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1. Overview

1.1 Features

The R8C/32D Group of single-chip MCUs incorporates the R8C CPU core, employing sophisticated instructions for a high level of efficiency. With 1 Mbyte of address space, and it is capable of executing instructions at high speed. In addition, the CPU core boasts a multiplier for high-speed operation processing.

Power consumption is low, and the supported operating modes allow additional power control. These MCUs are designed to maximize EMI/EMS performance.

Integration of many peripheral functions, including multifunction timer and serial interface, reduces the number of system components.

1.1.1 Applications

Electronic household appliances, office equipment, audio equipment, consumer equipment, etc.

1.1.2 Specifications

Tables 1.1 and 1.2 outline the Specifications for R8C/32D Group.

Table 1.1 Specifications for R8C/32D Group (1)

| Item | Function | Specification |
|--------------------------------|---------------------------|---|
| CPU | Central processing unit | <p>R8C CPU core</p> <ul style="list-style-type: none"> Number of fundamental instructions: 89 Minimum instruction execution time: <ul style="list-style-type: none"> 50 ns ($f(XIN) = 20$ MHz, $VCC = 2.7$ to 5.5 V) 200 ns ($f(XIN) = 5$ MHz, $VCC = 1.8$ to 5.5 V) Multiplier: 16 bits \times 16 bits \rightarrow 32 bits Multiply-accumulate instruction: 16 bits \times 16 bits + 32 bits \rightarrow 32 bits Operation mode: Single-chip mode (address space: 1 Mbyte) |
| Memory | ROM, RAM | Refer to Table 1.3 Product List for R8C/32D Group . |
| Power Supply Voltage Detection | Voltage detection circuit | <ul style="list-style-type: none"> Power-on reset Voltage detection 3 (detection level of voltage detection 0 and voltage detection 1 selectable) |
| I/O Ports | Programmable I/O ports | <ul style="list-style-type: none"> Input-only: 1 pin CMOS I/O ports: 15, selectable pull-up resistor High current drive ports: 15 |
| Clock | Clock generation circuits | <p>4 circuits: XIN clock oscillation circuit, XCIN clock oscillation circuit (32 kHz), High-speed on-chip oscillator (with frequency adjustment function), Low-speed on-chip oscillator,</p> <ul style="list-style-type: none"> Oscillation stop detection: XIN clock oscillation stop detection function Frequency divider circuit: Dividing selectable 1, 2, 4, 8, and 16 Low power consumption modes: <ul style="list-style-type: none"> Standard operating mode (high-speed clock, low-speed clock, high-speed on-chip oscillator, low-speed on-chip oscillator), wait mode, stop mode <p>Real-time clock (timer RE)</p> |
| Interrupts | | <ul style="list-style-type: none"> Number of interrupt vectors: 69 External Interrupt: 7 ($\overline{INT} \times 3$, Key input $\times 4$) Priority levels: 7 levels |
| Watchdog Timer | | <ul style="list-style-type: none"> 14 bits \times 1 (with prescaler) Reset start selectable Low-speed on-chip oscillator for watchdog timer selectable |
| Timer | Timer RA | <p>8 bits \times 1 (with 8-bit prescaler)</p> <p>Timer mode (period timer), pulse output mode (output level inverted every period), event counter mode, pulse width measurement mode, pulse period measurement mode</p> |
| | Timer RB | <p>8 bits \times 1 (with 8-bit prescaler)</p> <p>Timer mode (period timer), programmable waveform generation mode (PWM output), programmable one-shot generation mode, programmable wait one-shot generation mode</p> |
| | Timer RC | <p>16 bits \times 1 (with 4 capture/compare registers)</p> <p>Timer mode (input capture function, output compare function), PWM mode (output 3 pins), PWM2 mode (PWM output pin)</p> |
| | Timer RE | <p>8 bits \times 1</p> <p>Real-time clock mode (count seconds, minutes, hours, days of week)</p> |
| Serial Interface | UART0 | Clock synchronous serial I/O/UART |
| | UART2 | Clock synchronous serial I/O/UART, I ² C mode (I ² C-bus), multiprocessor communication function |
| A/D Converter | | 10-bit resolution \times 4 channels, includes sample and hold function, with sweep mode |
| Comparator B | | 2 circuits |

Table 1.2 Specifications for R8C/32D Group (2)

| Item | Function | Specification |
|------------------------------------|----------|---|
| Flash Memory | | <ul style="list-style-type: none"> • Programming and erasure voltage: VCC = 2.7 to 5.5 V • Programming and erasure endurance: 1,000 times (program ROM) • Program security: ROM code protect, ID code check • Debug functions: On-chip debug, on-board flash rewrite function |
| Operating Frequency/Supply Voltage | | f(XIN) = 20 MHz (VCC = 2.7 to 5.5 V) f(XIN) = 5 MHz (VCC = 1.8 to 5.5 V) |
| Current consumption | | Typ. 6.5 mA (VCC = 5.0 V, f(XIN) = 20 MHz) Typ. 3.5 mA (VCC = 3.0 V, f(XIN) = 10 MHz) Typ. 3.5 μ A (VCC = 3.0 V, wait mode (f(XCIN) = 32 kHz)) Typ. 2.0 μ A (VCC = 3.0 V, stop mode) |
| Operating Ambient Temperature | | -20 to 85°C (N version) -40 to 85°C (D version) (1) |
| Package | | 20-pin LSSOP Package code: PLSP0020JB-A (previous code: 20P2F-A) |

Note:

1. Specify the D version if D version functions are to be used.

1.2 Product List

Table 1.3 lists Product List for R8C/32D Group, and Figure 1.1 shows a Part Number, Memory Size, and Package of R8C/32D Group.

Table 1.3 Product List for R8C/32D Group **Current of Feb. 2010**

| Part No. | ROM Capacity | RAM Capacity | Package Type | Remarks |
|------------------|--------------|--------------|--------------|-----------|
| R5F21321DNSP | 4 Kbytes | 1 Kbyte | PLSP0020JB-A | N version |
| R5F21322DNSP | 8 Kbytes | 1 Kbyte | PLSP0020JB-A | |
| R5F21324DNSP | 16 Kbytes | 1 Kbyte | PLSP0020JB-A | |
| R5F21321DDSP (D) | 4 Kbytes | 1 Kbyte | PLSP0020JB-A | D version |
| R5F21322DDSP (D) | 8 Kbytes | 1 Kbyte | PLSP0020JB-A | |
| R5F21324DDSP (D) | 16 Kbytes | 1 Kbyte | PLSP0020JB-A | |

(D): Under development

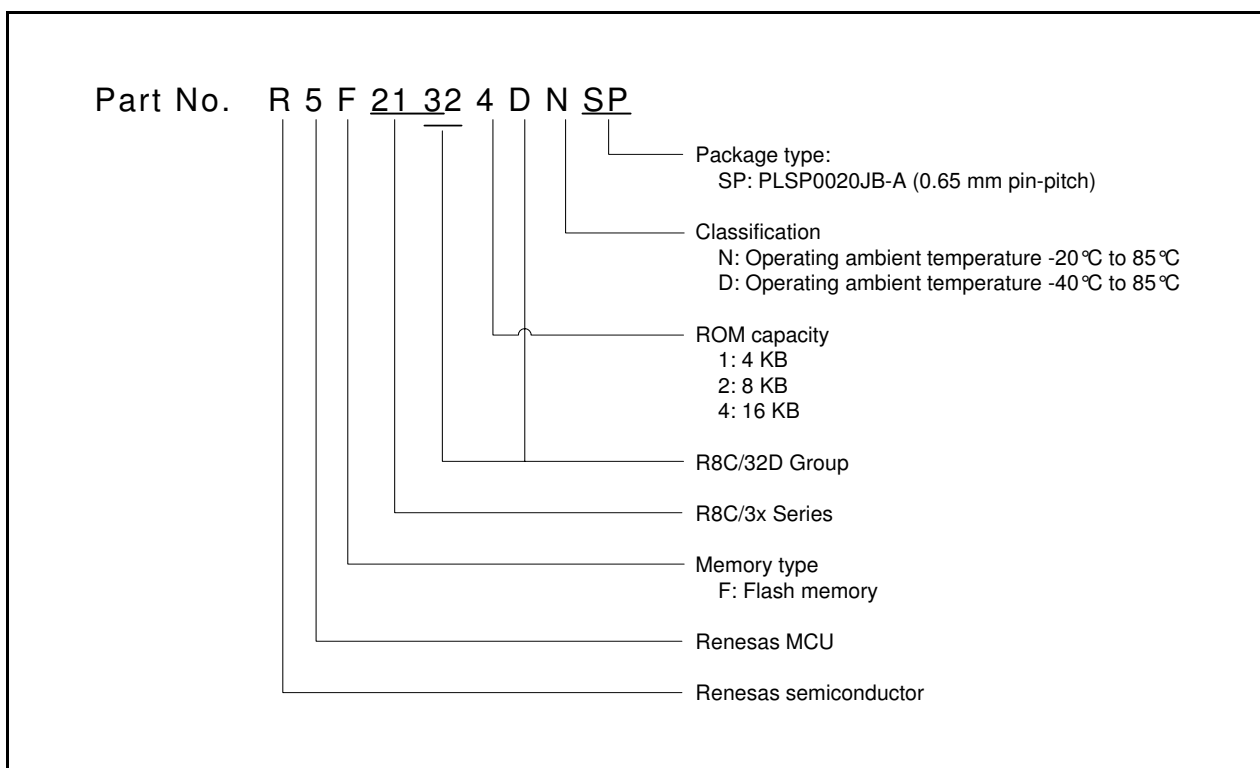


Figure 1.1 Part Number, Memory Size, and Package of R8C/32D Group

1.3 Block Diagram

Figure 1.2 shows a Block Diagram.

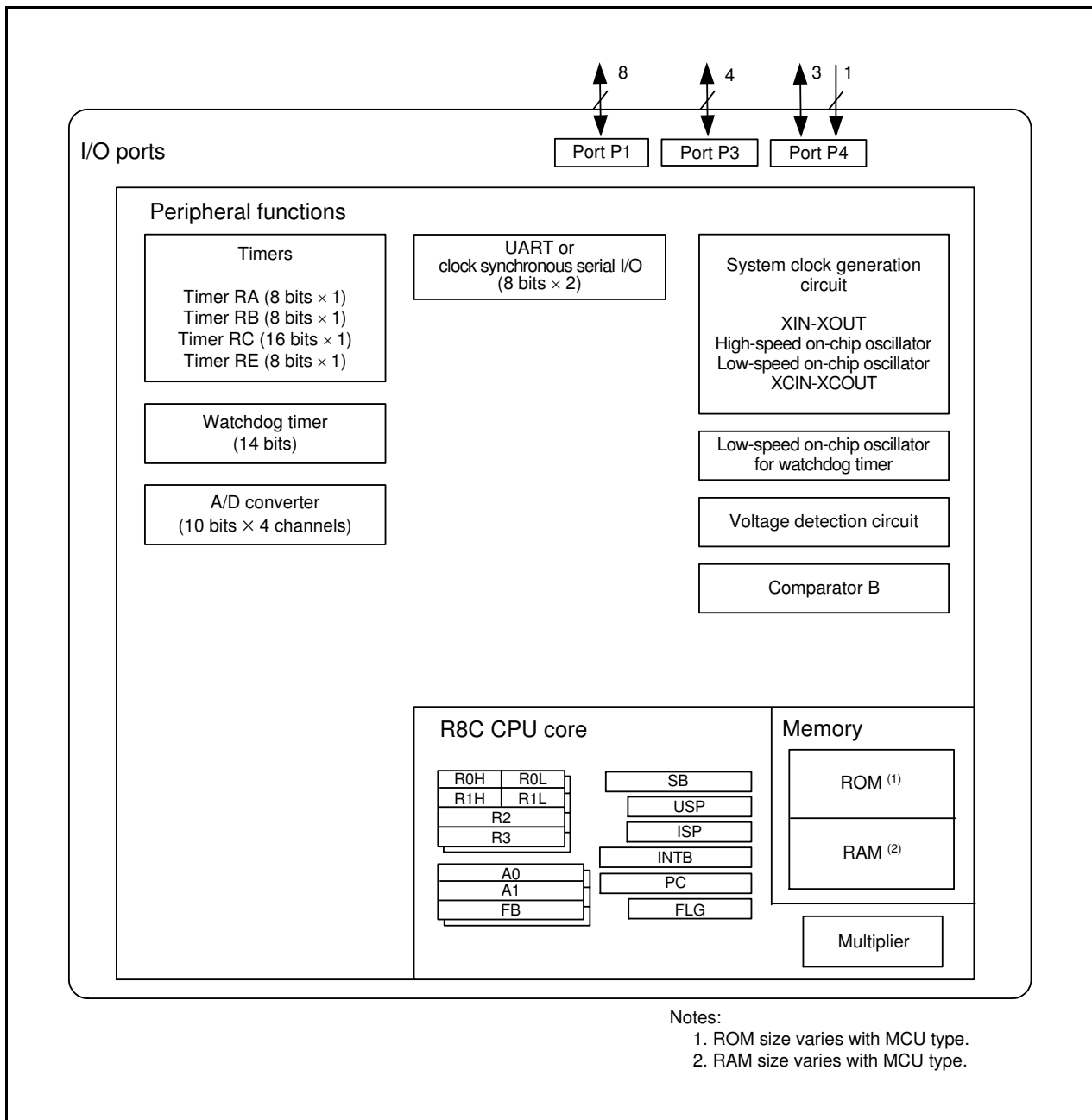


Figure 1.2 Block Diagram

1.4 Pin Assignment

Figure 1.3 shows Pin Assignment (Top View). Table 1.4 outlines the Pin Name Information by Pin Number.

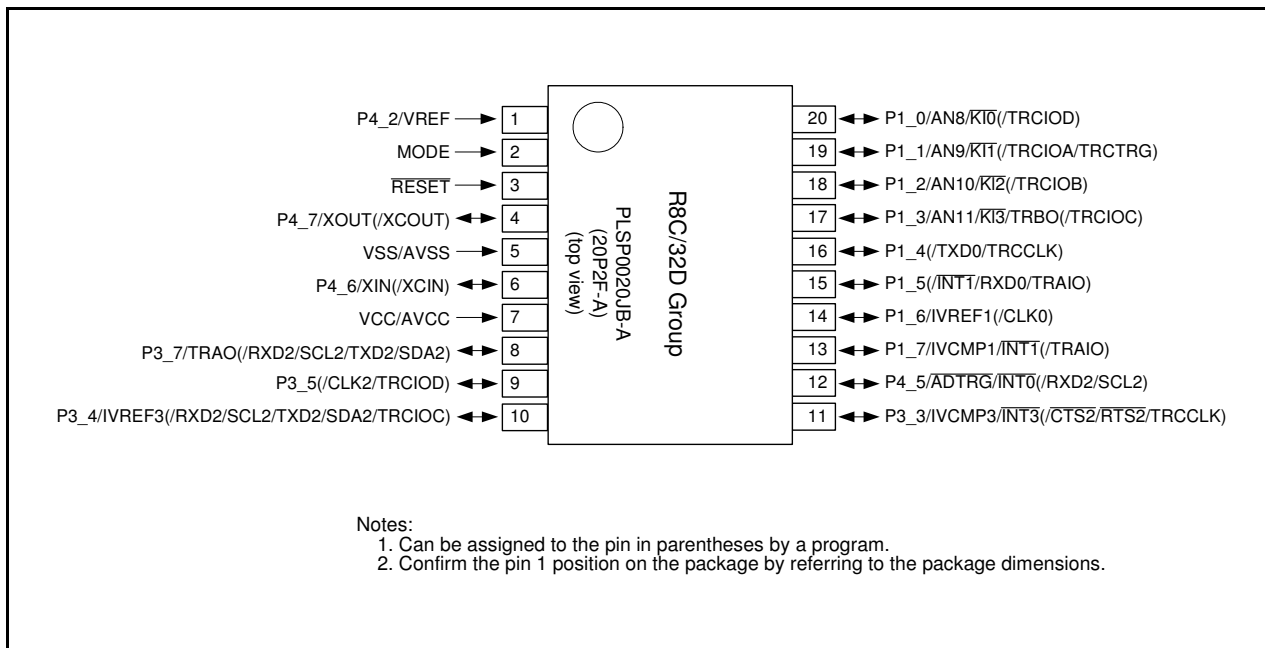


Figure 1.3 Pin Assignment (Top View)

Table 1.4 Pin Name Information by Pin Number

| Pin Number | Control Pin | Port | I/O Pin Functions for Peripheral Modules | | | |
|------------|---------------------------|------|--|-----------------|---|-----------------------------|
| | | | Interrupt | Timer | Serial Interface | A/D Converter, Comparator B |
| 1 | | P4_2 | | | | VREF |
| 2 | MODE | | | | | |
| 3 | $\overline{\text{RESET}}$ | | | | | |
| 4 | XOUT(/XCOUT) | P4_7 | | | | |
| 5 | VSS/AVSS | | | | | |
| 6 | XIN(/XCIN) | P4_6 | | | | |
| 7 | VCC/AVCC | | | | | |
| 8 | | P3_7 | | TRA0 | (RXD2/SCL2/ TXD2/SDA2) | |
| 9 | | P3_5 | | (TRCIOD) | (CLK2) | |
| 10 | | P3_4 | | (TRCIOA) | (RXD2/SCL2/ TXD2/SDA2) | IVREF3 |
| 11 | | P3_3 | $\overline{\text{INT3}}$ | (TRCCLK) | ($\overline{\text{CTS2}}$ / $\overline{\text{RTS2}}$) | IVCMP3 |
| 12 | | P4_5 | $\overline{\text{INT0}}$ | | (RXD2/SCL2) | $\overline{\text{ADTRG}}$ |
| 13 | | P1_7 | $\overline{\text{INT1}}$ | (TRAIO) | | IVCMP1 |
| 14 | | P1_6 | | | (CLK0) | IVREF1 |
| 15 | | P1_5 | ($\overline{\text{INT1}}$) | (TRAIO) | (RXD0) | |
| 16 | | P1_4 | | (TRCCLK) | (TXD0) | |
| 17 | | P1_3 | $\overline{\text{KI3}}$ | TRBO(/TRCIOA) | | AN11 |
| 18 | | P1_2 | $\overline{\text{KI2}}$ | (TRCIOB) | | AN10 |
| 19 | | P1_1 | $\overline{\text{KI1}}$ | (TRCIOA/TRCTRG) | | AN9 |
| 20 | | P1_0 | $\overline{\text{KI0}}$ | (TRCIOD) | | AN8 |

Note:

1. Can be assigned to the pin in parentheses by a program.

1.5 Pin Functions

Table 1.5 lists Pin Functions.

