RoHS

COMPLIANT

HALOGEN

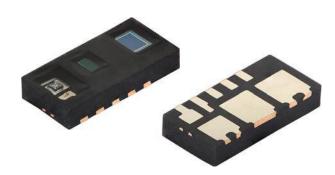
FREE GREEN

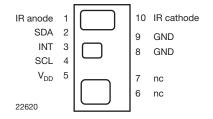


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Vishay Semiconductors

High Resolution Digital Biosensor for Wearable Applications With I²C Interface





DESCRIPTION

The VCNL4020C is a fully integrated biosensor and ambient light sensor. Fully integrated means that the infrared emitter is included in the package. It has 16 bit resolution. It includes a signal processing IC and features standard I²C communication interface. It features an interrupt function.

APPLICATIONS

- Wearables
- Health monitoring
- · Pulse oximetry

FEATURES

- · Package type: surface-mount
- Package form: SMD
- Dimensions (L x W x H in mm): 4.90 x 2.40 x 0.83
- Integrated modules: infrared emitter (IRED), ambient light sensor (ALS), photo diode (PD), and signal conditioning IC
- Interrupt function
- Supply voltage range V_{DD}: 2.5 V to 3.6 V
- Supply voltage range IR anode: 2.5 V to 5 V
- Communication via I²C interface
- I2C bus H-level range: 1.7 V to 5 V
- Floor life: 72 h, MSL 4, according to J-STD-020
- Low stand by current consumption: 1.5 μA
- Material categorization: for definitions of compliance please see www.vishav.com/doc?99912

OPTICAL BIOSENSORS FUNCTION

- Built-in infrared emitter and broader sensitivity photodiode allows to also work with green and red LEDs
- 16 bit effective resolution ensures excellent cross talk immunity
- Programmable LED drive current from 10 mA to 200 mA in 10 mA steps
- Excellent ambient light suppression through signal modulation

AMBIENT LIGHT FUNCTION

- Built-in ambient light photo-pin-diode with close-to-human-eye sensitivity
- 16 bit dynamic range from 0.25 lx to 16 klx
- 100 Hz and 120 Hz flicker noise rejection

PRODUCT	SUMMARY						
PART NUMBER	OPERATING VOLTAGE RANGE (V)	I ² C BUS VOLTAGE RANGE (V)	LED PULSE CURRENT ⁽¹⁾ (mA)	AMBIENT LIGHT RANGE (lx)	$\begin{array}{c} \text{SPECTRAL} \\ \text{BANDWIDTH} \\ \text{RANGE} \\ \lambda_{0.5} \text{ (nm)} \end{array}$	OUTPUT	ADC RESOLUTION BIOSENSOR / AMBIENT LIGHT SENSOR
VCNL4020C	2.5 to 3.6	1.7 to 5	10 to 200	0.25 to 16 383	550 to 970	16 bit, I ² C	16 bit / 16 bit

Note

(1) Adjustable through I2C interface



ORDERING INFORMATION							
ORDERING CODE	PACKAGING	VOLUME (1)	REMARKS				
VCNL4020C-GS08	Tana and roal	MOQ: 3300 pcs	4.90 mm x 2.40 mm x 0.83 mm				
VCNL4020C-GS18	Tape and reel	MOQ: 13 000 pcs	4.90 111111 X 2.40 111111 X 0.63 111111				

Note

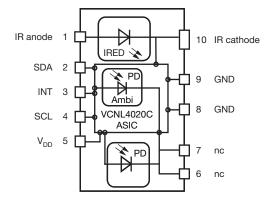
(1) MOQ: minimum order quantity

ABSOLUTE MAXIMUM RATINGS (T _{amb} = 25 °C, unless otherwise specified)									
PARAMETER	TEST CONDITION	SYMBOL	MIN.	MAX.	UNIT				
Supply voltage		V_{DD}	-0.3	5.5	V				
Operation temperature range		T _{amb}	-25	+85	°C				
Storage temperature range		T _{stg}	-25	+85	°C				
Total power dissipation	T _{amb} ≤ 25 °C	P _{tot}	-	50	mW				
Junction temperature		Tj	-	100	°C				

