### **DATASHEET**

## **General Description**

The 9DMU0431 is a member of IDT's SOC-Friendly 1.5V Ultra-Low-Power (ULP) PCIe Gen1-2-3 family. Each of the 4 outputs has its own dedicated OE# pin for optimal system control and power management. The part provides asynchronous and glitch-free switching modes.

## **Recommended Application**

2:4 PCIe Gen1-2-3 clock multiplexer

## **Output Features**

• 4 - Low-Power (LP) HCSL DIF pair

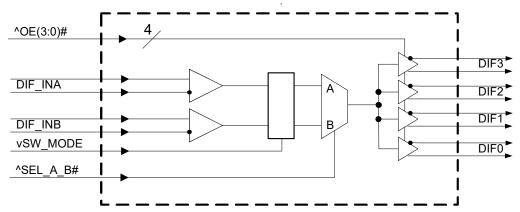
## **Key Specifications**

- DIF additive cycle-to-cycle jitter <5ps
- DIF phase jitter is PCIe Gen1-2-3 compliant
- Additive phase jitter @ 125MHz: 535fs rms typical (12kHz to 20MHz)
- DIF output-to-output skew <50ps

### Features/Benefits

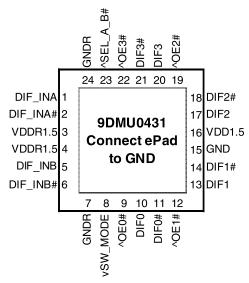
- LP-HCSL outputs; save 8 resistors compared to standard HCSL outputs
- 1.5V operation; 31mW typical power consumption
- Selectable asynchronous or glitch-free switching; allows the mux to be selected at power up even if both inputs are not running, then transition to glitch-free switching mode
- Spread Spectrum Compatible; supports EMI reduction
- OE# pins; support DIF power management
- HCSL differential inputs; can be driven by common clock sources
- 1MHz to 167MHz operating frequency
- Space saving 24-pin 4x4mm VFQFPN; minimal board space

# **Block Diagram**



1

# **Pin Configuration**



### 24 VFQFPN, 4x4 mm, 0.5mm pitch

^ prefix indicates internal 120KOhm pull up resistor v prefix indicates internal 120KOhm pull down resistor

### **Power Management Table**

| OEx# Pin  | DIF IN   | DIFx     |           |  |
|-----------|----------|----------|-----------|--|
| OLX#1 III | Dii _iiv | True O/P | Comp. O/P |  |
| 0         | Running  | Running  | Running   |  |
| 1         | Running  | Low      | Low       |  |

### **Power Connections**

| Pin N | umber | Description             |  |  |  |
|-------|-------|-------------------------|--|--|--|
| VDD   | GND   | Description             |  |  |  |
| 3     | 24    | Input A receiver analog |  |  |  |
| 4     | 7     | Input B receiver analog |  |  |  |
| 16    | 15    | DIF outputs             |  |  |  |

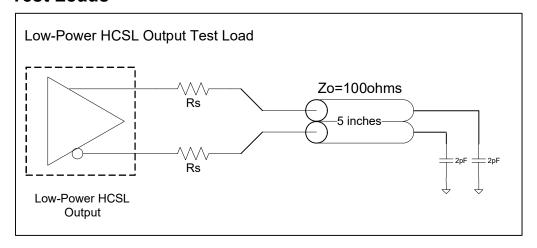
# **Pin Descriptions**

| Pin# | Pin Name | Туре | Pin Description  |
|------|----------|------|--|
| 1    | DIF_INA  | IN   | HCSL Differential True input   |
| 2    | DIF_INA# | IN   | HCSL Differential Complement Input   |
| 3    | VDDR1.5  | PWR  | 1.5V power for differential input clock (receiver). This VDD should be treated as an Analog power rail and filtered appropriately.   |
| 4    | VDDR1.5  | PWR  | 1.5V power for differential input clock (receiver). This VDD should be treated as an Analog power rail and filtered appropriately.   |
| 5    | DIF_INB  | IN   | HCSL Differential True input   |
| 6    | DIF_INB# | IN   | HCSL Differential Complement Input   |
| 7    | GNDR     | GND  | Analog Ground pin for the differential input (receiver)  |
| 8    | vSW_MODE | IN   | Switch Mode. This pin selects either asynchronous or glitch-free switching of the mux. Use asynchronous mode if 0 or 1 of the input clocks is running. Use glitch-free mode if both input clocks are running. This pin has an internal pull down resistor of ~120kohms.  0 = asynchronous mode  1 = glitch-free mode |
| 9    | ^OE0#    | IN   | Active low input for enabling DIF pair 0. This pin has an internal pull-up resistor.  1 =disable outputs, 0 = enable outputs   |
| 10   | DIF0     | OUT  | Differential true clock output   |
| 11   | DIF0#    | OUT  | Differential Complementary clock output  |
| 12   | ^OE1#    | IN   | Active low input for enabling DIF pair 1. This pin has an internal pull-up resistor.  1 =disable outputs, 0 = enable outputs   |
| 13   | DIF1     | OUT  | Differential true clock output   |
| 14   | DIF1#    | OUT  | Differential Complementary clock output  |
| 15   | GND      | GND  | Ground pin.  |