Table 1.5 Pin Functions

| Item | Pin Name | I/O Type | Description |
|---|--|----------|--|
| Power supply input | VCC, VSS | – | Apply 1.8 V to 5.5 V to the VCC pin. Apply 0 V to the VSS pin. |
| Analog power supply input | AVCC, AVSS | – | Power supply for the A/D converter. Connect a capacitor between AVCC and AVSS. |
| Reset input | $\overline{\text{RESET}}$ | I | Input “L” on this pin resets the MCU. |
| MODE | MODE | I | Connect this pin to VCC via a resistor. |
| XIN clock input | XIN | I | These pins are provided for XIN clock generation circuit I/O. Connect a ceramic resonator or a crystal oscillator between the XIN and XOUT pins ⁽¹⁾ . To use an external clock, input it to the XOUT pin and leave the XIN pin open. |
| XIN clock output | XOUT | I/O | |
| XCIN clock input | XCIN | I | These pins are provided for XCIN clock generation circuit I/O. Connect a crystal oscillator between the XCIN and XCOU pins ⁽¹⁾ . To use an external clock, input it to the XCIN pin and leave the XCOU pin open. |
| XCIN clock output | XCOU | O | |
| $\overline{\text{INT}}$ interrupt input | $\overline{\text{INT0}}$, $\overline{\text{INT1}}$, $\overline{\text{INT3}}$ | I | $\overline{\text{INT}}$ interrupt input pins. INT0 is timer RB, and RC input pin. |
| Key input interrupt | $\overline{\text{KI0}}$ to $\overline{\text{KI3}}$ | I | Key input interrupt input pins |
| Timer RA | TRAIO | I/O | Timer RA I/O pin |
| | TRAO | O | Timer RA output pin |
| Timer RB | TRBO | O | Timer RB output pin |
| Timer RC | TRCLK | I | External clock input pin |
| | TRCTR | I | External trigger input pin |
| | TRCIOA, TRCIOB, TRCIOC, TRCIOD | I/O | Timer RC I/O pins |
| Serial interface | CLK0, CLK2 | I/O | Transfer clock I/O pins |
| | RXD0, RXD2 | I | Serial data input pins |
| | TXD0, TXD2 | O | Serial data output pins |
| | $\overline{\text{CTS2}}$ | I | Transmission control input pin |
| | $\overline{\text{RTS2}}$ | O | Reception control output pin |
| | SCL2 | I/O | I ² C mode clock I/O pin |
| | SDA2 | I/O | I ² C mode data I/O pin |
| Reference voltage input | VREF | I | Reference voltage input pin to A/D converter |
| A/D converter | AN8 to AN11 | I | Analog input pins to A/D converter |
| | $\overline{\text{ADTRG}}$ | I | A/D external trigger input pin |
| Comparator B | IVCMP1, IVCMP3 | I | Comparator B analog voltage input pins |
| | IVREF1, IVREF3 | I | Comparator B reference voltage input pins |
| I/O port | P1_0 to P1_7, P3_3 to P3_5, P3_7, P4_5 to P4_7 | I/O | CMOS I/O ports. Each port has an I/O select direction register, allowing each pin in the port to be directed for input or output individually. Any port set to input can be set to use a pull-up resistor or not by a program. All ports can be used as LED drive ports. |
| Input port | P4_2 | I | Input-only port |

I: Input O: Output I/O: Input and output

Note:

1. Refer to the oscillator manufacturer for oscillation characteristics.

2. Central Processing Unit (CPU)

Figure 2.1 shows the CPU Registers. The CPU contains 13 registers. R0, R1, R2, R3, A0, A1, and FB configure a register bank. There are two sets of register bank.

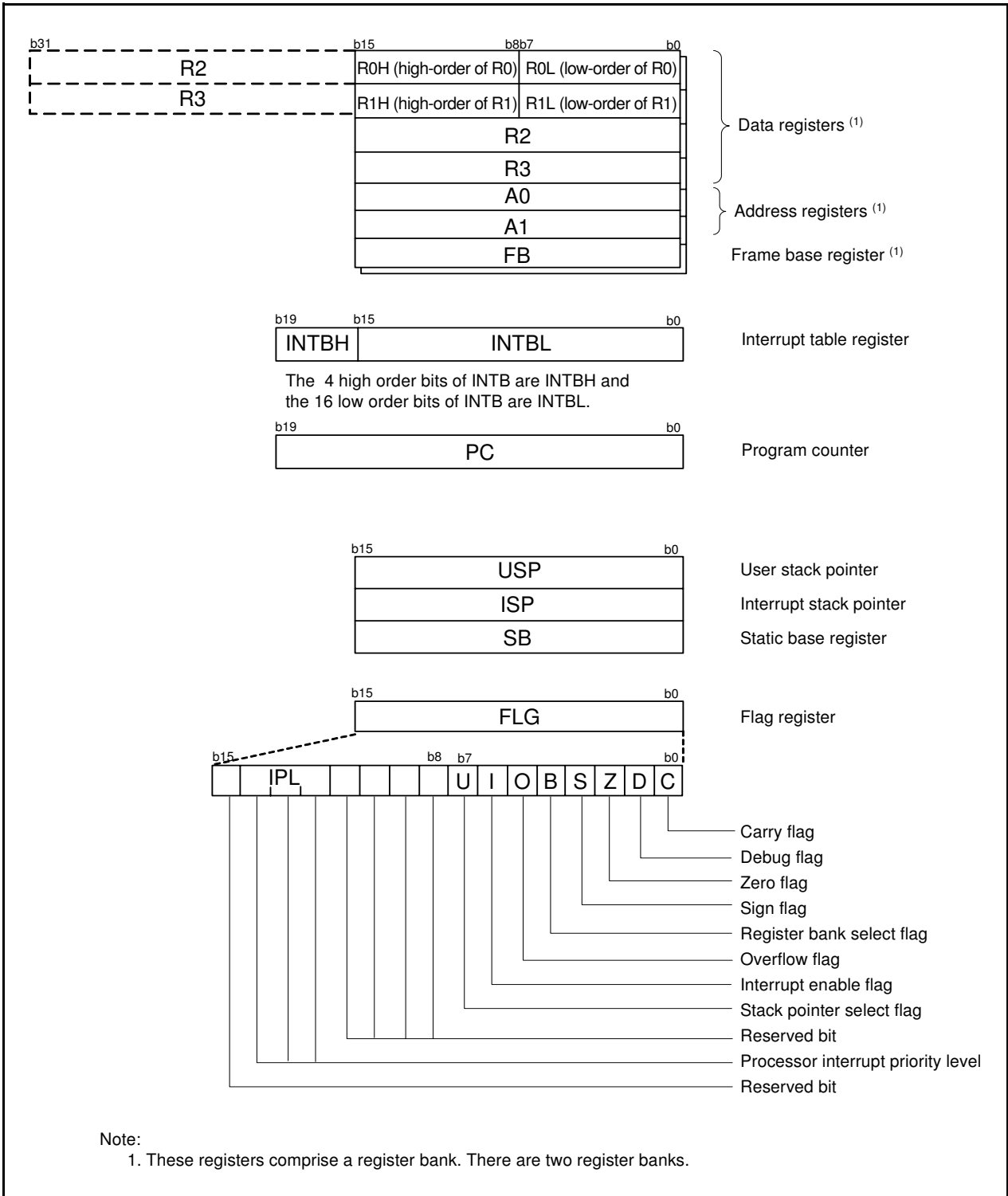


Figure 2.1 CPU Registers

2.1 Data Registers (R0, R1, R2, and R3)

R0 is a 16-bit register for transfer, arithmetic, and logic operations. The same applies to R1 to R3. R0 can be split into high-order bits (R0H) and low-order bits (R0L) to be used separately as 8-bit data registers. R1H and R1L are analogous to R0H and R0L. R2 can be combined with R0 and used as a 32-bit data register (R2R0). R3R1 is analogous to R2R0.

2.2 Address Registers (A0 and A1)

A0 is a 16-bit register for address register indirect addressing and address register relative addressing. It is also used for transfer, arithmetic, and logic operations. A1 is analogous to A0. A1 can be combined with A0 and as a 32-bit address register (A1A0).

2.3 Frame Base Register (FB)

FB is a 16-bit register for FB relative addressing.

2.4 Interrupt Table Register (INTB)

INTB is a 20-bit register that indicates the starting address of an interrupt vector table.

2.5 Program Counter (PC)

PC is 20 bits wide and indicates the address of the next instruction to be executed.

2.6 User Stack Pointer (USP) and Interrupt Stack Pointer (ISP)

The stack pointers (SP), USP and ISP, are each 16 bits wide. The U flag of FLG is used to switch between USP and ISP.

2.7 Static Base Register (SB)

SB is a 16-bit register for SB relative addressing.

2.8 Flag Register (FLG)

FLG is an 11-bit register indicating the CPU state.

2.8.1 Carry Flag (C)

The C flag retains carry, borrow, or shift-out bits that have been generated by the arithmetic and logic unit.

2.8.2 Debug Flag (D)

The D flag is for debugging only. Set it to 0.

2.8.3 Zero Flag (Z)

The Z flag is set to 1 when an arithmetic operation results in 0; otherwise to 0.

2.8.4 Sign Flag (S)

The S flag is set to 1 when an arithmetic operation results in a negative value; otherwise to 0.

2.8.5 Register Bank Select Flag (B)

Register bank 0 is selected when the B flag is 0. Register bank 1 is selected when this flag is set to 1.

2.8.6 Overflow Flag (O)

The O flag is set to 1 when an operation results in an overflow; otherwise to 0.

2.8.7 Interrupt Enable Flag (I)

The I flag enables maskable interrupts.

Interrupts are disabled when the I flag is set to 0, and are enabled when the I flag is set to 1. The I flag is set to 0 when an interrupt request is acknowledged.

2.8.8 Stack Pointer Select Flag (U)

ISP is selected when the U flag is set to 0; USP is selected when the U flag is set to 1.

The U flag is set to 0 when a hardware interrupt request is acknowledged or the INT instruction of software interrupt numbers 0 to 31 is executed.

2.8.9 Processor Interrupt Priority Level (IPL)

IPL is 3 bits wide and assigns processor interrupt priority levels from level 0 to level 7.

If a requested interrupt has higher priority than IPL, the interrupt is enabled.

2.8.10 Reserved Bit

If necessary, set to 0. When read, the content is undefined.

3. Memory

3.1 R8C/32D Group

Figure 3.1 is a Memory Map of R8C/32D Group. The R8C/32D Group has a 1-Mbyte address space from addresses 00000h to FFFFFh. The internal ROM (program ROM) is allocated lower addresses, beginning with address 0FFFFh. For example, a 16-Kbyte internal ROM area is allocated addresses 0C000h to 0FFFFh.

The fixed interrupt vector table is allocated addresses 0FFDCh to 0FFFFh. The starting address of each interrupt routine is stored here.

The internal RAM is allocated higher addresses, beginning with address 00400h. For example, a 1-Kbyte internal RAM area is allocated addresses 00400h to 007FFh. The internal RAM is used not only for data storage but also as a stack area when a subroutine is called or when an interrupt request is acknowledged.

Special function registers (SFRs) are allocated addresses 00000h to 002FFh. Peripheral function control registers are allocated here. All unallocated spaces within the SFRs are reserved and cannot be accessed by users.

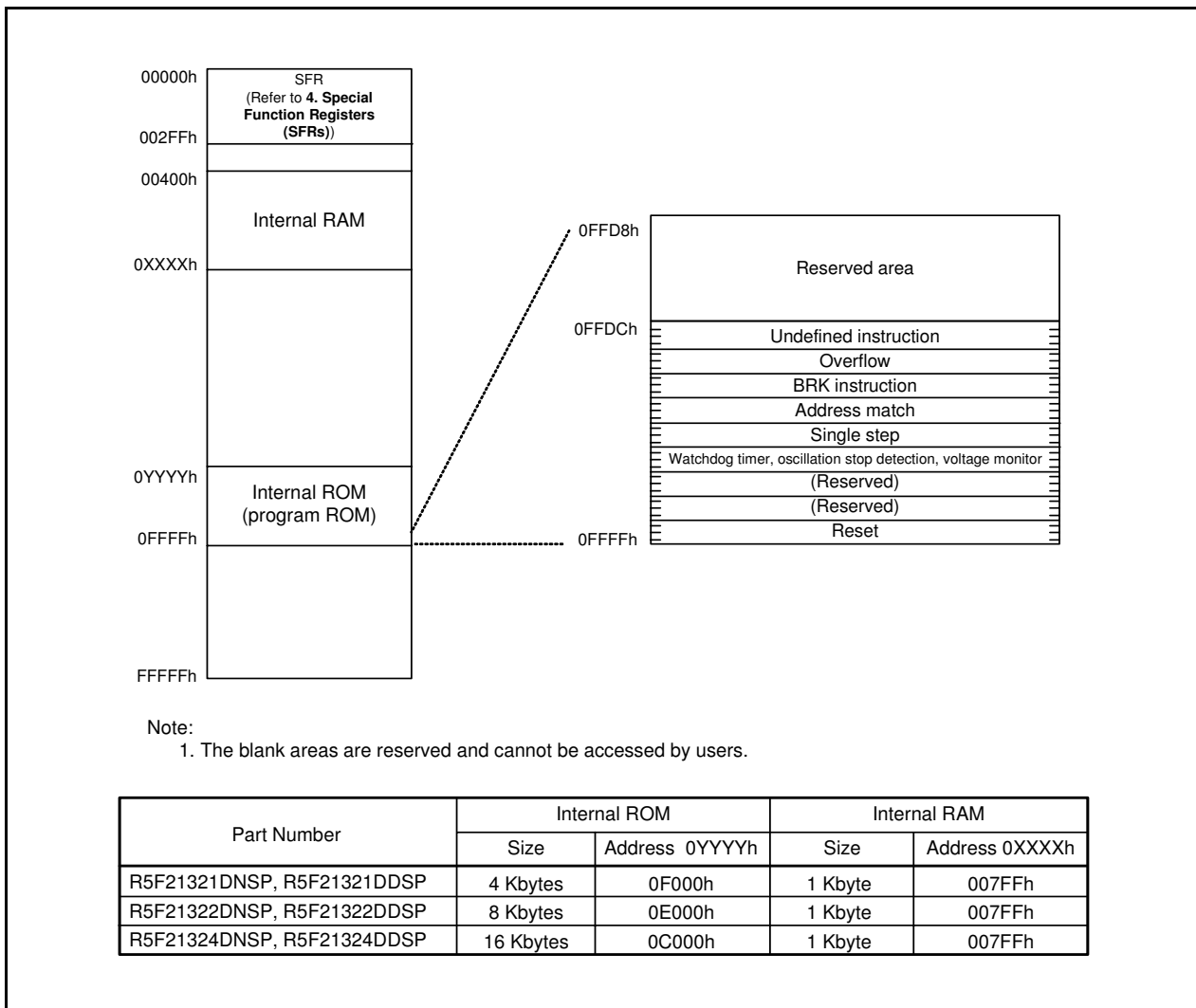


Figure 3.1 Memory Map of R8C/32D Group

4. Special Function Registers (SFRs)

An SFR (special function register) is a control register for a peripheral function. Tables 4.1 to 4.8 list the special function registers and Table 4.9 lists the ID Code Areas and Option Function Select Area.

