

## 带有 5.5V 至 18V 输入电压、固定 5V 输出电压和 4A 最大电流的双配电开关和单片同步降压稳压器

 查询样品: [TPS65280](#)

### 特性

#### 集成型双配电开关

- 运行输入电压的范围: **2.5V 到 6V**
- 接通阻抗为 **80mΩ** 的集成型背靠背功率金属氧化物场效应晶体管 (**MOSFET**)
- 高达 **1A** 最大负载电流
- 典型值 **1.2A** 上的电流限制 (还提供 **0.8A**, **1.6A** 或者 **2A** 的生产调整选项)
- 锁存过流保护版本
- 反向输入-输出电压保护
- 内置软启动
- 电源开关输出引脚上的 **4KV** 人体模型 (**HBM**) 和 **200V MM ESD** 保护
- 用 **10μF** 外部电容实现符合 **IEC 61000-4-2** 标准的 **15kV** 静电放电 (**ESD**) 保护
- 过温保护
- **24** 导线四方扁平无引线 (**QFN**)(**REG**) **4mm x 4mm** 封装

#### 集成型降压 DC/DC 转换器

- 宽输入电压范围: **5.5V 至 18V**
- 最大持续 **4A** 输出负载电流
- 固定输出电压: **5V±1%**
- **300kHz 至 1.4MHz** 间可调开关频率
- 外部时钟同步
- 具有  
内置 **1ms** 内部软启动时间的可调软启动和跟踪
- 逐周期电流限制
- 输出过压保护

#### 应用范围

- **USB** 端口和集线器
- 数字电视
- 机顶盒
- 网络语音 (**VOIP**) 电话
- 平板个人电脑

### 说明/订购信息

TPS65280 组装有一个用于 USB 配电系统的双 N 通道 MOSFET 电源开关, 此配电系统在一个单封装内需要双电源开关。它还集成了一个降压转换器, 此转换器将一个来自 5.5V 至 18V 电源总线的电压调节为一个精准的 5V 输出电压为电源开关供电。此器件用于为数字电视、机顶盒、VOIP 电话和平板电脑提供一个总体的 USB 配电解决方案, 在这些应用中需要精确电流限制或者有可能出现高电容负载或者短路。

当输出电流负载超过电流限制阈值时, 一个双 85mΩ 独立配电开关将输出电流限制在 1.2A (典型值) (提供 0.8A, 1.6A, 2A 的制造调整选项)。当输出负载超过电流限制阈值时, 通过使用一个恒定电流模式, TPS65280 器件将输出电流限制在一个安全水平上。在抗尖峰脉冲时间之后, 通过在过流或者反向电压情况下锁存电源开关, TPS65280 提供电路断路器功能。两个背靠背功率 MOSFET 防止关断时电流从输出注入输入。当输出电压被驱动至高于输入时, 一个内部反向电压比较器将电源开关禁用来保护正常运行时的开关输入端。在过流和反向电压情况下, nFAULT1/2 输出被置为低电平有效。

为了优化功效并减少用于实现一个固定 5V 输出电压的外部组件数量, 降压 DC/DC 转换器集成了功率 MOSFET。到降压转换器的宽 5.5V 至 18V 输入电源电压包括大多数运行自 9V, 12V 或者 15V 电源总线的的中间总线电压。恒定频率模式峰值电流模式简化了补偿并提供快速瞬态响应。装备有使能和软启动引脚, 为了与系统的其它电源轨保持一致, 可对 DC/DC 进行精准排序和斜升操作。逐周期过流保护和运行在断续模式限制了 MOSFET 在降压输出短路或者过载故障条件下的耗散。由于 ROSC 引脚上有一个外部电阻器, 转换器的开关频率可在 300kHz 至 1.4MHz 之间设定。由于 ROSC 引脚连接到 V7V 引脚, 悬空, 或者接地, 可选择一个缺省固定开关频率来减少外部组件。内部振荡器的频率可与一个自由振荡模式的外部时钟同步。



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

当持续的高过载或者短路增加了降压转换器或者电源开关的功率耗散时，内部热保护电路关闭降压调节器和电源开关来防止器件损坏。一旦器件充分冷却，此器件将自动从热关断中恢复。

TPS65280 采用一个 24 导线散热增强型 QFN (RGE) 4mm x 4mm 薄型封装。

### ORDERING INFORMATION<sup>(1)</sup>

T <sub>A</sub>	PACKAGE <sup>(2)</sup>	ORDERABLE PART NUMBER	TOP-SIDE MARKING
-40°C to 85°C	24-Pin QFN (RGE)	Reel 3000	TPS65280RGER
		Reel 250	TPS65280RGET
			TPS65280

(1) For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI web site at [www.ti.com](http://www.ti.com).

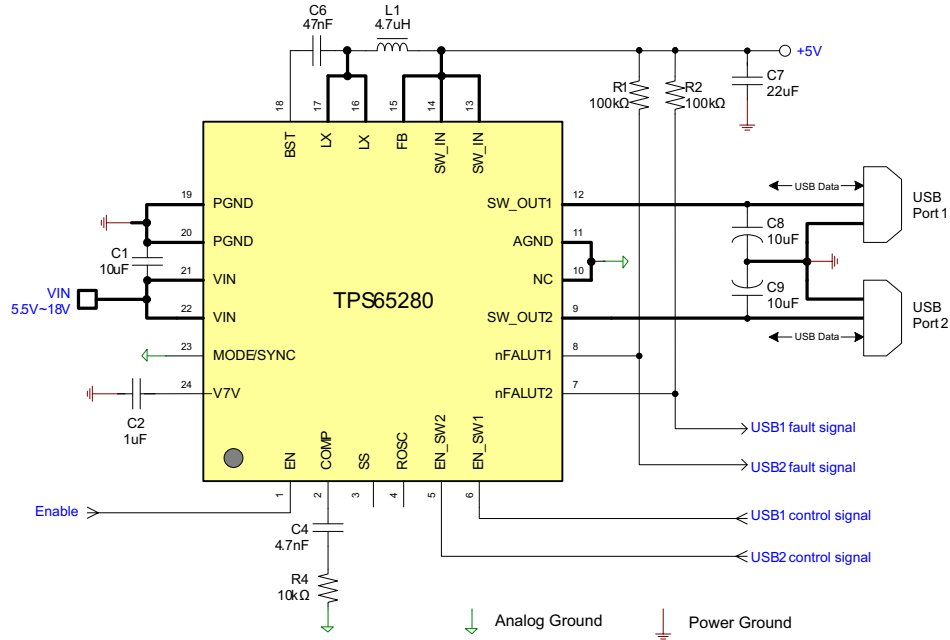
(2) Package drawings, thermal data, and symbolization are available at [www.ti.com/packaging](http://www.ti.com/packaging).



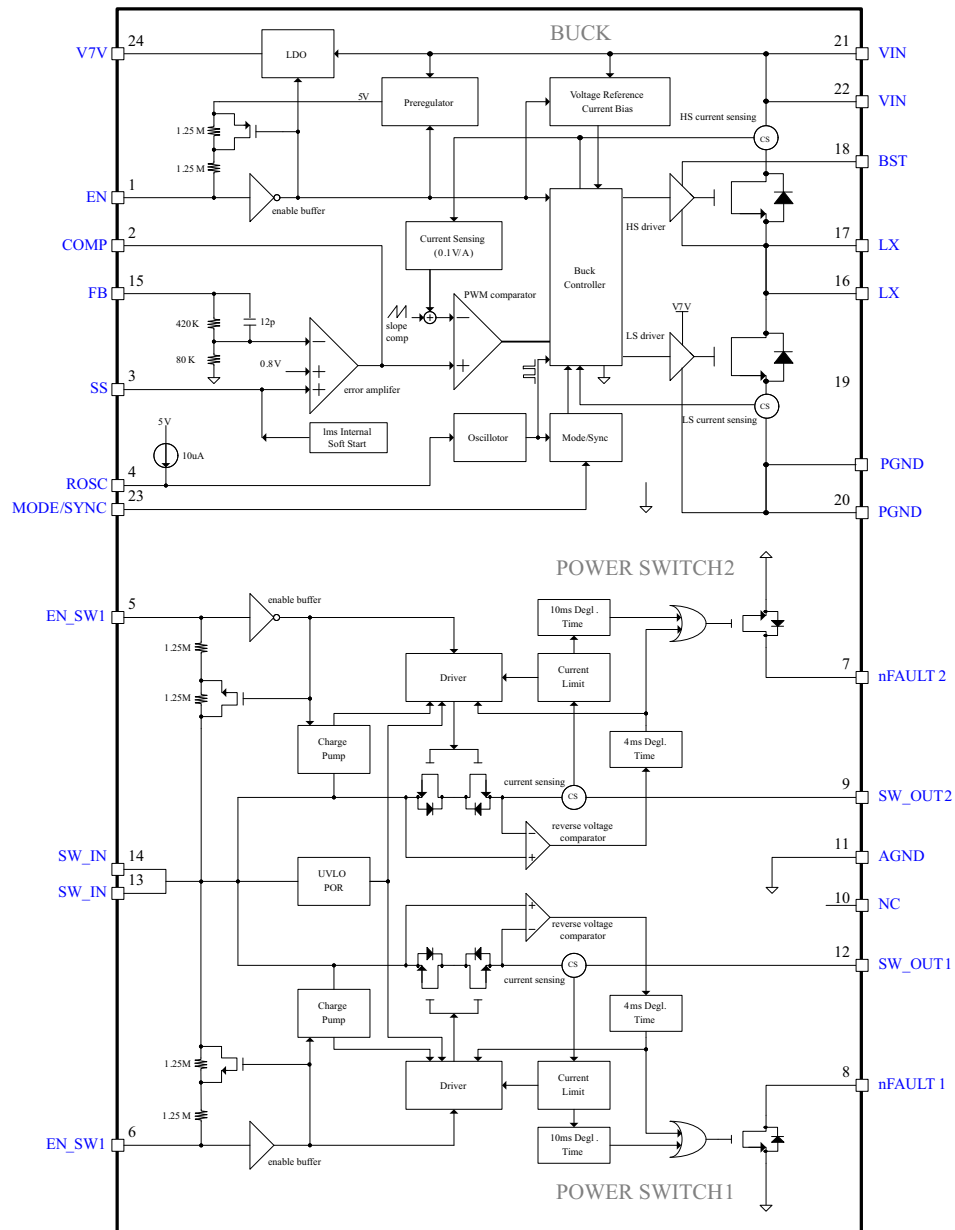
This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

**TYPICAL APPLICATION**

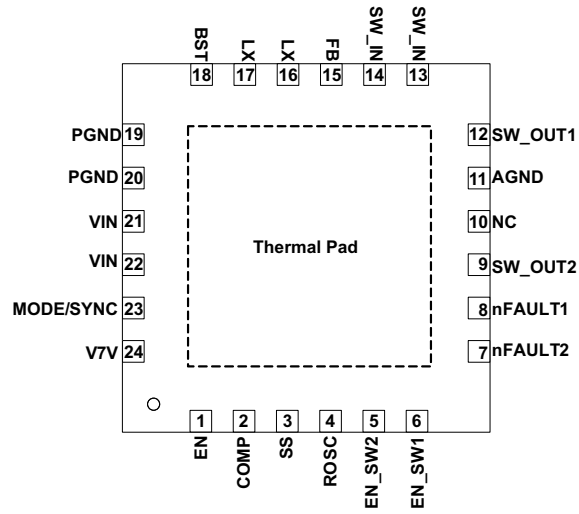


FUNCTION BLOCK DIAGRAM



## PIN OUT

### RGE PACKAGE (TOP VIEW)



There is no electric signal down bonded to thermal pad inside IC. Exposed thermal pad must be soldered to PCB for optimal thermal performance.