# Pin Descriptions (cont.)

| Pin# | Pin Name  | Туре | Pin Description  |
|------|-----------|------|--|
| 16   | VDD1.5    | PWR  | Power supply, nominally 1.5V   |
| 17   | DIF2      | OUT  | Differential true clock output   |
| 18   | DIF2#     | OUT  | Differential Complementary clock output  |
| 19   | ^OE2#     | IN   | Active low input for enabling DIF pair 2. This pin has an internal pull-up resistor.                 |
| 19   | NOE2#     | IIN  | 1 =disable outputs, 0 = enable outputs   |
| 20   | DIF3      | OUT  | Differential true clock output   |
| 21   | DIF3#     | OUT  | Differential Complementary clock output  |
| 22   | ^OE3#     | IN   | Active low input for enabling DIF pair 3. This pin has an internal pull-up resistor.                 |
|      | 7-OE3#    | IIN  | 1 =disable outputs, 0 = enable outputs   |
|      |           |      | Input to select differential input clock A or differential input clock B. This input has an internal |
| 23   | ^SEL_A_B# | IN   | pull-up resistor.  |
|      |           |      | 0 = Input B selected, 1 = Input A selected.  |
| 24   | GNDR      | GND  | Analog Ground pin for the differential input (receiver)  |
| 25   | EPAD      | GND  | Connect to Ground.   |

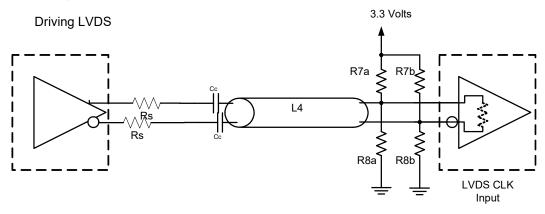
## **Test Loads**



### **Alternate Differential Output Terminations**

| Rs | Zo  | Units   |
|----|-----|---------|
| 33 | 100 | Ohms    |
| 27 | 85  | Offilis |

# **Driving LVDS**



### **Driving LVDS inputs**

|           | ,                              | Value            |      |  |  |  |  |
|-----------|--------------------------------|------------------|------|--|--|--|--|
|           | Receiver has Receiver does not |                  |      |  |  |  |  |
| Component | termination                    | have termination | Note |  |  |  |  |
| R7a, R7b  | 10K ohm                        | 140 ohm          |      |  |  |  |  |
| R8a, R8b  | 5.6K ohm                       | 75 ohm           |      |  |  |  |  |
| Cc        | 0.1 uF                         | 0.1 uF           |      |  |  |  |  |
| Vcm       | 1.2 volts                      | 1.2 volts        |      |  |  |  |  |

# **Electrical Characteristics-Absolute Maximum Ratings**

| PARAMETER                 | SYMBOL      | CONDITIONS                | MIN  | TYP | MAX                  | UNITS | NOTES |
|---------------------------|-------------|---------------------------|------|-----|----------------------|-------|-------|
| Supply Voltage            | VDDx        |                           | -0.5 |     | 2                    | V     | 1,2   |
| Input Voltage             | $V_{IN}$    |                           | -0.5 |     | V <sub>DD</sub> +0.5 | V     | 1,3   |
| Input High Voltage, SMBus | $V_{IHSMB}$ | SMBus clock and data pins |      |     | 3.3                  | V     | 1     |
| Storage Temperature       | Ts          |                           | -65  |     | 150                  | °C    | 1     |
| Junction Temperature      | Tj          |                           |      |     | 125                  | °C    | 1     |
| Input ESD protection      | ESD prot    | Human Body Model          | 2000 |     |                      | V     | 1     |

<sup>&</sup>lt;sup>1</sup>Guaranteed by design and characterization, not 100% tested in production.

