

Meter-Bus Transceiver

Features

- Meter-Bus Transceiver (for Slave) Meets Standard EN-1434-3
- Adjustable Constant-Current Sink via Resister
- Receiver Logic With Dynamic Level Recognition
- Module Supply Voltage Switch
- 3.3V Constant Voltage Source
- Remote Powering
- Polarity Independent
- Power Fail Function
- Up to 9600 Baud in Half Duplex for UART Protocol
- Slave Power Support
 - Supply From Meter-Bus via Output VDD
 - Supply From Meter-Bus via Output VDD or From Backup Battery
 - Supply From Battery – Meter-Bus Active for Data Transmission Only
- SOP16 package

General Description

BL15721B is a single chip transceiver developed for Meter-Bus standard (EN1434-3) applications.

The BL15721B interface circuit adjusts the different potentials between a slave system and the Meter-Bus master. The connection to the bus is polarity independent and supports full galvanic slave isolation with optocouplers.

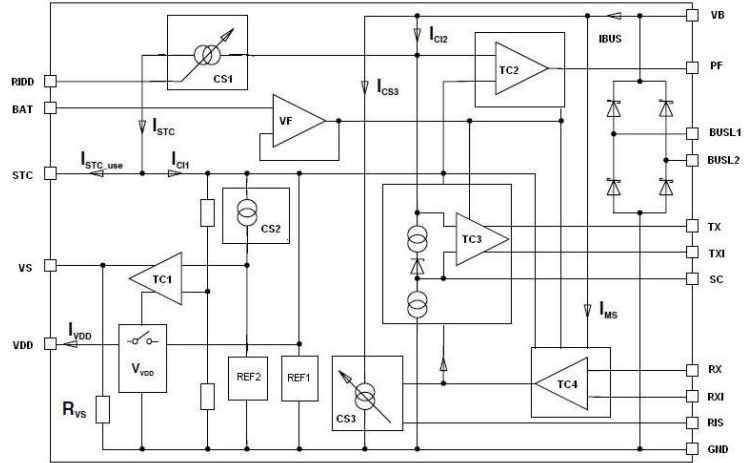
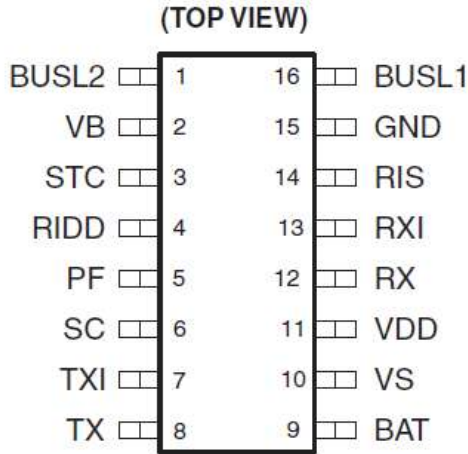
The receiver has dynamic level recognition, and the transmitter has a programmable current sink.

The circuit is supplied by the master via the bus. Therefore, this circuit offers no additional load for the slave battery.

The BL15721B integrates a power-fail function. And a 3.3V voltage regulator, with power reserve for a delayed switch off at bus fault, is integrated.

Order Information

Part Number	Package	Packing
BL15721B	SOP16	Tape & Reel
		Tube

Pin Diagram
Block Diagram

Pin Description

Pin #	Name	Description
1	BUSL2	Meter-Bus
2	VB	Differential bus voltage after rectifier
3	STC	Support capacitor
4	RIDD	Current adjustment input
5	PF	Power fail output
6	SC	Sampling capacitor
7	TXI	Data output inverted
8	TX	Data output
9	BAT	Logic level adjust
10	VS	Switch for bus or battery supply output
11	VDD	Voltage regulator output
12	RX	Data input
13	RXI	Data input inverted
14	RIS	Adjust input for modulation current
15	GND	Ground
16	BUSL1	Meter-Bus

Data Transmission, Master to Slave

The mark level on the bus lines $V_{BUS} = \text{MARK}$ is defined by the difference of BUSL1 and BUSL2 at the slave. It is dependent on the distance of Master to Slave, which affects the voltage drop on the wire. To make the receiver independent, a dynamic reference level on the SC pin is used for the voltage comparator TC3 (see Figure 1).

