

5-V DUAL RS-232 LINE DRIVER/RECEIVER WITH \pm 15-kV ESD PROTECTION

- ESD Protection for RS-232 Bus Pins
 ±15-kV Human-Body Model
- Meets or Exceeds the Requirements of TIA/EIA-232-F and ITU v.28 Standards
- Operates at 5-V V_{CC} Supply
- Operates Up To 120 kbit/s
- External Capacitors . . . $4 \times 0.1 \mu F$
- Latch-Up Performance Exceeds 100 mA Per JESD 78, Class II
- Applications
 - Battery-Powered Systems, PDAs, Notebooks, Laptops, Palmtop PCs, and Hand-Held Equipment

D, DW, N, OR PW PACKAGE (TOP VIEW) 16 VCC C1+ ∏ 1 V+ **1** 2 15 GND C1− []3 14 DOUT1 13 RIN1 C2+ [] 4 C2- [5 12**∏** ROUT1 V−¶6 11 DIN1 10 DIN2 DOUT2 I 7 9 ROUT2 RIN2 8

description/ordering information

The MAX202 device consists of two line drivers, two line receivers, and a dual charge-pump circuit with ± 15 -kV ESD protection pin to pin (serial-port connection pins, including GND). The device meets the requirements of TIA/EIA-232-F and provides the electrical interface between an asynchronous communication controller and the serial-port connector. The charge pump and four small external capacitors allow operation from a single 5-V supply. The device operates at data signaling rates up to 120 kbit/s and a maximum of 30-V/ μ s driver output slew rate.



Function Tables

EACH DRIVER

INPUT DIN	OUTPUT DOUT
L	Н
Н	L

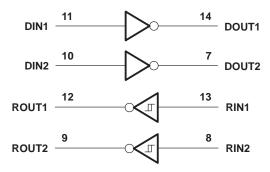
H = high level, L = low level

EACH RECEIVER

INPUT R _{IN}	OUTPUT ROUT
L	Н
Н	L
Open	Н

H = high level, L = low level, Open = input disconnected or connected driver off

logic diagram (positive logic)





absolute maximum ratings over operating free-air temperature range (unless otherwise noted)†

Supply voltage range, V _{CC} (see Note 1)	0.3 V to 6 V
Positive charge pump voltage range, V+ (see Note 1)	V _{CC} – 0.3 V to 14 V
Negative charge pump voltage range, V– (see Note 1)	–14 V to 0.3 V
Input voltage range, V _I : Drivers	0.3 V to V+ + 0.3 V
Receivers	±30 V
Output voltage range, VO: Drivers	V0.3 V to V+ + 0.3 V
Receivers	0.3 V to V _{CC} + 0.3 V
Short-circuit duration: D _{OUT}	Continuous
Package thermal impedance, θ_{JA} (see Notes 2 and 3):	D package 73°C/W
	DW package 57°C/W
	N package 67°C/W
	PW package 108°C/W
Operating virtual junction temperature, T _J	
Storage temperature range, T _{stg}	–65°C to 150°C

[†] Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

- NOTES: 1. All voltages are with respect to network GND.
 - 2. Maximum power dissipation is a function of $T_J(max)$, θ_{JA} , and T_A . The maximum allowable power dissipation at any allowable ambient temperature is $P_D = (T_J(max) T_A)/\theta_{JA}$. Operating at the absolute maximum T_J of 150°C can affect reliability.
 - 3. The package thermal impedance is calculated in accordance with JESD 51-7.

recommended operating conditions (see Note 4 and Figure 4)

				NOM	MAX	UNIT
	Supply voltage		4.5	5	5.5	V
VIH	Driver high-level input voltage	D _{IN}	2			V
V _{IL}	Driver low-level input voltage	D _{IN}			0.8	V
.,	Driver input voltage	D _{IN}	0		5.5	.,
VI	Receiver input voltage		-30		30	V
_		MAX202C	0		70	00
TA	Operating free-air temperature	MAX202I	-40		85	°C

NOTE 4: Test conditions are C1–C4 = 0.1 μ F at V_{CC} = 5 V \pm 0.5 V.

electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Note 4 and Figure 4)

PARAMETER	TEST CONDITIONS	MIN TYP‡	MAX	UNIT
ICC Supply current	No load, V _{CC} = 5 V	8	15	mA

[‡] All typical values are at V_{CC} = 5 V, and T_A = 25°C.