Table 4.1 SFR Information (1) (1)

| Address | Register | Symbol | After Reset |
|---------|--|----------|--------------------------------|
| 0000h | | | |
| 0001h | | | |
| 0002h | | | |
| 0003h | | | |
| 0004h | Processor Mode Register 0 | PM0 | 00h |
| 0005h | Processor Mode Register 1 | PM1 | 00h |
| 0006h | System Clock Control Register 0 | CM0 | 00101000b |
| 0007h | System Clock Control Register 1 | CM1 | 00100000b |
| 0008h | Module Standby Control Register | MSTCR | 00h |
| 0009h | System Clock Control Register 3 | CM3 | 00h |
| 000Ah | Protect Register | PRCR | 00h |
| 000Bh | Reset Source Determination Register | RSTFR | 0XXXXXXb (2) |
| 000Ch | Oscillation Stop Detection Register | OCD | 00000100b |
| 000Dh | Watchdog Timer Reset Register | WDTR | XXh |
| 000Eh | Watchdog Timer Start Register | WDTS | XXh |
| 000Fh | Watchdog Timer Control Register | WDTC | 00111111b |
| 0010h | | | |
| 0011h | | | |
| 0012h | | | |
| 0013h | | | |
| 0014h | | | |
| 0015h | High-Speed On-Chip Oscillator Control Register 7 | FRA7 | When shipping |
| 0016h | | | |
| 0017h | | | |
| 0018h | | | |
| 0019h | | | |
| 001Ah | | | |
| 001Bh | | | |
| 001Ch | Count Source Protection Mode Register | CSPR | 00h 10000000b (3) |
| 001Dh | | | |
| 001Eh | | | |
| 001Fh | | | |
| 0020h | | | |
| 0021h | | | |
| 0022h | | | |
| 0023h | High-Speed On-Chip Oscillator Control Register 0 | FRA0 | 00h |
| 0024h | High-Speed On-Chip Oscillator Control Register 1 | FRA1 | When shipping |
| 0025h | High-Speed On-Chip Oscillator Control Register 2 | FRA2 | 00h |
| 0026h | On-Chip Reference Voltage Control Register | OCVREFCR | 00h |
| 0027h | | | |
| 0028h | Clock Prescaler Reset Flag | CPSRF | 00h |
| 0029h | High-Speed On-Chip Oscillator Control Register 4 | FRA4 | When Shipping |
| 002Ah | High-Speed On-Chip Oscillator Control Register 5 | FRA5 | When Shipping |
| 002Bh | High-Speed On-Chip Oscillator Control Register 6 | FRA6 | When Shipping |
| 002Ch | | | |
| 002Dh | | | |
| 002Eh | | | |
| 002Fh | High-Speed On-Chip Oscillator Control Register 3 | FRA3 | When shipping |
| 0030h | Voltage Monitor Circuit Control Register | CMPA | 00h |
| 0031h | Voltage Monitor Circuit Edge Select Register | VCAC | 00h |
| 0032h | | | |
| 0033h | Voltage Detect Register 1 | VCA1 | 00001000b |
| 0034h | Voltage Detect Register 2 | VCA2 | 00h (4) 00100000b (5) |
| 0035h | | | |
| 0036h | Voltage Detection 1 Level Select Register | VD1LS | 00000111b |
| 0037h | | | |
| 0038h | Voltage Monitor 0 Circuit Control Register | VW0C | 1100X010b (4) 1100X011b (5) |
| 0039h | Voltage Monitor 1 Circuit Control Register | VW1C | 10001010b |

X: Undefined

Notes:

1. The blank areas are reserved and cannot be accessed by users.
2. The CWR bit in the RSTFR register is set to 0 after power-on and voltage monitor 0 reset. Hardware reset, software reset, or watchdog timer reset does not affect this bit.
3. The CSPROINI bit in the OFS register is set to 0.
4. The LVDAS bit in the OFS register is set to 1.
5. The LVDAS bit in the OFS register is set to 0.

Table 4.2 SFR Information (2) (1)

| Address | Register | Symbol | After Reset |
|---------|--|---------|-------------|
| 003Ah | Voltage Monitor 2 Circuit Control Register | VW2C | 1000010b |
| 003Bh | | | |
| 003Ch | | | |
| 003Dh | | | |
| 003Eh | | | |
| 003Fh | | | |
| 0040h | | | |
| 0041h | Flash Memory Ready Interrupt Control Register | FMRDYIC | XXXXX000b |
| 0042h | | | |
| 0043h | | | |
| 0044h | | | |
| 0045h | | | |
| 0046h | | | |
| 0047h | Timer RC Interrupt Control Register | TRCIC | XXXXX000b |
| 0048h | | | |
| 0049h | | | |
| 004Ah | Timer RE Interrupt Control Register | TREIC | XXXXX000b |
| 004Bh | UART2 Transmit Interrupt Control Register | S2TIC | XXXXX000b |
| 004Ch | UART2 Receive Interrupt Control Register | S2RIC | XXXXX000b |
| 004Dh | Key Input Interrupt Control Register | KUPIC | XXXXX000b |
| 004Eh | A/D Conversion Interrupt Control Register | ADIC | XXXXX000b |
| 004Fh | | | |
| 0050h | | | |
| 0051h | UART0 Transmit Interrupt Control Register | S0TIC | XXXXX000b |
| 0052h | UART0 Receive Interrupt Control Register | S0RIC | XXXXX000b |
| 0053h | | | |
| 0054h | | | |
| 0055h | | | |
| 0056h | Timer RA Interrupt Control Register | TRAIC | XXXXX000b |
| 0057h | | | |
| 0058h | Timer RB Interrupt Control Register | TRBIC | XXXXX000b |
| 0059h | INT1 Interrupt Control Register | INT1IC | XX00X000b |
| 005Ah | INT3 Interrupt Control Register | INT3IC | XX00X000b |
| 005Bh | | | |
| 005Ch | | | |
| 005Dh | INT0 Interrupt Control Register | INT0IC | XX00X000b |
| 005Eh | UART2 Bus Collision Detection Interrupt Control Register | U2BCNIC | XXXXX000b |
| 005Fh | | | |
| 0060h | | | |
| 0061h | | | |
| 0062h | | | |
| 0063h | | | |
| 0064h | | | |
| 0065h | | | |
| 0066h | | | |
| 0067h | | | |
| 0068h | | | |
| 0069h | | | |
| 006Ah | | | |
| 006Bh | | | |
| 006Ch | | | |
| 006Dh | | | |
| 006Eh | | | |
| 006Fh | | | |
| 0070h | | | |
| 0071h | | | |
| 0072h | Voltage Monitor 1 Interrupt Control Register | VCMP1IC | XXXXX000b |
| 0073h | Voltage Monitor 2 Interrupt Control Register | VCMP2IC | XXXXX000b |
| 0074h | | | |
| 0075h | | | |
| 0076h | | | |
| 0077h | | | |
| 0078h | | | |
| 0079h | | | |
| 007Ah | | | |
| 007Bh | | | |
| 007Ch | | | |
| 007Dh | | | |
| 007Eh | | | |
| 007Fh | | | |

X: Undefined

Note:

1. The blank areas are reserved and cannot be accessed by users.

Table 4.3 SFR Information (3) (1)

| Address | Register | Symbol | After Reset |
|---------|---|--------|-------------|
| 0080h | | | |
| 0081h | | | |
| 0082h | | | |
| 0083h | | | |
| 0084h | | | |
| 0085h | | | |
| 0086h | | | |
| 0087h | | | |
| 0088h | | | |
| 0089h | | | |
| 008Ah | | | |
| 008Bh | | | |
| 008Ch | | | |
| 008Dh | | | |
| 008Eh | | | |
| 008Fh | | | |
| 0090h | | | |
| 0091h | | | |
| 0092h | | | |
| 0093h | | | |
| 0094h | | | |
| 0095h | | | |
| 0096h | | | |
| 0097h | | | |
| 0098h | | | |
| 0099h | | | |
| 009Ah | | | |
| 009Bh | | | |
| 009Ch | | | |
| 009Dh | | | |
| 009Eh | | | |
| 009Fh | | | |
| 00A0h | UART0 Transmit / Receive Mode Register | U0MR | 00h |
| 00A1h | UART0 Bit Rate Register | U0BRG | XXh |
| 00A2h | UART0 Transmit Buffer Register | U0TB | XXh |
| 00A3h | | | XXh |
| 00A4h | UART0 Transmit / Receive Control Register 0 | U0C0 | 00001000b |
| 00A5h | UART0 Transmit / Receive Control Register 1 | U0C1 | 00000010b |
| 00A6h | UART0 Receive Buffer Register | U0RB | XXh |
| 00A7h | | | XXh |
| 00A8h | UART2 Transmit / Receive Mode Register | U2MR | 00h |
| 00A9h | UART2 Bit Rate Register | U2BRG | XXh |
| 00AAh | UART2 Transmit Buffer Register | U2TB | XXh |
| 00ABh | | | XXh |
| 00ACh | UART2 Transmit / Receive Control Register 0 | U2C0 | 00001000b |
| 00ADh | UART2 Transmit / Receive Control Register 1 | U2C1 | 00000010b |
| 00AEh | UART2 Receive Buffer Register | U2RB | XXh |
| 00AFh | | | XXh |
| 00B0h | UART2 Digital Filter Function Select Register | URXDF | 00h |
| 00B1h | | | |
| 00B2h | | | |
| 00B3h | | | |
| 00B4h | | | |
| 00B5h | | | |
| 00B6h | | | |
| 00B7h | | | |
| 00B8h | | | |
| 00B9h | | | |
| 00BAh | | | |
| 00BBh | UART2 Special Mode Register 5 | U2SMR5 | 00h |
| 00BCh | UART2 Special Mode Register 4 | U2SMR4 | 00h |
| 00BDh | UART2 Special Mode Register 3 | U2SMR3 | 000X0X0Xb |
| 00BEh | UART2 Special Mode Register 2 | U2SMR2 | X0000000b |
| 00BFh | UART2 Special Mode Register | U2SMR | X0000000b |

X: Undefined

Note:

1. The blank areas are reserved and cannot be accessed by users.

Table 4.4 SFR Information (4) (1)

| Address | Register | Symbol | After Reset |
|---------|----------------------------|---------|-------------|
| 00C0h | A/D Register 0 | AD0 | XXh |
| 00C1h | | | 000000XXb |
| 00C2h | A/D Register 1 | AD1 | XXh |
| 00C3h | | | 000000XXb |
| 00C4h | A/D Register 2 | AD2 | XXh |
| 00C5h | | | 000000XXb |
| 00C6h | A/D Register 3 | AD3 | XXh |
| 00C7h | | | 000000XXb |
| 00C8h | A/D Register 4 | AD4 | XXh |
| 00C9h | | | 000000XXb |
| 00CAh | A/D Register 5 | AD5 | XXh |
| 00CBh | | | 000000XXb |
| 00CCh | A/D Register 6 | AD6 | XXh |
| 00CDh | | | 000000XXb |
| 00CEh | A/D Register 7 | AD7 | XXh |
| 00CFh | | | 000000XXb |
| 00D0h | | | |
| 00D1h | | | |
| 00D2h | | | |
| 00D3h | | | |
| 00D4h | A/D Mode Register | ADMOD | 00h |
| 00D5h | A/D Input Select Register | ADINSEL | 11000000b |
| 00D6h | A/D Control Register 0 | ADCON0 | 00h |
| 00D7h | A/D Control Register 1 | ADCON1 | 00h |
| 00D8h | | | |
| 00D9h | | | |
| 00DAh | | | |
| 00DBh | | | |
| 00DCh | | | |
| 00DDh | | | |
| 00DEh | | | |
| 00DFh | | | |
| 00E0h | | | |
| 00E1h | Port P1 Register | P1 | XXh |
| 00E2h | | | |
| 00E3h | Port P1 Direction Register | PD1 | 00h |
| 00E4h | | | |
| 00E5h | Port P3 Register | P3 | XXh |
| 00E6h | | | |
| 00E7h | Port P3 Direction Register | PD3 | 00h |
| 00E8h | Port P4 Register | P4 | XXh |
| 00E9h | | | |
| 00EAh | Port P4 Direction Register | PD4 | 00h |
| 00EBh | | | |
| 00ECh | | | |
| 00EDh | | | |
| 00EEh | | | |
| 00EFh | | | |
| 00F0h | | | |
| 00F1h | | | |
| 00F2h | | | |
| 00F3h | | | |
| 00F4h | | | |
| 00F5h | | | |
| 00F6h | | | |
| 00F7h | | | |
| 00F8h | | | |
| 00F9h | | | |
| 00FAh | | | |
| 00FBh | | | |
| 00FCh | | | |
| 00FDh | | | |
| 00FEh | | | |
| 00FFh | | | |

X: Undefined

Note:

1. The blank areas are reserved and cannot be accessed by users.

Table 4.5 SFR Information (5) (1)

| Address | Register | Symbol | After Reset |
|---------|--|---------|-------------|
| 0100h | Timer RA Control Register | TRACR | 00h |
| 0101h | Timer RA I/O Control Register | TRAIOC | 00h |
| 0102h | Timer RA Mode Register | TRAMR | 00h |
| 0103h | Timer RA Prescaler Register | TRAPRE | FFh |
| 0104h | Timer RA Register | TRA | FFh |
| 0105h | | | |
| 0106h | | | |
| 0107h | | | |
| 0108h | Timer RB Control Register | TRBCR | 00h |
| 0109h | Timer RB One-Shot Control Register | TRBOCR | 00h |
| 010Ah | Timer RB I/O Control Register | TRBIOC | 00h |
| 010Bh | Timer RB Mode Register | TRBMR | 00h |
| 010Ch | Timer RB Prescaler Register | TRBPRE | FFh |
| 010Dh | Timer RB Secondary Register | TRBSC | FFh |
| 010Eh | Timer RB Primary Register | TRBPR | FFh |
| 010Fh | | | |
| 0110h | | | |
| 0111h | | | |
| 0112h | | | |
| 0113h | | | |
| 0114h | | | |
| 0115h | | | |
| 0116h | | | |
| 0117h | | | |
| 0118h | Timer RE Second Data Register | TRESEC | 00h |
| 0119h | Timer RE Minute Data Register | TREMIN | 00h |
| 011Ah | Timer RE Hour Data Register | TREHR | 00h |
| 011Bh | Timer RE Day of Week Data Register | TREWK | 00h |
| 011Ch | Timer RE Control Register 1 | TRECR1 | 00h |
| 011Dh | Timer RE Control Register 2 | TRECR2 | 00h |
| 011Eh | Timer RE Count Source Select Register | TRECSR | 00001000b |
| 011Fh | | | |
| 0120h | Timer RC Mode Register | TRCMR | 01001000b |
| 0121h | Timer RC Control Register 1 | TRCCR1 | 00h |
| 0122h | Timer RC Interrupt Enable Register | TRCIER | 01110000b |
| 0123h | Timer RC Status Register | TRCSR | 01110000b |
| 0124h | Timer RC I/O Control Register 0 | TRCIOR0 | 10001000b |
| 0125h | Timer RC I/O Control Register 1 | TRCIOR1 | 10001000b |
| 0126h | Timer RC Counter | TRC | 00h |
| 0127h | | | 00h |
| 0128h | Timer RC General Register A | TRCGRA | FFh |
| 0129h | | | FFh |
| 012Ah | Timer RC General Register B | TRCGRB | FFh |
| 012Bh | | | FFh |
| 012Ch | Timer RC General Register C | TRCGRC | FFh |
| 012Dh | | | FFh |
| 012Eh | Timer RC General Register D | TRCGRD | FFh |
| 012Fh | | | FFh |
| 0130h | Timer RC Control Register 2 | TRCCR2 | 00011000b |
| 0131h | Timer RC Digital Filter Function Select Register | TRCDF | 00h |
| 0132h | Timer RC Output Master Enable Register | TRCOER | 01111111b |
| 0133h | Timer RC Trigger Control Register | TRCADCR | 00h |
| 0134h | | | |
| 0135h | | | |
| 0136h | | | |
| 0137h | | | |
| 0138h | | | |
| 0139h | | | |
| 013Ah | | | |
| 013Bh | | | |
| 013Ch | | | |
| 013Dh | | | |
| 013Eh | | | |
| 013Fh | | | |

Note:

- The blank areas are reserved and cannot be accessed by users.

