



XT25F04D

Dual IO Serial NOR Flash Datasheet

深圳市芯天下技术有限公司 XTX Technology Limited

Tel: (86 755) 28229862 Fax: (86 755) 28229847

Web Site: http://www.xtxtech.com/ Technical Contact: fae@xtxtech.com

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Serial NOR Flash Memory

4M bits 3.3V Dual I/O Serial Flash Memory with 4KB Uniform Sector

- 4M -bit Serial Flash
 - 512 K-byte
 - 256 bytes per programmable page
- Standard, Dual SPI
 - Standard SPI: SCLK, CS#, SI, SO
 - Dual SPI: SCLK, CS#, IO0, IO1
- Flexible Architecture
 - Sector of 4K-byte
 - Block of 32k-byte
 - Block of 64k-byte
- Software Write Protection
 - Write protect all/portion of memory via software
- Advanced security Features
 - 2*256-Byte Security Registers With OTP Lock
- Package Options
 - See 1.1 Available Ordering OPN
 - All Pb-free packages are compliant RoHS, Halogen-Free and REACH.

- Temperature Range & Moisture Sensitivity Level
 - Industrial Level Temperature. (-40 $^\circ\!\mathrm{C}$ to +85 $^\circ\!\mathrm{C}$), MSL3
- Power Consumption
 - 20mA maximum active current
 - 13uA typical standby current
- Single Power Supply Voltage
 - 2.7~3.6V
- Support SFDP and 128 bits Unique ID
- Minimum 100,000 Program/Erase Cycle
- High Speed Clock Frequency
 - 120MHz for fast read with 30PF load
 - Dual I/O Data transfer up to 208Mbits/s
- Program/Erase Speed
 - Page Program time: 0.9ms typical
 - Sector Erase time: 90ms typical
 - Block Erase time:0.3s/ 0.45s typical
 - Chip Erase time: 3.2s typical



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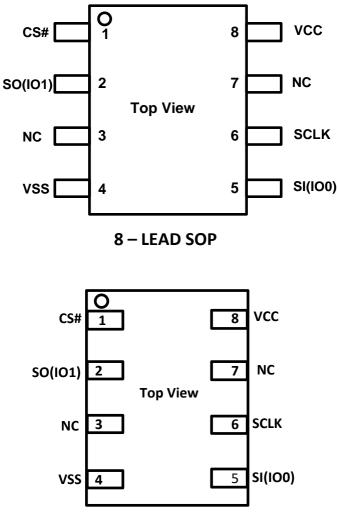
1. GENERAL DESCRIPTION

The XT25F04D Serial flash supports the standard Serial Peripheral Interface (SPI), and supports the Dual SPI: Serial Clock, Chip Select, Serial Data I/O0 (SI), I/O1 (SO). The Dual I/O data is transferred at a speed of 208Mbits/s.

1.1. Available Ordering OPN

| OPN | Package Type | Package Carrier |
|---------------|------------------------|-----------------|
| XT25F04DSOIGU | SO8 150mil | Tube |
| XT25F04DSOIGT | SO8 150mil Tape & Reel | |
| XT25F04DDTIGT | DFN8 2x3x0.4 mm | Tape & Reel |

1.2. Connection Diagram



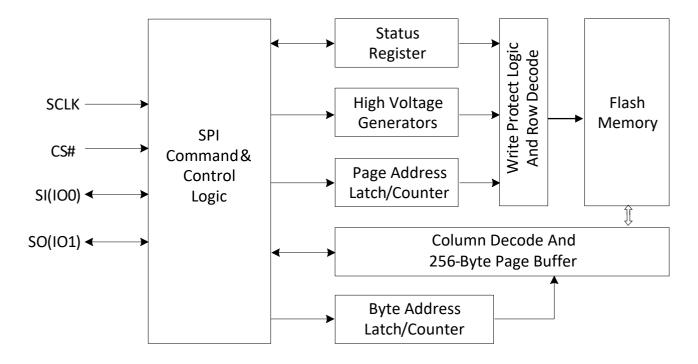
DFN8



1.3. Pin Description

| Pin Name | I/O | Description |
|----------|-----|-----------------------------------|
| CS# | I | Chip Select Input |
| SO (IO1) | I/O | Data Output (Data Input Output 1) |
| VSS | | Ground |
| SI (IO0) | I/O | Data Input (Data Input Output 0) |
| SCLK | I | Serial Clock Input |
| VCC | | Power Supply |
| NC | | No Connection |

1.4. Block Diagram





2. MEMORY ORGANIZATION

XT25F04D Memory Description

| Each block has | Each sector has | Each page has | |
|----------------|-----------------|---------------|---------|
| 32K/64K | 4К | 256 | bytes |
| 128/256 | 16 | - | pages |
| 8/16 | - | - | sectors |
| - | - | - | blocks |

XT25F04D 64K Bytes Block Sector Architecture

| Block | Sector | Address Range | | |
|-------|--------|---------------|---------|--|
| | 127 | 07F000H | 07FFFFH | |
| 7 | | | | |
| | 112 | 070000H | 070FFFH | |
| | 111 | 06F000H | 06FFFFH | |
| 6 | | | | |
| | 96 | 060000H | 060FFFH | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| | 47 | 02F000H | 02FFFFH | |
| 2 | | | | |
| | 32 | 020000H | 020FFFH | |
| | 31 | 01F000H | 01FFFFH | |
| 1 | | | | |
| | 16 | 010000H | 010FFFH | |
| | 15 | 00F000H | 00FFFFH | |
| 0 | | | | |
| | 0 | 000000Н | 000FFFH | |



3. DEVICE OPERATION

Standard SPI

The XT25F04D features a serial peripheral interface on 4 signals bus: Serial Clock (SCLK), Chip Select (CS#), Serial Data Input (SI) and Serial Data Output (SO). Both SPI bus mode 0 and 3 are supported. Input data is latched on the rising edge of SCLK and data shifts out on the falling edge of SCLK.

Dual SPI

The XT25F04D supports Dual SPI operation when using the "Dual Output Fast Read" and "Dual I/O Fast Read" (3BH and BBH) commands. These commands allow data to be transferred to or from the device at two times the rate of the standard SPI. When using the Dual SPI command the SI and SO pins become bidirectional I/O pins: IO0 and IO1.

4. STATUS REGISTER

| S7 | S6 | S5 | S4 | S 3 | S2 | S1 | S0 |
|-----------|----|----------|-----------|------------|-----|-----------|-----|
| Reserved* | LB | Reserved | BP2 | BP1 | BPO | WEL | WIP |

*Please contact XTX sales or FAE if SRWD bit is needed

The status and control bits of the Status Register are as follows:

WIP bit.

The Write In Progress (WIP) bit indicates whether the memory is busy in program/erase/write status register progress. When WIP bit sets to 1, means the device is busy in program/erase/write status register progress, when WIP bit sets 0, means the device is not in program/erase/write status register progress.

WEL bit.

The Write Enable Latch (WEL) bit indicates the status of the internal Write Enable Latch. When set to 1 the internal Write Enable Latch is set, when set to 0 the internal Write Enable Latch is reset and no Write Status Register, Program or Erase command is accepted.

LB bit.

The LB bit is a non-volatile One Time Program (OTP) bit in Status Register (S6) that provide the write protect control and status to the Security Registers. The default state of LB is 0, the security registers are unlocked. LB can be set to 1 using the Write Register instruction. LB is One Time Programmable, once it's set to 1, the Security Registers will become read-only permanently.

BP2, BP1, BP0 bits.

The Block Protect (BP2, BP1, BP0) bits are non-volatile. They define the size of the area to be software protected against Program and Erase commands. These bits are written with the Write Status Register (WRSR) command. When the Block Protect (BP2, BP1, BP0) bits are set to 1, the relevant memory area (as defined in Table1) becomes protected against Page Program (PP), Sector Erase (SE) and Block Erase (BE) commands. Chip Erase command will be ignored if one or more of the Block Protect (BP2, BP1, BP0) bits are 1.



Table1. the protected memory area of set BP2, BP1, BP0 bits

| Status Register Content | | | Memory Content | | | |
|-------------------------|-----|-----|-----------------|-----------------|---------|---------------|
| BP2 | BP1 | BPO | Blocks | Addresses | Density | Portion |
| 0 | 0 | 0 | None | None | None | None |
| 0 | 0 | 1 | Sector 0 to 125 | 000000H-07DFFFH | 504KB | Lower 126/128 |
| 0 | 1 | 0 | Sector 0 to 123 | 000000H-07BFFFH | 496KB | Lower 124/128 |
| 0 | 1 | 1 | Sector 0 to 119 | 000000H-077FFH | 480KB | Lower 120/128 |
| 1 | 0 | 0 | Sector 0 to 111 | 000000H-06FFFH | 448KB | Lower 112/128 |
| 1 | 0 | 1 | Sector 0 to 95 | 000000H-05FFFFH | 384KB | Lower 96/128 |
| 1 | 1 | 0 | Sector 0 to 63 | 000000H-03FFFFH | 256KB | Lower 64/128 |
| 1 | 1 | 1 | All | 000000H-07FFFH | 512KB | All |

SRWD bit.

