Omega$ |
| $\mathrm{I}_{\text {LEAK }}$ | N -channel leakage current | $\mathrm{V}_{\mathrm{DS}}=25 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ | 2 |  | $\mu \mathrm{A}$ |
| limit | N-channel MOSFET current limit |  | 1.6 | 1.9 | A |
| $\mathrm{f}_{\text {SW }}$ | Switching frequency |  | 1.125 |  | MHz |
| IINRUSH | Inrush current on start-up | $\mathrm{V}_{\mathrm{IN}}=3.6 \mathrm{~V}, 1 \%$ duty cycle setting | 1.1 |  | A |
|  |  | $\mathrm{V}_{\mathrm{IN}}=3.6 \mathrm{~V}, 100 \%$ duty cycle setting | 2.1 |  |  |
| L | Inductor |  | 18 |  | $\mu \mathrm{H}$ |
| $\mathrm{C}_{\text {OUT }}$ | Output capacitor | Ceramic | 4.7 |  | $\mu \mathrm{F}$ |
|  | ESR of output capacitor |  | 20 |  | $\mathrm{m} \Omega$ |

## WLED CURRENT SINK1, SINK2

| $\mathrm{V}_{\text {SINK } 1,2}$ | Overvoltage protection threshold at ISINK1, ISINK2 pins |  |  | 19 | V |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\mathrm{DO}, \mathrm{SINK} 1,2}$ | Current sink drop-out voltage | Measured from ISINK to GND | 400 |  | mV |
| $\mathrm{V}_{\text {ISET } 1,2}$ | ISET1, ISET2 pin voltage |  | 1.24 |  | V |
| $\mathrm{I}_{\text {SINK1,2 }}$ | WLED current range (ISINK1, ISINK2) |  | 1 | 25 | mA |
|  | WLED sink current | $\mathrm{R}_{\text {ISET }}=130.0 \mathrm{k} \Omega$ | 10 |  |  |
|  |  | $\mathrm{R}_{\text {ISET }}=86.6 \mathrm{k} \Omega$ | 15 |  |  |
|  |  | $\mathrm{R}_{\text {ISET }}=64.9 \mathrm{k} \Omega$ | 20 |  |  |
|  |  | $\mathrm{R}_{\text {ISET }}=52.3 \mathrm{k} \Omega$ | 25 |  |  |
|  | DC current set accuracy | $\mathrm{I}_{\text {SINK }}=5 \mathrm{~mA}$ to $25 \mathrm{~mA}, 100 \%$ duty cycle | -5\% | 5\% |  |
|  | DC current matching | $\begin{aligned} & \mathrm{R}_{\mathrm{SET} 1}=52.3 \mathrm{k} \Omega, \mathrm{I}_{\text {SINK }}=25 \mathrm{~mA}, \\ & \mathrm{~V}_{\mathrm{BAT}}=3.6 \mathrm{~V}, 100 \% \text { duty cycle } \end{aligned}$ | -5\% | 5\% |  |
|  |  | $\begin{aligned} & R_{\text {SET } 1}=130 \mathrm{k} \Omega, \mathrm{I}_{\text {SINK }}=10 \mathrm{~mA}, \\ & \mathrm{~V}_{\mathrm{BAT}}=3.6 \mathrm{~V}, 100 \% \text { duty cycle } \end{aligned}$ | -5\% | 5\% |  |
| $\mathrm{f}_{\text {PWM }}$ | PWM dimming frequency | FDIM[1:0] $=00 \mathrm{~b}$ | 100 |  | Hz |
|  |  | FDIM[1:0] = 01b | 200 |  |  |
|  |  | FDIM [1:0] = 10b | 500 |  |  |
|  |  | FDIM[1:0] = 11b | 1000 |  |  |

## ANALOG MULTIPLEXER

| g | Gain, VBAT (VBAT $/ \mathrm{V}_{\text {OUt,MuX }}$ ); VSYS ( $\left.\mathrm{V}_{\text {SYS }} / \mathrm{V}_{\text {OUt,MUX }}\right)$ |  | 3 | V/V |
| :---: | :---: | :---: | :---: | :---: |
|  | Gain, VTS (V $\mathrm{V}_{\text {TS }} / \mathrm{V}_{\text {OUT,MUX }}$ ); MUX_IN ( $\mathrm{V}_{\text {MUX_IN }} / \mathrm{V}_{\text {MUX_OUT }}$ ) |  | 1 |  |
|  | Gain, Vicharge (Vout,mux / Vicharge) | ICHRG[1:0] = 00b | 7.575 | V/A |
|  |  | ICHRG[1:0] = 01b | 5.625 |  |
|  |  | ICHRG[1:0] = 10b | 4.5 |  |
|  |  | ICHRG[1:0] = 11b | 3.214 |  |
| $\mathrm{V}_{\text {OUT }}$ | Buffer headroom ( $\mathrm{V}_{\text {SYS }}-\mathrm{V}_{\text {MUX_OUT }}$ ) | $\begin{aligned} & \mathrm{V}_{\text {SYS }}=3.6 \mathrm{~V}, \text { MUX[2:0] }=101 \mathrm{~b} \\ & \left(\mathrm{~V}_{\text {MUX_IN }}-\mathrm{V}_{\text {MUX_OUT }}\right) / \mathrm{V}_{\text {MUX_IN }}>1 \% \end{aligned}$ | 0.7 | V |

## Electrical Characteristics (continued)

$\mathrm{V}_{\text {BAT }}=3.6 \mathrm{~V} \pm 5 \%, \mathrm{~T}_{\mathrm{J}}=27^{\circ} \mathrm{C}$ (unless otherwise noted)

|  | PARAMETER | TEST CONDITIONS | MIN | TYP |
| :--- | :--- | :--- | :---: | :---: |
| $\mathrm{R}_{\text {OUT }}$ | Output Impedance |  | MAX | UNIT |
| $\mathrm{I}_{\text {LEAK }}$ | Leakage current | MUX[2:0] $=000 \mathrm{~b}(\mathrm{HiZ}), \mathrm{V}_{\text {MUX }}=2.25 \mathrm{~V}$ |  |  |

LOGIC LEVELS AND TIMING CHARACTERISTICS
(SCL, SDA, PB_IN, PGOOD, LDO_PGOOD, PWR_EN, nINT, nWAKEUP, nRESET)

| $\mathrm{P}_{\text {GTH }}$ | PGOOD comparator treshold, All DC/DC converters and LDOs ${ }^{(1)}$ | Output voltage falling, \% of set voltage |  | 90\% |  | ms |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Output voltage rising, \% of set voltage |  | 95\% |  |  |
| $\mathrm{P}_{\mathrm{GDG}}$ | PGOOD deglitch time | Output voltage falling, DCDC1, DCDC2, DCDC3 | 2 |  | 4 |  |
|  |  | Output voltage falling, LDO1, LDO2, LDO3, LDO4 | 1 |  | 2 |  |
| $\mathrm{P}_{\text {GLLY }}$ | PGOOD delay time | PGDLY[1:0] = 00b |  | 20 |  | ms |
|  |  | PGDLY[1:0] = 01b |  | 100 |  |  |
|  |  | PGDLY[1:0] = 10b |  | 200 |  |  |
|  |  | PGDLY[1:0] = 11b |  | 400 |  |  |
| $\mathrm{t}_{\text {HRST }}$ | PB-IN hard-reset-detect time ${ }^{(1)}$ |  |  | 8 |  | s |
| $t_{\text {DG }}$ | PB_IN pin deglitch time ${ }^{(1)}$ |  |  | 50 |  | ms |
|  | PWR_EN pin deglitch time ${ }^{(1)}$ |  |  | 50 |  |  |
|  | nRESET pin deglitch time ${ }^{(1)}$ |  |  | 30 |  |  |
| $\mathrm{R}_{\text {PULLUP }}$ | PB_IN internal pullup resistor |  |  | 100 |  | k $\Omega$ |
|  | nRESET internal pullup resistor |  |  | 100 |  |  |
| $\mathrm{V}_{\mathrm{IH}}$ | High-level input voltage PB_IN, SCL, SDA, PWR_EN, nRESET |  | 1.2 |  | $\mathrm{V}_{\text {IN }}$ | V |
| $\mathrm{V}_{\text {IL }}$ | Low-level input voltage PB_IN, SCL, SDA, PWR_EN, nRESET |  | 0 |  | 0.4 | V |
| $\mathrm{I}_{\text {BIAS }}$ | Input bias current PB_IN, SCL, SDA |  |  | 0.01 | 1 | $\mu \mathrm{A}$ |
| $\mathrm{V}_{\mathrm{OL}}$ | Output low voltage | nINT, nWAKEUP, $\mathrm{I}_{0}=1 \mathrm{~mA}$ |  |  | 0.3 | V |
|  |  | PGOOD, LDO_PGOOD, $\mathrm{I}_{\mathrm{O}}=1 \mathrm{~mA}$ |  |  | 0.3 |  |
| $\mathrm{V}_{\mathrm{OH}}$ | Output high voltage | PGOOD, LDO_PGOOD, $\mathrm{I}_{\mathrm{O}}=1 \mathrm{~mA}$ | $\mathrm{V}_{10}-0.3$ |  |  | V |
| $\mathrm{l}_{\text {LEAK }}$ | Pin leakage current nINT, nWAKEUP | Pin pulled up to 3.3-V supply |  |  | 0.2 | $\mu \mathrm{A}$ |
|  | $\mathrm{I}^{2} \mathrm{C}$ slave address |  |  | 0x24h |  |  |
| OSCILLATOR |  |  |  |  |  |  |
| fosc | Oscillator frequency |  |  | 9 |  | MHz |
|  | Oscillator frequency accuracy | $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $105^{\circ} \mathrm{C}$ | -10\% |  | 10\% |  |
| OVERTEMPERATURE SHUTDOWN |  |  |  |  |  |  |
| Tots | Overtemperature shutdown | Increasing junction temperature |  | 150 |  | ${ }^{\circ} \mathrm{C}$ |
|  | Hysteresis | Decreasing junction temperature |  | 20 |  | ${ }^{\circ} \mathrm{C}$ |

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## $7.6 I^{2} \mathrm{C}$ Timing Requirements

$\mathrm{V}_{\mathrm{BAT}}=3.6 \mathrm{~V} \pm 5 \%, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}, \mathrm{C}_{\mathrm{L}}=100 \mathrm{pF}$ (unless otherwise noted). For the $\mathrm{I}^{2} \mathrm{C}$ timing diagram, see Figure 1 .

|  |  |  | MIN | NOM MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{f}_{\mathrm{SCL}}$ | Serial clock frequency |  | 100 | 400 | kHz |
| $\mathrm{t}_{\text {HD } ; \text { STA }}$ | Hold time (repeated) START condition. After this period, the first clock pulse is generated | $\mathrm{SCL}=100 \mathrm{KHz}$ | 4 |  | $\mu \mathrm{s}$ |
|  |  | $\mathrm{SCL}=400 \mathrm{KHz}$ | 600 |  | ns |
| t LOW | LOW period of the SCL clock | SCL $=100 \mathrm{KHz}$ | 4.7 |  | $\mu \mathrm{s}$ |
|  |  | SCL $=400 \mathrm{KHz}$ | 1.3 |  |  |
| $\mathrm{t}_{\text {HIGH }}$ | HIGH period of the SCL clock | SCL $=100 \mathrm{KHz}$ | 4 |  | $\mu \mathrm{s}$ |
|  |  | $\mathrm{SCL}=400 \mathrm{KHz}$ | 600 |  | ns |
| $\mathrm{t}_{\text {SU }}$;STA | Set-up time for a repeated START condition | SCL $=100 \mathrm{KHz}$ | 4.7 |  | $\mu \mathrm{s}$ |
|  |  | $\mathrm{SCL}=400 \mathrm{KHz}$ | 600 |  | ns |
| $t_{\text {HD } ; \text { DAT }}$ | Data hold time | $\mathrm{SCL}=100 \mathrm{KHz}$ | 0 | 3.45 | $\mu \mathrm{s}$ |
|  |  | $\mathrm{SCL}=400 \mathrm{KHz}$ | 0 | 900 | ns |
| $t_{\text {SU }}$ DAT | Data set-up time | $\mathrm{SCL}=100 \mathrm{KHz}$ | 250 |  | ns |
|  |  | $\mathrm{SCL}=400 \mathrm{KHz}$ | 100 |  |  |
| $\mathrm{t}_{\mathrm{r}}$ | Rise time of both SDA and SCL signals | SCL $=100 \mathrm{KHz}$ |  | 1000 | ns |
|  |  | $\mathrm{SCL}=400 \mathrm{KHz}$ |  | 300 |  |
| $\mathrm{t}_{\mathrm{f}}$ | Fall time of both SDA and SCL signals | $\mathrm{SCL}=100 \mathrm{KHz}$ |  | 300 | ns |
|  |  | $\mathrm{SCL}=400 \mathrm{KHz}$ |  | 300 |  |
| tsu;STO | Set-up time for STOP condition | SCL $=100 \mathrm{KHz}$ | 4 |  | $\mu \mathrm{s}$ |
|  |  | $\mathrm{SCL}=400 \mathrm{KHz}$ | 600 |  | ns |
| $t_{\text {BUF }}$ | Bus free time between stop and start condition | $\mathrm{SCL}=100 \mathrm{KHz}$ | 4.7 |  | $\mu \mathrm{s}$ |
|  |  | $\mathrm{SCL}=400 \mathrm{KHz}$ | 1.3 |  |  |
| $\mathrm{t}_{\text {SP }}$ | Pulse duratoin of spikes which mst be suppressed by the input filter | SCL $=100 \mathrm{KHz}$ | NA | NA |  |
|  |  | $\mathrm{SCL}=400 \mathrm{KHz}$ | 0 | 50 | ns |
| $\mathrm{C}_{\mathrm{b}}$ | Capacitive load for each bus line | SCL $=100 \mathrm{KHz}$ |  | 400 | pF |
|  |  | $\mathrm{SCL}=400 \mathrm{KHz}$ |  | 400 |  |



Figure 1. $I^{2} C$ Data Transmission Timing

### 7.7 Typical Characteristics



Figure 2. TPS65217x DC/DC Efficiency, $5 \mathrm{~V}_{\mathrm{IN}}$ and an LQM2HPN2R2MGOL Inductor

## 8 Detailed Description

### 8.1 Overview

The TPS65217x device has three step-down converters, two low-dropout (LDO) regulators, two load switches, a linear battery charger, a white LED driver, and a power path. The system can be supplied by any combination of a USB port, $5-\mathrm{V}$ AC adaptor, or Li-ion battery. The device is characterized across a temperature range from $-40^{\circ} \mathrm{C}$ to $+105^{\circ} \mathrm{C}$, making it suitable for industrial applications where a $5-\mathrm{V}$ power supply rail is available. The device offers configurable power-up and power-down sequencing and several low-speed, system-level functions such as a power-good output, push-button monitor, hardware-reset function, and temperature sensor to protect the battery.
The $I^{2} \mathrm{C}$ interface has comprehensive features for using the TPS65217x device. All rails, load switches, and LDO regulators can be enabled or disabled. Power-up and power-down sequences, overtemperature thresholds, and overcurrent threshold can be programmed through the $1^{2} \mathrm{C}$ interface. The $I^{2} \mathrm{C}$ interface also monitors battery charging and controls LED dimming parameters.
The three $\mathrm{DC} / \mathrm{DC}$ step-down converters can each supply up to 1.2 A of current. The output voltages for each converter can be adjusted through the $I^{2} \mathrm{C}$ interface in real time to support processor clock frequency changes. All three converters feature dynamic voltage positioning to decrease voltage undershoots and overshoots. Typically, the converters work at a fixed-frequency of 2.25 MHz , pulse-width modulation (PWM) at moderate-toheavy load currents. At light load currents the converters automatically go to power save mode and operate in pulse-frequency modulation (PFM) for maximum efficiency across the widest possible range of load currents. For low-noise applications, each converter can be forced into fixed-frequency PWM using the $I^{2} \mathrm{C}$ interface. The stepdown converters allow the use of small inductors and capacitors to achieve a small solution size.
The device has two traditional LDO regulators: LDO1 and LDO2. The LDO1 and LDO2 regulators can support up to 100 mA each during normal operation, but in the SLEEP state they are limited to 1 mA to decrease quiescent current while supporting system-standby mode. The TPS65217A variant of the device also has two load switches: LS1 and LS2. For all other TPS65217x variants, these two outputs are configured as LDO regulators: LDO3 and LDO4. The LDO3 and LDO4 regulators can support up to 200 mA (TPS65217B), or 400 mA (TPS65217C and TPS65217D). All four LDO regulators have a wide input voltage range that allows them to be supplied either from one of the DC/DC converters or directly from the system voltage node.
The device has two power-good logic signals. The primary power-good signal, PGOOD, monitors the DCDC1, DCDC2, and DCDC3 converters, and LS1 (or LDO3) and LS2 (or LDO4) configurable power outputs. This signal is high in the ACTIVE state, but low in the SLEEP, RESET, and OFF states. The secondary power-good signal, LDO_PGOOD, monitors LDO1 and LDO2; the signal is high in the ACTIVE and SLEEP states, but low in the RESET and OFF states. The PGOOD and LDO_PGOOD signals are both pulled low when all the monitored rails are pulled low, or when one or more of the monitored rails are enabled and have encountered a fault, typically an output short or overcurrent condition.
The highly-efficient boost converter has two current sinks that can drive two strings of up to 10 LEDs at 25 mA each, or one string of 20 LEDs at 50 mA . An internal PWM signal and $\mathrm{I}^{2} \mathrm{C}$ control support brightness and dimming. Both current sources are controlled together and cannot operate independently.
The triple system power path lets simultaneous and independent powering of the system and battery charging through the linear battery charger for single-cell Li-ion and Li-Polymer batteries. The AC input is prioritized over USB input as the power source for charging the battery and powering the system. Both these sources are prioritized over the battery for powering the system to decrease the number of charge and discharge cycles on the battery.

### 8.2 Functional Block Diagram



### 8.3 Feature Description

### 8.3.1 Wake-Up and Power-Up Sequencing

The TPS65217x device has a predefined power-up-power-down sequence which, in a typical application, does not require changing. However, users can define custom sequences through $I^{2} \mathrm{C}$ control. The power-up sequence is defined by strobes and delay times. Each output rail is assigned to a strobe to determine the order in which the rails are enabled. The delay times from one strobe to the next are programmable in a range from 1 ms to 10 ms .

## NOTE

Although the user can modify the power-up and power-down sequence through the SEQx registers, those registers are reset to default values when the device goes to the SLEEP, OFF, or RESET state. In practice, this situation means that the power-up sequence is fixed and a custom power-down sequence must be written each time the device is powered up.
Custom power-up and power-down sequences can be tested and verified in the ACTIVE state (PWR_EN pin pulled high) by using ${ }^{2} \mathrm{C}$ to toggle the SEQUP and SEQDWN bits. Permanent changes to the default power-up sequence timing require custom programming at the TI factory.

### 8.3.1.1 Power-Up Sequencing

When the power-up sequence is initiated, STROBE1 occurs and any rail assigned to this strobe is enabled. After a delay time of DLY1, STROBE2 occurs and the rail assigned to this strobe is powered up. The sequence continues until all strobes have occurred and all DLYx times have been executed.


The power-up sequence is defined by strobes and delay times. In this example, push-button low is the power-up event.

Figure 3. Power-Up Sequence
The default power-up sequence can be changed by writing to the SEQ1 through SEQ6 registers. Strobes are assigned to rails by writing to the SEQ1 through SEQ4 registers. A rail can be assigned to only one strobe but multiple rails can be assigned to the same strobe. Delays between strobes are defined in the SEQ5 and SEQ6 registers.

## Feature Description (continued)



For default power-up sequences of the other TPS65217x family members, refer to the Powering the AM335x with the TPS65217x user's guide.

Figure 4. Default Power-Up Sequence for the TPS65217A Device
The power-up sequence is executed if the following events occurs:
From the OFF state (going to the ACTIVE state):

- Push-button is pressed (falling edge on PB_IN) OR
- USB voltage is asserted (rising edge on USB) OR
- The AC adaptor is inserted (rising edge on the AC pin)

The PWR_EN pin is level-sensitive (opposed to edge-sensitive), and the pin can be asserted before or after the previously listed power-up events. However, the PWR_EN pin must be asserted within 5 s of the power-up event; otherwise, the power-down sequence is triggered and the device goes to the OFF state. If a fault occurs because the device is in undervoltage lockout (UVLO) or requires overtemperature shutdown (OTS), the device goes to the OFF state.

## From the SLEEP state (going to the ACTIVE state):

- The push-button is pressed (falling edge on the PB_IN pin) OR
- The USB voltage is asserted (rising edge on the USB pin) OR
- The AC adaptor is inserted (rising edge on the AC pin) OR
- The PWR_EN pin is asserted (pulled high).

In the SLEEP state, the power-up sequence can be triggered by asserting the PWR_EN pin only, and the pushbutton press or AC and USB assertion are not required. If a fault occurs because the device is in undervoltage lockout (UVLO) or requires overtemperature shutdown (OTS), the device goes to the OFF state.
In the ACTIVE state:

## Feature Description (continued)

The sequencer can be triggered any time by setting the SEQUP bit in the SEQ6 register high. The SEQUP bit is automatically cleared after the sequencer is complete.
Rails that are not assigned to a strobe (the SEQ bit set to 0000b) are not affected by power-up and power-down sequencing and stay in their current ON or OFF state regardless of the sequencer. Any rail can be enabled or disabled at any time by setting the corresponding enable bit in the ENABLE register with the only exception that the ENABLE register cannot be accessed while the sequencer is active. Enable bits always reflect the current enable state of the rail, that is, the sequencer sets or resets the enable bits for the rails under its control. Also, whenever faults occur which shut-down the power-rails, the corresponding enable bits are reset.

