

#### **Features**

**■** Exceeds Requirements of EIA-485 Standard

■ Data Rate: 500 kbps

Support Failsafe function

Low Power Consumption: < 1 μA Standby Supply Current

■ Large Receiver Hysteresis: 60mV

■ Up to 256 Nodes on a Bus (1/8 unit load)

■ Wide Supply Voltage 4.5V to 5.5V

■ SOP8 Package for Backward Compatibility

**■** Bus-Pin Protection:

• ±18 kV HBM protection

±12 kV IEC61000-4-2 Contact Discharge

### **Description**

The TPT485E is 4.5V~5.5V powered transceivers that meet the RS-485 and RS-422 standards for balanced communication. Driver outputs and receiver inputs are protected against ±18 kV ESD strikes without latch-up.

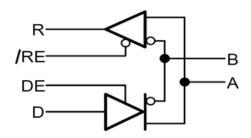
Transmitters in this family deliver exceptional differential output voltages as 2.5V (min) in 5Vcc power supplier, into the RS-485 required  $54\Omega$  load, for better noise immunity. These devices have very low bus currents so they present a true "1/8 unit load" to the RS-485 bus. This allows up to 256 transceivers on the network without using repeaters. Receiver (RX) inputs feature a "Full Fail-Safe" design, which ensures a logic high Rx output if Rx inputs are floating, shorted, or on a terminated but undriven bus.

The TPT485E is available in an SOP8 package, and is characterized from -40°C to 125°C.

### **Applications**

- E-Metering Networks
- HVAC Systems
- Video Surveillance Systems
- DMX512-Networks

# **Simplified Schematic**



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# **Revision History**

| Date      | Revision     | Notes            |
|-----------|--------------|------------------|
| 2019/3/27 | Rev. Pre 0.1 | Definition Draft |
| 2019/9/10 | Rev. Pre 0.2 | Update ESD data  |
| 2019/9/25 | Rev. 0       | Final version    |
|           |              |                  |
|           |              |                  |
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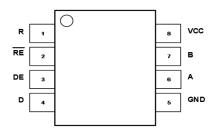
## **Order Information**

| Model Name | ame Order Number Pac |           | Transport Media, Quantity | Marking<br>Information |
|------------|----------------------|-----------|---------------------------|------------------------|
| TPT485E    | TPT485E-SO1R         | 8-Pin SOP | Tape and Reel 4,000       | T485E                  |

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# **Pin Configuration and Functions**

#### TPT485E-SO1R



| Pin No. | Pin Name        | I/O              | Description   |  |  |
|---------|-----------------|------------------|---|--|--|
| 1       | RO              | Digital output   | Receiver Output.  |  |  |
| 2       | /RE             | Digital input    | Receiver Output Enable.   |  |  |
| 3       | DE              | Digital input    | Driver Output Enable.   |  |  |
| 4       | DI              | Digital input    | Driver Input.   |  |  |
| 5       | GND             | Ground           | Ground.   |  |  |
| 6       | Α               | Bus input/output | Noninverting Receiver Input A and Noninverting Driver Output A. |  |  |
| 7       | В               | Bus input/output | Inverting Receiver Input B and Inverted Driver Output B.        |  |  |
| 8       | V <sub>CC</sub> | Power            | Power Supply.   |  |  |

## **Functional Table**

#### **DRIVER PIN FUNCTIONS**

| INPUT | ENABLE      | OUT | PUTS | DESCRIPTION                |  |  |  |
|-------|-------------|-----|------|----------------------------|--|--|--|
| D     | DE          | Α   | В    | DESCRIPTION                |  |  |  |
|       | NORMAL MODE |     |      |                            |  |  |  |
| Н     | Н           | Н   | L    | Actively drives bus High   |  |  |  |
| L     | Н           | L   | Н    | Actively drives bus Low    |  |  |  |
| Х     | L           | Z   | Z    | Driver disabled            |  |  |  |
| Х     | OPEN        | Z   | Z    | Driver disabled by default |  |  |  |
| OPEN  | Н           | Н   | L    | Actively drives bus High   |  |  |  |

