

## Description

The MT5087/MT5088 is a high efficiency fully integrated synchronous Boost converter with builtin main switch and synchronous switch. The device has 20A switch peak current capability and provides output voltage up to 18V(MT5087) or 30V(MT5088). Synchronous rectification increases efficiency, and eases thermal reduces power losses requirements, allowing the MT5087/MT5088 to be used in high power step-up applications. The 2.7V to 18V(MT5087) or 30V(MT5088) input voltage range supports a wide range of battery and AC powered inputs. The 70µA no load quiescent current extends operating run time in batterypowered systems. The operating frequency can be externally set for a 50kHz to 1MHz range, as for operation mode:

- MT5087/MT5088 is automatic PSM/PWM mode.
- MT5087A is Forced PWM mode.

The MT5087/MT5088 implements a programmable soft-start function, an adjustable cycle by cycle switching peak current limit function and thermal shutdown protection. The MT5087/MT5088 is available in a small 20 pin 4mm×4mm QFN package.

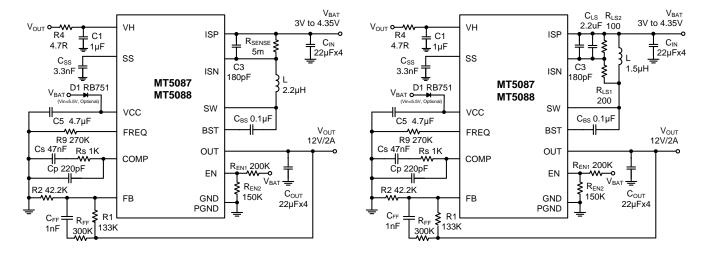
#### Features

- MT5087: 2.7V to 18V Input Range 3V to 18V Output Voltage Integrated 18V Rating 9mΩ Main and Synchronous Power Switches with 20A Peak Current Capability MT5087A: Forced PWM Mode Option
- MT5088: 2.7V to 30V Input Range 3V to 30V Output Voltage Integrated 30V Rating 12mΩ Main and Synchronous Power Switches with 20A Peak Current Capability
- Adjustable Input UVLO through EN pin
- Low Quiescent Current 70µA
- Low Shutdown Supply Current 3.5µA
- Resistor or Inductor DCR Current Sensing
- Adjustable Frequency from 50kHz to 1MHz
- Programmable Soft-start
- Cycle-by-Cycle Current Limit
- Thermal Shutdown
- QFN4×4\_20L Packages
- Pb-Free ROHS compliant

#### Application

- USB TypeC-PD and Thunderbolt Port for PCs
- Industrial Battery Powered POS Terminals
- Quick Charge Power Banks
- Electronic Cigarette
- Hi Power Bluetooth Speaker

#### **Typical Application**



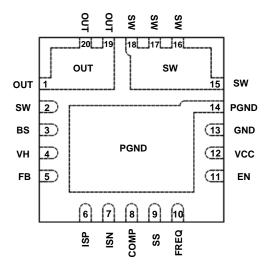


## **Ordering Information**

Part No.	Marking	Temp. Range	Package	MOQ
MT5087NQFR	MT5087 YWWxx	-40°C ~+85°C	QFN4X4_20L	5,000/Tape & Reel
MT5087AQFR	5087A YWWxx	-40°C ~+85°C	QFN4X4_20L	5,000/Tape & Reel
MT5088NQFR	MT5088 YWWxx	-40°C ~+85°C	QFN4X4_20L	5,000/Tape & Reel

Note: Y:Year, WW:Week, xx:Control Code

## **Pin Configuration**



#### MT5087/MT5088 TOP VIEW

## **Pin Description**

PIN NAME	PIN NO.	DESCRIPTION
OUT	1, 19, 20	Output of the Boost converter.
SW	2, 15, 16, 17, 18	Switching node of the Boost converter. Connect this pin to the inductor.
BST	3	Bootstrap capacitor node for Synchronous MOSFET. Connect the bootstrap capacitor $0.1\mu$ F from BST pin to the SW pin.
VH	4	The supply pin to On-Chip LDO Regulator. The operating voltage range on this pin is 2.7V to 18V (30V abs max). Bypass VH to PGND with a $0.1\mu$ F ceramic capacitor. When the input voltage Vin is < 5.5V, connect VH to the output of Boost converter to get maximum voltage for gate drivers. When the input voltage Vin is > 5.5V, connect VH to the input voltage to improve efficiency.
FB	5	Error amplifier input and feedback pin for output voltage regulation. Connect FB to the center tap of a resistor divider to set the output voltage.



PIN NAME	PIN NO.	DESCRIPTION
ISP	6	Positive Current Sense Amplifier Input. The current sense resistor is normally placed at the input of the Boost converter in series with the inductor. The common mode voltage range on the ISP and ISN pins is 2.5V to 20V (30V Abs Max).
ISN	7	Negative Current Sense Amplifier Input.
COMP	8	Output of the internal transconductance error amplifier. The feedback loop compensation network is connected from COMP pin to GND.
SS	9	Soft-start programming pin. An external capacitor sets the ramp rate of the internal error amplifier's reference voltage during soft-start period. Typically connect SS to GND with a 3.3nF ceramic capacitor.
FREQ	10	Oscillator Frequency Set Input. A resistor from FREQ to GND sets the oscillator frequeny from 50kHz to 1000kHz (Typical $R_{FREQ}$ =270k $\Omega$ sets Fosc=250kHz). Leave this pin float to set 460kHz default frequency.
EN	11	Enable input. Pull EN above 1.205V to turn on the converter, and pull EN below 1.11V to shutdown the converter. EN pin can be used to implement externally adjustable input voltage under voltage lockout (UVLO) with two resistors. Connect EN to the center tap of a resistor divider to set the input UVLO threshold.
vcc	12	5.4V On-Chip Low Dropout Linear Regulator Output (LDO). This regulator powers all internal circuitry including the low side and high side N-channel MOSFET gate drivers. Bypass VCC to PGND with a 1μF or greater ceramic capacitor. When the input voltage Vin is < 5.5V, Connect Vcc to Vin through a Diode.
GND	13	Signal Ground pin of the converter. All small-signal components and compensation components should be connected to this signal ground.
PGND	14	Power ground of the converter. It is connected to the source of the main MOSFET. Connect this pin to the (–) terminal(s) of $C_{\rm IN}$ and $C_{\rm OUT}$ .



