Driver IC for PPC

High Performance, High Reliability 50V DC Brush Motor Driver for PPC's others

BD63130AFM

General Description

BD63130AFM is one H-bridge motor driver for DC brush motor. This driver can facilitate low power consumption by direct PWM or PWM constant current control. There are built in protection circuits in this IC. It is possible to output an abnormal detection signal for Wired-OR that notifies each protection circuit operation, which contributes to set high reliability.

Features

- Single Power Supply Input (rated voltage of 50V)
- Rated Output Current (peak): 3.0A(4.0A)
- Low ON-Resistance DMOS Output
- Forward, Reverse, Brake, Open
- Power Save Function
- External PWM Control
- PWM Constant Current Control (current limit function)
- Built-in Spike Noise Cancel Function (external noise filter is unnecessary)
- Driver for DC Brush Motor
- Built-in Logic Input Pull-down Resistor
- Cross-conduction Prevention Circuit
- Output Detection Signal during Abnormal states (Wired-OR)
- Thermal Shutdown Circuit (TSD)
- Over-current Protection Circuit (OCP)
- Under Voltage Lock out Circuit (UVLO)
- Over Voltage Lock out Circuit (OVLO)
- Ghost Supply Prevention (protects against malfunction when power supply is disconnected)
- HSOP-M36 package

Application

- Plain Paper Copier (PPC), Multi-function Printer, Laser Printer, Inkjet Printer, Photo Printer, FAX, Mini Printer and etc.

Key Specifications

- Power Supply Voltage Range: 8.0V to 46.2V
- Rated Output Current: 3.0A
- Rated Output Current (Peak): 4.0A
- Operating Temperature Range: -25°C to +85°C
- Output ON-Resistance: 0.55Ω(Typ)
  (Total of upper and lower resistors)

Package
	W(Typ) x D(Typ)x H(Max)
HSOP-M36	18.50mm x 9.90mm x 2.40mm

Figure 1. HSOP-M36

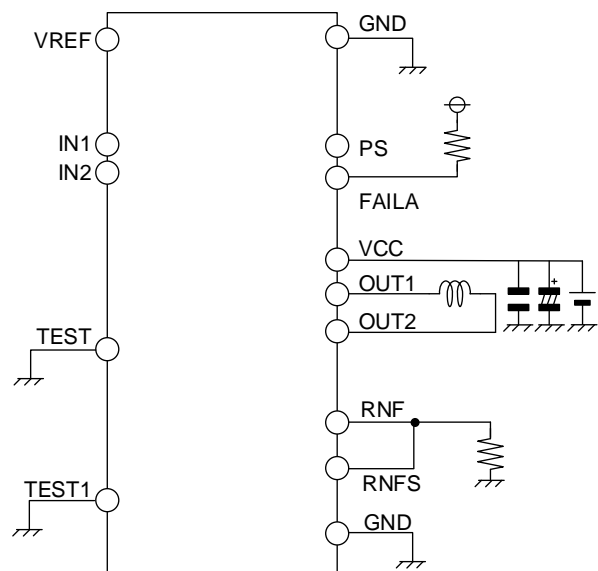## Typical Application Circuit

Figure 2. Application Circuit

○Product structure : silicon monolithic integrated circuit ○This product has no designed protection against radioactive rays.
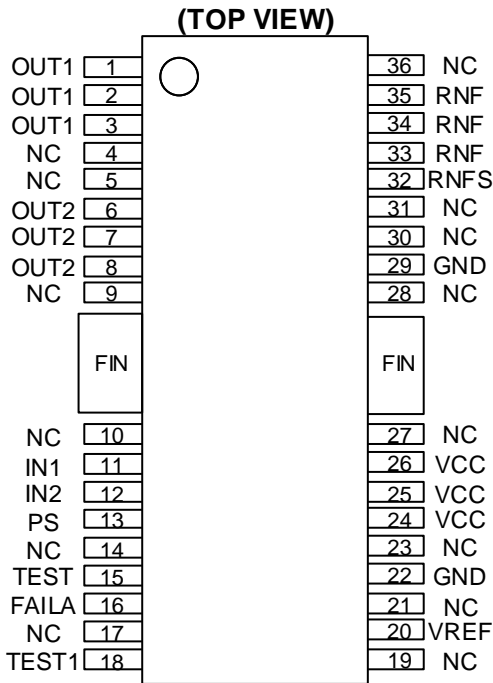
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Pin Configuration

(TOP VIEW)

Figure 3. Pin Configuration

Block Diagram
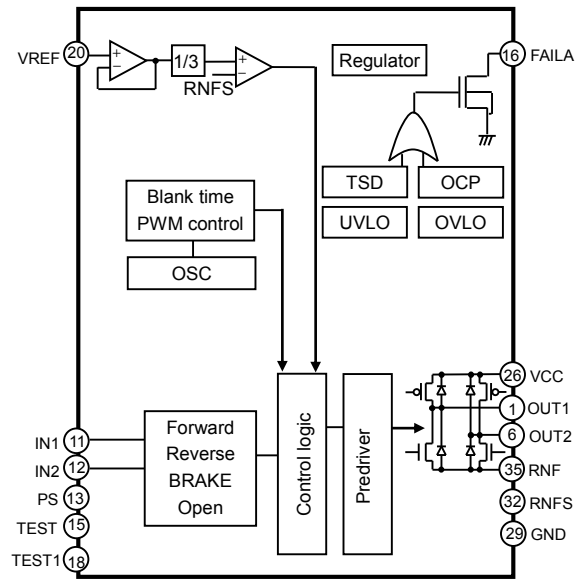
Figure 4. Block Diagram

Pin Descriptions

Pin No.	Pin Name	Function	Pin No.	Pin Name	Function
1	OUT1		19	NC	Non-connection
2	OUT1	H bridge output pin	20	VREF	Current limit setting pin
3	OUT1		21	NC	Non-connection
4	NC	Non-connection	22	GND	Ground pin
5	NC	Non-connection	23	NC	Non-connection
6	OUT2		24	VCC	
7	OUT2	H bridge output pin	25	VCC	Power supply pin
8	OUT2		26	VCC	
9	NC	Non-connection	27	NC	Non-connection
FIN	FIN	Fin pin (used by connecting with GND)	FIN	FIN	Fin pin (used by connecting with GND)
10	NC	Non-connection	28	NC	Non-connection
11	IN1	H bridge control pin	29	GND	Ground pin
12	IN2	H bridge control pin	30	NC	Non-connection
13	PS	Power save pin	31	NC	Non-connection
14	NC	Non-connection	32	RNFS	Input pin of current detection comparator
15	TEST	Pin for testing (used by connecting with GND)	33	RNF	
16	FAILA	Output signal to detect abnormal states	34	RNF	Connection pin of resistor for output current detection
17	NC	Non-connection	35	RNF	
18	TEST1	Pin for testing (used by connecting with GND)	36	NC	Non-connection

Absolute Maximum Ratings (Ta=25°C)

Parameter	Symbol	Rating	Unit
Supply Voltage	V_{CC}	-0.2 to +50.0	V
Input Voltage for Control Pin	V_{IN}	-0.2 to +5.5	V
RNF Maximum Voltage	V_{RNF}	0.7	V
Output Current	I_{OUT}	3.0 (Note 1)	A/ch
Output Current (PEAK) (Note 2)	$I_{OUTPEAK}$	4.0 (Note 1)	A/ch
Output Current (BRAKE) (Note 3)	$I_{OUTBRAKE}$	6.0 (Note 1)	A/ch
Storage Temperature Range	Tstg	-55 to +150	°C
Maximum Junction Temperature	Tjmax	+150	°C