The Status Register Write Disable (SRWD) bit is a non-volatile One Time Program(OTP) bit in the status register that provide another software protection. Once it is set to 1, the Write Status Register (WRSR) instruction is not accepted and the Block Protect bits (BP2, BP1, BP0) are read only.

| SRWD | Status register |
|------|--|
| | Status register can be written in (WEL bit is set to "1") and the SRWD, BP2-BP0 bits can be changed |
| 1 | The BP2-BP0 of status register bits cannot be changed |

Note: The SRWD bit is reserved by default, please contact XTX sales or FAE if needed.

5. DATA PROTECTION

The XT25F04D provides the following data protection methods:

- Write Enable (WREN) command: The WREN command is set the Write Enable Latch bit (WEL). The WEL bit will return to reset by the following situation:
 - Power-Up
 - Write Disable (WRDI)
 - Write Status Register (WRSR)
 - Page Program (PP)
 - Sector Erase (SE) / Block Erase (BE) / Chip Erase (CE)
 - Erase Security Register / Program Security Register
- Software Protection Mode:
 - SRWD=0, the Block Protect (BP2, BP1, BP0) bits define the section of the memory array that can be read and change
 - SRWD=1, the Write Status Register (WRSR) instruction is no longer accepted for execution and the SRWD bit and Block Protect bits (BP2, BP1, BP0) are read only.

Note: The Software Protection Mode is reserved by default, please contact XTX sales or FAE if needed.



6. COMMANDS DESCRIPTION

All commands, addresses and data are shifted in and out of the device, beginning with the most significant bit on the first rising edge of SCLK after CS# is driven low. Then, the one-byte command code must be shifted in to the device, most significant bit first on SI, each bit being latched on the rising edges of SCLK.

See Table 2, every command sequence starts with a one-byte command code. Depending on the command, this might be followed by address bytes, or by data bytes, or by both or none. CS# must be driven high after the last bit of the command sequence has been shifted in. For the command of Read, Fast Read, Read Status Register or Read Device ID, the shifted-in command sequence is followed by a data-out sequence. CS# can be driven high after any bit of the data-out sequence is being shifted out.

For the command of Page Program, Sector Erase, Block Erase, Chip Erase, Write Status Register, Write Enable or Write Disable command, CS# must be driven high exactly at the byte boundary, otherwise the command is rejected, and is not executed. That is CS# must be driven high when the number of clock pulses after CS# being driven low is an exact multiple of eight. For Page Program, if at any time the input byte is not a full byte, nothing will happen and WEL will not be reset.

| Command Name | Byte1 | Byte2 | Byte3 | Byte4 | Byte5 | Byte6 | n-Bytes |
|--|--------|-----------------|--------------------|-------------------|-----------------|-------------|--------------|
| Write Enable | 06H | | | | | | |
| Write Enable for Volatile Status Register | 50H | | | | | | |
| Write Disable | 04H | | | | | | |
| Read Status Register | 05H | (S7-S0) | | | | | (continuous) |
| Write Status Register | 01H | (S7-S0) | | | | | |
| Read Data | 03H | A23-A16 | A15-A8 | A7-A0 | (D7-D0) | (Next byte) | (continuous) |
| Fast Read | OBH | A23-A16 | A15-A8 | A7-A0 | dummy | (D7-D0) | (continuous) |
| Dual Output Fast Read | 3BH | A23-A16 | A15-A8 | A7-A0 | dummy | (D7-D0)(1) | (continuous) |
| Dual I/O Fast Read | BBH | A23-A8(2) | A7-A0 M7-M0(2) | (D7-D0)(1) | | | (continuous) |
| Continuous read reset | FFH | | | | | | |
| Page Program | 02H | A23-A16 | A15-A8 | A7-A0 | (D7-D0) | (Next byte) | |
| Sector Erase | 20H | A23-A16 | A15-A8 | A7-A0 | | | |
| Block Erase(32KB) | 52H | A23-A16 | A15-A8 | A7-A0 | | | |
| Block Erase(64KB) | D8H | A23-A16 | A15-A8 | A7-A0 | | | |
| Chip Erase | C7/60H | | | | | | |
| Read Manufacturer/Device ID | 90H | A23-A16 | A15-A8 | A7-A0 | (MID7- MID0) | (DID7-DID0) | (continuous) |
| Read Identification | 9FH | (MID7- MID0) | (JDID15- JDID8) | (JDID7- JDID0) | | | (continuous) |
| Read Unique ID | 4BH | 00H | 00H | 00H | 00H | (D7-D0) | |
| Read SFDP | 5AH | | | | | | |
| Erase Security Register | 44H | A23-A16 | A15-A8 | A7-A0 | | | |
| Program Security Register | 42H | A23-A16 | A15-A8 | A7-A0 | (D7-D0) | (Next byte) | |
| Read Security Register | 48H | A23-A16 | A15-A8 | A7-A0 | dummy | (D7-D0) | |
| High Speed Mode | A3H | dummy | dummy | dummy | | | |
| Enable Reset | 66H | | | | | | |
| Reset | 99H | | | | | | |

Table 2. Commands



NOTE:

1. Dual Output data

IO0 = (D6, D4, D2, D0)

IO1 = (D7, D5, D3, D1)

2. Dual Input Address

IO0 = A22, A20, A18, A16, A14, A12, A10, A8, A6, A4, A2, A0, M6, M4, M2, M0

IO1 = A23, A21, A19, A17, A15, A13, A11, A9, A7, A5, A3, A1, M7, M5, M3, M1

3. Security Registers Address:

Security Register 0: A23-A16=00H, A15-A8=00H, A7-A0= Byte Address;

Security Register 1: A23-A16=00H, A15-A8=01H, A7-A0= Byte Address;

Table of ID Definitions:

XT25F04D

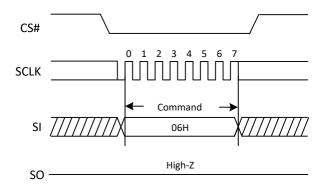
| Operation Code | M7-M0 | ID15-ID8 | ID7-ID0 |
|----------------|-------|----------|---------|
| 9FH | OB | 40 | 13 |
| 90H | OB | | 12 |
| ABH | | | 12 |



6.1. Write Enable (WREN) (06H)

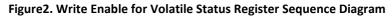
The Write Enable (WREN) command is for setting the Write Enable Latch (WEL) bit. The Write Enable Latch (WEL) bit must be set prior to every Page Program (PP), Sector Erase (SE), Block Erase (BE), Chip Erase (CE), Program Security Register, Erase Security Register and Write Status Register (WRSR) command. The Write Enable (WREN) command sequence: CS# goes low→sending the Write Enable command→CS# goes high.

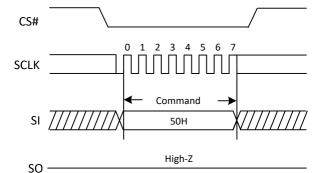
Figure1. Write Enable Sequence Diagram



6.2. Write Enable for Volatile Status Register (50H)

The non-volatile Status Register bits can also be written to as volatile bits. This gives more flexibility to change the system configuration and memory protection schemes quickly without waiting for the typical non-volatile bit write cycles or affecting the endurance of the Status Register non-volatile bits. The Write Enable for Volatile Status Register command must be issued prior to a Write Status Register command and any other commands can't be inserted between them. Otherwise, Write Enable for Volatile Status Register will be cleared. The Write Enable for Volatile Status Register command will not set the Write Enable Latch bit, it is only valid for the Write Status Register command to change the volatile Status Register bit values.



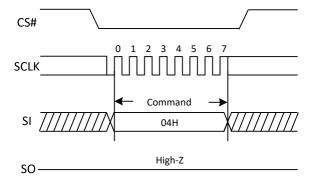


6.3. Write Disable (WRDI) (04H)

The Write Disable command is for resetting the Write Enable Latch (WEL) bit. The Write Disable command sequence: CS# goes low \rightarrow sending the Write Disable command \rightarrow CS# goes high. The WEL bit is reset by following condition: Power-up and upon completion of the Write Status Register, Page Program, Sector Erase, Block Erase and Chip Erase commands.

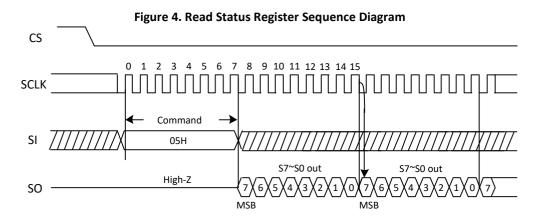


Figure 3. Write Disable Sequence Diagram



6.4. Read Status Register (RDSR) (05H)

The Read Status Register (RDSR) command is for reading the Status Register. The Status Register may be read at any time, even while a Program, Erase or Write Status Register cycle is in progress. When one of these cycles is in progress, it is recommended to check the Write In Progress (WIP) bit before sending a new command to the device. It is also possible to read the Status Register continuously.



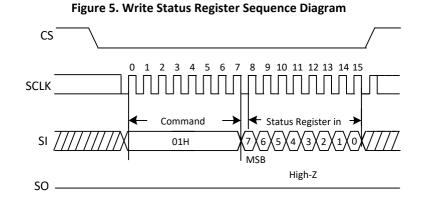
6.5. Write Status Register (WRSR) (01H)

The Write Status Register (WRSR) command allows new values to be written to the Status Register. Before it can be accepted, a Write Enable (WREN) command must previously have been executed. After the Write Enable (WREN) command has been decoded and executed, the device sets the Write Enable Latch (WEL).