# Electrical Characteristics-Input/Supply/Common Parameters-Normal Operating Conditions

TA = T<sub>AMB.</sub> Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

|                        | peration conditions, see rest Loads for Loading Con  |   |   |   |   |   |
|------------------------|--|---|---|---|---|---|
| SYMBOL                 | CONDITIONS   | MIN   | TYP   | MAX   | UNITS   | NOTES   |
| VDDx                   | Supply voltage for core and analog   | 1.425   | 1.5   | 1.575   | ٧   |   |
| $T_AMB$                | Industrial range   | -40   | 25  | 85  | ô   | 1   |
| $V_{IH}$               | Single-ended inputs, except SMBus  | 0.75 V <sub>DD</sub>  |   | $V_{DD} + 0.3$  | ٧   |   |
| $V_{IL}$               | Single-ended inputs, except SMBus  | -0.3  |   | 0.25 V <sub>DD</sub>  | ٧   |   |
| I <sub>IN</sub>        | Single-ended inputs, $V_{IN} = GND$ , $V_{IN} = VDD$   | -5  |   | 5   | uA  |   |
| I <sub>INP</sub>       | Single-ended inputs $V_{IN} = 0 \text{ V}$ ; Inputs with internal pull-up resistors $V_{IN} = \text{VDD}$ ; Inputs with internal pull-down resistors | -200  |   | 200   | uA  |   |
| $F_{in}$               |  | 1   |   | 167   | MHz   | 2   |
| $L_{pin}$              |  |   |   | 7   | nΗ  | 1   |
| $C_{IN}$               | Logic Inputs, except DIF_IN  | 1.5   |   | 5   | рF  | 1   |
| C <sub>INDIF_IN</sub>  | DIF_IN differential clock inputs   | 1.5   |   | 2.7   | рF  | 1,4   |
| C <sub>OUT</sub>       | Output pin capacitance   |   |   | 6   | рF  | 1   |
| T <sub>STAB</sub>      | From V <sub>DD</sub> Power-Up and after input clock stabilization or de-assertion of PD# to 1st clock  |   |   | 1   | ms  | 1,2   |
| f <sub>MODINPCle</sub> | Allowable Frequency for PCIe Applications (Triangular Modulation)  | 30  |   | 33  | kHz   |   |
| f <sub>MODIN</sub>     | Allowable Frequency for non-PCIe Applications<br>(Triangular Modulation)   | 0   |   | 66  | kHz   |   |
| t <sub>LATOE#</sub>    | DIF start after OE# assertion DIF stop after OE# deassertion   | 1   |   | 3   | clocks  | 1,3   |
| t <sub>F</sub>         | Fall time of single-ended control inputs   |   |   | 5   | ns  | 2   |
| t <sub>R</sub>         | Rise time of single-ended control inputs   |   |   | 5   | ns  | 2   |
|                        | SYMBOL  VDDX  TAMB  VIH  VIL  IIN  IINP  Fin  CIN  CINDIF_IN  COUT  TSTAB  fMODINPCIe  fMODIN  tLATOE#  tF   | SYMBOL  VDDx  Supply voltage for core and analog  T_AMB  Industrial range  V_IH  Single-ended inputs, except SMBus  V_IL  Single-ended inputs, V_IN = GND, V_IN = VDD  Single-ended inputs  V_IN = 0 V; Inputs with internal pull-up resistors  V_IN = VDD; Inputs with internal pull-down resistors  F_IN  L_DIN  C_INDIF_IN  C_INDIF_IN  DIF_IN differential clock inputs  C_OUT  Output pin capacitance  T_STAB  From V_DD Power-Up and after input clock stabilization or de-assertion of PD# to 1st clock  Allowable Frequency for PCIe Applications  (Triangular Modulation)  Allowable Frequency for non-PCIe Applications  (Triangular Modulation)  DIF start after OE# assertion  DIF stop after OE# deassertion  Fall time of single-ended control