

## 1MHZ CMOS Rail-to-Rail IO Opamp with RF Filter

### Features

Single-Supply Operation from +1.8V ~ +6V Rail-to-Rail Input / Output Gain-Bandwidth Product: 1MHz (Typ) Low Input Bias Current: 1pA (Typ) Low Offset Voltage: 3.5mV (Max)

- Quiescent Current: 75µA per Amplifier (Typ) Embedded RF Anti-EMI Filter
- Operating Temperature: -40°C ~ +125°C
  Small Package:

HT6001 Available in SOT23-5 and SC70-5 Packages HT6002 Available in SOP-8 and MSOP-8 Packages HT6004 Available in SOP-14 and TSSOP-14 Packages

## **General Description**

The HT600X family have a high gain-bandwidth product of 1MHz, a slew rate of 0.8V/µs, and a quiescent current of 75µA/amplifier at 5V. The HT600X family is designed to provide optimal performance in low voltage and low noise systems. They provide rail-to-rail output swing into heavy loads. The input common mode voltage range includes ground, and the maximum input offset voltage is 3.5mV for HT600X family. They are specified over the extended industrial temperature range (-40~125°). The operating range is from 1.8V to 6V. The HT6001 single is available in Green SC70-5 and SOT23-5 packages. The HT6002 dual is available in Green SOP-8 and MSOP-8 packages. The HT6004 Quad is available in Green SOP-14 and TSSOP-14 packages.

## Applications

ASIC Input or Output Amplifier Sensor Interface Medical Communication Smoke Detectors

Audio Output Piezoelectric Transducer Amplifier Medical Instrumentation Portable Systems

## **Pin Configuration**

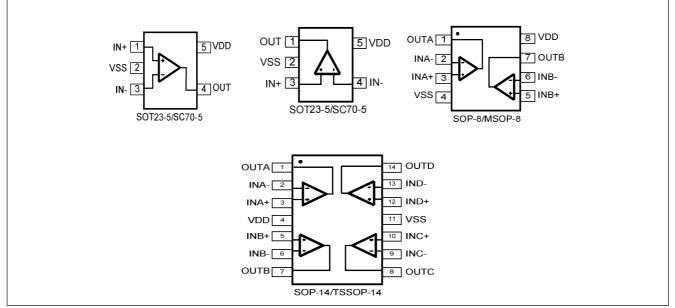


Figure 1. Pin Assignment Diagram



## **Absolute Maximum Ratings**

Condition	Min	Max			
Power Supply Voltage (V <sub>DD</sub> to Vss)	-0.5V	+7.5V			
Analog Input Voltage (IN+ or IN-)	Vss-0.5V	V <sub>DD</sub> +0.5V			
PDB Input Voltage	Vss-0.5V	+7V			
Operating Temperature Range	-40°C	+125°C			
Junction Temperature	+16	0°C			
Storage Temperature Range	-55°C	+150°C			
Lead Temperature (soldering, 10sec)	+260°C				
Package Thermal Resistance (T <sub>A</sub> =+25 <sub></sub> )					
SOP-8, θ <sub>JA</sub>	125°C/W				
MSOP-8, θ <sub>JA</sub>	216°	216°C/W			
SOT23-5, θ <sub>JA</sub>	190°	190°C/W			
SC70-5, θ <sub>JA</sub>	333°C/W				
ESD Susceptibility					
НВМ	6KV				
MM	40	400V			

**Note:** Stress greater than those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions outside those indicated in the operational sections of this specification are not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.



# **Electrical Characteristics**

(At VS = +5V, RL = $100k\Omega$ conne	ected to VS/2, and VOUT	= VS/2, unless otherwise noted.)

