# **NXS0102**

# Dual supply translating transceiver; open drain; auto direction sensing

Rev. 1 — 17 December 2019

Product data sheet

# 1. General description

The NXS0102 is a 2-bit, dual supply translating transceiver with auto direction sensing, that enables bidirectional voltage level translation. It features two 2-bit input-output ports (An and Bn), one output enable input (OE) and two supply pins ( $V_{CC(A)}$  and  $V_{CC(B)}$ ).  $V_{CC(A)}$  can be supplied at any voltage between 1.65 V and 3.6 V and  $V_{CC(B)}$  can be supplied at any voltage between 2.3 V and 5.5 V, making the device suitable for translating between any of the voltage nodes (1.8 V, 2.5 V, 3.3 V and 5.0 V). Pins An and OE are referenced to  $V_{CC(A)}$  and pins Bn are referenced to  $V_{CC(B)}$ . A LOW level at pin OE causes the outputs to assume a high-impedance OFF-state. This device is fully specified for partial power-down applications using  $I_{OFF}$ . The  $I_{OFF}$  circuitry disables the output, preventing the damaging backflow current through the device when it is powered down.

### 2. Features and benefits

- Wide supply voltage range:
  - V<sub>CC(A)</sub>: 1.65 V to 3.6 V and V<sub>CC(B)</sub>: 2.3 V to 5.5 V
- Maximum data rates:
  - · Push-pull: 24 Mbps
- I<sub>OFF</sub> circuitry provides partial Power-down mode operation
- Inputs accept voltages up to 5.5 V
- ESD protection:
  - HBM: ANSI/ESDA/Jedec JS-001 Class 2 exceeds 2.5 kV for A port
  - HBM: ANSI/ESDA/Jedec JS-001 Class 3B exceeds 8 kV for B port
  - CDM: ANSI/ESDA/Jedec JS-002 Class C3 exceeds 1.5 kV
- Latch-up performance exceeds 100 mA per JESD 78B Class II
- · Multiple package options
- Specified from -40 °C to +85 °C and -40 °C to +125 °C

# 3. Applications

- Desktop PC
- Handset
- Smartphone
- Tablet



### Dual supply translating transceiver; open drain; auto direction sensing

# 4. Ordering information

**Table 1. Ordering information** 

Type number	Package			
	Temperature range	Name	Description	Version
NXS0102DC [1]	-40 °C to +125 °C	VSSOP8	plastic very thin shrink small outline package; 8 leads; body width 2.3 mm	SOT765-1
NXS0102GT	-40 °C to +125 °C	XSON8	plastic extremely thin small outline package; no leads; 8 terminals; body 1 × 1.95 × 0.5 mm	SOT833-1

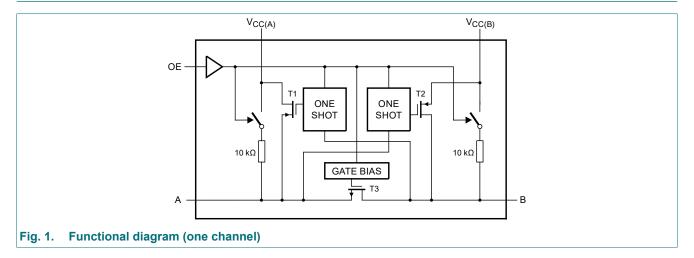
<sup>[1]</sup> This product is in development.

# 5. Marking

Table 2. Marking

Type number	Marking code
NXS0102DC	m2
NXS0102GT	m2

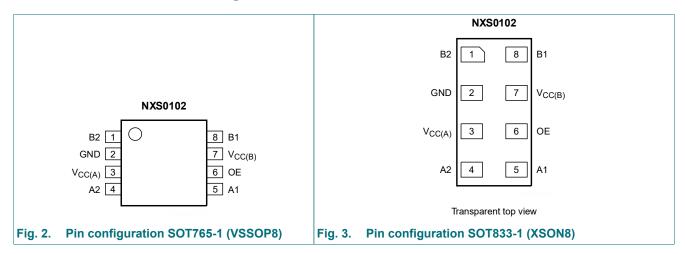
# 6. Functional diagram



#### Dual supply translating transceiver; open drain; auto direction sensing

# 7. Pinning information

### 7.1. Pinning



### 7.2. Pin description

Table 3. Pin description

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Symbol	Pin	Description			
B2, B1	1, 8	data input or output (referenced to V <sub>CC(B)</sub> )			
GND	2	ground (0 V)			
V <sub>CC(A)</sub>	3	supply voltage A			
A2, A1	4, 5	data input or output (referenced to V <sub>CC(A)</sub> )			
OE	6	output enable input (active HIGH; referenced to $V_{\text{CC(A)}}$ )			
V <sub>CC(B)</sub>	7	supply voltage B			

# 8. Functional description

#### **Table 4. Function table**

 $H = HIGH \ voltage \ level; \ L = LOW \ voltage \ level; \ X = don't \ care; \ Z = high-impedance \ OFF-state.$ 

Supply voltage		Input	Input/output	
V <sub>CC(A)</sub> [1] V <sub>CC(B)</sub>		OE	An	Bn
1.65 V to 3.6 V	2.3 V to 5.5 V	L	Z	Z
1.65 V to 3.6 V	2.3 V to 5.5 V	Н	input or output	output or input
GND	2.3 V to 5.5 V	Х	Z	Z
1.65 V to 3.6 V	GND	Х	Z	Z

[1]  $V_{CC(A)}$  must be less than or equal to  $V_{CC(B)}$ .