#### Absolute Maximum Rating (Note1)

VH, ISP, ISN, OUT to GND (MT5087)	0.3V to +20V
VH, ISP, ISN, OUT to GND (MT5088)	0.3V to +32V
ISP to ISN, PGND to GND	0.3V to +0.3V
SW to GND	1V to V <sub>OUT</sub> +1V
Dynamic $V_{\text{SW}}$ in 50ns Duration	-3V to $V_{OUT}$ +3V

BST to SW	0.3V to +6V
EN, FB, COMP, VCC to GND	0.3V to +6V
Lead Temperature	260°C
Junction temperature range, TJ	-40°C ~+150°C
Storage temperature range, Tstg	-55°C~+150°C

### **Recommend Operating Conditions (Note2)**

Input Voltage (V <sub>IN</sub> ) (MT5087)	+2.7V to +18V
Output Voltage (V <sub>OUT</sub> ) (MT5087)	+3V to +18V
Input Voltage (V <sub>IN</sub> ) (MT5088)	+2.7V to +30V
Output Voltage (V <sub>OUT</sub> ) (MT5088)	+3V to +30V

<b>Operating Temperature Range</b>	40°C to +85°C
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#### Thermal Information (Note3,4)

Maximum Power Dissipation (TA=+25°C ) ..... 2.0W

Note(1): Stress exceeding those listed "Absolute Maximum Ratings" may damage the device.

Note(2): The device is not guaranteed to function outside of the recommended operating conditions.

Note(3): Measured on JESD51-7, 4-Layer PCB.

Note(4): The maximum allowable power dissipation is a function of the maximum junction temperature  $T_{J\_MAX}$ , the junction to ambient thermal resistance  $\theta_{JA}$ , and the ambient temperature  $T_A$ . The maximum allowable continuous power dissipation at any ambient temperature is calculated by  $P_{D\_MAX}$ =  $(T_{J\_MAX}-T_A)/\theta_{JA}$ . Exceeding the maximum allowable power dissipation will cause excessive die temperature, and the regulator will go into thermal shutdown. Internal thermal shutdown circuitry protects the device from permanent damage.

## **Electrical Characteristics**

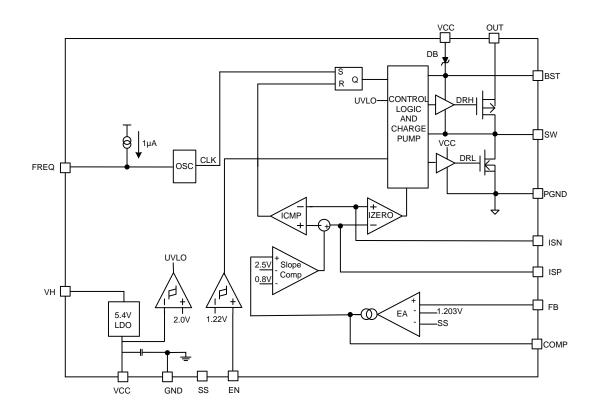
PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT	
Supply and Enable						
	MT5087	2.7		18	V	
Input supply range V <sub>H</sub>	MT5088	2.7		30	V	
	MT5087	3		18	V	
Output Voltage V <sub>OUT</sub>	MT5088	3		30	V	
	MT5087 6V <v<sub>H&lt;18V</v<sub>	5.1	5.4	5.7	V	
Linear Regulator V <sub>CC</sub> Output Voltage	MT5088 6V <v<sub>H&lt;30V</v<sub>	5.0	5.4	5.8	V	
	V <sub>H</sub> =V <sub>CC</sub> Rising		2.0	2.5		
V <sub>CC</sub> Under-voltage lockout threshold	V <sub>H</sub> =V <sub>CC</sub> Falling		1.8		V	
EN Pin On Threshold	V <sub>EN</sub> Rising, Turn On the device	1.12	1.205	1.32	V	
EN Pin Off Threshold	V <sub>EN</sub> Falling, Turn Off the device		1.10		V	
EN Pin Input Current	V <sub>EN</sub> =2V		100		nA	
Operating Quiescent current into VH	MT5087 and MT5088 V <sub>FB</sub> =1.25V, Device no switching		70	100	μA	
Operating Quiescent current into VH	MT5087A V <sub>FB</sub> =1.25V, Device no switching		140	200	μA	
Shutdown Current	V <sub>EN</sub> =0V		3.5	10	μA	
Error Amplifier	· · ·	·				
	PWM Mode	1.185	85 1.203 1.221			
Feedback voltage V <sub>FB</sub>	Light Load PSM Mode		1.211		V	
Feedback Current I <sub>FB</sub>	V <sub>FB</sub> =1.22V	-100	1	+100	nA	
Error Amplifier Transconductance	V <sub>COMP</sub> =1.6V		1.3		mA/V	