inputs | $\begin{array}{c ccccccccccccccccccccccccccccccccccc$ | SYMBOL       CONDITIONS       MIN       TYP         VDDx       Supply voltage for core and analog       1.425       1.5         TAMB       Industrial range       -40       25         VIH       Single-ended inputs, except SMBus       0.75 VDD         VIL       Single-ended inputs, except SMBus       -0.3         IIN       Single-ended inputs, VIN = GND, VIN = VDD       -5         Single-ended inputs       -200         VIN = VDD; Inputs with internal pull-up resistors       -200         VIN = VDD; Inputs with internal pull-down resistors       -200         Fin       1         Lpin       1         CIN       Logic Inputs, except DIF_IN       1.5         COUT       Output pin capacitance       1.5         COUT       Output pin capacitance | SYMBOL         CONDITIONS         MIN         TYP         MAX           VDDx         Supply voltage for core and analog         1.425         1.5         1.575           T <sub>AMB</sub> Industrial range         -40         25         85           V <sub>IH</sub> Single-ended inputs, except SMBus         0.75 V <sub>DD</sub> V <sub>DD</sub> + 0.3           V <sub>IL</sub> Single-ended inputs, except SMBus         -0.3         0.25 V <sub>DD</sub> I <sub>IN</sub> Single-ended inputs, except SMBus         -0.3         0.25 V <sub>DD</sub> I <sub>IN</sub> Single-ended inputs, except SMBus         -0.3         0.25 V <sub>DD</sub> I <sub>IN</sub> Single-ended inputs, except SMBus         -0.3         0.25 V <sub>DD</sub> I <sub>IN</sub> Single-ended inputs, except SMBus         -0.3         0.25 V <sub>DD</sub> Single-ended inputs, except DIF_IN         -5         5           I <sub>INP</sub> V <sub>I</sub> P oV; Inputs with internal pull-up resistors v <sub>I</sub> P over the sistors v <sub>I</sub> P over t | SYMBOL         CONDITIONS         MIN         TYP         MAX         UNITS           VDDx         Supply voltage for core and analog         1.425         1.5         1.575         V           TAMB         Industrial range         -40         25         85         °C           V <sub>IH</sub> Single-ended inputs, except SMBus         0.75 V <sub>DD</sub> V <sub>DD</sub> + 0.3         V           V <sub>IL</sub> Single-ended inputs, except SMBus         -0.3         0.25 V <sub>DD</sub> V           I <sub>IN</sub> Single-ended inputs, V <sub>IN</sub> = GND, V <sub>IN</sub> = VDD         -5         5         uA           Single-ended inputs, V <sub>IN</sub> = GND, V <sub>IN</sub> = VDD         -5         5         uA           Single-ended inputs, except DIF_IN         -5         5         uA           V <sub>IN</sub> = 0 V; Inputs with internal pull-up resistors V <sub>IN</sub> = VDD; Inputs with internal pull-down resistors         -200         200         uA           Fin         1         167         MHz         MHz           L <sub>pin</sub> 7         nH         T         nH         T         nH           C <sub>INDIF-IN</sub> DIF_IN differential clock inputs         1.5         2.7         pF           C <sub>OUT</sub> Output pin capacitance         6         pF |