(Note 1) Do not, however exceed Tjmax=150°C.
(Note 2) 2s or under and duty 20% over 3A.
(Note 3) This current is flowed switching from forward rotation and reverse rotation to the brake mode.
Caution 1: *Operating the IC over the absolute maximum ratings may damage the IC. The damage can either be a short circuit between pins or an open circuit between pins and the internal circuitry. Therefore, it is important to consider circuit protection measures, such as adding a fuse, in case the IC is operated over the absolute maximum ratings.*
Caution 2: *Should by any chance the maximum junction temperature rating be exceeded the rise in temperature of the chip may result in deterioration of the properties of the chip. In case of exceeding this absolute maximum rating, design a PCB boards with thermal resistance taken into consideration by increasing board size and copper area so as not to exceed the maximum junction temperature rating.*

Recommended Operating Conditions

Parameter	Symbol	Range	Unit
Operating Temperature Range	Topr	-25 to +85	°C
Supply Voltage	V_{CC}	8.0 to 46.2	V
Maximum Output Current (Continuous)	I_{OUT}	2.0 (Note 4)	A/ch

(Note 4) Do not, however exceed Tjmax=150°C.

Thermal Resistance (Note 5)

Parameter	Symbol	Thermal Resistance (Typ) 1s (Note 7)	2s2p (Note 8)	Unit
HSOP-M36				
Junction to Ambient	θ_{JA}	53.9	26.4	°C/W
Junction to Top Characterization Parameter (Note 6)	Ψ_{JT}	3	2	°C/W

(Note 5) Based on JESD51-2A(Still-Air).
(Note 6) The thermal characterization parameter to report the difference between junction temperature and the temperature at the top center of the outside surface of the component package.
(Note 7) Using a PCB board based on JESD51-3.
(Note 8) Using a PCB board based on JESD51-7.

Layer Number of Measurement Board	Material	Board Size
Single	FR-4	114.3mm x 76.2mm x 1.57mmt

Top	
Copper Pattern	Thickness
Footprints and Traces	70μm

Layer Number of Measurement Board	Material	Board Size
4 Layers	FR-4	114.3mm x 76.2mm x 1.6mmt

Top		2 Internal Layers		Bottom	
Copper Pattern	Thickness	Copper Pattern	Thickness	Copper Pattern	Thickness
Footprints and Traces	70μm	74.2mm x 74.2mm	35μm	74.2mm x 74.2mm	70μm

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Electrical Characteristics (Unless otherwise specified Ta=25°C, V$_{CC}$=24V)

Parameter	Symbol	Limit			Unit	Conditions
		Min	Typ	Max		
【Whole】						
Circuit Current at Standby	I$_{CCST}$	-	-	10	µA	PS=L
Circuit Current	I$_{CC}$	-	2.5	5.0	mA	PS=H, VREF=2V
【Control Input】						
H Level Input Voltage	V$_{INH}$	2.0	-	-	V	
L Level Input Voltage	V$_{INL}$	-	-	0.8	V	
H Level Input Current	I$_{INH}$	35	50	100	µA	V$_{IN}$=5V
L Level Input Current	I$_{INL}$	-10	0	-	µA	V$_{IN}$=0V
【Output (OUT1, OUT2)】						
Output ON-Resistance	R$_{ON}$	-	0.55	0.72	Ω	I$_{OUT}$ =±2.0A (Sum of upper and lower)
Output Leak Current	I$_{LEAK}$	-	-	10	µA	
【Current Control】						
RNF Input Current	I$_{RNF}$	-80	-40	-	µA	RNF=0V
VREF Input Current	I$_{VREF}$	-2.0	-0.1	-	µA	VREF=0V
VREF Input Voltage Range	V$_{VREF}$	-	-	2.0	V	
Minimum on Time (Blank Time)	t$_{ONMIN}$	0.7	1.5	3.0	µs	
Comparator Threshold	V$_{CTH}$	0.475	0.500	0.525	V	VREF=1.5V

Application Information

Points to Notice for Pin Description and PCB Layout

(1) PS/ Power Save Pin

PS can make circuit into standby state and make motor outputs OPEN.

Be careful because there is a delay of 40μs(Max), as PS=L→H, until it is returned from standby state to normal state and the motor output becomes ACTIVE.

PS	State
L	POWER SAVE (STANDBY)
H	ACTIVE

(2) IN1, IN2/ H Bridge Control Pin

It decides output logic for H bridge.

Input			Output		State
PS	IN1	IN2	OUT1	OUT2	
L	x	x	OPEN	OPEN	POWER SAVE (STANDBY)
H	L	L	OPEN	OPEN	STOP
H	H	L	H	L	FORWARD
H	L	H	L	H	REVERSE
H	H	H	L	L	BRAKE

x : H or L

(3) TEST, TEST1/ Pin for Testing

This is the pin used at the time of distribution test. Connect to GND. Be careful because there is a possibility of malfunction if it is not connected to GND.

(4) VCC/ Power Supply Pin

Motor's drive current is flowing in it, so the wire is thick, short and has low impedance. Voltage VCC may have great fluctuation, so arrange the bypass capacitor of about 100μF to 470μF as close to the pin as possible and adjust the voltage VCC is stable. Increase the capacity as needed especially, when a large current is used or those motors that have great back electromotive force are used.

In addition, for the purpose of reducing of power supply's impedance in wideband, it is recommended to set parallel connection of multi-layered ceramic capacitor of 0.01μF to 0.1μF etc. Extreme care must be used to make sure that the voltage VCC does not exceed the rating even for a moment. Still more, in the power supply pin, there is built-in clamp component for preventing of electrostatic destruction. When a steep pulse signal or voltage such as a surge exceeding the absolute maximum rating is applied, this clamp component operates, as a result there is the danger of destruction, so be sure that the absolute maximum rating must not be exceeded. It is effective to mount a Zener diode of about the absolute maximum rating. Moreover, the diode for preventing of electrostatic destruction is inserted between VCC pin and GND pin, as a result there is the danger of IC destruction if reverse voltage is applied between VCC pin and GND pin, so be careful.

(5) GND/ Ground Pin

In order to reduce the noise caused by switching current and to stabilize the internal reference voltage of IC, the wiring impedance from this pin is made as low as possible to achieve the lowest electrical potential no matter what operating state it may be. Moreover, design patterns not to have any common impedance with other GND patterns.

(6) OUT1, OUT2/ H Bridge Output Pin

Motor's drive current is flowing in it, so the wire is thick, short and has low impedance. It is also effective to add a Schottky diode if output has positive or negative great fluctuation when large current is used. For example, counter electromotive voltage etc. Moreover, in the output pin, there is built-in clamp component for preventing of electrostatic destruction. When a steep pulse signal or voltage such as a surge exceeding the absolute maximum rating is applied, this clamp component operates, as a result there is the danger of even destruction, so be sure that the absolute maximum rating must not exceeded.

(7) RNF/ Connection Pin of Resistor for Detecting of Output Current

Connect the resistor of 0.1Ω to 0.3Ω for current detection between this pin and GND. Determine the resistor so that power consumption $W=I_{OUT}^2 \cdot R$ [W] of the current-detecting resistor does not exceed the power dissipation of the resistor. In addition, it has a low impedance and does not have a common impedance with other GND patterns because motor's drive current flows in the pattern through RNF Pin to current-detecting resistor to GND. Do not exceed the rating because there is the possibility of circuits' malfunction etc., if RNF voltage has exceeded the maximum rating (0.7V). If RNF pin is open, then there is the possibility of such malfunction as output current does not flow either, so do not let it open.