## 20A Fully Integrated Synchronous Boost Converter

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
	Hi Clamp Voltage, V <sub>FB</sub> =1.1V		3		
COMP pin clamp voltage	Hi Clamp Voltage, V <sub>FB</sub> =1.3V		0.4		V
Current Sense Amplifier					
Maximum current sense threshold	$\Delta V_{(ISP-ISN)}$	90	100	110	mV
Zero current sense threshold	$\Delta V_{(ISP-ISN)}$		0		mV
ISP/ISN Current Sense Input Current	V <sub>ISP</sub> =V <sub>ISN</sub> =3.6V		10	20	μA
ISP/ISN Current Sense Input Range		2.7		30	V
Oscillator Frequency					
Oscillator fraguency E	R <sub>FREQ</sub> =220kΩ	240	300	360	
Dscillator frequency Fosc	R <sub>FREQ</sub> float		460		kHz
Maximum Duty Cycle			93		%
Minimum On Time			200		ns
Power Switches					
Low Side Main Switch On Resistance	MT5087		9		mΩ
Low Side Main Switch On Resistance	MT5088		12		mΩ
High Side Switch On Resistance	MT5087		9		mΩ
	MT5088		12		mΩ
Power Switch Leakage current	MT5087, $V_{EN}$ =0V, $V_{SW}$ =18V and 0V		1	20	μA
	MT5088, $V_{EN}$ =0V, $V_{SW}$ =30V and 0V		1	20	μA
Thermal Shutdown					
Thermal Shutdown Threshold			160		°C
Thermal Shutdown Hysteresis			35		°C

# **Functional Block Diagram**



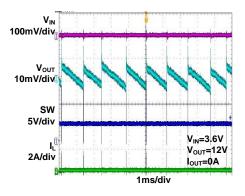


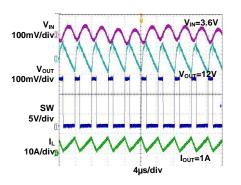
## 20A Fully Integrated Synchronous Boost Converter

## **TYPICAL PERFORMANCE CHARACTERISTICS**

 $C_{IN}$ =22uFx4,  $C_{OUT}$  = 22uFx4, L=1.5uH,  $R_{FREQ}$ =270K,  $T_{A}$ =+25°C

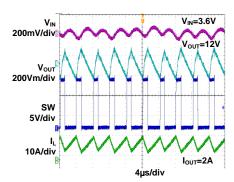
**Steady State Test** 

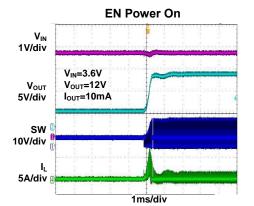


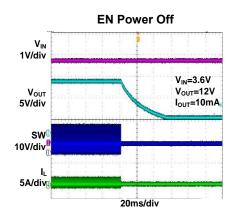


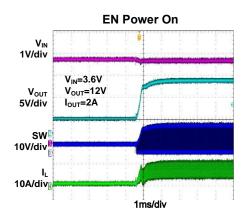
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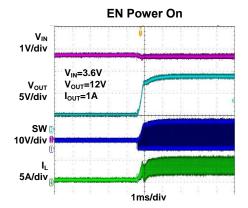
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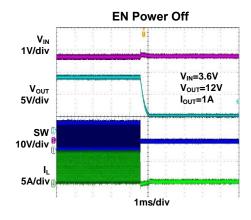


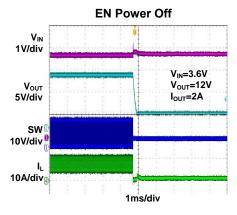










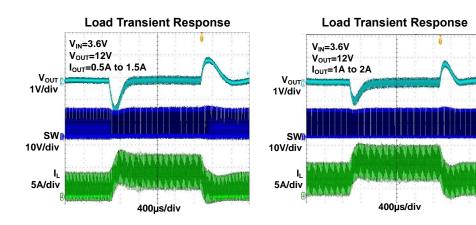


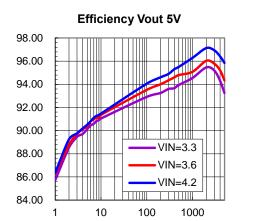


## 20A Fully Integrated Synchronous Boost Converter

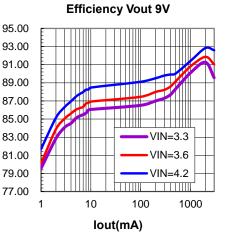
## **TYPICAL PERFORMANCE CHARACTERISTICS**

 $C_{\text{IN}}\text{=}22uFx4,\,C_{\text{OUT}}\text{=}22uFx4,\,L\text{=}1.5uH,\,R_{\text{FREQ}}\text{=}270K\,,\,T_{\text{A}}\text{=}+25^{\circ}\text{C}$ 