<sup>&</sup>lt;sup>1</sup>Guaranteed by design and characterization, not 100% tested in production.

<sup>&</sup>lt;sup>2</sup> Operation under these conditions is neither implied nor guaranteed.

<sup>&</sup>lt;sup>3</sup> Not to exceed 2.0V.

<sup>&</sup>lt;sup>2</sup>Control input must be monotonic from 20% to 80% of input swing.

<sup>&</sup>lt;sup>3</sup>Time from deassertion until outputs are >200 mV

<sup>&</sup>lt;sup>4</sup> DIF\_IN input

## **Electrical Characteristics-Clock Input Parameters**

TA = T<sub>AMB</sub>. Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

| 71115                                 | •                  |   |                       |     |      |       |       |
|---------------------------------------|--------------------|---|-----------------------|-----|------|-------|-------|
| PARAMETER                             | SYMBOL             | CONDITIONS  | MIN                   | TYP | MAX  | UNITS | NOTES |
| Input High Voltage - DIF_IN           | V <sub>IHDIF</sub> | Differential inputs (single-ended measurement)                | 300                   | 750 | 1150 | mV    | 1     |
| Input Low Voltage - DIF_IN            | V <sub>ILDIF</sub> | Differential inputs (single-ended measurement)                | V <sub>SS</sub> - 300 | 0   | 300  | mV    | 1     |
| Input Common Mode<br>Voltage - DIF_IN | V <sub>COM</sub>   | Common Mode Input Voltage                                     | 200                   |     | 725  | mV    | 1     |
| Input Amplitude - DIF_IN              | V <sub>SWING</sub> | Peak to Peak value (V <sub>IHDIF</sub> - V <sub>ILDIF</sub> ) | 300                   |     | 1450 | mV    | 1     |
| Input Slew Rate - DIF_IN              | dv/dt              | Measured differentially                                       | 0.35                  |     | 8    | V/ns  | 1,2   |
| Input Leakage Current                 | I <sub>IN</sub>    | $V_{IN} = V_{DD}$ , $V_{IN} = GND$                            | -5                    |     | 5    | uA    |       |
| Input Duty Cycle                      | d <sub>tin</sub>   | Measurement from differential wavefrom                        | 45                    | 50  | 55   | %     | 1     |
| Input Jitter - Cycle to Cycle         | $J_{DIFIn}$        | Differential Measurement                                      | 0                     | ·   | 150  | ps    | 1     |

<sup>&</sup>lt;sup>1</sup> Guaranteed by design and characterization, not 100% tested in production.

## **Electrical Characteristics-DIF Low-Power HCSL Outputs**

TA = T<sub>AMB</sub>. Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

| 7. TAIVID, Cappily Totages per Herman Sporation Conditions, Cost Total Educating Conditions |            |  |      |      |      |         |       |  |  |
|---|------------|--|------|------|------|---------|-------|--|--|
| PARAMETER   | SYMBOL     | CONDITIONS   | MIN  | TYP  | MAX  | UNITS   | NOTES |  |  |
| Slew rate   | dV/dt      | Scope averaging on, fast setting                       | 1.2  | 2.5  | 4.2  | V/ns    | 1,2,3 |  |  |
| Slew rate matching  | ∆dV/dt     | Slew rate matching, Scope averaging on                 |      | 10   | 20   | %       | 1,2,4 |  |  |
| Voltage High  | $V_{HIGH}$ | Statistical measurement on single-ended signal         | 550  | 761  | 850  | mV      |       |  |  |
| Voltage Low   | $V_{LOW}$  | using oscilloscope math function. (Scope averaging on) |      | 33   | 150  | ] ''' [ |       |  |  |
| Max Voltage   | Vmax       | Measurement on single ended signal using               |      | 800  | 1150 | mV      |       |  |  |
| Min Voltage   | Vmin       | absolute value. (Scope averaging off)                  | -300 | -1   |      | IIIV    |       |  |  |
| Vswing  | Vswing     | Scope averaging off                                    | 300  | 1457 |      | mV      | 1,2   |  |  |
| Crossing Voltage (abs)  | Vcross_abs | Scope averaging off                                    | 250  | 404  | 550  | mV      | 1,5   |  |  |
| Crossing Voltage (var)  | Δ-Vcross   | Scope averaging off                                    |      | 15   | 140  | mV      | 1,6   |  |  |

<sup>&</sup>lt;sup>1</sup>Guaranteed by design and characterization, not 100% tested in production.

# **Electrical Characteristics-Current Consumption**

TA = T<sub>AMB</sub>. Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

| PARAMETER                | SYMBOL            | CONDITIONS                      | MIN | TYP | MAX | UNITS | NOTES |
|--------------------------|-------------------|---------------------------------|-----|-----|-----|-------|-------|
| Operating Supply Current | I <sub>DD</sub>   | VDD, All outputs active @100MHz |     | 19  | 27  | mA    | 1     |
| Powerdown Current        | I <sub>DDPD</sub> | VDD, all outputs disabled       |     | 1.4 | 2.5 | mA    | 1, 2  |

<sup>&</sup>lt;sup>1</sup> Guaranteed by design and characterization, not 100% tested in production.

<sup>&</sup>lt;sup>2</sup> Slew rate measured through +/-75mV window centered around differential zero

<sup>&</sup>lt;sup>2</sup> Measured from differential waveform

<sup>&</sup>lt;sup>3</sup> Slew rate is measured through the Vswing voltage range centered around differential 0V. This results in a +/-150mV window around differential 0V.