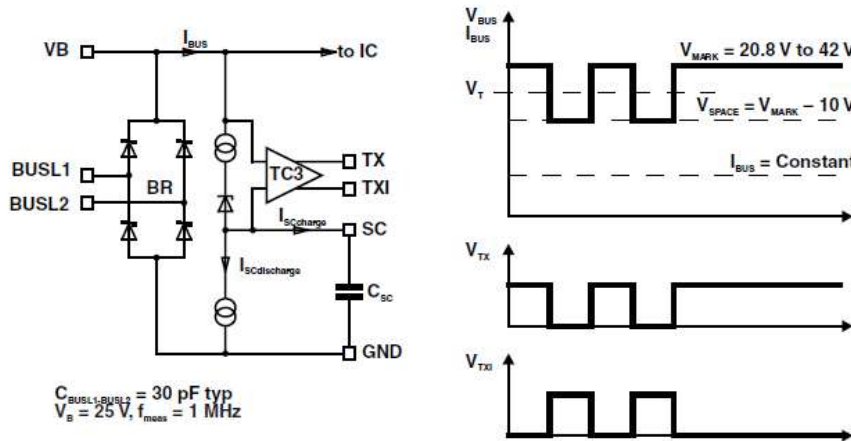


Figure 2. Data Transmission, Master to Slave

Figure 1. Data Transmission, Master to Slave

A capacitor C_{SC} at pin SC is charged by a current $I_{SCcharge}$ and is discharged with a current $I_{SCdischarge}$ where:

$$I_{SCdischarge} = \frac{I_{SCcharge}}{40 \text{ (typ)}}$$

There must be sufficient time to recharge the capacitor C_{SC} . The input level detector TC3 detects voltage modulations from the master, and switches the inverted output TXI and the non-inverted output TX.

Data Transmission, Slave to Master

The device uses current modulation to transmit information from the slave to the master while the bus voltage remains constant. The current source CS3 modulates the bus current and the master detects the modulation. The constant current source CS3 is controlled by the inverted input RXI or the non-inverted input RX. The current source CS3 can be programmed by an external resistor R_{RIS} . The modulation supply current I_{MS} flows in addition to the current source CS3 during the modulation time.

Because the BL15721B is configured for half-duplex only, the current modulation from RX or RXI is repeated concurrently as ECHO on the outputs TX and TXI. If the slave, as well as the master, is trying to send information via the lines, the added signals appear on the outputs TX and TXI, which indicates the data collision to the slave.

The bus topology requires a constant current consumption by each connected slave.

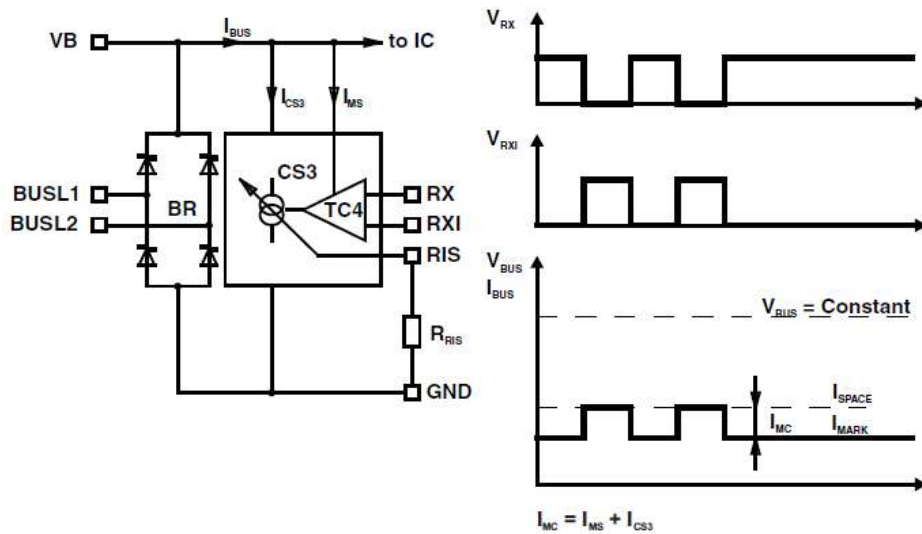


Figure 2. Data Transmission, Slave to Master

To calculate the value of the programming resistor R_{RIS} , use the formula shown in Figure 3.

