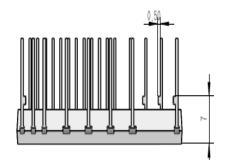
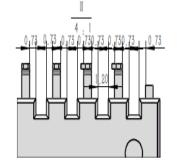
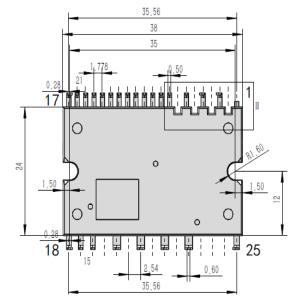


# **Features**

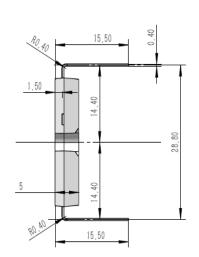
- Adopt the latest trench IGBT technology to get a good overall loss trade-off.
- Open Emitter on N terminal for low cost current sensing application.
- Matched propagation delay and arm shooting through prevention.
- Built-in bootstrap diodes with current limiting resistor.
- Provided a fault signal (FO pin) and shut-off internal IGBT when suffer S.C. and under-voltage faulty event.
- RoHS compatible.
- UL 1557 Compliance.





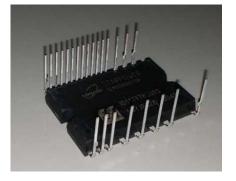






#### **TERMINAL CODE**

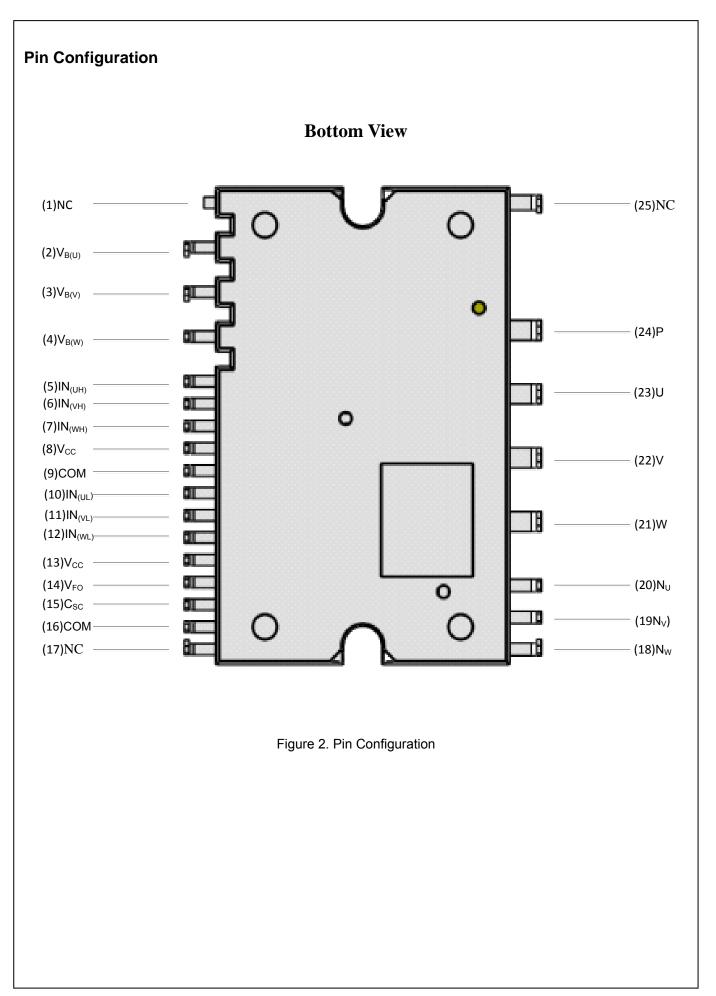
1 NC	16 COM
$2 \; V_{B(U)}$	17 NC
3 V <sub>B(V)</sub>	$18 \; \text{N}_{\text{W}}$
$4 V_{B(W)}$	$19 \; N_V$
5 IN <sub>(UH)</sub>	$20 \; \text{N}_{\text{U}}$
6 IN <sub>(VH)</sub>	21 W
7 IN <sub>(WH)</sub>	22 V
8 V <sub>CC</sub>	23 U
9 COM	24 P
10 IN <sub>(UL</sub> )	25 NC
11 IN <sub>(VL)</sub>	
12 IN <sub>(WL)</sub>	
$13 V_{CC}$	
$14 V_{FO}$	
15 C <sub>SC</sub>	