			HT6001/2/4				
PARAMETER	SYMBOL	SYMBOL CONDITIONS		MIN/MAX OVER TEMPERATURE			
			+25	+25	-40 to	UNITS	MIN/MAX
INPUT CHARACTERISTICS							
Input Offset Voltage	Vos	$V_{CM} = V_S/2$	0.8	3.5	5.6	mV	MAX
Input Bias Current	Ι <sub>Β</sub>		1			pА	TYP
Input Offset Current	I <sub>OS</sub>		1			pА	TYP
Common-Mode Voltage Range	V <sub>CM</sub>	V <sub>S</sub> = 5.5V	-0.1 to +5.6			V	TYP
Common Mode Paiastian Patia	CMRR	$V_{\rm S}$ = 5.5V, $V_{\rm CM}$ = -0.1V to 4V	70	62	62	dB	MINI
Common-Mode Rejection Ratio	CIVIRK	$V_{\rm S}$ = 5.5V, $V_{\rm CM}$ = -0.1V to 5.6V	68	56	55		MIN
	•	$R_L$ = 5k $\Omega$ , $V_O$ = +0.1V to +4.9V	80	70	70	dB	MINI
Open-Loop Voltage Gain	A <sub>OL</sub>	$R_L$ = 10k $\Omega$ , $V_O$ = +0.1V to +4.9V	100	94	85		MIN
Input Offset Voltage Drift	$\Delta V_{OS} / \Delta_T$		2.7			μV/	TYP
OUTPUT CHARACTERISTICS							
Output Voltage Swing from Rail	V <sub>OH</sub>	R <sub>L</sub> = 100kΩ	4.997	4.980	4.970	V	MIN
	V <sub>OL</sub>	R <sub>L</sub> = 100kΩ	5	20	30	mV	MAX
	V <sub>он</sub>	$R_L = 10k\Omega$	4.992	4.970	4.960	V	MIN
	V <sub>OL</sub>	$R_L = 10k\Omega$	8	30	40	mV	MAX
Outrast Ourrant	ISOURCE	D 400 L 1/ /0	84	60	45	~^ MI	MINI
Output Current	I <sub>SINK</sub>	$R_L = 10\Omega$ to $V_S/2$	75	60	45	- mA	MIN
POWER SUPPLY							
Operating Vallage Dange				1.8	1.8	V	MIN
Operating Voltage Range				6	6	V	MAX
Power Supply Rejection Ratio	PSRR	$V_{\rm S}$ = +2.5V to +6V, $V_{\rm CM}$ = +0.5V	82	60	58	dB	MIN
Quiescent Current / Amplifier	Ιq		75	110	125	μA	MAX
DYNAMIC PERFORMANCE (CL	_ = 100pF)						•
Gain-Bandwidth Product	GBP		1			MHz	TYP
Slew Rate	SR	G = +1, 2V Output Step	0.8			V/µs	TYP
Settling Time to 0.1%	ts	G = +1, 2V Output Step	5.3			μs	TYP
Overload Recovery Time		V <sub>IN</sub> ·Gain = V <sub>S</sub>	2.6			μs	TYP
NOISE PERFORMANCE							
Vallaga Naiga Daraitu		f = 1kHz	27			$nV/_{\gamma}Hz$	TYP
Voltage Noise Density	en	f = 10kHz	20			$nV/_{\chi}Hz$	TYP





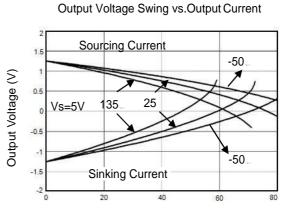
# **Typical Performance characteristics**

Output Voltage Swing vs.Output Current

At T\_A=+25°C, R\_L=100K\Omega connected to V\_S/2 and V\_{OUT}= V\_S/2, unless otherwise noted.

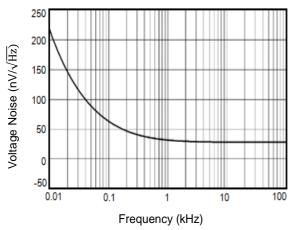
Sourcing Current -50 1. Output Voltage (V) 0.5 Vs=3V 135 25 -0.5 -1 -50 -1.5 Sinking Current -2 L 20 40 60 80

Output Current(mA)

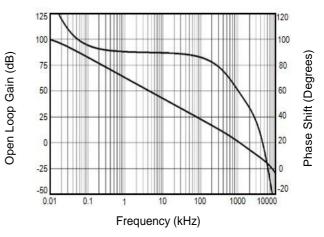


Output Current(mA)





Open Loop Gain, Phase Shift vs. Frequency





## **Application Note**

#### Size

HT600X family series op amps are unity-gain stable and suitable for a wide range of general-purpose applications. The small footprints of the HT600X family packages save space on printed circuit boards and enable the design of smaller electronic products.

#### **Power Supply Bypassing and Board Layout**

HT600X family series operates from a single 1.8V to 6V supply or dual ±0.9V to ±3V supplies. For best performance, a  $0.1 \mu F$  ceramic capacitor should be placed close to the V<sub>DD</sub> pin in single supply operation. For dual supply operation, both V<sub>DD</sub> and V<sub>SS</sub> supplies should be bypassed to ground with separate  $0.1 \mu F$  ceramic capacitors.