Table 4.6 SFR Information (6) (1)

| Address | Register | Symbol | After Reset |
|---------|----------|--------|-------------|
| 0140h | | | |
| 0141h | | | |
| 0142h | | | |
| 0143h | | | |
| 0144h | | | |
| 0145h | | | |
| 0146h | | | |
| 0147h | | | |
| 0148h | | | |
| 0149h | | | |
| 014Ah | | | |
| 014Bh | | | |
| 014Ch | | | |
| 014Dh | | | |
| 014Eh | | | |
| 014Fh | | | |
| 0150h | | | |
| 0151h | | | |
| 0152h | | | |
| 0153h | | | |
| 0154h | | | |
| 0155h | | | |
| 0156h | | | |
| 0157h | | | |
| 0158h | | | |
| 0159h | | | |
| 015Ah | | | |
| 015Bh | | | |
| 015Ch | | | |
| 015Dh | | | |
| 015Eh | | | |
| 015Fh | | | |
| 0160h | | | |
| 0161h | | | |
| 0162h | | | |
| 0163h | | | |
| 0164h | | | |
| 0165h | | | |
| 0166h | | | |
| 0167h | | | |
| 0168h | | | |
| 0169h | | | |
| 016Ah | | | |
| 016Bh | | | |
| 016Ch | | | |
| 016Dh | | | |
| 016Eh | | | |
| 016Fh | | | |
| 0170h | | | |
| 0171h | | | |
| 0172h | | | |
| 0173h | | | |
| 0174h | | | |
| 0175h | | | |
| 0176h | | | |
| 0177h | | | |
| 0178h | | | |
| 0179h | | | |
| 017Ah | | | |
| 017Bh | | | |
| 017Ch | | | |
| 017Dh | | | |
| 017Eh | | | |
| 017Fh | | | |

X: Undefined

Note:

1. The blank areas are reserved and cannot be accessed by users.

Table 4.7 SFR Information (7) (1)

| Address | Register | Symbol | After Reset |
|---------|---|---------|-------------|
| 0180h | Timer RA Pin Select Register | TRASR | 00h |
| 0181h | Timer RC Pin Select Register | TRBRCSR | 00h |
| 0182h | Timer RC Pin Select Register 0 | TRCPSR0 | 00h |
| 0183h | Timer RC Pin Select Register 1 | TRCPSR1 | 00h |
| 0184h | | | |
| 0185h | | | |
| 0186h | | | |
| 0187h | | | |
| 0188h | UART0 Pin Select Register | U0SR | 00h |
| 0189h | | | |
| 018Ah | UART2 Pin Select Register 0 | U2SR0 | 00h |
| 018Bh | UART2 Pin Select Register 1 | U2SR1 | 00h |
| 018Ch | | | |
| 018Dh | | | |
| 018Eh | INT Interrupt Input Pin Select Register | INTSR | 00h |
| 018Fh | I/O Function Pin Select Register | PINSR | 00h |
| 0190h | | | |
| 0191h | | | |
| 0192h | | | |
| 0193h | | | |
| 0194h | | | |
| 0195h | | | |
| 0196h | | | |
| 0197h | | | |
| 0198h | | | |
| 0199h | | | |
| 019Ah | | | |
| 019Bh | | | |
| 019Ch | | | |
| 019Dh | | | |
| 019Eh | | | |
| 019Fh | | | |
| 01A0h | | | |
| 01A1h | | | |
| 01A2h | | | |
| 01A3h | | | |
| 01A4h | | | |
| 01A5h | | | |
| 01A6h | | | |
| 01A7h | | | |
| 01A8h | | | |
| 01A9h | | | |
| 01AAh | | | |
| 01ABh | | | |
| 01ACh | | | |
| 01ADh | | | |
| 01AEh | | | |
| 01AFh | | | |
| 01B0h | | | |
| 01B1h | | | |
| 01B2h | Flash Memory Status Register | FST | 10000X00b |
| 01B3h | | | |
| 01B4h | Flash Memory Control Register 0 | FMR0 | 00h |
| 01B5h | Flash Memory Control Register 1 | FMR1 | 00h |
| 01B6h | Flash Memory Control Register 2 | FMR2 | 00h |
| 01B7h | | | |
| 01B8h | | | |
| 01B9h | | | |
| 01BAh | | | |
| 01BBh | | | |
| 01BCh | | | |
| 01BDh | | | |
| 01BEh | | | |
| 01BFh | | | |

X: Undefined

Note:

1. The blank areas are reserved and cannot be accessed by users.

Table 4.8 SFR Information (8) (1)

| Address | Register | Symbol | After Reset |
|---------|---|--------|-------------|
| 01C0h | Address Match Interrupt Register 0 | RMAD0 | XXh |
| 01C1h | | | XXh |
| 01C2h | | | 0000XXXXb |
| 01C3h | Address Match Interrupt Enable Register | AIER | 00h |
| 01C4h | Address Match Interrupt Register 1 | RMAD1 | XXh |
| 01C5h | | | XXh |
| 01C6h | | | 0000XXXXb |
| 01C7h | | | |
| 01C8h | | | |
| 01C9h | | | |
| 01CAh | | | |
| 01CBh | | | |
| 01CCh | | | |
| 01CDh | | | |
| 01CEh | | | |
| 01CFh | | | |
| 01D0h | | | |
| 01D1h | | | |
| 01D2h | | | |
| 01D3h | | | |
| 01D4h | | | |
| 01D5h | | | |
| 01D6h | | | |
| 01D7h | | | |
| 01D8h | | | |
| 01D9h | | | |
| 01DAh | | | |
| 01DBh | | | |
| 01DCh | | | |
| 01DDh | | | |
| 01DEh | | | |
| 01DFh | | | |
| 01E0h | Pull-Up Control Register 0 | PUR0 | 00h |
| 01E1h | Pull-Up Control Register 1 | PUR1 | 00h |
| 01E2h | | | |
| 01E3h | | | |
| 01E4h | | | |
| 01E5h | | | |
| 01E6h | | | |
| 01E7h | | | |
| 01E8h | | | |
| 01E9h | | | |
| 01EAh | | | |
| 01EBh | | | |
| 01ECh | | | |
| 01EDh | | | |
| 01EEh | | | |
| 01EFh | | | |
| 01F0h | Port P1 Drive Capacity Control Register | P1DRR | 00h |
| 01F1h | | | |
| 01F2h | Drive Capacity Control Register 0 | DRR0 | 00h |
| 01F3h | Drive Capacity Control Register 1 | DRR1 | 00h |
| 01F4h | | | |
| 01F5h | Input Threshold Control Register 0 | VLT0 | 00h |
| 01F6h | Input Threshold Control Register 1 | VLT1 | 00h |
| 01F7h | | | |
| 01F8h | Comparator B Control Register 0 | INTCMP | 00h |
| 01F9h | | | |
| 01FAh | External Input Enable Register 0 | INTEN | 00h |
| 01FBh | | | |
| 01FCh | INT Input Filter Select Register 0 | INTF | 00h |
| 01FDh | | | |
| 01FEh | Key Input Enable Register 0 | KIEN | 00h |
| 01FFh | | | |

X: Undefined

Note:

1. The blank areas are reserved and cannot be accessed by users.

Table 4.9 ID Code Areas and Option Function Select Area

| Address | Area Name | Symbol | After Reset |
|---------|-----------------------------------|--------|-------------|
| FFDBh | Option Function Select Register 2 | OFS2 | (Note 1) |
| FFDFh | ID1 | | (Note 2) |
| FFE3h | ID2 | | (Note 2) |
| FFEBh | ID3 | | (Note 2) |
| FFEFh | ID4 | | (Note 2) |
| FFF3h | ID5 | | (Note 2) |
| FFF7h | ID6 | | (Note 2) |
| FFFBh | ID7 | | (Note 2) |
| FFFFh | Option Function Select Register | OFS | (Note 1) |

Notes:

1. The option function select area is allocated in the flash memory, not in the SFRs. Set appropriate values as ROM data by a program. Do not write additions to the option function select area. If the block including the option function select area is erased, the option function select area is set to FFh.
When blank products are shipped, the option function select area is set to FFh. It is set to the written value after written by the user.
When factory-programming products are shipped, the value of the option function select area is the value programmed by the user.
2. The ID code areas are allocated in the flash memory, not in the SFRs. Set appropriate values as ROM data by a program. Do not write additions to the ID code areas. If the block including the ID code areas is erased, the ID code areas are set to FFh.
When blank products are shipped, the ID code areas are set to FFh. They are set to the written value after written by the user.
When factory-programming products are shipped, the value of the ID code areas is the value programmed by the user.

5. Electrical Characteristics

Table 5.1 Absolute Maximum Ratings

| Symbol | Parameter | Condition | Rated Value | Unit |
|-----------------------------------|-------------------------------|---------------------------------|--|------|
| V _{CC} /AV _{CC} | Supply voltage | | -0.3 to 6.5 | V |
| V _I | Input voltage | | -0.3 to V _{CC} + 0.3 | V |
| V _O | Output voltage | | -0.3 to V _{CC} + 0.3 | V |
| P _d | Power dissipation | -40°C ≤ T _{opr} ≤ 85°C | 500 | mW |
| T _{opr} | Operating ambient temperature | | -20 to 85 (N version) / -40 to 85 (D version) | °C |
| T _{stg} | Storage temperature | | -65 to 150 | °C |

Table 5.2 Recommended Operating Conditions

| Symbol | Parameter | | Conditions | Standard | | | Unit | | |
|-----------------------------------|---|---------------------------------------|---|--|---------------------------------|----------------------|----------------------|----------------------|---|
| | | | | Min. | Typ. | Max. | | | |
| V _{CC} /AV _{CC} | Supply voltage | | | 1.8 | – | 5.5 | V | | |
| V _{SS} /AV _{SS} | Supply voltage | | | – | 0 | – | V | | |
| V _{IH} | Input “H” voltage | Other than CMOS input | | | 0.8 V _{CC} | – | V _{CC} | V | |
| | | CMOS input | Input level switching function (I/O port) | Input level selection : 0.35 V _{CC} | 4.0 V ≤ V _{CC} ≤ 5.5 V | 0.5 V _{CC} | – | V _{CC} | V |
| | | | | | 2.7 V ≤ V _{CC} < 4.0 V | 0.55 V _{CC} | – | V _{CC} | V |
| | | | | | 1.8 V ≤ V _{CC} < 2.7 V | 0.65 V _{CC} | – | V _{CC} | V |
| | | | Input level selection : 0.5 V _{CC} | | 4.0 V ≤ V _{CC} ≤ 5.5 V | 0.65 V _{CC} | – | V _{CC} | V |
| | | | | 2.7 V ≤ V _{CC} < 4.0 V | 0.7 V _{CC} | – | V _{CC} | V | |
| | | | | 1.8 V ≤ V _{CC} < 2.7 V | 0.8 V _{CC} | – | V _{CC} | V | |
| | | | Input level selection : 0.7 V _{CC} | | 4.0 V ≤ V _{CC} ≤ 5.5 V | 0.85 V _{CC} | – | V _{CC} | V |
| | | | | 2.7 V ≤ V _{CC} < 4.0 V | 0.85 V _{CC} | – | V _{CC} | V | |
| | | | | 1.8 V ≤ V _{CC} < 2.7 V | 0.85 V _{CC} | – | V _{CC} | V | |
| | | External clock input (XOUT) | | | 1.2 | – | V _{CC} | V | |
| V _{IL} | Input “L” voltage | Other than CMOS input | | | 0 | – | 0.2 V _{CC} | V | |
| | | CMOS input | Input level switching function (I/O port) | Input level selection : 0.35 V _{CC} | 4.0 V ≤ V _{CC} ≤ 5.5 V | 0 | – | 0.2 V _{CC} | V |
| | | | | | 2.7 V ≤ V _{CC} < 4.0 V | 0 | – | 0.2 V _{CC} | V |
| | | | | | 1.8 V ≤ V _{CC} < 2.7 V | 0 | – | 0.2 V _{CC} | V |
| | | | Input level selection : 0.5 V _{CC} | | 4.0 V ≤ V _{CC} ≤ 5.5 V | 0 | – | 0.4 V _{CC} | V |
| | | | | 2.7 V ≤ V _{CC} < 4.0 V | 0 | – | 0.3 V _{CC} | V | |
| | | | | 1.8 V ≤ V _{CC} < 2.7 V | 0 | – | 0.2 V _{CC} | V | |
| | | | Input level selection : 0.7 V _{CC} | | 4.0 V ≤ V _{CC} ≤ 5.5 V | 0 | – | 0.55 V _{CC} | V |
| | | | | 2.7 V ≤ V _{CC} < 4.0 V | 0 | – | 0.45 V _{CC} | V | |
| | | | | 1.8 V ≤ V _{CC} < 2.7 V | 0 | – | 0.35 V _{CC} | V | |
| | External clock input (XOUT) | | | 0 | – | 0.4 | V | | |
| I _{OH(sum)} | Peak sum output “H” current | Sum of all pins I _{OH(peak)} | | | – | – | –160 | mA | |
| I _{OH(sum)} | Average sum output “H” current | Sum of all pins I _{OH(avg)} | | | – | – | –80 | mA | |
| I _{OH(peak)} | Peak output “H” current | Drive capacity Low | | | – | – | –10 | mA | |
| | | Drive capacity High | | | – | – | –40 | mA | |
| I _{OH(avg)} | Average output “H” current | Drive capacity Low | | | – | – | –5 | mA | |
| | | Drive capacity High | | | – | – | –20 | mA | |
| I _{OL(sum)} | Peak sum output “L” current | Sum of all pins I _{OL(peak)} | | | – | – | 160 | mA | |
| I _{OL(sum)} | Average sum output “L” current | Sum of all pins I _{OL(avg)} | | | – | – | 80 | mA | |
| I _{OL(peak)} | Peak output “L” current | Drive capacity Low | | | – | – | 10 | mA | |
| | | Drive capacity High | | | – | – | 40 | mA | |
| I _{OL(avg)} | Average output “L” current | Drive capacity Low | | | – | – | 5 | mA | |
| | | Drive capacity High | | | – | – | 20 | mA | |
| f _(XIN) | XIN clock input oscillation frequency | 2.7 V ≤ V _{CC} ≤ 5.5 V | | | – | – | 20 | MHz | |
| | | 1.8 V ≤ V _{CC} < 2.7 V | | | – | – | 5 | MHz | |
| f _(XCIN) | XCIN clock input oscillation frequency | 1.8 V ≤ V _{CC} ≤ 5.5 V | | | – | 32.768 | 50 | kHz | |
| f _{OCO40M} | When used as the count source for timer RC ⁽³⁾ | 2.7 V ≤ V _{CC} ≤ 5.5 V | | | 32 | – | 40 | MHz | |
| f _{OCO-F} | f _{OCO-F} frequency | 2.7 V ≤ V _{CC} ≤ 5.5 V | | | – | – | 20 | MHz | |
| | | 1.8 V ≤ V _{CC} < 2.7 V | | | – | – | 5 | MHz | |
| – | System clock frequency | 2.7 V ≤ V _{CC} ≤ 5.5 V | | | – | – | 20 | MHz | |
| | | 1.8 V ≤ V _{CC} < 2.7 V | | | – | – | 5 | MHz | |
| f _(BCLK) | CPU clock frequency | 2.7 V ≤ V _{CC} ≤ 5.5 V | | | – | – | 20 | MHz | |
| | | 1.8 V ≤ V _{CC} < 2.7 V | | | – | – | 5 | MHz | |

Notes:

- V_{CC} = 1.8 to 5.5 V at T_{opr} = –20 to 85°C (N version) / –40 to 85°C (D version), unless otherwise specified.
- The average output current indicates the average value of current measured during 100 ms.
- f_{OCO40M} can be used as the count source for timer RC in the range of V_{CC} = 2.7 V to 5.5V.