### 8.3.1.2 Power-Down Sequencing

By default, power-down sequencing follows the reverse power-up sequence. When the power-down sequence is triggered, STROBE7 occurs first, and any rail assigned to STROBE7 is shut down. After a delay time of DLY6, STROBE6 occurs, and any rail assigned to STROBE6 is shut down. The sequence continues until all strobes have occurred and all DLYx times have been executed.
In some applications, all rails may be required to shut down at the same time with no delay between rails. Set the INSTDWN bit in the SEQ6 register to bypass all delay times and shut-down all rails at the same time when the power-down sequence is triggered.
A power-down sequence is executed if one of the following events occurs:

- The SEQDWN bit is set.
- The PWR_EN pin is pulled low.
- The push-button is pressed for more than 8 s .
- The nRESET pin is pulled low.
- A fault occurs in the device (either an OTS, UVLO, or PGOOD failure).
- The PWR_EN pin is not asserted (pulled high) within 5 s of a power-up event and the OFF bit is set to 1 b .

When the device goes from the ACTIVE to the OFF state, any rail not controlled by the sequencer is shut down after the power-down sequencer is complete. When the device goes from the ACTIVE to the SLEEP state, any rail not controlled by the power-down sequencer stays in its present state.


Figure 5. Power-Down Sequence from ON State to OFF State (All Rails Turned OFF)


STROBE14 and STROBE15 are omitted to let the LDO1 or LDO2 regulators stay ON.
Figure 6. Power-Down Sequence from ON State to SLEEP State

## Feature Description (continued)

### 8.3.1.3 Special Strobes (STROBE 14 and 15)

STROBE 14 and STROBE 15 are not assigned to the sequencer but used to control rails that are always-on, that is, are powered up as soon as the device goes out of the OFF state and stay ON in the SLEEP state. STROBE 14 and STROBE 15 options are available only for the LDO1 and LDO2 rails and not for any of the other rails.
STROBE 15 occurs as soon as the push-button is pressed or the USB or AC adaptor is connected to the device. STROBE 14 occurs after a delay time of DLY6. The LDO1 and LDO2 rails can be assigned to either strobe but by default only LDO1 is assigned to special STROBE 15 (default settings must be programmed by Tl at the factory because all registers are reset during transitions to the OFF or SLEEP states).
When a power-down sequence is initiated, STROBE 15 and STROBE 14 occur only if the OFF bit is set. Otherwise both strobes are omitted, and the LDO1 and LDO2 rails keep their state.

### 8.3.2 Power Good

The power-good signals are used to indicate if an output rail is in regulation or at fault. Internally, all power-good signals of the enabled rails are monitored at all times and if any of the signals goes low, a fault is declared. All power-good signals are internally deglitched. When a fault occurs, all output rails are powered down and the device goes to the OFF state.
The TPS65217x device has two power-good output pins: one is dedicated to the LDO1 and LDO2 rails (LDO_PGOOD) and one for all other rails (PGOOD). The power-good signals that are indicated by the PGOOD pin are programmable. The following rules apply to both output pins:

- The power-up default state for the PGOOD pin and the LDO_PGOOD pin is low. When all rails are disabled, the PGOOD and LDO_PGOOD pins are both low.
- Only enabled rails are monitored. Disabled rails are ignored.
- Power-good monitoring of a particular rail starts 5 ms after the rail has been enabled. The power-good signal is continuously monitored after the 5 -ms deglitch time expires.
- The signals controlling the PGOOD and LDO_PGOOD pins are delayed by the PGDLY ( 20 ms default) after the sequencer is done.
- If a fault occurs on an enabled rail (such as a shorted output, OTS condition, or UVLO condition), the PGOOD pin, LDO_PGOOD pin, or both pins are pulled low, and all rails are shut down.
- If the user disables a rail (either manually or through the sequencer), this action has no effect on the PGOOD or LDO_PGOOD pin.
- If the user disables all rails (either manually or through the sequencer), the PGOOD pin, LDO_PGOOD pin, or both pins are pulled low.


### 8.3.2.1 LDO1, LDO2 Power-Good (LDO_PGOOD)

The LDO_PGOOD pin is a push-pull output that is driven to a high level when either the LDO1 regulator or the LDO2 regulator is enabled and in regulation. The LDO_PGOOD pin is pulled low when both LDO regulators are disabled or one is enabled but has encountered a fault. A typical fault is an output short or overcurrent condition. In normal operation, the LDO_PGOOD pin is high in the ACTIVE and SLEEP states and low in the RESET and OFF states.

### 8.3.2.2 Primary Power-Good (PGOOD)

The primary PGOOD pin has similar functionality to the LDO_PGOOD pin except that PGOOD monitors the DCDC1, DCDC2, and DCDC3 converters, and the LDO3 and LDO4 outputs configured as LDO regulators. The user can also choose to monitor the LDO1 and LDO2 regulators by setting the LDO1PGM and LDO2PGM mask bits low in the DEFPG register. By default, the power-good signal of the LDO1 and LDO2 regulators does not affect the PGOOD pin (mask bits are set to 1b by default). In normal operation the PGOOD pin is high in the ACTIVE state but low in the SLEEP, RESET, and OFF states.
In the SLEEP state and the WAIT PWR_EN state, the PGOOD pin is forced low. The PGOOD pin is set high after the device goes to the ACTIVE state, the power sequencer is complete, and the PGDLY time is expired.

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## Feature Description (continued)

### 8.3.2.3 Load Switch PGOOD

When either LS1 or LS2 is configured as a load switch, the device ignores the respective power-good signal. An overcurrent or short condition present on the LS1 or LS2 load switch does not affect the PGOOD pin or any of the power rails unless the power dissipation leads to thermal shutdown.


This figure also shows the power-down sequence for the case of a short on the DCDC2 output.
Figure 7. Default Power-Up Sequence

### 8.3.3 Push-Button Monitor (PB_IN)

The TPS65217x device has an active-low PB_IN input pin that is typically connected to ground through a pushbutton switch. The PB_IN input has a $50-\mathrm{ms}$ deglitch time and an internal pull-up resistor that is connected to an always-on supply. The always-on supply is an unregulated internal power rail that is functionally equivalent to the power path. The source of the always-on supply is the same as the source of the SYS pin. The push-button monitor has two functions. The first is to power-up the device from the OFF or SLEEP state when a falling edge is detected on the PB_IN pin. The second is to power cycle the device when the PB_IN pin is held low for more than 8 s .

For a description of each function, see the Device Functional Modes section. A change in push-button status (the PB_IN pin goes from high to low or low to high) is signaled to the host through the PBI interrupt bit in the INT register. The current status of the interrupt can be checked by reading the PB status bit in the STATUS register. Figure 8 shows a timing diagram for the push-button monitor.

## Feature Description (continued)



Figure 8. Timing Diagram of the Push-Button Monitor Circuit

### 8.3.4 nWAKEUP Pin (nWAKEUP)

The nWAKEUP pin is an open-drain, active-low output that is used to signal a wakeup event to the system host. This pin is pulled low whenever the device is in the OFF or SLEEP state and detects a wakeup event as described in the Device Functional Modes section. The nWAKEUP pin is delayed for 50 ms over the power-up event and stays low for 50 ms after the PWR_EN pin has been asserted. If the PWR_EN pin is not asserted within 5 s of the power-up event, the device shuts down and goes to the OFF state. In the ACTIVE state, the nWAKEUP pin is always high. Figure 9 shows the timing diagram for the nWAKEUP pin.

### 8.3.5 Power Enable Pin (PWR_EN)

The PWR_EN pin is used to keep the device in the ACTIVE mode after it detects a wakeup event as described in the Device Functional Modes section. If the PWR_EN pin is not asserted within 5 s of the nWAKEUP pin being pulled low, the device shuts down the power and goes to either the OFF or SLEEP state, depending on the OFF bit in the STATUS register. The PWR_EN pin is level-sensitive, meaning that PWR_EN may be pulled high before the wake-up event.

The PWR_EN pin can also be used to toggle between the ACTIVE and SLEEP states. For more information, see SLEEP in the PMIC States section.

## Feature Description (continued)



In the example shown, the wakeup event is a falling edge on the PB_IN.
(1) If the PWR_EN pin is not asserted within 5 s of the WAKEUP pin being pulled low, the device goes to the OFF or SLEEP state

Figure 9. nWAKEUP Timing Diagram

### 8.3.6 Reset Pin (nRESET)

When the nRESET pin is pulled low, all power rails, including LDO1 and LDO2, are powered down, and the default register settings are restored. The device stays powered down as long as the nRESET pin is held low, but for a minimum of 1 s . After the nRESET pin is pulled high, the device goes to the ACTIVE state, and the default power-up sequence executes. For more information, see RESET in the PMIC States section.

### 8.3.7 Interrupt Pin (nINT)

The interrupt pin is used to signal any event or fault condition to the host processor. Whenever a fault or event occurs in the device, the corresponding interrupt bit is set in the INT register, and the open-drain output is pulled low. The nINT pin is released (Hi-Z) and the fault bits are cleared when the INT register is read by the host. However, if a failure continues, the corresponding INT bit stays set and the nINT pin is pulled low again after a maximum of $32 \mu \mathrm{~s}$.
Interrupt events include pushing or releasing the push-button and a change in the USB or AC voltage status.
The mask bits in the INT register are used to mask events from generating interrupts. The mask settings affect the nINT pin only and have no impact on the protection and monitor circuits themselves.

## NOTE

Continuous event conditions such as an ISINK-enabled shutdown can cause the nINT pin to be pulled low for an extended period of time, which can keep the host in a loop trying to resolve the interrupt. If this behavior is not desired, set the corresponding mask bit after receiving the interrupt and poll the INT register to determine when the event condition resolves and the corresponding interrupt bit is cleared. Then the interrupt that caused the nINT pin to stay low can be un-masked.

### 8.3.8 Analog Multiplexer

The TPS65217x device has an analog multiplexer (mux) that provides access to critical system voltages. The voltages that can be measured by an ADC at the MUX_OUT pin are as follows:

- Battery voltage (VBAT)
- System voltage (VSYS)


## Feature Description (continued)

- Temperature-sense voltage (VTS), and
- VICHARGE, a voltage proportional to the charging current, and
- MUX_IN, an external input pin to monitor an additional system voltage

In addition, one external input is available. The VBAT and VSYS voltages are divided by three (for example, MUX_OUT = VBAT / 3) to be compatible with the input-voltage range of the ADC that resides on the system-host side. The output of the MUX is buffered and can drive a maximum of $1-\mathrm{mA}$ load current.


Figure 10. Analog Multiplexer

### 8.3.9 Battery Charger and Power Path

The TPS65217x device has a linear charger for Li+ batteries and a triple system-power path targeted at spacelimited portable applications. The power path lets simultaneous and independent charging of the battery and powering of the system. This feature enables the system to run with a defective or absent battery pack and lets instant system turnon even with a totally discharged battery. The input power source for charging the battery and running the system can be either an AC adapter or a USB port. The power path prioritizes the AC input over the USB input, and both over the battery input, to decrease the number of charge and discharge cycles on the battery. Charging current is automatically decreased when the system load increases to the point where the AC or USB power supply reach the maximum allowable current. If the AC or USB power supply cannot provide enough current to the system, the battery supplies the additional current required and the battery will discharge until the system load is reduced. Figure 11 shows a block diagram of the power path. Figure 12 shows an example of the power path management function.

Feature Description (continued)


Figure 11. Block Diagram of the Power Path and Battery Charger

## Feature Description (continued)



In this example, the AC input current limit is set to 1300 mA , battery charge current is 500 mA , and system load is 700 mA . As the system load increases to 1000 mA , the battery charging current is decreased to 300 mA to keep the AC input current of 1300 mA .

Figure 12. Power Path Management
The detection thresholds for AC and USB inputs are a function of the battery voltage, and three basic use cases must be considered: shorted or absent battery, dead battery, and good battery.

### 8.3.9.1 Shorted or Absent Battery ( $V_{B A T}<1.5 \mathrm{~V}$ )

The AC or USB inputs are valid and the device powers up if the AC or USB input voltage increases above 4.3 V . After powering up, the input voltage can decrease to a value of $\mathrm{V}_{\text {UVLO }}+\mathrm{V}_{\text {OFFSET }}$ (for example, $3.3 \mathrm{~V}+200 \mathrm{mV}$ ) before the device powers down.
The AC input is prioritized over the USB input; that is, if both inputs are valid, current is pulled from the AC input and not the USB input. If both AC and USB supplies are available, the power-path switches to the USB input if AC voltage decreases to less than 4.1 V (fixed threshold).

## NOTE

The rise time of the AC and USB input voltage must be less than 50 ms for the detection circuits to operate correctly. If the rise time is longer than 50 ms , the device may fail to power up.

The linear charger periodically applies a $10-\mathrm{mA}$ current source to the BAT pin to check for the presence of a battery. This applied current causes the BAT pin to float up to more than 3 V , which may interfere with AC removal detection and prevent switching from the AC to the USB input. For this reason, TI does not recommend using both the AC and USB inputs when the battery is absent.

### 8.3.9.2 Dead Battery (1.5 $\left.V<V_{B A T}<V_{U V L O}\right)$

Functionality for this case is the same as for the shorted battery case. The only difference is that after the AC input is selected as the input, the power-path does not switch back to the USB input as AC input voltage decreases to less than 4.1 V .

## Feature Description (continued)

### 8.3.9.3 Good Battery ( $V_{B A T}>V_{U V L O}$ )

The AC and USB supplies are detected when the input is 190 mV above the battery voltage, and are considered absent when the voltage difference to the battery is less than 125 mV . This feature makes sure that the AC and USB supplies are used whenever possible to save battery life. The USB and AC inputs are both current-limited and controlled through the PPATH register.
In case AC or USB is not present or is blocked by the power path control logic (for example, in the OFF state), the battery voltage always supplies the system (SYS pin).

### 8.3.9.4 AC and USB Input Discharge

The AC and USB inputs have $90-\mu \mathrm{A}$ internal current sinks which are used to discharge the input pins to avoid false detection of an input source. The AC sink is enabled when the USB input is a valid supply and the AC voltage $\left(\mathrm{V}_{\mathrm{AC}}\right)$ is less than the detection threshold. Likewise, the USB sink is enabled when the AC input is a valid supply and the USB voltage ( $\mathrm{V}_{\text {USB }}$ ) is less than the detection limit. Both current sinks can be forced OFF by setting the ACSINK and USBSINK bits to 11 b. Both bits are located in the PPATH register (address $0 \times 01$ ).

## NOTE

Setting the ACSINK or USBSINK bit to 01 b and 10 b is not recommended as these settings may cause unexpected enabling and disabling of the current sinks.

### 8.3.10 Battery Charging

When the charger is enabled (the CH_EN bit is set to 1b), it first checks for a short circuit on the BAT pin by sourcing a small current and monitoring the BAT voltage. If the voltage on the BAT pin increases to more than the BAT pin short-circuit detection threshold ( $\mathrm{V}_{\mathrm{BAT}(\mathrm{SC})}$ ), a battery is present and charging can start. The battery is charged in three phases: precharge, constant-current fast charge (current regulation), and constant-voltage (CV) charge (voltage regulation). In all charge phases, an internal control loop monitors the device junction temperature and decreases the charge current if an internal temperature threshold is exceeded. Figure 13 shows a typical charging profile. Figure 14 shows a modified charging profile.


Figure 13. Charging Profiles-Typical Charge Current Profile With Termination Enabled

## Feature Description (continued)



Figure 14. Charging Profiles-Modified Charging Profile With Thermal Regulation Loop Active and Termination Enabled

In the precharge phase, the battery is charged at the precharge current ( ${ }_{\text {PRECHG }}$ ), which is typically $10 \%$ of the fast-charge current rate. The battery voltage starts rising. After the battery voltage crosses the precharge-to-fastcharge transition threshold ( $\mathrm{V}_{\text {LOwv }}$ ), the battery is charged at the fast charge current ( $\mathrm{I}_{\mathrm{CHG}}$ ). The battery voltage continues to rise. When the battery voltage reaches the battery charger voltage ( $\mathrm{V}_{\text {OREG }}$ ), the battery is held at a constant value of $\mathrm{V}_{\text {OREG. }}$. The battery current now decreases as the battery approaches full charge. When the battery current reaches the charge current for termination detection threshold (ITERM), the TERMI bit in the CHGCONFIGO register is set to 1 b . To avoid false termination when the charger goes to either the dynamic power path management (DPPM) loop or thermal loop, termination is disabled when either loop is active.
The charge current cannot exceed the input current limit of the power path minus the load current on the SYS pin because the power-path manager decreases the charge current to support the system load if the input current limit is exceeded. Whenever the nominal charge current is decreased by action of the power-path manger, the DPPM loop, or the thermal loop, the safety timer is clocked with half the nominal frequency to extend the charging time by a factor of 2 .

### 8.3.11 Precharge

The precharge current is preset to a factor of $10 \%$ of the fast-charge current (ICHRG[1:0]) and cannot be changed by the user.

### 8.3.12 Charge Termination

When the charging current decreases to less than the termination current threshold, the charger is turned off. The value of the termination current threshold can be set in the CHGCONFIG3 register using the TERMIF[1:0] bits. The termination current has a default setting of $7.5 \%$ of the ICHRG[1:0] setting.

## Feature Description (continued)

Charge termination is enabled by default and can be disabled by setting the TERM bit of the CHGCONFIG1 register to 1 b . When termination is disabled, the device goes through the precharge, fast-charge, and CV phases, then stays in the CV phase. The charger behaves like an LDO regulator with an output voltage equal to the battery charger voltage ( $\mathrm{V}_{\text {OREG }}$ ) and can source current up to the fast charge current ( $\mathrm{I}_{\mathrm{CHG}}$ ) or maximum input current ( $\mathrm{I}_{\mathrm{IN}-\mathrm{MAX}}$ ), whichever is less. Battery detection is not performed.

## NOTE

The termination current threshold is not a tightly controlled parameter. Using the lowest setting ( $2.5 \%$ of the nominal charge current) is not recommended because the minimum termination current can be very close to 0 . Any leakage on the battery side may cause the termination not to trigger and charging to time out eventually.

### 8.3.13 Battery Detection and Recharge

Whenever the battery voltage decreases to less than the recharge detection threshold $\left(\mathrm{V}_{\mathrm{RCH}}\right)$, the sink current for battery detection ( $I_{\text {BAT(DETT }}$ ) is pulled from the battery for the battery detection time ( $t_{\text {DET }}$ ) to determine if the battery was removed. The voltage on the BAT pin staying above $\mathrm{V}_{\text {Lowv }}$ voltage indicates that the battery is still connected. If the charger is enabled (the CH_EN bit set to 1b), a new battery charging cycle starts.
When the BAT pin voltage is decreasing and less than the V Lowv voltage in the battery detection test, this indicates that the battery was removed. The device then checks for battery insertion by turning on the charging path and sources the $I_{\text {PRECHG }}$ current out of the BAT pin for the $\mathrm{t}_{\text {DET }}$ time. Failure of the voltage to increase to greater than the $\mathrm{V}_{\mathrm{RCH}}$ voltage indicates that a battery has been inserted, and a new charge cycle can start. If, however, the voltage is already greater than the $\mathrm{V}_{\mathrm{RCH}}$ voltage, a fully charged battery was possibly inserted. To check for this case, the $I_{\text {BAT(DET) }}$ current is pulled from the battery for the $\mathrm{t}_{\text {DET }}$ time and if the voltage falls below the $\mathrm{V}_{\text {Lowv }}$ voltage, no battery is present. The battery detection cycle continues until the device detects a battery or the charger is disabled.
When the battery is removed from the system, the charger also flags a BATTEMP error which indicates that the TS input is not connected to a thermistor.

### 8.3.14 Safety Timer

The TPS65217x device hosts an internal safety timer for the precharge and fast-charge phases to help prevent potential damage to either the battery or the system. The default fast-charge time can be changed in the CHGCONFIG1 register and the precharge time can be changed in the CHGCONFIG3 register. The timer functions can be disabled by resetting the TMR_EN bit of the CHGCONFIG1 register to 0b. Both timers are disabled when the charge termination is disabled (the TERM bit is cleared to $0 b$ ).

### 8.3.14.1 Dynamic Timer Function

Under some circumstances, the charger current is decreased to ensure support when changes in the system load or junction temperature occur. Two events can decrease the charging current. The first event is an increase in the system load current, which causes the DPPM loop to decrease the available charging current. The second event is when the junction temperature exceeds the temperature regulation limit ( $T_{J(R E G)}$ ), which causes the device to go to thermal regulation.
In each of these events, the timer is clocked with half-frequency to extend the charger time by a factor of 2 , and charger termination is disabled. Normal operation starts again after the device junction temperature decreases to less than ( $\left.T_{J(R E G)}\right)$ and the system load decreases to a level where enough current is available to charge the battery at the desired charge rate. This feature is enabled by default and can be disabled by resetting the DYNTMR bit in the CHGCONFIG2 register to 0b. Figure 14 shows a modified charge cycle with the thermal loop active.

### 8.3.14.2 Timer Fault

A timer fault occurs if the battery voltage does not exceed the $\mathrm{V}_{\text {LOWv }}$ voltage in the $\mathrm{t}_{\text {PRECHG }}$ time during precharging. A timer fault also occurs if the battery current does not reach the $I_{\text {TERM }}$ current in fast charge before the safety timer expires. Fast-charge time is measured from the start of the fast-charge cycle.

## Feature Description (continued)

The fault status is indicated by the CHTOUT and PCHTOUT bits in the CHGCONFIG0 register. Time-out faults are cleared and a new charge cycle is started when either the USB or AC supply is connected (rising edge of $\mathrm{V}_{\text {USB }}$ or $\mathrm{V}_{\mathrm{AC}}$ ), the charger RESET bit is set to 1 b in the CHGCONFIG1 register, or the battery voltage decreases to less than the recharge threshold $\left(\mathrm{V}_{\mathrm{RCH}}\right)$.