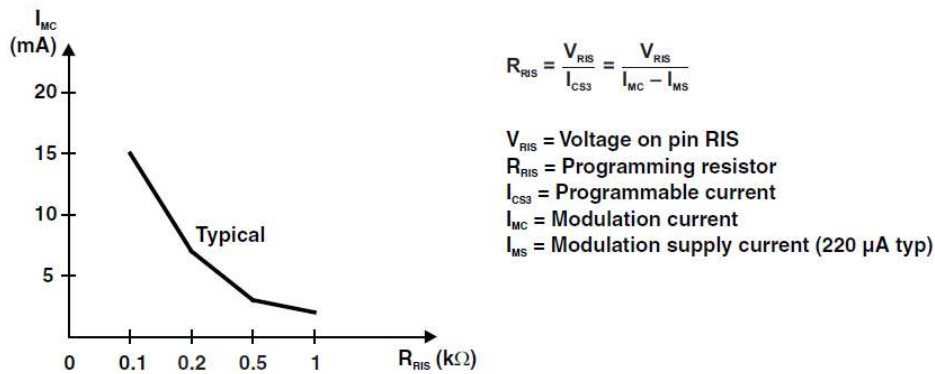


Figure 3. Calculate Programming Resistor R_{RIS}

Slave Supply, 3.3 V

The BL15721B has an internal 3.3V voltage regulator. The output power of this voltage regulator is supplied by the storage capacitor C_{STC} at pin STC. The storage capacitor C_{STC} at pin STC is charged with constant current I_{STC_use} from the current source CS1. The maximum capacitor voltage is limited to REF1. The charge current I_{STC} has to be defined by an external resistor at pin RIDD. The adjustment resistor R_{RIDD} can be calculated using below Equation.

$$R_{RID} = 25 \frac{V_{RIDD}}{I_{STC}} = 25 \frac{V_{RIDD}}{I_{STC_use} + I_{IC1}}$$

Where,

I_{STC} = current from current source CS1

I_{STC_use} = charge current for support capacitor

I_{IC1} = internal current

V_{RIDD} = voltage on pin RIDD

R_{RIDD} = value of adjustment resistor

The voltage level of the storage capacitor C_{STC} is monitored with comparator TC1. Once the voltage V_{STC} reaches V_{VDD_on} , the switch S_{VDD} connects the stabilized voltage V_{VDD} to pin VDD. VDD is turned off if the voltage V_{STC} drops below the V_{VDD_off} level.

Voltage variations on the capacitor C_{STC} create bus current changes (see Figure 4).

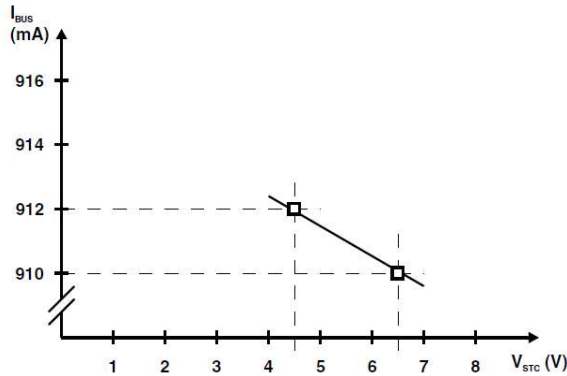


Figure 4. Single Mode Bus Load

At a bus fault the shut down time of VDD (t_{off}) in which data storage can be performed depends on the system current I_{VDD} and the value of capacitor C_{STC} . See Figure 5, which shows a correlation between the shutdown of the bus voltage V_{BUS} and V_{DD_off} and t_{off} for dimensioning the capacitor.

The output VS is meant for slave systems that are driven by the bus energy, as well as from a battery should the bus line voltage fail. The switching of VS is synchronized with VDD and is controlled by the comparator TC1. An external transistor at the output VS allows switching from the Meter-Bus remote supply to battery.