**TERMINAL FUNCTIONS**

NAME	NO.	DESCRIPTION
EN	1	Enable for buck converter. Logic high enables buck converter and bias supply to power switches. Forcing the pin below 0.4 V shuts down the entire device, reducing the quiescent current to approximately 7 $\mu$ A. There is a 1.25-M $\Omega$ pull-up resistor connecting this pin to internal 5-V power rail. Not recommend floating this pin. The device can be automatically started up with connecting EN pin to VIN though a 10-k $\Omega$ resistor or connecting a capacitor to program the delay of enabling the device.
COMP	2	Error amplifier output and Loop compensation pin for buck. Connect a series resistor and capacitor to compensate the control loop of buck converter with peak current PWM mode.
SS	3	Soft-start and tracking input for buck converter. An internal 5- $\mu$ A pull-up current source is connected to this pin. An external soft-start can be programmed by connecting a capacitor between this pin and ground. Leave the pin floating to have a default 1 ms of soft-start time. This pin allows the start-up of buck output to track an external voltage using an external resistor divider at this pin.
ROSC	4	Oscillator clock frequency control pin. Connect the pin to ground for a fixed 300-kHz switching frequency. Connect the pin to V7V or float the pin for a fixed 600-kHz switching frequency. Other switch frequency between 300 kHz to 1.4 MHz can be programmed using a resistor connected from this pin to ground. An internal 10- $\mu$ A pull-up current develops a voltage to be used in oscillator. Directly adjusting the ROSC pin voltage can linearly adjust switching frequency.
EN_SW2	5	Enable power switch 2. Logic high turns on power switch. Forcing the pin below 0.4 V shuts down power switch. Not recommend floating this pin, though there is a 1.25-M $\Omega$ pull-up resistor connecting this pin.
EN_SW1	6	Enable power switch 1. Logic high turns on power switch. Forcing the pin below 0.4 V shuts down power switch. Not recommend floating this pin, though there is a 1.25-M $\Omega$ pull-up resistor connecting this pin.
nFAULT2	7	Active low open drain output, asserted during over-current or reverse-voltage condition of power switch 2.
nFAULT1	8	Active low open drain output, asserted during over-current or reverse-voltage condition of power switch 1.
SW_OUT2	9	Power switch 2 output.
NC	10	No connection. Connection to ANGD recommended.
AGND	10, 11	Analog ground common to buck controller and power switch controller. Pin 10 must be routed separately from high current power grounds to the (-) terminal of bypass capacitor of internal V7V LDO output.
SW_OUT1	12	Power switch 1 output.
SW_IN	13, 14	Power switch input voltage. Connect to buck output, or other power supply input.
FB	15	Kelvin sensing pin for +5-V buck output voltage. Connect this pin to the (+) terminal of buck output capacitor. The internal feedback resistor divider (420 k $\Omega$ /80 k $\Omega$ ) in buck converter sets a fixed 5-V $\pm$ 1% output voltage at room temperature.
LX	16, 17	Switching node connection to the inductor and bootstrap capacitor for buck converter. This pin voltage swings from a diode voltage below the ground up to V <sup>IN</sup> voltage.
BST	18	Bootstrapped supply to the high side floating gate driver in buck converter. Connect a capacitor (47 nF recommended) from this pin to LX.
PGND	19, 20	Power ground connection. Connect this pin as close as practical to the (-) terminal of input ceramic capacitor.
VIN	21, 22	Input power supply for buck. Connect this pin as close as practical to the (+) terminal of an input ceramic capacitor (10 $\mu$ F recommended).
MODE/SYNC	23	External synchronization input to internal clock oscillator in forced continuous mode. When an external clock is applied to this pin, the internal oscillator will force the rising edge of clock signal to be synchronized with the rising edge of the external clock. When not synchronizing to an external clock, connecting this pin to ground forces a continuous current mode (CCM) operation of Buck.
V7V	24	Internal low-drop linear regulator (LDO) output. The internal driver and control circuits are powered from this voltage. Decouple this pin to power ground with a minimum 1- $\mu$ F ceramic capacitor. The output voltage level of LDO is regulated to typical 6.3 V for optimal conduction on-resistances of internal power MOSFETs. In PCB design, the power ground and analog ground should have one-point common connection at the (-) terminal of V7V bypass capacitor.
Thermal PAD		Exposed pad beneath the IC. Connect to the power ground. Always solder thermal pad to the board, and have as many vias as possible on the PCB to enhance power dissipation. There is no electric signal down bonded to the thermal pad inside the IC package.

## ABSOLUTE MAXIMUM RATINGS <sup>(1)</sup>

over operating free-air temperature range (unless otherwise noted)

VIN, LX		–0.3 to 18	V
LX (Maximum withstand voltage transient < 20ns)		–1.0 to 18	V
BST referenced to LX pin		–0.3 to 7	V
SW_IN, SW_OUT1, SW_OUT2		–0.3 to 7	V
EN, EN_SW1, EN_SW2, nFAULT1, nFAULT2, V7V, ROSC, MODE/SYNC		–0.3 to 7	V
SS, COMP		–0.3 to 3.6	V
V7, R AGND, PGND		–0.3 to 0.3	V
T <sub>J</sub>	Operating virtual junction temperature range	–40 to 125	°C
T <sub>STG</sub>	Storage temperature range	–55 to 150	°C

- (1) Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute–maximum–rated conditions for extended periods may affect device reliability.

## RECOMMENDED OPERATING CONDITIONS

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
VIN	Input operating voltage	5.5		18	V
T <sub>A</sub>	Ambient temperature	–40		85	°C

## ELECTROSTATIC DISCHARGE (ESD) PROTECTION <sup>(1)</sup>

	MIN	MAX	UNIT
Human body model (HBM)	2000		V
Charge device model (CDM)	500		V

- (1) SW\_OUT1/2 pins' human body model (HBM) ESD protection rating 4 kV, and machine model (MM) rating 200V.

## THERMAL INFORMATION

THERMAL METRIC <sup>(1)</sup>	TPS65280	UNITS
	RGE	
	24 PINS	
θ <sub>JA</sub> Junction-to-ambient thermal resistance <sup>(2)</sup>	38.1	°C/W
θ <sub>JCtop</sub> Junction-to-case (top) thermal resistance <sup>(3)</sup>	45.3	
θ <sub>JB</sub> Junction-to-board thermal resistance <sup>(4)</sup>	16.9	
ψ <sub>JT</sub> Junction-to-top characterization parameter <sup>(5)</sup>	0.9	
ψ <sub>JB</sub> Junction-to-board characterization parameter <sup>(6)</sup>	16.9	
θ <sub>JCbot</sub> Junction-to-case (bottom) thermal resistance <sup>(7)</sup>	6.2	

- (1) 有关传统和新的热 度量的更多信息，请参阅 *IC 封装热量应用报告*，[SPRA953](#)。
- (2) 在 JESD51-2a 描述的环境中，按照 JESD51-7 的指定，在一个 JEDEC 标准高 K 电路板上进行仿真，从而获得自然 对流条件下的结至环境热阻。
- (3) 通过在封装顶部模拟一个冷板测试来获得结至芯片外壳（顶部）的热阻。不存在特定的 JEDEC 标准测试，但可在 ANSI SEMI 标准 G30-88 中找到内容接近的说明。
- (4) 按照 JESD51-8 中的说明，通过 在配有用于控制 PCB 温度的环形冷板夹具的环境中进行仿真，以获得结板热阻。
- (5) 结至顶部特征参数，ψ<sub>JT</sub>，估算真实系统中器件的结温，并使用 JESD51-2a（第 6 章和第 7 章）中 描述的程序从仿真数据中提取出该参数以便获得 θ<sub>JA</sub>。
- (6) 结至电路板特征参数，ψ<sub>JB</sub>，估算真实系统中器件的结温，并使用 JESD51-2a（第 6 章和第 7 章）中 描述的程序从仿真数据中提取出该参数以便获得 θ<sub>JA</sub>。
- (7) 通过在外露（电源）焊盘上进行冷板测试仿真来获得 结至芯片外壳（底部）热阻。不存在特定的 JEDEC 标准 测试，但可在 ANSI SEMI 标准 G30-88 中找到内容接近的说明。

## ELECTRICAL CHARACTERISTICS

T<sub>J</sub> = 25°C, V<sub>IN</sub> = 12 V, f<sub>SW</sub> = 600 kHz, R<sub>nFAULTx</sub> = 100 kΩ (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>INPUT SUPPLY</b>						
V <sub>IN</sub>	Input voltage range	VIN1 and VIN2	5.5		18	V
IDD <sub>SDN</sub>	Shutdown supply current	EN = EN_SW1 = EN_SW2 = low		7	20	μA
IDD <sub>Q_NSW</sub>	Switching quiescent current with no load at DCDC output	EN = high, EN_SWx = low, FB = 6 V With Buck not switching		0.8		mA
IDD <sub>Q_SW</sub>	Switching quiescent current with no load at DCDC output, Buck switching	EN = high, EN_SWx = low, FB = 5 V With Buck switching		13		mA
UVLO	V <sub>IN</sub> under voltage lockout	Rising V <sub>IN</sub>	4	4.25	4.50	V
		Falling V <sub>IN</sub>	3.75	4	4.25	
		Hysteresis		0.25		
V <sub>7V</sub>	Internal biasing supply	V <sub>7V</sub> load current = 0 A, V <sub>IN</sub> = 12 V	6.05	6.25	6.45	V
<b>OSCILLATOR</b>						
f <sub>SW_BK</sub>	Switching frequency range	Set by external resistor ROSC	300		1400	kHz
f <sub>SW</sub>	Programmable frequency	ROSC = 51 kΩ		500		kHz
		ROSC = 140 kΩ		1400		
		ROSC floating or connected to V7V	510	600	690	
		ROSC connected to ground	255	300	345	
<b>BUCK CONVERTER</b>						
V <sub>IN</sub>	Input supply voltage	For a fixed 5-V output	5.5		18	V
V <sub>OUT</sub>	Regulated +5-V output voltage	V <sub>COMP</sub> = 1.2 V, T <sub>J</sub> = 25°C	4.95	5	5.05	V
		V <sub>COMP</sub> = 1.2 V, T <sub>J</sub> = -40°C to 125°C	4.9	5	5.1	
V <sub>LINREG</sub>	Line regulation - DC	I <sub>OUT</sub> = 2 A		0.5		%/V
V <sub>LOADREG</sub>	Load regulation - DC	I <sub>OUT</sub> = (10% - 90%) × I <sub>OUT_max</sub>		0.5		%/A
G <sub>m_EA</sub>	Error amplifier trans-conductance <sup>(1)</sup>	-2 μA < I <sub>COMP</sub> < 2 μA		520		μs
G <sub>m_SRC</sub>	COMP voltage to inductor current G <sub>m</sub> <sup>(1)</sup>	I <sub>LX</sub> = 0.5 A		10		A/V
V <sub>ENH</sub>	EN high level input voltage		2			V
V <sub>ENL</sub>	EN low level input voltage				0.4	V
I <sub>SS</sub>	Soft-start charging current			4.5		μA
t <sub>SS_INT</sub>	Internal soft-start time	SS pin floats	0.5	1	1.5	ms
I <sub>LIMIT</sub>	Buck peak inductor current limit			5.2		A
R <sub>dson_HS</sub>	On resistance of high side FET in buck	V <sub>7V</sub> = 6.25 V		80		mΩ
R <sub>dson_LS</sub>	On resistance of low side FET in buck	V <sub>IN</sub> = 12 V		50		mΩ
<b>POWER DISTRIBUTION SWITCH</b>						
V <sub>SW_IN</sub>	Power switch input voltage range		2.5		6	V
V <sub>UVLO_SW</sub>	Input under-voltage lock out	V <sub>SW_IN</sub> rising	2.15	2.25	2.35	V
		V <sub>SW_IN</sub> falling	2.05	2.15	2.25	V
		Hysteresis		100		mV
R <sub>DSON_SW</sub>	Power switch NDMOS on-resistance	V <sub>SW_INx</sub> = 5 V, I <sub>SW_OUT</sub> = 0.5 A, T <sub>J</sub> = 25°C, including bond wire resistance		100		mΩ
		V <sub>SW_INx</sub> = 2.5 V, I <sub>SW_OUT</sub> = 0.5 A, T <sub>J</sub> = 25°C, includes bond wire resistance		100		
t <sub>D_on</sub>	Turn-on delay time	V <sub>SW_IN</sub> = 5 V, C <sub>L</sub> = 1 μF, R <sub>L</sub> = 100 Ω (see Figure 1)		1.1		ms
t <sub>D_off</sub>	Turn-off delay time			1.2		ms
t <sub>r</sub>	Output rise time			0.6		ms
t <sub>f</sub>	Output fall time			0.3		ms
I <sub>OCP_SW</sub>	Current limit threshold (maximum DC current delivered to load) and short circuit current, SW_OUTx connect to ground		1.05	1.2	1.35	A
t <sub>IOS</sub>	Response time to short circuit	V <sub>SW_IN</sub> = 5 V		2		us

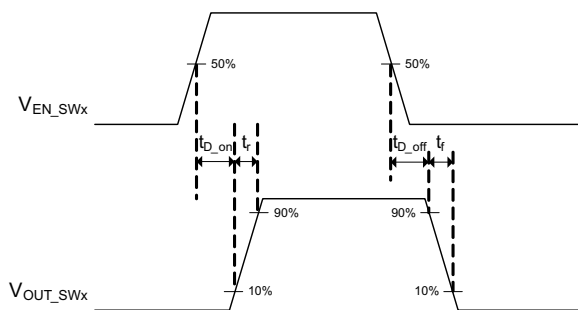
(1) Specified by design.