The Write Status Register (WRSR) command has no effect on S5, S1 and S0 of the Status Register. CS# must be driven high after the eighth bit of the data byte has been latched in. If not, the Write Status Register (WRSR) command is not executed. As soon as CS# is driven high, the self-timed Write Status Register cycle (whose duration is tw) is initiated. While the Write Status Register cycle is in progress, the Status Register may be read to check the value of the Write In Progress (WIP) bit. The Write In Progress (WIP) bit is 1 during the self-timed Write Status Register cycle, and is 0 when it is completed. When the cycle is completed, the Write Enable Latch (WEL) is reset.

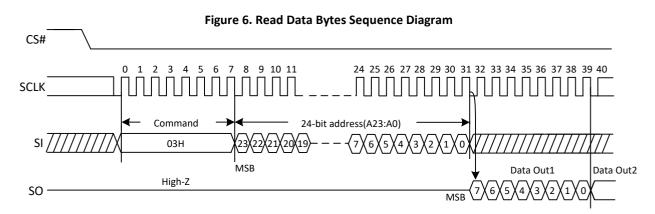
The Write Status Register (WRSR) command allows the user to change the values of the Block Protect (BP2, BP1, BP0) bits, to define the size of the area that is to be treated as read-only, as defined in Table1. The Status Register Write Disable (SRWD) bit is a non-volatile One Time Program(OTP) bit, the Write Status Register (WRSR) command allows the user to set the Status Register Write Disable (SRWD) bit to 1. The Status Register Write Disable (SRWD) bit allow the device to be put in another Software Protected Mode. Once the SRWD bit is set to 1, the Write Status Register (WRSR) command is not executed, and the Block Protect bits (BP2, BP1, BP0) are read only.





6.6. Read Data Bytes (READ) (03H)

The Read Data Bytes (READ) command is followed by a 3-byte address (A23-A0), each bit being latched-in during the rising edge of SCLK. Then the memory content, at that address, is shifted out on SO, each bit being shifted out, at a Max frequency fR, during the falling edge of SCLK. The first byte addressed can be at any location. The address is automatically incremented to the next address after each byte of data is shifted out. The whole memory can, therefore, be read with a single Read Data Bytes (READ) command. Any Read Data Bytes (READ) command, while an Erase, Program or Write cycle is in progress, is rejected without having any effects on the cycle that is in progress.



6.7. Read Data Bytes At Higher Speed (Fast Read) (0BH)

The Read Data Bytes at Higher Speed (Fast Read) command is for fast reading data out. It is followed by a 3byte address (A23-A0) and a dummy byte, each bit being latched-in during the rising edge of SCLK. Then the memory content, at that address, is shifted out on SO, each bit being shifted out, at a Max frequency fC, during the falling edge of SCLK. The first byte addressed can be at any location. The address is automatically incremented to the next address after each byte of data is shifted out.



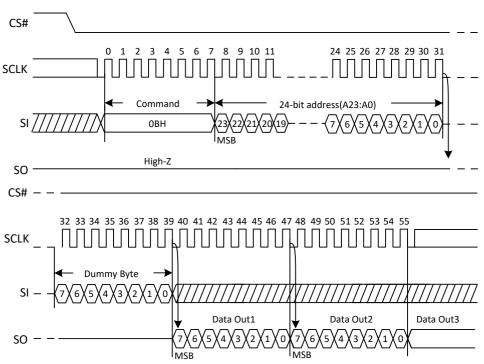
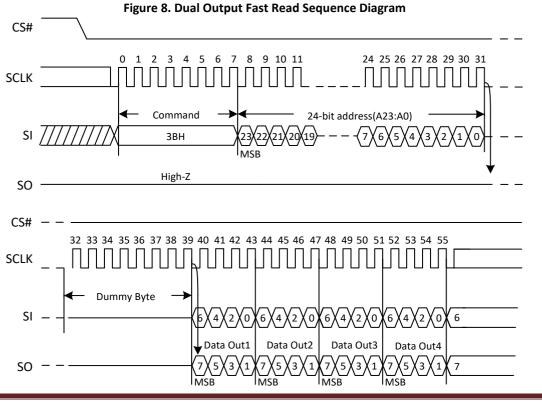


Figure 7. Read Data Bytes at Higher Speed Sequence Diagram

6.8. Dual Output Fast Read (3BH)

The Dual Output Fast Read command is followed by 3-byte address (A23-A0) and a dummy byte, each bit being latched in during the rising edge of SCLK, then the memory contents are shifted out 2-bit per clock cycle from SI and SO. The command sequence is shown in Figure 8. The first byte addressed can be at any location. The address is automatically incremented to the next address after each byte of data is shifted out.



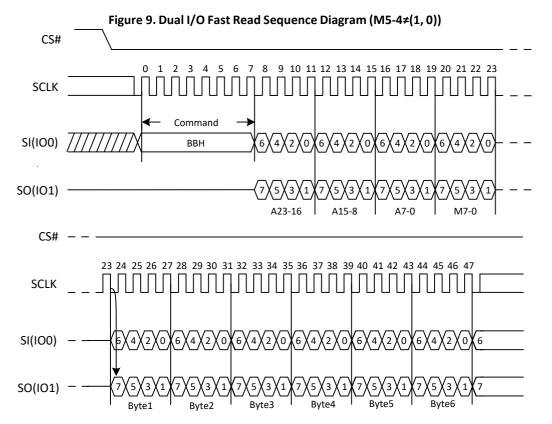


6.9. Dual I/O Fast Read (BBH)

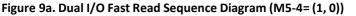
The Dual I/O Fast Read command is similar to the Dual Output Fast Read command but with the capability to input the 3-byte address (A23-0) and a "Continuous Read Mode" byte 2-bit per clock by SI and SO, each bit being latched in during the rising edge of SCLK, then the memory contents are shifted out 2-bit per clock cycle from SI and SO. The command sequence is shown in Figure 9. The first byte addressed can be at any location. The address is automatically incremented to the next address after each byte of data is shifted out.

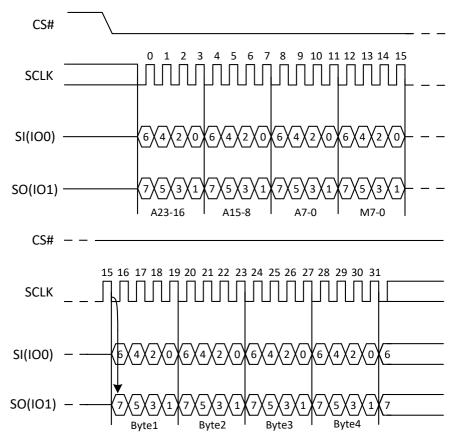
Dual I/O Fast Read with "Continuous Read Mode"

The Dual I/O Fast Read command can further reduce command overhead through setting the "Continuous Read Mode" bits (M7- 0) after the input 3-byte address (A23-A0). If the "Continuous Read Mode" bits (M5- 4) =(1, 0), then the next Dual I/O Fast Read command (after CS# is raised and then lowered) does not require the BBH command code. The command sequence is shown in figure 9. If the "Continuous Read Mode" bits (M5- 4) do not equal (1, 0), the next command requires the first BBH command code, thus returning to normal operation. A "Continuous Read Mode" Reset command can be used to reset (M5-4) before issuing normal command.









6.10. Page Program (PP) (02H)

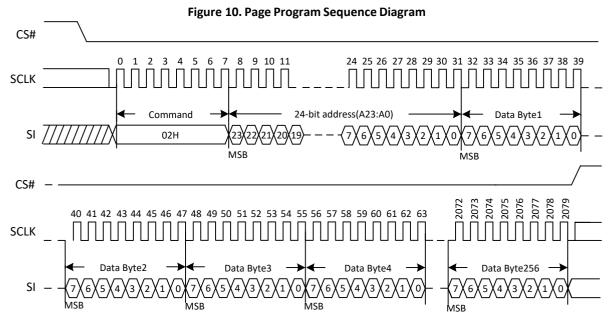
The Page Program (PP) command is for programming the memory. A Write Enable (WREN) command must previously have been executed to set the Write Enable Latch (WEL) bit before sending the Page Program command.

The Page Program (PP) command is entered by driving CS# Low, followed by the command code, three address bytes and at least one data byte on SI. If the 8 least significant address bits (A7-A0) are not all zero, all transmitted data that goes beyond the end of the current page are programmed from the start address of the same page (from the address whose 8 least significant bits (A7-A0) are all zero). CS# must be driven low for the entire duration of the sequence. The Page Program command sequence: CS# goes low \rightarrow sending Page Program command \rightarrow 3-byte address on SI \rightarrow at least 1 byte data on SI \rightarrow CS# goes high. The command sequence is shown in Figure 10. If more than 256 bytes are sent to the device, previously latched data are discarded and the last 256 data bytes are guaranteed to be programmed correctly within the same page. If less than 256 data bytes are sent to device, they are correctly programmed at the requested addresses without having any effects on the other bytes of the same page. CS# must be driven high after the eighth bit of the last data byte has been latched in; otherwise the Page Program (PP) command is not executed.

As soon as CS# is driven high, the self-timed Page Program cycle (whose duration is tPP) is initiated. While the Page Program cycle is in progress, the Status Register may be read to check the value of the Write In Progress (WIP) bit. The Write In Progress (WIP) bit is 1 during the self-timed Page Program cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset.