Application Information – continued

(8) RNFS/ Input Pin of Current detection Comparator

In this series, RNFS pin, which is the input pin of current detection comparator, is independently arranged in order to decrease the lowering of current-detecting accuracy caused by the wire impedance inside the IC of RNF pin. Therefore, be sure to connect RNF pin and RNFS pin together when using in the case of PWM constant current control. In addition, because the wires from RNFS pin is connected near the current-detecting resistor in the case of interconnection, the lowering of current-detecting accuracy, which is caused by the impedance of board pattern between RNF pin and the current-detecting resistor, can be decreased. Moreover, design the pattern there is no noise plunging.

(9) VREF/ Output Current limit setting Pin

[When to use current limit]

This is the pin to set the current limit value. It can be set by VREF voltage and current-detecting resistor (RNF resistor).

$$I_{OUT} = \frac{VREF}{3} / \; RNF \qquad [A]$$

Where:

I_{OUT} is the output current.
VREF   is the voltage of output current limit setting.
RNF   is the current-detecting resistor.

Avoid using it with VREF pin open because if VREF pin is open, the input is unsettled, and the VREF voltage increases, and then there is the possibility of such malfunctions as the setting current increases and a large current flows etc. Keep to the input voltage range because if the voltage of 2V or more is applied on VREF pin, then there is also the danger that a large current flows in the output and so OCP or TSD will operate. Besides, select the resistance value in consideration of the outflow current (Max 2μA) if it is inputted by resistance division. The minimum current, which can be controlled by VREF voltage, is determined by motor coil's L, R values and minimum ON time because there is a minimum ON time in PWM drive.

[When not to use current limit]

Short RNF pin with the GND. However, there is a possibility of PWM constant current control depending on the impedance of board pattern. For the reason, when not to use PWM constant current control, input 1V to 2V to VREF pin (Refer to figure 8.).

(10) FAILA/ Fault Signal Output Pin

FAILA outputs abnormality detection signal when Over-Current Protection (OCP) or Thermal Shutdown (TSD) operates. Even if Under Voltage Lock Out (UVLO) or Over Voltage Lock Out (OVLO) operates, FAILA signal doesn't turn abnormality detection signal (i.e. high). This signal can be connected to the microcomputer and the system can be shut down.

This pin is an open drain type, so set the pull up resistor (5kΩ to 100kΩ) to power supply 7V or less (i.e. 5V or 3.3V). If not using this pin, connect it to GND.

OCP	TSD	FAILA
OFF	OFF	H (OFF)
OFF	ON	M (ON)
ON	OFF	L (ON)
ON	ON	L (ON)

(11) NC Pin

This pin is unconnected electrically with IC internal circuit.

(12) FIN Pin

HSOP-M36 package is mounted with the heat-radiating FIN pin, and be sure to connect the metal by solder with the GND on the board and get as wide GND pattern as possible. Be careful because Thermal Resistance is increasing if not connected by solder.

Moreover, the FIN pin is shorted with IC chip's back side and becomes the GND potential, so there is the danger of malfunction and destruction if shorted with potentials other than GND. Therefore, absolutely do not connect with potentials other than GND.

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Protection Circuits

Thermal Shutdown (TSD)

This IC has a built-in Thermal Shutdown circuit for thermal protection. When the IC's chip temperature rises 175°C (Typ) or more, the motor output becomes OPEN. Also, when the temperature returns to 150°C (Typ) or less, it automatically returns to normal operation. However, even when TSD is in operation, if heat is continued to be applied externally, heat overdrive can lead to destruction.

Over-Current Protection (OCP)

This IC has a built in Over-Current Protection circuit as a provision against destruction when the motor outputs are shorted to each other or VCC-motor output or motor output-GND is shorted. This circuit latches the motor output to OPEN condition when the regulated current flows for 4μs (Typ). It returns with power reactivation or a reset of the PS pin. The over-current protection circuit aims to prevent the destruction of the IC only from abnormal situations such as when motor output is shorted and it is not meant to be used as protection or security for the device. Therefore, the device should not be designed to make use of the function of this circuit. After OCP operation, if abnormal situations continue and returned by power reactivation or reset of the PS pin happens repeatedly, then OCP operates constantly. The IC may generate heat or otherwise deteriorate. When the L value of the wiring is great due to the wiring being long, if the output pin voltage jumps up and the absolute maximum values may be exceeded after the over current has flowed, there is a possibility of destruction. Also when current which is the output current rating or more and the OCP detection current or less flows, the IC can heat up to Tjmax=150°C or more and can deteriorate, so current which exceeds the output rating should not be applied.

Under Voltage Lock Out (UVLO)

This IC has a built-in Under Voltage Lock Out function to prevent false operation such as IC output during power supply under voltage. When the applied voltage to the VCC pin goes 5V (Typ) or less, the motor output is set to OPEN. This switching voltage has a 1V (Typ) hysteresis to prevent false operation by noise etc. Be aware that this protection circuit does not operate during power save mode.

Over Voltage Lock Out (OVLO)

This IC has a built-in Over Voltage Lock Out function to protect the IC output and the motor during power supply over voltage. When the applied voltage to the VCC pin goes 52V (Typ) or more, the motor output is set to OPEN. This switching voltage has a 1V (Typ) hysteresis and a 4μs (Typ) mask time to prevent false operation by noise etc. Although this over voltage locked out circuit is built-in, there is a possibility of destruction if the absolute maximum value for power supply voltage is exceeded. Therefore, the absolute maximum value should not be exceeded. Be aware that this protection circuit does not operate during power save mode.

Ghost Supply Prevention (protects against malfunction when power supply is disconnected)

If a control signal (IN1, IN2, PS, and VREF) is applied when there is no power supplied to the IC, there is a function which prevents a malfunction where voltage is supplied to power supply of this IC or other IC in the set via the electrostatic destruction prevention diode from these input pins to the VCC. Therefore, there is no malfunction in the circuit even when voltage is supplied to these input pin while there is no power supply.

Operation Under Strong Electromagnetic Field

The IC is not designed for using in the presence of strong electromagnetic field. Be sure to confirm that no malfunction is found when using the IC in a strong electromagnetic field.

Direct PWM Control

This series can control PWM by IN1, IN2 input directly from the microcomputer (up to100kHz).
Decay mode can be SLOW DECAY or FAST DECAY.
Below are examples of control sequence and current decay path.