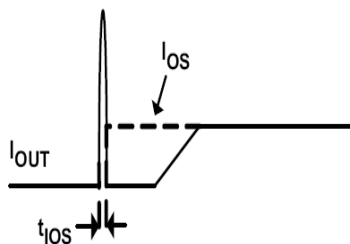
**ELECTRICAL CHARACTERISTICS (continued)**

$T_J = 25^\circ\text{C}$ ,  $V_{IN} = 12\text{ V}$ ,  $f_{SW} = 600\text{ kHz}$ ,  $R_{nFAULTx} = 100\text{ k}\Omega$  (unless otherwise noted)

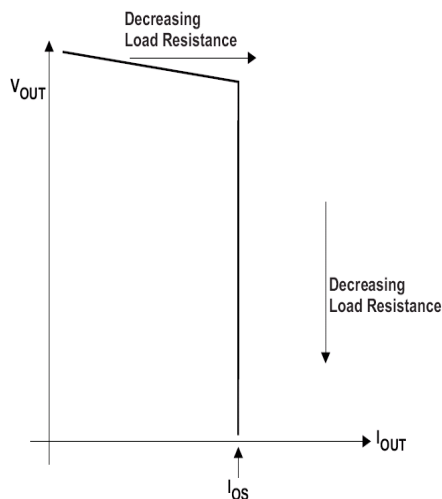
PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$t_{DEGLITCH(OCF)}$	Switch over current fault deglitch	7	10	13	ms
$V_{L_nFAULT}$	nFAULTx pin output low voltage		150		mV
$V_{EN\_SWH}$	EN_SWx high level input voltage	2			V
$V_{EN\_SWL}$	EN_SWx high level input voltage			0.4	V
$R_{DIS}$	Discharge resistance		100		$\Omega$
<b>THERMAL SHUTDOWN</b>					
$T_{TRIP\_BUCK}$	Thermal protection trip point		160		$^\circ\text{C}$
$T_{HYST\_BUCK}$	Thermal protection hysteresis		20		$^\circ\text{C}$



**Figure 1. Power Switches Test Circuit and Voltage Waveforms**



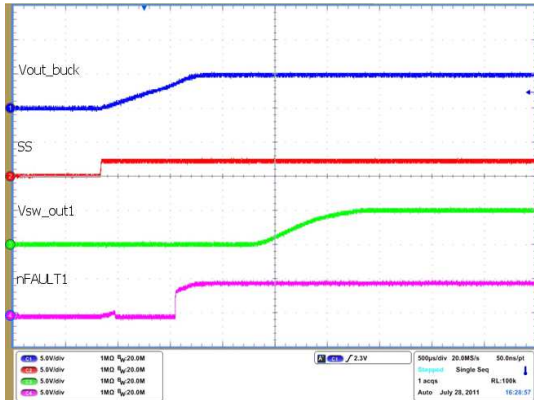
**Figure 2. Response Time to Short Circuit Waveform**



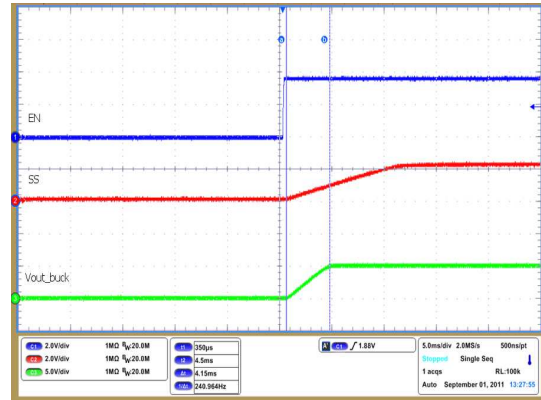
**Figure 3. Output Voltage vs Current Limit Threshold**

**TYPICAL CHARACTERISTICS**

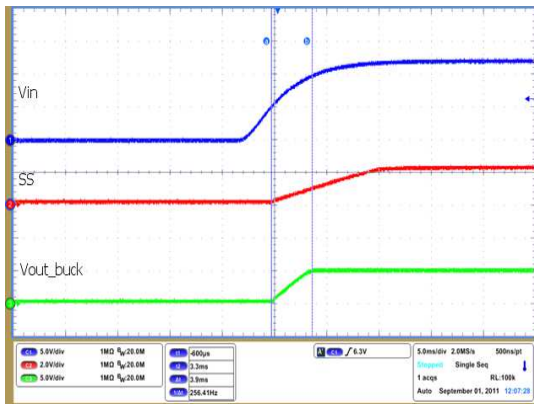
$T_J = 25^\circ\text{C}$ ,  $V_{IN} = 12\text{ V}$ ,  $f_{SW} = 600\text{ kHz}$ ,  $R_{nFAULTx} = 100\text{ k}\Omega$  (unless otherwise noted)



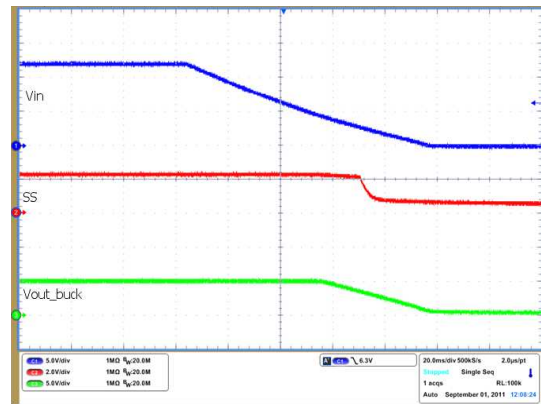
**Figure 4. Buck Start Up by EN Pin With Internal Soft-Start (SS Pin Open)**



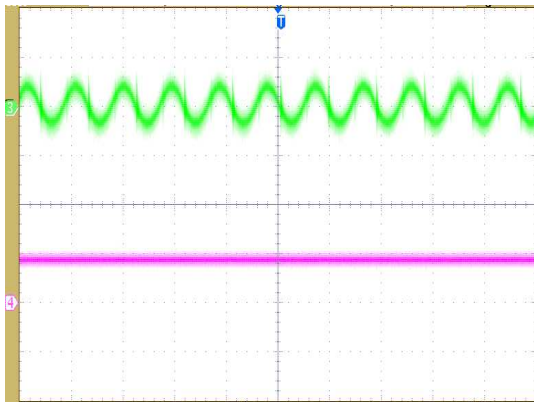
**Figure 5. Buck Start Up by EN Pin With an External 22-nF SS Capacitor**



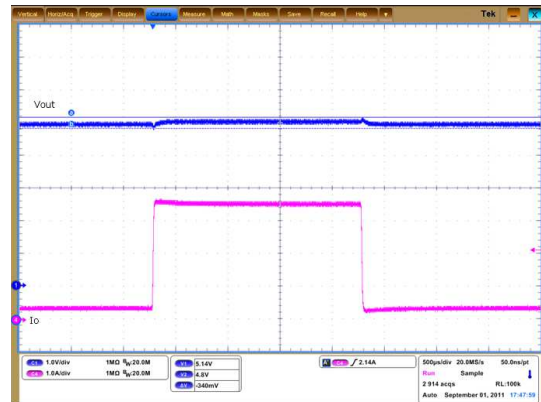
**Figure 6. Ramp  $V_{IN}$  to Start Up Buck With an External 22-nF SS Capacitor**



**Figure 7. Ramp  $V_{IN}$  to Power Down Buck With an External 22-nF SS Capacitor**



**Figure 8. Buck Output Voltage Ripple (Chan3:  $V_{OUT}$ , 10 mV/DIV; Chan4:  $I_O$ , 2A/DIV; Time: 2  $\mu\text{s}$ /DIV)**



**Figure 9. Buck Output Load Transient**

**TYPICAL CHARACTERISTICS (continued)**

$T_J = 25^\circ\text{C}$ ,  $V_{IN} = 12\text{ V}$ ,  $f_{SW} = 600\text{ kHz}$ ,  $R_{nFAULTx} = 100\text{ k}\Omega$  (unless otherwise noted)

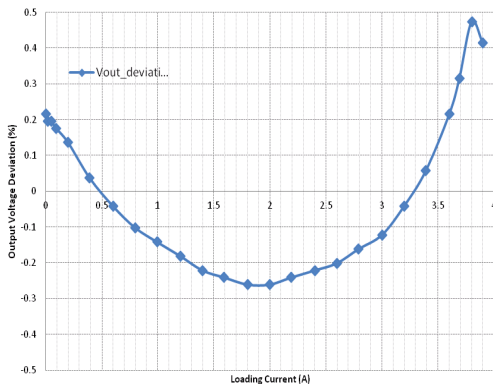


Figure 10. Buck Load Regulation

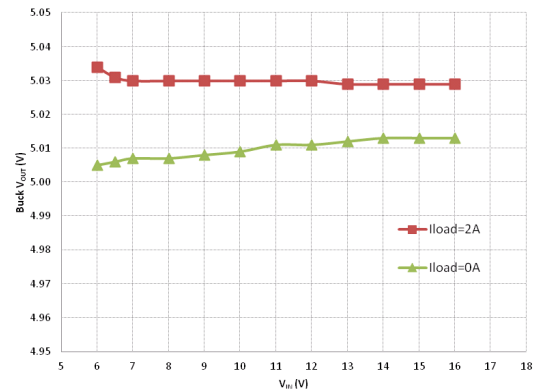


Figure 11. Buck Line Regulation

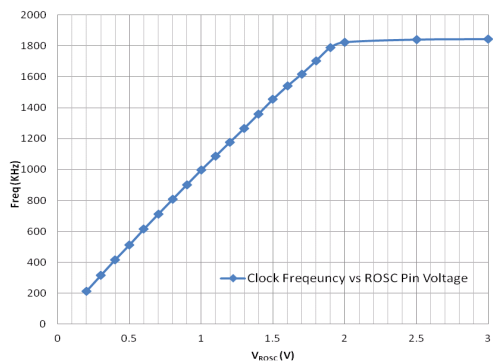


Figure 12. Oscillator Frequency vs Rosc Voltage  
(Note that Select ROSC Resistance =  $V_{ROSC} \times 100\text{ k}\Omega$  for Desired Frequency)

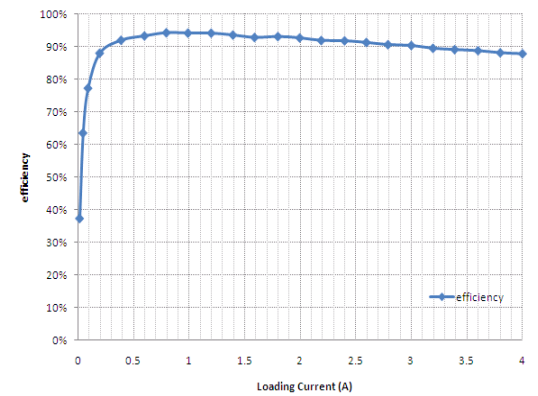


Figure 13. Buck Efficiency

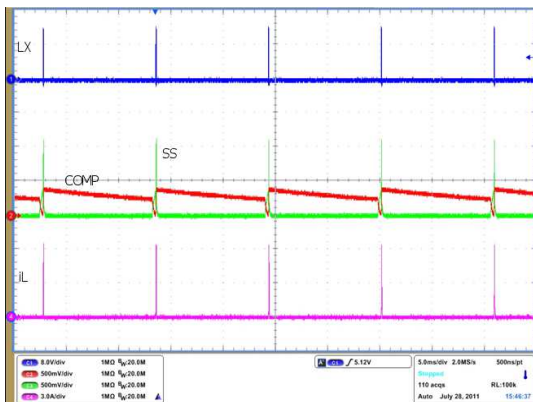


Figure 14. Buck Hiccup Response to Hard-Short Circuit

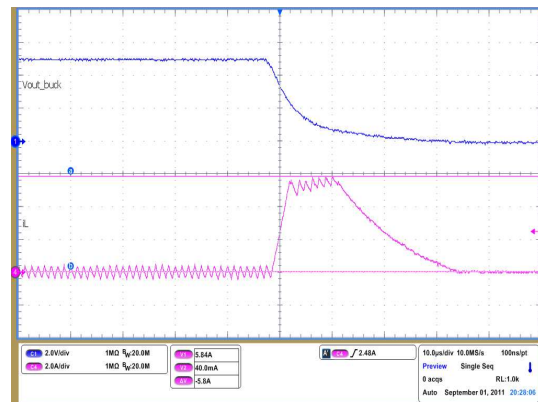
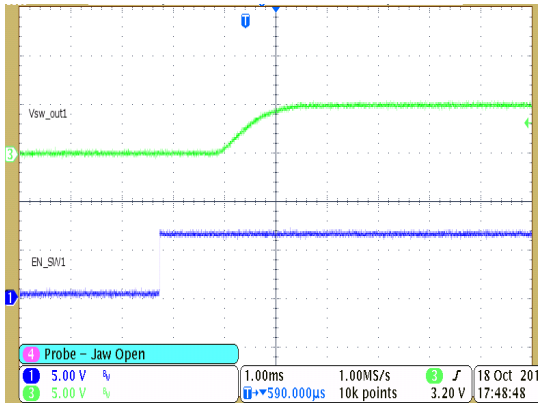