A Page Program (PP) command applied to a page which is protected by the Block Protect (BP2, BP1, BP0) is not executed.

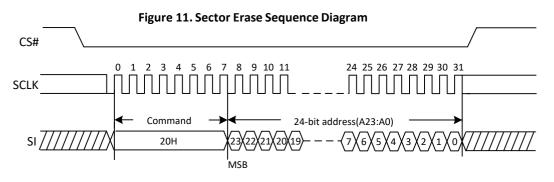




6.11. Sector Erase (SE) (20H)

The Sector Erase (SE) command is for erasing the all data of the chosen sector. A Write Enable (WREN) command must previously have been executed to set the Write Enable Latch (WEL) bit. The Sector Erase (SE) command is entered by driving CS# low, followed by the command code, and 3-address byte on SI. Any address inside the sector is a valid address for the Sector Erase (SE) command. CS# must be driven low for the entire duration of the sequence.

The Sector Erase command sequence: CS# goes low \rightarrow sending Sector Erase command \rightarrow 3-byte address on SI \rightarrow CS# goes high. The command sequence is shown in Figure 11. CS# must be driven high after the eighth bit of the last address byte has been latched in; otherwise the Sector Erase (SE) command is not executed. As soon as CS# is driven high, the self-timed Sector Erase cycle (whose duration is tSE) is initiated. While the Sector Erase cycle is in progress, the Status Register may be read to check the value of the Write In Progress (WIP) bit. The Write In Progress (WIP) bit is 1 during the self-timed Sector Erase cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset. A Sector Erase (SE) command applied to a sector which is protected by the Block Protect (BP2, BP1, BP0) bit (see Table1) is not executed. Note: Power disruption during erase operation will cause incomplete erase and data corruption, thus recommend to perform a re-erase once power resume.



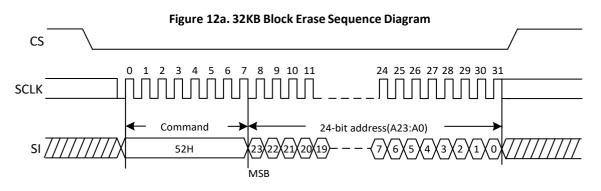
6.12. 32KB Block Erase (BE) (52H)

The 32KB Block Erase (BE) command is for erasing the all data of the chosen block. A Write Enable (WREN) command must previously have been executed to set the Write Enable Latch (WEL) bit. The 32KB Block Erase (BE) command is entered by driving CS# low, followed by the command code, and three address bytes on SI. Any



address inside the block is a valid address for the 32KB Block Erase (BE) command. CS# must be driven low for the entire duration of the sequence.

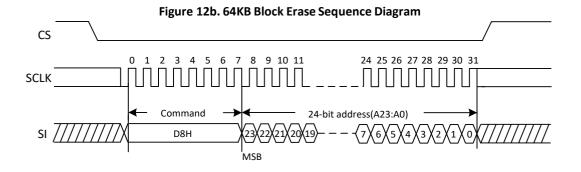
The 32KB Block Erase command sequence: CS# goes low \rightarrow sending 32KB Block Erase command \rightarrow 3-byte address on SI \rightarrow CS# goes high. The command sequence is shown in Figure12a. CS# must be driven high after the eighth bit of the last address byte has been latched in; otherwise the 32KB Block Erase (BE) command is not executed. As soon as CS# is driven high, the self-timed Block Erase cycle (whose duration is tBE) is initiated. While the Block Erase cycle is in progress, the Status Register may be read to check the value of the Write In Progress (WIP) bit. The Write In Progress (WIP) bit is 1 during the self-timed Block Erase cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset. A 32KB Block Erase (BE) command applied to a block which is protected by the Block Protect (BP2, BP1, BP0) bits (see Table1) will not be executed. Note: Power disruption during erase operation will cause incomplete erase and data corruption, thus recommend to perform a re-erase once power resume.



6.13. 64KB Block Erase (BE) (D8H)

The 64KB Block Erase (BE) command is for erasing the all data of the chosen block. A Write Enable (WREN) command must previously have been executed to set the Write Enable Latch (WEL) bit. The 64KB Block Erase (BE) command is entered by driving CS# low, followed by the command code, and three address bytes on SI. Any address inside the block is a valid address for the 64KB Block Erase (BE) command. CS# must be driven low for the entire duration of the sequence.

The 64KB Block Erase command sequence: CS# goes low \rightarrow sending 64KB Block Erase command \rightarrow 3byte address on SI \rightarrow CS# goes high. The command sequence is shown in Figure 12b. CS# must be driven high after the eighth bit of the last address byte has been latched in; otherwise the 64KB Block Erase (BE) command is not executed. As soon as CS# is driven high, the self-timed Block Erase cycle (whose duration is tBE) is initiated. While the Block Erase cycle is in progress, the Status Register may be read to check the value of the Write In Progress (WIP) bit. The Write In Progress (WIP) bit is 1 during the self-timed Block Erase cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset. A 64KB Block Erase (BE) command applied to a block which is protected by the Block Protect (BP2, BP1, BP0) bits (see Table1) is not executed. Note: Power disruption during erase operation will cause incomplete erase and data corruption, thus recommend to perform a re-erase once power resume.





6.14. Chip Erase (CE) (60/C7H)

The Chip Erase (CE) command is for erasing the all data of the chip. A Write Enable (WREN) command must previously have been executed to set the Write Enable Latch (WEL) bit .The Chip Erase (CE) command is entered by driving CS# Low, followed by the command code on Serial Data Input (SI). CS# must be driven Low for the entire duration of the sequence.

The Chip Erase command sequence: CS# goes low \rightarrow sending Chip Erase command \rightarrow CS# goes high. The command sequence is shown in Figure 13. CS# must be driven high after the eighth bit of the command code has been latched in, otherwise the Chip Erase command is not executed. As soon as CS# is driven high, the self-timed Chip Erase cycle (whose duration is tCE) is initiated. While the Chip Erase cycle is in progress, the Status Register may be read to check the value of the Write In Progress (WIP) bit. The Write In Progress (WIP) bit is 1 during the self-timed Chip Erase cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset. The Chip Erase (CE) command is executed if the Block Protect (BP2, BP1, BP0) bits are all 0. The Chip Erase (CE) command is ignored if one or more sectors are protected. Note: Power disruption during erase operation will cause incomplete erase and data corruption, thus recommend to perform a re-erase once power resume.

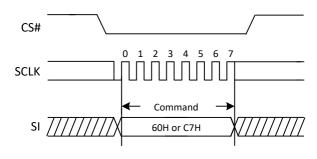


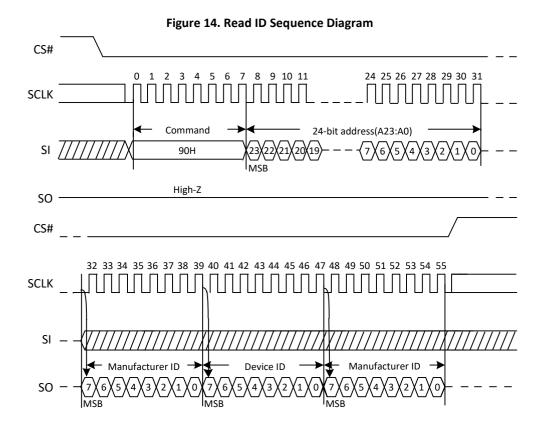
Figure 13. Chip Erase Sequence Diagram



6.15. Read Manufacture ID/ Device ID (REMS) (90H)

The Read Manufacturer/Device ID command is an alternative to the Release from Power-Down / Device ID command that provides both the JEDEC assigned Manufacturer ID and the specific Device ID.

The command is initiated by driving the CS# pin low and shifting the command code "90H" followed by a 24-bit address (A23-A0) of 000000H. After which, the Manufacturer ID and the Device ID are shifted out on the falling edge of SCLK with most significant bit (MSB) first is shown in Figure 14. If the 24-bit address is initially set to 000001H, the Device ID will be read first.

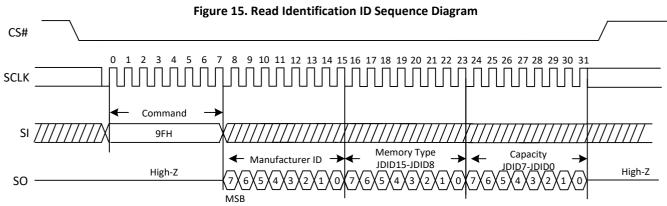


6.16. Read Identification (RDID) (9FH)

The Read Identification (RDID) command allows the 8-bit manufacturer identification to be read, followed by two bytes of device identification. The device identification indicates the memory type in the first byte, and the memory capacity of the device in the second byte. Any Read Identification (RDID) command while an Erase or Program cycle is in progress, is not decoded, and has no effect on the cycle that is in progress.

The device is first selected by driving CS# to low. Then, the 8-bit command code for the command is shifted in. This is followed by the 24-bit device identification, stored in the memory, being shifted out on Serial Data Output, each bit being shifted out during the falling edge of Serial Clock. The command sequence is shown in Figure15. The Read Identification (RDID) command is terminated by driving CS# to high at any time during data output. When CS# is driven high, the device is put in the Standby Mode. Once in the Standby Mode, the device waits to be selected, so that it can receive, decode and execute commands.