<sup>&</sup>lt;sup>4</sup> Matching applies to rising edge rate for Clock and falling edge rate for Clock#. It is measured using a +/-75mV window centered on the average cross point where Clock rising meets Clock# falling. The median cross point is used to calculate the voltage thresholds the oscilloscope is to use for the edge rate calculations.

<sup>&</sup>lt;sup>5</sup> Vcross is defined as voltage where Clock = Clock# measured on a component test board and only applies to the differential rising edge (i.e. Clock rising and Clock# falling).

<sup>&</sup>lt;sup>6</sup> The total variation of all Vcross measurements in any particular system. Note that this is a subset of Vcross\_min/max (Vcross absolute) allowed. The intent is to limit Vcross induced modulation by setting Δ-Vcross to be smaller than Vcross absolute.

<sup>&</sup>lt;sup>2</sup> Input clock stopped.

# Electrical Characteristics-Output Duty Cycle, Jitter, Skew and PLL Characteristics

TA = T<sub>AMB</sub>. Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

| PARAMETER              | SYMBOL                | CONDITIONS                                   | MIN  | TYP   | MAX  | UNITS | NOTES |
|------------------------|-----------------------|--|------|-------|------|-------|-------|
| Duty Cycle Distortion  | t <sub>DCD</sub>      | Measured differentially, Bypass Mode @100MHz | -1   | -0.05 | 1    | %     | 1,3   |
| Skew, Input to Output  | t <sub>pdBYP</sub>    | Bypass Mode, $V_T = 50\%$                    | 2046 | 2864  | 4010 | ps    | 1     |
| Skew, Output to Output | t <sub>sk3</sub>      | V <sub>T</sub> = 50%                         |      | 19    | 50   | ps    | 1,4   |
| Jitter, Cycle to cycle | t <sub>jcyc-cyc</sub> | Additive Jitter in Bypass Mode               |      | 0.1   | 5    | ps    | 1,2   |

<sup>&</sup>lt;sup>1</sup> Guaranteed by design and characterization, not 100% tested in production.

### **Electrical Characteristics-Phase Jitter Parameters**

TA = T<sub>AMB.</sub> Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

|                                       |                        |   |     |       |     | INDUSTRY |             |               |
|---------------------------------------|------------------------|---|-----|-------|-----|----------|-------------|---------------|
| PARAMETER                             | SYMBOL                 | CONDITIONS  | MIN | TYP   | MAX | LIMIT    | UNITS       | Notes         |
|                                       | t <sub>jphPCleG1</sub> | PCIe Gen 1  |     | 1.3   | 5   | N/A      | ps (p-p)    | 1,2,3,5       |
|                                       | t <sub>jphPCleG2</sub> | PCIe Gen 2 Lo Band<br>10kHz < f < 1.5MHz  |     | 0.1   | 0.5 | N/A      | ps<br>(rms) | 1,2,3,4,<br>5 |
|                                       |                        | PCIe Gen 2 High Band<br>1.5MHz < f < Nyquist (50MHz)                                  |     | 0.1   | 0.6 | N/A      | ps<br>(rms) | 1,2,3,4       |
| Additive Phase Jitter,<br>Bypass Mode | t <sub>jphPCleG3</sub> | PCIe Gen 3<br>(PLL BW of 2-4 or 2-5MHz, CDR = 10MHz)                                  |     | 0.170 | 0.3 | N/A      | ps<br>(rms) | 1,2,3,4       |
|                                       | t <sub>jph125M0</sub>  | 125MHz, 1.5MHz to 10MHz, -20dB/decade rollover < 1.5MHz, -40db/decade rolloff > 10MHz |     | 365   | 380 | N/A      | fs<br>(rms) | 1,6           |
|                                       | t <sub>jph125M1</sub>  | 125MHz, 12KHz to 20MHz, -20dB/decade rollover < 12kHz, -40db/decade rolloff > 20MHz   |     | 535   | 550 | N/A      | fs<br>(rms) | 1,6           |

<sup>&</sup>lt;sup>1</sup>Guaranteed by design and characterization, not 100% tested in production.

asured from differential waveform

<sup>&</sup>lt;sup>4</sup> All outputs at default slew rate

<sup>&</sup>lt;sup>5</sup> The MIN/TYP/MAX values of each BW setting track each other, i.e., Low BW MAX will never occur with Hi BW MIN.