Power On/Off

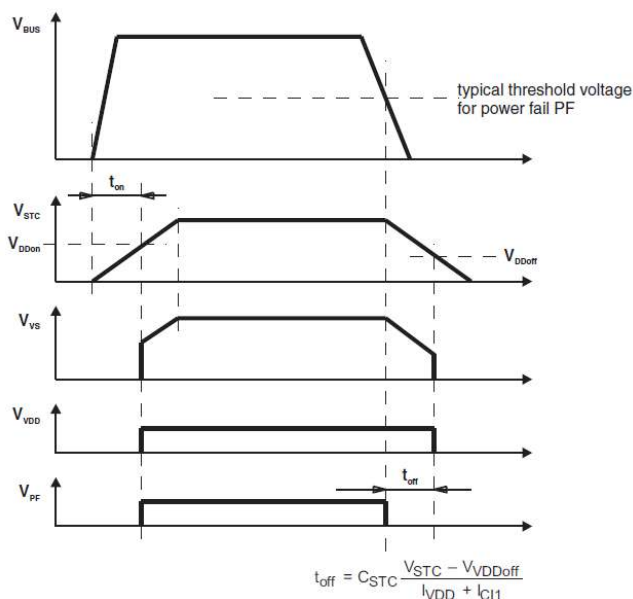


Figure 5. Power On/Off Timing

Power Fail Function

Because of the rectifier bridge BR at the input, BUSL1, and BUSL2, the BL15721B is polarity independent. The pin VB to ground (GND) delivers the bus voltage V_{VB} less the voltage drop over the rectifier BR. The voltage comparator TC2 monitors the bus voltage. If the voltage $V_{VB} > V_{STC} + 0.8 \text{ V}$, then the output PF = 1. The output level PF = 0 (power fail) provides a warning of a critical voltage drop to the microcontroller to save the data immediately.

Absolute Maximum Ratings

Over operating free-air temperature range(unless otherwise noted)

V_{MB}	Voltage, BUSL1 to BUSL2		$\pm 50\text{V}$
V_I	Input voltage range	RX and RXI	- 0.3 V to 5.5 V
		BAT	- 0.3 V to 5.5 V
T_A	Operating free-air temperature range		-25°C to 85°C
T_{STG}	Storage temperature range		- 65°C to 150°C

Recommended Operating Conditions (note1)

		Min	Max	Unit	
V_{MB}	Bus voltage, BUSL2-BUSL1	Receiver	10.8	42	V
		Transmitter	12	42	
V_I	Input voltage	VB(receive mode)	9.3		V
		BAT(note2)	2.5	3.8	
R_{RIDD}	RIDD resistor	13	80	K Ω	
R_{RIS}	RIS resistor	100		Ω	
T_A	Operating free-air temperature	-25	85	°C	

Note1: All voltage values are measured with respect to the GND terminal unless otherwise noted.

Note2: $V_{BAT(max)} \leq V_{STC} - 1 \text{ V}$

Electrical Characteristics(note1)

over operating free-air temperature range (unless otherwise noted)

Symbol	Parameter	Conditions	Spec			Unit
			Min.	Typ.	Max.	
ΔV_{BR}	Voltage drop at rectifier BR	$I_{BUS} = 3 \text{ mA}$		1.03	1.5	V
ΔV_{CS1}	Voltage drop at current source CS1	$R_{RIDD} = 13 \text{ k}\Omega$		0.95	1.8	V
I_{BUS}	BUS current	$V_{STC}=6.5\text{V},$ $I_{MC}=0\text{mA}$	$R_{RIDD} = 13 \text{ k}\Omega$	2.84	3.3	mA
			$R_{RIDD} = 30 \text{ k}\Omega$	1.34	1.8	
ΔI_{BUS}	BUS current accuracy	$\Delta V_{BUS} = 10\text{V}, I_{MC} = 0 \text{ mA}, R_{RIDD} = 13 \text{ k}\Omega \text{ to } 30 \text{ k}\Omega$			2	%
I_{CC}	Supply current	$V_{STC} = 6.5 \text{ V}, I_{MC} = 0 \text{ mA}, V_{BAT} =$		480	650	μA