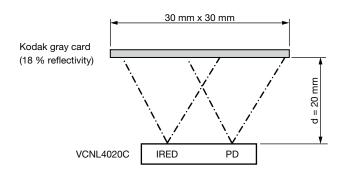
PARAMETER	TICS (T _{amb} = 25 °C, unless o	SYMBOL	MIN.	TYP.	MAX.	UNIT
Supply voltage V _{DD}			2.5	-	3.6	V
Supply voltage IR anode			2.5	-	5	V
I ² C bus H-level range			1.7	-	5	V
INT H-level range			1.7	-	5	V
INT low voltage	3 mA sink current		-	-	0.4	V
Current consumption	Standby current, no LED-operation		-	1.5	2	μA
Current consumption	2 measurements per second, LED current 20 mA		-	5	-	μA
	250 measurements per second, LED current 20 mA		-	520	-	μΑ
pulse mode incl. LED (averaged)	2 measurements per second, LED current 200 mA		=	35	-	μΑ
(averaged)	250 measurements per second, LED current 200 mA		-	4	-	mA
	2 measurements per second averaging = 1		=	2.5	-	μA
Current consumption ambient	8 measurements per second averaging = 1		-	10	-	μΑ
light mode	2 measurements per second averaging = 64		-	160	-	μΑ
	8 measurements per second averaging = 64		-	640	-	μΑ
Ambient light resolution	Digital resolution (LSB count) - 0.25		-	lx		
Ambient light output	E _V = 100 lx averaging = 64		-	400	400 -	
I ² C clock rate range		f _{SCL}	-	-	3400	kHz



CIRCUIT BLOCK DIAGRAM



TEST CIRCUIT



Note

nc must not be electrically connected
 Pads 6 and 7 are only considered as solder pads

BASIC CHARACTERISTICS (T_{amb} = 25 °C, unless otherwise specified)

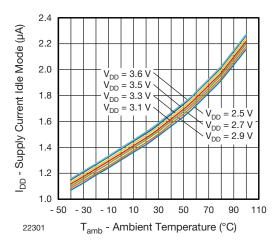


Fig. 1 - Idle Current vs. Ambient Temperature

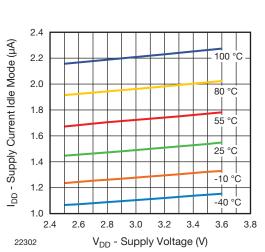


Fig. 2 - Idle Current vs. V_{DD}

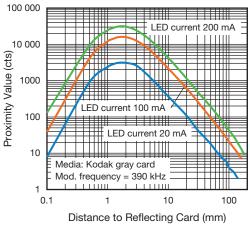


Fig. 3 - Proximity Value vs. Distance

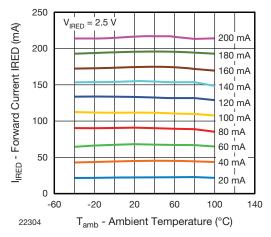


Fig. 4 - Forward Current vs. Temperature



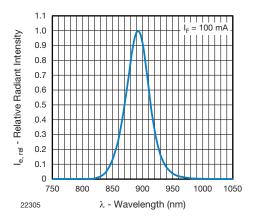


Fig. 5 - Relative Radiant Intensity vs. Wavelength

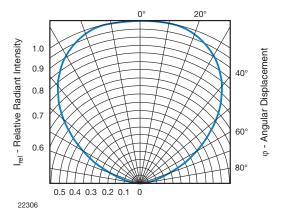


Fig. 6 - Relative Radiant Intensity vs. Angular Displacement

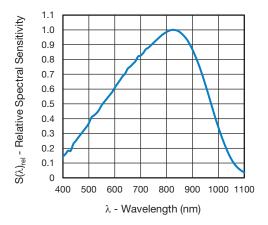


Fig. 7 - Relative Spectral Sensitivity vs. Wavelength (Biosensor)

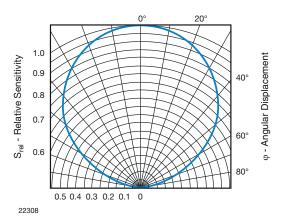


Fig. 8 - Relative Radiant Sensitivity vs. Angular Displacement (Proximity Sensor)

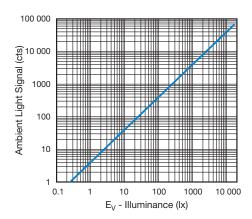


Fig. 9 - Ambient Light Value vs. Illuminance

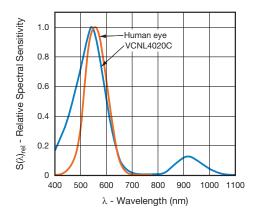


Fig. 10 - Relative Spectral Sensitivity vs. Wavelength (Ambient Light Sensor)



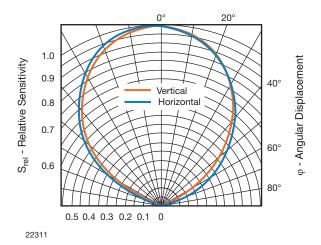


Fig. 11 - Relative Radiant Sensitivity vs. Angular Displacement (Ambient Light Sensor)

APPLICATION INFORMATION

The digital biosensor VCNL4020C needs just one decoupling-C at V_{DD} if connected to a regulated power supply.