NOTE 4: Test conditions are C1–C4 = 0.1 μF at V_CC = 5 V \pm 0.5 V.



DRIVER SECTION

electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Note 4 and Figure 4)

PARAMETER		TEST CONDITIONS		MIN	TYP†	MAX	UNIT
Vон	High-level output voltage	D _{OUT} at R _L = 3 k Ω to GND,	D _{IN} = GND	5	9		V
VOL	Low-level output voltage	D_{OUT} at $R_L = 3 \text{ k}\Omega$ to GND,	$D_{IN} = V_{CC}$	-5	-9		V
lн	High-level input current	VI = VCC			15	200	μΑ
Ι _Ι L	Low-level input current	V _I at 0 V			-15	-200	μΑ
los‡	Short-circuit output current	V _{CC} = 5.5 V,	V _O = 0 V		±10	±60	mA
r _O	Output resistance	V_{CC} , V+, and V- = 0 V,	V _O = ±2 V	300		·	Ω

[†] All typical values are at $V_{CC} = 5 \text{ V}$, and $T_A = 25^{\circ}\text{C}$.

NOTE 4: Test conditions are C1–C4 = 0.1 μ F at V_{CC} = 5 V \pm 0.5 V.

switching characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Note 4 and Figure 4)

PARAMETER		TEST C	TEST CONDITIONS		TYP [†]	MAX	UNIT
	Maximum data rate	C _L = 50 to1000 pF, One D _{OUT} switching,	R_L = 3 kΩ to 7 kΩ, See Figure 1	120			kbit/s
^t PLH (D)	Propagation delay time, low- to high-level output	C _L = 2500 pF, All drivers loaded,	$R_L = 3 kΩ$, See Figure 1		2		μs
^t PHL (D)	Propagation delay time, high- to low-level output	C _L = 2500 pF, All drivers loaded,	$R_L = 3 \text{ k}\Omega$, See Figure 1		2		μs
t _{sk(p)}	Pulse skew§	$C_L = 150 \text{ pF to } 2500 \text{ pF},$	R_L = 3 kΩ to 7 kΩ, See Figure 2		300		ns
SR(tr)	Slew rate, transition region (see Figure 1)	$C_L = 50 \text{ pF to } 1000 \text{ pF,}$ $V_{CC} = 5 \text{ V}$	$R_L = 3 \text{ k}\Omega \text{ to } 7 \text{ k}\Omega,$	3	6	30	V/μs

[†] All typical values are at $V_{CC} = 5 \text{ V}$, and $T_A = 25^{\circ}\text{C}$.

ESD protection

PIN	TEST CONDITIONS	TYP	UNIT
Dout, RIN	Human-Body Model	±15	kV

^{\$\}frac{1}{2}\$ Short-circuit durations should be controlled to prevent exceeding the device absolute power-dissipation ratings, and not more than one output should be shorted at a time.

[§] Pulse skew is defined as $|tp_{LH} - tp_{HL}|$ of each channel of the same device. NOTE 4: Test conditions are C1–C4 = 0.1 μ F at V_{CC} = 5 V \pm 0.5 V.