		3.8 V, R _{RIDD} = 13 kΩ(note2)					
I _{CL1}	CI1 current	V _{STC} = 6.5 V, I _{MC} = 0 mA, V _{BAT} = 3.8 V, R _{RIDD} = 13 kΩ, V _{BUS} = 6.5 V, RX/RXI = off (note2)			350	μA	
I _{BAT}	BAT current		-0.5		0.5	μA	
I _{BAT} + I _{VDD}	BAT plus VDD current	V _{BUS} = 0 V, V _{STC} = 0 V	-0.5		0.5	μA	
V _{VDD}	VDD voltage	-I _{VDD} = 1 mA, V _{STC} = 6.5 V	3.1	3.25	3.5	V	
R _{VDD}	VDD resistance	-I _{VDD} = 2 to 8 mA, V _{STC} = 4.5 V		2	5	Ω	
V _{STC}	STC voltage	VDD = on, VS = on	5.6	6.16	6.4	V	
		VDD = off, VS = off	3.4	4.0	4.3		
		I _{VDD} < I _{STC_use}	6.5	7.18	7.7		
I _{STC_use}	STC current	V _{STC} = 5 V	R _{RIDD} =30 kΩ	0.65		1.2	mA
			R _{RIDD} =13 kΩ	1.85		2.5	
V _{RIDD}	RIDD voltage	R _{RIDD} = 30 kΩ	1.2		1.33	V	
V _{VS}	VS voltage	VDD = on, I _{VS} = -5 μA	V _{STC} -0.4		V _{STC}	V	
R _{VS}	VS resistance	VDD = off	0.3		1	MΩ	
V _{PF}	PF voltage	V _{STC} =6.5V	V _{VB} = V _{STC} + 1.2 V, I _{PF} = -100 μA	V _{BAT} -0.6		V _{BAT}	V
			V _{VB} = V _{STC} + 0.5 V, I _{PF} = 1 μA	0		0.6	
			V _{VB} = V _{STC} + 0.5 V, I _{PF} = 5 μA	0		0.9	

Note1: All voltage values are measured with respect to the GND terminal, unless otherwise noted.

Note2: Inputs RX/RXI and outputs TX/TXI are open, I_{CC} = I_{CL1} + I_{CL2}

Receiver Section Electrical Characteristics(note1)

over operating free-air temperature range (unless otherwise noted)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V _T			MARK-0.82		MARK-5.7	V
V _{SC}	SC voltage				V _{VB}	V
I _{SCcharge}	SC charge current	V _{SC} = 24 V, V _{VB} = 36 V	-15	-24.7	-40	μA
I _{SCdischarge}	SC discharge current	V _{SC} = V _{VB} = 24 V	0.3		-0.033X I _{SCdischarge}	μA
V _{OH}	High-level output voltage (TX, TXI)	I _{TX} /I _{TXI} = -100 μA,	V _{BAT} -0.6		V _{BAT}	V
V _{OL}	Low-level	I _{TX} /I _{TXI} = 100 μA	0	0.47	0.6	V

	output voltage(TX, TXI)	$I_{TX} = 1.1 \text{ mA}$	0	1.0	1.5	
I_{TX} I_{TXI}	TX, TXI current	$V_{TX} = 7.5\text{V}$, $V_{VB} = 12\text{V}$, $V_{STC} = 6\text{V}$, $V_{BAT} = 3.8\text{V}$	0	0.8	10	μA

Note1: All voltage values are measured with respect to the GND terminal, unless otherwise noted.