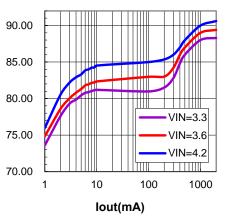




#### lout(mA)



## Efficiency Vout 12V





20A Fully Integrated Synchronous Boost Converter

#### Detailed Description (Refer to the Functional Block Diagram)

The MT5087/MT5088 is a fully-integrated synchronous boost converter with a 9mΩ main power switch and a 9mΩ Synchronous switch to output. The device is capable of providing an output voltage up to 18V(MT5087) or 30V(MT5088) and delivering up to 25W power from a 2.7 V to 18V(MT5087) or 30V(MT5088) wide input. Voltage regulation is achieved employing constant frequency current mode pulse width modulation (PWM) control. The switching frequency is set either externally from 50kHz to 1MHz by an external timing resistor from FREQ pin to GND or default 460kHz by floating FREQ pin. The PWM control circuitry turns on the low side MOSFET at the beginning of each oscillator clock cycle, as the error amplifier compares the output voltage feedback signal at the FB pin to the internal 1.203V reference voltage. The low side MOSFET is turned-off when the inductor current reaches a threshold level set by the error amplifier output. After the low side MOSFET is turned off, the high side synchronous rectifier MOSFET is turned on until the beginning of the next oscillator clock cycle or until the inductor current reaches the zero current sense threshold. The input voltage is applied across the inductor and stores the energy as inductor current ramps up during the portion of the switching cycle when the low side MOSFET is on. Meanwhile the output capacitor supplies load current. When the low side MOSFET is turned off by the PWM comparator, the inductor transfers stored energy via the synchronous rectifier MOSFET to replenish the output capacitor and supply the load current. This operation repeats every switching cycle. The device skips pulse to improve efficiency at light load. In the light load mode, the converter only operates when the output voltage trips below a FB set threshold voltage 1.211V. It ramps up the output voltage with one or several pulses and skips pulse once the output voltage exceeds the set threshold voltage. The devices feature internal slope compensation to avoid sub-harmonic oscillation that is intrinsic to peak current mode control at duty cycles higher than 50%. They also feature optional lossless inductor DCR current sensing, cycle-by-cycle current limit and over-temperature protection.

## **Application Information**

The MT5087/MT5088 external component selection is driven by the load requirement, and begins with the selection of switching frequency, inductor and  $R_{SENSE}$ . Finally, input and output capacitors are selected.

#### **Switching Frequency Selections**

The first step is to determine the switching frequency of the Boost converter. There are tradeoffs to consider when selecting a higher or lower switching frequency. Typically, the designer uses the highest switching frequency possible since this results in the smallest solution size. A higher switching frequency allows for lower value inductors and smaller output capacitors compared to a Step-up converter that switches at a lower frequency. A lower switching frequency will produce a larger solution size but typically has a better efficiency by reducing MOSFET switching losses. The switching frequency is also limited by the minimum on-time of the converter based on the input voltage and the output voltage of the application. Minimum on-time, t<sub>ONmin</sub> (200ns TYP), is the smallest time duration that the MT5087/MT5088 is capable of turning on the low side MOSFET and correctly sensing inductor current for peak current mode control. To determine the maximum allowable switching frequency, first estimate the continuous conduction mode (CCM) duty cycle using Equation 1 with the maximum input voltage.

$$f_{OSCmax} = \frac{D_{\min}}{t_{ON\min}} = \frac{\frac{V_{OUT} - V_{IN\max}}{V_{OUT}}}{200ns}$$
(Equation 1)

To determine the timing resistance at FREQ pin for a given switching frequency use the curve in Figure 1.

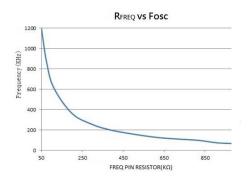


Figure 1. Switching Frequency versus Resistor Value at the FREQ Pin



#### **Input Capacitor Selection**

Place a high quality  $0.1\mu$ F in parallel with at least a  $10\mu$ F or higher ceramic type X5R or X7R bypass capacitor at the V<sub>IN</sub> pin to power ground PGND for proper decoupling. Based on the application requirements additional bulk capacitance are needed to meet input voltage ripple, transient and EMI requirements. The value of the C<sub>IN</sub> is a function of the source impedance, and in general, the higher the source impedance, the larger input capacitance. The required amount of input capacitance is also greatly affected by the duty cycle. High output current applications that also experience high duty cycles can place great demands on the input supply, both in terms of DC current and ripple current. The input capacitor voltage rating should exceed the maximum input voltage range.

#### **Inductor Selection**

The selection of the inductor affects the steady-state operation as well as transient behavior and loop stability. These factors make it an important component in a switching power supply design. The three most important inductor specifications to consider are inductor value, DC resistance (DCR), and saturation current rating. In a step-up topology the average inductor current is equal to the input current. The highest average current through the inductor and the converter depends on the maximum output load, converter efficiency  $\eta$ , the minimum input voltage (V<sub>INmin</sub>), and the output voltage (V<sub>OUT</sub>). The inductor saturation current rating should be greater (by some margin) than the maximum average inductor average current. Estimation of the maximum average inductor current can be done using Equation 2:

$$I_{L \max} = I_{OUT \max} \times \frac{V_{OUT}}{V_{IN\min} \times \eta}$$
 (Equation 2)

For example, for an output current of 2A at 12V with 90% efficiency, at least 8.9A of average current flows through the inductor at a minimum input voltage of 3V.

The inductor value has a direct effect on ripple current. Let the parameter  $\Delta I_L$  represent the inductor peak-peak ripple current. The inductor ripple current contributes to the output current ripple that must be filtered by the output capacitor. Therefore, choosing high inductor ripple currents impacts the selection of the output capacitor. Higher values of  $\Delta I_L$  lead to discontinuous mode (DCM) operation at moderate to light loads. The inductor ripple current  $\Delta IL$  decreases with higher inductance or frequency and increases with higher V<sub>IN</sub>. Estimation of the inductor ripple current can be done using Equation 3:

$$\Delta I_{L} = \frac{V_{IN}}{f_{OSC} \bullet L} \left( 1 - \frac{V_{IN}}{V_{OUT}} \right)$$
 (Equation 3)

Accepting larger values of  $\Delta I_L$  allows the use of low inductances, but results in higher output voltage ripple and greater core losses. A reasonable starting point for setting ripple current is  $\Delta I_L = 0.3 \sim 0.5^* I_{Lmax}$ . In a step-up topology, the maximum ripple current  $\Delta IL$  occurs at 50% duty cycle ( $V_{IN} = \frac{1}{2} * V_{OUT}$ ).

The MT5087/MT5088 Boost converters have been optimized to operate with an effective inductance in the range of  $1\mu$ H to  $10\mu$ H. Larger or smaller inductor values can be used to optimize the performance of the device for specific operating conditions.