SLOW DECAY (forward rotation)

Input			Output		State
PS	IN1	IN2	OUT1	OUT2	
H	H	L	H	L	ON
H	H	H	L	L	SLOW DECAY
H	H	L	H	L	ON
H	H	H	L	L	SLOW DECAY
H	H	L	H	L	ON

FAST DECAY (synchronous rectification, forward rotation)

Input			Output		State
PS	IN1	IN2	OUT1	OUT2	
H	H	L	H	L	ON
H	L	H	L	H	FAST DECAY
H	H	L	H	L	ON
H	L	H	L	H	FAST DECAY
H	H	L	H	L	ON

SLOW DECAY

FAST DECAY
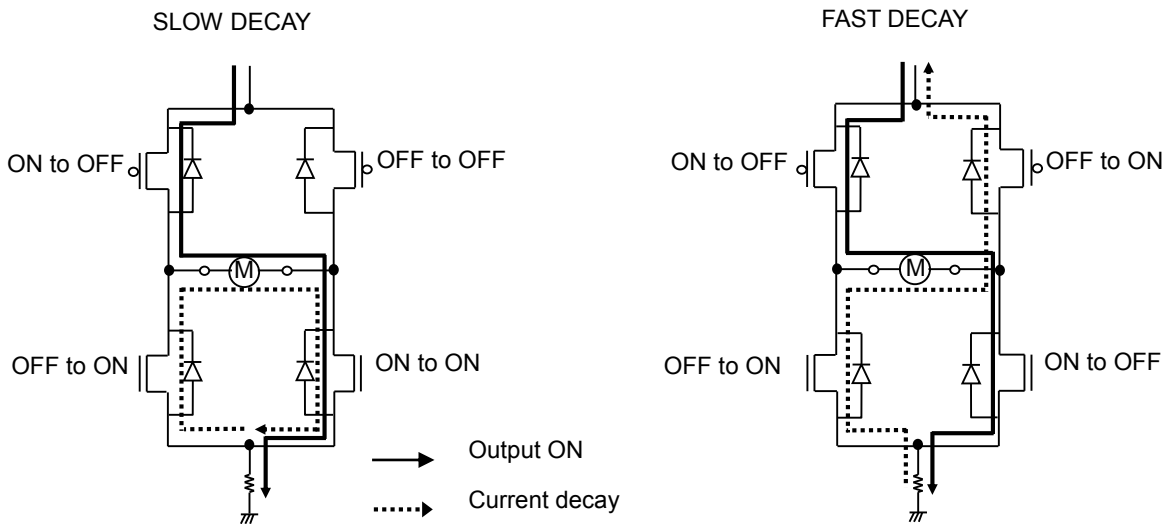
Figure 5. Route of Regenerative Current during Current Decay

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PWM Constant Current Control
This function can limit the peak current such as switching current in driving DC brush motor.

(1) Current Control Operation
The output current increases due to the output transistor turned on. When the voltage on the RNF pin, the output current is converted it due to connect the external resistance to RNF pin, reaches the voltage value set by the VREF input voltage, the current limit comparator engages and enters current decay mode. Thereafter the output turned on again after a period of time determined the CR pin. The process repeats itself constantly.

(2) Blank Time (Fixed in Internal Circuit)
In order to avoid misdetection of current detection comparator due to RNF spikes that occur when the output turns ON, the internal voltage between 0.4V and 0.8V is provided as minimum ON time (t_{ONMIN} 1.5µs Typ). During this time, the current detection is disabled after the output transistor is turned on. This allows for constant-current drive without the need for an external filter.

(3) Internal Timer (Fixed in Internal Circuit)
 Repeat charging and discharging between 0.4V to 0.9V internal voltage determined by IC internal circuit.
 When internal voltage is changed charge from discharge, the output is then ON from the current decay mode.
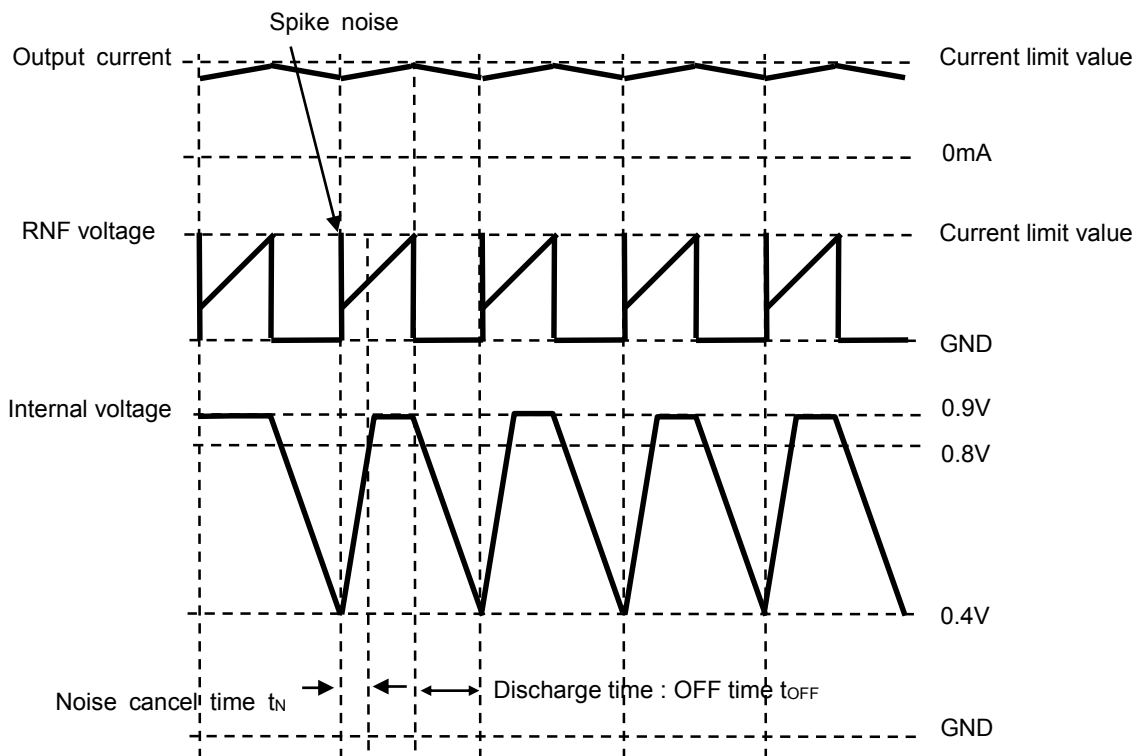

Figure 6. Timing Chart of Internal Voltage, RNF Voltage and Output Current

Power Dissipation

Confirm that the IC's chip temperature Tj is not over 150°C in consideration of the IC's power consumption (W), thermal resistance (°C/W) and ambient temperature (Ta). When Tj=150°C is exceeded, the functions as a semiconductor do not operate and problems such as parasitism and leaks occur. Constant use under these circumstances leads to deterioration and eventually destruction of the IC. Tjmax=150°C must be strictly obeyed under all circumstances.

(1) Thermal Calculation

The IC's consumed power can be estimated roughly with the power supply voltage (V_{CC}), circuit current (I_{CC}), output ON-Resistance (R_{ONH}, R_{ONL}) and motor output current value (I_{OUT}).

The calculation method during direct PWM drive, SLOW DECAY is shown here:

$$W_{VCC} = V_{CC} \times I_{CC} \qquad [W]$$

where:
- W_{VCC} is the consumed power of the V_{CC}.
- V_{CC} is the power supply voltage.
- I_{CC} is the circuit current.

$$W_{DMOS} = W_{ON} + W_{DECAY} \qquad [W]$$

$$W_{ON} = (R_{ONH} + R_{ONL}) \times I_{OUT}^2 \times \frac{on\_duty}{100} \qquad [W]$$

$$W_{DECAY} = (2 \times R_{ONL}) \times I_{OUT}^2 \times \frac{100 - on\_duty}{100} \qquad [W]$$

where:
- W_{DMOS} is the consumed power of the output DMOS.
- W_{ON} is the consumed power during output ON.
- W_{DECAY} is the consumed power during current decay.
- R_{ONH} is the upper P-channel DMOS ON-resistance.
- R_{ONL} is the lower N-channel DMOS ON-resistance.
- I_{OUT} is the motor output current value
- on_duty PWM on duty[%]

Model Number	Upper P-Channel DMOS ON-Resistance $R_{ONH}[\Omega]$ (Typ)	Lower N-Channel DMOS ON-Resistance $R_{ONL}[\Omega]$ (Typ)
BD63130AFM	0.32	0.23

$$W\_total = W_{VCC} + W_{DMOS} \qquad [W]$$

$$Tj = Ta + \theta ja \times W\_total \qquad [°C]$$

where:
- W_total is the consumed total power of IC.
- Tj is the junction temperature.
- Ta is the air temperature.
- θja is the thermal resistance value.