Figure 15. State Diagram of Battery Charger

### 8.3.15 Battery-Pack Temperature Monitoring

The TS pin of the TPS65217x device connects to the NTC resistor in the battery pack. During charging, if the NTC resistance indicates that battery operation is less than or greater than the limits of normal operation, charging is suspended and the safety timer value is paused and held at the present value. When the battery pack temperature returns to within the limits of normal operation, charging resumes and the safety time is started again without resetting.
By default, the device supports a $10-\mathrm{k} \Omega$ NTC resistor with a B-value of 3480 . The NTC resistor is biased through a $7.35-\mathrm{k} \Omega$ internal resistor connected to the BYPASS rail ( 2.25 V ) and requires an external $75-\mathrm{k} \Omega$ resistor parallel to the NTC resistor to linearize the temperature response curve.
The TPS65217x device supports two different temperature ranges for charging: $0^{\circ} \mathrm{C}$ to $45^{\circ} \mathrm{C}$ and $0^{\circ} \mathrm{C}$ to $60^{\circ} \mathrm{C}$. The temperature range is selected through the TRANGE bit in the CHCONFIG3 register.

## Feature Description (continued)

## NOTE

The device can be configured to support a $100-\mathrm{k} \Omega$ NTC resistor (with a B-value of 3960) by setting the NTC_TYPE bit to 1 b in the CHGCONFIG1 register. However, TI does not recommended this real-time manual configuration. In the SLEEP state, the charger continues charging the battery, but all register values are reset to default values, in which case the charger gets the wrong temperature information. If $100-\mathrm{k} \Omega$ NTC resistor support is required, custom programming during production at the TI factory is required.


Figure 16. Charge Current as a Function of Battery Temperature


Figure 17. NTC Bias Circuit

## Feature Description (continued)

### 8.3.16 DC/DC Converters

### 8.3.16.1 Operation

The TPS65217x step-down converters typically operate with $2.25-\mathrm{MHz}$ fixed-frequency pulse-width modulation (PWM) at moderate-to-heavy load currents. At light load currents, the converter automatically goes to powersave mode and operates in pulse-frequency modulation (PFM).
During PWM operation, the converter uses a unique fast-response voltage-mode controller scheme with inputvoltage feed-forward to achieve good line and load regulation. This controller scheme allows the use of small ceramic input and output capacitors. At the start of each clock cycle, the high-side MOSFET is turned on. The current flows from the input capacitor through the high-side MOSFET through the inductor to the output capacitor and load. During this phase, the current ramps up until the PWM comparator trips and the control logic turns off the switch. The current-limit comparator also turns off the switch in case the current limit of the high-side MOSFET switch is exceeded. After a dead time to prevent shoot-through current, the low-side MOSFET rectifier is turned on and the inductor current ramps down. The direction of current flow is now from the inductor to the output capacitor and to the load. The current returns back to the inductor through the low-side MOSFET rectifier.

The next cycle turns off the low-side MOSFET rectifier and turns on the on the high-side MOSFET.
The DC/DC converters operate in synchronization with each other, with converter 1 as the master. A $120^{\circ}$ phase shift between DCDC1 and DCDC2 and between DCDC2 and DCDC3 decreases the combined input root mean square (RMS) current at the VIN_DCDCx pins. Therefore, smaller input capacitors can be used.

### 8.3.16.2 Output Voltage Setting

The setpoint of the output voltage for the $\mathrm{DC} / \mathrm{DC}$ converters is determined in one of two different ways. The first way is as a fixed-voltage converter where the voltage is defined in the DEFDCDCx register. The second way is an external resistor network. Set the XADJx bit in the DEFDCDCx register and use Equation 1 to calculate the output voltage.

$$
V_{\text {OUT }}=V_{\text {REF }} \times\left(1+\frac{R_{1}}{R_{2}}\right)
$$

where

- $\mathrm{V}_{\text {REF }}$ is the feedback voltage of 0.6 V

TI recommends selecting values to keep the combined resistance of the R1 and R2 resistors less than $1 \mathrm{M} \Omega$. Shield the VDCDC1, VDCDC2, and VDCDC3 lines from switching nodes and from the L1, L2, and L3 inductors to prevent coupling of noise into the feedback pins.


DCDC1, DCDC2, and DCDC3 offer two methods to adjust the output voltage.
Figure 18. Example for DCDC3-Fixed-Voltage Options Programmable Through $I^{2} C$ (XADJ3 $=0 b$, default)


DCDC1, DCDC2, and DCDC3 offer two methods to adjust the output voltage.
Figure 19. Example for DCDC3-Voltage is Set by External Feedback Resistor Network (XADJ3 = 1b)

### 8.3.16.3 Power-Save Mode and Pulse-Frequency Modulation (PFM)

By default, all three DC/DC converters go to pulse-frequency modulation (PFM) mode at light loads, and fixedfrequency pulse-width modulation (PWM) mode at heavy loads. In some applications, forcing PWM operation even at light loads is required, which is done by setting the PFM_ENx bits in the DEFSLEW registers to 1 b (default setting is Ob). In PFM mode, the converter skips switching cycles and operates with decreased frequency with a minimum quiescent current to keep high efficiency. The converter positions the output voltage typically $1 \%$ above the nominal output voltage. This voltage-positioning feature minimizes the voltage drop caused by a sudden load step.

The converters go from PWM to PFM mode after the inductor current in the low-side MOSFET switch becomes 0 A.
When the converters are in power-save mode, the output voltage is monitored with a PFM comparator. As the output voltage decreases to less than the PFM comparator threshold of $\mathrm{V}_{\text {OUT }}+1 \%$, the device starts a PFM current pulse. Starting the pulse is done by turning on the high-side MOSFET and ramping up the inductor current. Then the high-side MOSFET turns off and the low-side MOSFET switch turns on until the inductor current becomes 0 A again.
The converter effectively delivers a current to the output capacitor and the load. If the load is less than the delivered current, the output voltage rises. If the output voltage is equal to or greater than the PFM comparator threshold, the device stops switching and goes to a sleep mode with a typical $15-\mu \mathrm{A}$ current consumption. In case the output voltage is still less than the PFM comparator threshold, additional PFM current pulses are generated until the PFM comparator threshold is reached. The converter starts switching again after the output voltage decreases to less than the PFM comparator threshold.
With one threshold comparator, the output-voltage ripple during PFM mode operation can be kept very small. The ripple voltage depends on the PFM comparator delay, the size of the output capacitor, and the inductor value. Increasing the value of the output capacitors, inductors, or both keeps the output ripple at a minimum.
The converter goes from PFM mode and goes to PWM mode the output current can no longer be supported in PFM mode or if the output voltage decreases to less than a second threshold, called the PFM comparator-low threshold. This PFM comparator-low threshold is set to a value of $\mathrm{V}_{\text {OUT }}-1 \%$ and enables a fast transition from power-save mode to PWM mode during a load step.
The power-save mode can be disabled through the $I^{2} \mathrm{C}$ interface for each of the step-down converters, independently of each other. If the power-save mode is disabled, the converter then operates in fixed-PWM mode.

### 8.3.16.4 Dynamic Voltage Positioning

This feature decreases the voltage undershoots and overshoots at load steps from light to heavy load and from heavy to light load. This feature is active in power-save mode and provides more headroom for both the voltage drop at a load step and the voltage increase at a load removal. This improves load-transient behavior. At light loads in which the converter operates in PFM mode, the output voltage is regulated typically $1 \%$ greater than the nominal value ( $\mathrm{V}_{\text {OUT }}$ ). In case of a load transient from light load to heavy load, the output voltage drops until it reaches the low threshold of the PFM comparator set to $-1 \%$ less than the nominal value, and goes to PWM mode. During a load removal from heavy load to light load, the voltage overshoot is low because of active regulation turning on the low-side MOSFET.


Figure 20. Dynamic Voltage Positioning in Power Save Mode

### 8.3.16.5 100\% Duty-Cycle Low-Dropout Operation

The converter starts to go to the $100 \%$ duty-cycle mode after the input voltage $\left(\mathrm{V}_{\mathbb{I N}}\right)$ comes close to the nominal output voltage. To keep the output voltage steady, the high-side MOSFET is turned on $100 \%$ for one or more cycles. As the $\mathrm{V}_{\mathbb{I}}$ voltage decreases further, the high-side MOSFET is turned on completely. In this case, the converter offers a low input-to-output voltage difference which is particularly useful in battery-powered applications to achieve longest operation time by taking full advantage of the whole battery voltage range.
Use Equation 2 to calculate the minimum input voltage to keep regulation ( $\mathrm{V}_{\mathrm{IN}, \mathrm{MIN}}$ ) which depends on the load current and output voltage.
$\mathrm{V}_{\text {IN, MIN }}=\mathrm{V}_{\text {OUT, MAX }}+\mathrm{I}_{\text {OUT, MAX }} \times\left(\mathrm{R}_{\text {DSON, MAX }}+\mathrm{R}_{\mathrm{L}}\right)$
where

- $V_{\text {Out,MAX }}$ is the nominal output voltage plus the maximum output voltage tolerance.
- I lout,Max the maximum output current plus the inductor ripple current.
- $R_{D S O N, M A X}$ is the maximum upper MOSFET switch $\mathrm{R}_{\text {DSON }}$ resistance.
- $R_{L}$ is the $D C$ resistance of the inductor.


### 8.3.16.6 Short-Circuit Protection

High-side and low-side MOSFET switches are short-circuit protected. After the high-side MOSFET switch reaches its current limit, it is turned off and the low-side MOSFET switch is turned on. The high-side MOSFET switch can only turn on again after the current in the low-side MOSFET switch decreases to less than its current limit.

### 8.3.16.7 Soft Start

The three step-down converters in the TPS65217x device have an internal soft-start circuit that controls the ramp-up of the output voltage. The output voltage ramps up from $5 \%$ to $95 \%$ of its nominal value within $750 \mu \mathrm{~s}$. This ramp up limits the inrush current in the converter during start-up and prevents possible input voltage drops when a battery or high-impedance power source is used. The soft-start circuit is enabled after the start-up time, $\mathrm{t}_{\text {start, }}$ expires.


Figure 21. Output of the DC/DC Converters is Ramped Up Within $750 \mu \mathrm{~s}$

### 8.3.17 Standby LDO Regulators (LDO1, LDO2)

The LDO1 and LDO2 regulators support up to 100 mA each, are internally current limited, and have a maximum dropout voltage of 200 mV at the rated output current. In SLEEP mode, however, the output current is limited to 1 mA each. When disabled, both outputs are discharged to ground through a $430-\Omega$ resistor.

The LDO1 regulator supports an output voltage range from 1 V to 1.8 V , which is controlled through the DEFLDO1 register. The LDO2 regulator supports an output voltage range from 0.9 V to 1.5 V , and is controlled through the DEFLDO2 register. By default, the LDO1 regulator is enabled immediately after a power-up event as described in the PMIC States section and stays on in the SLEEP state to support system standby. Each LDO regulator has low standby current of less than $15 \mu \mathrm{~A}$ (typical).

The LDO2 regulator can be configured to track the output voltage of the DCDC3 converter (core voltage). When the TRACK bit is set to 1 b in the DEFLDO2 register, the output is determined by the DCDC3[5:0] bits of the DEFDCDC3 register and the LDO2[5:0] bits of the DEFLDO2 register are ignored.
The LDO1 and LDO2 regulators can be controlled through STROBE 1 through 6, special STROBES 14 and 15, or through the corresponding enable bits in the ENABLE register. By default, the LDO1 regulator is controlled by STROBE 15, which keeps LDO1 on in the SLEEP state. The STROBE assignments can be changed by the user while the device is in the ACTIVE state, but all register settings are reset to the default values when the device goes to the SLEEP or OFF state. TI does not recommend real-time modification of the STROBE assignments of the LDO1 or LDO2 regulator. For permanent changes to the default STROBE assignments, custom programming during production at the TI factory is required.

### 8.3.18 Load Switches or LDO Regulators (LS1 or LDO3, LS2 or LDO4)

The TPS65217x device has two general-purpose load switches that can also be configured as LDOs. As LDOs, they support up to 200 mA (TPS65217B) or 400 mA (TPS65217C and TPS65217D) each, are internally currentlimited, and have a maximum dropout voltage of 200 mV at rated output current. These two outputs are configured as LS1 and LS2 load switched in the TPS65217A variant of the device. The on-off state of the load switches (LS1 and LS2) or the LDO regulators (LDO3 and LDO4) is controlled either through the sequencer or the LS1_EN and LS2_EN bits of the ENABLE register. When disabled, both outputs are discharged to ground through a $375-\Omega$ resistor.
Configured as load switches, LS1 and LS2 have a maximum impedance of $650 \mathrm{~m} \Omega$. Different from LDO operation, load switches can stay in current limit indefinitely without affecting the internal power-good signal or affecting the other rails.

## NOTE

Excessive power dissipation in the switches may cause thermal shutdown of the device.
Load switch and LDO modes are controlled by the LS1LDO3 and LS2LDO4 bits of the DEFLS1 and DEFLS2 registers.

### 8.3.19 White LED Driver

The TPS65217x device has a boost converter and two current sinks capable of driving two strings containing up to 10 LEDs in each string (also known as a $2 \times 10$ matrix) LEDs at 25 mA or one string of up to 10 LEDs at 50 mA of current. Use Equation 3 to calculate the current of each current sink.

$$
\begin{equation*}
\mathrm{I}_{\mathrm{LED}}=1048 \times \frac{1.24 \mathrm{~V}}{\mathrm{R}_{\mathrm{SET}}} \tag{3}
\end{equation*}
$$

Two different current levels can be programmed using two external $\mathrm{R}_{\text {SET }}$ resistors. Only one current setting is active at any given time, and both current sinks are always regulated to the same current. The active current setting is selected through the ISEL bit of the WLEDCTRL1 register.
An internal PWM signal and $I^{2} C$ control support brightness and dimming. Both current sources are controlled together and cannot operate independently. By default, the PWM frequency is set to 200 Hz , but can be changed to $100 \mathrm{~Hz}, 500 \mathrm{~Hz}$, or 1000 Hz . The PWM duty cycle can be adjusted from $1 \%$ (default) to $100 \%$ in $1 \%$ steps through the WLEDCTRL2 register.
When the ISINK_EN bit of WLEDCTRL1 register is set to 1 b , both current sinks are enabled, and the boost output voltage at the FB_WLED pin is regulated to support the same sink current through each current sink. The boost output voltage, however, is internally limited to 39 V .
If only one WLED string is required, short the ISINK1 and ISINK2 pins together and connect them to the cathode of the diode string. In this case, the LED current two times the sink current. Figure 22 shows the basic schematic and internal circuitry of the WLED driver used to drive two strings. Figure 23 shows the basic schematic and internal circuitry of the WLED driver used to one string. 表 33 and 表 34 list the recommended inductors and output capacitors for the WLED boost converters.


Figure 22. Block Diagram of WLED Driver-Dual-String Operation


This operation has the same LED current as dual-string operation. For single-string operation, both ISINK pins are shorted together and the RSET resistor values (R1 and R2) are doubled to halve the current that each ISINKx pin pulls, resulting in the same current through the LEDs as in dual-string operation.

Figure 23. Block Diagram of WLED Driver-Single-String Operation

### 8.4 Device Functional Modes


(1) Only if USB or AC supply is present
(2) Rails are powered-down as controlled by the sequencer in default EEPROM settings
(3) Battery voltage always supplies the system (from BAT pin to SYS pin)
(4) LDO1 is assigned to STROBE15 in default EEPROM settings and this special strobe is not controlled by the sequencer. LDO1 can only source 1 mA in the SLEEP state
(5) The $9-\mathrm{MHz}$ oscillator is enabled only when WLED or DCDC or PPATH or CHARGER is enabled.
(6) The charger, auto-discharge, PPATH, and $9-\mathrm{MHz}$ oscillator are ON in the SLEEP state if AC or USB is present and the charger is enabled and not fully charged.
(7) Any USB $=1(\uparrow)$ or AC $=1(\uparrow)$ event in the WAIT MIN OFF TIME2 state makes the device go from the SLEEP state when the timer expires. Any USB $=1(\uparrow)$ or $\mathrm{AC}=1(\uparrow)$ event in the WAIT MIN OFF TIME3 state makes the device go from the PRE-OFF state when the timer expires.
(8) All user registers are reset to default values each time the device goes to the SLEEP state.
(9) UVLO and OTS are monitored in all the states except the OFF, POR, and WAIT DEGLITCH states.

Figure 24. Global State Diagram

## Device Functional Modes (continued)

### 8.4.1 PMIC States

### 8.4.1.1 OFF State

In the OFF state, the PMIC is completely shut down with the exception of a few circuits to monitor the voltage on the AC, USB, and PB_IN pins. All output power rails are turned off and the registers are reset to their default values. The $I^{2} C$ communication interface is turned off. The lowest amount of power is used in this state. To exit the OFF state, one of the following wake-up events must occur:

- The PB_IN pin is pulled low.
- The USB supply is connected (positive edge).
- The AC adapter is connected (positive edge).

To go to the OFF state, set the OFF bit in the STATUS register to 1 b , and then pull the PWR_EN pin low. In normal operation, the device can only go to the OFF state from the ACTIVE state. Whenever a fault occurs during operation, such as thermal shutdown, power-good fail, undervoltage lockout, or a PWR EN pin timeout, all power rails are shut down and the device goes to the OFF state. The device stays in the OFF state until the fault is removed then a new power-up event occurs.

### 8.4.1.2 ACTIVE State

This state is the typical mode of operation when the system is up and running. All $\mathrm{DC} / \mathrm{DC}$ converters, LDO regulators, load switches, the WLED driver, and the battery charger are operational and can be controlled through the $\mathrm{I}^{2} \mathrm{C}$ interface.
After a wake-up event, the PMIC enables all rails not controlled by the sequencer and pulls the nWAKEUP pin low to signal the event to the host processor. The device goes to the ACTIVE state only if the host asserts the PWR_EN pin within 5 s after the wake-up event. Otherwise, the device goes to the OFF state. In the ACTIVE state, the sequencer is triggered to automatically enable the remaining power rails. The nWAKEUP pin returns to the Hi-Z state after the PWR_EN pin has been asserted. Figure 3 shows a timing diagram. The device can also go directly to the ACTIVE state from the SLEEP state by pulling the PWR_EN pin high. For more information, see the description of the SLEEP State.
The PWR_EN pin must be pulled low for the device to go from ACTIVE state.

### 8.4.1.3 SLEEP State

The SLEEP state is a low-power mode of operation intended to support system standby. Typically, all power rails are turned off with the exception of the LDO1 rail, and the registers are reset to their default values. The LDO1 rail stays operational but can support only a limited amount of current ( 1 mA typical).
To go to the SLEEP state, set the OFF bit in the STATUS register to 0b (default), and then pull the PWR_EN pin low. All power rails controlled by the power-down sequencer are shut down, and after 1 s the device goes to the SLEEP state. If the LDO1 rail was enabled in the ACTIVE state, the LDO1 rail stays enabled in the SLEEP sate. All rails not controlled by the power-down sequencer also keep state. The battery charger stays active for as long as either the USB or AC supply is connected to the device. All register values are reset when the device goes to the SLEEP state, including charger parameters.

The device goes to the ACTIVE state after detecting a wake-up event as described in the previous sections. In addition, the device goes from the SLEEP to the ACTIVE state when the PWR_EN pin is pulled high. The system host can go between the ACTIVE and SLEEP states by control of the PWR_EN pin only. This feature bypasses the requirement for a wake-up event from an external source to occur.

## Device Functional Modes (continued)

### 8.4.1.4 RESET State

The TPS65217x device can be reset by either pulling the nRESET pin low or by holding the PB_IN pin low for more than 8 s . All rails are shut down by the sequencer and all register values are reset to their default values. Rails not controlled by the sequencer are shut down after the power-down sequencer is complete. The device stays in the this state for as long as the reset pin is held low, and the nRESET pin must be high for the device to go from the RESET state. However, the device stays in the RESET state for a minimum of 1 s before going back to the ACTIVE state. As detailed in the description of the ACTIVE State, the PWR_EN pin must be asserted within 5 s of the nWAKEUP pin going low for the device to go to the ACTIVE state. The RESET function powercycles the device and only shuts down the output rails temporarily. Resetting the device does put the device in the OFF state.
If the PB_IN pin is kept low for an extended amount of time, the device continues to cycle between the ACTIVE and RESET states, and goes to the RESET state after each 8 -s time period.

### 8.5 Programming

### 8.5.1 $1^{2} \mathrm{C}$ Bus Operation

The TPS65217x device hosts a slave $I^{2} \mathrm{C}$ interface that is compliant with $I^{2} \mathrm{C}$ standard 3.0 and supports data rates up to $400 \mathrm{kbit} / \mathrm{s}$ and auto-increments addressing.


Figure 25. Subaddress in $I^{2} \mathrm{C}$ Transmission
The $I^{2} C$ bus is a communications link between a controller and a series of slave terminals. The link is established using a two-wire bus consisting of a serial clock signal (SCL) and a serial data signal (SDA). The serial clock is sourced from the controller in all cases, where the serial data line is bidirectional for data communication between the controller and the slave terminals. Each device has an open-drain output to transmit data on the serial data line. An external pullup resistor must be placed on the serial data line to pull the drain output high during data transmission.
Data transmission is initiated with a start bit from the controller as shown in Figure 28. The start condition is recognized when the SDA line goes from high to low during the high portion of the SCL signal. On reception of a start bit, the device receives serial data on the SDA input and checks for valid address and control information. If the appropriate group and address bits are set for the device, then the device issues an acknowledge (ACK) pulse and prepares for the reception of subaddress data. Subaddress data is decoded and responded to according to the Register Maps. Data transmission is completed by either the reception of a stop condition or the reception of the data word sent to the device. A stop condition is recognized as a low-to-high transition of the SDA input during the high portion of the SCL signal. All other transitions of the SDA line must occur during the low portion of the SCL signal. An acknowledge is issued after the reception of a valid address, subaddress, and data words. The $I^{2} \mathrm{C}$ interface auto-sequences through the register addresses, so that multiple data words can be sent for a given $I^{2} \mathrm{C}$ transmission. For details, see Figure 26, Figure 27, and Figure 28.