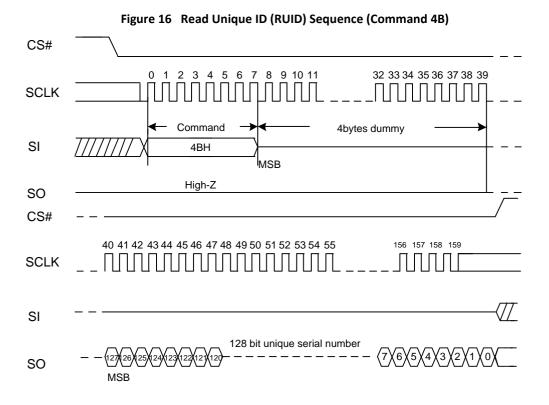


6.17. Read Unique ID (4BH)

The Read Unique ID command accesses a factory-set read-only 128bit number that is unique to each device. The Unique ID can be used in conjunction with user software methods to help prevent copying or cloning of a system.

The Read Unique ID command sequence: CS# goes low \rightarrow sending Read Unique ID command \rightarrow 4 dummy clocks \rightarrow 128bit Unique ID Out \rightarrow CS# goes high.

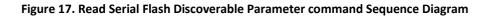
The command sequence is show below.



6.18. Read Serial Flash Discoverable Parameter (5AH)

The Serial Flash Discoverable Parameter (SFDP) standard provides a consistent method of describing the functional and feature capabilities of serial flash devices in a standard set of internal parameter tables. These parameter tables can be interrogated by host system software to enable adjustments needed to accommodate divergent features from multiple vendors. The concept is similar to the one found in the Introduction of JEDEC Standard, JESD68 on CFI. SFDP is a standard of JEDEC Standard No.216.





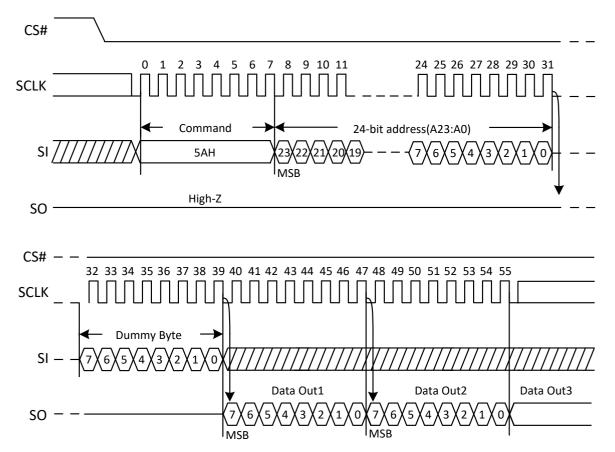




Table 3. Parameter Table (0): Signature and Parameter Identification Data Values

| Description | Comment | Add(H) (Byte) | DW Add (Bit) | Data | Data |
|--|--|------------------|-----------------|------|------|
| SFDP Signature | Fixed:50444653H | 00H | 07:00 | 53H | 53H |
| | | 01H | 15:08 | 46H | 46H |
| | | 02H | 23:16 | 44H | 44H |
| | | 03H | 31:24 | 50H | 50H |
| SFDP Minor Revision Number | Start from 00H | 04H | 07:00 | 02H | 02H |
| SFDP Major Revision Number | Start from 01H | 05H | 15:08 | 01H | 01H |
| Number of Parameters Headers | Start from 00H | 06H | 23:16 | 01H | 01H |
| Unused | Contains 0xFFH and can never be changed | 07H | 31:24 | FFH | FFH |
| ID number (JEDEC) | 00H: It indicates a JEDEC specified header | 08H | 07:00 | 00Н | 00H |
| Parameter Table Minor Revision Number | Start from 0x00H | 09Н | 15:08 | 02H | 02H |
| Parameter Table Major Revision Number | Start from 0x01H | 0AH | 23:16 | 01H | 01H |
| Parameter Table Length (in double word) | How many DWORDs in the Parameter table | OBH | 31:24 | 09H | 09H |
| Parameter Table Pointer (PTP) | First address of JEDEC Flash | 0CH | 07:00 | 30H | 30H |
| | Parameter table | 0DH | 15:08 | 00H | 00H |
| | | 0EH | 23:16 | 00H | 00H |
| Unused | Contains 0xFFH and can never be changed | OFH | 31:24 | FFH | FFH |
| ID Number | It is indicates XTX | 10H | 07:00 | OBH | OBH |
| (XTX Manufacturer ID) | manufacturer ID | | | | |
| Parameter Table Minor Revision Number | Start from 0x00H | 11H | 15:08 | 02H | 02H |
| Parameter Table Major Revision Number | Start from 0x01H | 12H | 23:16 | 01H | 01H |
| Parameter Table Length | How many DWORDs in the | 13H | 31:24 | 03H | 03H |
| (in double word) | Parameter table | | | | |
| Parameter Table Pointer (PTP) | First address of XTX Flash Parame- | 14H | 07:00 | 60H | 60H |
| | ter table | 15H | 15:08 | 00H | 00H |
| | | 16H | 23:16 | 00H | 00H |
| Unused | Contains 0xFFH and can never be changed | 17H | 31:24 | FFH | FFH |



Parameter Table (1): JEDEC Flash Parameter Tables

| Description | Comment | Add(H) (Byte) | DW Add (Bit) | Data | Data |
|---|---|------------------|-----------------|--------|------|
| Block/Sector Erase Size | 00: Reserved; 01: 4KB erase; 10: Reserved; 11: not support 4KB erase | | 01:00 | 01b | |
| Write Granularity | 0: 1Byte, 1: 64Byte or larger | | 02 | 1b | - |
| Write Enable Instruction Requested for Writing to Volatile Status Registers | 0: Nonvolatile status bit 1: Volatile status bit (BP status register bit) | 30Н | 03 | Ob | Е5Н |
| Write Enable Opcode Select for Writ- ing to Volatile Status Registers | 0: Use 50H Opcode, 1: Use 06H Opcode, Note: If target flash status register is Nonvolatile, then bits 3 and 4 must be set to 00b. | | 04 | Ob | |
| Unused | Contains 111b and can never be changed | | 07:05 | 111b | |
| 4KB Erase Opcode | | 31H | 15:08 | 20H | 20H |
| (1-1-2) Fast Read | 0=Not support, 1=Support | | 16 | 1b | |
| Address Bytes Number used in addressing flash array | 00: 3Byte only, 01: 3 or 4Byte, 10: 4Byte only, 11: Reserved | | 18:17 | 00b | |
| Double Transfer Rate (DTR) clocking | 0=Not support, 1=Support | 32H | 19 | Ob | 91H |
| (1-2-2) Fast Read | 0=Not support, 1=Support | | 20 | 1b | - |
| (1-4-4) Fast Read | 0=Not support, 1=Support | | 21 | 0b | - |
| (1-1-4) Fast Read | 0=Not support, 1=Support | | 22 | Ob | |
| Unused | | | 23 | 1b | |
| Unused | | 33H | 31:24 | FFH | FFH |
| Flash Memory Density | | 37H:34H | 31:00 | 003FF | FFH |
| (1-4-4) Fast Read Number of Wait states | 0 0000b: Wait states (Dummy Clocks) not support (M7-M0 excluded) | 38H | 04:00 | 00000b | 00H |
| (1-4-4) Fast Read Number of Mode Bits | 000b:Mode Bits not support | | 07:05 | 000b | |
| (1-4-4) Fast Read Opcode | | 39H | 15:08 | FFH | FFH |
| (1-1-4) Fast Read Number of Wait states | 0 0000b: Wait states (Dummy Clocks) not support | 2411 | 20:16 | 00000b | 0011 |
| (1-1-4) Fast Read Number of Mode Bits | 000b:Mode Bits not support | ЗАН | 23:21 | 000b | 00H |
| (1-1-4) Fast Read Opcode | | 3BH | 31:24 | FFH | FFH |