#### **ISP and ISN Pins**

MT5087/MT5088 can use either a discrete sense resistor (R<sub>SENSE</sub>) or inductor DCR (DC resistance) sensing for current sensing. The choice between the two current sensing schemes is largely a design trade-off between cost, power consumption and accuracy. DCR sensing is becoming popular because it does not require current sensing resistors and is more power efficient, especially in high current applications. However, current sensing resistors provide the most accurate current limits for the converter.

The ISP and ISN pins are the inputs to the current sense amplifier. The common mode input voltage range of the current sense amplifier is 2.7V to 18V(MT5087) or 30V(MT5088). The current sense resistor is normally placed at the input of the converter in series with the inductor. The ISP pin also provides power to the current comparator. ISP draws approximately 10~30µA during normal operation. There is a typical 10µA bias current that flows into the ISN pin. The sense lines should be Kelvin-sense connection underneath the current sense resistor (shown in Figure 2). If inductor DCR sensing is used (Figure 3b), sense resistor R1 should be placed close to the switching node, and the mutual filter capacitor C1 should be placed close to the MT5087/MT5088 to prevent noise from coupling into sensitive small-signal nodes.



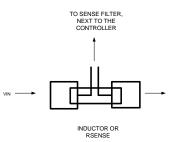
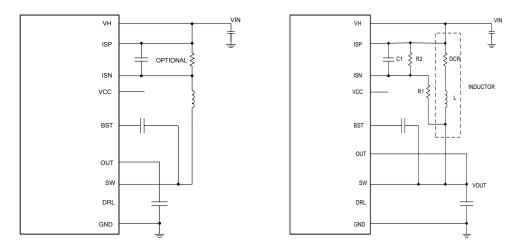


Figure 2. Sense Lines Placement with Inductor or Sense Resistor





#### **Current Sensing Resistor**

A typical sensing circuit using a discrete resistor is shown in Figure 3a.  $R_{SENSE}$  is chosen based on the required maximum average inductor current. The current comparator has a maximum threshold  $V_{SENSEmax}$  of 100mV (typical) and 90mV (minimum). To ensure that the application will deliver full load current over the full operating temperature range, choose the minimum value 92mV for the maximum current sense threshold  $V_{SENSEmax}$ . The current comparator threshold sets the peak of the inductor current, yielding a maximum average inductor current,  $I_{Lmax}$ , equal to the peak value less half the peak-to-peak ripple current,  $\Delta I_L$ . To calculate the sense resistor value, use the Equation 4:

$$R_{SENSE} = \frac{V_{SENSE \max}}{I_{L \max} + \frac{\Delta I_L}{2}} = \frac{90mV}{I_{L \max} + \frac{\Delta I_L}{2}}$$
(Equation 4)

 $R_{\text{SENSE}}$  also affects the current mode control loop gain. Choose  $R_{\text{SENSE}}$  in the 3~20m $\Omega$  range.

#### **Inductor DCR Sensing**

For applications requiring the highest possible efficiency at high load currents, the MT5087/MT5088 is capable of sensing the voltage drop across the inductor DCR, as shown in Figure 3b. The DCR sensing reduces conduction loss through a sense resistor and improve efficiency by a few percent. A flat frequency response is achieved when the inductor time constant matches that of the RC sense network. If the external R1||R2 • C1 time constant is chosen to be exactly equal to the L/DCR time constant, the voltage drop across the external capacitor is equal to the drop across the inductor DCR multiplied by R2/(R1 + R2). R2 scales the voltage across the sense terminals for applications where the DCR is greater than the target sense resistor value. The DCR of



### 20A Fully Integrated Synchronous Boost Converter

the inductor can be less than  $5m\Omega$  for high current inductors, and the R2 resistor is not used. To properly dimension the external filter components, the DCR of the inductor must be known. It can be measured using a good RLC meter, but the DCR tolerance is not always the same and varies with temperature. Consult the manufacturer's data sheets for detailed information. Using the inductor ripple current value from the inductor section, the equivalent sense resistor value is calculated with Equation 5:

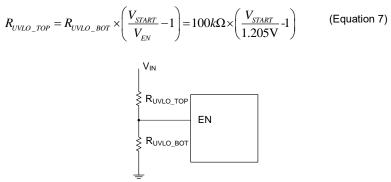
$$R_{SENSE(EQUIV)} = DCR \cdot \frac{R2}{R1 + R2} = \frac{V_{SENSE \min}}{I_{L \max} + \frac{\Delta I_L}{2}} = \frac{90mV}{I_{L \max} + \frac{\Delta I_L}{2}}$$
(Equation 5)

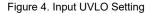
Choose R1|| R2 around 200 $\Omega$  to reduce error due to the ISN pin 10µA(Typical) input bias current. C1 is calculated by Equation 6 and usually selected to be in the range of 100nF to 10µF.

$$C1 = \frac{L}{DCR \cdot R1 / R2} = \frac{L}{DCR} \cdot \frac{R1 + R2}{R1 \cdot R2}$$
(Equation 6)

#### Setting Input Under-voltage Lockout (UVLO)

The EN pin voltage must be greater than 1.22 V (typical) to enable MT5087/MT5088. The device enters shutdown mode when the EN voltage is less than 0.4V. In shutdown mode, the input supply current for the device is less than 5 $\mu$ A. When the EN pin voltage is higher than the shutdown threshold but less than 1.22V, the devices are in standby mode. Adjustable input UVLO can be accomplished using the EN pin. As shown in Figure 4, a resistor divider from the V<sub>IN</sub> pin to GND sets the input UVLO level. Choose the bottom UVLO resistor R<sub>UVLO\_BOT</sub> in the 10k $\Omega$ ~200k $\Omega$  range to set the divider current at 10 $\mu$ A or higher. Typically select R<sub>UVLO\_BOT</sub>=100k $\Omega$ . The value of top resistor R<sub>UVLO\_TOP</sub>, depending on the the desired turn-on voltage V<sub>START</sub> at the V<sub>IN</sub> pin, can be calculated with Equation 7:





#### **Bootstrap Capacitor Selection**

Place a 10nF~0.1µF X5R or X7R ceramic capacitor between BST and SW pins for the proper operation. This capacitor provides gate drive voltage to turn on the high-side MOSFET.