#### **RECEIVER PIN FUNCTIONS**

| DIFFERENTIAL INPUT           | ENABLE | OUTPUT | DESCRIPTION                     |
|------------------------------|--------|--------|---------------------------------|
| $V_{ID} = V_A - V_B$         | /RE    | R      | DESCRIFTION                     |
|                              |        |        | NORMAL MODE                     |
| $V_{IT+} < V_{ID}$           | L      | Н      | Receive valid bus High          |
| $V_{IT-} < V_{ID} < V_{IT+}$ | L      | ?      | Indeterminate bus state         |
| $V_{ID} < V_{IT-}$           | L      | L      | Receive valid bus Low           |
| X                            | Н      | Z      | Receiver disabled               |
| X                            | OPEN   | Z      | Receiver disabled               |
| Open, short, idle Bus        | L      | Н      | Out of polarity correction time |

## **Absolute Maximum Ratings**

| V <sub>CC</sub> to GND                      | -0.3V to +7V            |
|---|-------------------------|
| Input Voltages DI, DE, /RE                  | -0.3V to (VCC + 0.3V)   |
| I/O Voltages A, B                           | -15V to +15V            |
| A, B (Transient Pulse Through $100\Omega$ ) | . ±100V                 |
| R   | -0.3V to (VCC +0.3V)    |
| Short Circuit Duration A, B                 | Continuous              |
| ESD Rating                                  | See Specification Table |

<sup>\*</sup> **Note:** Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

# **Recommended Operating Conditions**

| Supply Voltage                                 | . 4.5V to 5.5V |
|--|----------------|
| Temperature Range                              | 40°C to +125°C |
| Bus Pin Common Mode Voltage Range              | 7V to +12V     |
| Thermal Resistance, OJA (Typical)              |                |
| 8-Pin SOP Package                              | 136°C/W        |
| Maximum Junction Temperature (Plastic Package) | +150°C         |
| Maximum Storage Temperature Range              | 65°C to +150°C |

# **ESD Rating**

|   |                        | Value | Unit |
|---|------------------------|-------|------|
| Contact Discharge, per IEC 61000-4-2                | Bus Pin                | 12    | kV   |
| HDM por ANGL/EQDA/JEDEC IS 004 / ANGL/EQD CTME F 1  | Bus Pin                | 18    | kV   |
| HBM, per ANSI/ESDA/JEDEC JS-001 / ANSI/ESD STM5.5.1 | All Pin Except Bus Pin | 4     | kV   |
| CDM, per ANSI/ESDA/JEDEC JS-002                     |                        | 1500  | V    |

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## **Electrical Characteristics**

Test Conditions: VCC = 5V, Over operating free-air temperature range (unless otherwise noted)