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## Programming (continued)



Figure 26. $I^{2} \mathrm{C}$ Data Protocol-Master Writes Data To Slave


Figure 27. $\mathrm{I}^{2} \mathrm{C}$ Data Protocol-Master Reads Data from Slave


Figure 28. $I^{2} \mathrm{C}$ Start-Stop-Acknowledge Protocol

## Programming (continued)

### 8.5.2 Password Protection

Registers $0 \times 0 \mathrm{~B}$ through $0 \times 1 \mathrm{~F}$, with the exception of the password register, are protected against accidental writing by an 8 -bit password. The password must be written before writing to a protected register and is automatically reset to $0 \times 00$ after the following $I^{2} \mathrm{C}$ transaction, regardless of the register that was accessed and regardless of the transaction type (read or write). The password is required for write access only and is not required for read access.

### 8.5.2.1 Level1 Protection

To write to a Level1 protected register, follow these steps:

1. Write the address of the destination register, XORed with the protection password (0x7D) to the PASSWORD register.
2. Write data to the password-protected register.
3. Data is only transferred to the protected register if the content of the PASSWORD register XORed with the address sent in Step 2 matches 0x7D. Otherwise, the transaction is ignored. The PASSWORD register is reset to $0 \times 00$ after the transaction regardless of whether the XOR logical function matched $0 \times 7 \mathrm{D}$ or not.
The cycle must be repeated for any other register that is Level1 write protected.

### 8.5.2.2 Level2 Protection

To write to a Level2 protected register, follow these steps:

1. Write the address of the destination register, XORed with the protection password (0x7D) to the PASSWORD register.
2. Write data to the password-protected register.
3. The data is temporarily stored if the content of the PASSWORD register XORed with the address sent in Step 2 matches $0 \times 7 \mathrm{D}$. The register value does not change at this point, but the PASSWORD register is reset to $0 \times 00$ after the transaction regardless of whether the XOR logical function matched $0 \times 7 \mathrm{D}$ or not.
4. Write the address of the destination register, XORed with the protection password (0x7D) to the PASSWORD register.
5. Write the same data as in Step 2 to the password protected register.
6. The content of the PASSWORD register is XORed again with the address sent in Step 5 must match 0x7D for the data to be valid.
7. The register is updated only if both data transfers in Step 2 and Step 5 were valid, and the transferred data matched.

## NOTE

No other $I^{2} \mathrm{C}$ transaction can occur between Step 2 and Step 5, and the register is not updated if any other transaction occurs between Step 2 and Step 5 . The cycle must be repeated for any other register that is Level2 write protected.

### 8.5.3 Resetting of Registers to Default Values

All registers are reset to default values when one or more of the following conditions occur:

- The device goes from the ACTIVE state to the SLEEP state or OFF state.
- The BAT or USB supply is applied from a power-less state (power-on reset).
- The push-button input is pulled low for more than 8 s .
- The nRESET pin is pulled low.
- A fault occurs.


### 8.6 Register Maps

### 8.6.1 Register Address Map

Figure 29 lists the memory-mapped registers for the device registers. All register offset addresses not listed in should be considered as reserved locations and the register contents should not be modified.

Figure 29. Register Address Map

| Address (Decimal) | Address (Hexadecimal) | Name | Password Protection Level | Default Value | Description | Section |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | $0 \times 00$ | CHIPID | None | X | Chip ID | Go |
| 1 | $0 \times 01$ | PPATH | None | 0x3D | Power path control | Go |
| 2 | $0 \times 02$ | INT | None | $0 \times 80$ | Interrupt flags and masks | Go |
| 3 | $0 \times 03$ | CHGCONFIGO | None | $0 \times 00$ | Charger control register 0 | Go |
| 4 | $0 \times 04$ | CHGCONFIG1 | None | 0xB1 | Charger control register 1 | Go |
| 5 | $0 \times 05$ | CHGCONFIG2 | None | 0x80 | Charger control register 2 | Go |
| 6 | $0 \times 06$ | CHGCONFIG3 | None | 0xB2 | Charger control register 3 | Go |
| 7 | $0 \times 07$ | WLEDCTRL1 | None | 0xB1 | WLED control register | Go |
| 8 | $0 \times 08$ | WLEDCTRL2 | None | $0 \times 00$ | WLED PWM duty cycle | Go |
| 9 | $0 \times 09$ | MUXCTRL | None | $0 \times 00$ | Analog multiplexer control register | Go |
| 10 | $0 \times 0 \mathrm{~A}$ | STATUS | None | $0 \times 00$ | Status register | Go |
| 11 | $0 \times 0 \mathrm{~B}$ | PASSWORD | None | $0 \times 00$ | Write password | Go |
| 12 | 0x0C | PGOOD | None | $0 \times 00$ | Power good (PG) flags | Go |
| 13 | 0x0D | DEFPG | Level1 | 0x0C | Power good (PG) delay | Go |
| 14 | 0x0E | DEFDCDC1 | Level2 | X | DCDC1 voltage adjustment | Go |
| 15 | $0 \times 0 \mathrm{~F}$ | DEFDCDC2 | Level2 | X | DCDC2 voltage adjustment | Go |
| 16 | $0 \times 10$ | DEFDCDC3 | Level2 | $0 \times 08$ | DCDC3 voltage adjustment | Go |
| 17 | $0 \times 11$ | DEFSLEW | Level2 | 0x06 | Slew control for DCDC1, DCDC2, DCDC3, and PFM mode enable | Go |
| 18 | $0 \times 12$ | DEFLDO1 | Level2 | 0x09 | LDO1 voltage adjustment | Go |
| 19 | $0 \times 13$ | DEFLDO2 | Level2 | 0x38 | LDO2 voltage adjustment | Go |
| 20 | $0 \times 14$ | DEFLS1 | Level2 | X | LS1 or LDO3 voltage adjustment | Go |
| 21 | $0 \times 15$ | DEFLS2 | Level2 | X | LS2 or LDO4 voltage adjustment | Go |
| 22 | $0 \times 16$ | ENABLE | Level1 | 0x00 | Enable register | Go |
| 23 | $0 \times 18$ | DEFUVLO | Level1 | 0x03 | UVLO control register | Go |
| 24 | $0 \times 19$ | SEQ1 | Level1 | X | Power-up STROBE definition | Go |
| 25 | $0 \times 1 \mathrm{~A}$ | SEQ2 | Level1 | X | Power-up STROBE definition | Go |
| 26 | $0 \times 1 \mathrm{~B}$ | SEQ3 | Level1 | X | Power-up STROBE definition | Go |
| 27 | $0 \times 1 \mathrm{C}$ | SEQ4 | Level1 | 0x40 | Power-up STROBE definition | Go |
| 28 | 0x1D | SEQ5 | Level1 | X | Power-up delay times | Go |
| 29 | 0x1E | SEQ6 | Level1 | $0 \times 00$ | Power-up delay times | Go |

Bit access types are abbreviated to fit into small table cells. Table 1 shows the abbreviation codes that are used for access types in this section. Registers that are different for each TPS65217x variant will have different hexadecimal reset values and are shown as $X$. The hexadecimal reset value can de determined by converting the binary reset value.

Table 1. Access Type Codes

| Access Type ${ }^{(1)}$ | Code | Description |
| :--- | :--- | :--- |
| Read | R | Read-only |
| Read/Write | R/W | Read and Write |

(1) Reserved bits can be R or R/W. Read-only (R) Reserved bits are not used and writing data to these bits will have no effect on device operation. Read and Write (R/W) Reserved bits are settings that cannot be modified. The reset value must always be written to these bits. Modifying a R/W Reserved bit will have an impact on device operation and can produce unwanted device behavior.

### 8.6.2 Chip ID Register (CHIPID) (Address = 0x00) [reset = X]

CHIPID is shown in Figure 30 and described in Table 2.
Return to Summary Table.
Figure 30. CHIPID Register

| DATA BIT |  | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME |  | CHIP[3:0] |  |  |  |  |  |  |  |
| READ/WRITE |  | R | R | R | R | R | R | R | R |
| RESET VALUE | TPS65217A | Ob | 1b | 1b | 1b | 0b | 0b | 1b | Ob |
|  | TPS65217B | 1b | 1b | 1b | 1b | 0b | 0b | 1b | 0b |
|  | TPS65217C | 1b | 1b | 1b | 0b | 0b | 0b | 1b | 0b |
|  | TPS65217D | 0b | 1b | 1b | Ob | 0b | 0b | 1b | 0b |

Table 2. CHIPID Register Field Descriptions

| Bit | Field | Type | Reset | Description |
| :---: | :---: | :---: | :---: | :---: |
| 7-4 | CHIP[3:0] | R | TPS65217A: 0111b <br> TPS65217B: 1111b <br> TPS65217C: 1110b <br> TPS65217D: 0110b | $\begin{aligned} & \text { Chip ID } \\ & 0000 \mathrm{~b}=\text { Future use } \\ & 0001 \mathrm{~F}=\text { Future use } \\ & 0110 \mathrm{~b}=\text { TPS65217D } \\ & 0111 \mathrm{~b}=\text { TPS65217A } \\ & 1000 \mathrm{~b}=\text { Future use } \\ & 1001 \mathrm{to} 1101 \mathrm{~b}=\text { Reserved } \\ & 1110 \mathrm{~b}=\text { TPS65217C } \\ & 1111 \mathrm{~b}=\text { TPS65217B } \end{aligned}$ |
| 3-0 | REV[3:0] | R | 0010b | $\begin{aligned} & \text { Revision code } \\ & 0000 \mathrm{~b}=\text { revision } 1.0 \\ & 0001 \mathrm{~b}=\text { revision } 1.1 \\ & 0010 \mathrm{~b}=\text { revision } 1.2 \\ & 0011 \mathrm{to} 1110 \mathrm{~b}=\text { Reserved } \\ & 1111 \mathrm{~b}=\text { Future use } \end{aligned}$ |

### 8.6.3 Power Path Control Register (PPATH) (Address = 0x01) [reset = 0x3D]

PPATH is shown in Figure 31 and described in Table 3.

## Return to Summary Table.

Figure 31. PPATH Register

| DATA BIT | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ | $\mathbf{0}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME | ACSINK | USBSINK | AC_EN | USB_EN | IAC[1:0] |  | IUSB[1:0] |  |
| READ/WRITE | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| RESET VALUE | 0 b | 0 b | 1 b | 1 b | 1 b | 1 b | 0 b | 1 b |

Table 3. PPATH Register Field Descriptions

| Bit |  | Field | Type | Reset |
| :---: | :--- | :--- | :--- | :--- |
| 7 | ACSINK |  | Description |  |

### 8.6.4 Interrupt Register (INT) (Address = 0x02) [reset = 0x80]

INT is shown in Figure 32 and described in Table 4.
Return to Summary Table.
Figure 32. INT Register

| DATA BIT | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ | $\mathbf{0}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME | Reserved | PBM | ACM | USBM | Reserved | PBI | ACI | USBI |
| READ/WRITE | R/W | R/W | R/W | R/W | R | R | R | R |
| RESET VALUE | lb | 0 b | 0 b | 0 b | 0 b | 0 b | 0 b | 0 b |

Table 4. INT Register Field Descriptions

| Bit | Field | Type | Reset |  |
| :---: | :--- | :--- | :--- | :--- | :--- |
| 7 | Reserved | R/W | 1b | This bit is reserved |

### 8.6.5 Charger Configuration Register 0 (CHGCONFIGO) (Address $=0 \times 03$ ) [reset $=0 \times 00$ ]

CHGCONFIGO is shown in Figure 33 and described in Table 5.

## Return to Summary Table.

Figure 33. CHGCONFIGO Register

| DATA BIT | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ | $\mathbf{0}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME | TREG | DPPM | TSUSP | TERMI | ACTIVE | CHGTOUT | PCHGTOUT | BATTEMP |
| READ/WRITE | R | R | R | R | R | R | R | R |
| RESET VALUE | 0 b | 0 b | 0 b | 0 b | 0 b | 0 b | 0 b | 0 b |

Table 5. CHGCONFIGO Register Field Descriptions

| Bit | Field | Type | Reset | Description |
| :---: | :---: | :---: | :---: | :---: |
| 7 | TREG | R | Ob | Thermal regulation <br> $\mathrm{Ob}=$ Charger is in normal operation. <br> $1 \mathrm{~b}=$ Charge current is reduced because of high chip temperature. |
| 6 | DPPM | R | Ob | DPPM active <br> $\mathrm{Ob}=$ DPPM loop is not active. <br> $1 \mathrm{~b}=$ DPPM loop is active; charge current is reduced to support the load with the current required. |
| 5 | TSUSP | R | 0b | Thermal suspend <br> $\mathrm{Ob}=$ Charging is allowed. <br> $1 \mathrm{~b}=$ Charging is temporarily suspended because battery temperature is out of range. |
| 4 | TERMI | R | Ob | Termination current detect <br> $\mathrm{Ob}=$ Charging, charge termination current threshold has not been crossed. <br> $1 \mathrm{~b}=$ Charge termination current threshold has been crossed and charging has been stopped. This can be from a battery reaching full capacity or to a battery removal condition. |
| 3 | ACTIVE | R | Ob | Charger active bit <br> $0 \mathrm{~b}=$ Charger is not charging. <br> $1 \mathrm{~b}=$ Charger is charging (DPPM or thermal regulation may be active). |
| 2 | CHGTOUT | R | 0b | Charge timer time-out <br> $\mathrm{Ob}=$ Charging, timers did not time out. <br> $1 \mathrm{~b}=$ One of the timers has timed out and charging has been terminated. |
| 1 | PCHGTOUT | R | Ob | Precharge timer time-out <br> $0 \mathrm{~b}=$ Charging, precharge timer did not time out. <br> $1 \mathrm{~b}=$ Precharge timer has timed out and charging has been terminated. |
| 0 | BATTEMP | R | Ob | Battery temperature and NTC error <br> NOTE: This bit does not indicate that the battery temperature is within the valid range for charging. <br> $0 \mathrm{~b}=$ Battery temperature is in the allowed range for charging. <br> $1 \mathrm{~b}=$ No temperature sensor detected or battery temperature outside valid charging range |

### 8.6.6 Charger Configuration Register 1 (CHGCONFIG1) (Address = 0x04) [reset = 0xB1]

CHGCONFIG1 is shown in Figure 34 and described in Table 6.
Return to Summary Table.
Figure 34. CHGCONFIG1 Register

| DATA BIT | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ | $\mathbf{0}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME | TIMER[1:0] |  | TMR_EN | NTC_TYPE | RESET | TERM | SUSP | CHG_EN |
| READ/WRITE | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| RESET VALUE | 1 b | 0 b | 1 b | 1 b | 0 b | 0 b | 0 b | 1 b |

Table 6. CHGCONFIG1 Register Field Descriptions

| Bit | Field | Type | Reset | Description |
| :---: | :---: | :---: | :---: | :---: |
| 7-6 | TIMER[1:0] | R/W | 10b | Charge safety timer setting (fast-charge timer) $\begin{aligned} & 00 b=4 h \\ & 01 b=5 h \\ & 10 b=6 h \\ & 11 b=8 h \end{aligned}$ |
| 5 | TMR_EN | R/W | 1b | Safety timer enable <br> $\mathrm{Ob}=$ Precharge timer and fast charge timer are disabled. <br> $1 \mathrm{~b}=$ Precharge timer and fast charge time are enabled. |
| 4 | NTC_TYPE | R/W | 1b | NTC type (for battery temperature measurement) $\begin{aligned} & 0 b=100 k \text { (curve } 1, B=3960) \\ & 1 b=10 k \text { (curve } 2, B=3480) \end{aligned}$ |
| 3 | RESET | R/W | Ob | Charger reset <br> $0 \mathrm{~b}=$ Inactive <br> $1 \mathrm{~b}=$ Reset active. This bit must be set and then reset via the serial interface to restart the charge algorithm. |
| 2 | TERM | R/W | Ob | Charge termination on-off <br> $\mathrm{Ob}=$ Charge termination enabled, based on timers and termination current <br> $1 \mathrm{~b}=$ Current-based charge termination does not occur and the charger is always on |
| 1 | SUSP | R/W | Ob | Suspend charge <br> $\mathrm{Ob}=$ Safety timer and precharge timers are not suspended. <br> $1 \mathrm{~b}=$ Safety timer and precharge timers are suspended. |
| 0 | CHG_EN | R/W | 1b | Charger enable $\mathrm{Ob}=$ Charger is disabled. <br> $1 \mathrm{~b}=$ Charger is enabled. |

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### 8.6.7 Charger Configuration Register 2 (CHGCONFIG2) (Address = 0x05) [reset = 0x80]

CHGCONFIG2 is shown in Figure 35 and described in Table 7.
Return to Summary Table.
Figure 35. CHGCONFIG2 Register

| DATA BIT | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ | $\mathbf{0}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME | DYNTMR | VPRECHG | VOREG $[1: 0]$ |  | Reserved | Reserved | Reserved | Reserved |
| READ/WRITE | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| RESET VALUE | 1 b | 0 b | 0 b | 0 b | 0 b | 0 b | 0 b | 0 b |

Table 7. CHGCONFIG2 Register Field Descriptions

| Bit | Field | Type | Reset | Description |
| :---: | :--- | :--- | :--- | :--- |
| 7 | DYNTMR | R/W | 1 b | Dynamic timer function <br> $0 \mathrm{~b}=$ Safety timers run with their nominal clock speed. <br> $1 \mathrm{~b}=$ Clock speed is divided by 2 if thermal loop or DPPM loop is <br> active. |
| 6 | VPRECHG | R/W | 0 b | Precharge voltage <br> $0 \mathrm{~b}=$ Precharge to fast-charge transition voltage is 2.9 V. <br> $1 \mathrm{~b}=$ Precharge to fast-charge transition voltage is 2.5 V. |
| $5-4$ | VOREG[1:0] | R/W | 00 b | Charge voltage selection <br> $00 \mathrm{~b}=4.1 \mathrm{~V}$ <br> $01 \mathrm{~b}=4.15 \mathrm{~V}$ <br> $10 \mathrm{~b}=4.2 \mathrm{~V}$ <br> $11 \mathrm{~b}=4.2 \mathrm{~V}$ |
| $3-0$ | Reserved |  | R/W | 0000 b |

### 8.6.8 Charger Configuration Register 3 (CHGCONFIG3) (Address = 0x06) [reset = 0xB2]

CHGCONFIG3 is shown in Figure 36 and described in Table 8.
Return to Summary Table.
Figure 36. CHGCONFIG3 Register

| DATA BIT | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME | ICHRG[1:0] |  | DPPMTH[1:0] |  | PCHRGT | TERMIF[1:0] |  | TRANGE |
| READ/WRITE | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| RESET VALUE | 1 b | 0b | 1 b | 1 b | Ob | 0b | 1b | 0b |

Table 8. CHGCONFIG3 Register Field Descriptions

| Bit | Field | Type | Reset | Description |
| :---: | :--- | :--- | :--- | :--- |
| $7-6$ | ICHRG[1:0] | R/W | 10 b | Charge current setting <br> $00 \mathrm{~b}=300 \mathrm{~mA}$ <br> $01 \mathrm{~b}=400 \mathrm{~mA}$ <br> $10 \mathrm{~b}=500 \mathrm{~mA}$ |
|  |  |  |  |  |
| $5-4$ | DPPMTH[1:0] |  |  |  |

### 8.6.9 WLED Control Register 1 (WLEDCTRL1) (Address $=0 \times 07$ ) [reset $=0 \times B 1$ ]

WLEDCTRL1 is shown in Figure 37 and described in Table 9.
Return to Summary Table.
Figure 37. WLEDCTRL1 Register

| DATA BIT | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ | $\mathbf{0}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME | Reserved | Reserved | Reserved | Reserved | ISINK_EN | ISEL | FDIM[1:0] |  |
| READ/WRITE | R | R | R | R | $R / W$ | $R / W$ | $R / W$ | $R / W$ |
| RESET VALUE | 0 b | 0 b | 0 b | 0 b | 0 b | 0 b | 0 b | 1 b |

Table 9. WLEDCTRL1 Register Field Descriptions

| Bit | Field | Type | Reset | Description |
| :---: | :---: | :---: | :---: | :---: |
| 7-4 | Reserved | R | 0000b | These bits are reserved |
| 3 | ISINK_EN | R/W | 0b | Current sink enable <br> NOTE: This bit enables both current sinks. <br> $\mathrm{Ob}=$ Current sink is disabled (OFF). <br> $1 \mathrm{~b}=$ Current sink is enabled (ON). |
| 2 | ISEL | R/W | Ob | ISET selection bit <br> Ob = Low-level (define by ISET1 pin) <br> 1b = High-level (defined by ISET2 pin) |
| 1-0 | FDIM[1:0] | R/W | 01b | PWM dimming frequency $\begin{aligned} & 00 \mathrm{~b}=100 \mathrm{~Hz} \\ & 01 \mathrm{~b}=200 \mathrm{~Hz} \\ & 10 \mathrm{~b}=500 \mathrm{~Hz} \\ & 11 \mathrm{~b}=1000 \mathrm{~Hz} \end{aligned}$ |

8.6.10 WLED Control Register 2 (WLEDCTRL2) (Address $=0 \times 08$ ) [reset $=0 \times 00$ ]

WLEDCTRL2 is shown in Figure 38 and described in Table 10.
Return to Summary Table.
Figure 38. WLEDCTRL2 Register

| DATA BIT | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME | Reserved | DUTY[6:0] |  |  |  |  |  |  |
| READ/WRITE | R | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| RESET VALUE | 0b | 0b | 0b | 0b | 0b | Ob | 0b | 0b |

Table 10. WLEDCTRL2 Register Field Descriptions

| Bit | Field | Type | Reset | Description |
| :---: | :---: | :---: | :---: | :---: |
| 7 | Reserved | R | 0b | This bit is reserved |
| 6-0 | DUTY[6:0] | R/W | 0000000b | PWM dimming duty cycle $\begin{aligned} & 000 \text { 0000b }=1 \% \\ & 0000001 b=2 \% \end{aligned}$ $\begin{aligned} & 1100010 b=99 \% \\ & 1100011 b=100 \% \\ & 1100100 b=0 \% \end{aligned}$ <br> $1111110 b=0 \%$ $1111111 b=0 \%$ |