#### VCC Low-Dropout Linear Regulator

The MT5087/MT5088 features an internal P-channel low dropout linear regulator (LDO) that supplies power to the VCC pin from the VH supply pin. VCC powers the gate drivers and MT5087/MT5088's internal circuitry. The LDO output VCC is regulated to 5.4V. It can supply at least 20mA and must be bypassed to ground with  $1\mu$ F~4.7 $\mu$ F X5R or better grade ceramic capacitor. The capacitor should have a 10 V or higher voltage rating. Good bypassing is needed to supply the high transient currents required by the MOSFET gate drivers. A VCC under-voltage detection circuit prevents the internal PWM control circuitry and power switches from operation when VCC voltage is below 2V (typical).

#### **Output Capacitor Selection**



#### 20A Fully Integrated Synchronous Boost Converter

In a step-up converter, the output has a discontinuous current, so output capacitor  $C_{OUT}$  must be capable of reducing the output voltage ripple and filtering the high di/dt path of the supply. It is recommended to use X5R or X7R ceramic capacitors placed as close as possible to the V<sub>OUT</sub> pin and power ground PGND pin. The effects of ESR (equivalent series resistance) and the bulk capacitance must be considered when choosing the right capacitor for a given output ripple voltage. The steady ripple voltage due to charging and discharging the bulk output capacitance in a single phase step-up converter is given by Equation 8. This value does not take into account the ESR of the output capacitor.

$$\Delta V_{OUT} = \frac{I_{OUT\,\text{max}} \times D_{\text{max}}}{C_{OUT} \times f_{OSC}} = \frac{I_{OUT\,\text{max}} \times \frac{V_{OUT} - V_{IN\,\text{min}}}{V_{OUT}}}{C_{OUT} \times f_{OSC}}$$
(Equation 8)

Where  $C_{OUT}$  is the output filter capacitor.

For example: Build 5V nominal output voltage from the minimum 3V input supply voltage. Select switching frequency 600kHz. Choose output capacitor to get less than 50mV ripple (1% of  $V_{OUT}$ ) at maximum 4Amp output current. The minimum output capacitor is 53µF required to limit the output voltage ripple.

$$C_{OUT} \ge \frac{I_{OUT \max} \times D_{\max}}{\Delta V_{OUT} \times f_{OSC}} = \frac{4A \times \frac{5V - 3V}{5V}}{5V \times 1\% \times 600 kHz} = 53 \mu F$$

Multiple capacitors placed in parallel may be needed to meet the ESR and RMS current handling requirements. Ceramic capacitors have excellent low ESR characteristics but can have a DC Bias effect, which will have a strong influence on the final effective capacitance. Capacitance deratings for aging, temperature and dc bias increase the minimum value required. The voltage rating must be greater than the output voltage with some tolerance for output voltage ripple and overshoot in transient conditions. For this example 4 x  $22\mu$ F, 25 V ceramic capacitors with 5 m $\Omega$  of ESR are used. The 40% derated capacitance is 52.8 $\mu$ F, approximately equal to the calculated minimum.

#### **Setting Output Voltage**

The MT5087/MT5088 output voltage is set by an external feedback resistor divider carefully placed across the output, as shown in Figure 5. Great care should be taken to route the VFB line away from noise sources, such as the inductor or the SW line. Also, keep the FB trace as short as possible to avoid noise pickup. The typical value of the voltage on the FB pin is 1.224V. The maximum allowed value for the output voltage is 18V. Choose the bottom resistor RFB\_BOT in the  $10k\Omega \sim 200k\Omega$  range to set the divider current at  $6\mu$ A or higher. Typically select RFB\_BOT= $100k\Omega$ . The value of top resistor RFB\_TOP, depending on the needed output voltage VoUT, can be calculated using Equation 8:

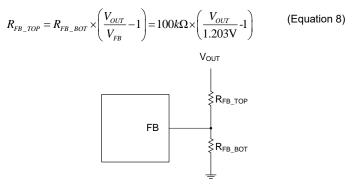


Figure 5. Output Voltage Setting

#### **The Control Loop Compensation**

The series  $R_c$ - $C_c$  filter at COMP pin sets the dominant pole-zero loop compensation. The resistor  $R_c$  in series with a capacitor  $C_c$  creates a compensating zero. A capacitor  $C_{c1}$  in parallel to these two components can be added to form a compensating pole. In a step-up topology, the maximum crossover frequency is typically limited by the right-half plane zero (RHPZ). The compensation



design should be done at the minimum input voltage and full load when the RHPZ is at the lowest frequency. The crossover frequency should also be limited to less than 1/4 of the RHPZ frequency.

Table 1. Gives  $R_c$ ,  $C_c$  and  $C_{c1}$  values for certain inductors, input and output voltages providing a very stable system. For a faster response time, a higher  $R_c$  value can be used to enlarge the bandwidth, as well as a slightly lower value of  $C_c$  to keep enough phase margin. These adjustments should be performed in parallel with the load transient response monitoring of MT5087/MT5088.