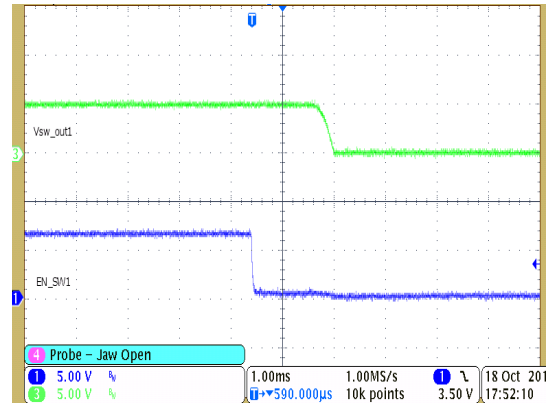
Figure 15. Zoom In Buck Output Hard Short Response

**TYPICAL CHARACTERISTICS (continued)**

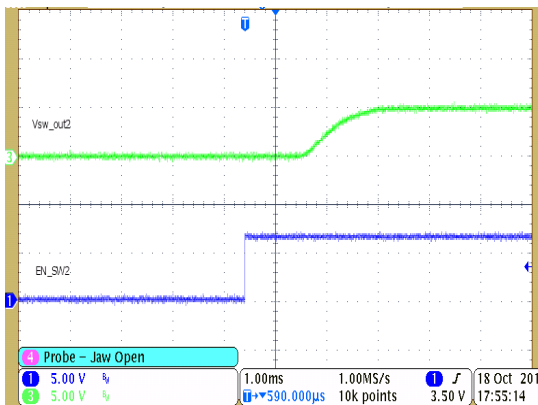
$T_J = 25^\circ\text{C}$ ,  $V_{IN} = 12\text{ V}$ ,  $f_{SW} = 600\text{ kHz}$ ,  $R_{nFAULTx} = 100\text{ k}\Omega$  (unless otherwise noted)



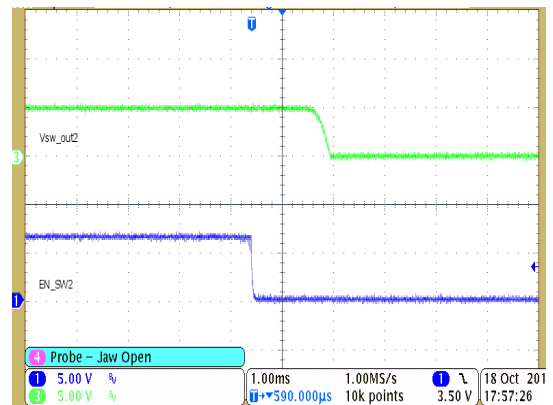
**Figure 16. Power Switch 1 Turn On Delay and Rise Time**  
 $R_{OUT} = 5\ \Omega$ ,  $C_{OUT} = 22\ \mu\text{F}$



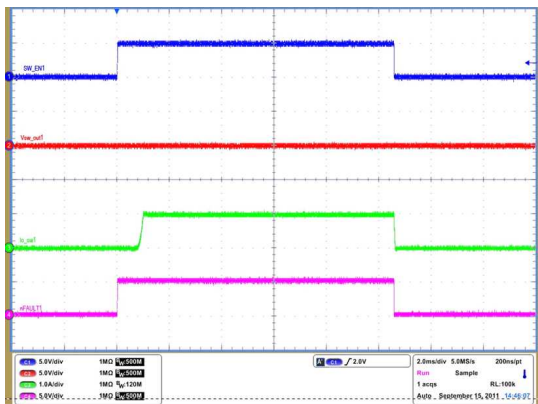
**Figure 17. Power Switch 1 Turn Off Delay and Fall Time**  
 $R_{OUT} = 5\ \Omega$ ,  $C_{OUT} = 22\ \mu\text{F}$



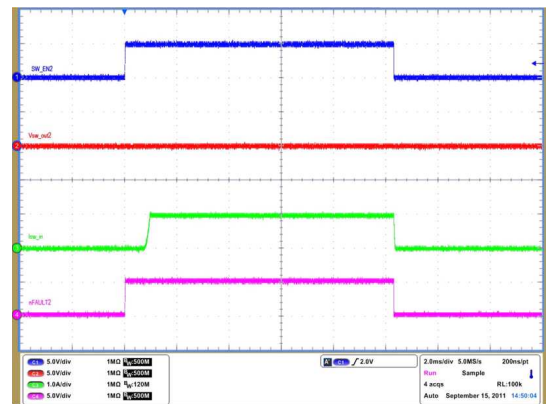
**Figure 18. Power Switch 2 Turn On Delay and Rise Time**  
 $R_{OUT} = 5\ \Omega$ ,  $C_{OUT} = 22\ \mu\text{F}$



**Figure 19. Power Switch 2 Turn Off Delay and Fall Time**  
 $R_{OUT} = 5\ \Omega$ ,  $C_{OUT} = 22\ \mu\text{F}$



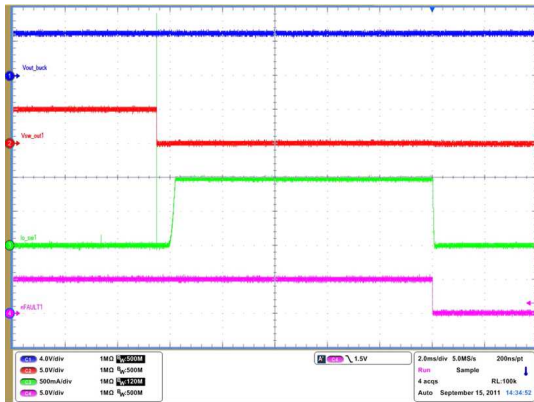
**Figure 20. Power Switch 1 Enable Into Short Circuit**



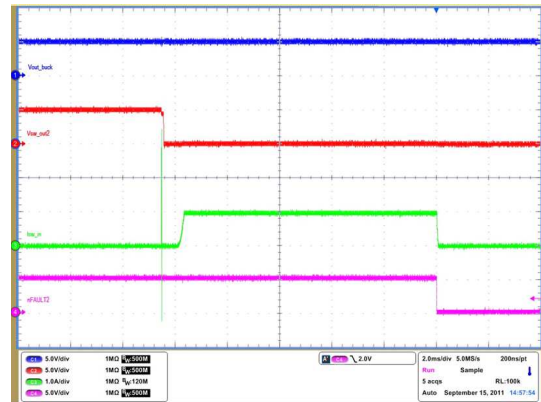
**Figure 21. Power Switch 2 Enable Into Short Circuit**

**TYPICAL CHARACTERISTICS (continued)**

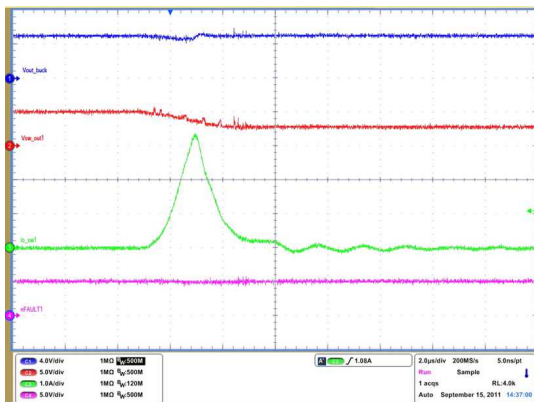
$T_J = 25^\circ\text{C}$ ,  $V_{IN} = 12\text{ V}$ ,  $f_{SW} = 600\text{ kHz}$ ,  $R_{nFAULTx} = 100\text{ k}\Omega$  (unless otherwise noted)



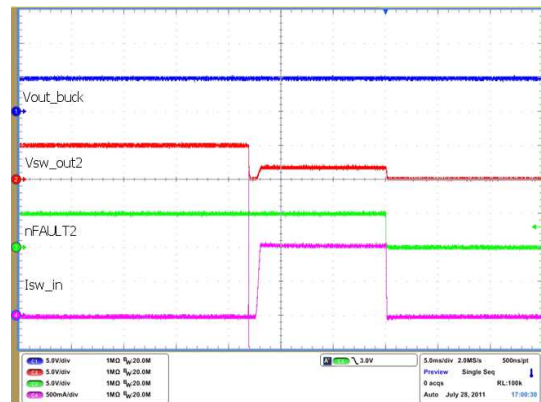
**Figure 22. Power Switch 1 No Load to Short-Circuit Transient Response**



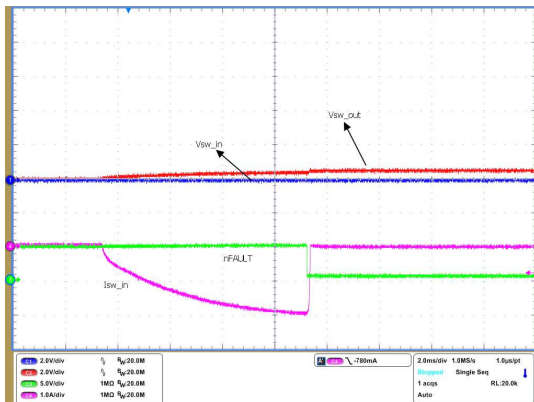
**Figure 23. Power Switch 2 No Load to Short-Circuit Transient Response**



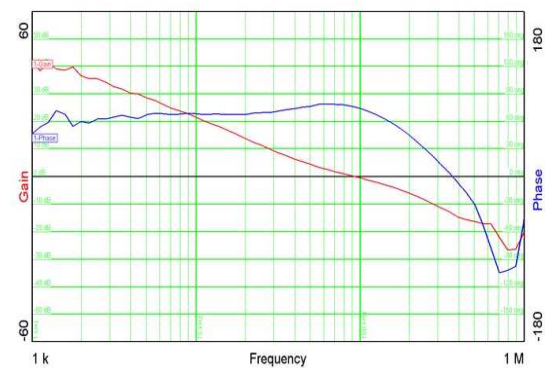
**Figure 24. Power Switch Responses Time ( $T_{IOs}$ ) to Output Hard Short**



**Figure 25. Power Switch No Load to 1- $\Omega$  Transient Response**



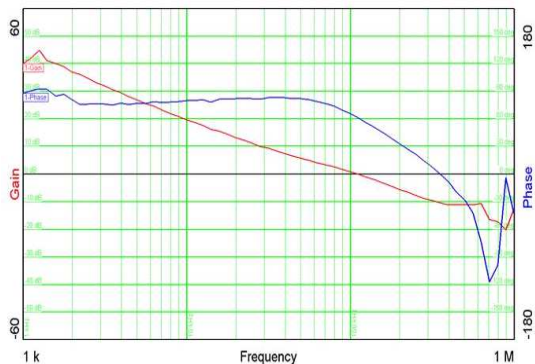
**Figure 26. Power Switch Reverse Voltage Protection Response**



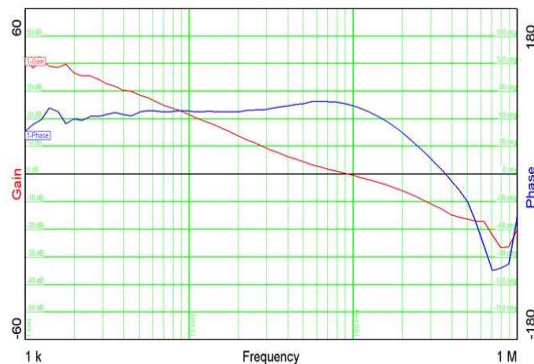
**Figure 27. Bode Plot**  
 $V_{IN} = 12\text{ V}$ ,  $V_{out\_buck} = 5\text{ V}/0.5\text{ A}$ ,  $I_{sw1} = I_{sw2} = 0.8\text{ A}$

**TYPICAL CHARACTERISTICS (continued)**

$T_J = 25^\circ\text{C}$ ,  $V_{IN} = 12\text{ V}$ ,  $f_{SW} = 600\text{ kHz}$ ,  $R_{nFAULTx} = 100\text{ k}\Omega$  (unless otherwise noted)



**Figure 28. Loop Stability Bode Plot**  
 $V_{IN} = 12\text{ V}$ , Buck Loads 0.5 A,  
 Power Switch 1 and 2 Have No Load



**Figure 29. Loop Stability Bode Plot**  
 $V_{IN} = 12\text{ V}$ , Buck Load 0.5 A,  
 Power Switch 1 and 2 Load 0.8 A Each

## OVERVIEW

TPS65280 PMIC integrates two independent current-limited, power distribution switches using N-channel MOSFETs for applications where short circuits or heavy capacitive loads will be encountered and provide up to 1-A of continuous load current. Additional device features include over temperature protection and reverse-voltage protection. The device incorporates an internal charge pump and gate drive circuitry necessary to drive the N-channel MOSFET. The charge pump supplies power to the driver circuit and provides the necessary voltage to pull the gate of the MOSFET above the source. The charge pump operates from the input voltage of power switches as low as 2.5 V and requires little supply current. The driver controls the gate voltage of the power switch. The driver incorporates circuitry that controls the rise and fall times of output voltage to limit large current and voltage surges and provides built-in soft-start functionality. TPS65280 device limits output current to a safe level when the output load exceeds the current limit threshold. After deglitching time, device latches off when the load exceeds the current limit threshold. The device asserts the nFAULT1/2 signal during the over current or reverse voltage faulty condition.