However, the thermal resistance value θja [°C/W] differs greatly depending on circuit board conditions. The calculated values above are only theoretical. For actual thermal design, perform sufficient thermal evaluation for the application board used, and create the thermal design with enough margin to not exceed Tjmax=150°C. Although unnecessary with normal use, if the IC is to be used under especially strict heat conditions, consider externally attaching a Schottky diode between the motor output pin and GND to abate heat from the IC.

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Power Dissipation – continued

(2) Temperature Monitoring

There is a way to directly measure the approximate chip temperature by using the TEST pin. However, temperature monitor using TEST pin is only for evaluation and experimenting, and must not be used in actual usage conditions. TEST pin has a protection diode to prevent electrostatic discharge. The temperature can be monitored using this protection diode.

(a) Measure the pin voltage when a current of I_{DIODE}=50µA flows from the TEST pin to the GND, without supplying VCC to the IC. This measurement is the V_F voltage inside the diode.

(b) Measure the temperature characteristics of this pin voltage. (V_F has a linear negative temperature factor against the temperature.) With the results of these temperature characteristics, chip temperature can be calibrated from the TEST pin voltage.

(c) Supply VCC, confirm the TEST pin voltage while running the motor, and the chip temperature can be approximated from the results of (b).
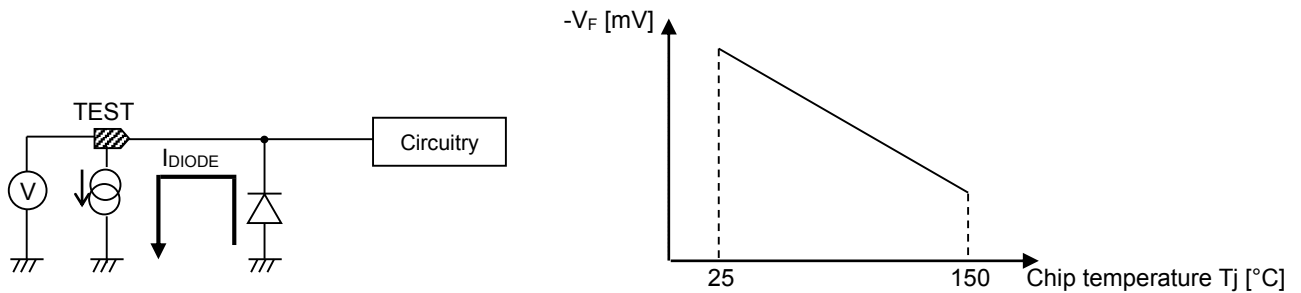
Figure 7. Model Diagram for Measuring Chip Temperature

Application Circuit Diagram
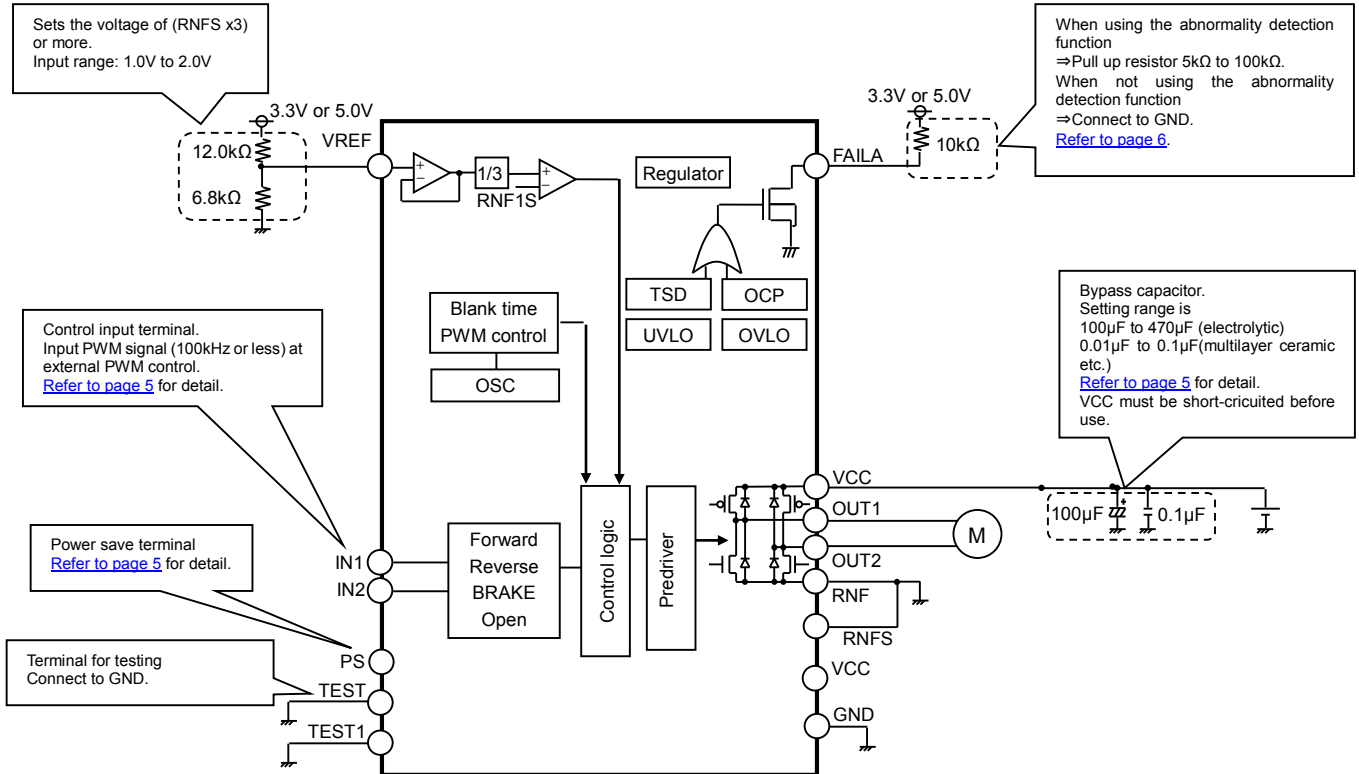### (1)Constant Voltage Control or External PWM Control

Sets the voltage of (RNFS x3) or more.
Input range: 1.0V to 2.0V

When using the abnormality detection function
⇒Pull up resistor 5kΩ to 100kΩ.
When not using the abnormality detection function
⇒Connect to GND.
Refer to page 6.

3.3V or 5.0V

12.0kΩ
6.8kΩ

VREF
1/3
RNF1S
Regulator
FAILA
10kΩ

3.3V or 5.0V

Control input terminal.
Input PWM signal (100kHz or less) at external PWM control.
Refer to page 5 for detail.

Blank time
PWM control
OSC

TSD   OCP
UVLO   OVLO

Bypass capacitor.
Setting range is
100μF to 470μF (electrolytic)
0.01μF to 0.1μF(multilayer ceramic etc.)
Refer to page 5 for detail.
VCC must be short-cricuited before use.

Power save terminal
Refer to page 5 for detail.