#### Dual supply translating transceiver; open drain; auto direction sensing

# 9. Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions		Min	Max	Unit
V <sub>CC(A)</sub>	supply voltage A			-0.5	+6.5	V
V <sub>CC(B)</sub>	supply voltage B			-0.5	+6.5	V
VI	input voltage	OE	[1]	-0.5	+6.5	V
		Power-down or 3-state mode				
		A, B	[1]	-0.5	+6.5	V
		Active mode				
		A, B	[1][2][3]	-0.5	V <sub>CCI</sub> + 0.5	V
V <sub>O</sub>	output voltage	Power-down or 3-state mode				
		A, B	[1]	-0.5	+6.5	V
		Active mode				
		A, B	[1][3][4]	-0.5	V <sub>CCO</sub> + 0.5	V
I <sub>IK</sub>	input clamping current	V <sub>I</sub> < 0 V		-50	-	mA
I <sub>OK</sub>	output clamping current	V <sub>O</sub> < 0 V		-50	-	mA
Io	output current	V <sub>O</sub> = 0 V to V <sub>CCO</sub>	[4]	-	±50	mA
I <sub>CC</sub>	supply current	I <sub>CC(A)</sub> or I <sub>CC(B)</sub>		-	100	mA
I <sub>GND</sub>	ground current			-100	-	mA
T <sub>stg</sub>	storage temperature			-65	+150	°C
P <sub>tot</sub>	total power dissipation	T <sub>amb</sub> = -40 °C to +125 °C	[5]	-	250	mW

The minimum input and minimum output voltage ratings may be exceeded if the input and output current ratings are observed.

V<sub>CCI</sub> is the supply voltage associated with the input.

 $V_{CCI}$  + 0.5 V or  $V_{CCO)}$  + 0.5 V should not exceed 6.5 V. [3]

<sup>[4]</sup> 

 $V_{\rm CCO}$  is the supply voltage associated with the output. For SOT765-1 (VSSOP8) packages:  $P_{\rm tot}$  derates linearly with 4.9 mW/K above 99 °C. For SOT833-1 (XSON8) packages: Ptot derates linearly with 3.1 mW/K above 68 °C.

### Dual supply translating transceiver; open drain; auto direction sensing

# 10. Recommended operating conditions

Table 6. Recommended operating conditions [1] [2]

Symbol	Parameter	Conditions		Min	Max	Unit
V <sub>CC(A)</sub>	supply voltage A			1.65	3.6	V
V <sub>CC(B)</sub>	supply voltage B			2.3	5.5	V
VI	input voltage	OE		0	5.5	V
		Power-down or 3-state mode				
		A		0	3.6	V
		В		0	5.5	V
		Active mode				
		A, B	[3]	0	V <sub>CCI</sub>	V
V <sub>O</sub>	output voltage	Power-down or 3-state mode				
		A		0	3.6	V
		В		0	5.5	V
		Active mode				
		A, B	[4]	0	V <sub>CCO</sub>	V
T <sub>amb</sub>	ambient temperature			-40	+125	°C
Δt/ΔV	input transition rise and fall rate	A or B port; push-pull driving				
		V <sub>CC(A)</sub> = 1.65 V to 3.6 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V		-	10	ns/V
		OE input				
		V <sub>CC(A)</sub> = 1.65 V to 3.6 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V		-	10	ns/V

<sup>[1]</sup> The A and B sides of an unused I/O pair must be held in the same state, both at  $V_{CCI}$  or both at GND.

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 $V_{CC(A)}$  must be less than or equal to  $V_{CC(B)}$ .  $V_{CCI}$  is the supply voltage associated with the input.  $V_{CCO}$  is the supply voltage associated with the output.

#### Dual supply translating transceiver; open drain; auto direction sensing

# 11. Static characteristics

**Table 7. Typical static characteristics** 

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); T<sub>amb</sub> = 25 °C.[1]

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
I <sub>1</sub>	input leakage current	OE input; $V_{CC(A)} = 1.65 \text{ V to } 3.6 \text{ V}; V_{CC(B)} = 2.3 \text{ V to } 5.5 \text{ V}$	-	-	±1	μΑ
l <sub>OZ</sub>	OFF-state output current	A or B port; $V_{CC(A)} = 1.65 \text{ V}$ to $3.6 \text{ V}$ ; $V_{CC(B)} = 2.3 \text{ V}$ to $5.5 \text{ V}$ ; OE = 0 V	-	-	±1	μΑ
I <sub>OFF</sub>	power-off leakage current	A port; $V_{CC(A)} = 0 \text{ V}$ ; $V_{CC(B)} = 0 \text{ V}$ to 5.5 V	-	-	±1	μΑ
		B port; V <sub>CC(B)</sub> = 0 V; V <sub>CC(A)</sub> = 0 V to 3.6 V	-	-	±1	μΑ
Cı	input capacitance	OE input; V <sub>CC(A)</sub> = 3.3 V; V <sub>CC(B)</sub> = 3.3 V	-	2.0	-	pF
C <sub>I/O</sub>	input/output	A port; V <sub>CC(A)</sub> = 3.3 V; V <sub>CC(B)</sub> = 3.3 V				
	capacitance	enabled	-	10	-	pF
		disabled	-	4	-	pF
		B port; V <sub>CC(A)</sub> = 3.3 V; V <sub>CC(B)</sub> = 3.3 V				
		enabled	-	10	-	pF
		disabled	-	7	-	pF

<sup>[1]</sup>  $V_{CC(A)}$  must be less than or equal to  $V_{CC(B)}$ .