Table 1. Recommended Compensation Network Values								
Application	OUT_MAX	Fsw	Inductor	RSENSE	CIN	Cout	Rc	C <sub>c</sub> and C <sub>c1</sub>
1-Cell step-up to 5V	5A	250kHz	1.5µH	5mΩ	4*22µF	4*22µF	1kΩ	C <sub>c</sub> =47nF
Vin Range: 3V~4.35V	JA	ZJUNI IZ	I <sub>SAT</sub> =18A	511122	16V	16V	1832	C <sub>C1</sub> =220pF
1-Cell step-up to 9V	ЗA	250kHz	1.5µH	5mΩ	4*22µF	4*22µF	1kΩ	C <sub>C</sub> =47nF
Vin Range: 3V~4.35V	3A	200612	I <sub>SAT</sub> =18A	SUIC	25V	25V	1622	C <sub>C1</sub> =220pF
1-Cell step-up to 12V	2A	250kHz	1.5µH	5mΩ	4*22µF	4*22µF	1kΩ	C <sub>c</sub> =47nF
Vin Range: 3V~4.35V	ZA	200612	I <sub>SAT</sub> =18A	SUIC	25V	25V	1622	C <sub>C1</sub> =220pF
2-Cell step-up to 12V	2A	250kHz	1.5µH	FmO	4*22µF	4*22µF	1kΩ	CC=47nF
Vin Range: 6V~8.4V	ZA	230KHZ	ISAT=18A	5mΩ	25V	25V	1652	C <sub>C1</sub> =220pF

Table 1. Recommended Compensation Network Values

## **Thermal information**

Implementation of integrated circuits in low-profile and fine-pitch surface-mount packages typically requires special attention to power dissipation. Many system-dependent issues such as thermal coupling, airflow, added heat sinks and convection surfaces, and the presence of other heat-generating components affect the power-dissipation limits of a given component. Three basic approaches for enhancing thermal performance are listed below:

- Improve the power dissipation capability of the PCB design
- Improve the thermal coupling of the component to the PCB
- Introducing airflow in the system

The maximum junction temperature (T<sub>J</sub>) of the MT5087/MT5088 devices is 160°C and worse case won't excess 145°C, The thermal resistance of the 20-pin QFN package is  $\theta_{JA}$  = 50°C /W, if the Exposed PAD is soldered. Specified regulator operation is assured to a maximum ambient temperature T<sub>A</sub> of +85°C. Therefore, the maximum power dissipation for the 20-pin QFN package it is about 1W. More power can be dissipated if the maximum ambient temperature of the application is lower.

$$P_{D(MAX)} = \frac{T_{J(MAX)} - T_A}{R_{\theta JA}} = \frac{145^{\circ}C - 85^{\circ}C}{50^{\circ}C/W} = 1.2W$$

#### Layout consideration

For designing the MT5087/MT5088 a boost power supply, especially those operating at high output voltage and current application, PCB layout is a very important in design step. To prevent radiation of high frequency noise (for example, EMI), proper layout of the high-frequency switching path is essential. Minimize the length and area of all traces connected to the SW pin to reducing the high frequency noise of coupling to GND plane to cause EMI or power system unstable.

Check the following layout rules:

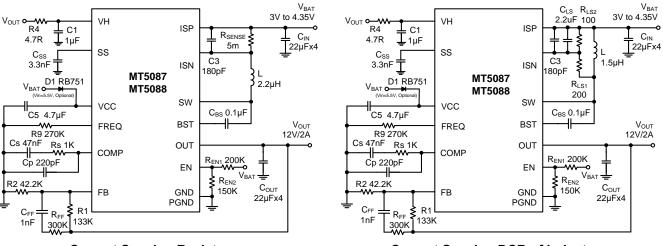
- 1. Put the input capacitors GND, output capacitors GND and the PGND of MT5087/MT5088 in the same of power plane to reduce impedance to avoid EMI and increase efficiency of power system.
- The GND and PGND kept separate and used dot short skill to avoid noise coupling to GND to cause power system unstable as MT5087/MT5088 EV board PCB design.
- ISP and ISN trace routing like a differential pail to shielding each other to filter the common mode noise. And far away the SW
  trace to avoid to be coupled that will cause the current limit protection circuit fault. Ensure accurate current sensing with Kelvin
  connections at the sense resistor or the DCR of inductor.
- 4. Keep the switching node (SW and PGND) and boost node (BST) away from sensitive small-signal nodes.