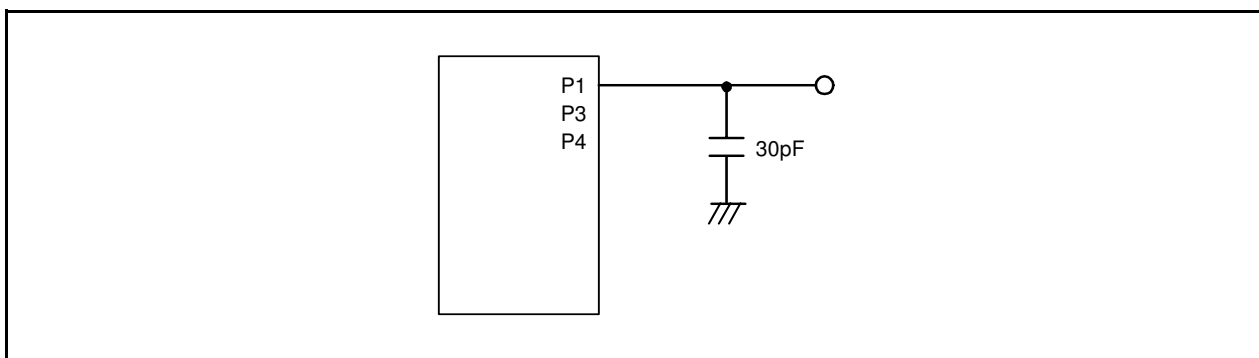


Figure 5.1 Ports P1, P3, P4 Timing Measurement Circuit

Table 5.3 A/D Converter Characteristics

| Symbol | Parameter | | Conditions | Standard | | | Unit |
|-------------------|-------------------------------------|-------------|--|----------|------|-----------|---------------|
| | | | | Min. | Typ. | Max. | |
| – | Resolution | | $V_{ref} = AV_{CC}$ | – | – | 10 | Bit |
| – | Absolute accuracy | 10-bit mode | $V_{ref} = AV_{CC} = 5.0\text{ V}$, AN8 to AN11 input | – | – | ± 3 | LSB |
| | | | $V_{ref} = AV_{CC} = 3.3\text{ V}$, AN8 to AN11 input | – | – | ± 5 | LSB |
| | | | $V_{ref} = AV_{CC} = 3.0\text{ V}$, AN8 to AN11 input | – | – | ± 5 | LSB |
| | | | $V_{ref} = AV_{CC} = 2.2\text{ V}$, AN8 to AN11 input | – | – | ± 5 | LSB |
| | | 8-bit mode | $V_{ref} = AV_{CC} = 5.0\text{ V}$, AN8 to AN11 input | – | – | ± 2 | LSB |
| | | | $V_{ref} = AV_{CC} = 3.3\text{ V}$, AN8 to AN11 input | – | – | ± 2 | LSB |
| | | | $V_{ref} = AV_{CC} = 3.0\text{ V}$, AN8 to AN11 input | – | – | ± 2 | LSB |
| | | | $V_{ref} = AV_{CC} = 2.2\text{ V}$, AN8 to AN11 input | – | – | ± 2 | LSB |
| ϕAD | A/D conversion clock | | $4.0\text{ V} \leq V_{ref} = AV_{CC} \leq 5.5\text{ V}^{(2)}$ | 2 | – | 20 | MHz |
| | | | $3.2\text{ V} \leq V_{ref} = AV_{CC} \leq 5.5\text{ V}^{(2)}$ | 2 | – | 16 | MHz |
| | | | $2.7\text{ V} \leq V_{ref} = AV_{CC} \leq 5.5\text{ V}^{(2)}$ | 2 | – | 10 | MHz |
| | | | $2.2\text{ V} \leq V_{ref} = AV_{CC} \leq 5.5\text{ V}^{(2)}$ | 2 | – | 5 | MHz |
| – | Tolerance level impedance | | | – | 3 | – | k Ω |
| tCONV | Conversion time | 10-bit mode | $V_{ref} = AV_{CC} = 5.0\text{ V}$, $\phi AD = 20\text{ MHz}$ | 2.15 | – | – | μs |
| | | 8-bit mode | $V_{ref} = AV_{CC} = 5.0\text{ V}$, $\phi AD = 20\text{ MHz}$ | 2.15 | – | – | μs |
| tsAMP | Sampling time | | $\phi AD = 20\text{ MHz}$ | 0.75 | – | – | μs |
| I _{Vref} | V _{ref} current | | $V_{CC} = 5\text{ V}$, $XIN = f1 = \phi AD = 20\text{ MHz}$ | – | 45 | – | μA |
| V _{ref} | Reference voltage | | | 2.2 | – | AV_{CC} | V |
| V _{IA} | Analog input voltage ⁽³⁾ | | | 0 | – | V_{ref} | V |
| OCVREF | On-chip reference voltage | | $2\text{ MHz} \leq \phi AD \leq 4\text{ MHz}$ | 1.19 | 1.34 | 1.49 | V |

Notes:

- $V_{CC}/AV_{CC} = V_{ref} = 2.2$ to 5.5 V , $V_{SS} = 0\text{ V}$ at $T_{opr} = -20$ to 85°C (N version) / -40 to 85°C (D version), unless otherwise specified.
- The A/D conversion result will be undefined in wait mode, stop mode, when the flash memory stops, and in low-current-consumption mode. Do not perform A/D conversion in these states or transition to these states during A/D conversion.
- When the analog input voltage is over the reference voltage, the A/D conversion result will be 3FFh in 10-bit mode and FFh in 8-bit mode.

Table 5.4 Comparator B Electrical Characteristics

| Symbol | Parameter | Condition | Standard | | | Unit | |
|------------------|---|-----------|-----------------------------------|------|----------------|-------|---------------|
| | | | Min. | Typ. | Max. | | |
| V _{ref} | IVREF1, IVREF3 input reference voltage | | 0 | – | $V_{CC} - 1.4$ | V | |
| V _I | IVCMP1, IVCMP3 input voltage | | -0.3 | – | $V_{CC} + 0.3$ | V | |
| – | Offset | | – | 5 | 100 | mV | |
| t _d | Comparator output delay time ⁽²⁾ | | $V_I = V_{ref} \pm 100\text{ mV}$ | | – | 0.1 | μs |
| I _{CMP} | Comparator operating current | | $V_{CC} = 5.0\text{ V}$ | | – | 17.5 | μA |

Notes:

- $V_{CC} = 2.7$ to 5.5 V , $T_{opr} = -20$ to 85°C (N version) / -40 to 85°C (D version), unless otherwise specified.
- When the digital filter is disabled.

Table 5.5 Flash Memory (Program ROM) Electrical Characteristics

| Symbol | Parameter | Conditions | Standard | | | Unit |
|-------------------------------|---|----------------------------|----------------------|------|-----------------------------|-------|
| | | | Min. | Typ. | Max. | |
| – | Program/erase endurance ⁽²⁾ | | 1,000 ⁽³⁾ | – | – | times |
| – | Byte program time | | – | 80 | 500 | μs |
| – | Block erase time | | – | 0.3 | – | s |
| t _d (SR-SUS) | Time delay from suspend request until suspend | | – | – | 5 + CPU clock × 3 cycles | ms |
| – | Interval from erase start/restart until following suspend request | | 0 | – | – | μs |
| – | Time from suspend until erase restart | | – | – | 30 + CPU clock × 1 cycle | μs |
| t _d (CMDRST-READY) | Time from when command is forcibly stopped until reading is enabled | | – | – | 30+CPU clock × 1 cycle | μs |
| – | Program, erase voltage | | 2.7 | – | 5.5 | V |
| – | Read voltage | | 1.8 | – | 5.5 | V |
| – | Program, erase temperature | | 0 | – | 60 | °C |
| – | Data hold time ⁽⁷⁾ | Ambient temperature = 55°C | 20 | – | – | year |

Notes:

- V_{CC} = 2.7 to 5.5 V at T_{opr} = 0 to 60°C, unless otherwise specified.
- Definition of programming/erasure endurance
The programming and erasure endurance is defined on a per-block basis.
If the programming and erasure endurance is n (n = 1,000), each block can be erased n times. For example, if 1,024 1-byte writes are performed to different addresses in block A, a 1 Kbyte block, and then the block is erased, the programming/erasure endurance still stands at one.
However, the same address must not be programmed more than once per erase operation (overwriting prohibited).
- Endurance to guarantee all electrical characteristics after program and erase. (1 to Min. value can be guaranteed).
- In a system that executes multiple programming operations, the actual erasure count can be reduced by writing to sequential addresses in turn so that as much of the block as possible is used up before performing an erase operation. For example, when programming groups of 16 bytes, the effective number of rewrites can be minimized by programming up to 128 groups before erasing them all in one operation. It is also advisable to retain data on the erasure endurance of each block and limit the number of erase operations to a certain number.
- If an error occurs during block erase, attempt to execute the clear status register command, then execute the block erase command at least three times until the erase error does not occur.
- Customers desiring program/erase failure rate information should contact their Renesas technical support representative.
- The data hold time includes time that the power supply is off or the clock is not supplied.

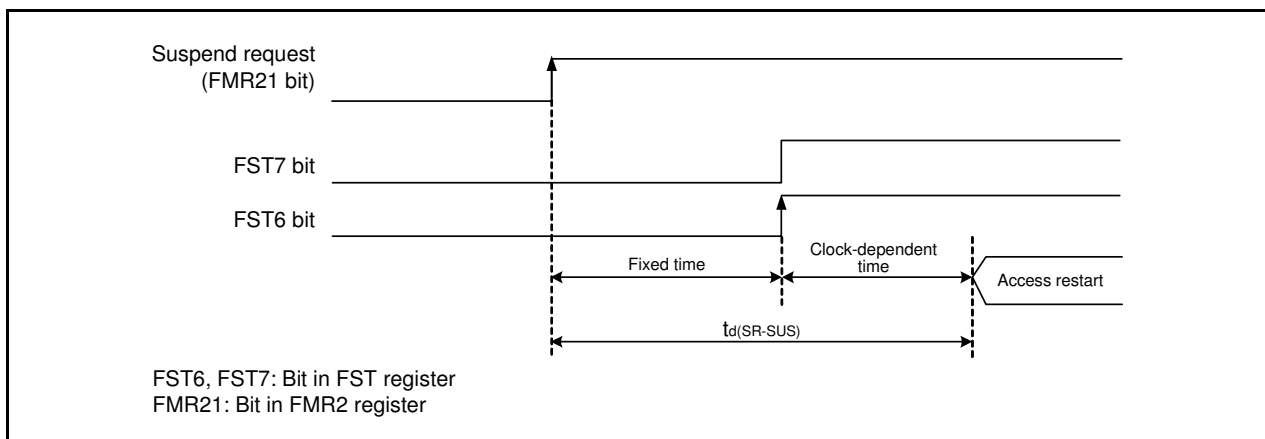
**Figure 5.2 Time delay until Suspend**

Table 5.6 Voltage Detection 0 Circuit Electrical Characteristics

| Symbol | Parameter | Condition | Standard | | | Unit |
|---------------------|---|---|----------|------|------|------|
| | | | Min. | Typ. | Max. | |
| Vdet0 | Voltage detection level Vdet0_0 (2) | | 1.80 | 1.90 | 2.05 | V |
| | Voltage detection level Vdet0_1 (2) | | 2.15 | 2.35 | 2.50 | V |
| | Voltage detection level Vdet0_2 (2) | | 2.70 | 2.85 | 3.05 | V |
| | Voltage detection level Vdet0_3 (2) | | 3.55 | 3.80 | 4.05 | V |
| – | Voltage detection 0 circuit response time (4) | At the falling of Vcc from 5 V to (Vdet0_0 – 0.1) V | – | 6 | 150 | μs |
| – | Voltage detection circuit self power consumption | VCA25 = 1, Vcc = 5.0 V | – | 1.5 | – | μA |
| t _{d(E-A)} | Waiting time until voltage detection circuit operation starts (3) | | – | – | 100 | μs |

Notes:

1. The measurement condition is V_{CC} = 1.8 V to 5.5 V and T_{opr} = –20 to 85°C (N version) / –40 to 85°C (D version).
2. Select the voltage detection level with bits VDSEL0 and VDSEL1 in the OFS register.
3. Necessary time until the voltage detection circuit operates when setting to 1 again after setting the VCA25 bit in the VCA2 register to 0.
4. Time until the voltage monitor 0 reset is generated after the voltage passes V_{det0}.

Table 5.7 Voltage Detection 1 Circuit Electrical Characteristics

| Symbol | Parameter | Condition | Standard | | | Unit |
|---------------------|--|---|----------|------|------|------|
| | | | Min. | Typ. | Max. | |
| Vdet1 | Voltage detection level Vdet1_0 (2) | At the falling of Vcc | 2.00 | 2.20 | 2.40 | V |
| | Voltage detection level Vdet1_1 (2) | At the falling of Vcc | 2.15 | 2.35 | 2.55 | V |
| | Voltage detection level Vdet1_2 (2) | At the falling of Vcc | 2.30 | 2.50 | 2.70 | V |
| | Voltage detection level Vdet1_3 (2) | At the falling of Vcc | 2.45 | 2.65 | 2.85 | V |
| | Voltage detection level Vdet1_4 (2) | At the falling of Vcc | 2.60 | 2.80 | 3.00 | V |
| | Voltage detection level Vdet1_5 (2) | At the falling of Vcc | 2.75 | 2.95 | 3.15 | V |
| | Voltage detection level Vdet1_6 (2) | At the falling of Vcc | 2.85 | 3.10 | 3.40 | V |
| | Voltage detection level Vdet1_7 (2) | At the falling of Vcc | 3.00 | 3.25 | 3.55 | V |
| | Voltage detection level Vdet1_8 (2) | At the falling of Vcc | 3.15 | 3.40 | 3.70 | V |
| | Voltage detection level Vdet1_9 (2) | At the falling of Vcc | 3.30 | 3.55 | 3.85 | V |
| | Voltage detection level Vdet1_A (2) | At the falling of Vcc | 3.45 | 3.70 | 4.00 | V |
| | Voltage detection level Vdet1_B (2) | At the falling of Vcc | 3.60 | 3.85 | 4.15 | V |
| | Voltage detection level Vdet1_C (2) | At the falling of Vcc | 3.75 | 4.00 | 4.30 | V |
| | Voltage detection level Vdet1_D (2) | At the falling of Vcc | 3.90 | 4.15 | 4.45 | V |
| | Voltage detection level Vdet1_E (2) | At the falling of Vcc | 4.05 | 4.30 | 4.60 | V |
| | Voltage detection level Vdet1_F (2) | At the falling of Vcc | 4.20 | 4.45 | 4.75 | V |
| – | Hysteresis width at the rising of Vcc in voltage detection 1 circuit | Vdet1_0 to Vdet1_5 selected | – | 0.07 | – | V |
| | | Vdet1_6 to Vdet1_F selected | – | 0.10 | – | V |
| – | Voltage detection 1 circuit response time (3) | At the falling of Vcc from 5 V to (Vdet1_0 – 0.1) V | – | 60 | 150 | μs |
| – | Voltage detection circuit self power consumption | VCA26 = 1, Vcc = 5.0 V | – | 1.7 | – | μA |
| t _{d(E-A)} | Waiting time until voltage detection circuit operation starts (4) | | – | – | 100 | μs |

Notes:

1. The measurement condition is V_{CC} = 1.8 V to 5.5 V and T_{opr} = –20 to 85°C (N version) / –40 to 85°C (D version).
2. Select the voltage detection level with bits VD1S0 to VD1S3 in the VD1LS register.
3. Time until the voltage monitor 1 interrupt request is generated after the voltage passes V_{det1}.
4. Necessary time until the voltage detection circuit operates when setting to 1 again after setting the VCA26 bit in the VCA2 register to 0.

Table 5.8 Voltage Detection 2 Circuit Electrical Characteristics

| Symbol | Parameter | Condition | Standard | | | Unit |
|---------------------|--|---|----------|------|------|------|
| | | | Min. | Typ. | Max. | |
| V _{det2} | Voltage detection level V _{det2_0} | At the falling of V _{cc} | 3.70 | 4.00 | 4.30 | V |
| – | Hysteresis width at the rising of V _{cc} in voltage detection 2 circuit | | – | 0.10 | – | V |
| – | Voltage detection 2 circuit response time ⁽²⁾ | At the falling of V _{cc} from 5 V to (V _{det2_0} – 0.1) V | – | 20 | 150 | μs |
| – | Voltage detection circuit self power consumption | VCA27 = 1, V _{cc} = 5.0 V | – | 1.7 | – | μA |
| t _{d(E-A)} | Waiting time until voltage detection circuit operation starts ⁽³⁾ | | – | – | 100 | μs |

Notes:

1. The measurement condition is V_{cc} = 1.8 V to 5.5 V and T_{opr} = –20 to 85°C (N version) / –40 to 85°C (D version).
2. Time until the voltage monitor 2 interrupt request is generated after the voltage passes V_{det2}.
3. Necessary time until the voltage detection circuit operates after setting to 1 again after setting the VCA27 bit in the VCA2 register to 0.

Table 5.9 Power-on Reset Circuit (2)

| Symbol | Parameter | Condition | Standard | | | Unit |
|------------------|--|----------------|----------|------|-------|---------|
| | | | Min. | Typ. | Max. | |
| t _{rth} | External power V _{cc} rise gradient | ⁽¹⁾ | 0 | – | 50000 | mV/msec |

Notes:

1. The measurement condition is T_{opr} = –20 to 85°C (N version) / –40 to 85°C (D version), unless otherwise specified.
2. To use the power-on reset function, enable voltage monitor 0 reset by setting the LVDAS bit in the OFS register to 0.