#### Table 8. Typical supply current

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); T<sub>amb</sub> = 25 °C.

V <sub>CC(A)</sub>	$V_{CC(A)}$ $V_{CC(B)}$							
	2.5 V		3.3 V		5.0 V			
	I <sub>CC(A)</sub>	I <sub>CC(B)</sub>	I <sub>CC(A)</sub>	I <sub>CC(B)</sub>	I <sub>CC(A)</sub>	I <sub>CC(B)</sub>		
1.8 V	0.1	0.5	0.1	1.5	0.1	4.6	μΑ	
2.5 V	0.1	0.1	0.1	0.8	0.1	3.8	μΑ	
3.3 V	-	-	0.1	0.1	0.1	2.8	μΑ	

### Dual supply translating transceiver; open drain; auto direction sensing

**Table 9. Static characteristics** 

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).[1]

Symbol	Parameter	Conditions	-40 °C to	o +85 °C	-40 °C to	Unit	
			Min	Max	Min	Max	
V <sub>IH</sub>	HIGH-level	A port					
	input voltage	V <sub>CC(A)</sub> = 1.65 V to 1.95 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V	V <sub>CC(A)</sub> - 0.2	V <sub>CC(A)</sub>	V <sub>CC(A)</sub> - 0.2	V <sub>CC(A)</sub>	V
		V <sub>CC(A)</sub> = 2.3 V to 3.6 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V	V <sub>CC(A)</sub> - 0.4	V <sub>CC(A)</sub>	V <sub>CC(A)</sub> - 0.4	V <sub>CC(A)</sub>	V
		B port					
		V <sub>CC(A)</sub> = 1.65 V to 3.6 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V	V <sub>CC(B)</sub> - 0.4	V <sub>CC(B)</sub>	V <sub>CC(B)</sub> - 0.4	V <sub>CC(B)</sub>	V
		OE input					
		V <sub>CC(A)</sub> = 1.65 V to 3.6 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V	0.65V <sub>CC(A)</sub>	V <sub>CC(A)</sub>	0.65V <sub>CC(A)</sub>	V <sub>CC(A)</sub>	V
V <sub>IL</sub>	LOW-level	A or B port					
	input voltage	V <sub>CC(A)</sub> = 1.65 V to 3.6 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V	0	0.15	0	0.15	V
		OE input					
		V <sub>CC(A)</sub> = 1.65 V to 3.6 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V	0	0.35V <sub>CC(A)</sub>	0	0.35V <sub>CC(A)</sub>	V
V <sub>OH</sub>	HIGH-level output voltage	A port; $I_O = -20 \mu A$ ; $V_I \ge V_{CC(B)} - 0.4 V$					
		V <sub>CC(A)</sub> = 1.65 V to 3.6 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V	0.67V <sub>CC(A)</sub>	-	0.67V <sub>CC(A)</sub>	-	V
		B port; $I_O = -20 \mu A$ ; $V_I \ge V_{CC(A)} - 0.2 V$					
		V <sub>CC(A)</sub> = 1.65 V to 3.6 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V	0.67V <sub>CC(B)</sub>	-	0.67V <sub>CC(B)</sub>	-	V
V <sub>OL</sub>	LOW-level	A or B port; $I_0 = 1 \text{ mA}$ ; $V_1 \le 0.15 \text{ V}$					
	output voltage	V <sub>CC(A)</sub> = 1.65 V to 3.6 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V	-	0.4	-	0.4	V
I <sub>I</sub>	input leakage current	OE input; V <sub>CC(A)</sub> = 1.65 V to 3.6 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V	-	±2	-	±12	μΑ
l <sub>OZ</sub>	OFF-state output current	A or B port; $V_{CC(A)} = 1.65 \text{ V}$ to 3.6 V; $V_{CC(B)} = 2.3 \text{ V}$ to 5.5 V	-	±2	-	±12	μΑ
I <sub>OFF</sub>	power-off leakage	A port; $V_{CC(A)} = 0 \text{ V}$ ; $V_{CC(B)} = 0 \text{ V to } 5.5 \text{ V}$	-	±2	-	±12	μΑ
	current	B port; V <sub>CC(B)</sub> = 0 V; V <sub>CC(A)</sub> = 0 V to 3.6 V	-	±2	-	±12	μΑ

#### Dual supply translating transceiver; open drain; auto direction sensing

Symbol	Parameter	Conditions	-40 °C t	o +85 °C	-40 °C to	+125 °C	Unit
			Min	Max	Min	Max	
I <sub>CC</sub>	supply current	OE = 0 V or V <sub>CC(A)</sub> ; An, Bn open					
		I <sub>CC(A)</sub>					
		V <sub>CC(A)</sub> = 1.65 V to 3.6 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V	-	2.4	-	15	μA
		V <sub>CC(A)</sub> = 3.6 V; V <sub>CC(B)</sub> = 0 V	-	2.2	-	15	μA
		V <sub>CC(A)</sub> = 0 V; V <sub>CC(B)</sub> = 5.5 V	-	-1	-	-8	μA
		I <sub>CC(B)</sub>					
		V <sub>CC(A)</sub> = 1.65 V to 3.6 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V	-	12	-	30	μA
		V <sub>CC(A)</sub> = 3.6 V; V <sub>CC(B)</sub> = 0 V	-	-1	-	-5	μA
		$V_{CC(A)} = 0 \text{ V}; V_{CC(B)} = 5.5 \text{ V}$	-	1	-	6	μA
		I <sub>CC(A)</sub> + I <sub>CC(B)</sub>					
		$V_{CC(A)}$ = 1.65 V to 3.6 V; $V_{CC(B)}$ = 2.3 V to 5.5 V	-	14.4	-	30	μΑ

<sup>[1]</sup>  $V_{CC(A)}$  must be less than or equal to  $V_{CC(B)}$  and  $V_{CC(A)}$  must not exceed 3.6 V.