### 8.6.11 MUX Control Register (MUXCTRL) (Address = 0x09) [reset = 0x00]

MUXCTRL is shown in Figure 39 and described in Table 11.
Return to Summary Table.
Figure 39. MUXCTRL Register

| DATA BIT | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{c \|} \mathbf{1}$ | $\mathbf{0}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME | Reserved | Reserved | Reserved | Reserved | Reserved | MUX[2:0] |  |  |
| READ/WRITE | R | R | R | R | R | $\mathrm{R} / \mathrm{W}$ | $\mathrm{R} / \mathrm{W}$ | $\mathrm{R} / \mathrm{W}$ |
| RESET VALUE | 0 b | 0 b | 0 b | 0 b | 0 b | 0 b | 0 b | 0 b |

Table 11. MUXCTRL Register Field Descriptions

| Bit | Field | Type | Reset | Description |
| :---: | :---: | :---: | :---: | :---: |
| 7-3 | Reserved | R | 00000b | These bits are reserved |
| 2-0 | MUX[2:0] | R/W | 000b | $\begin{aligned} & \text { Analog multiplexer selection } \\ & 000 \mathrm{~b}=\text { MUX is disabled, output is Hi-Z. } \\ & 001 \mathrm{l}=\text { VBAT } \\ & 010 \mathrm{~b}=\text { VSYS } \\ & 011 \mathrm{~b}=\text { VTS } \\ & 100 \mathrm{~b}=\text { VICHARGE } \\ & 101 \mathrm{l}=\text { MUX_IN (external input) } \\ & 110 \mathrm{~b}=\text { MUX is disabled, output is Hi-Z. } \\ & 111 \mathrm{~b}=\text { MUX is disabled, output is Hi-Z. } \end{aligned}$ |

### 8.6.12 Status Register (STATUS) (Address $=0 \times 0 \mathrm{~A})$ [reset $=0 \times 00$ ]

STATUS is shown in Figure 40 and described in Table 12.
Return to Summary Table.
Figure 40. STATUS Register

| DATA BIT | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ | $\mathbf{0}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME | OFF | Reserved | Reserved | Reserved | ACPWR | USBPWR | Reserved | PB |
| READ/WRITE | $\mathrm{R} / \mathrm{W}$ | R | R | R | R | R | R | R |
| RESET VALUE | 0 b | 0 b | 0 b | 0 b | 0 b | 0 b | 0 b | 0 b |

Table 12. STATUS Register Field Descriptions

| Bit | Field | Type | Reset | Description |
| :---: | :--- | :--- | :--- | :--- |
| 7 | OFF | R/W | Ob | OFF bit. Set this bit to 1 b to enter the OFF state when PWR_EN <br> pin is pulled low. The bit is automatically reset to Ob. |
| $6-4$ | Reserved | R | 000b | These bits are reserved |

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### 8.6.13 Password Register (PASSWORD) (Address = 0x0B) [reset = 0x00]

PASSWORD is shown in Figure 41 and described in Table 13.
Return to Summary Table.
Figure 41. PASSWORD Register

| DATA BIT | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ | $\mathbf{0}$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME |  |  |  |  |  |  |  |  |  |  |  |
| READ/WRITE | $\mathrm{R} / \mathrm{W}$ | $\mathrm{R} / \mathrm{W}$ | $\mathrm{R} / \mathrm{W}$ | $\mathrm{R} / \mathrm{W}$ | $\mathrm{R} / \mathrm{W}$ | $\mathrm{R} / \mathrm{W}$ | $\mathrm{R} / \mathrm{W}$ | $\mathrm{R} / \mathrm{W}$ |  |  |  |
| RESET VALUE | 0 b | 0 b | 0 b | 0 b | 0 b | 0 b | 0 b | 0 b |  |  |  |

Table 13. Password Register (PASSWORD) Field Descriptions

| Bit | Field | Type | Reset | Description |
| :---: | :---: | :---: | :---: | :---: |
| 7-0 | PWRD[7:0] | R/W | 00000000b | Password protection locking and unlocking <br> NOTE: Register is automatically reset to $0 \times 00$ after the following $I^{2} \mathrm{C}$ transaction. See the Password Protection section for details. <br> 0000 0000b = Password-protected registers are locked for write access. <br> 0111 1100b = Password-protected registers are locked for write access. <br> 0111 1101b = Allows writing to a password-protected register in the next write cycle <br> 0111 1110b = Password-protected registers are locked for write access. <br> 1111 1111b = Password-protected registers are locked for write access. |

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### 8.6.14 Power Good Register (PGOOD) (Address = 0x0C) [reset = 0x00]

PGOOD is shown in Figure 42 and described in Table 14.
Return to Summary Table.
Figure 42. PGOOD Register

| DATA BIT | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ | $\mathbf{0}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME | Reserved | LDO3_PG | LDO4_PG | DC1_PG | DC2_PG | DC3_PG | LDO1_PG | LDO2_PG |
| READ/WRITE | R | R | R | R | R | R | R | R |
| RESET VALUE | 0 b | 0 b | 0 b | 0 b | 0 b | 0 b | 0 b | 0 b |

Table 14. PGOOD Register Field Descriptions

| Bit | Field | Type | Reset |  |
| :---: | :--- | :--- | :--- | :--- |
| 7 | Reserved | R | Ob | This bit is reserved |

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### 8.6.15 Power-Good Control Register (DEFPG) (Address = 0x0D) [reset = 0x0C]

DEFPG is shown in Figure 43 and described in Table 15.
Return to Summary Table.
This register is password protected.
Figure 43. DEFPG Register

| DATA BIT | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ | $\mathbf{0}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME | Reserved | Reserved | Reserved | Reserved | LDO1PGM | LDO2PGM | PGDLY[1:0] |  |
| READ/WRITE | R | R | R | R | $\mathrm{R} / \mathrm{W}$ | $\mathrm{R} / \mathrm{W}$ | R/W | R/W |
| RESET VALUE | 0 b | 0 b | 0 b | 0 b | 1 b | 1 b | 0 b | 0 b |

Table 15. DEFPG Register Field Descriptions

| Bit | Field | Type | Reset | Description |
| :---: | :--- | :--- | :--- | :--- |
| $7-4$ | Reserved | R | 0000b | These bits are reserved |

### 8.6.16 DCDC1 Control Register (DEFDCDC1) (Address = 0x0E) [reset = X]

DEFDCDC1 is shown in Figure 44 and described in Table 16.
Return to Summary Table.
This register is password protected.
Figure 44. DEFDCDC1 Register

| DATA BIT |  | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME |  | XADJ1 | Reserved | DCDC1[5:0] |  |  |  |  |  |
| READ/WRITE |  | R/W | R | R/W | R/W | R/W | R/W | R/W | R/W |
| RESET <br> VALUE | TPS65217A | Ob | 0b | Ob | 1b | 1b | 1b | 1b | Ob |
|  | TPS65217B | 0b | 0b | 0b | 1b | 1 b | 1b | 1b | 0b |
|  | TPS65217C | Ob | 0b | Ob | 1b | 1b | Ob | Ob | 0b |
|  | TPS65217D | Ob | Ob | Ob | 1b | 0b | Ob | 1b | 0b |

Table 16. DEFDCDC1 Register Field Descriptions

| Bit | Field | Type | Reset | Description |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 7 | XADJ1 | R/W | 0b | DCDC1 voltage adjustment option <br> $\mathrm{Ob}=$ Output voltage is adjusted through the register setting. <br> $1 \mathrm{~b}=$ Output voltage is externally adjusted. |  |  |  |
| 6 | Reserved | R | 0b | This bit is reserved |  |  |  |
| 5-0 | DCDC1[5:0] | R/W | $\begin{array}{\|l} \text { TPS65217A: } 01 \\ 1110 \mathrm{~b} \end{array}$ | DCDC1 output-voltage setting |  |  |  |
|  |  |  | TPS65217B: 01 1110b TPS65217C: 01 1000b TPS65217D: 01 0010b | $000000 \mathrm{~b}=0.9 \mathrm{~V}$ $000001 \mathrm{~b}=0.925$ V $000010 \mathrm{~b}=0.95 \mathrm{~V}$ $000011 \mathrm{~b}=0.975$ V $000100 \mathrm{~b}=1 \mathrm{~V}$ $000101 \mathrm{~b}=1.025$ V $000110 \mathrm{~b}=1.05 \mathrm{~V}$ $00011 \mathrm{~b}=1.075$ V $001000 \mathrm{~b}=1.1 \mathrm{~V}$ $001001 \mathrm{~b}=1.125$ V $001010 \mathrm{~b}=1.15 \mathrm{~V}$ $001011 \mathrm{~b}=1.175$ V $001100 \mathrm{~b}=1.2 \mathrm{~V}$ 00 V V $001101 \mathrm{~b}=1.225$ 00 V V | $010000 \mathrm{~b}=1.3 \mathrm{~V}$ $010001 \mathrm{~b}=1.325$ V $010010 \mathrm{~b}=1.35 \mathrm{~V}$ $010011 \mathrm{~b}=1.375$ V $010100 \mathrm{~b}=1.4 \mathrm{~V}$ $010101 \mathrm{~b}=1.425$ V $010110 \mathrm{~b}=1.45 \mathrm{~V}$ $010111 \mathrm{~b}=1.475$ V $011000 \mathrm{~b}=1.5 \mathrm{~V}$ $011001 \mathrm{~b}=1.55 \mathrm{~V}$ $011010 \mathrm{~b}=1.6 \mathrm{~V}$ $011011 \mathrm{~b}=1.65 \mathrm{~V}$ $011100 \mathrm{~b}=1.7 \mathrm{~V}$ $011101 \mathrm{~b}=1.75 \mathrm{~V}$ $011110 \mathrm{~b}=1.80 \mathrm{~V}$ $011111 \mathrm{~b}=1.85 \mathrm{~V}$ | $\begin{aligned} & 100000 \mathrm{~b}=1.9 \mathrm{~V} \\ & 100001 \mathrm{~b}=1.95 \mathrm{~V} \\ & 100010 \mathrm{~b}=2 \mathrm{~V} \\ & 100011 \mathrm{~b}=2.05 \mathrm{~V} \\ & 100100 \mathrm{~b}=2.1 \mathrm{~V} \\ & 100101 \mathrm{~b}=2.15 \mathrm{~V} \\ & 100110 \mathrm{~b}=2.2 \mathrm{~V} \\ & 100111 \mathrm{~b}=2.25 \mathrm{~V} \\ & 101000 \mathrm{~b}=2.3 \mathrm{~V} \\ & 101001 \mathrm{~b}=2.35 \mathrm{~V} \\ & 101010 \mathrm{~b}=2.4 \mathrm{~V} \\ & 101011 \mathrm{~b}=2.45 \mathrm{~V} \\ & 101100 \mathrm{~b}=2.5 \mathrm{~V} \\ & 101101 \mathrm{~b}=2.55 \mathrm{~V} \\ & 101110 \mathrm{~b}=2.6 \mathrm{~V} \\ & 101111 \mathrm{~b}=2.65 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 110000 \mathrm{~b}=2.7 \mathrm{~V} \\ & 110001 \mathrm{~b}=2.75 \mathrm{~V} \\ & 110010 \mathrm{~b}=2.8 \mathrm{~V} \\ & 110011 \mathrm{~b}=2.85 \mathrm{~V} \\ & 110100 \mathrm{~b}=2.9 \mathrm{~V} \\ & 110101 \mathrm{~b}=3 \mathrm{~V} \\ & 110110 \mathrm{~b}=3.1 \mathrm{~V} \\ & 110111 \mathrm{~b}=3.2 \mathrm{~V} \\ & 111000 \mathrm{~b}=3.3 \mathrm{~V} \\ & 111001 \mathrm{~b}=3.3 \mathrm{~V} \\ & 111010 \mathrm{~b}=3.3 \mathrm{~V} \\ & 111011 \mathrm{~b}=3.3 \mathrm{~V} \\ & 111100 \mathrm{~b}=3.3 \mathrm{~V} \\ & 111101 \mathrm{~b}=3.3 \mathrm{~V} \\ & 111110 \mathrm{~b}=3.3 \mathrm{~V} \\ & 11111 \mathrm{~b}=3.3 \mathrm{~V} \end{aligned}$ |

### 8.6.17 DCDC2 Control Register (DEFDCDC2) (Address = 0x0F) [reset = X]

DEFDCDC2 is shown in Figure 45 and described in Table 17.
Return to Summary Table.
This register is password protected.
Figure 45. DEFDCDC2 Register

| DATA BIT |  | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME |  | XADJ2 | Reserved | DCDC2[5:0] |  |  |  |  |  |
| READ/WRITE |  | R/W | R | R/W | R/W | R/W | R/W | R/W | R/W |
| RESET VALUE | TPS65217A | Ob | Ob | 1b | 1b | 1b | Ob | Ob | Ob |
|  | TPS65217B | Ob | Ob | Ob | Ob | 1b | Ob | Ob | Ob |
|  | TPS65217C | Ob | Ob | Ob | Ob | 1 b | Ob | Ob | Ob |
|  | TPS65217D | Ob | Ob | Ob | Ob | 1 b | Ob | Ob | Ob |

Table 17. DEFDCDC2 Register Field Descriptions

| Bit | Field | Type | Reset | Description |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 7 | XADJ2 | R/W | 0b | DCDC2 voltage adjustment option <br> $\mathrm{Ob}=$ Output voltage is adjusted through the register setting. <br> $1 \mathrm{~b}=$ Output voltage is externally adjusted. |  |  |  |
| 6 | Reserved | R | 0b | This bit is reserved |  |  |  |
| 5-0 | DCDC2[5:0] | R/W | $\begin{aligned} & \text { TPS65217A: } 11 \\ & \text { 1000b } \end{aligned}$ | DCDC2 output voltage setting |  |  |  |
|  |  |  | TPS65217B: 00 1000b TPS65217C: 00 1000b TPS65217D: 00 1000b | $000000 \mathrm{~b}=0.9 \mathrm{~V}$ $00 \quad 0001 \mathrm{~b}=0.925$ V $000010 \mathrm{~b}=0.950 \mathrm{~V}$ $000011 \mathrm{~b}=0.975$ V $000100 \mathrm{~b}=1 \mathrm{~V}$ $00 \quad 0101 \mathrm{~b}=1.025$ V $00 \quad 0110 \mathrm{~b}=1.05 \mathrm{~V}$ $00 \quad 0111 \mathrm{~b}=1.075$ V $001000 \mathrm{~b}=1.1 \mathrm{~V}$ $001001 \mathrm{~b}=1.125$ V $001010 \mathrm{~b}=1.15 \mathrm{~V}$ $00 \quad 1011 \mathrm{~b}=1.175$ V $001100 \mathrm{~b}=1.2 \mathrm{~V}$ $00 \quad 1101 \mathrm{~b}=1.225$ V $001110 \mathrm{~b}=1.25 \mathrm{~V}$ $00 \quad 1111 \mathrm{~b}=1.275$ V | $010000 \mathrm{~b}=1.3 \mathrm{~V}$ $01 \quad 0001 \mathrm{~b}=1.325$ V $010010 \mathrm{~b}=1.35 \mathrm{~V}$ $01 \quad 0011 \mathrm{~b}=1.375$ V $010100 \mathrm{~b}=1.4 \mathrm{~V}$ $01 \quad 0101 \mathrm{~b}=1.425$ V $010110 \mathrm{~b}=1.45 \mathrm{~V}$ $01 \quad 011 \mathrm{~b}=1.475$ V $011000 \mathrm{~b}=1.5 \mathrm{~V}$ $011001 \mathrm{~b}=1.55 \mathrm{~V}$ $011010 \mathrm{~b}=1.6 \mathrm{~V}$ $011011 \mathrm{~b}=1.65 \mathrm{~V}$ $011100 \mathrm{~b}=1.7 \mathrm{~V}$ $011101 \mathrm{~b}=1.75 \mathrm{~V}$ $011110 \mathrm{~b}=1.8 \mathrm{~V}$ $011111 \mathrm{~b}=1.85 \mathrm{~V}$ | $\begin{aligned} & 100000 \mathrm{~b}=1.9 \mathrm{~V} \\ & 100001 \mathrm{~b}=1.95 \mathrm{~V} \\ & 100010 \mathrm{~b}=2 \mathrm{~V} \\ & 100011 \mathrm{~b}=2.05 \mathrm{~V} \\ & 100100 \mathrm{~b}=2.1 \mathrm{~V} \\ & 100101 \mathrm{~b}=2.15 \mathrm{~V} \\ & 100110 \mathrm{~b}=2.2 \mathrm{~V} \\ & 100111 \mathrm{~b}=2.25 \mathrm{~V} \\ & 10 \mathrm{1000b}=2.3 \mathrm{~V} \\ & 101001 \mathrm{~b}=2.35 \mathrm{~V} \\ & 10 \mathrm{1010b}=2.4 \mathrm{~V} \\ & 10 \text { 1011b}=2.45 \mathrm{~V} \\ & 101100 \mathrm{~b}=2.5 \mathrm{~V} \\ & 10 \mathrm{1101b}=2.55 \mathrm{~V} \\ & 101110 \mathrm{~b}=2.6 \mathrm{~V} \\ & 10111 \mathrm{~b}=2.65 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 110000 \mathrm{~b}=2.7 \mathrm{~V} \\ & 110001 \mathrm{~b}=2.75 \mathrm{~V} \\ & 110010 \mathrm{~b}=2.8 \mathrm{~V} \\ & 110011 \mathrm{~b}=2.85 \mathrm{~V} \\ & 110100 \mathrm{~b}=2.9 \mathrm{~V} \\ & 110101 \mathrm{~b}=3 \mathrm{~V} \\ & 110110 \mathrm{~b}=3.1 \mathrm{~V} \\ & 110111 \mathrm{~b}=3.2 \mathrm{~V} \\ & 111000 \mathrm{~b}=3.3 \mathrm{~V} \\ & 111001 \mathrm{~b}=3.3 \mathrm{~V} \\ & 111010 \mathrm{~b}=3.3 \mathrm{~V} \\ & 111011 \mathrm{~b}=3.3 \mathrm{~V} \\ & 111100 \mathrm{~b}=3.3 \mathrm{~V} \\ & 111101 \mathrm{~b}=3.3 \mathrm{~V} \\ & 111110 \mathrm{~b}=3.3 \mathrm{~V} \\ & 111111 \mathrm{~b}=3.3 \mathrm{~V} \end{aligned}$ |

### 8.6.18 DCDC3 Control Register (DEFDCDC3) (Address = 0x10) [reset = 0x08]

DEFDCDC3 is shown in Figure 46 and described in Table 18.
Return to Summary Table.
This register is password protected.
Figure 46. DEFDCDC3 Register

| DATA BIT | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME | XADJ3 | Reserved | DCDC3[5:0] |  |  |  |  |  |
| READ/WRITE | R/W | R | R/W | R/W | R/W | R/W | R/W | R/W |
| RESET VALUE | Ob | Ob | 0b | Ob | 1b | Ob | Ob | Ob |

Table 18. DEFDCDC3 Register Field Descriptions

| Bit | Field | Type | Reset | Description |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 7 | XADJ3 | R/W | 0b | DCDC3 voltage adjustment option <br> $\mathrm{Ob}=$ Output voltage is adjusted through register setting <br> $1 \mathrm{~b}=$ Output voltage is externally adjusted |  |  |  |
| 6 | Reserved | R | 0b | This bit is reserved |  |  |  |
| 5-0 | DCDC3[5:0] | R/W | 00 1000b | DCDC3 output voltage setting |  |  |  |
|  |  |  |  | $\begin{aligned} & 000000 \mathrm{~b}=0.9 \mathrm{~V} \\ & 000001 \mathrm{~b}=0.925 \mathrm{~V} \\ & 000010 \mathrm{~b}=0.95 \mathrm{~V} \\ & 000011 \mathrm{~b}=0.975 \mathrm{~V} \\ & 000100 \mathrm{~b}=1 \mathrm{~V} \\ & 000101 \mathrm{~b}=1.025 \mathrm{~V} \\ & 000110 \mathrm{~b}=1.05 \mathrm{~V} \\ & 000111 \mathrm{~b}=1.075 \mathrm{~V} \\ & 001000 \mathrm{~b}=1.1 \mathrm{~V} \\ & 001001 \mathrm{~b}=1.125 \mathrm{~V} \\ & 001010 \mathrm{~b}=1.15 \mathrm{~V} \\ & 001011 \mathrm{~b}=1.175 \mathrm{~V} \\ & 001100 \mathrm{~b}=1.2 \mathrm{~V} \\ & 001101 \mathrm{~b}=1.225 \mathrm{~V} \\ & 001110 \mathrm{~b}=1.25 \mathrm{~V} \\ & 001111 \mathrm{~b}=1.275 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 010000 \mathrm{~b}=1.3 \mathrm{~V} \\ & 010001 \mathrm{~b}=1.325 \mathrm{~V} \\ & 010010 \mathrm{~b}=1.35 \mathrm{~V} \\ & 010011 \mathrm{~b}=1.375 \mathrm{~V} \\ & 010100 \mathrm{~b}=1.4 \mathrm{~V} \\ & 010101 \mathrm{~b}=1.425 \mathrm{~V} \\ & 010110 \mathrm{~b}=1.45 \mathrm{~V} \\ & 010111 \mathrm{~b}=1.475 \mathrm{~V} \\ & 011000 \mathrm{~b}=1.5 \mathrm{~V} \\ & 011001 \mathrm{~b}=1.55 \mathrm{~V} \\ & 011010 \mathrm{~b}=1.6 \mathrm{~V} \\ & 011011 \mathrm{~b}=1.65 \mathrm{~V} \\ & 011100 \mathrm{~b}=1.7 \mathrm{~V} \\ & 011101 \mathrm{~b}=1.75 \mathrm{~V} \\ & 011110 \mathrm{~b}=1.8 \mathrm{~V} \\ & 011111 \mathrm{~b}=1.85 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 100000 \mathrm{~b}=1.9 \mathrm{~V} \\ & 100001 \mathrm{~b}=1.95 \mathrm{~V} \\ & 100010 \mathrm{~b}=2 \mathrm{~V} \\ & 100011 \mathrm{~b}=2.05 \mathrm{~V} \\ & 100100 \mathrm{~b}=2.1 \mathrm{~V} \\ & 100101 \mathrm{~b}=2.15 \mathrm{~V} \\ & 100110 \mathrm{~b}=2.2 \mathrm{~V} \\ & 100111 \mathrm{~b}=2.25 \mathrm{~V} \\ & 101000 \mathrm{~b}=2.30 \mathrm{~V} \\ & 101001 \mathrm{~b}=2.35 \mathrm{~V} \\ & 101010 \mathrm{~b}=2.4 \mathrm{~V} \\ & 101011 \mathrm{~b}=2.45 \mathrm{~V} \\ & 101100 \mathrm{~b}=2.5 \mathrm{~V} \\ & 101101 \mathrm{~b}=2.55 \mathrm{~V} \\ & 101110 \mathrm{~b}=2.6 \mathrm{~V} \\ & 101111 \mathrm{~b}=2.65 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 110000 \mathrm{~b}=2.7 \mathrm{~V} \\ & 110001 \mathrm{~b}=2.75 \mathrm{~V} \\ & 110010 \mathrm{~b}=2.8 \mathrm{~V} \\ & 110011 \mathrm{~b}=2.85 \mathrm{~V} \\ & 110100 \mathrm{~b}=2.9 \mathrm{~V} \\ & 110101 \mathrm{~b}=3 \mathrm{~V} \\ & 110110 \mathrm{~b}=3.1 \mathrm{~V} \\ & 110111 \mathrm{~b}=3.2 \mathrm{~V} \\ & 111000 \mathrm{~b}=3.3 \mathrm{~V} \\ & 111001 \mathrm{~b}=3.3 \mathrm{~V} \\ & 111010 \mathrm{~b}=3.3 \mathrm{~V} \\ & 111011 \mathrm{~b}=3.3 \mathrm{~V} \\ & 111100 \mathrm{~b}=3.3 \mathrm{~V} \\ & 111101 \mathrm{~b}=3.3 \mathrm{~V} \\ & 11110 \mathrm{~b}=3.3 \mathrm{~V} \\ & 111111 \mathrm{~b}=3.3 \mathrm{~V} \end{aligned}$ |