TPS65280 PMIC also integrates a synchronous step-down converter with a fixed 5-V output voltage to provide the power for power switches in the USB ports. The synchronous buck converter incorporates an 80-mΩ high side power MOSFET and 50-mΩ low side power MOSFET to achieve high efficiency power conversion. The converter supports an input voltage range from 5.5 V to 18 V for a fixed 5-V output. The converter operates in continuous conduction mode with peak current mode control for simplified loop compensation. The switching clock frequency can be programmed from 300 kHz to 1.4 MHz from the ROSC pin connection. The peak inductor current limit threshold is internally set at 5 A. The soft-start time can be adjusted with connecting an external capacitor at the SS pin, or fixed at 1 ms with floating at the SS pin.

## POWER SWITCH DETAILED DESCRIPTION

### Over Current Condition

The TPS65280 responds to over-current conditions on power switches by limiting the output currents to the  $I_{OCP\_SW}$  level, which is fixed internally. The load current is less than the current-limit threshold and the device does not limit current. During normal operation the N-channel MOSFET is fully enhanced, and  $V_{SW\_OUT} = V_{SW\_IN} - (I_{SW\_OUT} \times R_{dson\_SW})$ . The voltage drop across the MOSFET is relatively small compared to  $V_{SW\_IN}$ , and  $V_{SW\_OUT} \approx V_{SW\_IN}$ . When an over current condition is detected, the device maintains a constant output current and reduces the output voltage accordingly. During current-limit operation, the N-channel MOSFET is no longer fully enhanced and the resistance of the device increases. This allows the device to effectively regulate the current to the current-limit threshold. The effect of increasing the resistance of the MOSFET is that the voltage drop across the device is no longer negligible ( $V_{SW\_IN} \neq V_{SW\_OUT}$ ), and  $V_{SW\_OUT}$  decreases. The amount that  $V_{SW\_OUT}$  decreases is proportional to the magnitude of the overload condition. The expected  $V_{SW\_OUT}$  can be calculated by  $I_{OCP\_SW} \times R_{LOAD}$ , where  $I_{OCP\_SW}$  is the current-limit threshold and  $R_{LOAD}$  is the magnitude of the overload condition.

The manufacture trim options are available for the current limiting thresholds at 0.8 A, 1.2 A, 1.6 A and 2 A.

Three possible overload conditions can occur as summarized in [Table 1](#).

**Table 1. Possible Overload Conditions**

CONDITIONS	BEHAVIORS
Short circuit or partial short circuit present when the device is powered up or enabled	The output voltage is held near zero potential with respect to ground and the TPS65280 ramps output current to $I_{OCP\_SW}$ . The device limits the current to IOS until the overload condition is removed or the internal deglitch time (10 ms typical) is reached and the device is turned off. The device will remain off until power is cycled or the device enable is toggled.
Gradually increasing load (<100 A/s) from normal operating current to $I_{OCP\_SW}$	The current rises until current limit. Once the threshold has been reached, the device switches into its current limiting at $I_{OCP\_SW}$ . The device limits the current to IOS until the overload condition is removed or the internal deglitch time (10 ms typical) is reached and the device is turned off. The device will remain off until power is cycled or the device enable is toggled.
Short circuit, partial short circuit or fast transient overload occurs while the device is enabled and powered on	The device responds to the over-current condition within time $t_{IOS}$ (see <a href="#">Figure 3</a> ). The current sensing amplifier is overdriven during this time, and needs time for loop response. Once $t_{IOS}$ has passed, the current sensing amplifier recovers and limits the current to $I_{OCP\_SW}$ . The device limits the current to IOS until the overload condition is removed or the internal deglitch time (10 ms typical) is reached and the device is turned off. The device will remain off until power is cycled or the device enable is toggled.

## Reverse Current and Voltage Protection

A power switch in the TPS65280 incorporates two back-to-back N-channel power MOSFETs as to prevent the reverse current flowing back the input through body diode of MOSFET when power switches are off.

The reverse-voltage protection feature turns off the N-channel MOSFET whenever the output voltage exceeds the input voltage by 135 mV (typical) for 4 ms (typical). This prevents damage to devices on the input side of the TPS65280 by preventing significant current from sinking into the input capacitance of power switch or buck output capacitance. The TPS65280 device keeps the power switch turned off even if the reverse-voltage condition is removed and do not allow the N-channel MOSFET to turn on until power is cycled or the device enable is toggled. The reverse-voltage comparator also asserts the nFAULT1/2 output (active-low) after 4 ms.

## nFAULT1/2 Response

The nFAULT1/nFAULT2 open-drain output is asserted (active low) during an over current, over temperature or reverse-voltage condition. The TPS65280 asserts the nFAULT signal during a fault condition and remains asserted while the part is latched-off. The nFAULT signal is de-asserted once device power is cycled or the enable is toggled and the device resumes normal operation. The TPS65280 is designed to eliminate false nFAULT reporting by using an internal delay deglitch circuit for over current (10 ms typical) and reverse-voltage (4 ms typical) conditions without the need for external circuitry. This ensures that nFAULT is not accidentally asserted due to normal operation such as starting into a heavy capacitive load. Deglitching circuitry delays entering and leaving fault conditions. Over temperature conditions are not deglitched and assert the FAULT signal immediately.

## Under-Voltage Lockup (UVLO)

The under-voltage lockout (UVLO) circuit disables the power switch until the input voltage reaches the UVLO turn-on threshold. Built-in hysteresis prevents unwanted on/off cycling due to input voltage drop from large current surges.

## Enable and Output Discharge

The logic enable EN\_SW1/EN\_SW2 controls the power switch, bias for the charge pump, driver, and other circuits. The supply current from power switch driver is reduced to less than 1  $\mu$ A when a logic low is present on EN\_SW1/2. A logic high input on EN\_SW1/EN\_SW2 enables the driver, control circuits, and power switch. The enable input is compatible with both TTL and CMOS logic levels.

When enable is de-asserted, the discharge function is active. The output capacitor of power switch is discharged through an internal NMOS that has a discharge resistance of 100  $\Omega$ . Hence, the output voltage drops down to zero. The time taken for discharge is dependent on the RC time constant of the resistance and the output capacitor.

## Power Switch Input and Output Capacitance

Input and output capacitance improves the performance of the device. The actual capacitance should be optimized for the particular application. It is recommended to place the output capacitor in the buck converter between SW\_IN and AGND as close to the device as possible for local noise de-coupling. Additional capacitance may be needed on the input to reduce voltage overshoot from exceeding the absolute maximum voltage of the device during heavy transient conditions. This is especially important during bench testing when long, inductive cables are used to connect the input of power switches in the evaluation board to the bench power-supply.

Placing a high-value electrolytic capacitor on the output pin is recommended when large transient currents are expected on the output.



## UNIVERSAL SERIAL BUS (USB) POWER-DISTRIBUTION REQUIREMENTS

One application for this device is for current limiting in universal serial bus (USB) applications. The original USB interface was a 12-Mb/s or 1.5-Mb/s, multiplexed serial bus designed for low-to-medium bandwidth PC peripherals (e.g., keyboards, printers, scanners, and mice). As the demand for more bandwidth increased, the USB 2.0 standard was introduced increasing the maximum data rate to 480-Mb/s. The four-wire USB interface is conceived for dynamic attach-detach (hot plug-unplug) of peripherals. Two lines are provided for differential data, and two lines are provided for 5-V power distribution.

USB data is a 3.3-V level signal, but power is distributed at 5 V to allow for voltage drops in cases where power is distributed through more than one hub across long cables. Each function must provide its own regulated 3.3 V from the 5-V input or its own internal power supply. The USB specification classifies two different classes of devices depending on its maximum current draw. A device classified as low-power can draw up to 100 mA as defined by the standard. A device classified as high-power can draw up to 500 mA. It is important that the minimum current-limit threshold of the current-limiting power-switch exceed the maximum current-limit draw of the intended application. The latest USB standard should always be referenced when considering the current-limit threshold.

The USB specification defines two types of devices as hubs and functions. A USB hub is a device that contains multiple ports for different USB devices to connect and can be self-powered (SPH) or bus-powered (BPH). A function is a USB device that is able to transmit or receive data or control information over the bus. A USB function can be embedded in a USB hub. A USB function can be one of three types included in the list below.

- Low-power, bus-powered function
- High-power, bus-powered function
- Self-powered function

SPHs and BPHs distribute data and power to downstream functions. The TPS65280 has higher current capability than required for a single USB port allowing it to power multiple downstream ports.

### Self-Powered and Bus-Powered HUBs

A SPH has a local power supply that powers embedded functions and downstream ports. This power supply must provide between 4.75 V and 5.25 V to downstream facing devices under full-load and no-load conditions. SPHs are required to have current-limit protection and must report over-current conditions to the USB controller. Typical SPHs are desktop PCs, monitors, printers, and stand-alone hubs.

A BPH obtains all power from an upstream port and often contains an embedded function. It must power up with less than 100 mA. The BPH usually has one embedded function, and power is always available to the controller of the hub. If the embedded function and hub require more than 100 mA on power up, the power to the embedded function may need to be kept off until enumeration is completed. This is accomplished by removing power or by shutting off the clock to the embedded function. Power switching the embedded function is not necessary if the aggregate power draw for the function and controller is less than 100 mA. The total current drawn by the bus-powered device is the sum of the current to the controller, the embedded function, and the downstream ports, and it is limited to 500 mA from an upstream port.

### Low-Power Bus-Powered and High-Power Bus-Powered Functions

Both low-power and high-power bus-powered functions obtain all power from upstream ports. Low-power functions always draw less than 100 mA; high-power functions must draw less than 100 mA at power up and can draw up to 500 mA after enumeration. If the load of the function is more than the parallel combination of 44  $\Omega$  and 10  $\mu\text{F}$  at power up, the device must implement inrush current limiting.

## USB Power Distribution Requirements

USB can be implemented in several ways regardless of the type of USB device being developed. Several power-distribution features must be implemented.

SPHs must:

- Current limit downstream ports
- Report over-current conditions

BPHs must:

- Enable/disable power to downstream ports
- Power up at  $< 100$  mA
- Limit inrush current ( $< 44 \Omega$  and  $10 \mu\text{F}$ )

Functions must:

- Limit inrush currents
- Power up at  $< 100$  mA

The feature set of the TPS65280 meets each of these requirements. The integrated current limiting and over-current reporting is required by self-powered hubs. The logic-level enable and controlled rise times meet the need of both input and output ports on bus-powered hubs and the input ports for bus-powered functions.

## BUCK DC/DC CONVERTER DETAILED DESCRIPTION

### Output Voltage

The TPS65280 regulates a fixed +5-V output voltage set by an internal feedback resistor divider as shown in Figure 30. Pin 15 is a Kelvin sensing feedback of output voltage. This pin should be directly connected to (+) terminal of output capacitor. Great care should be taken to route the FB line away from noise sources, such as the inductor or the LX switching node line.

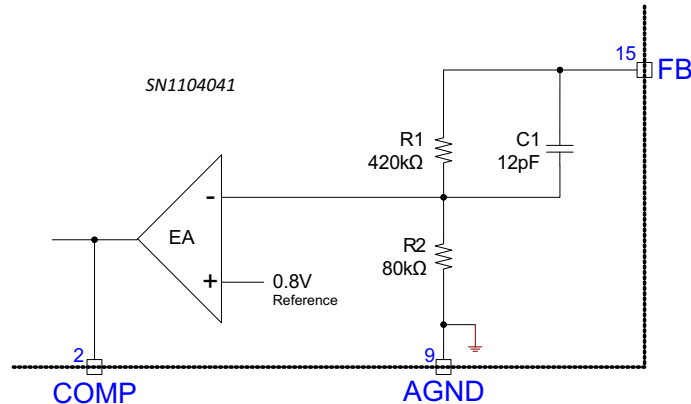


Figure 30. Buck Internal Feedback Resistor Divider

### Switching Frequency Selection and Clock Synchronization

The selection of switching frequency is a tradeoff between efficiency and component size. Low frequency operation increases efficiency by reducing MOSFET switching losses, but requires larger inductance and capacitance to maintain low output ripple voltage. The switching frequency of the TPS65280 buck controller can be selected with the connection at ROsc pin. The ROsc pin can be connected to AGND, tied to V7V, open or programmed through an external resistor. Tying ROsc pin to AGND selects 300 kHz, while tying ROsc pin to V7V or floating ROsc pin selects 600 kHz. Placing a resistor between ROsc and AGND allows the buck switching frequency to be programmed between 300 kHz to 1.4 MHz, as shown in Figure 12. The programmed clock frequency by an external resistor can be calculated with the following equation:

$$f_{sw} = 10 \times R_{osc} \quad (1)$$

An external clock source can be connected to the MODE/SYNC pin. The internal oscillator synchronizes the internal clock and rising edge of the on, high side power MOSFET to the rising edge of the synchronized external clock signal. When not using clock synchronization, always connect MODE/SYNC pin to ground.