# 12. Dynamic characteristics

Table 10. Dynamic characteristics for temperature range -40 °C to +85 °C

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 7; for waveforms see Fig. 4 to Fig. 6.

Symbol	Parameter	Conditions	V <sub>CC(B)</sub>						Unit
			2.5 V	± 0.2 V	3.3 V	± 0.3 V	5.0 V ± 0.5 V		
			Min	Max	Min	Max	Min	Max	
V <sub>CC(A)</sub> =	1.8 V ± 0.15 V								
t <sub>PHL</sub>	HIGH to LOW propagation delay	A to B	-	5.3	-	5.4	-	6.8	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	A to B	-	7.1	-	7.1	-	7.5	ns
t <sub>PHL</sub>	HIGH to LOW propagation delay	B to A	-	4.4	-	4.5	-	4.7	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	B to A	-	5.3	-	4.5	-	0.5	ns
t <sub>en</sub>	enable time	OE to A, B	-	200	-	200	-	200	ns
t <sub>dis</sub>	disable time	OE to A, B; no external load [1][2]	-	35	-	35	-	35	ns
		OE to A	-	230	-	230	-	230	ns
		OE to B	-	200	-	200	-	200	ns
t <sub>TLH</sub>	LOW to HIGH	A port	3.2	9.5	2.3	9.3	1.8	7.6	ns
	output transition time	B port	3.3	10.8	2.7	9.1	2.7	7.6	ns
t <sub>THL</sub>	HIGH to LOW	A port	2.0	5.9	1.9	6.0	1.7	13.3	ns
	output transition time	B port	2.9	7.6	2.8	7.9	2.8	10.5	ns
t <sub>sk(o)</sub>	output skew time	between channels [3]	-	0.7	-	0.7	-	0.7	ns
t <sub>W</sub>	pulse width	data inputs	41	-	41	-	41	-	ns
f <sub>data</sub>	data rate		-	24	-	24	-	24	Mbps

#### Dual supply translating transceiver; open drain; auto direction sensing

Symbol Parameter		Conditions			Vc	C(B)			Unit
			2.5 V	± 0.2 V	3.3 V	± 0.3 V	5.0 V :	± 0.5 V	
			Min	Max	Min	Max	Min	Max	
V <sub>CC(A)</sub> =	2.5 V ± 0.2 V			1					1
t <sub>PHL</sub>	HIGH to LOW propagation delay	A to B	-	3.2	-	3.7	-	3.8	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	A to B	-	3.5	-	4.4	-	4.6	ns
t <sub>PHL</sub>	HIGH to LOW propagation delay	B to A	-	3.0	-	3.6	-	4.3	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	B to A	-	2.5	-	1.6	-	1.0	ns
t <sub>en</sub>	enable time	OE to A, B	-	200	-	200	-	200	ns
t <sub>dis</sub>	disable time	OE to A, B; no external load [1][2]	-	35	-	35	-	35	ns
		OE to A	-	200	-	200	-	200	ns
		OE to B	-	200	-	200	-	200	ns
t <sub>TLH</sub>	LOW to HIGH	A port	2.8	7.5	2.6	6.6	1.8	6.5	ns
	output transition time	B port	3.2	8.5	2.9	7.9	2.4	6.8	ns
t <sub>THL</sub>	HIGH to LOW	A port	1.9	5.7	1.9	5.5	1.8	5.3	ns
	output transition time	B port	2.2	7.8	2.4	6.7	2.6	6.9	ns
$t_{sk(o)}$	output skew time	between channels [3]	-	0.7	-	0.7	-	0.7	ns
$t_W$	pulse width	data inputs	41	-	41	-	41	-	ns
f <sub>data</sub>	data rate		-	24	-	24	-	24	Mbps
$V_{CC(A)} =$	3.3 V ± 0.3 V								
t <sub>PHL</sub>	HIGH to LOW propagation delay	A to B	-	-	-	2.4	-	3.1	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	A to B	-	-	-	4.2	-	4.4	ns
t <sub>PHL</sub>	HIGH to LOW propagation delay	B to A	-	-	-	2.5	-	3.3	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	B to A	-	-	-	2.5	-	2.6	ns
t <sub>en</sub>	enable time	OE to A, B	-	-	-	200	-	200	ns
t <sub>dis</sub>	disable time	OE to A, B; no external load [1][2]	-	-	-	35	-	35	ns
		OE to A	-	-	-	260	-	260	ns
		OE to B	-	-	-	200	-	200	ns
t <sub>TLH</sub>	LOW to HIGH	A port	-	-	2.3	6.2	1.9	6.3	ns
	output transition time	B port	-	-	2.5	6.9	2.1	7.4	ns
t <sub>THL</sub>	HIGH to LOW	A port	-	-	2.0	5.4	1.9	5.0	ns
	output transition time	B port	-	-	2.3	7.4	2.4	7.6	ns
t <sub>sk(o)</sub>	output skew time	between channels [3]	-	-	-	0.7	-	0.7	ns
t <sub>W</sub>	pulse width	data inputs	-	-	41	-	41	-	ns
f <sub>data</sub>	data rate		-	-	-	24	-	24	Mbps

 $t_{\text{dis}}$  is the same as  $t_{\text{PLZ}}$  and  $t_{\text{PHZ}}$ .