#### **Low Supply Current**

The low supply current (typical 75µA per channel) of HT600X family will help to maximize battery life. They are ideal for battery powered systems.

#### **Operating Voltage**

HT600X family operates under wide input supply voltage (1.8V to 6V). In addition, all temperature specifications apply from -40 °C to +125 °C. Most behavior remains unchanged throughout the full operating voltage range. These guarantees ensure operation throughout the single Li-lon battery lifetime.

#### **Rail-to-Rail Input**

The input common-mode range of HT600X family extends 100mV beyond the supply rails ( $V_{SS}$ -0.1V to  $V_{DD}$ +0.1V). This is achieved by using complementary input stage. For normal operation, inputs should be limited to this range.

#### **Rail-to-Rail Output**

Rail-to-Rail output swing provides maximum possible dynamic range at the output. This is particularly important when operating in low supply voltages. The output voltage of HT600X family can typically swing to less than 10mV from supply rail in light resistive loads (>100k $\Omega$ ), and 60mV of supply rail in moderate resistive loads (10k $\Omega$ ).

#### **Capacitive Load Tolerance**

The HT600X family is optimized for bandwidth and speed, not for driving capacitive loads. Output capacitance will create a pole in the amplifier's feedback path, leading to excessive peaking and potential oscillation. If dealing with load capacitance is a requirement of the application, the two strategies to consider are (1) using a small resistor in series with the amplifier's output and the load capacitance and (2) reducing the bandwidth of the amplifier's feedback loop by increasing the overall noise gain. Figure 2 shows a unity gain follower using the series resistor strategy. The resistor isolates the output from the capacitance and, more importantly, creates a zero in the feedback path that compensates for the pole created by the output capacitance.

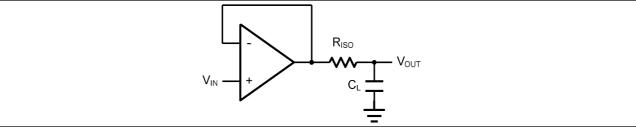


Figure 2 Indirectly Driving a Capacitive Load Using Isolation Resistor



The bigger the  $R_{ISO}$  resistor value, the more stable  $V_{OUT}$  will be. However, if there is a resistive load  $R_L$  in parallel with the capacitive load, a voltage divider (proportional to  $R_{ISO}/R_L$ ) is formed, this will result in a gain error.

The circuit in Figure 3 is an improvement to the one in Figure 2.  $R_F$  provides the DC accuracy by feed-forward the V<sub>IN</sub> to  $R_L$ .  $C_F$  and  $R_{ISO}$  serve to counteract the loss of phase margin by feeding the high frequency component of the output signal back to the amplifier's inverting input, thereby preserving the phase margin in the overall feedback loop. Capacitive drive can be increased by increasing the value of  $C_F$ . This in turn will slow down the pulse response.

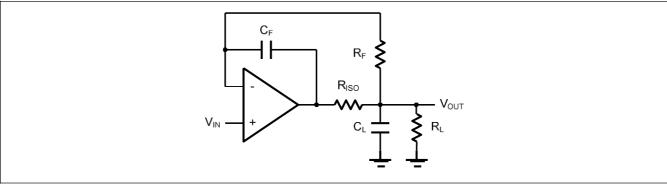


Figure 3. Indirectly Driving a Capacitive Load with DC Accuracy



## **Typical Application Circuits**

#### **Differential amplifier**

The differential amplifier allows the subtraction of two input voltages or cancellation of a signal common the two inputs. It is useful as a computational amplifier in making a differential to single-end conversion or in rejecting a common mode signal. Figure 4. shown the differential amplifier using HT600X family.

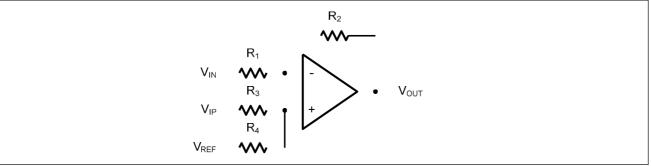


Figure 4. Differential Amplifier

$$V_{\text{OUT}} = (\underbrace{R_1 + R_2}_{R_3 + R_4}) \underbrace{R_4}_{R_1} V_{N} - \underbrace{R_2}_{R_1} V_{P} + (\underbrace{R_1 + R_2}_{R_3 + R_4}) \underbrace{R_3}_{R_1} V_{REF}$$

If the resistor ratios are equal (i.e.  $R_1=R_3$  and  $R_2=R_4$ ), then

 $V_{\text{OUT}} = \frac{R_2}{R_1} (V_{\text{IP}} - V_{\text{IN}}) + V_{\text{REF}}$ 

#### **Low Pass Active Filter**

The low pass active filter is shown in Figure 5. The DC gain is defined by  $-R_2/R_1$ . The filter has a -20dB/decade roll-off after its corner frequency  $f_c=1/(2\pi R_3 C_1)$ .