### 8.6.19 Slew-Rate Control Register (DEFSLEW) (Address = 0x11) [reset = 0x06]

DEFSLEW is shown in Figure 47 and described in Table 19.
Return to Summary Table.
Slew-rate control applies to all three DC/DC converters.
This register is password protected.
Figure 47. DEFSLEW Register

| DATA BIT | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME | GO | GODSBL | PFM_EN1 | PFM_EN2 | PFM_EN3 | SLEW[2:0] |  |  |
| READ/WRITE | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| RESET VALUE | Ob | Ob | Ob | Ob | Ob | 1b | 1b | Ob |

Table 19. DEFSLEW Register Field Descriptions

| Bit | Field | Type | Reset | Description |
| :---: | :---: | :---: | :---: | :---: |
| 7 | GO | R/W | Ob | Go bit <br> NOTE: Bit is automatically reset at the end of the voltage transition. <br> $0 \mathrm{~b}=$ No change <br> $1 \mathrm{~b}=$ Initiates the transition from the present state to the output voltage setting currently stored in the DEFDCDCx register |
| 6 | GODSBL | R/W | Ob | Go Disable bit <br> Ob = Enabled <br> 1b = Disabled; DCDCx output voltage changes whenever setpoint is updated in DEFDCDCx register without having to write to the GO bit. SLEW[2:0] setting does apply. |
| 5 | PFM_EN1 | R/W | Ob | PFM enable bit, DCDC1 <br> $\mathrm{Ob}=\mathrm{DC} / \mathrm{DC}$ converter operates in the PWM or PFM mode, depending on load. <br> $1 \mathrm{~b}=\mathrm{DC} / \mathrm{DC}$ converter is forced into the fixed-frequency PWM mode. |
| 4 | PFM_EN2 | R/W | Ob | PFM enable bit, DCDC2 <br> Ob = DC/DC converter operates in the PWM or PFM mode, depending on load. <br> $1 \mathrm{~b}=\mathrm{DC} / \mathrm{DC}$ converter is forced into the fixed-frequency PWM mode. |
| 3 | PFM_EN3 | R/W | Ob | PFM enable bit, DCDC3 <br> Ob = DC/DC converter operates in the PWM or PFM mode, depending on load. <br> $1 \mathrm{~b}=\mathrm{DC} / \mathrm{DC}$ converter is forced into the fixed-frequency PWM mode. |
| 2-0 | SLEW[2:0] | R/W | 0110b | Output slew-rate setting <br> NOTE: The actual slew rate depends on the voltage step per code. See the DCDC1 and DCDC2 registers for details. <br> $000 \mathrm{~b}=224 \mu \mathrm{~s} / \mathrm{step}(0.11 \mathrm{mV} / \mu \mathrm{s}$ at 25 mV per step) <br> $001 \mathrm{~b}=112 \mu \mathrm{~s} / \mathrm{step}(0.22 \mathrm{mV} / \mu \mathrm{s}$ at 25 mV per step) <br> $010 \mathrm{~b}=56 \mu \mathrm{~s} / \mathrm{step}(0.45 \mathrm{mV} / \mu \mathrm{s}$ at 25 mV per step) <br> $011 \mathrm{~b}=28 \mu \mathrm{~s} /$ step $(0.90 \mathrm{mV} / \mu \mathrm{s}$ at 25 mV per step) <br> $100 \mathrm{~b}=14 \mu \mathrm{~s} /$ step $(1.80 \mathrm{mV} / \mu \mathrm{s}$ at 25 mV per step) <br> $101 \mathrm{~b}=7 \mu \mathrm{~s} / \mathrm{step}(3.60 \mathrm{mV} / \mu \mathrm{s}$ at 25 mV per step) <br> $110 \mathrm{~b}=3.5 \mu \mathrm{~s} / \mathrm{step}(7.2 \mathrm{mV} / \mu \mathrm{s}$ at 25 mV per step) <br> $111 \mathrm{~b}=$ Immediate; slew rate is only limited by the control loop response time. |

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### 8.6.20 LDO1 Control Register (DEFLDO1) (Address $=0 \times 12$ ) [reset $=0 \times 09$ ]

DEFLDO1 is shown in Figure 48 and described in Table 20.
Return to Summary Table.
This register is password protected.
Figure 48. DEFLDO1 Register

| DATA BIT | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ | $\mathbf{0}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME | Reserved | Reserved | Reserved | Reserved |  | LDO1[3:0] |  |  |
| READ/WRITE | R | R | R | R | $\mathrm{R} / \mathrm{W}$ | $\mathrm{R} / \mathrm{W}$ | $\mathrm{R} / \mathrm{W}$ | $\mathrm{R} / \mathrm{W}$ |
| RESET VALUE | 0 b | 0 b | 0 b | 0 b | 1 b | 0 b | 0 b | 1 b |

Table 20. DEFLDO1 Register Field Descriptions

| Bit | Field | Type | Reset | Description |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 7-4 | Reserved | R | 0000b | These bits are reserved |  |
| 3-0 | LDO1[3:0] | R/W | 1001b | LDO1 output voltage setting |  |
|  |  |  |  | $\begin{aligned} & 0000 \mathrm{~b}=1 \mathrm{~V} \\ & 0001 \mathrm{~b}=1.1 \mathrm{~V} \\ & 0010 \mathrm{~b}=1.2 \mathrm{~V} \\ & 0011 \mathrm{~b}=1.25 \mathrm{~V} \\ & 0100 \mathrm{~b}=1.3 \mathrm{~V} \\ & 0101 \mathrm{~b}=1.35 \mathrm{~V} \\ & 0110 \mathrm{~b}=1.4 \mathrm{~V} \\ & 0111 \mathrm{~b}=1.5 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 1000 \mathrm{~b}=1.6 \mathrm{~V} \\ & 1001 \mathrm{~b}=1.8 \mathrm{~V} \\ & 1010 \mathrm{~b}=2.5 \mathrm{~V} \\ & 1011 \mathrm{~b}=2.75 \mathrm{~V} \\ & 1100 \mathrm{~b}=2.8 \mathrm{~V} \\ & 1101 \mathrm{~b}=3 \mathrm{~V} \\ & 1110 \mathrm{~b}=3.1 \mathrm{~V} \\ & 1111 \mathrm{~b}=3.3 \mathrm{~V} \end{aligned}$ |

### 8.6.21 LDO2 Control Register (DEFLDO2) (Address = 0x13) [reset = 0x38]

DEFLDO2 is shown in Figure 49 and described in Table 21.
Return to Summary Table.
This register is password protected.
Figure 49. DEFLDO2 Register

| DATA BIT | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME | Reserved | TRACK | LDO2[5:0] |  |  |  |  |  |
| READ/WRITE | R | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| RESET VALUE | 0b | 0b | 1 b | 1 b | 1 b | 0b | Ob | 0b |

Table 21. DEFLDO2 Register Field Descriptions

| Bit | Field | Type | Reset | Description |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 7 | Reserved | R | 0b | This bit is reserved |  |  |  |
| 6 | TRACK | R/W | Ob | LDO2 tracking bit <br> $0 \mathrm{~b}=$ Output voltage is defined by the LDO2[5:0] bits. <br> $1 \mathrm{~b}=$ Output voltage follows the DCDC3 voltage setting (DEFDCDC3 register). |  |  |  |
| 5-0 | LDO2[5:0] | R/W | 11 1000b | LDO2 output voltage setting |  |  |  |
|  |  |  |  | $\begin{aligned} & 000000 \mathrm{~b}=0.9 \mathrm{~V} \\ & 000001 \mathrm{~b}=0.925 \mathrm{~V} \\ & 000010 \mathrm{~b}=0.95 \mathrm{~V} \\ & 000011 \mathrm{~b}=0.975 \mathrm{~V} \\ & 000100 \mathrm{~b}=1 \mathrm{~V} \\ & 000101 \mathrm{~b}=1.025 \mathrm{~V} \\ & 000110 \mathrm{~b}=1.05 \mathrm{~V} \\ & 000111 \mathrm{~b}=1.075 \mathrm{~V} \\ & 001000 \mathrm{~b}=1.1 \mathrm{~V} \\ & 001001 \mathrm{~b}=1.125 \mathrm{~V} \\ & 001010 \mathrm{~b}=1.15 \mathrm{~V} \\ & 001011 \mathrm{~b}=1.175 \mathrm{~V} \\ & 001100 \mathrm{~b}=1.2 \mathrm{~V} \\ & 001101 \mathrm{~b}=1.225 \mathrm{~V} \\ & 001110 \mathrm{~b}=1.25 \mathrm{~V} \\ & 001111 \mathrm{~b}=1.275 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 010000 \mathrm{~b}=1.3 \mathrm{~V} \\ & 010001 \mathrm{~b}=1.325 \mathrm{~V} \\ & 010010 \mathrm{~b}=1.35 \mathrm{~V} \\ & 010011 \mathrm{~b}=1.375 \mathrm{~V} \\ & 010100 \mathrm{~b}=1.4 \mathrm{~V} \\ & 010101 \mathrm{~b}=1.425 \mathrm{~V} \\ & 010110 \mathrm{~b}=1.45 \mathrm{~V} \\ & 01011 \mathrm{~b}=1.475 \mathrm{~V} \\ & 011000 \mathrm{~b}=1.5 \mathrm{~V} \\ & 011001 \mathrm{~b}=1.55 \mathrm{~V} \\ & 011010 \mathrm{~b}=1.60 \mathrm{~V} \\ & 01101 \mathrm{~b}=1.65 \mathrm{~V} \\ & 011100 \mathrm{~b}=1.7 \mathrm{~V} \\ & 011101 \mathrm{~b}=1.75 \mathrm{~V} \\ & 011110 \mathrm{~b}=1.8 \mathrm{~V} \\ & 01111 \mathrm{~b}=1.85 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 100000 \mathrm{~b}=1.9 \mathrm{~V} \\ & 100001 \mathrm{~b}=1.95 \mathrm{~V} \\ & 100010 \mathrm{~b}=2 \mathrm{~V} \\ & 100011 \mathrm{~b}=2.05 \mathrm{~V} \\ & 100100 \mathrm{~b}=2.1 \mathrm{~V} \\ & 100101 \mathrm{~b}=2.15 \mathrm{~V} \\ & 100110 \mathrm{~b}=2.2 \mathrm{~V} \\ & 100111 \mathrm{~b}=2.25 \mathrm{~V} \\ & 10 \mathrm{1000b}=2.3 \mathrm{~V} \\ & 101001 \mathrm{~b}=2.35 \mathrm{~V} \\ & 101010 \mathrm{~b}=2.4 \mathrm{~V} \\ & 101011 \mathrm{~b}=2.45 \mathrm{~V} \\ & 101100 \mathrm{~b}=2.5 \mathrm{~V} \\ & 101101 \mathrm{~b}=2.55 \mathrm{~V} \\ & 101110 \mathrm{~b}=2.6 \mathrm{~V} \\ & 101111 \mathrm{~b}=2.65 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 110000 \mathrm{~b}=2.7 \mathrm{~V} \\ & 110001 \mathrm{~b}=2.75 \mathrm{~V} \\ & 110010 \mathrm{~b}=2.8 \mathrm{~V} \\ & 110011 \mathrm{~b}=2.85 \mathrm{~V} \\ & 110100 \mathrm{~b}=2.9 \mathrm{~V} \\ & 110101 \mathrm{~b}=3 \mathrm{~V} \\ & 110110 \mathrm{~b}=3.1 \mathrm{~V} \\ & 110111 \mathrm{~b}=3.2 \mathrm{~V} \\ & 111000 \mathrm{~b}=3.3 \mathrm{~V} \\ & 111001 \mathrm{~b}=3.3 \mathrm{~V} \\ & 111010 \mathrm{~b}=3.3 \mathrm{~V} \\ & 111011 \mathrm{~b}=3.3 \mathrm{~V} \\ & 111100 \mathrm{~b}=3.3 \mathrm{~V} \\ & 111101 \mathrm{~b}=3.3 \mathrm{~V} \\ & 111110 \mathrm{~b}=3.3 \mathrm{~V} \\ & 111111 \mathrm{~b}=3.3 \mathrm{~V} \end{aligned}$ |

### 8.6.22 Load Switch1 or LDO3 Control Register (DEFLS1) (Address = 0x14) [reset = X]

DEFLS1 is shown in Figure 50 and described in Table 22.
Return to Summary Table.
This register is password protected.
Figure 50. DEFLS1 Register

| DATA BIT |  | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME |  | Reserved | Reserved | LS1LDO3 | LDO3[4:0] |  |  |  |  |
| READ/WRITE |  | R | R | R/W | R/W | R/W | R/W | R/W | R/W |
| RESET VALUE | TPS65217A | 0b | Ob | Ob | 0b | 0b | 1b | 1b | Ob |
|  | TPS65217B | 0b | 0b | 1b | 1b | 1b | 1b | 1b | 1b |
|  | TPS65217C | Ob | Ob | 1b | Ob | 0b | 1 b | 1b | Ob |
|  | TPS65217D | 0b | Ob | 1 b | Ob | 0b | 1b | 1b | Ob |

Table 22. DEFLS1 Register Field Descriptions

| Bit | Field | Type | Reset | Description |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 7-6 | Reserved | R | 00b | This bit is reserved |  |
| 5 | LS1LDO3 | R/W | TPS65217A: 0b TPS65217B: 1b TPS65217C: 1b TPS65217D: 1b | LS or LDO tracking bit $0 \mathrm{~b}=\mathrm{FET}$ functions as load switch (LS1). $1 b=$ FET is configured as LDO3. |  |
| 4-0 | LDO3[4:0] | R/W | TPS65217A: 0 0110bTPS65217B: 1111 bTPS65217C: 00110 bTPS65217D: 00110 b | LDO3 output voltage setting (LS1LDO3 = 1b) |  |
|  |  |  |  | $\begin{aligned} & 00000 \mathrm{~b}=1.5 \mathrm{~V} \\ & 00001 \mathrm{~b}=1.55 \mathrm{~V} \\ & 00010 \mathrm{~b}=1.6 \mathrm{~V} \\ & 00011 \mathrm{~b}=1.65 \mathrm{~V} \\ & 00100 \mathrm{~b}=1.7 \mathrm{~V} \\ & 00101 \mathrm{~b}=1.75 \mathrm{~V} \\ & 00110 \mathrm{~b}=1.8 \mathrm{~V} \\ & 00111 \mathrm{~b}=1.85 \mathrm{~V} \\ & 01000 \mathrm{~b}=1.90 \mathrm{~V} \\ & 01001 \mathrm{~b}=2 \mathrm{~V} \\ & 01010 \mathrm{~b}=2.1 \mathrm{~V} \\ & 01011 \mathrm{~b}=2.2 \mathrm{~V} \\ & 01100 \mathrm{~b}=2.3 \mathrm{~V} \\ & 01101 \mathrm{~b}=2.4 \mathrm{~V} \\ & 01110 \mathrm{~b}=2.45 \mathrm{~V} \\ & 01111 \mathrm{~b}=2.5 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 10000 \mathrm{~b}=2.55 \mathrm{~V} \\ & 10001 \mathrm{~b}=2.6 \mathrm{~V} \\ & 10010 \mathrm{~b}=2.65 \mathrm{~V} \\ & 10011 \mathrm{~b}=2.7 \mathrm{~V} \\ & 10100 \mathrm{~b}=2.75 \mathrm{~V} \\ & 10101 \mathrm{~b}=2.8 \mathrm{~V} \\ & 10110 \mathrm{~b}=2.85 \mathrm{~V} \\ & 10111 \mathrm{~b}=2.9 \mathrm{~V} \\ & 11000 \mathrm{~b}=2.95 \mathrm{~V} \\ & 11001 \mathrm{~b}=3 \mathrm{~V} \\ & 11010 \mathrm{~b}=3.05 \mathrm{~V} \\ & 11011 \mathrm{~b}=3.1 \mathrm{~V} \\ & 11100 \mathrm{~b}=3.15 \mathrm{~V} \\ & 11101 \mathrm{~b}=3.2 \mathrm{~V} \\ & 11110 \mathrm{~b}=3.25 \mathrm{~V} \\ & 11111 \mathrm{~b}=3.3 \mathrm{~V} \end{aligned}$ |

### 8.6.23 Load Switch2 or LDO4 Control Register (DEFLS2) (Address = 0x15) [reset = X]

DEFLS2 is shown in Figure 51 and described in Table 23.
Return to Summary Table.
This register is password protected.
Figure 51. DEFLS2 Register

| DATA BIT |  | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME |  | Reserved | Reserved | LS2LDO4 | LDO4[4:0] |  |  |  |  |
| READ/WRITE |  | R | R | R/W | R/W | R/W | R/W | R/W | R/W |
| RESET VALUE | TPS65217A | Ob | 0b | 0b | 1b | Ob | 1 b | 0b | 1 b |
|  | TPS65217B | 0b | 0b | 1b | 1b | 1 b | 1 b | 1 b | 1 b |
|  | TPS65217C | 0b | 0b | 1b | 1b | 1b | 1 b | 1b | 1 b |
|  | TPS65217D | Ob | 0b | 1 b | 1b | 1b | 1 b | 1 b | 1 b |

Table 23. DEFLS2 Register Field Descriptions

| Bit | Field | Type | Reset | Description |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 7-6 | Reserved | R | 00b | These bits are reserved |  |
| 5 | LS2LDO4 | R/W | TPS65217A: 0b TPS65217B: 1b TPS65217C: 1b TPS65217D: 1b | LS or LDO configuration bit $\mathrm{Ob}=\mathrm{FET}$ functions as load a switch (LS2). $1 b=F E T$ is configured as LDO4. |  |
| 4-0 | LDO4[4:0] | R/W | TPS65217A: 1 0101b TPS65217B: 11111b TPS65217C: 1 1111b TPS65217D: 1 1111b | LDO4 output voltage setting (LS2LDO4 = 1b) |  |
|  |  |  |  | $\begin{aligned} & 00000 \mathrm{~b}=1.5 \mathrm{~V} \\ & 00001 \mathrm{~b}=1.55 \mathrm{~V} \\ & 00010 \mathrm{~b}=1.6 \mathrm{~V} \\ & 00011 \mathrm{~b}=1.65 \mathrm{~V} \\ & 00100 \mathrm{~b}=1.7 \mathrm{~V} \\ & 00101 \mathrm{~b}=1.75 \mathrm{~V} \\ & 00110 \mathrm{~b}=1.8 \mathrm{~V} \\ & 00111 \mathrm{~b}=1.85 \mathrm{~V} \\ & 01000 \mathrm{~b}=1.9 \mathrm{~V} \\ & 01001 \mathrm{~b}=2 \mathrm{~V} \\ & 01010 \mathrm{~b}=2.1 \mathrm{~V} \\ & 01011 \mathrm{~b}=2.2 \mathrm{~V} \\ & 01100 \mathrm{~b}=2.3 \mathrm{~V} \\ & 01101 \mathrm{~b}=2.4 \mathrm{~V} \\ & 01110 \mathrm{~b}=2.45 \mathrm{~V} \\ & 01111 \mathrm{~b}=2.5 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 10000 \mathrm{~b}=2.55 \mathrm{~V} \\ & 10001 \mathrm{~b}=2.6 \mathrm{~V} \\ & 10010 \mathrm{~b}=2.65 \mathrm{~V} \\ & 10011 \mathrm{~b}=2.7 \mathrm{~V} \\ & 10100 \mathrm{~b}=2.75 \mathrm{~V} \\ & 10101 \mathrm{~b}=2.8 \mathrm{~V} \\ & 10110 \mathrm{~b}=2.85 \mathrm{~V} \\ & 1011 \mathrm{~b}=2.9 \mathrm{~V} \\ & 11000 \mathrm{~b}=2.95 \mathrm{~V} \\ & 11001 \mathrm{~b}=3 \mathrm{~V} \\ & 11010 \mathrm{~b}=3.05 \mathrm{~V} \\ & 11011 \mathrm{~b}=3.1 \mathrm{~V} \\ & 11100 \mathrm{~b}=3.15 \mathrm{~V} \\ & 11101 \mathrm{~b}=3.2 \mathrm{~V} \\ & 11110 \mathrm{~b}=3.25 \mathrm{~V} \\ & 11111 \mathrm{~b}=3.3 \mathrm{~V} \end{aligned}$ |