### Soft-Start Time

The start-up of buck output is controlled by the voltage on the respective SS pin. When the voltage on the SS pin is less than the internal 0.8-V reference, the TPS65280 regulates the internal feedback voltage to the voltage on the SS pin instead of 0.8 V. The SS pin can be used to program an external soft-start function or to allow output of the buck to track another supply during start-up. The device has an internal pull-up current source of 4.5  $\mu$ A that charges an external soft-start capacitor to provide a linear ramping voltage at SS pin. The SN1104041 will regulate the internal feedback voltage (and hence 5-V output of buck) according to the voltage on the SS pin, allowing  $V_{OUT}$  to rise smoothly from 0 V to its final regulated 5 V value. The total soft-start time will be approximately:

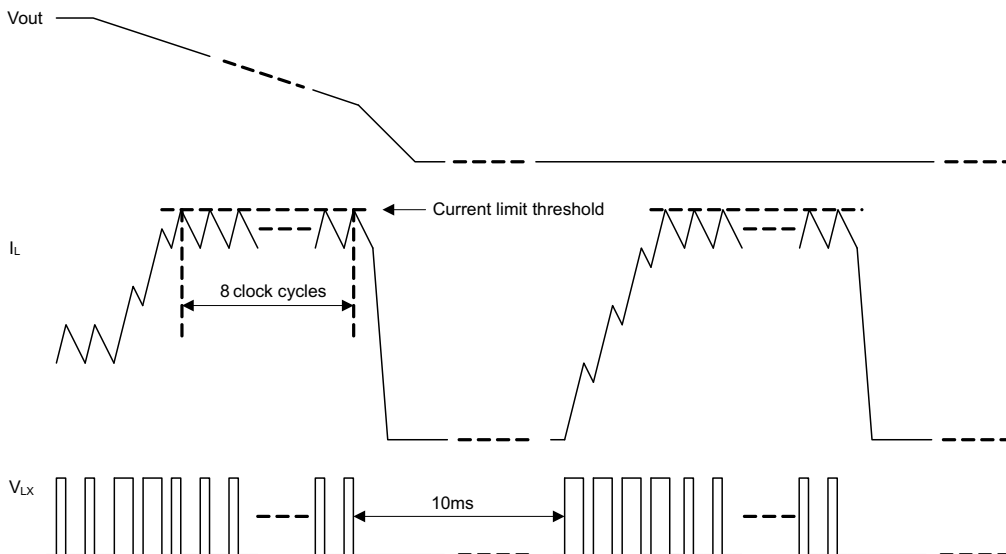
$$T_{ss} = C_{ss} \cdot \left( \frac{0.8 \cdot V}{4.5 \cdot \mu A} \right) \quad (2)$$

## Internal V7V Regulator

The TPS65280 features an internal P-channel low dropout linear regulator (LDO) that supplies power at the V7V pin from the VIN supply. V7V powers the gate drivers and much of the TPS65280's internal circuitry. The LDO regulates V7V to 6.3 V of over drive voltage on the power MOSFET for the best efficiency performance. The LDO can supply a peak current of 50 mA and must be bypassed to ground with a minimum 1- $\mu$ F ceramic capacitor. The capacitor placed directly adjacent to the V7V and PGND pins is highly recommended to supply the high transient currents required by the MOSFET gate drivers.

## Short Circuit Protection

During the PWM on-time, the current through the internal high side switching MOSFET is sampled. The sampled current is compared to a nominal 5-A over-current limit. If the sampled current exceeds the over-current limit reference level, an internal over-current fault counter is set to 1 and an internal flag is set. Both internal high side and low side power MOSFETs are immediately turned off and will not be turned on again until the next switching cycle. If the over-current condition persists for eight sequential clock cycles, the over-current fault counter overflows indicating an over-current fault condition exists. The buck regulator is shut down and stays turned off for 10 ms. If the over-current condition clears prior to the counter reaching eight consecutive cycles, the internal flag and counter are reset. The protection circuitry attempts to recover from the over-current condition after 10-ms power down time. The internal over-current flag and counter are reset. A normal soft-start cycle is attempted and normal operation continues if the over-current fault condition has cleared. If the over-current fault counter overflows during soft-start, the converter shuts down and this hiccup mode operation repeats.



**Figure 31. DC/DC Over-Current Protection**

## Inductor Selection

The higher operating frequency allows the use of smaller inductor and capacitor values. A higher frequency generally results in lower efficiency because of MOSFET gate charge losses. In addition to this basic trade-off, the effect of the inductor value on ripple current and low current operation must also be considered. The ripple current depends on the inductor value. The inductor ripple current,  $i_L$ , decreases with higher inductance or higher frequency and increases with higher input voltage,  $V_{IN}$ . Accepting larger values of  $i_L$  allows the use of low inductances, but results in higher output voltage ripple and greater core losses.

Use [Equation 3](#) to calculate the value of the output inductor. LIR is a coefficient that represents inductor peak-to-peak ripple to DC load current. It is suggested to use 0.1 ~ 0.3 for most LIR applications.

Actual core loss of the inductor is independent of core size for a fixed inductor value, but it is dependent on the inductance value selected. As inductance increases, core losses decrease. Unfortunately, increased inductance requires more turns of wire and therefore copper losses will increase. Ferrite designs have very low core loss and are preferred for high switching frequencies, so design goals can concentrate on copper loss and preventing saturation. Ferrite core material saturates hard, which means that inductance collapses abruptly when the peak design current is exceeded. It results in an abrupt increase in inductor ripple current and consequent output voltage ripple. Do not allow the core to saturate. It is important that the RMS current and saturation current ratings are not exceeding the inductor specification. The RMS and peak inductor current can be calculated from [Equation 5](#) and [Equation 6](#).

$$L = \frac{V_{in} - V_{out}}{I_O \cdot LIR} \cdot \frac{V_{out}}{V_{in} \cdot f_{sw}} \quad (3)$$

$$\Delta i_L = \frac{V_{in} - V_{out}}{I_O} \cdot \frac{V_{out}}{V_{in} \cdot f_{sw}} \quad (4)$$

$$i_{Lrms} = \sqrt{I_O^2 + \frac{(V_{out} \cdot (V_{inmax} - V_{out}))^2}{V_{inmax} \cdot L \cdot f_{sw} \cdot 12}} \quad (5)$$

$$I_{Lpeak} = I_O \cdot \frac{\Delta i_L}{2} \quad (6)$$

For this design example, use LIR = 0.3, and the inductor is calculated to be 5.40  $\mu$ H with  $V_{IN} = 12$  V. Choose a 4.7  $\mu$ H standard inductor, the peak to peak inductor ripple is about 34% of 3-A DC load current.

### Output Capacitor Selection

There are two primary considerations for selecting the value of the output capacitor. The output capacitors are selected to meet load transient and output ripple's requirements.

[Equation 7](#) gives the minimum output capacitance to meet the transient specification. For this example,  $L_O = 4.7$   $\mu$ H,  $\Delta I_{OUT} = 3$  A – 0.0 A = 3 A and  $\Delta V_{OUT} = 500$  mV (10% of regulated 5 V). Using these numbers gives a minimum capacitance of 17  $\mu$ F. A standard 22  $\mu$ F ceramic capacitor is used in the design.

$$C_O > \frac{\Delta I_{OUT}^2 \cdot L}{V_{out} \cdot \Delta V_{out}} \quad (7)$$

The selection of  $C_{OUT}$  is driven by the effective series resistance (ESR). [Equation 8](#) calculates the minimum output capacitance needed to meet the output voltage ripple specification. Where  $f_{sw}$  is the switching frequency,  $\Delta V_{OUT}$  is the maximum allowable output voltage ripple, and  $\Delta i_L$  is the inductor ripple current. In this case, the maximum output voltage ripple is 50 mV (1% of regulated 5 V). From [Equation 4](#), the output current ripple is 1 A. From [Equation 8](#), the minimum output capacitance meeting the output voltage ripple requirement is 4.6  $\mu$ F with 3-m $\Omega$  esr resistance.

$$C_O > \frac{1}{8 \cdot f_{sw}} \cdot \frac{1}{\frac{\Delta V_{out}}{\Delta i_L} - esr} \quad (8)$$

After considering both requirements, for this example, one 22  $\mu$ F 6.3 V X7R ceramic capacitor with 3 m $\Omega$  of ESR will be used.

### Input Capacitor Selection

A minimum 10  $\mu$ F X7R/X5R ceramic input capacitor is recommended to be added between VIN and GND. These capacitors should be connected as close as physically possible to the input pins of the converters, as they handle the RMS ripple current shown in [Equation 9](#). For this example,  $I_{OUT} = 2$  A,  $V_{OUT} = 5$  V, minimum  $V_{in\_min} = 9.6$  V. The input capacitors must support a ripple current of 1 A RMS.

$$I_{inrms} = I_{out} \cdot \sqrt{\frac{V_{out}}{V_{inmin}} \cdot \frac{(V_{inmin} - V_{out})}{V_{inmin}}} \quad (9)$$

The input capacitance value determines the input ripple voltage of the regulator. The input voltage ripple can be calculated using Equation 10. Using the design example values,  $I_{out\_max} = 2$  A,  $C_{IN} = 10$   $\mu$ F,  $f_{SW} = 600$  kHz, yields an input voltage ripple of 83 mV.

$$\Delta V_{in} = \frac{I_{out\_max} \cdot 0.25}{C_{in} \cdot f_{sw}} \quad (10)$$

To prevent large voltage transients, a low ESR capacitor sized for the maximum RMS current must be used.

## Output Capacitor Selection

The external bootstrap capacitor connected to the BST pins supply the gate drive voltages for the toplevel MOSFETs. The capacitor between BST pin and LX pin is charged through an internal diode from  $V_{7V}$  when the LX pin is low. When high side MOSFETs are to be turned on, the driver places the bootstrap voltage across the gate-source of the desired MOSFET. This enhances the top MOSFET switch and turns it on. The switch node voltage, LX, rises to  $V_{IN}$  and the BST pin follows. With the internal high side MOSFET on, the bootstrap voltage is above the input supply:  $V_{BST} = V_{IN} + V_{7V}$ . The selection on bootstrap capacitance is related with internal high side power MOSFET gate capacitance. A 0.047- $\mu$ F ceramic capacitor is recommended to be connected between the BST to LX pin for proper operation. It is recommended to use a ceramic capacitor with X5R or better grade dielectric. The capacitor should have 10-V or higher voltage rating.

## Loop Compensation

The integrated buck DC/DC converter in TPS65280 incorporates a peak current mode. The error amplifier is a trans-conductance amplifier with a gain of 350  $\mu$ A/V. A typical type II compensation circuit adequately delivers a phase margin between 60° and 90°.  $C_b$  adds a high frequency pole to attenuate high frequency noise when needed. To calculate the external compensation components, follow these steps:

1. Select switching frequency,  $f_{SW}$ , that is appropriate for application depending on L and C sizes, output ripple and EMI. Switching frequency between 500 kHz and 1 MHz gives the best trade off between performance and cost. To optimize efficiency, a lower switching frequency is desired.
2. Set up cross over frequency,  $f_c$ , which is typically between 1/5 and 1/20 of  $f_{SW}$ .
3. RC can be determined by:

$$R_C = \frac{2\pi \cdot f_c \cdot V_o \cdot C_o}{g_M \cdot V_{ref} \cdot g_{m_{ps}}} \quad (11)$$

where  $g_m$  is the error amplifier gain (350  $\mu$ A/V) and  $g_{m_{ps}}$  is the power stage voltage to current conversion gain (10 A/V).

4. Calculate  $C_C$  by placing a compensation zero at or before the dominant pole,  $f_p = \frac{1}{C_o \cdot R_L \cdot 2\pi}$ .

$$C_C = \frac{R_L \cdot C_o}{R_C} \quad (12)$$

5. Optional  $C_b$  can be used to cancel the zero from the ESR associated with  $C_o$ .

$$C_b = \frac{R_{esr} \cdot C_o}{R_C} \quad (13)$$

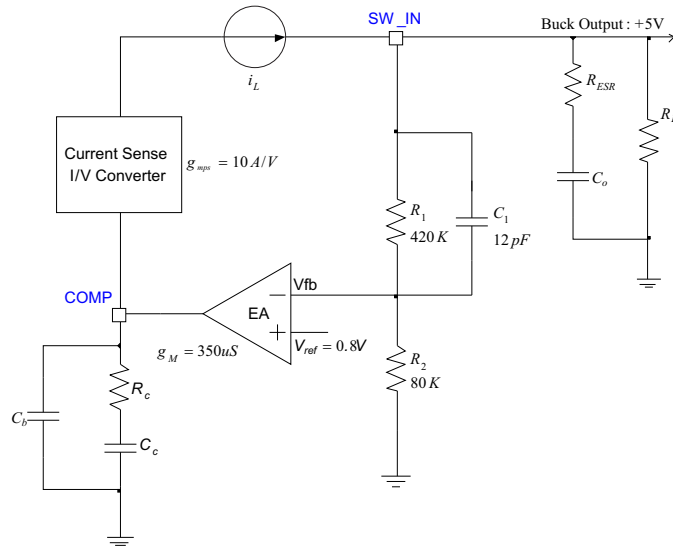


Figure 32. DC/DC Loop Compensation

## APPLICATION INFORMATION

### Thermal Shutdown

The device implements an internal thermal shutdown to protect itself if the junction temperature exceeds 160°C. The thermal shutdown forces the buck converter to stop switching when the junction temperature exceeds thermal trip threshold. Once the die temperature decreases below 140°C, the device reinitiates the power up sequence. The thermal shutdown hysteresis is 20°C.