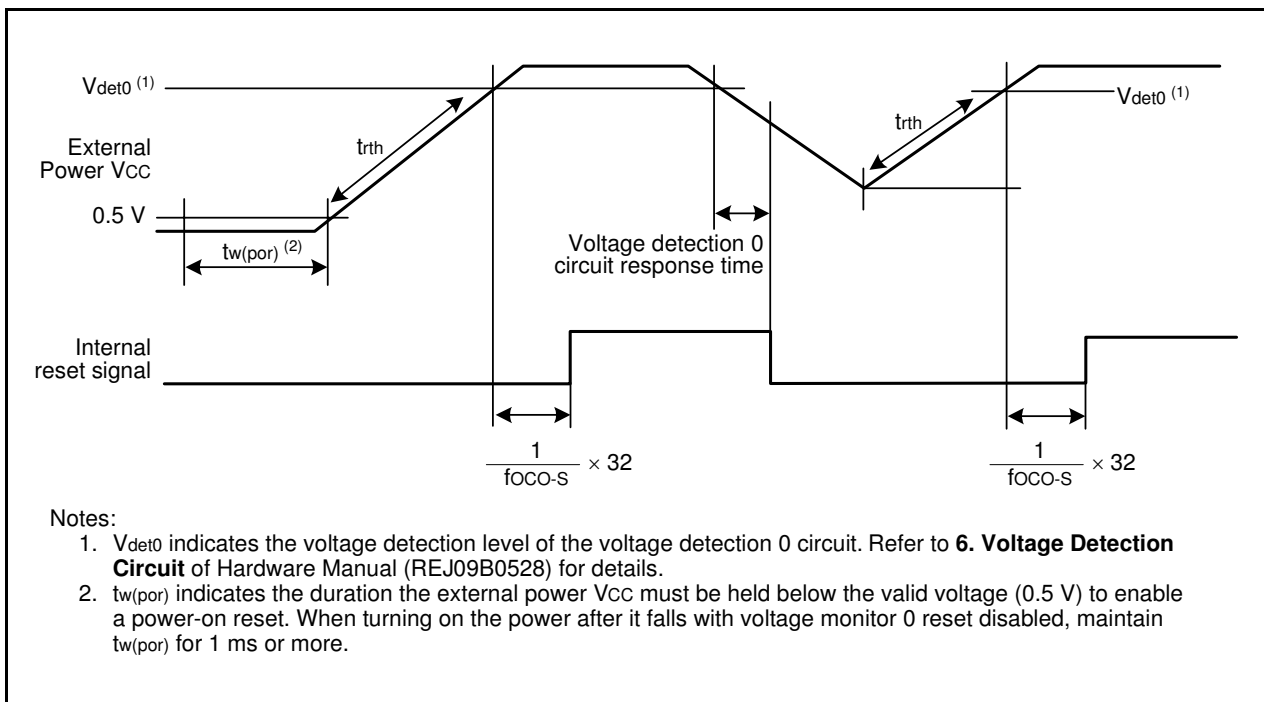
**Figure 5.3 Power-on Reset Circuit Electrical Characteristics**

Table 5.10 High-speed On-Chip Oscillator Circuit Electrical Characteristics

| Symbol | Parameter | Condition | Standard | | | Unit |
|--------|--|--|----------|--------|--------|---------------|
| | | | Min. | Typ. | Max. | |
| – | High-speed on-chip oscillator frequency after reset | $V_{CC} = 1.8 \text{ V to } 5.5 \text{ V}$ $-20^{\circ}\text{C} \leq T_{opr} \leq 85^{\circ}\text{C}$ | 38.4 | 40 | 41.6 | MHz |
| | | $V_{CC} = 1.8 \text{ V to } 5.5 \text{ V}$ $-40^{\circ}\text{C} \leq T_{opr} \leq 85^{\circ}\text{C}$ | 38.0 | 40 | 42.0 | MHz |
| – | High-speed on-chip oscillator frequency when the FRA4 register correction value is written into the FRA1 register and the FRA5 register correction value into the FRA3 register ⁽³⁾ | $V_{CC} = 1.8 \text{ V to } 5.5 \text{ V}$ $-20^{\circ}\text{C} \leq T_{opr} \leq 85^{\circ}\text{C}$ | 35.389 | 36.864 | 38.338 | MHz |
| | | $V_{CC} = 1.8 \text{ V to } 5.5 \text{ V}$ $-40^{\circ}\text{C} \leq T_{opr} \leq 85^{\circ}\text{C}$ | 35.020 | 36.864 | 38.707 | MHz |
| – | High-speed on-chip oscillator frequency when the FRA6 register correction value is written into the FRA1 register and the FRA7 register correction value into the FRA3 register | $V_{CC} = 1.8 \text{ V to } 5.5 \text{ V}$ $-20^{\circ}\text{C} \leq T_{opr} \leq 85^{\circ}\text{C}$ | 30.72 | 32 | 33.28 | MHz |
| | | $V_{CC} = 1.8 \text{ V to } 5.5 \text{ V}$ $-40^{\circ}\text{C} \leq T_{opr} \leq 85^{\circ}\text{C}$ | 30.40 | 32 | 33.60 | MHz |
| – | Oscillation stability time | $V_{CC} = 5.0 \text{ V}$, $T_{opr} = 25^{\circ}\text{C}$ | – | 0.5 | 3 | ms |
| – | Self power consumption at oscillation | $V_{CC} = 5.0 \text{ V}$, $T_{opr} = 25^{\circ}\text{C}$ | – | 400 | – | μA |

Notes:

1. $V_{CC} = 1.8$ to 5.5 V , $T_{opr} = -20$ to 85°C (N version) / -40 to 85°C (D version), unless otherwise specified.
2. This indicates the precision error for the oscillation frequency of the high-speed on-chip oscillator.
3. This enables the setting errors of bit rates such as 9600 bps and 38400 bps to be 0% when the serial interface is used in UART mode.

Table 5.11 Low-speed On-Chip Oscillator Circuit Electrical Characteristics

| Symbol | Parameter | Condition | Standard | | | Unit |
|--------|--|---|----------|------|------|---------------|
| | | | Min. | Typ. | Max. | |
| fOCO-S | Low-speed on-chip oscillator frequency | | 60 | 125 | 250 | kHz |
| – | Oscillation stability time | $V_{CC} = 5.0 \text{ V}$, $T_{opr} = 25^{\circ}\text{C}$ | – | 30 | 100 | μs |
| – | Self power consumption at oscillation | $V_{CC} = 5.0 \text{ V}$, $T_{opr} = 25^{\circ}\text{C}$ | – | 2 | – | μA |

Note:

1. $V_{CC} = 1.8$ to 5.5 V , $T_{opr} = -20$ to 85°C (N version) / -40 to 85°C (D version), unless otherwise specified.

Table 5.12 Power Supply Circuit Timing Characteristics

| Symbol | Parameter | Condition | Standard | | | Unit |
|---------------------|---|-----------|----------|------|------|---------------|
| | | | Min. | Typ. | Max. | |
| t _{d(P-R)} | Time for internal power supply stabilization during power-on ⁽²⁾ | | – | – | 2000 | μs |

Notes:

1. The measurement condition is $V_{CC} = 1.8$ to 5.5 V and $T_{opr} = 25^{\circ}\text{C}$.
2. Waiting time until the internal power supply generation circuit stabilizes during power-on.

Table 5.13 Electrical Characteristics (1) [4.2 V ≤ Vcc ≤ 5.5 V]

| Symbol | Parameter | | Condition | | Standard | | | Unit |
|---------------------|---------------------|--|-------------------------------|---------------|-----------|------|------|------|
| | | | | | Min. | Typ. | Max. | |
| VOH | Output "H" voltage | Other than XOUT | Drive capacity High Vcc = 5 V | IOH = -20 mA | Vcc - 2.0 | - | Vcc | V |
| | | | Drive capacity Low Vcc = 5 V | IOH = -5 mA | Vcc - 2.0 | - | Vcc | V |
| | | XOUT | Vcc = 5V | IOH = -200 μA | 1.0 | - | Vcc | V |
| VOL | Output "L" voltage | Other than XOUT | Drive capacity High Vcc = 5 V | IOL = 20 mA | - | - | 2.0 | V |
| | | | Drive capacity Low Vcc = 5 V | IOL = 5 mA | - | - | 2.0 | V |
| | | XOUT | Vcc = 5V | IOL = 200 μA | - | - | 0.5 | V |
| VT+-VT- | Hysteresis | INT0, INT1, INT3, KI0, KI1, KI2, KI3, TRAIO, TRBO, TRCIOA, TRCIOB, TRCIOC, TRCIOD, TRCTRG, TRCCLK, ADTRG, RXD0, RXD2, CLK0, CLK2 | | | 0.1 | 1.2 | - | V |
| | | RESET | | | 0.1 | 1.2 | - | V |
| I _{IH} | Input "H" current | | VI = 5 V, Vcc = 5.0 V | | - | - | 5.0 | μA |
| I _{IL} | Input "L" current | | VI = 0 V, Vcc = 5.0 V | | - | - | -5.0 | μA |
| R _{PULLUP} | Pull-up resistance | | VI = 0 V, Vcc = 5.0 V | | 25 | 50 | 100 | kΩ |
| R _{IXIN} | Feedback resistance | XIN | | | - | 0.3 | - | MΩ |
| R _{IXCIN} | Feedback resistance | XCIN | | | - | 8 | - | MΩ |
| V _{RAM} | RAM hold voltage | | During stop mode | | 1.8 | - | - | V |

Note:

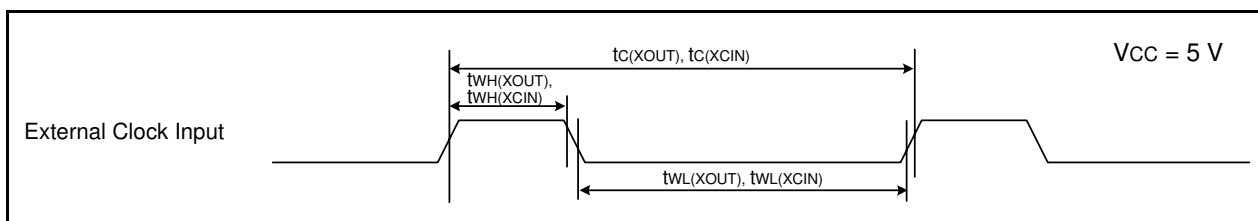
- 4.2 V ≤ Vcc ≤ 5.5 V at T_{opr} = -20 to 85°C (N version) / -40 to 85°C (D version), f(XIN) = 20 MHz, unless otherwise specified.

Table 5.14 Electrical Characteristics (2) [3.3 V ≤ Vcc ≤ 5.5 V]
(Topr = −20 to 85°C (N version) / −40 to 85°C (D version), unless otherwise specified.)

| Symbol | Parameter | Condition | Standard | | | Unit | |
|--------|---|------------------------------------|--|------|------|------|----|
| | | | Min. | Typ. | Max. | | |
| Icc | Power supply current (Vcc = 3.3 to 5.5 V) Single-chip mode, output pins are open, other pins are Vss | High-speed clock mode | XIN = 20 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz No division | – | 6.5 | 15 | mA |
| | | | XIN = 16 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz No division | – | 5.3 | 12.5 | mA |
| | | | XIN = 10 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz No division | – | 3.6 | – | mA |
| | | | XIN = 20 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8 | – | 3.0 | – | mA |
| | | | XIN = 16 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8 | – | 2.2 | – | mA |
| | | | XIN = 10 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8 | – | 1.5 | – | mA |
| | | High-speed on-chip oscillator mode | XIN clock off High-speed on-chip oscillator on fOCO-F = 20 MHz Low-speed on-chip oscillator on = 125 kHz No division | – | 7.0 | 15 | mA |
| | | | XIN clock off High-speed on-chip oscillator on fOCO-F = 20 MHz Low-speed on-chip oscillator on = 125 kHz Divide-by-8 | – | 3.0 | – | mA |
| | | | XIN clock off High-speed on-chip oscillator on fOCO-F = 4 MHz Low-speed on-chip oscillator on = 125 kHz Divide-by-16 MSTTRC = 1 | – | 1 | – | mA |
| | | Low-speed on-chip oscillator mode | XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8, FMR27 = 1, VCA20 = 0 | – | 90 | 400 | μA |
| | | Low-speed clock mode | XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator off XCIN clock oscillator on = 32 kHz No division FMR27 = 1, VCA20 = 0 | – | 85 | 400 | μA |
| | | | XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator off XCIN clock oscillator on = 32 kHz No division Program operation on RAM Flash memory off, FMSTP = 1, VCA20 = 0 | – | 47 | – | μA |
| | | Wait mode | XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz While a WAIT instruction is executed Peripheral clock operation VCA27 = VCA26 = VCA25 = 0 VCA20 = 1 | – | 15 | 100 | μA |
| | | | XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz While a WAIT instruction is executed Peripheral clock off VCA27 = VCA26 = VCA25 = 0 VCA20 = 1 | – | 4 | 90 | μA |
| | | | XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator off XCIN clock oscillator on = 32 kHz (peripheral clock off) While a WAIT instruction is executed VCA27 = VCA26 = VCA25 = 0 VCA20 = 1 | – | 3.5 | – | μA |
| | | Stop mode | XIN clock off, Topr = 25°C High-speed on-chip oscillator off Low-speed on-chip oscillator off CM10 = 1 Peripheral clock off VCA27 = VCA26 = VCA25 = 0 | – | 2.0 | 5.0 | μA |
| | | | XIN clock off, Topr = 85°C High-speed on-chip oscillator off Low-speed on-chip oscillator off CM10 = 1 Peripheral clock off VCA27 = VCA26 = VCA25 = 0 | – | 5.0 | – | μA |

Timing Requirements(Unless Otherwise Specified: $V_{CC} = 5\text{ V}$, $V_{SS} = 0\text{ V}$ at $T_{op} = 25^\circ\text{C}$)**Table 5.15 External Clock Input (XOUT, XCIN)**

| Symbol | Parameter | Standard | | Unit |
|-----------------------|-----------------------|----------|------|---------------|
| | | Min. | Max. | |
| $t_c(\text{XOUT})$ | XOUT input cycle time | 50 | – | ns |
| $t_{WH}(\text{XOUT})$ | XOUT input “H” width | 24 | – | ns |
| $t_{WL}(\text{XOUT})$ | XOUT input “L” width | 24 | – | ns |
| $t_c(\text{XCIN})$ | XCIN input cycle time | 14 | – | μs |
| $t_{WH}(\text{XCIN})$ | XCIN input “H” width | 7 | – | μs |
| $t_{WL}(\text{XCIN})$ | XCIN input “L” width | 7 | – | μs |

**Figure 5.4 External Clock Input Timing Diagram when $V_{CC} = 5\text{ V}$** **Table 5.16 TRAIO Input**

| Symbol | Parameter | Standard | | Unit |
|------------------------|------------------------|----------|------|------|
| | | Min. | Max. | |
| $t_c(\text{TRAIO})$ | TRAIO input cycle time | 100 | – | ns |
| $t_{WH}(\text{TRAIO})$ | TRAIO input “H” width | 40 | – | ns |
| $t_{WL}(\text{TRAIO})$ | TRAIO input “L” width | 40 | – | ns |

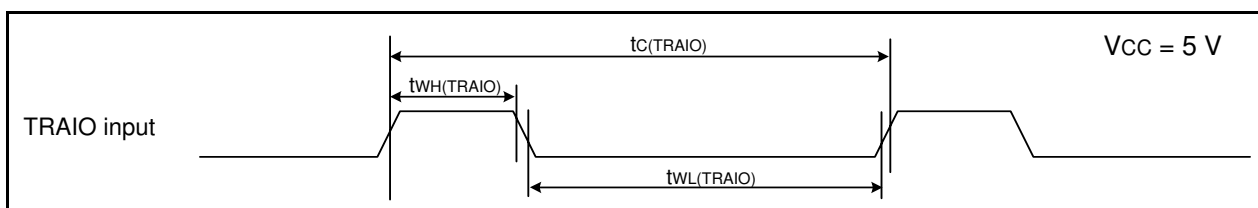
**Figure 5.5 TRAIO Input Timing Diagram when $V_{CC} = 5\text{ V}$**

Table 5.17 Serial Interface

| Symbol | Parameter | Standard | | Unit |
|---------------|------------------------|----------|------|------|
| | | Min. | Max. | |
| $t_{c(CK)}$ | CLKi input cycle time | 200 | – | ns |
| $t_{w(CKH)}$ | CLKi input “H” width | 100 | – | ns |
| $t_{w(CKL)}$ | CLKi input “L” width | 100 | – | ns |
| $t_{d(C-Q)}$ | TXDi output delay time | – | 50 | ns |
| $t_{h(C-Q)}$ | TXDi hold time | 0 | – | ns |
| $t_{su(D-C)}$ | RXDi input setup time | 50 | – | ns |
| $t_{h(C-D)}$ | RXDi input hold time | 90 | – | ns |

$i = 0, 2$

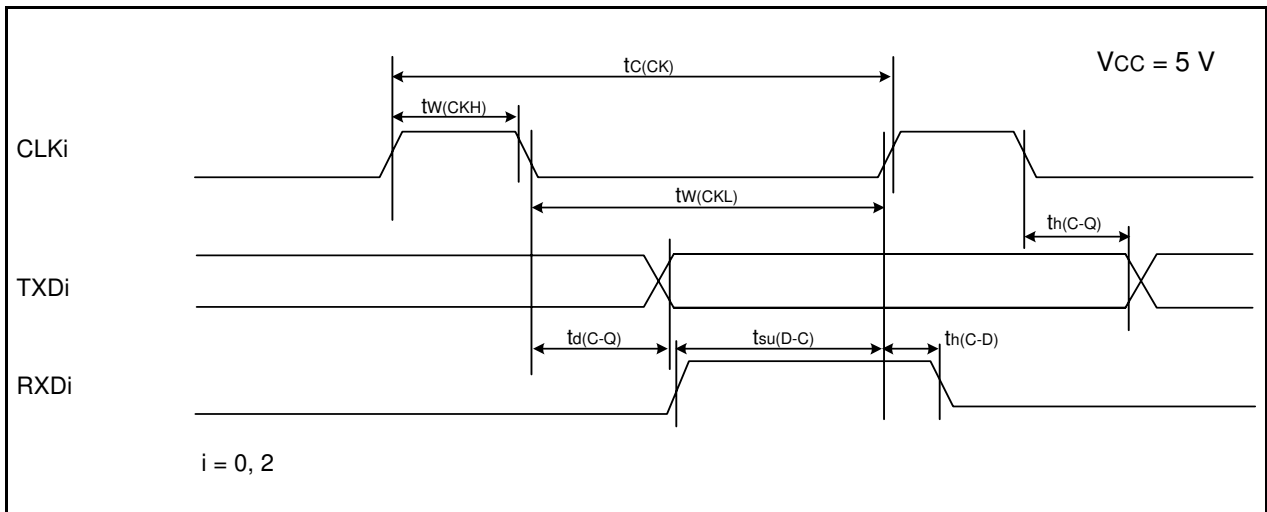


Figure 5.6 Serial Interface Timing Diagram when Vcc = 5 V

Table 5.18 External Interrupt \overline{INTi} ($i = 0, 1, 3$) Input, Key Input Interrupt \overline{Kli} ($i = 0$ to 3)

| Symbol | Parameter | Standard | | Unit |
|--------------|---|----------|------|------|
| | | Min. | Max. | |
| $t_{w(INH)}$ | \overline{INTi} input “H” width, \overline{Kli} input “H” width | 250 (1) | – | ns |
| $t_{w(INL)}$ | \overline{INTi} input “L” width, \overline{Kli} input “L” width | 250 (2) | – | ns |

Notes:

1. When selecting the digital filter by the \overline{INTi} input filter select bit, use an \overline{INTi} input HIGH width of either (1/digital filter clock frequency \times 3) or the minimum value of standard, whichever is greater.
2. When selecting the digital filter by the \overline{INTi} input filter select bit, use an \overline{INTi} input LOW width of either (1/digital filter clock frequency \times 3) or the minimum value of standard, whichever is greater.

