

## Data Sheet Supplement Version 1.0

# Dynamic Differential Hall Effect Sensor TLE4924C-2 E6547

For all parameters not specified in this document the TLE4926C-HT E6547 data sheet is valid.



Туре	Marking	Ordering Code	Package
TLE4924C-2 E6547	24D82	SP000718250	PG-SSO-3-92



### 1. Absolute Maximum Ratings

Parameter	Symbol	min.	typ.	max.	Unit	Conditions
Junction	Tj	-40			°C	-
temperature				155	°C	2000 h (not additive)
				165	°C	1000 h (not additive)
				175	°C	168 h (not additive)
				195	°C	3x1 h (additive to the other life times).

### 2. Operating Range

Operating junction	Tj	-40		°C	-
temperature			155	°C	2000 h (not additive)
			165	°C	1000 h (not additive)
			175	°C	168 h (not additive)
					reduced signal
					quality permittable
					(e.g. jitter).

#### 3. AC/DC characteristics in Running Mode

Over operating range, unless otherwise specified. Typical values correspond to V<sub>S</sub>=12V and T<sub>A</sub>=25°C

delay time Falling edge	t <sub>d</sub>	7	12.5	18 20 <sup>1</sup>	µs µs	Only valid for Tj=25°C.
				20 25 <sup>2</sup>	μο	Tj=-40°C -Tj=175°C
Rising edge				25		Tj=-40°C -Tj=175°C
						Higher magnetic
						slopes and overshoots
						reduce $t_d$ , because the
						signal is filtered
						internal.3

<sup>&</sup>lt;sup>1</sup> only valid for the falling edge. <sup>2</sup> Not subject to production test-verified by design/characterisation <sup>3</sup> measured with a sinusoidal-field with 10mTpp and a frequency of 1kHz.



### 4. Magnetic Characteristics in Running Mode

Minimum signal	$ \Delta B_{min} $	0.35	0.75	1.35	mT	
amplitude						



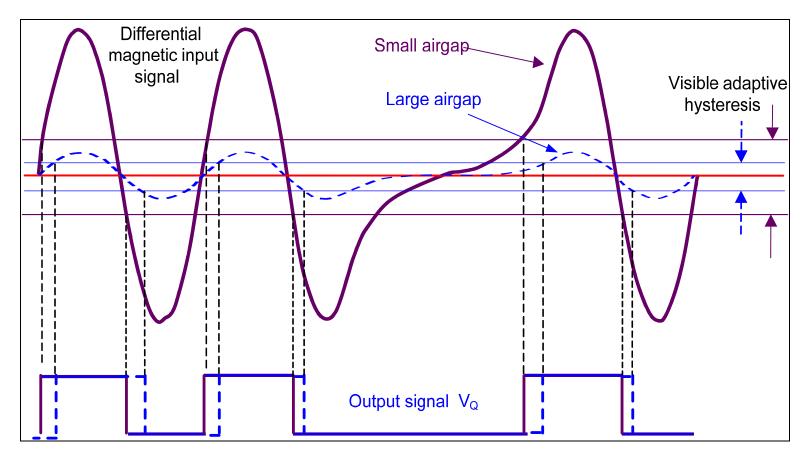


Figure 1 System operation with visible adaptive hysteresis



### 5. Typical Hysteresis Values

PGA	GainRange	Hysteresis (peak to peak)	FullRange =MaxSignal	Percentage thresholds
X1	6	10.6 mT	± 120 mT	4.42 %
X2	5	8.0 mT	± 60 mT	6.67 %
X4	4	5.5 mT	$\pm$ 30 mT	9.17 %
X8	3	3.8 mT	± 15 mT	12.67 %
X16	2	2.6 mT	± 7.5 mT	17.33 %
X32	1	1.8 mT	± 3.75 mT	24 %
X64	0	1.3 mT	± 1.875 mT	34.67 %



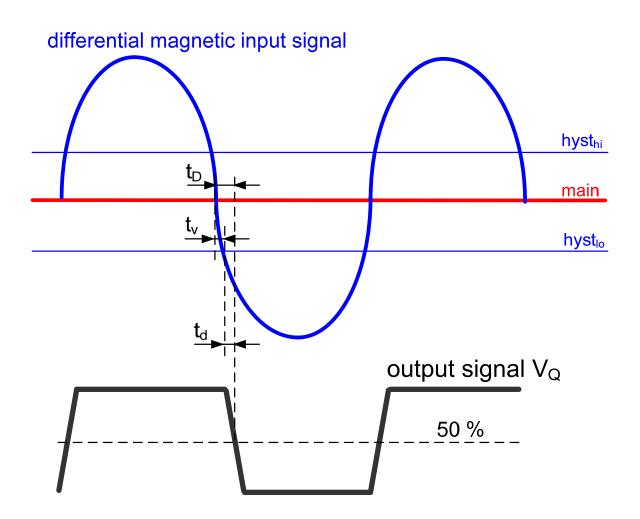


Figure 2 Delay time definitions

 $t_D = t_v + t_d$ 

- $t_D$  = Delay defined from  $diff_B$  = 0 to 50 % of output edge
- $t_d$  = Delay on signal path
- $t_v$  = Systematic delay because of visible hysteresis concept

 $t_{\nu}\xspace$  is a function of the magnetic signal amplitude and frequency



Revision History:		November 2009	Version 1.0
Previous V	ersion: -		
Page	Subjects (ma		
-	-		

Infineon Technologies AG © Infineon Technologies AIM SC All Rights Reserved. http://www.infineon.com/products/sensors

### We Listen to Your Comments

Any information within this document that you feel is wrong, unclear or missing at all? Your feedback will help us to continuously improve the quality of this document. Please send your proposal (including a reference to this document) to: Sensors@infineon.com