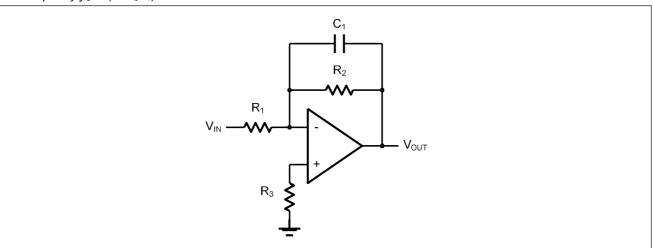


Figure 5. Low Pass Active Filter



### **Instrumentation Amplifier**

The triple HT600X family can be used to build a three-op-amp instrumentation amplifier as shown in Figure 6. The amplifier in Figure 6 is a high input impedance differential amplifier with gain of  $R_2/R_1$ . The two differential voltage followers assure the high input impedance of the amplifier.

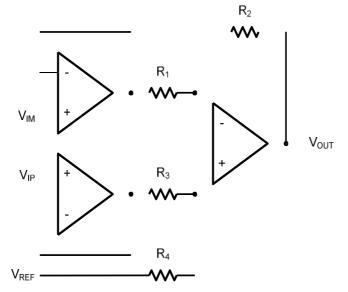
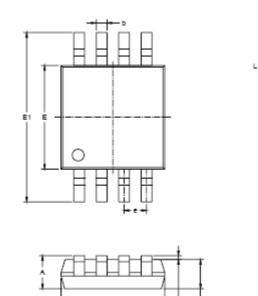


Figure 6. Instrument Amplifier



# **Package Information**

MSOP-8

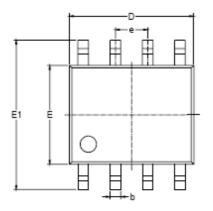


Symbol	Dimer In Milli	nsions meters	Dimensions In Inches		
	MIN	MAX	MIN	MAX	
А	0.820	1.100	0.032	0.043	
A1	0.020	0.150	0.001	0.006	
A2	0.750	0.950	0.030	0.037	
b	0.250	0.380	0.010	0.015	
с	0.090	0.230	0.004	0.009	
D	2.900	3.100	0.114	0.122	
E	2.900	3.100	0.114	0.122	
E1	4.750	5.050	0.187	0.199	
e	0.650	0.650 BSC		BSC	
L	0.400	0.800	0.016	0.031	
θ	0°	6°	0°	6°	

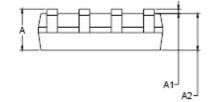
**A**1



## SOP-8



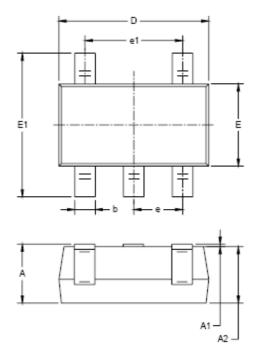


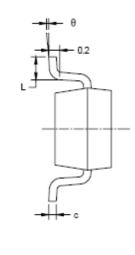


Symbol		nsions meters	Dimensions In Inches		
	MIN	MAX	MIN	MAX	
А	1.350	1.750	0.053	0.069	
A1	0.100	0.250	0.004	0.010	
A2	1.350	1.550	0.053	0.061	
b	0.330	0.510	0.013	0.020	
с	0.170	0.250	0.006	0.010	
D	4.700	5.100	0.185	0.200	
E	3.800	4.000	0.150	0.157	
E1	5.800	6.200	0.228	0.244	
e	1.27 BSC		0.050	BSC	
L	0.400	1.270	0.016	0.050	
6	0°	8°	0°	8°	