# Table1: Pin Descriptions

No.	Symbol	Pin Description
1	NC	No connection
2	V <sub>B(U)</sub>	High - side Bias Voltage for U Phase IGBT Driving
3	V <sub>B(V)</sub>	High - side Bias Voltage for V Phase IGBT Driving
4	V <sub>B(W)</sub>	High - side Bias Voltage for W Phase IGBT Driving
5	IN <sub>(UH)</sub>	Signal Input Terminal for High-side U Phase
6	IN <sub>(VH)</sub>	Signal Input Terminal for High-side V Phase
7	IN <sub>(WH)</sub>	Signal Input Terminal for High-side W Phase
8	Vcc	Supply Voltage Terminal for Driver IC
9	СОМ	Reference Voltage Terminal for Driver IC
10	IN <sub>(UL</sub> )	Signal Input Terminal for Low-side U Phase
11	IN <sub>(VL)</sub>	Signal Input Terminal for Low-side V Phase
12	IN <sub>(WL)</sub>	Signal Input Terminal for Low-side W Phase
13	V <sub>cc</sub>	Supply Voltage Terminal for Driver IC
14	V <sub>FO</sub>	Fault Output Terminal
15	Csc	Short-Current Detection Input
16	СОМ	Reference Voltage Terminal for Driver IC
17	NC	No connection
18	Nw	Negative DC-Link Input Terminal for W Phase
19	Nv	Negative DC-Link Input Terminal for V Phase
20	Nu	Negative DC-Link Input Terminal for U Phase
21	W	Output Terminal for W Phase
22	V	Output Terminal for V Phase
23	U	Output Terminal for U Phase
24	Р	Positive DC – Link Input
25	NC	No connection

(see figure 2, next page)



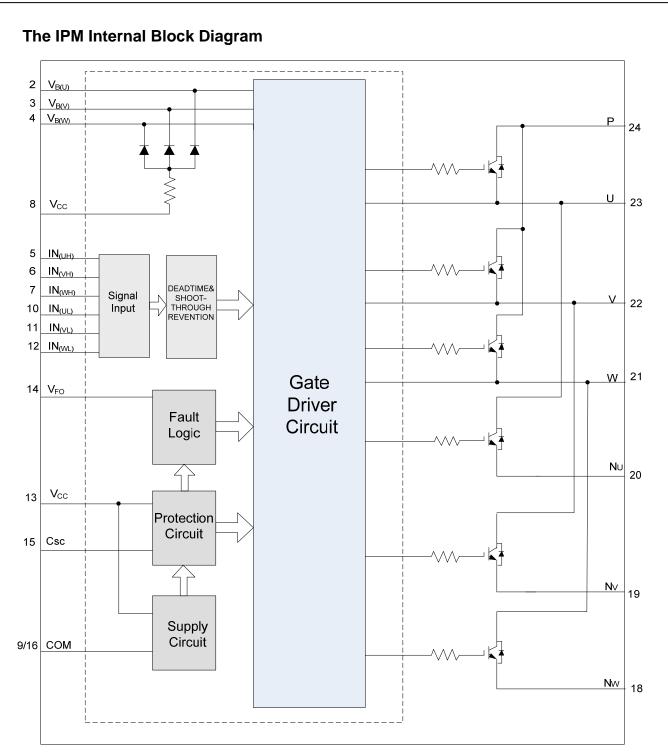


Figure 3. IPM Internal Block Diagram

#### Application:

- Short-circuit current protection AC 100~240Vrms class 3 phase output for low power motor control.
- Household electric appliances such as air conditioners, washing machines, refrigerators, etc..,
- Low power industrial servo drives applications such as sewing machine, treadmill, etc...