| Parameter                       |  | Conditions  |                                    | Min  | Тур     | Max | Units |
|---------------------------------|--|---|------------------------------------|------|---------|-----|-------|
| Driver                          |  |   |                                    |      |         |     |       |
|                                 | Driver differential-output voltage                                     | RL = 60 Ω,<br>-7V≤V test ≤12V   | See Figure 1B                      | 2.0  | 3.5     |     |       |
| $ V_{OD} $                      | magnitude  | RL = 54 Ω (RS-485)  | See Figure 1A                      | 2.0  | 3.4     |     | V     |
|                                 |  | RL = 100 Ω (RS-485)   |                                    | 2.7  | 3.7     |     |       |
| ⊿ V <sub>OD</sub>               | Change in magnitude of driver differential-output voltage              | RL = 54 Ω, CL=50pF  | See Figure 1A                      | -50  |         | 50  | mV    |
| V <sub>OC(SS)</sub>             | Steady-stage common-mode output voltage                                |   |                                    | 1    | VCC/2   | 3   | ٧     |
| △Voc                            | Change in differential driver common-mode output voltage               | Center of two 27-Ω load resistors   | See Figure 1A                      | -65  |         | 65  | mV    |
| $V_{\text{OC(PP)}}$             | Peak-to-peak driver common-<br>mode output voltage                     |   |                                    |      | 600     |     |       |
| I <sub>OS</sub>                 | Driver short-circuit output current                                    | los with A shorted to   | В                                  |      | 90      | 110 | mA    |
| Receiver                        |  |   |                                    |      |         |     |       |
| V <sub>IT+</sub>                | Positive-going receiver differential-input voltage threshold           |   |                                    |      | -100    | -15 | mV    |
| V <sub>IT</sub> -               | Negative-going receiver differential-input voltage threshold           |   |                                    | -240 | -150    |     | mV    |
| V <sub>HYS</sub> <sup>(1)</sup> | Receiver differential-input voltage threshold hysteresis (VIT+ – VIT-) |   |                                    |      | 60      |     | mV    |
| VIH                             | Logic Input High Voltage   | DI, DE, RE  |                                    | 2    |         |     | V     |
| VIL                             | Logic Input Low Voltage  | DI, DE, RE  |                                    |      |         | 0.8 | V     |
| V <sub>OH</sub>                 | Receiver high-level output voltage                                     | I <sub>OH</sub> = -8 mA   |                                    | 4.0  | VCC-0.3 |     | V     |
| V <sub>OL</sub>                 | Receiver low-level output voltage                                      | I <sub>OL</sub> = 8 mA  |                                    |      | 0.2     | 0.4 | V     |
| l <sub>i</sub>                  | DE=0, VCC=0 or VCC=5.5V  | VI=12V  |                                    |      | 30      | 120 | μA    |
| -1                              |  | VI=-7V  |                                    | -100 | -50     |     | μΑ    |
| RA, RB                          | Bus input impedance  | VA=-7V, VB=12V or VA  | =12V, VB=-7V                       | 96   |         |     | kΩ    |
| l <sub>oz</sub>                 | Receiver high-impedance output current                                 | VO = 0 V or VCC, /RE a  | at VCC                             | -1   |         | 1   | μΑ    |
| I <sub>OSR</sub>                | Receiver output short to ground current                                | REN=0, DE=VCC   |                                    |      | 80      | 95  | mA    |
| Logic                           |  |   |                                    |      |         |     |       |
| lin                             | Input current (RE, DE, D)  | 4.5V <vcc<5.5v< td=""><td>-5</td><td></td><td>5</td><td>uA</td></vcc<5.5v<> |                                    | -5   |         | 5   | uA    |
| Supply                          |  |   |                                    |      |         |     |       |
|                                 |  | Driver and receiver enabled   | DE = VCC, /RE = GND, No LOAD       |      | 650     | 800 |       |
|                                 | Supply current(quiescent)  | Driver enabled, receiver disabled   | DE = /RE = Vcc,<br>No LOAD         |      | 450     | 600 |       |
| I <sub>CC</sub>                 |  | Driver disabled, receiver enabled   | DE = /RE = GND,<br>No LOAD         |      | 450     | 600 | μΑ    |
|                                 |  | Driver and receiver disabled  | DE = GND, /RE =<br>D= VCC, No LOAD |      | 0.5     | 2   |       |

# **Switching CHARACTERISTICS**

| Parameter                           |  | Conditions                 |              | Min | Тур  | Max  | Units |
|-------------------------------------|--|----------------------------|--------------|-----|------|------|-------|
| DRIVER                              |  |                            |              |     |      |      |       |
| t <sub>r</sub> , t <sub>f</sub>     | Driver differential-output rise and fall times |                            |              |     | 300  |      |       |
| t <sub>PHL</sub> , t <sub>PLH</sub> | Driver propagation delay                       | RL = 54 $\Omega$ , CL=50pF | See Figure 2 | 200 | 300  | 410  | ns    |
| tsk(P)                              | Driver pulse skew,  tphl - tplh                |                            |              |     | 50   | 90   |       |
|                                     | Driver disable time                            | RE = 0                     |              |     | 50   | 100  | ns    |
| tphz, tplz                          | Driver disable time                            | RE = VCC                   | T _ [        |     | 50   | 100  |       |
| (DZII (DZI                          | Driver enable time                             | RE = 0                     | See Figure 3 |     | 200  | 450  | ns    |
| tPZH, tPZL                          |  | RE = VCC                   |              |     | 2800 | 4000 |       |
| RECEIVER                            |  |                            |              |     |      |      |       |
| tr, tf                              | Receiver output rise and fall times            |                            |              |     | 30   |      |       |
| tphL, tpLH                          | Receiver propagation delay time                | CL=15 pF                   | See Figure 5 |     | 100  | 150  | ns    |
| tsk(P)                              | Receiver pulse skew,  tphl - tplh              |                            |              |     |      | 25   |       |
| tPHZ, tPLZ                          | Receiver disable time                          |                            |              |     | 20   | 65   | ns    |
| tPZL                                |  | DE = VCC                   | See Figure 6 |     | 130  | 250  |       |
| tPZH                                | Receiver enable time                           | DE = 0                     | See Figure 6 |     | 2800 | 4000 | ns    |