## 20A Fully Integrated Synchronous Boost Converter

## MT5087/MT5088 Application Schematic

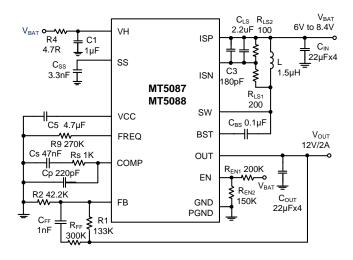
## **1-Cell Application:**



**Current Sensing Resistor** 

**Current Sensing DCR of Inductor** 

# 2-Cell Application:



#### **Current Sensing DCR of Inductor**



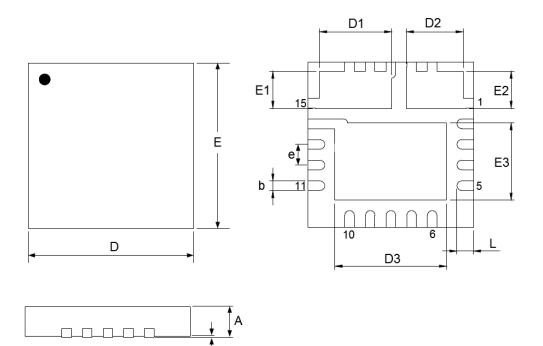
Qty	Ref	Va	lue	Description	Package
4	CIN	22	uF	Ceramic Capacitor, 16V, X5R	0805
4	Cout	22	uF	Ceramic Capacitor, 30V, X5R	0805
1	L	-	r L sense <sup>-</sup> R sense	MHCl06030-1R5M-R8, 15mΩ,18A(SAT), 9.5A(RMS) MHCl06030-2R2M-R8, 20mΩ,14A(SAT), 8.5A(RMS)	SMD
1	R1	133	βkΩ	Resistor, ±1%	0603
		Vout=5V	<b>42.2k</b> Ω		
1	R2	Vout=9V	20.5kΩ	Decister (10)	0603
I	RZ	Vout=12V	14.7kΩ	Resistor, ±1%	0603
		Vout=20V	$8.45 k\Omega$		
1	R <sub>FF</sub>	300	)kΩ	Resistor, ±5%	0603
1	R4	4.7	7Ω	Resistor, ±5%	0603
1	Rs	1k	úΩ	Resistor, ±1%	0603
1	R <sub>EN1</sub>	156	δkΩ	Resistor, ±5%	0603
1	REN1	200	kΩ	Resistor, ±5%	0603
1	REN2	150kΩ		Resistor, ±5%	0603
1	R9	270kΩ		Resistor, ±5%	0603
1	R <sub>SENSE</sub>	$5 m\Omega$		Resistor, ±1%	1206
1	R <sub>LS1</sub>	200Ω		Resistor, ±1%	0603
1	R <sub>LS2</sub>	100Ω		Resistor, ±1%	0603
1	C1	1ι	١F	Ceramic Capacitor, 10V, X5R	0603
1	C3	180	)pF	Ceramic Capacitor, 10V, X5R	0603
1	C5	4.7	′uF	Ceramic Capacitor, 10V, X5R	0603
1	C <sub>FF</sub>	1r	۱F	Ceramic Capacitor, 10V, X5R	0603
1	Css	3.3	InF	Ceramic Capacitor, 10V, X5R	0603
1	C <sub>BS</sub>	0.1uF		Ceramic Capacitor, 10V, X5R	0603
1	CLS	2.2uF		Ceramic Capacitor, 10V, X5R	0603
1	CS	47	nF	Ceramic Capacitor, 10V, X5R	0603
1	CP	220	)pF	Ceramic Capacitor, 10V, X5R	0603
1	D1	RB	751	Diode, RB751	
1	Power IC	MT5087	/MT5088	Boost DC/DC Converter	QFN4x4_20

#### **EVB BOM List**



## **PACKAGING INFORMATION**

## QFN4x4\_20L PACKAGE OUTLINE DIMENSIONS



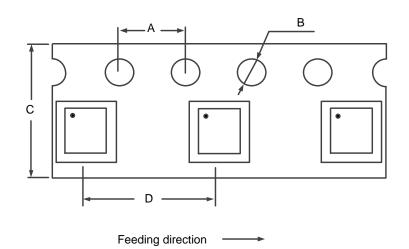
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	MILLIN	IETERS	INCH	IES
SYMBOLS	MIN.	MAX.	MIN.	MAX.
А	0.70	0.80	0.028	0.031
A1	0.00	0.05	0.000	0.002
b	0.20	0.30	0.008	0.012
E	3.90	4.10	4.10 0.154	
D	3.90	4.10	4.10 0.154	
E1	0.80	1.00	0.031	0.039
D1	1.65	1.85	0.065	0.073
E2	0.80	1.00	0.031	0.039
D2	1.27	1.47	1.47 0.050	
E3	1.77	1.97 0.070		0.078
D3	2.60	2.80 0.102		0.110
е	0.50	BSC	0.020	BSC
L	0.30	0.50	0.012	0.020

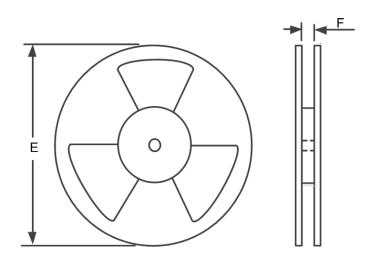


## **Carrier Tape & Reel Dimensions**

1. Orientation / Carrier Tape Information :



2. Rokreel Information :



#### 3. Dimension Details :

PKG Type	А	В	С	D	E	F	Q'ty/Reel
QFN4x4	4.0 mm	1.5 mm	12.0 mm	8.0 mm	13 inches	13.0 mm	5,000



## **Reflow Profile**

### **Classification Of IR Reflow Profile**

Reflow Profile	Green Assembly
Average Ramp-Up Rate (Ts <sub>min</sub> to Tp)	1~2°C/second, 3°C/second max.
Preheat & Soak	
-Temperature Min(Ts <sub>min</sub> )	150°C
-Temperature Max(Ts <sub>max</sub> )	200°C
-Time(ts <sub>min</sub> to ts ts <sub>max</sub> )	60~120 seconds
Time maintained above:	
-Temperature(T <sub>L</sub> )	217°C
-Time(t∟)	60~150 seconds
Peak Temperature(Tp)	See Classification Temp in table 1
Time within 5°C of actual Peak Temperature(tp)	30 seconds max.
Ramp-Down Rate	6°C/second max.
Time 25℃ to Peak Temperature	8 minutes max.

\* Tolerance for peak profile Temperature (T<sub>p</sub>) is defined as a supplier minimum and a user maximum.
 \*\* Tolerance for time at peak profile temperature (t<sub>p</sub>) is defined as a supplier minimum and a user maximum.

Table 1.	Pb-free	Process -	Cla	ssification	Tem	peratures	(Tc	)

Package Thickness	Volume mm <sup>3</sup> <350	Volume mm <sup>3</sup> 350-2000	Volume mm <sup>3</sup> >2000
<1.6 mm	260 °C	260 °C	260 °C
1.6 mm – 2.5 mm	260 °C	250 °C	245 °C
2.5 mm	250 °C	245 °C	245 °C

Note: For all temperature information, please refer to topside of the package, measured on the package body surface.