<sup>&</sup>lt;sup>2</sup> See http://www.pcisig.com for complete specs

<sup>&</sup>lt;sup>3</sup> Sample size of at least 100K cycles. This figures extrapolates to 108ps pk-pk @ 1M cycles for a BER of 1-12.

<sup>&</sup>lt;sup>4</sup> For RMS figures, additive jitter is calculated by solving the following equation: Additive jitter = SQRT[(total jitter)^2 - (input jitter)^2]

<sup>&</sup>lt;sup>5</sup> Driven by 9FGU0831 or equivalent

<sup>&</sup>lt;sup>6</sup> Rohde&Schartz SMA100

# **Marking Diagrams**



### Notes:

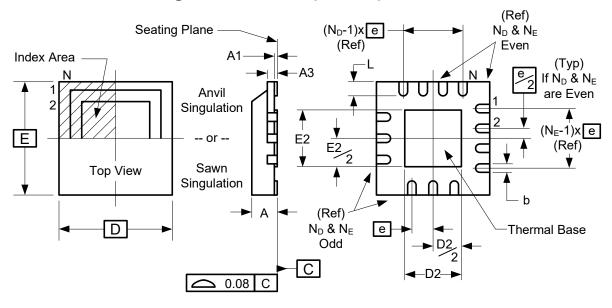
- 1. "LOT" denotes the lot number.
- 2. "YYWW" is the last two digits of the year and week that the part was assembled.
- 3. Line 2: truncated part number
- 4. "I" denotes industrial temperature grade.

## **Thermal Characteristics**

| PARAMETER          | SYMBOL         | CONDITIONS                      | PKG   | TYP<br>VALUE | UNITS | NOTES |
|--------------------|----------------|---------------------------------|-------|--------------|-------|-------|
| Thermal Resistance | $\theta_{JC}$  | Junction to Case                | NLG24 | 42           | °C/W  | 1     |
|                    | $\theta_{Jb}$  | Junction to Base                |       | 2.4          | °C/W  | 1     |
|                    | $\theta_{JA0}$ | Junction to Air, still air      |       | 39           | °C/W  | 1     |
|                    | $\theta_{JA1}$ | Junction to Air, 1 m/s air flow |       | 33           | °C/W  | 1     |
|                    | $\theta_{JA3}$ | Junction to Air, 3 m/s air flow |       | 28           | °C/W  | 1     |
|                    | $\theta_{JA5}$ | Junction to Air, 5 m/s air flow |       | 27           | °C/W  | 1     |

<sup>&</sup>lt;sup>1</sup>ePad soldered to board

# Package Outline and Package Dimensions (NLG24)



|                | Millimeters    |      |  |  |
|----------------|----------------|------|--|--|
| Symbol         | Min            | Max  |  |  |
| Α              | 0.80           | 1.00 |  |  |
| A1             | 0              | 0.05 |  |  |
| A3             | 0.25 Reference |      |  |  |
| b              | 0.18           | 0.30 |  |  |
| е              | 0.50 BASIC     |      |  |  |
| D x E BASIC    | 4.00 x 4.00    |      |  |  |
| D2 MIN./MAX.   | 2.3            | 2.55 |  |  |
| E2 MIN./MAX.   | 2.3            | 2.55 |  |  |
| L MIN./MAX.    | 0.30           | 0.50 |  |  |
| N              | 24             |      |  |  |
| $N_D$          | 6              |      |  |  |
| N <sub>F</sub> | 6              |      |  |  |

# **Ordering Information**

| Part / Order Number | Shipping Packaging | Package       | Temperature   |
|---------------------|--------------------|---------------|---------------|
| 9DMU0431AKILF       | Tubes              | 24-pin VFQFPN | -40 to +85° C |
| 9DMU0431AKILFT      | Tape and Reel      | 24-pin VFQFPN | -40 to +85° C |

<sup>&</sup>quot;LF" to the suffix denotes Pb-Free configuration, RoHS compliant.

<sup>&</sup>quot;A" is the device revision designator (will not correlate with the datasheet revision).

# **Revision History**

| Rev. | Initiator | Issue Date | Description   | Page # |
|------|-----------|------------|---|--------|
| Α    | RDW       | 9/24/2014  | Updated additive phase jitter and General Description     Move to final | 1,7    |

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### **Corporate Headquarters**

TOYOSU FORESIA, 3-2-24 Toyosu, Koto-ku, Tokyo 135-0061, Japan www.renesas.com

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