# **Test Circuits and Waveforms**

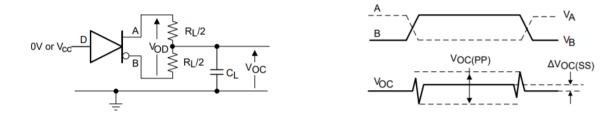


Figure 1. DC Driver Test Circuits

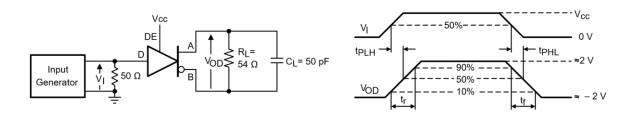


Figure 2. Driver Propagation Delay and Differential Transition Times

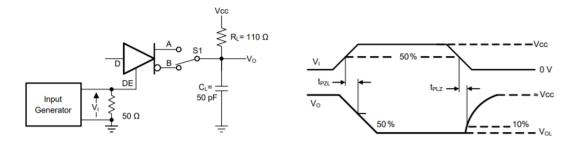


Figure 3. Driver Enable and Disable Times

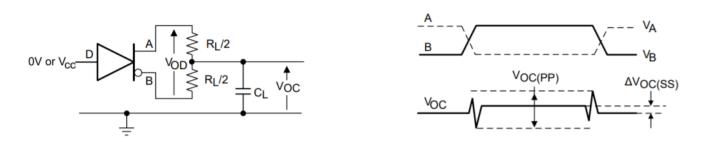


Figure 4. Driver Propagation Delay and Rise/Fall Time Measurement

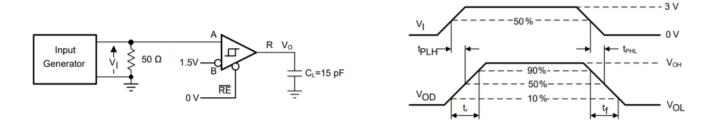


Figure 5. Receiver Propagation Delay and Data rate

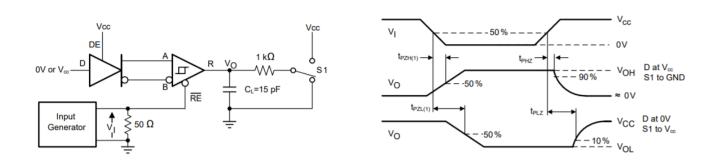
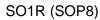
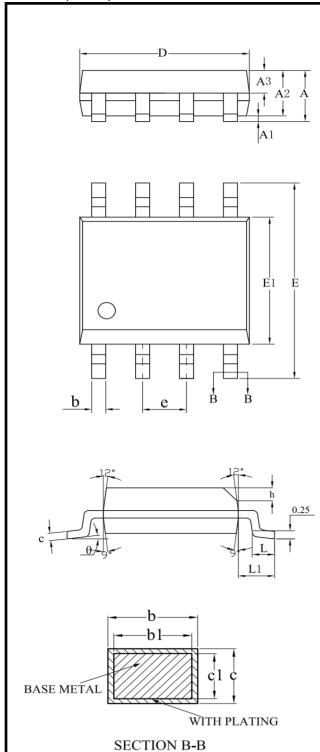


Figure 6. Receiver Enable and Disable Times

# **Package Outline Dimensions**





| SYMBOL  | MILLIMETER |         |       |  |  |
|---------|------------|---------|-------|--|--|
| STWIDOL | MIN        | NOM     | MAX   |  |  |
| A       | _          | _       | 1.75  |  |  |
| A1      | 0.10       | _       | 0.225 |  |  |
| A2      | 1.30       | 1.40    | 1.50  |  |  |
| A3      | 0.60       | 0.65    | 0.70  |  |  |
| b       | 0.39       | _       | 0.47  |  |  |
| b1      | 0.38       | 0.41    | 0.44  |  |  |
| с       | 0.20       | _       | 0.24  |  |  |
| c1      | 0.19       | 0.20    | 0.21  |  |  |
| D       | 4.80       | 4.90    | 5.00  |  |  |
| Е       | 5.80       | 6.00    | 6.20  |  |  |
| E1      | 3.80       | 3.90    | 4.00  |  |  |
| e       |            | 1.27BSC |       |  |  |
| h       | 0.25       | _       | 0.50  |  |  |
| L       | 0.50       | _       | 0.80  |  |  |
| L1      | 1.05REF    |         |       |  |  |
| θ       | 0          | _       | 8°    |  |  |

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