The disable time with no external load indicates the delay between when OE goes LOW and when outputs actually become disabled.

<sup>[2]</sup> [3] Skew between any two outputs of the same package switching in the same direction.

### Dual supply translating transceiver; open drain; auto direction sensing

Table 11. Dynamic characteristics for temperature range -40 °C to +125 °C

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 7; for waveforms see Fig. 4 to Fig. 6.

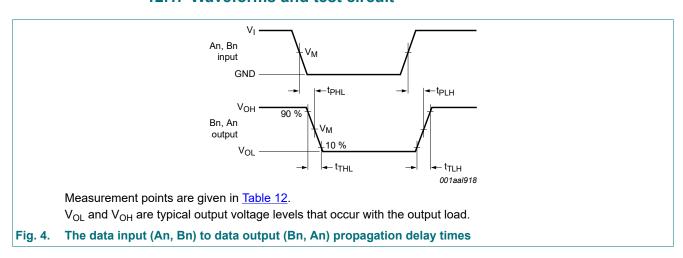
Symbol	Parameter	Conditions	V <sub>CC(B)</sub>						Unit
			2.5 V ± 0.2 V		3.3 V ± 0.3 V		5.0 V ± 0.5 V		
			Min	Max	Min	Max	Min	Max	
V <sub>CC(A)</sub> =	1.8 V ± 0.15 V				•				
t <sub>PHL</sub>	HIGH to LOW propagation delay	A to B	-	5.8	-	5.9	-	7.3	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	A to B	-	8.5	-	8.5	-	8.8	ns
t <sub>PHL</sub>	HIGH to LOW propagation delay	B to A	-	5.5	-	5.7	-	5.9	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	B to A	-	6.7	-	5.7	-	0.7	ns
t <sub>en</sub>	enable time	OE to A, B	-	200	-	200	-	200	ns
t <sub>dis</sub>	disable time	OE to A, B; no external load [1][2]	-	45	-	45	-	45	ns
		OE to A	-	250	-	250	-	250	ns
		OE to B	-	220	-	220	-	220	ns
t <sub>TLH</sub>	LOW to HIGH	A port	3.2	11.9	2.3	11.7	1.8	9.5	ns
	output transition time	B port	3.3	13.5	2.7	11.4	2.7	9.5	ns
t <sub>THL</sub>	HIGH to LOW	A port	2.0	7.4	1.9	7.5	1.7	16.7	ns
	output transition time	B port	2.9	9.5	2.8	9.4	2.8	12.5	ns
t <sub>sk(o)</sub>	output skew time	between channels [3]	-	0.8	-	0.8	-	8.0	ns
$t_W$	pulse width	data inputs	50	-	41	-	41	-	ns
f <sub>data</sub>	data rate		-	20	-	24	-	24	Mbps
$V_{CC(A)} =$	2.5 V ± 0.2 V								
t <sub>PHL</sub>	HIGH to LOW propagation delay	A to B	-	4.0	-	4.2	-	4.3	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	A to B	-	4.4	-	5.2	-	5.5	ns
t <sub>PHL</sub>	HIGH to LOW propagation delay	B to A	-	3.8	-	4.5	-	5.4	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	B to A	-	3.2	-	2.0	-	0.9	ns
t <sub>en</sub>	enable time	OE to A, B	-	200	-	200	-	200	ns
t <sub>dis</sub>	disable time	OE to A, B; no external load [1][2]	-	45	-	45	-	45	ns
		OE to A	-	220	-	220	-	220	ns
		OE to B	-	220	-	220	-	220	ns
t <sub>TLH</sub>	LOW to HIGH	A port	2.8	9.3	2.6	8.3	1.8	7.8	ns
	output transition time	B port	3.2	10.4	2.9	9.7	2.4	8.3	ns
t <sub>THL</sub>	HIGH to LOW	A port	1.9	7.2	1.9	6.9	1.8	6.7	ns
	output transition time B port		2.2	9.8	2.4	8.4	2.6	8.3	ns
t <sub>sk(o)</sub>	output skew time	between channels [3]	-	0.8	-	0.8	-	0.8	ns
t <sub>W</sub>	pulse width	data inputs	50	-	41	-	41	-	ns
f <sub>data</sub>	data rate		-	20	-	24	-	24	Mbps