IR cathode needs no external connection as the connection to the driver is done internally, but this allows also for adding external LEDs / IREDs to the driver.

1. Application Circuit

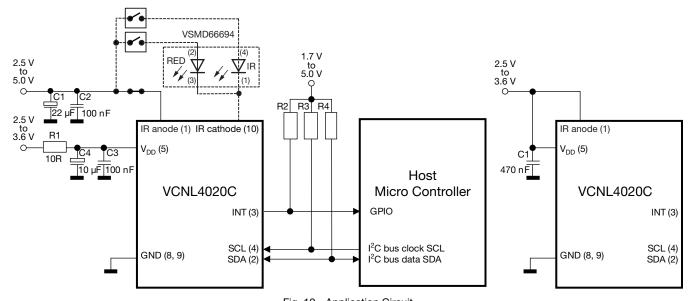


Fig. 12 - Application Circuit (x) = Pin Number

Note

The interrupt pin is an open drain output. The needed pull-up resistor may be connected to the same supply voltage as the application controller and the pull-up resistors at SDA / SCL. Proposed value R2 should be >1 kΩ, e.g. 10 kΩ to 100 kΩ.
 Proposed value for R3 and R4, e.g. 2.2 kΩ to 4.7 kΩ, depend also on the I²C bus speed.
 For detailed description about set-up and use of the interrupt as well as more application related information see AN: "Designing VCNL4020C into an Application".



2. I²C Interface

The VCNL4020C contains seventeen 8 bit registers for operation control, parameter setup and result buffering. All registers are accessible via I²C communication. Figure 13 shows the basic I²C communication with VCNL4020C.

The built in I²C interface is compatible with all I²C modes (standard, fast and high speed).

I²C H-level range = 1.7 V to 5 V.

Please refer to the I²C specification from NXP for details.

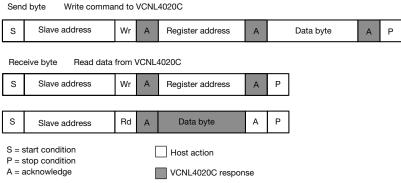


Fig. 13 - Send Byte/Receive Byte Protocol

Device Address

The VCNL4020C has a fix slave address for the host programming and accessing selection. The predefined 7 bit I^2C bus address is set to 0010 011 = 13h. The least significant bit (LSB) defines read or write mode. Accordingly the bus address is set to 0010 011x = 26h for write, 27h for read.

Register Addresses

VCNL4020C has seventeen user accessible 8 bit registers. The register addresses are 80h (register #0) to 90h (register #16).

REGISTER FUNCTIONS

Register #0 Command Register

Register address = 80h

The register #0 is for starting ambient light or biosensor measurements. This register contains 2 flag bits for data ready indication.

TABLE 1 - COMMAND REGISTER #0										
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0			
config_lock	als_data_rdy	bs_data_rdy	als_od	bs_od	als_en	bs_en	selftimed_en			
	Description									
confiç	g_lock	Read only bit. V	alue = 1							
als_data_rdy Read only bit. Value = 1 when ambient light measurement data is available in the result registers. This bit will be reset when one of the corresponding result registers (reg #5, reg #6) is read.										
bs_da	ita_rdy	Read only bit. Value = 1 when biosensor measurement data is available in the result registers. This bit will be reset when one of the corresponding result registers (reg #7, reg #8) is read.								
als	_od	sequence of rea		nd measurement f the averaged resuld #6(LB).						
bs.	_od			nd measurement f onversion for read		s #7(HB) and #8(LB).			
als	_en	R/W bit. Enable	s periodic als mea	asurement						
bs.	_en	R/W bit. Enable	R/W bit. Enables periodic biosensor measurement							
selftim	ned_en		s state machine a the corresponding	nd LP oscillator fog bit is set	or self timed meas	urements; no me	asurement is			