SOT23-5



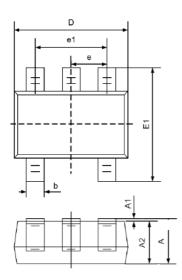


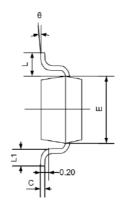
Symbol	Dimer In Milli	isions imeters	Dimensions In Inches		
	MIN	MAX	MIN	MAX	
A	1.050	1.250	0.041	0.049	
A1	0.000	0.100	0.000	0.004	
A2	1.050	1.150	0.041	0.045	
b	0.300	0.500	0.012	0.020	
с	0.100	0.200	0.004	0.008	
D	2.820	3.020	0.111	0.119	
E	1.500	1.700	0.059	0.067	
E1	2.650	2.950	0.104	0.116	
e	0.950	BSC	0.037 BSC		
e1	1.900 BSC		0.075	BSC	
L	0.300	0.600	0.012	0.024	
θ	0°	8°	0°	8°	



HT600x

SC70-5



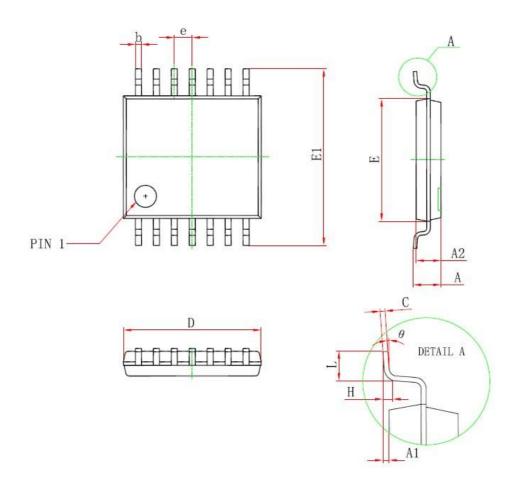


	Dimens	sions	Dimensions		
Symbol	In Milli	meters	In Inches		
	Min	Max	Min	Мах	
А	0.900	1.100	0.035	0.043	
A1	0.000	0.100	0.000	0.004	
A2	0.900	1.000	0.035	0.039	
b	0.150	0.350	0.006	0.014	
С	0.080	0.150	0.003	0.006	
D	2.000	2.200	0.079	0.087	
E	1.150	1.350	0.045	0.053	
E1	2.150	2.450	0.085	0.096	
е	0.650T	ΥP	0.026T	ΥP	
e1	1.200	1.400	0.047	0.055	
L	0.525R	EF	0.021R	EF	
L1	0.260	0.460	0.010	0.018	
θ	0°	8°	0°	8°	



HT600x

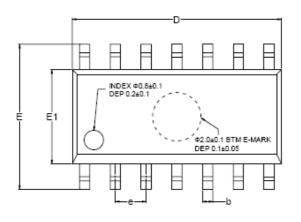
### TSSOP-14

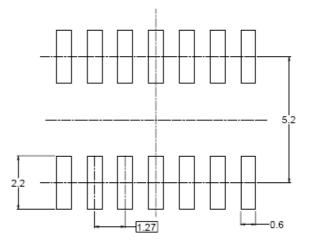


Symbol	Dimensions In	Millimeters	Dimensions In Inches	
Symbol	Min Max		Min	Max
D	4.900	5.100	0.193	0.201
E	4.300	4.500	0.169	0.177
b	0.190	0.300	0.007	0.012
с	0.090	0.200	0.004	0.008
E1	6.250	6.550	0.246	0.258
А		1.200		0.047
A2	0.800	1.000	0.031	0.039
A1	0.050	0.150	0.002	0.006
e	0.65 (BSC)		0.026	(BSC)
L	0.500	0.700	0.020	0.028
H	0.25(TYP)		0.01(TYP)	
θ	1°	7°	1°	7°

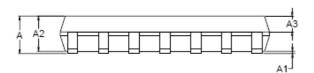


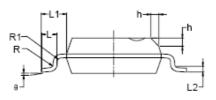
#### SOP-14





RECOMMENDED LAND PATTERN (Unit: mm)





Symbol	Dimensions In Millimeters			Dimensions In Inches		nches
Symbol	MIN	MOD	MAX	MIN	MOD	MAX
A	1.35		1.75	0.053		0.069
A1	0.10		0.25	0.004		0.010
A2	1.25		1.65	0.049		0.065
A3	0.55		0.75	0.022		0.030
b	0.36		0.49	0.014		0.019
D	8.53		8.73	0.336		0.344
E	5.80		6.20	0.228		0.244
E1	3.80		4.00	0.150		0.157
е	1.27 BSC			0.050 BSC		
L	0.45		0.80	0.018		0.032
L1		1.04 REF			0.040 REF	
L2	0.25 BSC		0.01 BSC			
R	0.07			0.003		
R1	0.07			0.003		
h	0.30		0.50	0.012		0.020
θ	0°		8°	0°		8°