| | | Add(H) | DW Add | | |
|--|---|---------|--------|---------|-------|
| Description | Comment | (Byte) | (Bit) | Data | Data |
| (1-1-2) Fast Read Number of Wait states | 0 0000b: Wait states (Dummy Clocks) not support | ЗСН | 04:00 | 01000b | 08H |
| (1-1-2) Fast Read Number of Mode Bits | 000b: Mode Bits not support | Jen | 07:05 | 000b | |
| (1-1-2) Fast Read Opcode | | 3DH | 15:08 | 3BH | 3BH |
| (1-2-2) Fast Read Number of Wait states | 0 0000b: Wait states (Dummy Clocks) not support (M7-M0 excluded) | 3EH | 20:16 | 000000b | 40H |
| (1-2-2) Fast Read Number of Mode Bits | 000b: Mode Bits not support 010b: 8bit Mode Bits = 2 dummy clocks (M7-M0) | | 23:21 | 010b | |
| (1-2-2) Fast Read Opcode | | 3FH | 31:24 | BBH | BBH |
| (2-2-2) Fast Read | 0=not support 1=support | | 00 | 0b | |
| Unused | | 40H | 03:01 | 111b | EEH |
| (4-4-4) Fast Read | 0=not support 1=support | | 04 | 0b | |
| Unused | | | 07:05 | 111b | - |
| Unused | | 43H:41H | 31:08 | 0xFFH | 0xFFH |
| Unused | | 45H:44H | 15:00 | 0xFFH | 0xFFH |
| (2-2-2) Fast Read Number of Wait states | 0 0000b: Wait states (Dummy Clocks) not support | 46H | 20:16 | 00000b | 00Н |
| (2-2-2) Fast Read Number of Mode Bits | 000b: Mode Bits not support | | 23:21 | 000b | |
| (2-2-2) Fast Read Opcode | | 47H | 31:24 | FFH | FFH |
| Unused | | 49H:48H | 15:00 | 0xFFH | 0xFFH |
| (4-4-4) Fast Read Number of Wait states | 0 0000b: Wait states (Dummy Clocks) not support (M7-M0 included) | 4AH | 20:16 | 00000b | 00H |
| (4-4-4) Fast Read Number of Mode Bits | 000b: Mode Bits not support | | 23:21 | 000b | |
| (4-4-4) Fast Read Opcode | | 4BH | 31:24 | FFH | FFH |
| Sector Type 1 Size | Sector/block size=2^N Bytes 0x00b: this sector type don't exist | 4CH | 07:00 | 0CH | ОСН |
| Sector Type 1 erase Opcode | | 4DH | 15:08 | 20H | 20H |
| Sector Type 2 Size | Sector/block size=2^N Bytes 0x00b: this sector type don't exist | 4EH | 23:16 | OFH | OFH |
| Sector Type 2 erase Opcode | | 4FH | 31:24 | 52H | 52H |
| Sector Type 3 Size | Sector/block size=2^N Bytes 0x00b: this sector type don't exist | 50H | 07:00 | 10H | 10H |
| Sector Type 3 erase Opcode | | 51H | 15:08 | D8H | D8H |
| Sector Type 4 Size | Sector/block size=2^N Bytes 0x00b: this sector type don't exist | 52H | 23:16 | 00Н | 00H |
| Sector Type 4 erase Opcode | | 53H | 31:24 | FFH | FFH |



Parameter Table (2): XTX Flash Parameter Tables

| Description | Comment | Add(H) (Byte) | DW Add (Bit) | Data | Data |
|--|---|------------------|-----------------|---------------------|-------|
| Vcc Supply Maximum Voltage | 2000H=2.000V 2700H=2.700V 3600H=3.600V | 91H:90H | 15:00 | 3600H | 3600H |
| Vcc Supply Minimum Voltage | 1650H=1.650V 2250H=2.250V 2350H=2.350V 2700H=2.700V | 93H:92H | 31:16 | 2700H | 2700H |
| HW Reset# pin | 0=not support 1=support | | 00 | 0b | |
| HW Hold# pin | 0=not support 1=support | | 01 | Ob | |
| Deep Power Down Mode | 0=not support 1=support | | 02 | Ob | |
| SW Reset | 0=not support 1=support | | 03 | 1b | |
| SW Reset Opcode | Should be issue Reset Enable(66H) before Reset cmd. | 95H:94H | 11:04 | 1001 1001b (99H) | 4998H |
| Program Suspend/Resume | 0=not support 1=support | _ | 12 | Ob | - |
| Erase Suspend/Resume | 0=not support 1=support | _ | 13 | Ob | - |
| Unused | | _ | 14 | 1b | - |
| Wrap-Around Read mode | 0=not support 1=support | _ | 15 | Ob | - |
| Wrap-Around Read mode Opcode | | 96H | 23:16 | FFH | FFH |
| Wrap-Around Read data length | 08H:support 8B wrap-around read 16H:8B&16B 32H:8B&16B&32B 64H:8B&16B&32B&64B | 97H | 31:24 | FFH | FFH |
| Individual block lock | 0=not support 1=support | | 00 | Ob | |
| Individual block lock bit (Volatile/Nonvolatile) | 0=Volatile 1=Nonvolatile | | 01 | Ob | |
| Individual block lock Opcode | | | 09:02 | FFH | - |
| Individual block lock Volatile protect bit default protect status | 0=protect 1=unprotect | 9BH:98H | 10 | Ob | EBFCH |
| Secured OTP | 0=not support 1=support | | 11 | 1b | |
| Read Lock | 0=not support 1=support | — | 12 | 0b | |
| Permanent Lock | 0=not support 1=support | — | 13 | 1b | |
| Unused | | — | 15:14 | 11b | |
| Unused | | | 31:16 | FFFFH | FFFFH |



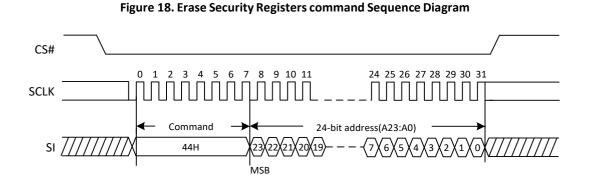
6.19. Erase Security Registers (44H)

The XT25F04D provides two 256-byte Security Registers which only erased all at once but able to program individually. These registers may be used by the system manufacturers to store security and other important information separately from the main memory array.

The Erase Security Registers command is similar to Sector/Block Erase command. A Write Enable (WREN) command must previously have been executed to set the Write Enable Latch (WEL) bit.

The Erase Security Registers command sequence: CS# goes low, sending Erase Security Registers Command, CS# goes high. The command sequence is shown in Figure 18. CS# must be driven high after the eighth bit of the command code has been latched in, otherwise the Erase Security Registers command is not executed. As soon as CS# is driven high, the self-timed Erase Security Registers cycle (whose duration is tSE) is initiated. While the Erase Security Registers cycle is in progress, the Status Register may be read to check the value of the Write In Progress (WIP) bit. The Write In Progress (WIP) bit is 1 during the self-timed Erase Security Registers cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset. The Security Registers Lock Bit (LB) in the Status Register can be used to OTP protect the security registers. Once the LB bit is set to 1, the Security Registers will be permanently locked; the Erase Security Registers command will be ignored.

| Address | A23-A16 | A15-A8 | A7-A0 |
|----------------------|---------|--------|------------|
| Security Registers 0 | 00H | 00H | Don't Care |
| Security Registers 1 | 00H | 01H | Don't Care |



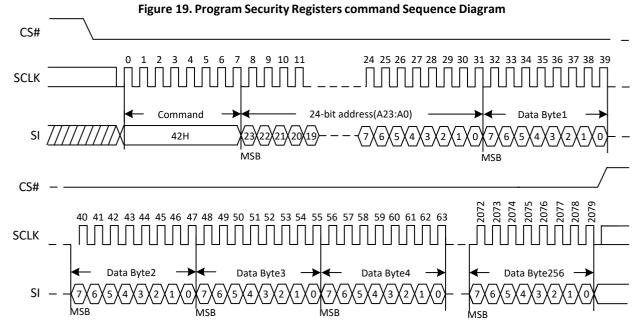
6.20. Program Security Registers (42H)

The Program Security Registers command is similar to the Page Program command. It allows from 1 to 256 bytes Security Registers data to be programmed. A Write Enable (WREN) command must previously have been executed to set the Write Enable Latch (WEL) bit before sending the Program Security Registers command. The Program Security Registers command is entered by driving CS# Low, followed by the command code (42H), three address bytes and at least one data byte on SI. As soon as CS# is driven high, the self-timed Program Security Registers cycle (whose duration is tPP) is initiated. While the Program Security Registers cycle is in progress, the Status Register may be read to check the value of the Write In Progress (WIP) bit. The Write In Progress (WIP) bit is 1 during the self-timed Program Security Registers cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset.

If the Security Registers Lock Bit (LB) is set to 1, the Security Registers will be permanently locked. Program Security Registers command will be ignored.

| Address | A23-A16 | A15-A8 | A7-A0 |
|----------------------|---------|--------|--------------|
| Security Registers 0 | 00H | 00H | Byte Address |
| Security Registers 1 | 00H | 01H | Byte Address |

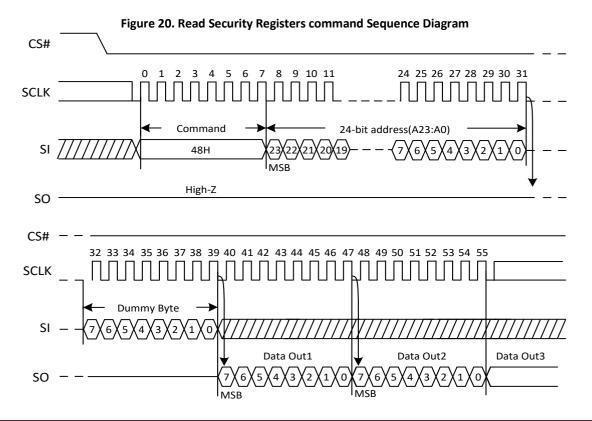




6.21. Read Security Registers (48H)

The Read Security Registers command is similar to Fast Read command. The command is followed by a 3byte address (A23-A0) and a dummy byte, each bit being latched-in during the rising edge of SCLK. Then the memory content, at that address, is shifted out on SO, each bit being shifted out, at a Max frequency fC, during the falling edge of SCLK. The first byte addressed can be at any location. The address is automatically incremented to the next address after each byte of data is shifted out. Once the A9-A0 address reaches the last byte of the register (Byte 3FFH), it will reset to 000H, the command is completed by driving CS# high.