#### Dual supply translating transceiver; open drain; auto direction sensing

Symbol	Parameter	Conditions		V <sub>CC(B)</sub>						
			2.5 V ± 0.2 V		3.3 V ± 0.3 V		5.0 V ± 0.5 V			
			Min	Max	Min Max		Min Max			
V <sub>CC(A)</sub> =	3.3 V ± 0.3 V									
t <sub>PHL</sub>	HIGH to LOW propagation delay	A to B	-	-	-	3.0	-	3.9	ns	
t <sub>PLH</sub>	LOW to HIGH propagation delay	A to B	-	-	-	5.3	-	5.5	ns	
t <sub>PHL</sub>	HIGH to LOW propagation delay	B to A	-	-	-	3.2	-	4.2	ns	
t <sub>PLH</sub>	LOW to HIGH propagation delay	B to A	-	-	-	3.2	-	3.3	ns	
t <sub>en</sub>	enable time	OE to A, B	-	-	-	200	-	200	ns	
t <sub>dis</sub>	disable time	OE to A, B; no external load [1][2]	-	-	-	45	-	45	ns	
		OE to A	-	-	-	280	-	280	ns	
		OE to B	-	-	-	220	-	220	ns	
t <sub>TLH</sub>	LOW to HIGH	A port	-	-	2.3	7.0	1.9	7.4	ns	
	output transition time	B port	-	-	2.5	8.0	2.1	9.3	ns	
t <sub>THL</sub>	HIGH to LOW	A port	-	-	2.0	6.8	1.9	6.3	ns	
output transition time		B port	-	-	2.3	9.3	2.4	9.5	ns	
t <sub>sk(o)</sub>	output skew time	between channels [3]	-	-	-	0.8	-	0.8	ns	
t <sub>W</sub>	pulse width	data inputs	-	-	41	-	41	-	ns	
f <sub>data</sub>	data rate		-	-	-	24	-	24	Mbps	

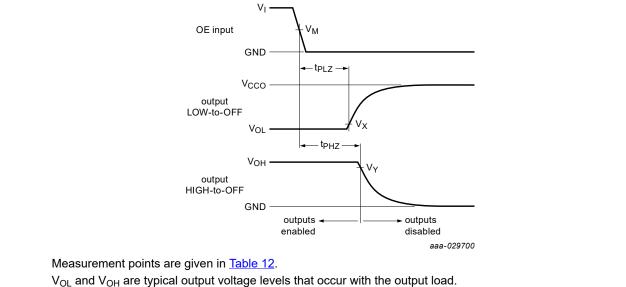
- $t_{dis}$  is the same as  $t_{PLZ}$  and  $t_{PHZ}$ .
- [2] [3] The disable time with no external load indicates the delay between when OE goes LOW and when outputs actually become disabled.
- Skew between any two outputs of the same package switching in the same direction.

### 12.1. Waveforms and test circuit



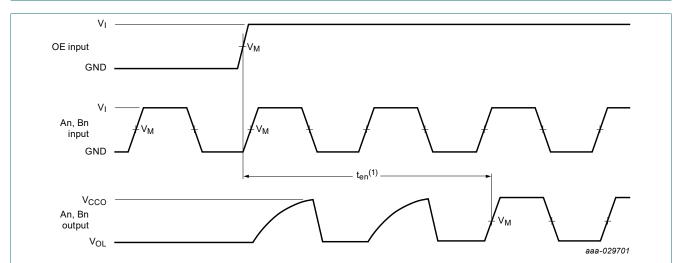
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#### Dual supply translating transceiver; open drain; auto direction sensing



V<sub>CCO</sub> is the supply voltage associated with the output.

**Disable times** Fig. 5.



(1) The enable time (t<sub>en</sub>) indicates the amount of time the user must allow for one one-shot circuitry to become operational after OE is taken HIGH. See also Section 13.6

Measurement points are given in Table 12.

V<sub>OL</sub> is a typical output voltage level that occur with the output load.

V<sub>CCO</sub> is the supply voltage associated with the output.

Fig. 6. **Enable times** 

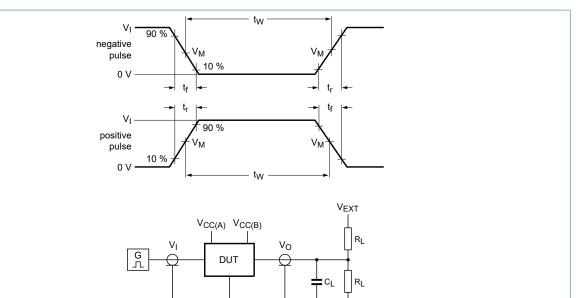
**Table 12. Measurement points** 

Supply voltage	Input	Output				
V <sub>cco</sub>	V <sub>M</sub> [1]	V <sub>M</sub> [2]	V <sub>X</sub>	V <sub>Y</sub>		
1.8 V ± 0.15 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.15 V	V <sub>OH</sub> - 0.15 V		
2.5 V ± 0.2 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.15 V	V <sub>OH</sub> - 0.15 V		
3.3 V ± 0.3 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.3 V	V <sub>OH</sub> - 0.3 V		
5.0 V ± 0.5 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.3 V	V <sub>OH</sub> - 0.3 V		

- V<sub>CCI</sub> is the supply voltage associated with the input.
- V<sub>CCO</sub> is the supply voltage associated with the output.

#### Dual supply translating transceiver; open drain; auto direction sensing

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Test data is given in Table 13.

All input pulses are supplied by generators having the following characteristics:

PRR  $\leq$  10 MHz;  $Z_O = 50 \Omega$ ;  $dV/dt \geq 1.0 V/ns$ .

R<sub>L</sub> = Load resistance.

C<sub>L</sub> = Load capacitance including jig and probe capacitance.

V<sub>EXT</sub> = External voltage for measuring switching times.