### Power Dissipation and Junction Temperature

The total power dissipation inside TPS65280 should not exceed the maximum allowable junction temperature of 125°C. The maximum allowable power dissipation is a function of the thermal resistance of the package,  $\theta_{JA}$ , and ambient temperature. The analysis below gives an approximation in calculating junction temperature based on the power dissipation in the package. However, it is important to note that thermal analysis is strongly dependent on additional system level factors. Such factors include air flow, board layout, copper thickness and surface area, and proximity to other devices dissipating power. Good thermal design practice must include all system level factors in addition to individual component analysis.

To calculate the temperature inside the device under continuous load, use the following procedure.

1. Define the total continuous current through the buck converter (including the load current through power switches). Make sure the continuous current does not exceed the maximum load current requirement.
2. From the graphs below, determine the expected losses (Y axis) in Watts for the buck converter inside the device. The loss  $P_{D\_BUCK}$  depends on the input supply and the selected switching frequency. Please note, the data is measured in the provided evaluation board (EVM).
3. Determine the load current  $I_{OUT1}$  and  $I_{OUT2}$  through the power switches. Read  $R_{DS(on)1/2}$  of the power switch from the typical characteristics graph.
4. The power loss through power switches can be calculated by:

$$P_{D\_PW} = R_{DS1(on)} \times I_{OUT1} + R_{DS2(on)} \times I_{OUT2} \quad (14)$$

5. The Dissipating Rating Table provides the thermal resistance,  $\theta_{JA}$ , for specific packages and board layouts.
6. The maximum temperature inside the IC can be calculated by:

$$T_J = P_{D\_BUCK} + P_{D\_PW} \times \theta_{JA} + T_A \quad (15)$$

Where:

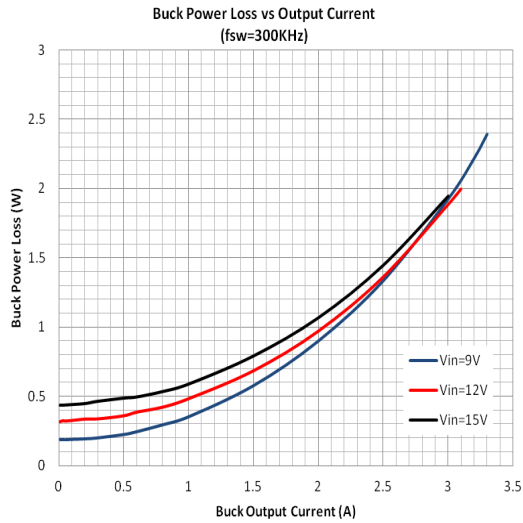
$T_A$  = Ambient temperature (°C)

$\theta_{JA}$  = Thermal resistance (°C/W)

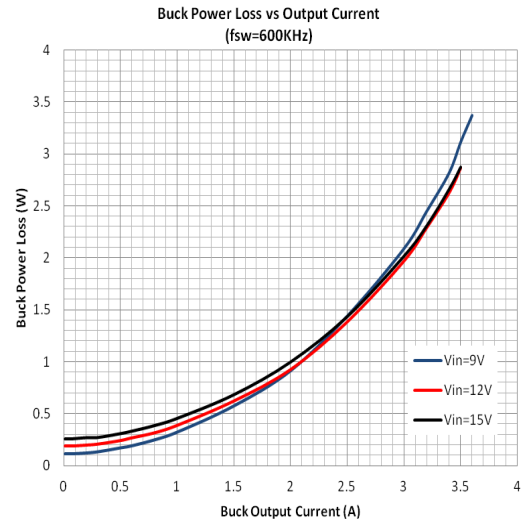
$P_{D\_BUCK}$  = Total power dissipation in buck converter (W)

$P_{D\_PW}$  = Total power dissipation in power switches (W)

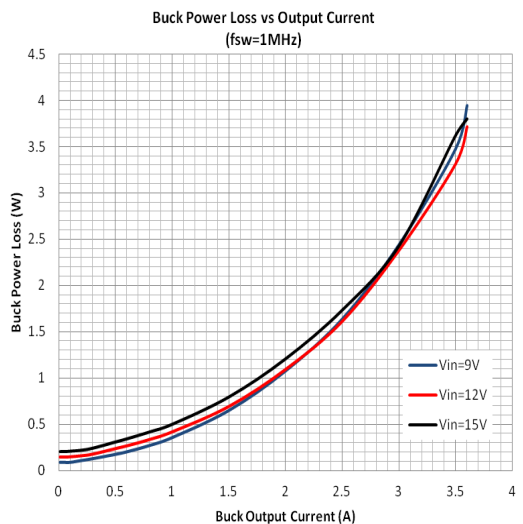




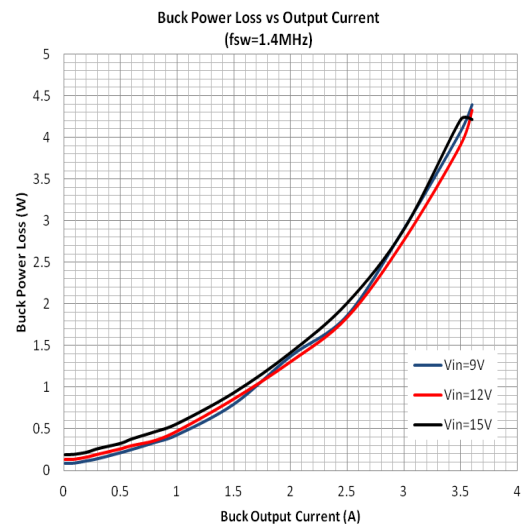
**Figure 33. Buck Loss vs Output Current ( $V_{IN} = 9\text{ V}$ ,  $12\text{ V}$  and  $15\text{ V}$ ,  $f_{SW} = 300\text{ kHz}$ )**



**Figure 34. Buck Loss vs Output Current ( $V_{IN} = 9\text{ V}$ ,  $12\text{ V}$  and  $15\text{ V}$ ,  $f_{SW} = 600\text{ kHz}$ )**



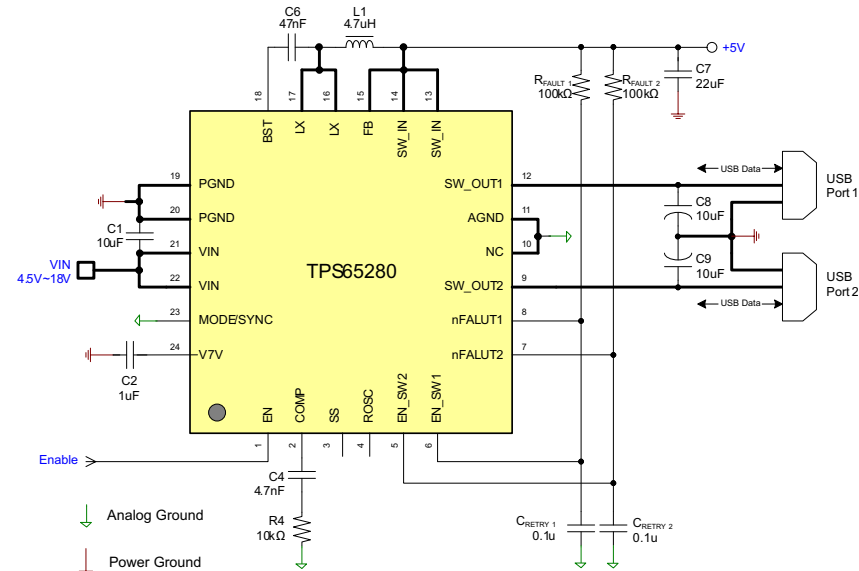
**Figure 35. Buck Loss vs Output Current ( $V_{IN} = 9\text{ V}$ ,  $12\text{ V}$  and  $15\text{ V}$ ,  $f_{SW} = 1\text{ MHz}$ )**



**Figure 36. Buck Loss vs Output Current ( $V_{IN} = 9\text{ V}$ ,  $12\text{ V}$  and  $15\text{ V}$ ,  $f_{SW} = 1.4\text{ MHz}$ )**

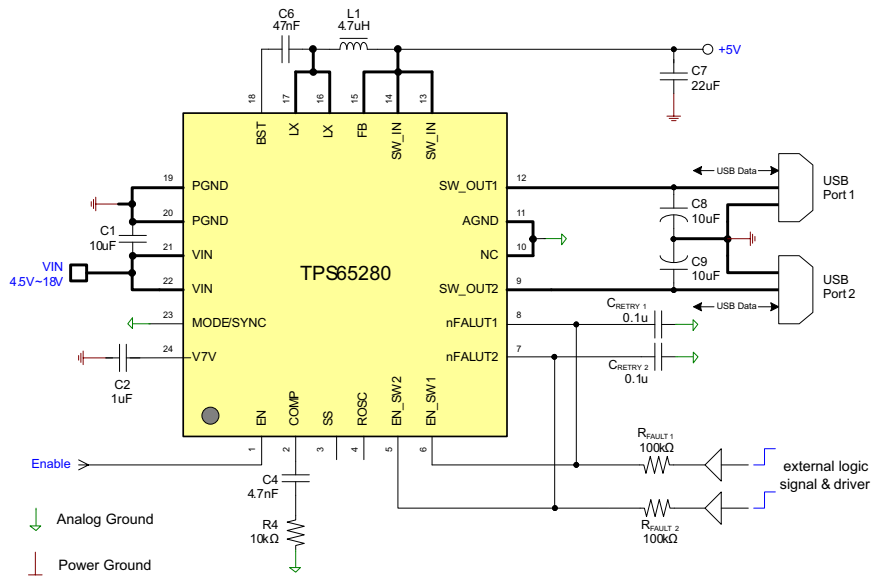
### Auto-Retry Functionality

Some applications require that an over-current condition disables the part momentarily during a fault condition and re-enables after a pre-set time. This auto-retry functionality can be implemented with an external resistor and capacitor shown in [Figure 37](#). During a fault condition, nFAULT pulls low disabling the part. The part is disabled when EN is pulled low, and nFAULT goes high impedance allowing CRETRY to begin charging. The part re-enables when the voltage on EN\_SW reaches the turn-on threshold, and the auto-retry time is determined by the resistor/capacitor time constant. The part will continue to cycle in this manner until the fault condition is removed.



**Figure 37. Auto Retry Functionality**

Some applications require auto-retry functionality and the ability to enable/disable with an external logic signal. [Figure 38](#) shows how an external logic signal can drive EN\_SW through RFAULT and maintain auto-retry functionality. The resistor/capacitor time constant determines the auto-retry time-out period.



**Figure 38. Auto Retry Functionality With External Enable Signal**

## PCB Layout Recommendation

When laying out the printed circuit board, the following guidelines should be used to ensure proper operation of the IC. These items are also illustrated graphically in the layout diagram of [Figure 39](#).

- There are several signal paths that conduct fast changing currents or voltages that can interact with stray inductance or parasitic capacitance to generate noise or degrade the power supplies performance. To help eliminate these problems, the VIN pin should be bypassed to ground with a low ESR ceramic bypass capacitor with X5R or X7R dielectric. This capacitor provides the AC current into the internal power MOSFETs. Connect the (+) terminal of the input capacitor as close as possible to the VIN pin, and connect the (-) terminal of the input capacitor as close as possible to the PGND pin. Care should be taken to minimize the loop area formed by the bypass capacitor connections, the VIN pins, and the power ground PGND connections.
- Since the LX connection is the switching node, the output inductor should be located close to the LX pin, and the area of the PCB conductor minimized to prevent excessive capacitive coupling. Keep the switching node, LX, away from all sensitive small-signal nodes.
- Connect V7V decoupling capacitor (connected close to the IC), between the V7V and the power ground PGND pin. This capacitor carries the MOSFET drivers' current peaks.
- Place the output filter capacitor of the buck converter close to SW\_IN pins and AGND pin. Try to minimize the ground conductor length while maintaining adequate width.
- The AGND pin should be separately routed to the (-) terminal of V7V bypass capacitor to avoid switching grounding path. A ground plane is recommended connecting to this ground path.
- The compensation should be as close as possible to the COMP pins. The COMP and ROSC pins are sensitive to noise so the components associated to these pins should be located as close as possible to the IC and routed with minimal lengths of trace. Flood all unused areas on all layers with copper. Flooding with copper will reduce the temperature rise of the power components. You can connect the copper areas to PGND, AGND, VIN or any other DC rail in your system.
- There is no electric signal internal connected to thermal pad in the device. Nevertheless connect the exposed pad beneath the IC to ground. Always solder the thermal pad to the board, and have as many vias as possible on the PCB to enhance power dissipation.