Note

With setting bit 3 and bit 4 at the same write command, a simultaneously measurement of ambient light and biosensor is done. Beside als_en and / or bs_en first selftimed_en needs to be set. On-demand measurement modes are disabled if selftimed_en bit is set. For the selftimed_en mode changes in reading rates (reg #4 and reg #2) can be made only when b0 (selftimed_en bit) = 0. For the als_od mode changes to the reg #4 can be made only when b4 (als_od bit) = 0; this is to avoid synchronization problems and undefined states between the clock domains. In effect this means that it is only reasonable to change rates while no selftimed conversion is ongoing.



Register #1 Product ID Revision Register

Register address = 81h. This register contains information about product ID and product revision.

Register data value of current revision = 21h.

TABLE 2 - PRODUCT ID REVISION REGISTER #1										
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0			
	Produ	uct ID		Revision ID						
			Descr	ription						
Prod	Product ID Read only bits. Value = 2									
Revision ID Read only bits. Value = 1										

Register #2 Rate of Biosensor Measurement

Register address = 82h.

TABLE 3 - BIOSENSOR RATE REGISTER #2											
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0				
n/a Rate of biosensor Measurement (no. of measurements per second)											
Description											
Biosen	sor rate	R/W bits. 000 - 1.95 meas 001 - 3.90625 m 010 - 7.8125 meas 100 - 31.25 meas 101 - 62.5 meas 110 - 125 meas 111 - 250 meas	AULT)								

Note

Register #3 LED Current Setting for Biosensor Mode

Register address = 83h. This register is to set the LED current value for biosensor measurement.

The value is adjustable in steps of 10 mA from 0 mA to 200 mA.

This register also contains information about the used device fuse program ID.

TABLE 4 -	TABLE 4 - LED CURRENT REGISTER #3									
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0			
Fuse prog ID LED current value										
Description										
Fuse p	Fuse prog ID Read only bits. Information about fuse program revision used for initial setup/calibration of the device.									
LED curr	R/W bits. LED current = Value (dec.) x 10 mA. LED current value Valid Range = 0 to 20d. e.g. 0 = 0 mA, 1 = 10 mA,, 20 = 200 mA (2 = 20 mA = DEFAULT) LED Current is limited to 200 mA for values higher as 20d.									

[•] If self_timed measurement is running, any new value written in this register will not be taken over until the mode is actualy cycled.



Register #4 Ambient Light Parameter Register

Register address = 84h.

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	
Cont. conv. mode		als_rate		Auto offset compensation	Averaging function (number of measurements per run)			
			Des	cription	,		· · · · · · · · · · · · · · · · · · ·	
R/W bit. Continuous conversion mode. Enable = 1; Disable = 0 = DEFAULT Cont. conversion mode This function can be used for performing faster ambient light measurements. This mode sho used with ambient light on-demand measurements. Do not use with self-timed mode. Please application information chapter 3.3 for details about this function.								
Ambient light m	easurement rate	000 - 1 sample	ss/s = DEFAULT ss/s ss/s ss/s ss/s ss/s	ement rate				
Auto offset o	compensation	Enable = 1 = D In order to com there is a built With active aut	R/W bit. Automatic offset compensation. Enable = 1 = DEFAULT; Disable = 0 In order to compensate a technology, package or temperature related drift of the ambient light values there is a built in automatic offset compensation function. With active auto offset compensation the offset value is measured before each ambient light measurement and subtracted automatically from actual reading.					
Averagin	g function	R/W bits. Averaging function. Bit values sets the number of single conversions done during one measurement cycle. Result is the average value of all conversions. Number of conversions = 2 ^{decimal_value} e.g. 0 = 1 conv., 1 = 2 conv, 2 = 4 conv.,7 = 128 conv. DEFAULT = 32 conv. (bit 2 to bit 0: 101)						

Note

• If self_timed measurement is running, any new value written in this register will not be taken over until the mode is actualy cycled.

Register #5 and #6 Ambient Light Result Register

Register address = 85h and 86h. These registers are the result registers for ambient light measurement readings.

The result is a 16 bit value. The high byte is stored in register #5 and the low byte in register #6.