IN1
IN2

Forward
Reverse
BRAKE
Open

Control logic

Predriver

VCC
OUT1
OUT2
RNF
RNFS
VCC
GND

M

100μF   0.1μF

Terminal for testing
Connect to GND.

PS
TEST
TEST1

Figure 8. Constant Voltage Control or External PWM Control

(a) Input/ Output table

Input			Output		State
PS	IN1	IN2	OUT1	OUT2	
L	x	x	OPEN	OPEN	POWER SAVE (STANDBY)
H	L	L	OPEN	OPEN	STOP
H	H	L	H	L	FORWARD
H	L	H	L	H	REVERSE
H	H	H	L	L	BRAKE

x : H or L

(b) Example of external PWM control sequence
SLOW DECAY (forward rotation)

Input			Output		State
PS	IN1	IN2	OUT1	OUT2	
H	H	L	H	L	ON
H	H	H	L	L	SLOW DECAY
H	H	L	H	L	ON
H	H	H	L	L	SLOW DECAY
H	H	L	H	L	ON

FAST DECAY (forward rotation)

Input			Output		State
PS	IN1	IN2	OUT1	OUT2	
H	H	L	H	L	ON
H	L	H	L	H	FAST DECAY
H	H	L	H	L	ON
H	L	H	L	H	FAST DECAY
H	H	L	H	L	ON

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Application Circuit Diagram – continued

(2)PWM Constant Current Control

Sets the current limit value.
Input range: 0V to 2V
Refer to page 6 for detail.

When using the fault abnormality detection function
⇒Pull up resistor 5kΩ to 100kΩ.
When not using the fault abnormality detection function
⇒Connect to GND.
Refer to page 6.

Control logic input terminal.
Refer to page 5.

Power save terminal
Refer to page 5 for detail.

Terminal for testing
Connect to GND.

Bypass capacitor.
Setting range is
100µF to 470µF(electrolytic)
0.01µF to 0.1µF(multilayer ceramic etc.)
Refer to page 5 for detail.
VCC must be short-cricuited before use.

Current detection setting resistor
0.05Ω to 0.14Ω
Refer to page 5, 6 for detail.

Figure 9. PWM Constant Current Control

(a) Input/ Output table

Input			Output		State
PS	IN1	IN2	OUT1	OUT2	
L	x	x	OPEN	OPEN	POWER SAVE (STANDBY)
H	L	L	OPEN	OPEN	STOP
H	H	L	H	L	FORWARD
H	L	H	L	H	REVERSE
H	H	H	L	L	BRAKE

x : H or L

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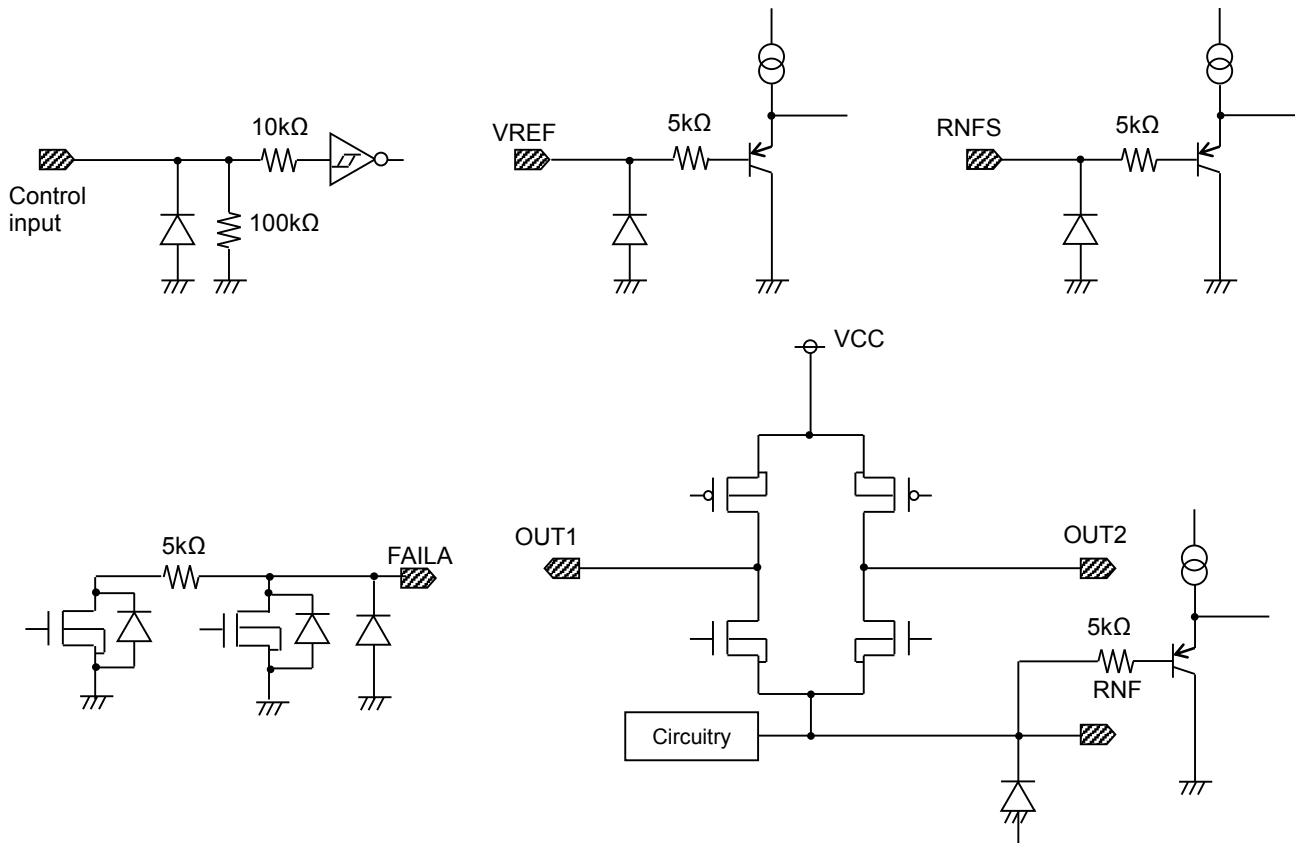
I/ O Equivalent Circuits

Figure 10. I/ O Equivalent Circuits

Operational Notes

1. **Reverse Connection of Power Supply**
   Connecting the power supply in reverse polarity can damage the IC. Take precautions against reverse polarity when connecting the power supply, such as mounting an external diode between the power supply and the IC's power supply pins.

2. **Power Supply Lines**
   Design the PCB layout pattern to provide low impedance supply lines. Furthermore, connect a capacitor to ground at all power supply pins. Consider the effect of temperature and aging on the capacitance value when using electrolytic capacitors.

3. **Ground Voltage**
   Ensure that no pins are at a voltage below that of the ground pin at any time, even during transient condition.

4. **Ground Wiring Pattern**
   When using both small-signal and large-current ground traces, the two ground traces should be routed separately but connected to a single ground at the reference point of the application board to avoid fluctuations in the small-signal ground caused by large currents. Also ensure that the ground traces of external components do not cause variations on the ground voltage. The ground lines must be as short and thick as possible to reduce line impedance.

5. **Recommended Operating Conditions**
   The function and operation of the IC are guaranteed within the range specified by the recommended operating conditions. The characteristic values are guaranteed only under the conditions of each item specified by the electrical characteristics.