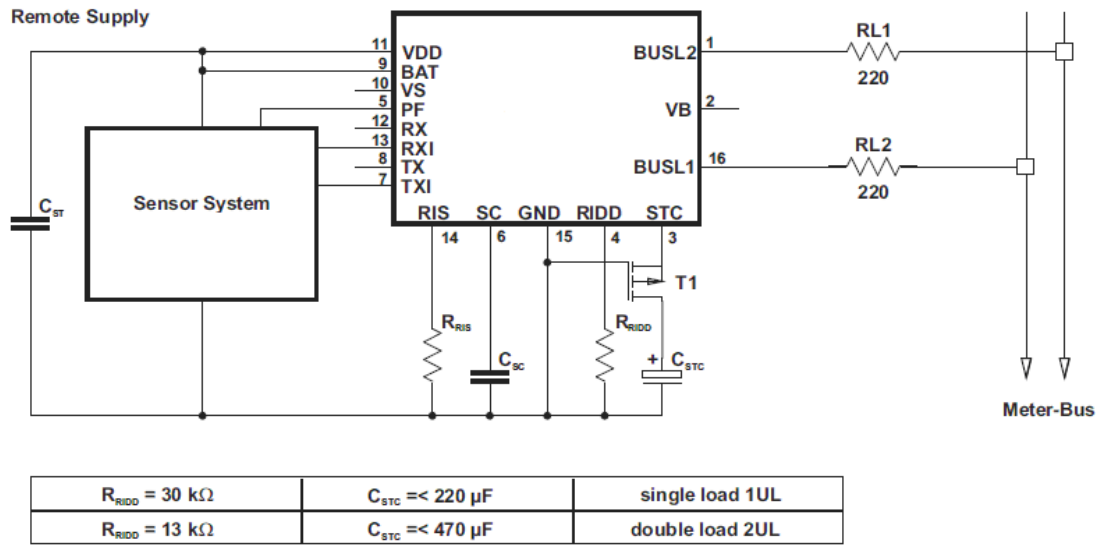
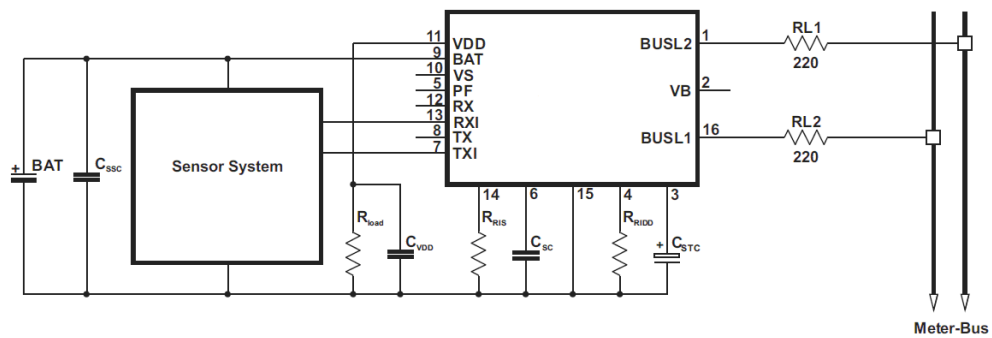
Transmitter Section Electrical Characteristics(note1)

Over operating free-air temperature range(unless otherwise noted)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
I_{MC}	MC voltage	$R_{RIS}=100\Omega$	11.5		19.5	mA
V_{RIS}	RIS voltage	$R_{RIS}=100\Omega$	1.4		1.7	V
		$R_{RIS}=1000\Omega$	1.5		1.8	
V_{IH}	High-level input voltage(RX,RXI)	See Figure 2(note2)	$V_{BAT}-0.8$		5.5	V
V_{IL}	Low-level input voltage(RX,RXI)	See Figure 2	0		0.8	V
I_{RX}	RX current	$V_{RX} = V_{BAT} = 3\text{V}$, $V_{VB} = V_{STC} = 0\text{V}$	-0.5		0.5	μA
		$V_{RX} = 0\text{V}$, $V_{BAT} = 3\text{V}$, $V_{STC} = 6.5\text{V}$	-10		-40	
I_{RXI}	RXI current	$V_{RXI} = V_{BAT} = 3\text{V}$, $V_{VB} = V_{STC} = 0\text{V}$	10		40	μA
		$V_{RXI} = V_{BAT} = 3\text{V}$, $V_{STC} = 6.5\text{V}$	10		40	

Note1: All voltage values are measured with respect to the GND terminal, unless otherwise noted.

Note 2: $V_{IH}(\text{max}) = 5.5\text{V}$ is valid only when $V_{STC} \geq 6.5\text{V}$.