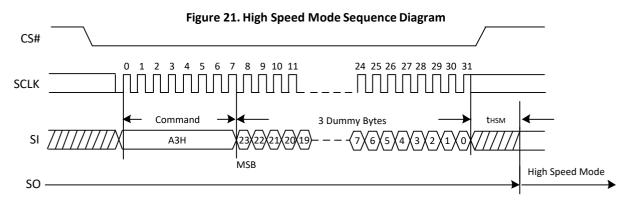
| Address | A23-A16 | A15-A8 | A7-A0 |
|----------------------|---------|--------|--------------|
| Security Registers 0 | 00H | 00H | Byte Address |
| Security Registers 1 | 00H | 01H | Byte Address |





6.22. High Speed Mode(HSM)(A3H)

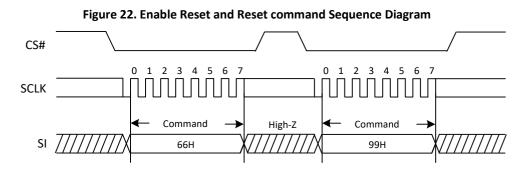
The High Speed Mode (HSM) command must be executed prior to Dual or Quad I/O commands when operating at high frequencies (see fR and fC1 in AC Electrical Characteristics). This command allows pre-charging of internal charge pumps so the voltages required for accessing the flash memory array are readily available. The command sequence: CS# goes low Sending A3H command Sending 3-dummy byte CS# goes high. See Figure 21. After the HSM command is executed, the device will maintain a slightly higher standby current (ICC8) than standard SPI operation. The Release from Power-Down or HSM command (ABH) can be used to return to standard SPI standby current (ICC1). In addition, Write Enable command (06H) and Power-Down command (B9H) will also release the device from HSM mode back to standard SPI standby state.



6.23. Enable Reset (66H) and Reset (99H)

If the Reset command is accepted, any on-going internal operation will be terminated and the device will return to its default power-on state and lose all the current volatile settings, such as Volatile Status Register bits, Write Enable Latch status (WEL).

The "Reset (99H)" command sequence as follow: CS# goes low \rightarrow Sending Enable Reset command \rightarrow CS# goes high \rightarrow CS# goes low \rightarrow Sending Reset command \rightarrow CS# goes high. Once the Reset command is accepted by the device, the device will take approximately tRSTR to reset. During this period, no command will be accepted.



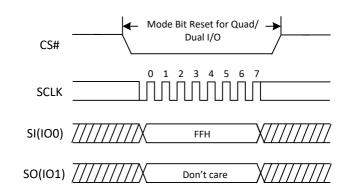


6.24. Continuous Read Mode Reset (CRMR) (FFH)

The Dual I/O Fast Read operations, "Continuous Read Mode" bits (M7-0) are implemented to further reduce command overhead. By setting the (M7-0) to AXH, the next Dual I/O Fast Read operations do not require the BBH command code.

Because the XT25F04D has no hardware reset pin, so if Continuous Read Mode bits are set to "AXH", the XT25F04D will not recognize any standard SPI commands. So Continuous Read Mode Reset command will release the Continuous Read Mode from the "AXH" state and allow standard SPI command to be recognized. The command sequence is shown in Figure 23.

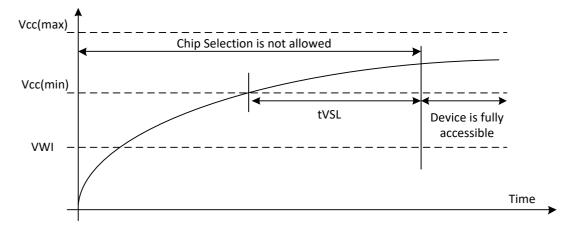
Figure 23. Continuous Read Mode Reset Sequence Diagram





7. ELECTRICAL CHARACTERISTICS

7.1. Power-on Timing



Power-Up Timing and Write Inhibit Threshold

| Symbol | Parameter | Min | Max | Unit |
|------------------|-----------------------|-----|-----|------|
| t _{vsL} | VCC(min) To CS# Low | 1 | | ms |
| V _{WI} | Write Inhibit Voltage | 1.5 | 2.5 | V |

7.2. Initial Delivery State

The device is delivered with the memory array erased: all bits are set to 1(each byte contains FFH). The Status Register contains 00H (all Status Register bits are 0).

7.3. Data Retention and Endurance

| Parameter | Typical | Unit |
|-------------------------|---------|--------|
| Data Retention Time | 20 | Years |
| Erase/Program Endurance | 100K | Cycles |

7.4. Latch up Characteristics

| Parameter | Min | Max |
|--|--------|----------|
| Input Voltage Respect To VSS On I/O Pins | -1.0V | VCC+1.0V |
| VCC Current | -100mA | 100mA |



7.5. Absolute Maximum Ratings

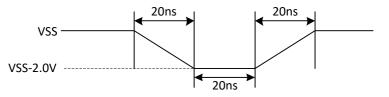
| Parameter | Value | Unit |
|--------------------------------|-------------|------|
| Ambient Operating Temperature | -40 to 85 | °C |
| Storage Temperature | -65 to 150 | °C |
| Output Short Circuit Current | 200 | mA |
| Applied Input / Output Voltage | -0.5 to 4.0 | V |
| VCC | -0.5 to 4.0 | V |

7.6. Capacitance Measurement Condition

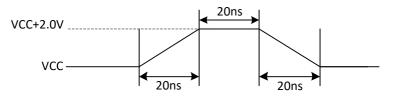
| Symbol | Parameter | Min | Тур | Max | Unit | Conditions |
|--------|---------------------------------|------------------|------------------|-----|------|------------|
| CIN | Input Capacitance | | | 6 | рF | VIN=0V |
| COUT | Output Capacitance | | | 8 | pF | VOUT=0V |
| CL | Load Capacitance | 30 | | pF | | |
| | Input Rise And Fall time | | | 5 | ns | |
| | Input Pulse Voltage | 0.1 | 0.1VCC to 0.8VCC | | V | |
| | Input Timing Reference Voltage | 0.2VCC to 0.7VCC | | V | | |
| | Output Timing Reference Voltage | | 0.5VCC | | V | |

Figure 24. Input Test Waveform and Measurement Level

Maximum Negative Overshoot Waveform



Maximum Positive Overshoot Waveform





7.7. DC Characteristics

(T=-40°C~85°C,VCC=2.7~3.6V)

| Symbol | Parameter | Test Condition | Min. | Тур | Max. | Unit | | |
|--------|-------------------------|-----------------------|---------|-----|---------|------|--|--|
| ILI | Input Leakage Current | | | | ±2 | μA | | |
| ILO | Output Leakage Current | | | | ±2 | μA | | |
| ICC1 | Standby Current | CS#=VCC | | 13 | 30 | μΑ | | |
| | Standby Current | VIN=VCC or VSS | | 15 | 50 | μА | | |
| | | CLK=0.1VCC/0.9VCC at | | | | | | |
| | | 40MHZ,Q=Open(*1 I/O) | | 5 | 7 | mA | | |
| | | CLK=0.1VCC/0.9VCC at | | | | | | |
| | | 50MHZ,Q=Open(*1 I/O) | | 6 | 8 | mA | | |
| | | CLK=0.1VCC/0.9VCC at | | | | | | |
| | | 120MHZ,Q=Open(*1 I/O) | | 8 | 12 | mA | | |
| ICC3 | Operating Current(Read) | CLK=0.1VCC/0.9VCC at | | | | | | |
| | | 40MHZ,Q=Open(*2 I/O) | | 5 | 8 | mA | | |
| | | CLK=0.1VCC/0.9VCC at | | 6 | | | | |
| | | 50MHZ,Q=Open(*2 I/O) | | | 9 | mA | | |
| | | CLK=0.1VCC/0.9VCC at | | | | | | |
| | | 120MHZ,Q=Open(*2 I/O) | | 10 | 15 | mA | | |
| ICC4 | Operating Current(PP) | CS#=VCC | | 10 | 20 | mA | | |
| ICC5 | Operating Current(WRSR) | CS#=VCC | | 10 | 20 | mA | | |
| ICC6 | Operating Current(SE) | CS#=VCC | | 10 | 20 | mA | | |
| ICC7 | Operating Current(BE) | CS#=VCC | | 10 | 20 | mA | | |
| VIL | Input Low Voltage | | -0.5 | | 0.2VCC | V | | |
| VIH | Input High Voltage | | 0.7VCC | | VCC+0.4 | v | | |
| VOL | Output Low Voltage | IOL=1.6mA | | | 0.4 | V | | |
| VOH | Output High Voltage | IOH=-100uA | VCC-0.2 | | | V | | |

Note:

1. Typical values given for TA=25°C.

2. Value guaranteed by design and/or characterization, not 100% tested in production.



7.8. AC Characteristics

(T=-40°C~85°C,VCC=2.7~3.6V, C_L=30pF)

| Symbol | Parameter | Min. | Тур. | Max. | Unit |
|--------|---|-------|------|------|------|
| fC | Serial Clock Frequency For: Fast Read(OBH), Dual Output(3BH) | DC | | 120 | MHz |
| fC1 | Serial Clock Frequency For: Dual I/O(BBH) | DC | | 104 | MHz |
| fR | Serial Clock Frequency For: Read (03H/9FH/90H) | DC | | 40 | MHz |
| tCLH | Serial Clock High Time | 45%PC | | | ns |
| tCLL | Serial Clock Low Time | 45%PC | | | ns |
| tCLCH | Serial Clock Rise Time(Slew Rate) | 0.2 | | | V/ns |
| tCHCL | Serial Clock Fall Time(Slew Rate) | 0.2 | | | V/ns |
| tSLCH | CS# Active Setup Time | 5 | | | ns |
| tCHSH | CS# Active Hold Time | 5 | | | ns |
| tSHCH | CS# Not Active Setup Time | 5 | | | ns |
| tCHSL | CS# Not Active Hold Time | 5 | | | ns |
| tSHSL | CS# High Time (read/write) | 20 | | | ns |
| tSHQZ | Output Disable Time | | | 6 | ns |
| tCLQX | Output Hold Time | 1 | | | ns |
| tDVCH | Data In Setup Time | 2 | | | ns |
| tCHDX | Data In Hold Time | 2 | | | ns |
| tCLQV | Clock Low To Output Valid | | | 6.5 | ns |
| tWHSL | Write Protect Setup Time Before CS# Low | 20 | | | ns |
| tSHWL | Write Protect Hold Time After CS# High | 100 | | | ns |
| tDP | CS# High To Deep Power-Down Mode | | | 0.1 | us |
| tRES1 | CS# High To Standby Mode Without Electronic Signature Read | | | 0.5 | us |
| tRES2 | CS# High To Standby Mode With Electronic Signature Read | | 0.5 | us | |
| tW | Write Status Register Cycle Time | | 5 | 600 | ms |
| tPP | Page Programming Time | | 0.9 | 3.0 | ms |
| tBP | Byte Program Time | | 3 | | us |
| tSE | Sector Erase Time | | 90 | 600 | ms |
| tBE | Block Erase Time(32K Bytes) | | 0.3 | 1.0 | s |
| tBE | Block Erase Time(64K Bytes) | | 0.45 | 1.5 | s |
| tCE | Chip Erase Time (4M) | | 3.2 | 10.0 | s |

Note:

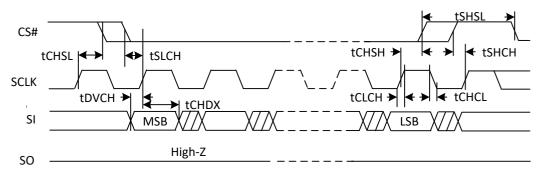
1. Clock high or Clock low must be more than or equal to 45%PC, PC=1/fC(Max).

2. Typical values given for TA=25°C.

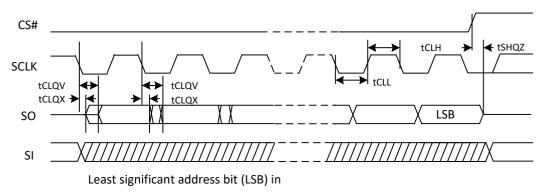
3. Value guaranteed by design and/or characterization, not 100% tested in production.







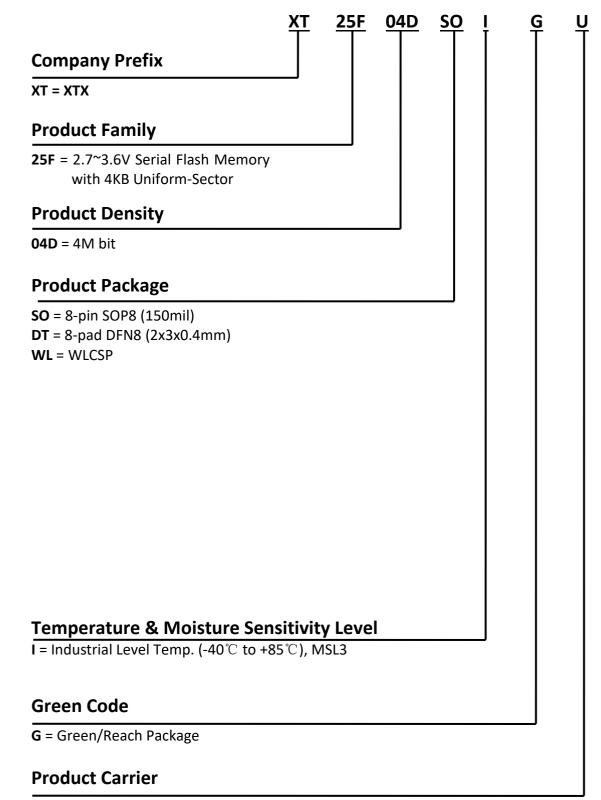






8. ORDERING INFORMATION

The ordering part number is formed by a valid combination of the following

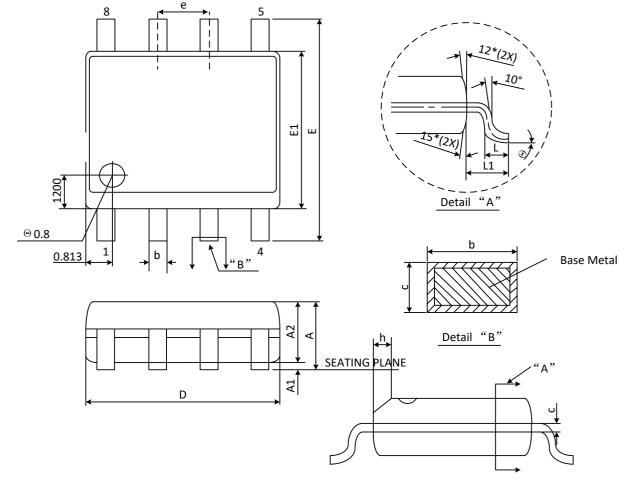


U = Tube; T = Tape & Reel; A = Tray



9. PACKAGE INFORMATION

9.1. Package SOP8 150MIL



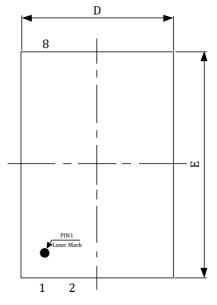
| | Dimensions in Millimeters | | | | |
|--------|---------------------------|-------|-------|--|--|
| Symbol | Min | Norm | Max | | |
| А | 1.350 | | 1.750 | | |
| A1 | 0.100 | | 0.250 | | |
| A2 | 1.300 | | 1.500 | | |
| b | 0.330 | | 0.510 | | |
| С | 0.190 | | 0.250 | | |
| D | 4.700 | 4.900 | 5.000 | | |
| E1 | 3.800 | 3.900 | 4.000 | | |
| е | | 1.270 | | | |
| E | 5.800 | 6.000 | 6.200 | | |
| h | 0.2500 | 0.350 | 0.500 | | |
| L | 0.508 | 0.635 | 0.762 | | |
| L1 | 0.837 | 1.040 | 1.243 | | |
| θ | 0° | | 8° | | |

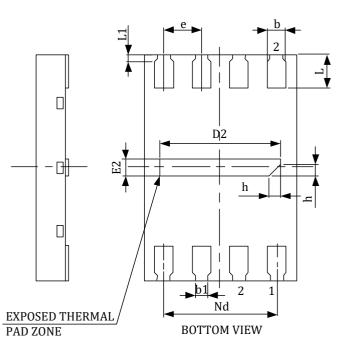
Note:

- 1. Coplanarity: 0.1mm
- 2. Max allowable mold flash is 0.15mm at the package ends. 0.25mm between leads.
- 3. All dimensions follow JEDEC MS-012 standard.

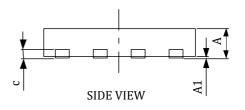


9.2. Package DFN8 (2x3x0.4) mm









| | Dimensions in Millimeters | | | | |
|--------|---------------------------|------|------|--|--|
| Symbol | Min | Norm | Max | | |
| Α | 0.36 | | 0.40 | | |
| A1 | 0 | 0.02 | 0.05 | | |
| b | 0.20 | 0.25 | 0.30 | | |
| С | 0.127REF | | | | |
| D | 1.90 | 2.00 | 2.10 | | |
| D2 | 1.50 | 1.60 | 1.70 | | |
| е | 0.50 BSC | | | | |
| Nd | 1.50 BSC | | | | |
| E | 2.90 | 3.00 | 3.10 | | |
| E2 | 0.10 | 0.20 | 0.30 | | |
| L | 0.40 | 0.45 | 0.50 | | |
| L1 | 0.05 | 0.10 | 0.15 | | |
| h | 0.05 | 0.15 | 0.25 | | |



10. REVISION HISTORY

| Revision | Description | |
|----------|--|---------------|
| 1.0 | Preliminary version base 2M/4M rev 1.4, 1.3 | Jan-14-2019 |
| 1.1 | Correct typos in SRWD description and add on 6.31. Read Serial Flash Discoverable Parameter tables, modified AC Characteristics according to qualification results | May-13-2019 |
| 1.2 | Add DFN8 (2x3x0.4) mm package type. Revise AC Characteristics (page #37) TsE max to 200mS. | Jul-12-2019 |
| 1.3 | Updated Note for power-down requirements at 7.1, deleted package SOP8 208mil, TSSOP8. Reserved SRWD bit and added Note. | Aug-7-2019 |
| 1.4 | Deleted related contents about deep power down, updated AC Characteristics | Dec-17-2019 |
| 1.5 | Updated figure of A3H | April 9, 2020 |
| 1.6 | Updated SFDP Table | Aug 12, 2020 |
| 1.7 | Deleted DFN 2x3x0.55mm package | Sep 7, 2020 |
| 1.8 | Add DFN8 connection diagram, updated Pin Description and data protection, change the sequence of status register and data protection. | Sep 24, 2020 |