6. **Inrush Current**
   When power is first supplied to the IC, it is possible that the internal logic may be unstable and inrush current may flow instantaneously due to the internal powering sequence and delays, especially if the IC has more than one power supply. Therefore, give special consideration to power coupling capacitance, power wiring, width of ground wiring, and routing of connections.

7. **Operation Under Strong Electromagnetic Field**
   Operating the IC in the presence of a strong electromagnetic field may cause the IC to malfunction.

8. **Testing on Application Boards**
   When testing the IC on an application board, connecting a capacitor directly to a low-impedance output pin may subject the IC to stress. Always discharge capacitors completely after each process or step. The IC's power supply should always be turned off completely before connecting or removing it from the test setup during the inspection process. To prevent damage from static discharge, ground the IC during assembly and use similar precautions during transport and storage.

9. **Inter-pin Short and Mounting Errors**
   Ensure that the direction and position are correct when mounting the IC on the PCB. Incorrect mounting may result in damaging the IC. Avoid nearby pins being shorted to each other especially to ground, power supply and output pin. Inter-pin shorts could be due to many reasons such as metal particles, water droplets (in very humid environment) and unintentional solder bridge deposited in between pins during assembly to name a few.

10. **Unused Input Pins**
    Input pins of an IC are often connected to the gate of a MOS transistor. The gate has extremely high impedance and extremely low capacitance. If left unconnected, the electric field from the outside can easily charge it. The small charge acquired in this way is enough to produce a significant effect on the conduction through the transistor and cause unexpected operation of the IC. So unless otherwise specified, unused input pins should be connected to the power supply or ground line.

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Operational Notes – continued

11. **Regarding the Input Pin of the IC**
This monolithic IC contains P+ isolation and P substrate layers between adjacent elements in order to keep them isolated. P-N junctions are formed at the intersection of the P layers with the N layers of other elements, creating a parasitic diode or transistor. For example (refer to figure below):

When GND > Pin A and GND > Pin B, the P-N junction operates as a parasitic diode.
When GND > Pin B, the P-N junction operates as a parasitic transistor.

Parasitic diodes inevitably occur in the structure of the IC. The operation of parasitic diodes can result in mutual interference among circuits, operational faults, or physical damage. Therefore, conditions that cause these diodes to operate, such as applying a voltage lower than the GND voltage to an input pin (and thus to the P substrate) should be avoided.
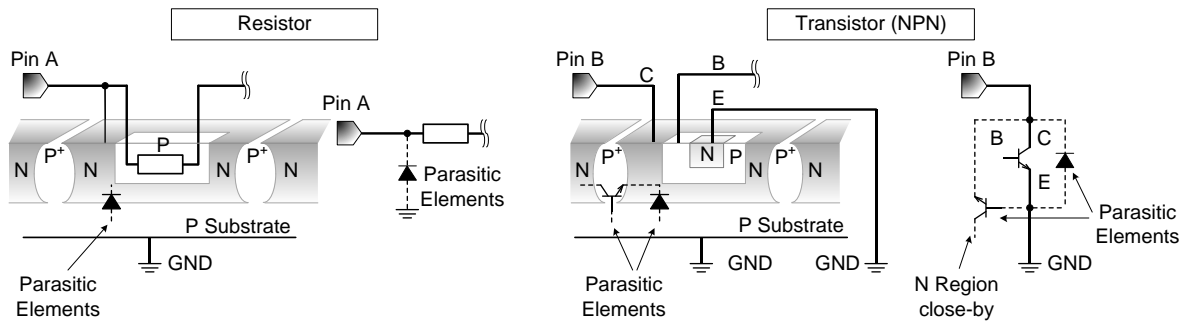

Figure 11. Example of monolithic IC structure

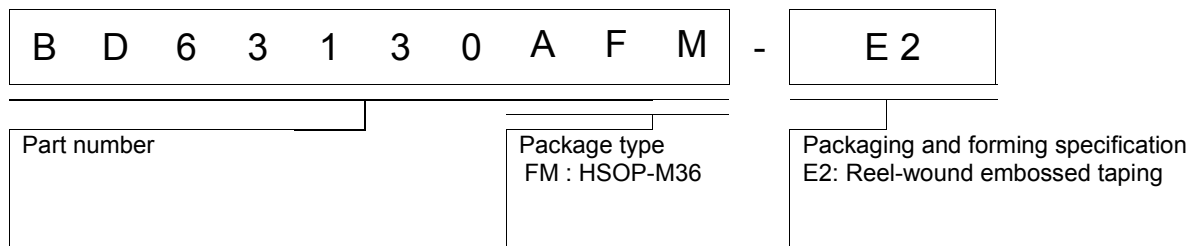12. **Thermal Shutdown Circuit(TSD)**
This IC has a built-in thermal shutdown circuit that prevents heat damage to the IC. Normal operation should always be within the IC's maximum junction temperature rating. If however the rating is exceeded for a continued period, the junction temperature (Tj) will rise which will activate the TSD circuit that will turn OFF power output pins. When the Tj falls below the TSD threshold, the circuits are automatically restored to normal operation.
Note that the TSD circuit operates in a situation that exceeds the absolute maximum ratings and therefore, under no circumstances, should the TSD circuit be used in a set design or for any purpose other than protecting the IC from heat damage.
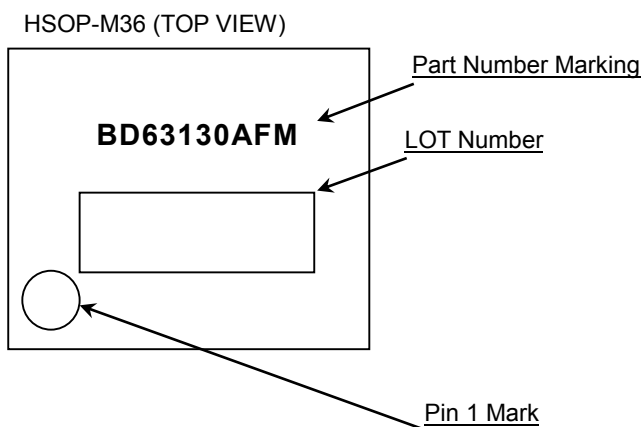
13. **Over Current Protection Circuit (OCP)**
This IC incorporates an integrated overcurrent protection circuit that is activated when the load is shorted. This protection circuit is effective in preventing damage due to sudden and unexpected incidents. However, the IC should not be used in applications characterized by continuous operation or transitioning of the protection circuit.
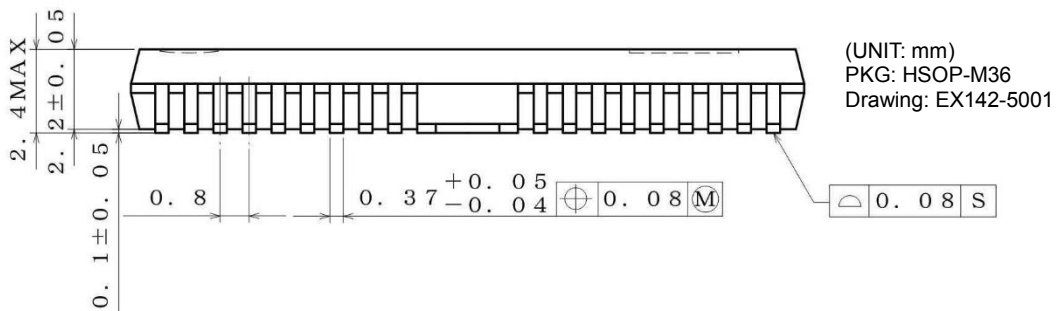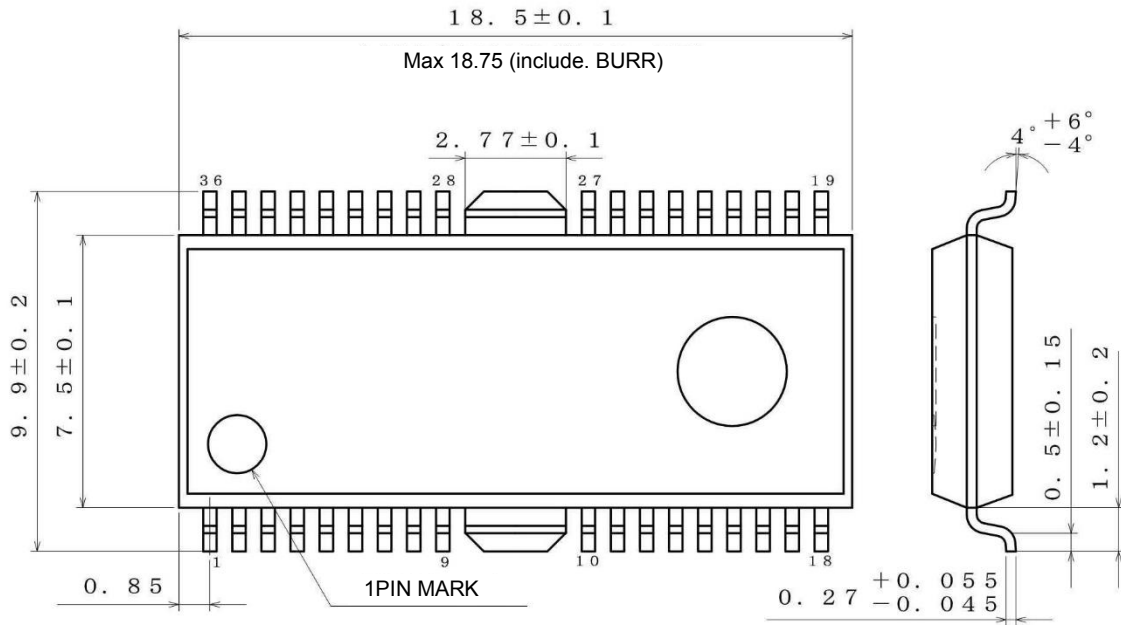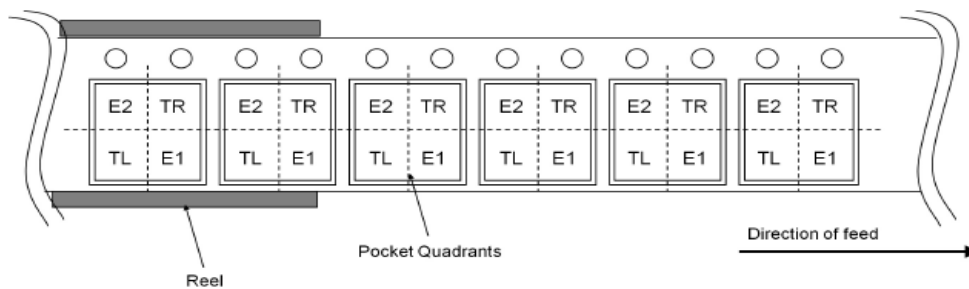
Ordering Information