Application Information

 Figure 6. Basic Application Circuit Using Support Capacitor $C_{STC} > 50 \mu\text{F}$


- | | |
|--|--|
| C_{SSC} - system stabilising capacitor | R_{RIDD} - slave-current adjustment resistor |
| C_{STC} - support capacitor | R_{RIS} - modulation-current resistor |
| C_{SC} - sampling capacitor | RL1, RL2 - protection resistors |
| C_{VDD} - stabilising capacitor (100 nF) | R_{LOAD} - discharge resistor (100 kΩ recommended) |
| $C_{STC} \cdot C_{VDD} \geq 4:1$ | |

Figure 7. Basic Application Circuit for Supply From Battery

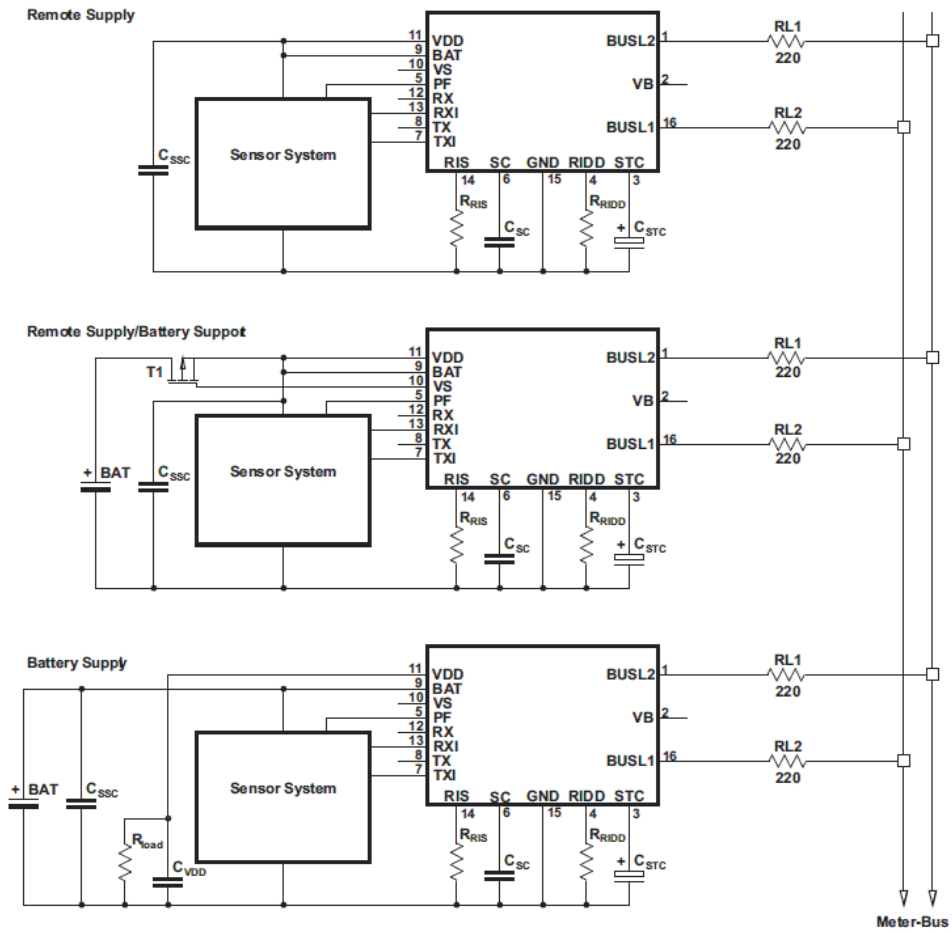