TABLE 6 - AMBIENT LIGHT RESULT REGISTER #5									
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0		
	Description								
	Read only bits. High byte (15:8) of ambient light measurement result								

TABLE 7 - AMBIENT LIGHT RESULT REGISTER #6										
Bit 7	Bit 7 Bit 6 Bit 5 Bit 4 Bit 3 Bit 2 Bit 1 Bit 0									
	Description									
Read only bits. Low byte (7:0) of ambient light measurement result										



Register #7 and #8 Biosensor Measurement Result Register

Register address = 87h and 88h. These registers are the result registers for biosensor measurement readings.

The result is a 16 bit value. The high byte is stored in register #7 and the low byte in register #8.

TABLE 8 - BIOSENSOR RESULT REGISTER #7									
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0		
Description									
		Read only bits	. High byte (15:8)	of biosensor meas	surement result				

TABLE 9 - BIOSENSOR RESULT REGISTER #8										
Bit 7	Bit 7 Bit 6 Bit 5 Bit 4 Bit 3 Bit 2 Bit 1 Bit 0									
Description										
	Read only bits. Low byte (7:0) of biosensor measurement result									

Register #9 Interrupt Control Register

Register address = 89h.

ABLE 10	- INTERRUP	T CONTROL	REGISTER #	9				
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	
Int count exceed		n/a	INT_BS_ ready_EN	INT_ALS_ ready_EN	INT_THRES_EN	INT_THRES		
			Desci	ription				
R/W bits. These bits contain the threshold 000 - 1 count = DEFAULT 001 - 2 count 010 - 4 count 011 - 8 count 100 - 16 count 101 - 32 count 110 - 64 count 111 - 128 count				number of consec	utive measureme	nts needed above/	below the	
INT_BS_r	ready_EN	R/W bit. Enable	s interrupt genera	tion at biosensor	data ready			
INT_ALS_	ready_EN	R/W bit. Enable	R/W bit. Enables interrupt generation at ambient data ready					
INT_THI	RES_EN	R/W bit. Enable	R/W bit. Enables interrupt generation when high or low threshold is exceeded					
INT_THE	RES_SEL	R/W bit. If 0: thresholds are applied to biosensor measurements If 1: thresholds are applied to als measurements						



Register #10 and #11 Low Threshold

Register address = 8Ah and 8Bh. These registers contain the low threshold value. The value is a 16 bit word. The high byte is stored in register #10 and the low byte in register #11.

TABLE 11 - LOW THRESHOLD REGISTER #10									
Bit 7	Bit 7 Bit 6 Bit 5 Bit 4 Bit 3 Bit 2 Bit 1 Bit 0								
Description									
	R/W bits. High byte (15:8) of low threshold value								

TABLE 12 - LOW THRESHOLD REGISTER #11									
Bit 7	Bit 7 Bit 6 Bit 5 Bit 4 Bit 3 Bit 2 Bit 1 Bit 0								
Description									
	R/W bits. Low byte (7:0) of low threshold value								

Register #12 and #13 High Threshold

Register address = 8Ch and 8Dh. These registers contain the high threshold value. The value is a 16 bit word. The high byte is stored in register #12 and the low byte in register #13.

TABLE 13 - HIGH THRESHOLD REGISTER #12										
Bit 7	Bit 7 Bit 6 Bit 5 Bit 4 Bit 3 Bit 2 Bit 1 Bit 0									
Description										
	R/W bits. High byte (15:8) of high threshold value									

TABLE 14 - HIGH THRESHOLD REGISTER #13										
Bit 7	Bit 7 Bit 6 Bit 5 Bit 4 Bit 3 Bit 2 Bit 1 Bit 0									
Description										
R/W bits. Low byte (7:0) of high threshold value										

Register #14 Interrupt Status Register

Register address = 8Eh. This register contains information about the interrupt status for either biosensor or ALS function and indicates if high or low going threshold exceeded.

TABLE 15 - INTERRUPT STATUS REGISTER #14									
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0		
	n/a int_bs_ready int_als_ready int_th_low int_th_hi								
Description									
int_bs_ready R/W bit. Indicates a generated in				terrupt for biosens	or				
int_als	int_als_ready R/W bit. Indicates a generated int								
int_th	int_th_low R/W bit. Indicates a low threshold exceed								
int_t	th_hi	R/W bit. Indicates a high threshold exceed							

Note

 Once an interrupt is generated the corresponding status bit goes to 1 and stays there unless it is cleared by writing a 1 in the corresponding bit. The int pad will be pulled down while at least one of the status bit is 1.



Register #15 Biosensor Modulator Timing Adjustment

Register address = 8Fh.