B	D	6	3	1	3	0	A	F	M	-	E 2

Part number

Package type
FM : HSOP-M36

Packaging and forming specification
E2: Reel-wound embossed taping

Marking Diagram

HSOP-M36 (TOP VIEW)

BD63130AFM

Part Number Marking

LOT Number

Pin 1 Mark

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Physical Dimension and Packing Information

Package Name	HSOP-M36

18.5±0.1
Max 18.75 (include. BURR)

2.77±0.1

36   28   27   19

9.9±0.2
7.5±0.1

4° +6° −4°

0.5±0.15
1.2±0.2

1   9   10   18

0.85

1PIN MARK

0.27 +0.055 −0.045

(UNIT: mm)
PKG: HSOP-M36
Drawing: EX142-5001

2.4MAX
2.2±0.2
2.05
0.1±0.05

0.8

0.37 +0.05 −0.04   ⊕ 0.08 (M)

△ 0.08 S

<Tape and Reel information>

Tape	Embossed carrier tape (with dry pack)
Quantity	1500pcs
Direction of feed	E2
	The direction is the 1pin of product is at the upper left when you hold reel on the left hand and you pull out the tape on the right hand

E2	TR
TL	E1

Reel

Pocket Quadrants

Direction of feed

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Revision History

Date	Revision	Changes
26.Dec.2017	001	New Release

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(Note1) Medical Equipment Classification of the Specific Applications

JAPAN	USA	EU	CHINA
CLASSⅢ	CLASSⅢ	CLASSⅡb	CLASSⅢ
CLASSⅣ		CLASSⅢ	

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    [c] Use of our Products in places where the Products are exposed to sea wind or corrosive gases, including Cl_2, H_2S, NH_3, SO_2, and NO_2
    [d] Use of our Products in places where the Products are exposed to static electricity or electromagnetic waves
    [e] Use of our Products in proximity to heat-producing components, plastic cords, or other flammable items
    [f] Sealing or coating our Products with resin or other coating materials
    [g] Use of our Products without cleaning residue of flux (even if you use no-clean type fluxes, cleaning residue of flux is recommended); or Washing our Products by using water or water-soluble cleaning agents for cleaning residue after soldering
    [h] Use of the Products in places subject to dew condensation

4. The Products are not subject to radiation-proof design.

5. Please verify and confirm characteristics of the final or mounted products in using the Products.

6. In particular, if a transient load (a large amount of load applied in a short period of time, such as pulse. is applied, confirmation of performance characteristics after on-board mounting is strongly recommended. Avoid applying power exceeding normal rated power; exceeding the power rating under steady-state loading condition may negatively affect product performance and reliability.

7. De-rate Power Dissipation depending on ambient temperature. When used in sealed area, confirm that it is the use in the range that does not exceed the maximum junction temperature.

8. Confirm that operation temperature is within the specified range described in the product specification.

9. ROHM shall not be in any way responsible or liable for failure induced under deviant condition from what is defined in this document.

Precaution for Mounting / Circuit board design

1. When a highly active halogenous (chlorine, bromine, etc.) flux is used, the residue of flux may negatively affect product performance and reliability.

2. In principle, the reflow soldering method must be used on a surface-mount products, the flow soldering method must be used on a through hole mount products. If the flow soldering method is preferred on a surface-mount products, please consult with the ROHM representative in advance.

For details, please refer to ROHM Mounting specification

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1. Product performance and soldered connections may deteriorate if the Products are stored in the places where:
   [a] the Products are exposed to sea winds or corrosive gases, including Cl2, H2S, NH3, SO2, and NO2
   [b] the temperature or humidity exceeds those recommended by ROHM
   [c] the Products are exposed to direct sunshine or condensation
   [d] the Products are exposed to high Electrostatic

2. Even under ROHM recommended storage condition, solderability of products out of recommended storage time period may be degraded. It is strongly recommended to confirm solderability before using Products of which storage time is exceeding the recommended storage time period.

3. Store / transport cartons in the correct direction, which is indicated on a carton with a symbol. Otherwise bent leads may occur due to excessive stress applied when dropping of a carton.

4. Use Products within the specified time after opening a humidity barrier bag. Baking is required before using Products of which storage time is exceeding the recommended storage time period.

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