RECEIVER SECTION

electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Note 4 and Figure 4)

PARAMETER		TEST CONDITIONS		MIN	TYP [†]	MAX	UNIT
Vон	High-level output voltage	I _{OH} = -1 mA		3.5V	V _{CC} -0.4 V		V
VOL	Low-level output voltage	I _{OL} = 1.6 mA				0.4	V
V _{IT+}	Positive-going input threshold voltage	$V_{CC} = 5 V$,	T _A = 25°C		1.7	2.4	V
V _{IT} _	Negative-going input threshold voltage	$V_{CC} = 5 V$,	T _A = 25°C	0.8	1.2		V
V _{hys}	Input hysteresis (V _{IT+} - V _{IT-})			0.2	0.5	1	V
rį	Input resistance	$V_I = \pm 3 \text{ V to } \pm 25 \text{ V}$		3	5	7	kΩ

[†] All typical values are at $V_{CC} = 5$ V, and $T_A = 25$ °C.

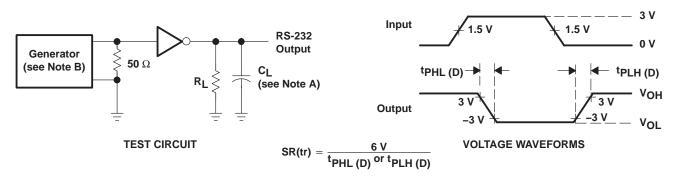
NOTE 4: Test conditions are C1–C4 = 0.1 μ F at V_{CC} = 5 V \pm 0.5 V.

switching characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Note 4 and Figure 3)

	PARAMETER	TEST CONDITIONS	MIN	TYP [†]	MAX	UNIT
tPLH (R)	Propagation delay time, low- to high-level output	C _L = 150 pF		0.5	10	μs
tPHL (R)	Propagation delay time, high- to low-level output	C _L = 150 pF		0.5	10	μs
tsk(p)	Pulse skew [‡]			300		ns

[†] All typical values are at $V_{CC} = 5$ V, and $T_A = 25$ °C.

PARAMETER MEASUREMENT INFORMATION



NOTES: A. C_L includes probe and jig capacitance.

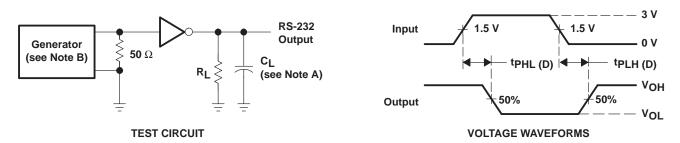
B. The pulse generator has the following characteristics: PRR = 120 kbit/s, $Z_O = 50 \Omega$, 50% duty cycle, $t_f \le 10$ ns. $t_f \le 10$ ns.

Figure 1. Driver Slew Rate

[‡] Pulse skew is defined as $|t_{PLH} - t_{PHL}|$ of each channel of the same device. NOTE 4: Test conditions are C1–C4 = 0.1 μ F, at V_{CC} = 5 V \pm 0.5 V.

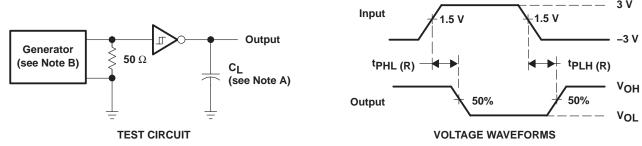


PARAMETER MEASUREMENT INFORMATION



- NOTES: A. C_L includes probe and jig capacitance.
 - B. The pulse generator has the following characteristics: PRR = 120 kbit/s, $Z_O = 50 \Omega$, 50% duty cycle, $t_f \le 10$ ns.

Figure 2. Driver Pulse Skew



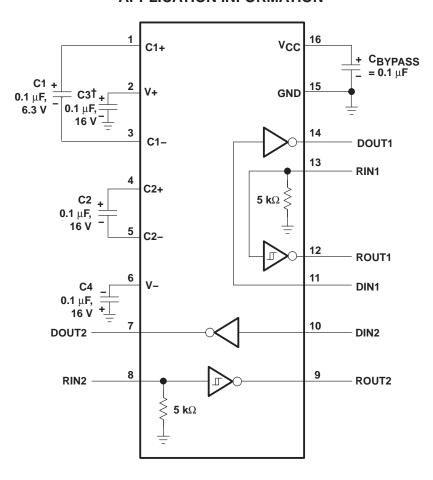
NOTES: A. C_L includes probe and jig capacitance.