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
N	Modulation delay tir	ne	Biosensor	frequency	M	odulation dead tir	ne
			Desci	ription			
		R/W bits. Settin	g a delay time be	tween LED signal	and detectors inpo	ut signal evaluatio	on.
Modulatio	on delay time		ent proximity sign		D and photo dioderect adjustment is		
R/W bits. Setting the biosensor test signal frequency The biosensor measurement is using a square signal as measurement signal. Four different various possible: Biosensor frequency 00 = 390.625 kHz (DEFAULT) 01 = 781.25 kHz 10 = 1.5625 MHz 11 = 3.125 MHz						erent values are	
R/W bits. Setting a dead time in evaluation of LED signal at t Modulation dead time This function is for reducing of possible disturbance effects. This function is reducing signal level and should be used car					e effects.	s of the signal. (D	EFAULT = 1)

Note

• The settings for best performance will be provided by Vishay. With first samples this is evaluated to: Delay time = 0; dead time = 1 and BS frequency = 00. With that register #15 should be programmed with 1 (= default value).

Register #16 Ambient IR Light Level Register

Register address = 90h.

This register is not intended to be used by customer.

3. IMPORTANT APPLICATION HINTS AND EXAMPLES

3.1 Receiver standby mode

In standby mode the receiver has the lowest current consumption of about 1.5 μ A. In this mode only the I²C interface is active. This is always valid, when there are no measurement demands executed. Also the current sink for the LED is inactive, so there is no need for changing register #3 (LED current).

3.2 Data Read

In order to get a certain register value, the register has to be addressed without data like shown in the following scheme. After this register addressing, the data from the addressed register is written after a subsequent read command.

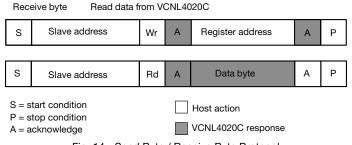


Fig. 14 - Send Byte / Receive Byte Protocol

The stop condition between these write and read sequences is not mandatory. It works also with a repeated start condition.

Note

For reading out 2 (or more) subsequent registers like the result registers, it is not necessary to address each of the registers separately. After
one read command the internal register counter is increased automatically and any subsequent read command is accessing the next
register.



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Example: read register "Ambient Light Result Register" #5 and #6:

Addressing:command: 26h, 85h (VCNL4020C_I²C_Bus_Write_Adr., Ambient Light Result Register #5 [85])

Read register #5:command: 27h, data (VCNL4020C_I²C_Bus_Read_Adr., {High Byte Data of Ambient Light Result register #5 [85])}

Read register #6:command: 27h, data (VCNL4020C_I²C_Bus_Read_Adr., {Low Byte Data of Ambient Light Result register #6 [86])}

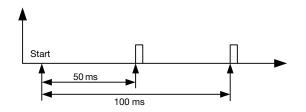
3.3 Continuous Conversion Mode in Ambient Light Measurement

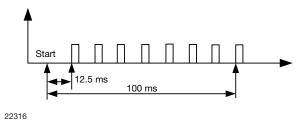
In the following is a detail description of the function "continuous conversion" (bit 7 of register #4)

Standard mode (bit 7 of reg #4 = 0):

In standard mode the ambient light measurement is done during a fixed time frame of 100 ms. The single measurement itself takes actually only appr. 300 µs.

The following figures show examples of this measurement timing in standard mode using averaging function 2 and 8 as examples for illustration (possible values up to 128).





22315

Fig. 15 - Ambient Light Measurement with Averaging = 2; Final Measurement Result = Average of these 2 Measurements

Fig. 16 - Ambient Light Measurement with Averaging = 8; Final Measurement Result = Average of these 8 Measurements

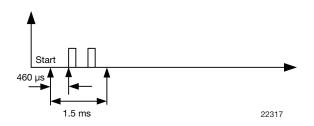
Note

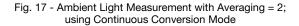
• ≥ Independent of setting of averaging the result is available only after 100 ms.

Continuous conversion mode (bit 7 of register #4 = 1):

In continuous conversion mode the single measurements are done directly subsequent after each other.