Fig. 7. Test circuit for measuring switching times

Table 13. Test data

Supply voltage		Input		Load		V <sub>EXT</sub>			
V <sub>CC(A)</sub>	V <sub>CC(B)</sub>	V <sub>I</sub> [1]	Δt/ΔV	CL	R <sub>L</sub> [2]	t <sub>PLH</sub> , t <sub>PHL</sub>	t <sub>PZH</sub> , t <sub>PHZ</sub>	t <sub>PZL</sub> , t <sub>PLZ</sub> [3]	
1.65 V to 3.6 V	2.3 V to 5.5 V	V <sub>CCI</sub>	≤ 1.0 ns/V	15 pF	50 kΩ, 1 MΩ	open	open	2V <sub>CCO</sub>	

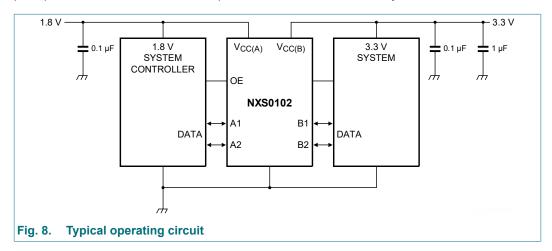
- [1] V<sub>CCI</sub> is the supply voltage associated with the input.
- [2] For measuring data rate, pulse width, propagation delay and output rise and fall measurements,  $R_L = 1 \text{ M}\Omega$ ; for measuring enable and disable times,  $R_L = 50 \text{ k}\Omega$ .
- [3] V<sub>CCO</sub> is the supply voltage associated with the output.

Dual supply translating transceiver; open drain; auto direction sensing

# 13. Application information

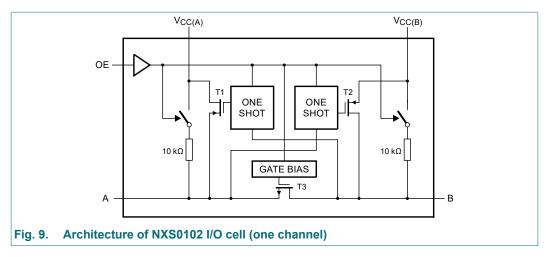
### 13.1. Applications

Voltage level-translation applications. The NXS0102 can be used in point-to-point applications to interface between devices or systems operating at different supply voltages. The device is primarily targeted at  $I^2C$  or 1-wire which use open-drain drivers, it may also be used in applications where push-pull drivers are connected to the ports, however the NXB0102 may be more suitable.



#### 13.2. Architecture

The architecture of the NXS0102 is shown in Fig. 9. The device does not require an extra input signal to control the direction of data flow from A to B or B to A.



The NXS0102 is a "switch" type voltage translator, it employs two key circuits to enable voltage translation:

- 1. A pass-gate transistor (N-channel) that ties the ports together.
- 2. An output edge-rate accelerator that detects and accelerates rising edges on the I/O pins.

The gate bias voltage of the pass gate transistor (T3) is set at approximately one threshold voltage above the  $V_{CC(A)}$  level of the low-voltage side. During a rising edge, the one shots turn on the PMOS transistors (T1, T2) for a short duration, accelerating the low-to-high transition. The one-shot is activated once the input transition reaches approximately  $0.5V_{CCI}$ . During the acceleration time the driver output resistance is between approximately  $50~\Omega$  and  $50~\Omega$ . To avoid signal contention and minimize dynamic  $I_{CC}$ , the user should wait for the one-shot circuit to turn-off before applying a

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#### Dual supply translating transceiver; open drain; auto direction sensing

signal in the opposite direction. Pull-up resistors are included in the device for DC current sourcing capability.

### 13.3. Input driver requirements

As the NXS0102 is a switch type translator, properties of the input driver directly effect the output signal. The external open-drain or push-pull driver applied to an I/O determines the static current sinking capability of the system. The max data rate, HIGH-to-LOW output transition time ( $t_{THL}$ ) and propagation delay ( $t_{PHL}$ ) are dependent upon the output impedance and edge-rate of the external driver. The limits provided for these parameters in the datasheet assume a driver with output impedance below 50  $\Omega$  is used.

#### 13.4. Output load considerations

The maximum lumped capacitive load that can be driven is dependant upon the one-shot pulse duration. In cases with very heavy capacitive loading there is a risk that the output will not reach the positive rail within the one-shot pulse duration. To avoid excessive capacitive loading and to ensure correct triggering of the one-shot it's recommended to use short trace lengths and low capacitance connectors on NXS0102 PCB layouts. To ensure low impedance termination and avoid output signal oscillations and one-shot re-triggering, the length of the PCB trace should be such that the round trip delay of any reflection is within the one-shot pulse duration.

### 13.5. Power up

During operation  $V_{CC(A)}$  must never be higher than  $V_{CC(B)}$ , however during power-up  $V_{CC(B)} \ge V_{CC(B)}$  does not damage the device, so any power supply can be ramped up first. There is no special power-up sequencing required. The NXS0102 includes circuitry that disables all output ports when either  $V_{CC(A)}$  or  $V_{CC(B)}$  is switched off.

#### 13.6. Enable and disable

An output enable input (OE) is used to disable the device. Setting OE to LOW causes all I/Os to assume the high-impedance OFF-state. The disable time ( $t_{\rm dis}$  with no external load) indicates the delay between when OE goes LOW and when outputs actually become disabled. The enable time ( $t_{\rm en}$ ) indicates the amount of time the user must allow for one one-shot circuitry to become operational after OE is taken HIGH. To ensure the high-impedance OFF-state during power-up or power-down, pin OE should be tied to GND through a pull-down resistor, the minimum value of the resistor is determined by the current-sourcing capability of the driver.