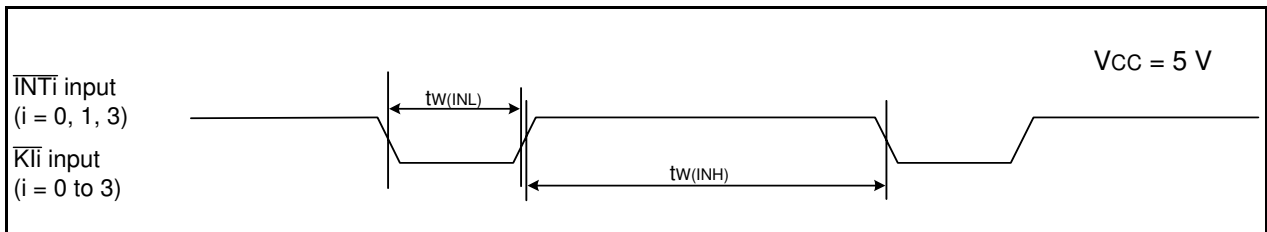


Figure 5.7 Input Timing for External Interrupt \overline{INTi} and Key Input Interrupt \overline{Kli} when Vcc = 5 V

Table 5.19 Electrical Characteristics (3) [$2.7\text{ V} \leq V_{CC} < 4.2\text{ V}$]

| Symbol | Parameter | | Condition | | Standard | | | Unit |
|----------------------------------|---------------------|---|---|---------------------------|-----------------------|------|-----------------|------|
| | | | | | Min. | Typ. | Max. | |
| V _{OH} | Output "H" voltage | Other than XOUT | Drive capacity High | I _{OH} = -5 mA | V _{CC} - 0.5 | - | V _{CC} | V |
| | | | Drive capacity Low | I _{OH} = -1 mA | V _{CC} - 0.5 | - | V _{CC} | V |
| | | XOUT | | I _{OH} = -200 μA | 1.0 | - | V _{CC} | V |
| V _{OL} | Output "L" voltage | Other than XOUT | Drive capacity High | I _{OL} = 5 mA | - | - | 0.5 | V |
| | | | Drive capacity Low | I _{OL} = 1 mA | - | - | 0.5 | V |
| | | XOUT | | I _{OL} = 200 μA | - | - | 0.5 | V |
| V _{T+} -V _{T-} | Hysteresis | <u>INT0</u> , <u>INT1</u> , <u>INT3</u> , <u>KI0</u> , <u>KI1</u> , <u>KI2</u> , <u>KI3</u> , <u>TRAIO</u> , <u>TRBO</u> , <u>TRCIOA</u> , <u>TRCIOB</u> , <u>TRCIOC</u> , <u>TRCIOD</u> , <u>TRCTRG</u> , <u>TRCCLK</u> , <u>ADTRG</u> , <u>RXD0</u> , <u>RXD2</u> , <u>CLK0</u> , <u>CLK2</u> | V _{CC} = 3.0 V | | 0.1 | 0.4 | - | V |
| | | <u>RESET</u> | V _{CC} = 3.0 V | | 0.1 | 0.5 | - | V |
| I _{IH} | Input "H" current | | V _I = 3 V, V _{CC} = 3.0 V | | - | - | 4.0 | μA |
| I _{IL} | Input "L" current | | V _I = 0 V, V _{CC} = 3.0 V | | - | - | -4.0 | μA |
| R _{PULLUP} | Pull-up resistance | | V _I = 0 V, V _{CC} = 3.0 V | | 42 | 84 | 168 | kΩ |
| R _{IXIN} | Feedback resistance | XIN | | | - | 0.3 | - | MΩ |
| R _{IXCIN} | Feedback resistance | XCIN | | | - | 8 | - | MΩ |
| V _{RAM} | RAM hold voltage | | During stop mode | | 1.8 | - | - | V |

Note:

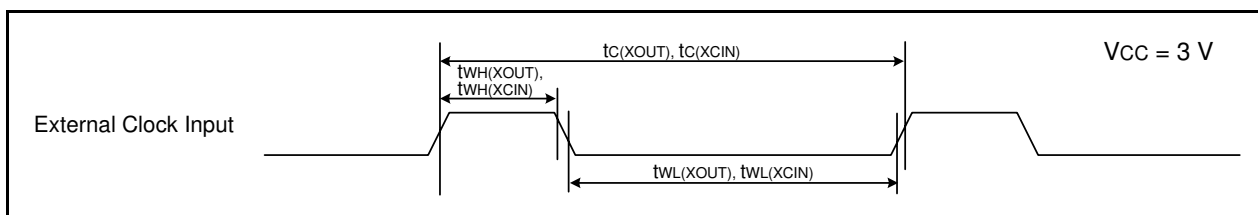
1. $2.7\text{ V} \leq V_{CC} < 4.2\text{ V}$ at T_{opr} = -20 to 85°C (N version) / -40 to 85°C (D version), f(XIN) = 10 MHz, unless otherwise specified.

Table 5.20 Electrical Characteristics (4) [2.7 V ≤ Vcc < 3.3 V]
(Topr = −20 to 85°C (N version) / −40 to 85°C (D version), unless otherwise specified.)

| Symbol | Parameter | Condition | Standard | | | Unit | |
|--|--|--|---|------|------|------|----|
| | | | Min. | Typ. | Max. | | |
| Icc | Power supply current (Vcc = 2.7 to 3.3 V) Single-chip mode, output pins are open, other pins are Vss | High-speed clock mode | XIN = 10 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz No division | − | 3.5 | 10 | mA |
| | | | XIN = 10 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8 | − | 1.5 | 7.5 | mA |
| | | High-speed on-chip oscillator mode | XIN clock off High-speed on-chip oscillator on fOCO-F = 20 MHz Low-speed on-chip oscillator on = 125 kHz No division | − | 7.0 | 15 | mA |
| | | | XIN clock off High-speed on-chip oscillator on fOCO-F = 20 MHz Low-speed on-chip oscillator on = 125 kHz Divide-by-8 | − | 3.0 | − | mA |
| | | | XIN clock off High-speed on-chip oscillator on fOCO-F = 10 MHz Low-speed on-chip oscillator on = 125 kHz No division | − | 4.0 | − | mA |
| | | | XIN clock off High-speed on-chip oscillator on fOCO-F = 10 MHz Low-speed on-chip oscillator on = 125 kHz Divide-by-8 | − | 1.5 | − | mA |
| | | | XIN clock off High-speed on-chip oscillator on fOCO-F = 4 MHz Low-speed on-chip oscillator on = 125 kHz Divide-by-16 MSTTRC = 1 | − | 1 | − | mA |
| | | Low-speed on-chip oscillator mode | XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8, FMR27 = 1, VCA20 = 0 | − | 90 | 390 | μA |
| | | Low-speed clock mode | XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator off XCIN clock oscillator on = 32 kHz No division FMR27 = 1, VCA20 = 0 | − | 80 | 400 | μA |
| | | | XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator off XCIN clock oscillator on = 32 kHz No division Program operation on RAM Flash memory off, FMSTP = 1, VCA20 = 0 | − | 40 | − | μA |
| | | Wait mode | XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz While a WAIT instruction is executed Peripheral clock operation VCA27 = VCA26 = VCA25 = 0, VCA20 = 1 | − | 15 | 90 | μA |
| | | | XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz While a WAIT instruction is executed Peripheral clock off VCA27 = VCA26 = VCA25 = 0, VCA20 = 1 | − | 4 | 80 | μA |
| | | | XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator off XCIN clock oscillator on = 32 kHz (peripheral clock off) While a WAIT instruction is executed VCA27 = VCA26 = VCA25 = 0, VCA20 = 1 | − | 3.5 | − | μA |
| | | Stop mode | XIN clock off, Topr = 25°C High-speed on-chip oscillator off Low-speed on-chip oscillator off CM10 = 1 Peripheral clock off VCA27 = VCA26 = VCA25 = 0 | − | 2.0 | 5.0 | μA |
| XIN clock off, Topr = 85°C High-speed on-chip oscillator off Low-speed on-chip oscillator off CM10 = 1 Peripheral clock off VCA27 = VCA26 = VCA25 = 0 | − | | 5.0 | − | μA | | |

Timing requirements**(Unless Otherwise Specified: $V_{CC} = 3\text{ V}$, $V_{SS} = 0\text{ V}$ at $T_{op} = 25^{\circ}\text{C}$)****Table 5.21 External Clock Input (XOUT, XCIN)**

| Symbol | Parameter | Standard | | Unit |
|----------------|-----------------------|----------|------|---------------|
| | | Min. | Max. | |
| $t_{c(XOUT)}$ | XOUT input cycle time | 50 | – | ns |
| $t_{WH(XOUT)}$ | XOUT input “H” width | 24 | – | ns |
| $t_{WL(XOUT)}$ | XOUT input “L” width | 24 | – | ns |
| $t_{c(XCIN)}$ | XCIN input cycle time | 14 | – | μs |
| $t_{WH(XCIN)}$ | XCIN input “H” width | 7 | – | μs |
| $t_{WL(XCIN)}$ | XCIN input “L” width | 7 | – | μs |

**Figure 5.8 External Clock Input Timing Diagram when $V_{CC} = 3\text{ V}$** **Table 5.22 TRAI0 Input**

| Symbol | Parameter | Standard | | Unit |
|-----------------|------------------------|----------|------|------|
| | | Min. | Max. | |
| $t_{c(TRAIO)}$ | TRAIO input cycle time | 300 | – | ns |
| $t_{WH(TRAIO)}$ | TRAIO input “H” width | 120 | – | ns |
| $t_{WL(TRAIO)}$ | TRAIO input “L” width | 120 | – | ns |

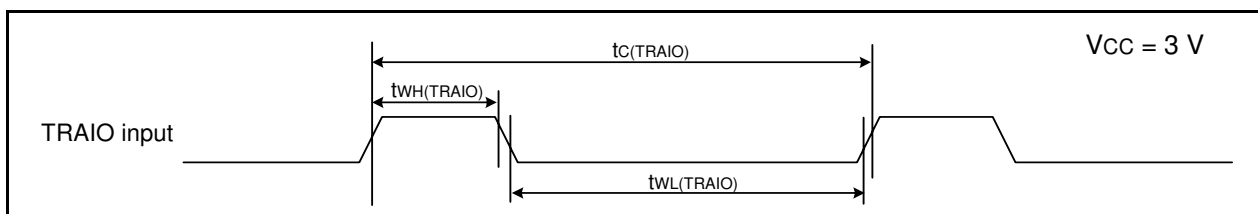
**Figure 5.9 TRAI0 Input Timing Diagram when $V_{CC} = 3\text{ V}$**

Table 5.23 Serial Interface

| Symbol | Parameter | Standard | | Unit |
|---------------|------------------------|----------|------|------|
| | | Min. | Max. | |
| $t_{c(CK)}$ | CLKi input cycle time | 300 | – | ns |
| $t_{w(CKH)}$ | CLKi input “H” width | 150 | – | ns |
| $t_{w(CKL)}$ | CLKi Input “L” width | 150 | – | ns |
| $t_{d(C-Q)}$ | TXDi output delay time | – | 80 | ns |
| $t_{h(C-Q)}$ | TXDi hold time | 0 | – | ns |
| $t_{su(D-C)}$ | RXDi input setup time | 70 | – | ns |
| $t_{h(C-D)}$ | RXDi input hold time | 90 | – | ns |

$i = 0, 2$

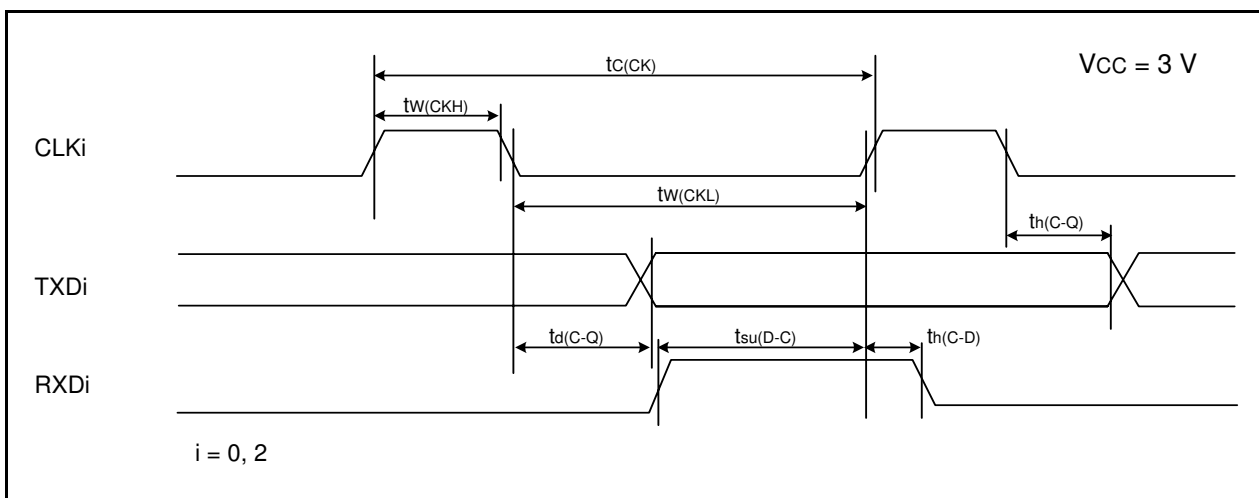


Figure 5.10 Serial Interface Timing Diagram when Vcc = 3 V

Table 5.24 External Interrupt \overline{INTi} ($i = 0, 1, 3$) Input, Key Input Interrupt \overline{Kli} ($i = 0$ to 3)

| Symbol | Parameter | Standard | | Unit |
|--------------|---|----------|------|------|
| | | Min. | Max. | |
| $t_{w(INH)}$ | \overline{INTi} input “H” width, \overline{Kli} input “H” width | 380 (1) | – | ns |
| $t_{w(INL)}$ | \overline{INTi} input “L” width, \overline{Kli} input “L” width | 380 (2) | – | ns |

Notes:

1. When selecting the digital filter by the \overline{INTi} input filter select bit, use an \overline{INTi} input HIGH width of either (1/digital filter clock frequency × 3) or the minimum value of standard, whichever is greater.
2. When selecting the digital filter by the \overline{INTi} input filter select bit, use an \overline{INTi} input LOW width of either (1/digital filter clock frequency × 3) or the minimum value of standard, whichever is greater.