B. The pulse generator has the following characteristics: $Z_O = 50~\Omega$, 50% duty cycle, $t_\Gamma \le 10~\text{ns}$.

Figure 3. Receiver Propagation Delay Times



APPLICATION INFORMATION



 $^\dagger\text{C3}$ can be connected to $\text{V}_{\mbox{CC}}$ or GND.

NOTES: A. Resistor values shown are nominal.

B. Nonpolarized ceramic capacitors are acceptable. If polarized tantalum or electrolytic capacitors are used, they should be connected as shown.

Figure 4. Typical Operating Circuit and Capacitor Values



APPLICATION INFORMATION

capacitor selection

The capacitor type used for C1–C4 is not critical for proper operation. The MAX202 requires 0.1- μ F capacitors, although capacitors up to 10 μ F can be used without harm. Ceramic dielectrics are suggested for the 0.1- μ F capacitors. When using the minimum recommended capacitor values, make sure the capacitance value does not degrade excessively as the operating temperature varies. If in doubt, use capacitors with a larger (e.g., 2×) nominal value. The capacitors' effective series resistance (ESR), which usually rises at low temperatures, influences the amount of ripple on V+ and V-.

Use larger capacitors (up to 10 μ F) to reduce the output impedance at V+ and V-.

Bypass V_{CC} to ground with at least 0.1 μ F. In applications sensitive to power-supply noise generated by the charge pumps, decouple V_{CC} to ground with a capacitor the same size as (or larger than) the charge-pump capacitors (C1–C4).

ESD protection

MAX202 devices have standard ESD protection structures incorporated on the pins to protect against electrostatic discharges encountered during assembly and handling. In addition, the RS232 bus pins (driver outputs and receiver inputs) of these devices have an extra level of ESD protection. Advanced ESD structures were designed to successfully protect these bus pins against ESD discharge of ±15-kV when powered down.

ESD test conditions

Stringent ESD testing is performed by TI, based on various conditions and procedures. Please contact TI for a reliability report that documents test setup, methodology, and results.

Human-Body Model (HBM)

The HBM of ESD testing is shown in Figure 5. Figure 6 shows the current waveform that is generated during a discharge into a low impedance. The model consists of a 100-pF capacitor, charged to the ESD voltage of concern, and subsequently discharged into the device under test (DUT) through a 1.5-k Ω resistor.

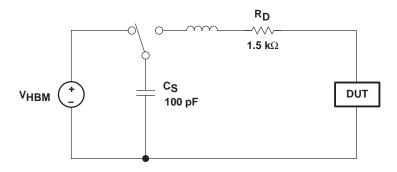


Figure 5. HBM ESD Test Circuit



APPLICATION INFORMATION

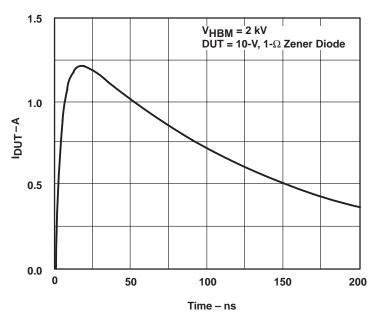


Figure 6. Typical HBM Current Waveform

Machine Model (MM)

The MM ESD test applies to all pins using a 200-pF capacitor with no discharge resistance. The purpose of the MM test is to simulate possible ESD conditions that can occur during the handling and assembly processes of manufacturing. In this case, ESD protection is required for all pins, not just RS-232 pins. However, after PC board assembly, the MM test no longer is as pertinent to the RS-232 pins.



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