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### 8.6.24 Enable Register (ENABLE) (Address = 0x16) [reset = 0x00]

ENABLE is shown in Figure 52 and described in Table 24.
Return to Summary Table.
This register is password protected.
Figure 52. ENABLE Register

| DATA BIT | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ | $\mathbf{0}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME | Reserved | LS1_EN | LS2_EN | DC1_EN | DC2_EN | DC3_EN | LDO1_EN | LDO2_EN |
| READ/WRITE | R | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| RESET VALUE | $0 b$ | $0 b$ | $0 b$ | $0 b$ | $0 b$ | $0 b$ | $0 b$ | $0 b$ |

Table 24. ENABLE Register Field Descriptions

| Bit | Field | Type | Reset | Description |
| :---: | :---: | :---: | :---: | :---: |
| 7 | Reserved | R | Ob | This bit is reserved |
| 6 | LS1_EN | R/W | Ob | LSW1 or LDO3 enable bit NOTE: PWR_EN pin must be high to enable LS1 or LDO3. <br> Ob = Disabled <br> 1b = Enabled |
| 5 | LS2_EN | R/W | Ob | LS2 or LDO4 enable bit <br> NOTE: PWR_EN pin must be high to enable LS2 or LDO4. <br> Ob = Disabled <br> $1 b=$ Enabled |
| 4 | DC1_EN | R/W | Ob | DCDC1 enable bit <br> NOTE: PWR_EN pin must be high to enable the DC/DC converter. <br> $0 \mathrm{~b}=\mathrm{DCDC} 1$ is disabled. <br> $1 \mathrm{~b}=\mathrm{DCDC} 1$ is enabled. |
| 3 | DC2_EN | R/W | Ob | DCDC2 enable bit <br> NOTE: PWR_EN pin must be high to enable the DC/DC converter. <br> $0 \mathrm{~b}=\mathrm{DCDC} 2$ is disabled. <br> $1 \mathrm{~b}=\mathrm{DCDC} 2$ is enabled. |
| 2 | DC3_EN | R/W | Ob | DCDC3 enable bit <br> NOTE: PWR_EN pin must be high to enable the DC/DC converter. <br> $0 \mathrm{~b}=\mathrm{DCDC} 3$ is disabled. <br> $1 \mathrm{~b}=\mathrm{DCDC} 3$ is enabled. |
| 1 | LDO1_EN | R/W | Ob | LDO1 enable bit Ob = Disabled 1b = Enabled |
| 0 | LDO2_EN | R/W | Ob | LDO2 enable bit 0b = Disabled 1b = Enabled |

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### 8.6.25 UVLO Control Register (DEFUVLO) (Address = 0x18) [reset = 0x03]

DEFUVLO is shown in Figure 53 and described in Table 25.
Return to Summary Table.
This register is password protected.
Figure 53. DEFUVLO Register

| DATA BIT | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ | $\mathbf{0}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME | Reserved | Reserved | Reserved | Reserved | Reserved | Reserved | UVLO[1:0] |  |
| READ/WRITE | $R$ | $R$ | $R$ | $R$ | $R$ | $R / W$ | $R / W$ | $R / W$ |
| RESET VALUE | $0 b$ | $0 b$ | $0 b$ | $0 b$ | $0 b$ | $0 b$ | $1 b$ | $1 b$ |

Table 25. DEFUVLO Register Field Descriptions

| Bit | Field | Type | Reset |  |
| :---: | :--- | :--- | :--- | :--- |
| $7-3$ | Reserved | R | 00000 b | These bits are reserved |
| 2 | Reserved | R/W | 0 b | This bit is reserved |
| $1-0$ | UVLO[1:0] | R/W | 11 b | Undervoltage lockout setting <br>  |
|  |  |  | $00 \mathrm{~b}=2.73 \mathrm{~V}$ <br>  |  |
|  |  |  | $101 \mathrm{~b}=2.89 \mathrm{~V}$ |  |
|  |  |  |  | $11 \mathrm{~b}=3.18 \mathrm{~V}$ |

### 8.6.26 Sequencer Register 1 (SEQ1) (Address = 0x19) [reset = X]

SEQ1 is shown in Figure 54 and described in Table 26.

## Return to Summary Table.

This register is password protected.
Figure 54. SEQ1 Register

| DATA BIT |  | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME |  | Reserved | DC1_SEQ[2:0] |  |  | Reserved | DC2_SEQ[2:0] |  |  |
| READ/WRITE |  | R | R/W | R/W | R/W | R | R/W | R/W | R/W |
| RESET VALUE | TPS65217A | Ob | Ob | Ob | 1 b | 0 b | Ob | 1b | Ob |
|  | TPS65217B | 0b | 0b | Ob | 1 b | Ob | 1b | Ob | 1b |
|  | TPS65217C | Ob | 0b | Ob | 1 b | 0b | 1b | Ob | 1b |
|  | TPS65217D | Ob | Ob | Ob | 1 b | Ob | 1b | Ob | 1b |

Table 26. SEQ1 Register Field Descriptions

| Bit | Field | Type | Reset | Description |
| :---: | :---: | :---: | :---: | :---: |
| 7 | Reserved | R | Ob | This bit is reserved |
| 6-4 | DC1_SEQ[3:0] | R/W | TPS65217A: 0001b TPS65217B: 0001b TPS65217C: 0001b TPS65217D: 0001b | DCDC1 enable STROBE <br> $0000 \mathrm{~b}=$ Rail is not controlled by sequencer. <br> 0001b = Enable at STROBE1 <br> 0010b = Enable at STROBE2 <br> 0011b = Enable at STROBE3 <br> 0100b = Enable at STROBE4 <br> 0101b = Enable at STROBE5 <br> 0110b = Enable at STROBE6 <br> 0111b = Enable at STROBE7 |
| 3 | Reserved | R | Ob | This bit is reserved |
| 2-0 | DC2_SEQ[3:0] | R/W | TPS65217A: 0010b <br> TPS65217B: 0101b <br> TPS65217C: 0101b <br> TPS65217D: 0101b | DCDC2 enable STROBE <br> $0000 \mathrm{~b}=$ Rail is not controlled by sequencer. <br> 0001b = Enable at STROBE1 <br> 0010b = Enable at STROBE2 <br> 0011b = Enable at STROBE3 <br> 0100b = Enable at STROBE4 <br> 0101b = Enable at STROBE5 <br> 0110b = Enable at STROBE6 <br> 0111b = Enable at STROBE7 |

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### 8.6.27 Sequencer Register 2 (SEQ2) (Address = 0x1A) [reset = X]

SEQ2 is shown in Figure 55 and described in Table 27.
Return to Summary Table.
This register is password protected.
Figure 55. SEQ2 Register

| DATA BIT |  | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME |  | Reserved | DC3_SEQ[2:0] |  |  | LDO1_SEQ[3:0] |  |  |  |
| READ/WRITE |  | R | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| RESET VALUE | TPS65217A | Ob | Ob | 1 b | 1 b | 1 b | 0b | 1b | 1b |
|  | TPS65217B | 0b | 1b | Ob | 1 b | 1 b | 1b | 1b | 1b |
|  | TPS65217C | 0b | 1 b | Ob | 1 b | 1 b | 1b | 1b | 1b |
|  | TPS65217D | Ob | 1 b | Ob | 1 b | 1 b | 1b | 1b | 1b |

Table 27. SEQ2 Register Field Descriptions

| Bit | Field | Type | Reset | Description |
| :---: | :---: | :---: | :---: | :---: |
| 7 | Reserved | R | 0b | This bit is reserved |
| 6-4 | $\begin{aligned} & \text { DC3_SEQ[2 } \\ & \text { :0] } \end{aligned}$ | R/W | TPS65217A: 011b <br> TPS65217B: 101b <br> TPS65217C: 101b <br> TPS65217D: 101b | DCDC3 enable STROBE <br> $000 \mathrm{~b}=$ Rail is not controlled by sequencer. <br> 001b = Enable at STROBE1 <br> 010b $=$ Enable at STROBE2 <br> 011b $=$ Enable at STROBE3 <br> $100 \mathrm{~b}=$ Enable at STROBE4 <br> 101b $=$ Enable at STROBE5 <br> $110 \mathrm{~b}=$ Enable at STROBE6 <br> $111 b=$ Enable at STROBE7 |
| 3-0 | $\begin{aligned} & \text { LDO1_SEQ } \\ & {[3: 0]} \end{aligned}$ | R/W | TPS65217A: 1011b TPS65217B: 1111b TPS65217C: 1111b TPS65217D: 1111b | LDO1 enable state $0000 \mathrm{~b}=$ Rail is not controlled by sequencer. 0001b = Enable at STROBE1 0010b = Enable at STROBE2 0011b = Enable at STROBE3 0100b = Enable at STROBE4 0101b = Enable at STROBE5 0110b = Enable at STROBE6 0111b = Enable at STROBE7 <br> $1000 \mathrm{~b}=$ Rail is not controlled by sequencer 1001b = Rail is not controlled by sequencer 1010b to 1101b = Reserved $1110 \mathrm{~b}=$ Enable at STROBE14 $1111 \mathrm{~b}=$ Enabled at STROBE15 (with SYS) |

### 8.6.28 Sequencer Register 3 (SEQ3) (Address = 0x1B) [reset = X]

SEQ3 is shown in Figure 56 and described in Table 28.

## Return to Summary Table.

This register is password protected.
Figure 56. SEQ3 Register

| DATA BIT |  | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME |  | LDO2_SEQ[3:0] |  |  |  | Reserved | LDO3_SEQ[2:0] |  |  |
| READ/WRITE |  | R/W | R/W | R/W | R/W | R | R/W | R/W | R/W |
| RESET VALUE | TPS65217A | 0b | Ob | 1 b | 0b | 0 b | 0b | 0b | 1b |
|  | TPS65217B | 0b | 0b | 1b | Ob | Ob | 0b | 1b | 1b |
|  | TPS65217C | 0b | 0b | 1 b | 1 b | Ob | 0b | 1b | Ob |
|  | TPS65217D | 0b | Ob | 1b | 1b | Ob | 0b | 1b | Ob |

Table 28. SEQ3 Register Field Descriptions

| Bit | Field | Type | Reset | Description |
| :---: | :---: | :---: | :---: | :---: |
| 7-4 | LDO2_SEQ[3:0] | R/W | TPS65217A: 0010b <br> TPS65217B: 0010b <br> TPS65217C: 0011b <br> TPS65217D: 0011b | LDO2 enable STROBE <br> $0000 \mathrm{~b}=$ Rail is not controlled by sequencer. <br> 0001b = Enable at STROBE1 <br> 0010b = Enable at STROBE2 <br> 0011b = Enable at STROBE3 <br> 0100b = Enable at STROBE4 <br> 0101b = Enable at STROBE5 <br> 0110b = Enable at STROBE6 <br> 0111b = Enable at STROBE7 <br> $1000 \mathrm{~b}=$ Rail is not controlled by sequencer. <br> 1001b = Rail is not controlled by sequencer. <br> 1010b to 1101b = Reserved <br> $1110 \mathrm{~b}=$ Enable at STROBE14 <br> $1111 \mathrm{~b}=$ Enabled at STROBE15 (with SYS) |
| 3 | Reserved | R | 0b | This bit is reserved |
| 2-0 | LDO3_SEQ[2:0] | R/W | TPS65217A: 001b TPS65217B: 011b TPS65217C: 010b TPS65217D: 010b | LS1 or LDO3 enable state <br> $000 \mathrm{~b}=$ Rail is not controlled by sequencer <br> 001b = Enable at STROBE1 <br> 010b = Enable at STROBE2 <br> 011b = Enable at STROBE3 <br> 100b $=$ Enable at STROBE4 <br> 101b $=$ Enable at STROBE5 <br> 110b = Enable at STROBE6 <br> $111 \mathrm{~b}=$ Enable at STROBE7 |

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### 8.6.29 Sequencer Register 4 (SEQ4) (Address = 0x1C) [reset = 0x40]

SEQ4 is shown in Figure 57 and described in Table 29.
Return to Summary Table.
This register is password protected.
Figure 57. SEQ4 Register

| DATA BIT | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME | Reserved | LDO4_SEQ[2:0] |  |  | Reserved | Reserved | Reserved | Reserved |
| READ/WRITE | R | R/W | R/W | R/W | R | R | R | R |
| RESET VALUE | 0b | 1b | Ob | 0b | Ob | Ob | Ob | Ob |

Table 29. SEQ4 Register Field Descriptions

| Bit | Field | Type | Reset | Description |
| :---: | :---: | :---: | :---: | :---: |
| 7 | Reserved | R | 0b | This bit is reserved |
| 6-4 | LDO4_SEQ[2:0] | R/W | 100b | LS2 or LDO4 enable state <br> $0000 \mathrm{~b}=$ Rail is not controlled by sequencer. <br> 0001b = Enable at STROBE1 <br> 0010b = Enable at STROBE2 <br> 0011b = Enable at STROBE3 <br> 0100b $=$ Enable at STROBE4 <br> 0101b = Enable at STROBE5 <br> 0110b = Enable at STROBE6 <br> 0111b = Enable at STROBE7 |
| 3-0 | Reserved | R | 0000b | These bits are reserved |

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### 8.6.30 Sequencer Register 5 (SEQ5) (Address = 0x1D) [reset = X]

SEQ5 is shown in Figure 58 and described in Table 30.

## Return to Summary Table.

This register is password protected.
Figure 58. SEQ5 Register

| DATA BIT |  | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME |  | DLY1[1:0] |  | DLY2[1:0] |  | DLY3[1:0] |  | DLY4[1:0] |  |
| READ/WRITE |  | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| RESET VALUE | TPS65217A | 1b | 0b | 0b | Ob | 0b | 0b | 0b | Ob |
|  | TPS65217B | 1b | 0b | 0b | Ob | 0b | 0b | 0b | Ob |
|  | TPS65217C | 0b | 0b | 1 b | Ob | 0b | 0b | 0b | Ob |
|  | TPS65217D | 0b | 0b | 1b | 0b | 0b | 0b | 0b | 0b |

Table 30. SEQ5 Register Field Descriptions

| Bit | Field | Type | Reset | Description |
| :---: | :---: | :---: | :---: | :---: |
| 7-6 | DLY1[1:0] | R/W | $\begin{aligned} & \text { TPS65217A: 10b } \\ & \text { TPS65217B: 10b } \\ & \text { TPS65217C: 00b } \\ & \text { TPS65217D: 00b } \end{aligned}$ | Delay1 time $00 \mathrm{~b}=1 \mathrm{~ms}$ $01 \mathrm{~b}=2 \mathrm{~ms}$ $10 \mathrm{~b}=5 \mathrm{~ms}$ $11 \mathrm{~b}=10 \mathrm{~ms}$ |
| 5-4 | DLY2[1:0] | R/W | TPS65217A: 00b <br> TPS65217B: 00b <br> TPS65217C: 10b <br> TPS65217D: 10b | Delay2 time $00 \mathrm{~b}=1 \mathrm{~ms}$ <br> $01 \mathrm{~b}=2 \mathrm{~ms}$ <br> $10 \mathrm{~b}=5 \mathrm{~ms}$ <br> $11 \mathrm{~b}=10 \mathrm{~ms}$ |
| 3-2 | DLY3[1:0] | R/W | 00b | Delay3 time $00 \mathrm{~b}=1 \mathrm{~ms}$ $01 \mathrm{~b}=2 \mathrm{~ms}$ $10 \mathrm{~b}=5 \mathrm{~ms}$ $11 \mathrm{~b}=10 \mathrm{~ms}$ |
| 1-0 | DLY4[1:0] | R/W | 00b | Delay4 time $00 \mathrm{~b}=1 \mathrm{~ms}$ <br> $01 \mathrm{~b}=2 \mathrm{~ms}$ <br> $10 \mathrm{~b}=5 \mathrm{~ms}$ <br> $11 \mathrm{~b}=10 \mathrm{~ms}$ |

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### 8.6.31 Sequencer Register 6 (SEQ6) (Address = 0x1E) [reset = 0x00]

SEQ6 is shown in Figure 59 and described in Table 31.
Return to Summary Table.
This register is password protected.
Figure 59. SEQ6 Register

| DATA BIT | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ | $\mathbf{0}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FIELD NAME | DLY5[1:0] |  | DLY6[1:0] | Reserved | SEQUP | SEQDWN | INSTDWN |  |
| READ/WRITE | R/W | R/W | R/W | R/W | R | R/W | R/W | R/W |
| RESET VALUE | 0 b | 0 b | 0 b | 0 b | 0 b | 0 b | 0 b | 0 b |

Table 31. SEQ6 Register Field Descriptions

| Bit | Field | Type | Reset | Description |
| :---: | :--- | :--- | :--- | :--- |
| $7-6$ | DLY5[1:0] | R/W | 00 b | Delay5 time <br> $00 \mathrm{~b}=1 \mathrm{~ms}$ <br> $01 \mathrm{~b}=2 \mathrm{~ms}$ <br> $10 \mathrm{~b}=5 \mathrm{~ms}$ <br> $11 \mathrm{~b}=10 \mathrm{~ms}$ |
| $5-4$ | DLY6[1:0] | R/W | 00 b | Delay6 time <br> $00 \mathrm{~b}=1 \mathrm{~ms}$ <br> $01 \mathrm{~b}=2 \mathrm{~ms}$ <br> $10 \mathrm{~b}=5 \mathrm{~ms}$ <br> $11 \mathrm{~b}=10 \mathrm{~ms}$ |
| 3 | Reserved | SEQUP | R | R/W |
| 2 | SEQDWN | Ob | This bit is reserved <br> Set this bit to 1b to trigger a power-up sequence. This bit is <br> automatically reset to Ob. |  |
| 0 | INSTDWN | R/W | Ob | Set this bit to 1b to trigger a power-down sequence. This bit is <br> automatically reset to Ob. |
| 1 |  | Ob | Instant shutdown bit <br> NOTE: Shutdown occurs when the PWR_EN pin is pulled low or <br> the SEQDWN bit is set. Only those rails controlled by the <br> sequencer are shut down. <br> Ob = Shutdown follows reverse power-up sequence <br> 1b $=$ All delays are bypassed and all rails are shut down at the <br> same time. |  |

## 9 Application and Implementation

## 注

Information in the following applications sections is not part of the TI component specification，and TI does not warrant its accuracy or completeness．TI＇s customers are responsible for determining suitability of components for their purposes．Customers should validate and test their design implementation to confirm system functionality．

## 9．1 Application Information

The TPS65217x device is designed to pair with various application processors．For detailed information on using the TPS65217x device with Sitara AM335x processors，refer to the Powering the AM335x with the TPS65217x user＇s guide．

## 9．2 Typical Application



For connection diagrams for all members of the TPS65217x family，refer to the Powering the AM335x with the TPS65217x user＇s guide．

图 60．Connection Diagram for Typical Application

## Typical Application（接下页）

## 9．2．1 Design Requirements

For this design example，use the parameters listed in 表 32.
表 32．Design Requirements

| RAIL | VOLTAGE | SEQUENCE |
| :---: | :---: | :---: |
| DCDC1 | 1.8 V | 1 |
| DCDC2 | 3.3 V | 2 |
| DCDC3 | 1.1 V | 3 |
| LDO1 | 1.8 V | 15 |
| LDO2 | 3.3 V | 2 |
| LS1 or LDO3 | Load switch | 1 |
| LS2 or LDO4 | Load switch | 4 |

## 9．2．2 Detailed Design Procedure

表 33 lists the recommended inductors for the WLED boost converter．表 34 lists the recommended capacitor for the WLED boost converter．

表 33．Recommended Inductors for WLED Boost Converter

| PART NUMBER | SUPPLIER | VALUE $(\boldsymbol{\mu H})$ | $\mathbf{R}_{\text {DS }}(\mathbf{m} \boldsymbol{\Omega})$ MAX | RATED CURRENT $(\mathbf{A})$ | DIMENSIONS <br> $(\mathbf{m m} \times \mathbf{m m} \times \mathbf{m m})$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| CDRH74NP－180M | Sumida | 18 | 73 | 1.31 | $7.5 \times 7.5 \times 4.5$ |
| P1167．183 | Pulse | 18 | 37 | 1.5 | $7.5 \times 7.5 \times 4.5$ |

表 34．Recommended Output Capacitor for WLED Boost Converter

| PART NUMBER | SUPPLIER | VOLTAGE RATING（V） | VALUE $(\boldsymbol{\mu F})$ | DIMENSIONS | DIELECTRIC |
| :---: | :---: | :---: | :---: | :---: | :---: |
| UMK316BJ475ML－T | Taiyo Yuden | 50 | 4.7 | 1206 | X5R |