See following examples in figure 17 and 18





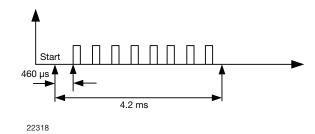
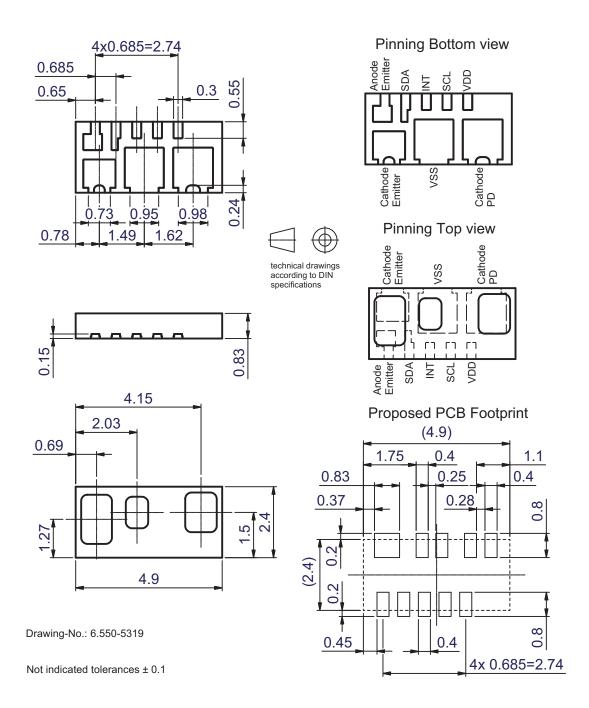


Fig. 18 - Ambient Light Measurement with Averaging = 8; using Continuous Conversion Mode

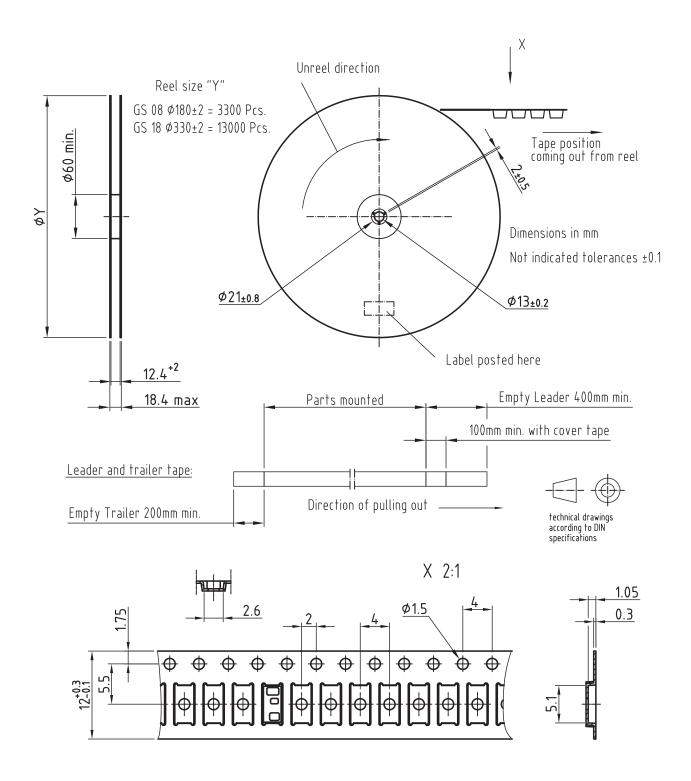




PACKAGE DIMENSIONS in millimeters



TAPE AND REEL DIMENSIONS in millimeters



Drawing-No.: 9.700-5387.01-4



SOLDER PROFILE

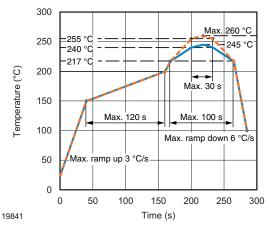


Fig. 19 - Lead (Pb)-free Reflow Solder Profile According to J-STD-020

DRYPACK

Devices are packed in moisture barrier bags (MBB) to prevent the products from moisture absorption during transportation and storage. Each bag contains a desiccant.

FLOOR LIFE

Floor life (time between soldering and removing from MBB) must not exceed the time indicated on MBB label:

Floor life: 72 h

Conditions: T_{amb} < 30 °C, RH < 60 %

Moisture sensitivity level 4, according to J-STD-020.

DRYING

In case of moisture absorption devices should be baked before soldering. Conditions see J-STD-020 or label. Devices taped on reel dry using recommended conditions 192 h at 40 $^{\circ}$ C (+ 5 $^{\circ}$ C), RH < 5 $^{\circ}$ M.



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