Figure 5.11 Input Timing for External Interrupt \overline{INTi} and Key Input Interrupt \overline{Kli} when Vcc = 3 V

Table 5.25 Electrical Characteristics (5) [$1.8\text{ V} \leq V_{CC} < 2.7\text{ V}$]

| Symbol | Parameter | | Condition | | Standard | | | Unit |
|----------------------------------|---------------------|---|---|---------------------------|-----------------------|------|-----------------|------|
| | | | | | Min. | Typ. | Max. | |
| V _{OH} | Output "H" voltage | Other than XOUT | Drive capacity High | I _{OH} = -2 mA | V _{CC} - 0.5 | - | V _{CC} | V |
| | | | Drive capacity Low | I _{OH} = -1 mA | V _{CC} - 0.5 | - | V _{CC} | V |
| | | XOUT | | I _{OH} = -200 μA | 1.0 | - | V _{CC} | V |
| V _{OL} | Output "L" voltage | Other than XOUT | Drive capacity High | I _{OL} = 2 mA | - | - | 0.5 | V |
| | | | Drive capacity Low | I _{OL} = 1 mA | - | - | 0.5 | V |
| | | XOUT | | I _{OL} = 200 μA | - | - | 0.5 | V |
| V _{T+} -V _{T-} | Hysteresis | INT0, INT1, INT3, KI0, KI1, KI2, KI3, TRAIO, TRBO, TRCIOA, TRCIOB, TRCIOC, TRCIOD, TRCTRG, TRCCLK, ADTRG, RXD0, RXD2, CLK0, CLK2 | | | 0.05 | 0.2 | - | V |
| | | RESET | | | 0.05 | 0.20 | - | V |
| I _{IH} | Input "H" current | | V _I = 2.2 V, V _{CC} = 2.2 V | | - | - | 4.0 | μA |
| I _{IL} | Input "L" current | | V _I = 0 V, V _{CC} = 2.2 V | | - | - | -4.0 | μA |
| R _{PULLUP} | Pull-up resistance | | V _I = 0 V, V _{CC} = 2.2 V | | 70 | 140 | 300 | kΩ |
| R _{IXIN} | Feedback resistance | XIN | | | - | 0.3 | - | MΩ |
| R _{IXCIN} | Feedback resistance | XCIN | | | - | 8 | - | MΩ |
| V _{RAM} | RAM hold voltage | | During stop mode | | 1.8 | - | - | V |

Note:

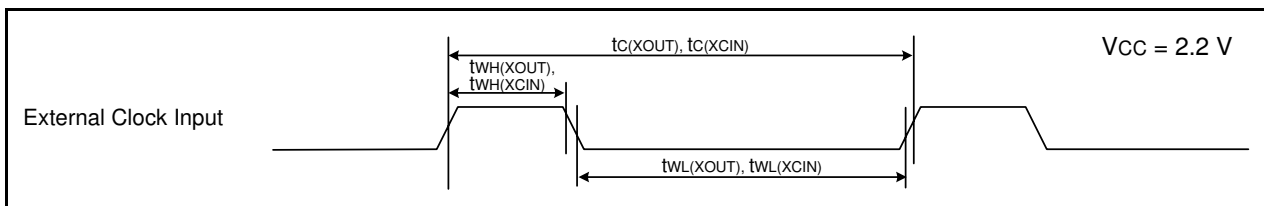
1. $1.8\text{ V} \leq V_{CC} < 2.7\text{ V}$ at T_{opr} = -20 to 85°C (N version) / -40 to 85°C (D version), f(XIN) = 5 MHz, unless otherwise specified.

Table 5.26 Electrical Characteristics (6) [1.8 V ≤ Vcc < 2.7 V]
(Topr = −20 to 85°C (N version) / −40 to 85°C (D version), unless otherwise specified.)

| Symbol | Parameter | Condition | Standard | | | Unit | |
|--------|---|------------------------------------|--|------|------|------|----|
| | | | Min. | Typ. | Max. | | |
| Icc | Power supply current (Vcc = 1.8 to 2.7 V) Single-chip mode, output pins are open, other pins are Vss | High-speed clock mode | XIN = 5 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz No division | – | 2.2 | – | mA |
| | | | XIN = 5 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8 | – | 0.8 | – | mA |
| | | High-speed on-chip oscillator mode | XIN clock off High-speed on-chip oscillator on fOCO-F = 5 MHz Low-speed on-chip oscillator on = 125 kHz No division | – | 2.5 | 10 | mA |
| | | | XIN clock off High-speed on-chip oscillator on fOCO-F = 5 MHz Low-speed on-chip oscillator on = 125 kHz Divide-by-8 | – | 1.7 | – | mA |
| | | | XIN clock off High-speed on-chip oscillator on fOCO-F = 4 MHz Low-speed on-chip oscillator on = 125 kHz Divide-by-16 MSTTRC = 1 | – | 1 | – | mA |
| | | Low-speed on-chip oscillator mode | XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8, FMR27 = 1, VCA20 = 0 | – | 90 | 300 | μA |
| | | Low-speed clock mode | XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator off XCIN clock oscillator on = 32 kHz No division FMR27 = 1, VCA20 = 0 | – | 80 | 350 | μA |
| | | | XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator off XCIN clock oscillator on = 32 kHz No division Program operation on RAM Flash memory off, FMSTP = 1, VCA20 = 0 | – | 40 | – | μA |
| | | Wait mode | XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz While a WAIT instruction is executed Peripheral clock operation VCA27 = VCA26 = VCA25 = 0 VCA20 = 1 | – | 15 | 90 | μA |
| | | | XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz While a WAIT instruction is executed Peripheral clock off VCA27 = VCA26 = VCA25 = 0 VCA20 = 1 | – | 4 | 80 | μA |
| | | | XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator off XCIN clock oscillator on = 32 kHz (peripheral clock off) While a WAIT instruction is executed VCA27 = VCA26 = VCA25 = 0 VCA20 = 1 | – | 3.5 | – | μA |
| | | Stop mode | XIN clock off, Topr = 25°C High-speed on-chip oscillator off Low-speed on-chip oscillator off CM10 = 1 Peripheral clock off VCA27 = VCA26 = VCA25 = 0 | – | 2.0 | 5 | μA |
| | | | XIN clock off, Topr = 85°C High-speed on-chip oscillator off Low-speed on-chip oscillator off CM10 = 1 Peripheral clock off VCA27 = VCA26 = VCA25 = 0 | – | 5.0 | – | μA |

Timing requirements(Unless Otherwise Specified: $V_{CC} = 2.2\text{ V}$, $V_{SS} = 0\text{ V}$ at $T_{opr} = 25^\circ\text{C}$)**Table 5.27 External Clock Input (XOUT, XCIN)**

| Symbol | Parameter | Standard | | Unit |
|----------------|-----------------------|----------|------|---------------|
| | | Min. | Max. | |
| $t_{c(XOUT)}$ | XOUT input cycle time | 200 | – | ns |
| $t_{WH(XOUT)}$ | XOUT input “H” width | 90 | – | ns |
| $t_{WL(XOUT)}$ | XOUT input “L” width | 90 | – | ns |
| $t_{c(XCIN)}$ | XCIN input cycle time | 14 | – | μs |
| $t_{WH(XCIN)}$ | XCIN input “H” width | 7 | – | μs |
| $t_{WL(XCIN)}$ | XCIN input “L” width | 7 | – | μs |

**Figure 5.12 External Clock Input Timing Diagram when $V_{CC} = 2.2\text{ V}$** **Table 5.28 TRAI0 Input**

| Symbol | Parameter | Standard | | Unit |
|-----------------|------------------------|----------|------|------|
| | | Min. | Max. | |
| $t_{c(TRAIO)}$ | TRAIO input cycle time | 500 | – | ns |
| $t_{WH(TRAIO)}$ | TRAIO input “H” width | 200 | – | ns |
| $t_{WL(TRAIO)}$ | TRAIO input “L” width | 200 | – | ns |

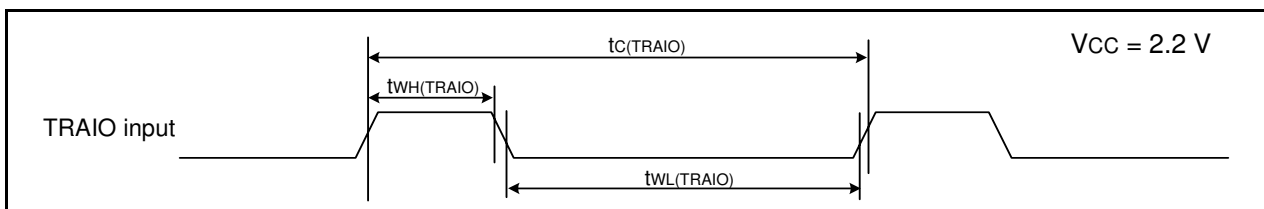
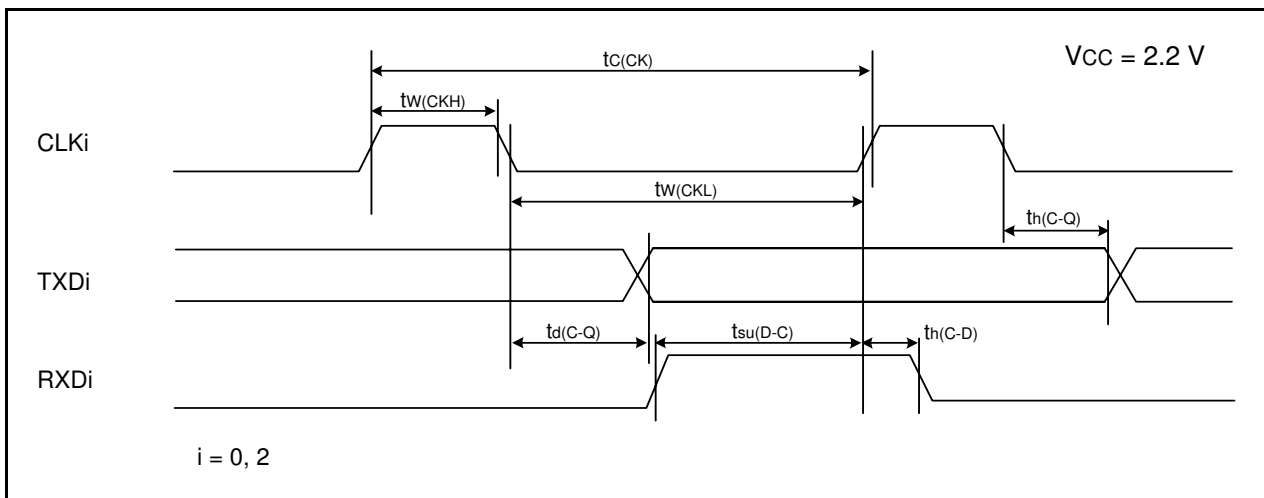
**Figure 5.13 TRAI0 Input Timing Diagram when $V_{CC} = 2.2\text{ V}$**

Table 5.29 Serial Interface

| Symbol | Parameter | Standard | | Unit |
|---------------|------------------------|----------|------|------|
| | | Min. | Max. | |
| $t_{c(CK)}$ | CLKi input cycle time | 800 | – | ns |
| $t_{w(CKH)}$ | CLKi input “H” width | 400 | – | ns |
| $t_{w(CKL)}$ | CLKi input “L” width | 400 | – | ns |
| $t_{d(C-Q)}$ | TXDi output delay time | – | 200 | ns |
| $t_{h(C-Q)}$ | TXDi hold time | 0 | – | ns |
| $t_{su(D-C)}$ | RXDi input setup time | 150 | – | ns |
| $t_{h(C-D)}$ | RXDi input hold time | 90 | – | ns |

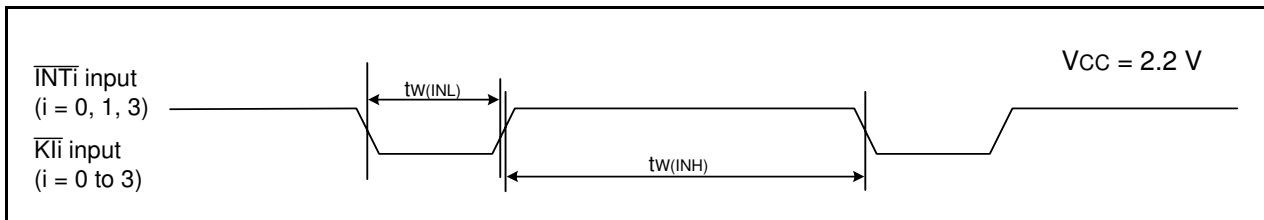
i = 0, 2

**Figure 5.14 Serial Interface Timing Diagram when Vcc = 2.2 V****Table 5.30 External Interrupt \overline{INTi} (i = 0, 1, 3) Input, Key Input Interrupt \overline{Kli} (i = 0 to 3)**

| Symbol | Parameter | Standard | | Unit |
|--------------|---|----------|------|------|
| | | Min. | Max. | |
| $t_{w(INH)}$ | \overline{INTi} input “H” width, \overline{Kli} input “H” width | 1000 (1) | – | ns |
| $t_{w(INL)}$ | \overline{INTi} input “L” width, \overline{Kli} input “L” width | 1000 (2) | – | ns |

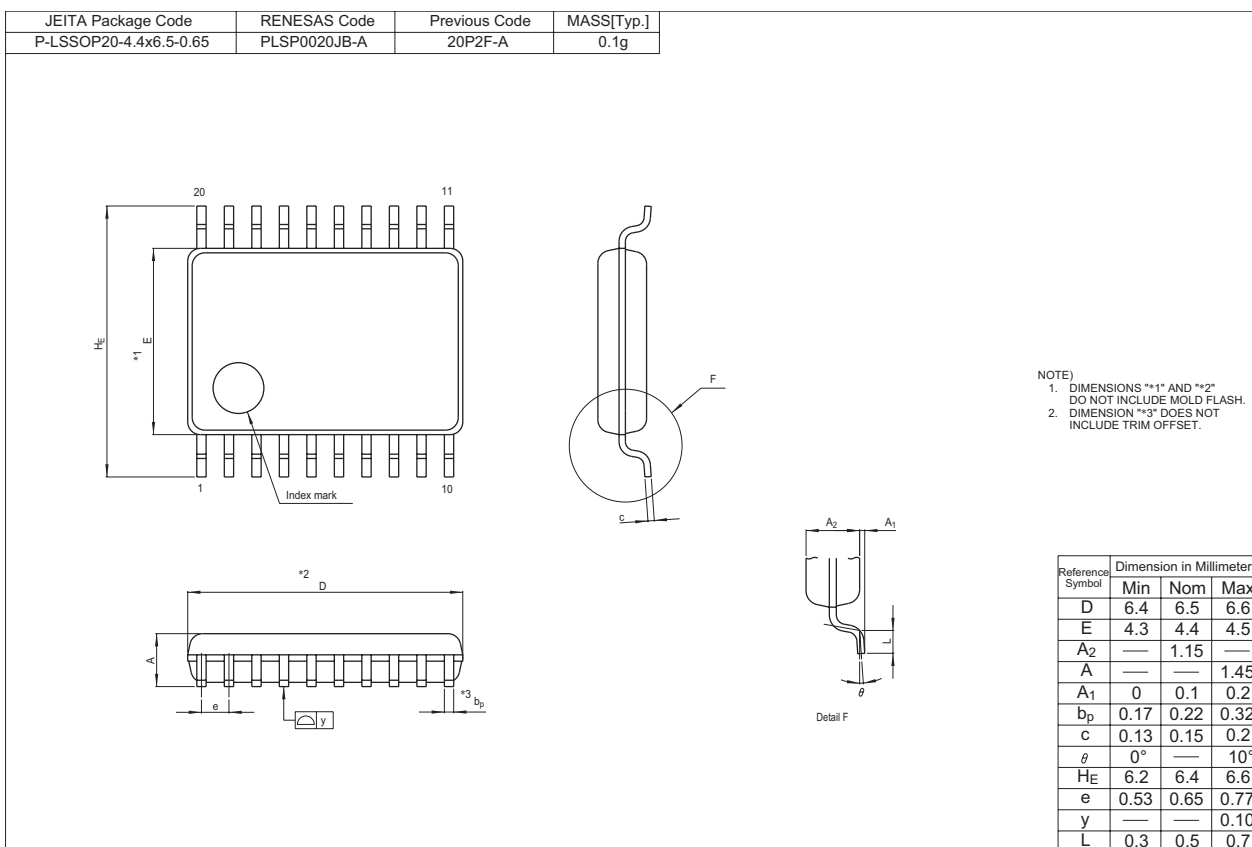
Notes:

- When selecting the digital filter by the \overline{INTi} input filter select bit, use an \overline{INTi} input HIGH width of either (1/digital filter clock frequency \times 3) or the minimum value of standard, whichever is greater.
- When selecting the digital filter by the \overline{INTi} input filter select bit, use an \overline{INTi} input LOW width of either (1/digital filter clock frequency \times 3) or the minimum value of standard, whichever is greater.

**Figure 5.15 Input Timing for External Interrupt \overline{INTi} and Key Input Interrupt \overline{Kli} when Vcc = 2.2 V**

Package Dimensions

Diagrams showing the latest package dimensions and mounting information are available in the “Packages” section of the Renesas Technology website.



| | |
|------------------|-------------------------|
| REVISION HISTORY | R8C/32D Group Datasheet |
|------------------|-------------------------|

| Rev. | Date | Description | |
|------|---------------|----------------------------|--|
| | | Page | Summary |
| 0.01 | Feb. 26, 2008 | – | First Edition issued |
| 1.00 | Feb. 26, 2010 | All pages 4 22 to 41 | “Preliminary”, “Under development” deleted Table 1.3 revised “5. Electrical Characteristics” added |
| | | | |

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Notes:

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