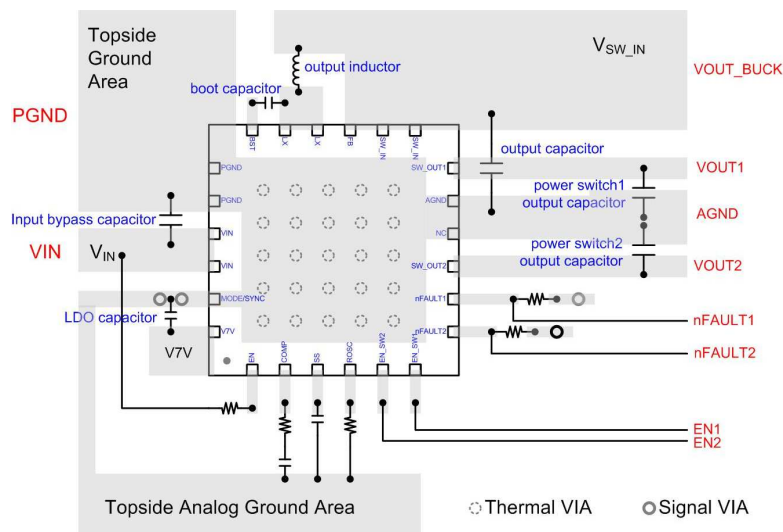


Figure 39. 2-Layers PCB Layout Recommendation Diagram

**PACKAGING INFORMATION**

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
TPS65280RGER	ACTIVE	VQFN	RGE	24	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	TPS 65280	<b>Samples</b>

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBsolete:** TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green:** TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=100ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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## TAPE AND REEL INFORMATION



### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPS65280RGER	VQFN	RGE	24	3000	330.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2

**TAPE AND REEL BOX DIMENSIONS**


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPS65280RGER	VQFN	RGE	24	3000	367.0	367.0	35.0

**RGE 24**

**GENERIC PACKAGE VIEW**

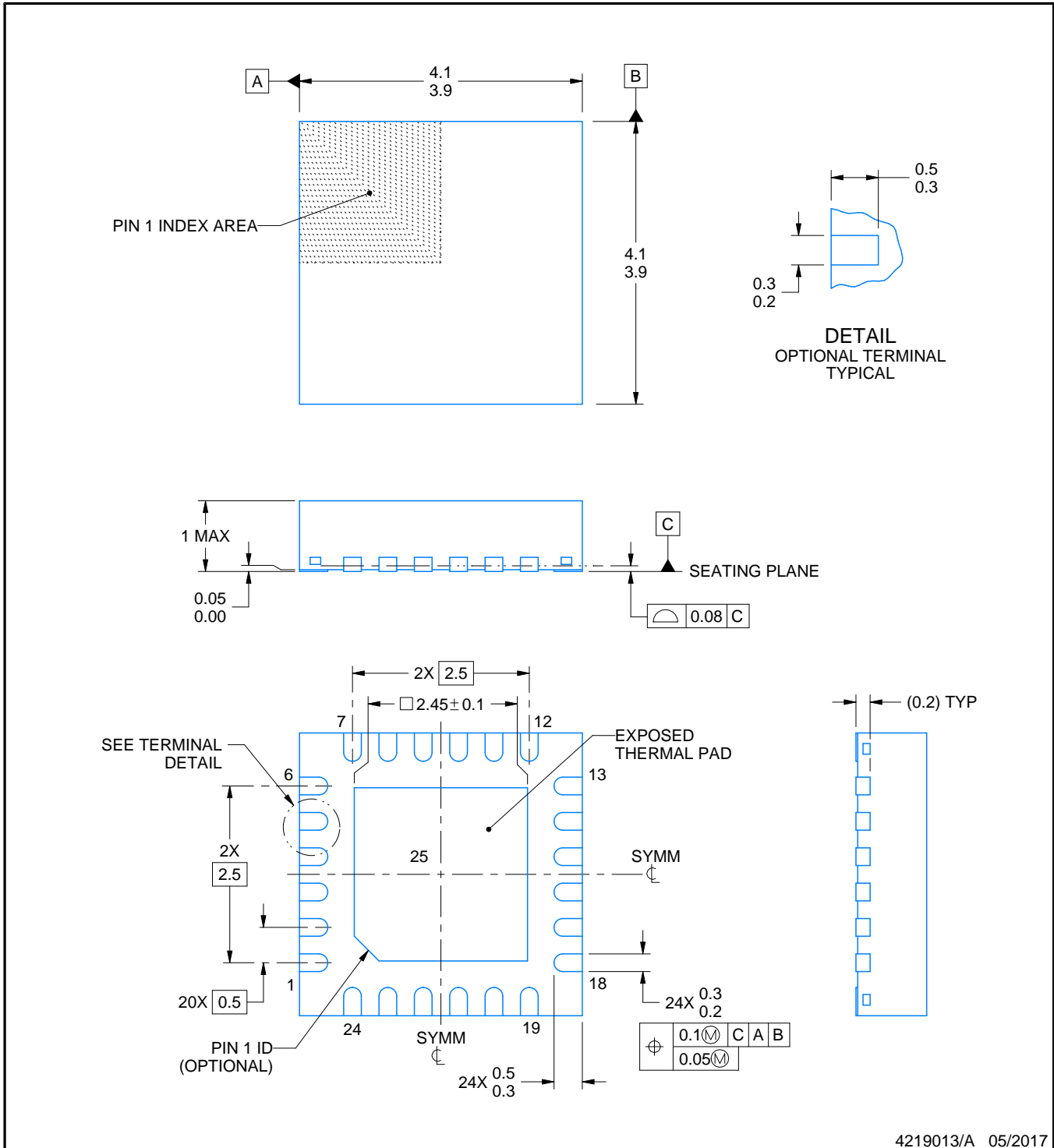
**VQFN - 1 mm max height**

PLASTIC QUAD FLATPACK - NO LEAD



Images above are just a representation of the package family, actual package may vary.  
Refer to the product data sheet for package details.

4204104/H



4219013/A 05/2017

NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

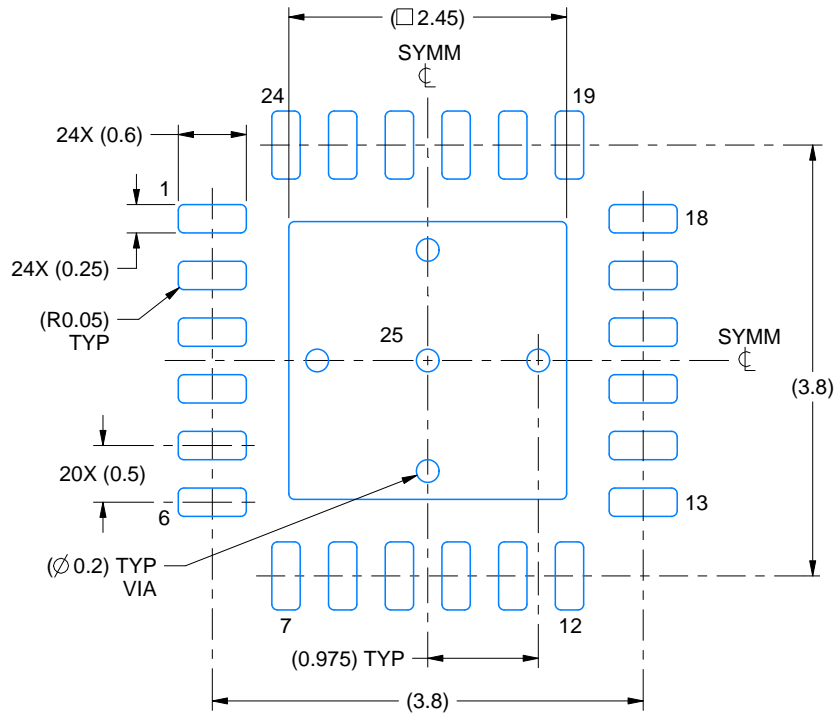


# EXAMPLE BOARD LAYOUT

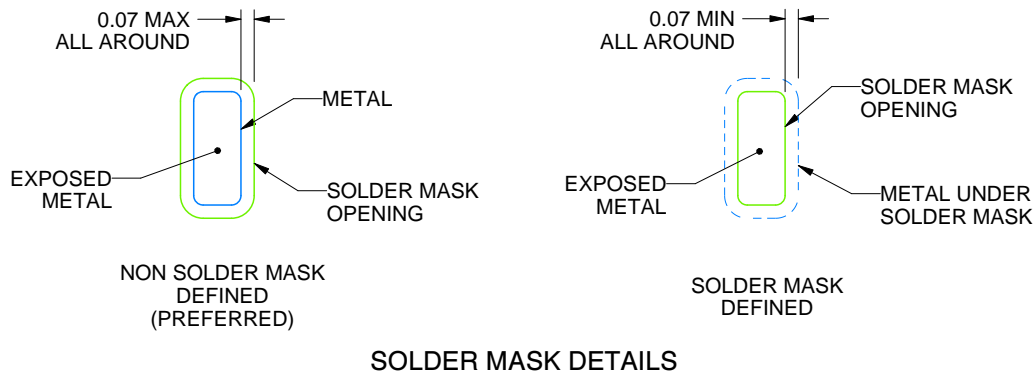
RGE0024B

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE:15X



SOLDER MASK DETAILS

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NOTES: (continued)

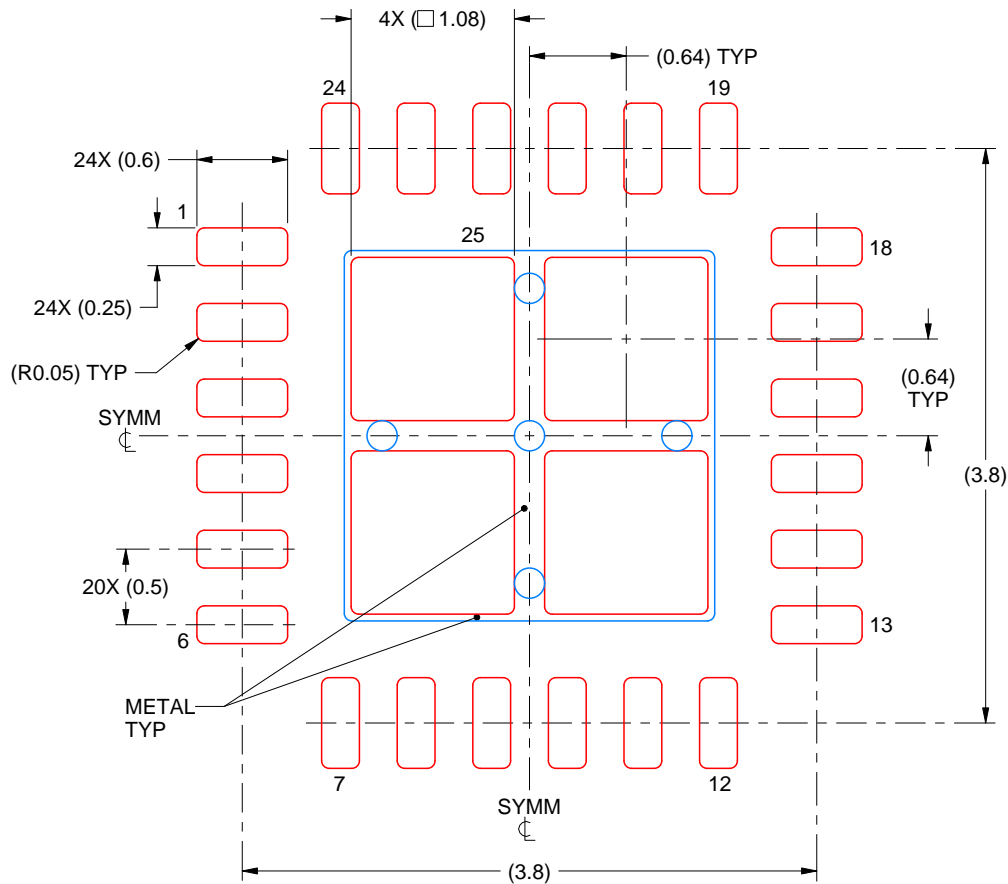
4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 ([www.ti.com/lit/sluea271](http://www.ti.com/lit/sluea271)).
5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

# EXAMPLE STENCIL DESIGN

RGE0024B

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



SOLDER PASTE EXAMPLE  
BASED ON 0.125 mm THICK STENCIL

EXPOSED PAD 25  
78% PRINTED SOLDER COVERAGE BY AREA UNDER PACKAGE  
SCALE:20X

4219013/A 05/2017

NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

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