Figure 8. Basic Applications for Different Supply Modes

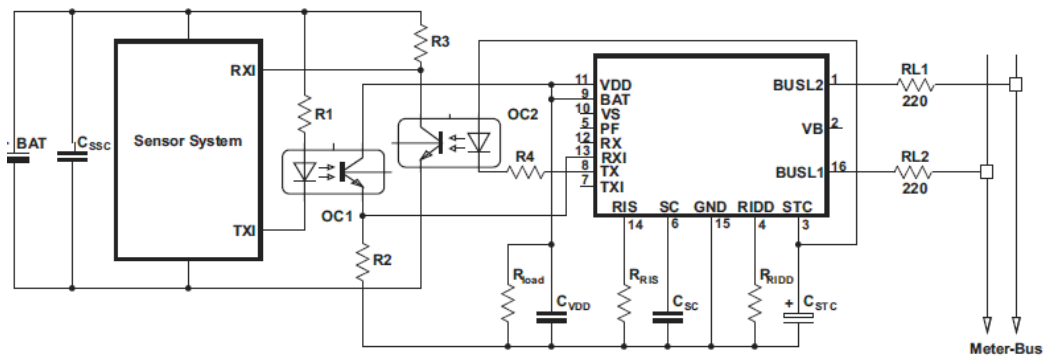
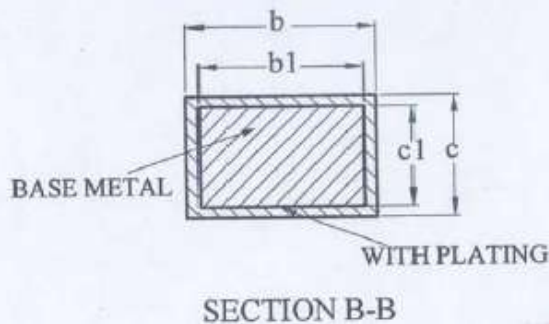
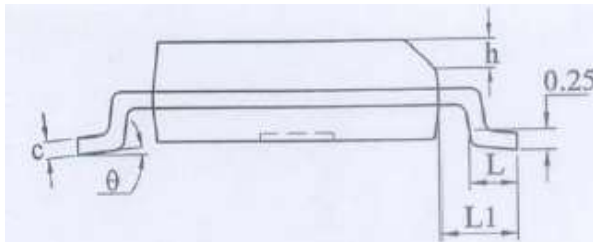
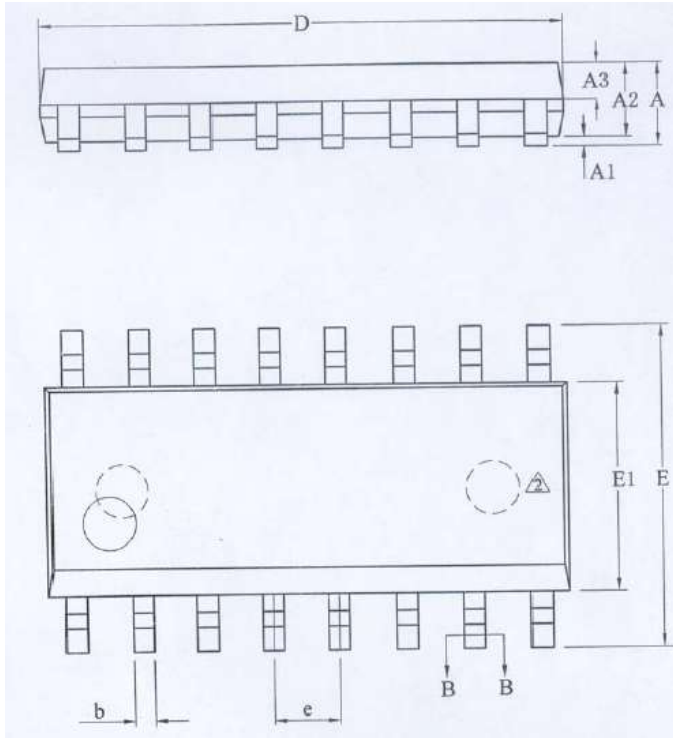


Figure 9. Basic Optocoupler Application

Outline Dimension (SOP-16)



SYMBOL	MILLIMETER		
	MIN	NOM	MAX
A	—	—	1.75
A1	0.05	—	0.225 \triangle
A2	1.30	1.40	1.50
A3	0.60	0.65	0.70
b	0.39	—	0.48
b1	0.38	0.41	0.43
c	0.21	—	0.26
c1	0.19	0.20	0.21
D	9.70	9.90	10.10
E	5.80	6.00	6.20
E1	3.70	3.90	4.10
e	1.27BSC		
h	0.25	—	0.50
L	0.50	—	0.80
L1	1.05BSC		
θ	0	—	8°