## 9．2．2．1 Output Filter Design（Inductor and Output Capacitor）

## 9．2．2．1．1 Inductor Selection for Buck Converters

The step－down converters operate typically with $2.2-\mu \mathrm{H}$ output inductors．Larger or smaller inductor values can be used to optimize the performance of the device for specific operation conditions．The selected inductor must be rated for its dc resistance and saturation current．The dc resistance of the inductance directly influences the efficiency of the converter．Therefore，an inductor with the lowest dc resistance should be selected for highest efficiency．
Use 公式 4 to calculate the maximum inductor current under static load conditions．The saturation current of the inductor should be rated higher than the maximum inductor current，because，during heavy load transients，the inductor current increases to a value greater than the calculated value．
$\mathrm{I}_{\mathrm{L} \text { max }}=\mathrm{I}_{\text {OUT } \text { max }}+\frac{\Delta \mathrm{I}_{\mathrm{L}}}{2}$
where
－$I_{\text {Lmax }}$ is the maximum inductor current
－I IOUTmax is the maximum output current
－$\Delta I_{\mathrm{L}}$ is the peak－to－peak inductor ripple current（see 公式 5）
$\Delta \mathrm{I}_{\mathrm{L}}=\mathrm{V}_{\text {OUT }} \times \frac{1-\frac{\mathrm{V}_{\text {OUT }}}{\mathrm{V}_{\text {IN }}}}{\mathrm{L} \times \mathrm{f}}$
where
－$L$ is the inductor value．
－$f$ is the switching frequency（ 2.25 MHz typical）．
The highest inductor current occurs at maximum input voltage $\left(\mathrm{V}_{\mathrm{IN}}\right)$ ．Open－core inductors have a soft saturation characteristic and can usually support greater inductor currents than a comparable shielded inductor．
A more conservative approach is to select the inductor current rating just for the maximum switch current of the corresponding converter．The core material must be considered because it differs from inductor to inductor and has an impact on the efficiency，especially at high switching frequencies．Also，the resistance of the windings greatly affects the converter efficiency at high load．表 35 lists the recommended inductors．

表 35．Recommended Inductors for DCDC1，DCDC2，and DCDC3

| PART NUMBER | SUPPLIER | VALUE $(\boldsymbol{\mu H})$ | $\mathbf{R}_{\mathbf{D S}}(\mathbf{m} \boldsymbol{\Omega})$ MAX | RATED CURRENT $(\mathbf{A})$ | DIMENSIONS $(\mathbf{m m})$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| LQM2HPN2R2MGOL | Murata | 2.2 | 100 | 1.3 | $2 \times 2.5 \times 0.9$ |
| VLCF4018T－2R2N1R4－2 | TDK | 2.2 | 60 | 1.44 | $3.9 \times 4.7 \times 1.8$ |

## 9．2．2．1．2 Output Capacitor Selection

The advanced fast－response voltage－mode control scheme of the two converters lets the use of small ceramic capacitors with a typical value of $10 \mu \mathrm{~F}$ ，without having large output－voltage undershoots and overshoots during heavy load transients．Ceramic capacitors having low ESR values result in the lowest output voltage ripple and are therefore recommended．
If ceramic output capacitors are used，the capacitor RMS ripple－current rating must always meet the application requirements．Use 公式 6 to calculate the RMS ripple current（ $\left.\mathrm{l}_{\text {RMSCout }}\right)$ ．

$$
\begin{equation*}
I_{\text {RMSCout }}=V_{\text {OUT }} \times \frac{1-\frac{V_{\text {OUT }}}{V_{\text {IN }}}}{L \times f} \times \frac{1}{2 \times \sqrt{3}} \tag{6}
\end{equation*}
$$

At the nominal load current，the inductive converters operate in PWM mode and the overall output voltage ripple is the sum of the voltage spike caused by the output capacitor ESR plus the voltage ripple caused by charging and discharging the output capacitor as shown in 公式 7.

$$
\Delta V_{\text {OUT }}=V_{\text {OUT }} \times \frac{1-\frac{V_{\text {OUT }}}{V_{\text {IN }}}}{L \times f} \times\left(\frac{1}{8 \times C_{\text {OUT }} \times f}+E S R\right)
$$

where
－the highest output voltage ripple occurs at the highest input voltage
At light－load currents，the converters operate in power－save mode，and the output－voltage ripple depends on the output capacitor value．The output－voltage ripple is set by the internal comparator delay and the external capacitor．The typical output－voltage ripple is less than $1 \%$ of the nominal output voltage．

## 9．2．2．1．3 Input Capacitor Selection

Because the buck converter has a pulsating input current，a low－ESR input capacitor is required for the best input voltage filtering and to minimize the interference with other circuits caused by high input－voltage spikes．The converters require a ceramic input capacitor of $10 \mu \mathrm{~F}$ ．The input capacitor can be increased without any limit for better input voltage filtering．表 36 lists the recommended ceramic capacitors．

表 36．Recommended Input Capacitors for DCDC1，DCDC2，and DCDC3

| PART NUMBER | SUPPLIER | VALUE $(\boldsymbol{\mu F})$ | DIMENSIONS |
| :---: | :---: | :---: | :---: |
| C2012X5R0J226MT | TDK | 22 | 0805 |
| JMK212BJ226MG | Taiyo Yuden | 22 | 0805 |
| JMK212BJ106M | Taiyo Yuden | 10 | 0805 |
| C2012X5R0J106M | TDK | 10 | 0805 |

## 9．2．2．2 5－V Operation Without a Battery

The TPS65217x device has a linear charger for Li＋batteries，and TI recommends that a battery is included in designs for ideal performance．However，the device can operate without a battery attached．Three basic use cases are available for operation without a battery：
1．The system is designed for battery operation，but the battery is removable and the end user does not have the battery inserted．The system can be powered by connecting an AC adaptor or USB supply．
2．A nonportable system operates on a（regulated）5－V supply，but the PMIC must provide protection against input overvoltage up to 20 V ．Electrically，this case is the same as the previous case where the device is powered by an AC adaptor．The battery pins（BAT and BATSENSE）are shorted together and floating，the temperature sensing pin（TS）is left floating，and power is provided through the AC pin．The DC／DC converters，the WLED driver，and the LDO regulators connect to the overvoltage－protected SYS pins．The load switches（or LDO3 and LDO4，depending on configuration）typically connect to one of the lower system rails，but can also be connected to the SYS pin．
3．A nonportable system operates on a regulated $5-\mathrm{V}$ supply that does not require input overvoltage protection． In this case，the $5-\mathrm{V}$ power supply is connected through the BAT pins．The DC／DC converter inputs，WLED driver，LDO1，and LDO2 are connected directly to the $5-\mathrm{V}$ supply．A standard，constant－value $10-\mathrm{k} \Omega$ resistor is connected from the TS pin to ground to simulate the NTC thermistor monitoring the battery．The load switches（or LDO3 and LDO4，depending on configuration）typically connect to one of the lower system rails， but can also be connected directly to the $5-\mathrm{V}$ input supply．
图 61 shows the connection of the input power supply to the device for $5-\mathrm{V}$ only operation，with $20-\mathrm{V}$ input overvoltage protection．图 62 shows the connection of the input power supply to the device for $5-\mathrm{V}$ only operation without $20-\mathrm{V}$ input overvoltage protection．表 37 lists the functional differences between both setups．


The SYS node and DC／DC converters are protected against input overvoltage up to 20 V．

图 61．Power Connection for 5－V Only Operation With OVP，Without a Battery

表 37．Functional Differences Between 5－V Only Operation Without a Battery and With and Without 20－V Input Overvoltage Protection

| RESOURCE IMPACTED | POWER SUPPLIED THROUGH AC PIN （CASE（1）AND（2）） | POWER SUPPLIED THROUGH BAT PIN （CASE（3）） |
| :---: | :---: | :---: |
| Input protection | The maximum operating input voltage is 5.8 V ， but the device is protected from input overvoltage up to 20 V ． | The maximum operating input voltage is 5.5 V ． |
| Power efficiency | The input current for DC／DC converters passes through AC－SYS power－path switch （approximately $150 \mathrm{~m} \Omega$ ）． | The internal power path is bypassed to minimize $I^{2} R$ losses． |
| BATTEMP bit | The BATTEMP bit（bit 0 in register $0 \times 03$ ）always reads 1，but has no effect on operation of the device． | The BATTEMP bit（bit 0 in register 0x03）always reads 0 ． |
| Output rail status on initial power connection | The LDO1 regulator is automatically powered up when the AC pin is connected to the $5-\mathrm{V}$ supply， and the device goes to the WAIT PWR＿EN state．If the PWR＿EN pin is not asserted within 5 s ，the LDO1 regulator turns OFF． | The LDO1 regulator is OFF when the BAT pin is connected to the $5-\mathrm{V}$ supply．The PB＿IN pin must be pulled low to go to the WAIT PWR＿EN state．The PB＿IN pin cannot stay low for greater than 8 s or a reset will occur． |
| Response to input overvoltage | Device goes to the OFF state．${ }^{(1)}$ | Not applicable |
| Power path | In an application with one source of input power， if the input power drops below UVLO and recovers before reaching 100 mV ，the rising edge may not be detected by the device．This condition，known as a brownout，can cause a lockup of the device in which the $I^{2} \mathrm{C}$ is responsive but SYS is not connected to the AC or USB through the power path．${ }^{(2)}$ | Not applicable |

（1）If a battery is present in the system，the TPS65217x device automatically switches from using the AC pin as the power supply to using BAT as the supply when the AC input exceeds 6.4 V ．The device automatically switches back to supplying power from the AC pin when the AC input recovers and the voltages decreases to less than 5.8 V ．
（2）As a workaround，supply power through the BAT input pin or change UVLO to 2.73 V by changing the UVLO［1：0］bits in register $0 \times 18$ to 00b．This setting must be changed during initialization after the first power－on event of the device．The bits return to the default value when all $I^{2} \mathrm{C}$ registers reset．As a result，if a brownout condition can occur during the first power－on event，then external circuitry must be added to prevent the TPS65217x device from being affected by the brownout condition．

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## 9．2．3 Application Curves



图 63．DCDCx Voltage Ripple and Inductor Current at 5 mA Load，1．1－V $V_{\text {OUt }}$


图 65．DCDCx Voltage Ripple and Inductor Current at 300 mA Load，1．1－V Vout


图 67．DCDCx Voltage Ripple and Inductor Current at 50 mA Load， $1.5-\mathrm{V} \mathrm{V}_{\text {OUT }}$


图 64．DCDCx Voltage Ripple and Inductor Current at 50 mA Load，1．1－V Vout


图 66．DCDCx Voltage Ripple and Inductor Current at 5 mA Load，1．5－V $\mathrm{V}_{\text {OUt }}$


图 68．DCDCx Voltage Ripple and Inductor Current at 300 mA Load， $1.5-\mathrm{V} \mathrm{V}_{\text {OUT }}$


图 69．DCDCx Voltage Ripple and Inductor Current at 5 mA Load，3．3－V V ${ }_{\text {OUT }}$


图 71．DCDCx Voltage Ripple and Inductor Current at 300 mA Load，3．3－V V


图 73．DCDCx Load Transient Response， $1.1 \mathrm{~V}_{\text {OUT }}$ ，200－ 1000－200 mA Load


图 70．DCDCx Voltage Ripple and Inductor Current at 50 mA Load，3．3－V Vout


图 72．DCDCx Load Transient Response，1．1 $\mathrm{V}_{\text {OUT }}$ ，50－500－ 50 mA Load


图 74．DCDCx Load Transient Response， 1.5 V ${ }_{\text {OUT }}$ ，50－500－ 50 mA Load

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图 75．DCDCx Load Transient Response， $1.5 \mathrm{~V}_{\text {OUT }}$ 200－ 1000－200 mA Load


图 76．DCDCx Load Transient Response， 3.3 Vout，50－500－ 50 mA Load


图 77．DCDCx Load Transient Response， 3.3 V ${ }_{\text {OUT }}$ ，200－1000－200 mA Load

## 10 Power Supply Recommendations

The device is designed to operate with an input voltage supply range from 2.75 V to 5.8 V ．This input supply can be from a single－cell Li－ion，Li－polymer batteries，dc supply，USB supply，or other externally regulated supply．If the input supply is located more than a few inches from the TPS65217x device，additional bulk capacitance may be required in addition to the ceramic bypass capacitors．An electrolytic capacitor with a value of $4.7 \mu \mathrm{~F}$ is a typical choice．

## 11 Layout

## 11．1 Layout Guidelines

As for all switching power supplies，the layout is an important step in the design．Proper function of the device requires careful attention to printed circuit－board（PCB）layout．Care must be taken in board layout to get the specified performance．
－The VIN＿DCDCx and VINLDO pins should be bypassed to ground with a low－ESR ceramic bypass capacitor． The typical recommended bypass capacitance is $10 \mu \mathrm{~F}$ and $4.7 \mu \mathrm{~F}$ with a X5R or X7R dielectric，respectively．
－The optimum placement of these bypass capacitors is close to the VIN＿DCDCx and VINLDO pins of the TPS65217x device．Care should be taken to minimize the loop area formed by the bypass capacitor connection，the VIN＿DCDCx and VINLDO pins，and the thermal pad of the device．
－The thermal pad should be tied to the PCB ground plane with multiple vias．
－The inductor traces from the Lx pins to the $\mathrm{V}_{\text {OUT }}$ node（VDCDCx）of each DCDCx converter should be kept on the PCB top layer and free of any vias．
－The VLDOx and VDCDCx pin（feedback pin labeled FB1 in 图 78）traces should be routed away from any potential noise source to avoid coupling．
－The DCDCx output capacitance should be placed immediately at the DCDCx pin．Excessive distance between the capacitance and DCDCx pin may cause poor converter performance．

## 11．2 Layout Example



图 78．Layout Example Schematic

## 12 器件和文档支持

## 12.1 器件支持

12．1．1 第三方产品免责声明
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## 12.2 文档支持

## 12．2．1 相关文档

请参阅如下相关文档：：

- 德州仪器（TI），降压转换器功率级的基本计算应用报告
- 德州仪器（TI），设计强大的 TPS65217系统，以便应对 $V_{I N}$ 欠压的情况应用报告
- 德州仪器（TI），借助适用于处理器应用的电源管理IC（PMIC）改进 设计应用报告
- 德州仪器（TI），TPS65217 电源管理 IC 评估模块用户指南
- 德州仪器（TI），使用 TPS65217x 为 AM335x 供电用户指南
- 德州仪器（TI），TPS65217x 原理图检查清单


## 12.3 接收文档更新通知

如需接收文档更新通知，请访问 www．ti．com．cn 网站上的器件产品文件夹。请单击右上角的提醒我进行注册，即可每周接收产品信息更改摘要。有关更改的详细信息，请查阅已修订文档中包含的修订历史记录。

## 12.4 社区资源

下列链接提供到 TI 社区资源的连接。链接的内容由各个分销商＂按照原样＂提供。这些内容并不构成 TI 技术规范，并且不一定反映 TI 的观点；请参阅 TI 的 《使用条款》。
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ESD 的损坏小至导致微小的性能降级，大至整个器件故障。精密的集成电路可能更容易受到损坏，这是因为非常细微的参数更改都可能会导致器件与其发布的规格不相符。

## 12．7 Glossary

SLYZ022－TI Glossary．
This glossary lists and explains terms，acronyms，and definitions．

## 13 机械，封装和可订购信息

以下页面包含机械，封装和可订购信息。这些信息是针对指定器件可提供的最新数据。数据如有变更，恕不另行通知，且不会对此文档进行修订。如需获取此数据表的浏览器版本，请查看左侧的导航面板。

## PACKAGING INFORMATION

| Orderable Device | Status <br> (1) | Package Type | Package Drawing | Pins | Package Qty | Eco Plan <br> (2) | Lead finish/ Ball material <br> (6) | MSL Peak Temp <br> (3) | Op Temp ( ${ }^{\circ} \mathrm{C}$ ) | Device Marking (4/5) | Samples |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| TPS65217ARSLR | ACTIVE | VQFN | RSL | 48 | 2500 | RoHS \& Green | NIPDAU | Level-3-260C-168 HR | -40 to 105 | TPS <br> 65217A | Samples |
| TPS65217ARSLT | ACTIVE | VQFN | RSL | 48 | 250 | RoHS \& Green | NIPDAU | Level-3-260C-168 HR | -40 to 105 | TPS 65217A | Samples |
| TPS65217BRSLR | ACTIVE | VQFN | RSL | 48 | 2500 | RoHS \& Green | NIPDAU | Level-3-260C-168 HR | -40 to 105 | TPS 65217B | Samples |
| TPS65217BRSLT | ACTIVE | VQFN | RSL | 48 | 250 | RoHS \& Green | NIPDAU | Level-3-260C-168 HR | -40 to 105 | TPS <br> 65217B | Samples |
| TPS65217CRSLR | ACTIVE | VQFN | RSL | 48 | 2500 | RoHS \& Green | NIPDAU | Level-3-260C-168 HR | -40 to 105 | TPS 65217C | Samples |
| TPS65217CRSLT | ACTIVE | VQFN | RSL | 48 | 250 | RoHS \& Green | NIPDAU | Level-3-260C-168 HR | -40 to 105 | TPS <br> 65217C | Samples |
| TPS65217DRSLR | ACTIVE | VQFN | RSL | 48 | 2500 | RoHS \& Green | NIPDAU | Level-3-260C-168 HR | -40 to 105 | $\begin{aligned} & \text { TPS } \\ & \text { 65217D } \end{aligned}$ | Samples |
| TPS65217DRSLT | ACTIVE | VQFN | RSL | 48 | 250 | RoHS \& Green | NIPDAU | Level-3-260C-168 HR | -40 to 105 | TPS <br> 65217D | Samples |

${ }^{(1)}$ The marketing status values are defined as follows:
ACTIVE: Product device recommended for new designs.
LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design
PREVIEW: Device has been announced but is not in production. Samples may or may not be available.
OBSOLETE: TI has discontinued the production of the device.

[^2]${ }^{(5)}$ Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a " $\sim$ " will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
${ }^{(6)}$ Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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## TAPE AND REEL INFORMATION



QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE


| Device | Package Type | Package Drawing | Pins | SPQ | Reel Diameter $(\mathrm{mm})$ | Reel Width W1 (mm) | $\begin{gathered} \text { A0 } \\ (\mathrm{mm}) \end{gathered}$ | $\begin{gathered} \text { B0 } \\ (\mathrm{mm}) \end{gathered}$ | $\begin{gathered} \mathrm{KO} \\ (\mathrm{~mm}) \end{gathered}$ | $\begin{gathered} \text { P1 } \\ (\mathrm{mm}) \end{gathered}$ | $\begin{gathered} \text { W } \\ (\mathrm{mm}) \end{gathered}$ | Pin1 Quadrant |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| TPS65217ARSLR | VQFN | RSL | 48 | 2500 | 330.0 | 16.4 | 6.3 | 6.3 | 1.1 | 12.0 | 16.0 | Q2 |
| TPS65217ARSLT | VQFN | RSL | 48 | 250 | 180.0 | 16.4 | 6.3 | 6.3 | 1.1 | 12.0 | 16.0 | Q2 |
| TPS65217BRSLR | VQFN | RSL | 48 | 2500 | 330.0 | 16.4 | 6.3 | 6.3 | 1.1 | 12.0 | 16.0 | Q2 |
| TPS65217BRSLT | VQFN | RSL | 48 | 250 | 180.0 | 16.4 | 6.3 | 6.3 | 1.1 | 12.0 | 16.0 | Q2 |
| TPS65217CRSLR | VQFN | RSL | 48 | 2500 | 330.0 | 16.4 | 6.3 | 6.3 | 1.1 | 12.0 | 16.0 | Q2 |
| TPS65217CRSLT | VQFN | RSL | 48 | 250 | 180.0 | 16.4 | 6.3 | 6.3 | 1.1 | 12.0 | 16.0 | Q2 |
| TPS65217DRSLR | VQFN | RSL | 48 | 2500 | 330.0 | 16.4 | 6.3 | 6.3 | 1.1 | 12.0 | 16.0 | Q2 |
| TPS65217DRSLT | VQFN | RSL | 48 | 250 | 180.0 | 16.4 | 6.3 | 6.3 | 1.1 | 12.0 | 16.0 | Q2 |


*All dimensions are nominal

| Device | Package Type | Package Drawing | Pins | SPQ | Length (mm) | Width (mm) | Height (mm) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| TPS65217ARSLR | VQFN | RSL | 48 | 2500 | 367.0 | 367.0 | 38.0 |
| TPS65217ARSLT | VQFN | RSL | 48 | 250 | 210.0 | 185.0 | 35.0 |
| TPS65217BRSLR | VQFN | RSL | 48 | 2500 | 367.0 | 367.0 | 38.0 |
| TPS65217BRSLT | VQFN | $R S L$ | 48 | 250 | 210.0 | 185.0 | 35.0 |
| TPS65217CRSLR | VQFN | RSL | 48 | 2500 | 367.0 | 367.0 | 38.0 |
| TPS65217CRSLT | VQFN | RSL | 48 | 250 | 210.0 | 185.0 | 35.0 |
| TPS65217DRSLR | VQFN | $R S L$ | 48 | 2500 | 367.0 | 367.0 | 38.0 |
| TPS65217DRSLT | VQFN | $R S L$ | 48 | 250 | 210.0 | 185.0 | 35.0 |



NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.
B. This drawing is subject to change without notice.
C. Quad Flatpack, No-leads (QFN) package configuration.
D. The package thermal pad must be soldered to the board for thermal and mechanical performance.
E. See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.

RSL (S-PVQFN-N48)

## THERMAL INFORMATION

This package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. The thermal pad must be soldered directly to the printed circuit board (PCB). After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For information on the Quad Flatpack No-Lead (QFN) package and its advantages, refer to Application Report, QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271. This document is available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.


Bottom View<br>Exposed Thermal Pad Dimensions

4207841-4/P 03/13
NOTE: All linear dimensions are in millimeters

RSL (S-PVQFN-N48)

## PLASTIC QUAD FLATPACK NO-LEAD

## Example Board Layout

Example Stencil Design
0.125 Thick Stencil
(Note E)

(61\% Printed Solder Coverage by Area)


NOTES:
A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Publication IPC-7351 is recommended for alternate designs.
D. This package is designed to be soldered to a thermal pad on the board. Refer to Application Note, QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com [http://www.ti.com](http://www.ti.com).
E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC 7525 for stencil design considerations.
F. Customers should contact their board fabrication site for recommended solder mask tolerances and via tenting recommendations for vias placed in the thermal pad.

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[^0]:    (1) Not tested in production

[^1]:    (3) Can be factory disabled.

[^2]:    ${ }^{(2)}$ RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed $0.1 \%$ by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. Tl may reference these types of products as "Pb-Free".
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    ${ }^{(3)}$ MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
    ${ }^{(4)}$ There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