#### 13.7. Pull-up or pull-down resistors on I/O lines

Each A port I/O has an internal 10 k $\Omega$  pull-up resistor to  $V_{CC(A)}$ , and each B port I/O has an internal 10 k $\Omega$  pull-up resistor to  $V_{CC(B)}$ . If a smaller value of pull-up resistor is required, an external resistor must be added parallel to the internal 10 k $\Omega$ , this will effect the  $V_{OL}$  level. When OE goes LOW the internal pull-ups of the NXS0102 are disabled.

#### Dual supply translating transceiver; open drain; auto direction sensing

# 14. Package outline

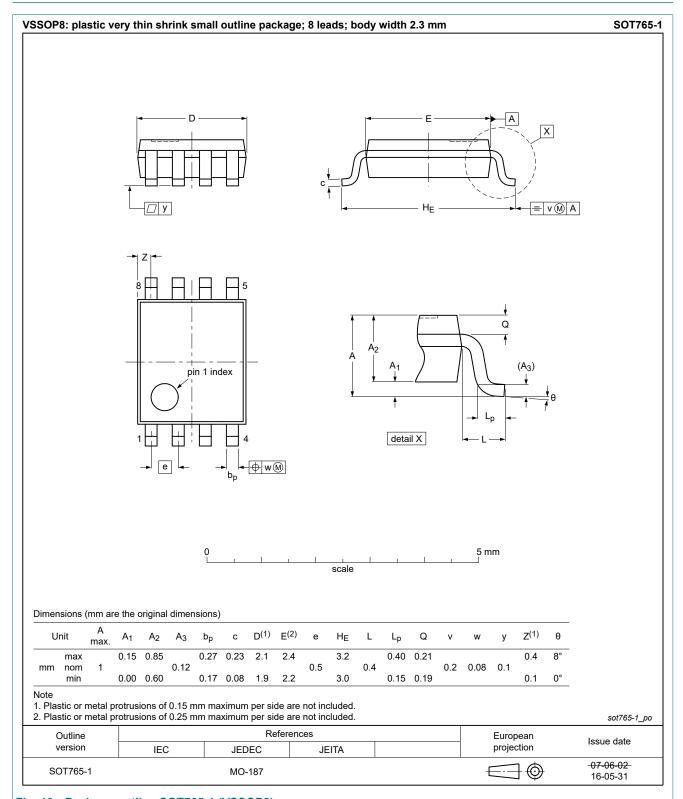


Fig. 10. Package outline SOT765-1 (VSSOP8)

#### Dual supply translating transceiver; open drain; auto direction sensing

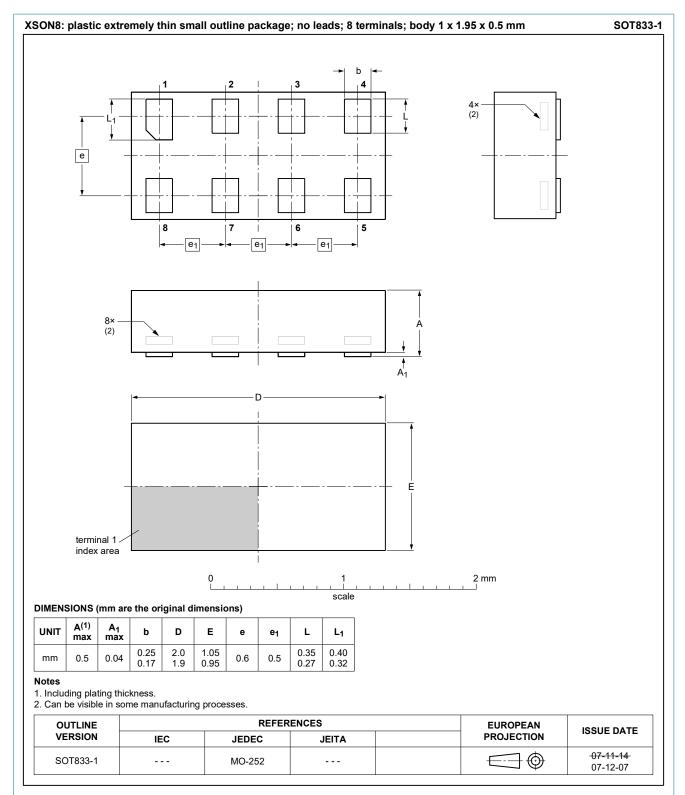


Fig. 11. Package outline SOT833-1 (XSON8)

### Dual supply translating transceiver; open drain; auto direction sensing

# 15. Abbreviations

#### **Table 14. Abbreviations**

Acronym	Description
CDM	Charged Device Model
DUT	Device Under Test
ESD	ElectroStatic Discharge
НВМ	Human Body Model
I <sup>2</sup> C	Inter-Integrated Circuit
PCB	Printed Circuit Board
PRR	Pulse Rate Repetition

# 16. Revision history

#### **Table 15. Revision history**

Document ID	Release date	Data sheet status	Change notice	Supersedes
NXS0102 v.1	20191217	Product data sheet	-	-

#### Dual supply translating transceiver; open drain; auto direction sensing

# 17. Legal information

#### Data sheet status

Document status [1][2]	Product status [3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

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### Dual supply translating transceiver; open drain; auto direction sensing

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