## **MAXIMUM RATINGS** (T<sub>j</sub> = $25^{\circ}$ C)

#### **INVERTER PART**

Item	Symbol	Min.	Max.	Unit
Between collector to emitter voltage	V <sub>CES</sub> (IGBT)	-	600	V
Supply voltage P-N	V <sub>PN</sub>	-	450	V
Supply voltage (surge) P-N	V <sub>PN (surge)</sub>	-	500	V
Each IGBT collector current	± I <sub>C</sub> (Tc = 25℃)	-	15	А
Each IGBT collector current (peak)	± I <sub>CP</sub> (Tc = 25℃, pulse)	-	45	А
Collector dissipation	$P_C$ (Tc = 25°C, per one chip)	-	60	W
Junction temperature	Tj (Note 1)	-40	+150	°C

Note 1: Power chip in IPM is qualified for 150°C operation. But overall junction temperature should be limited by  $T_j \leq 125^{\circ}$ C (@ Tc  $\leq$ 

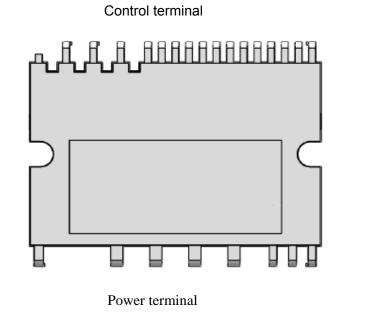
100°C) to fit long term reliability requirement.

### **CONTROL PART**

Item	Symbol	Min.	Max.	Unit
Driver IC supply voltage	V <sub>CC</sub>	-0.3	20	V
P - side floating supply voltage	V <sub>B(u)S(u),</sub> B(V)S(V), B(W)S(W)	-0.3	20	V
Current sensing input voltage	V <sub>SC</sub>	-0.3	Vcc+0.3	V
Logic input voltage	$IN_{(UH)}, IN_{(VH)}, IN_{(WH)},$ $IN_{(UL)}, IN_{(VL)}, IN_{(WL)}$	-0.3	Vcc+0.3	V
Fault output voltage	V <sub>FO</sub>	-0.3	Vcc+0.3	V
Fault output current	I <sub>FO</sub>	-	10	mA

### TOTAL SYSTEM

Item	Symbol	Min.	Max.	Unit
Module case operating temperature	T <sub>C</sub> (No	ote 2) -20	+100	°C
Storage temperature	T <sub>stg</sub>	-40	+125	°C
Isolation voltage (60Hz Sinusoidal, AC 1 minute, pins to heat-sink plate)	V <sub>iso</sub>	-	1500	Vrms



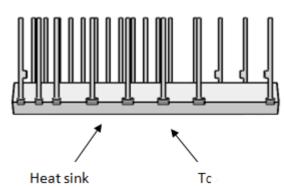


Figure 4. Tc Measurement Point

#### THERMAL RESISTANCE

Item	Symbol	Condition	Min.	Тур.	Max.	Unit
Junction to case thermal	R <sub>th(j-c)Q</sub>	IGBT part (1/6)	-	2.1		°C AA/
resistance	R <sub>th(j-c)F</sub>	FWD part (1/6)	-	2.7		°C/W

ELECTRICAL CHARACTERISTICS (Tj = 25°C)

#### **INVERTER PART**

Item	Symbol	Condition	Min.	Тур.	Max.	Unit
Collector-emitter saturation voltage	V <sub>CE (sat)</sub>	$V_{CC} = V_{B(U)S(U), B(V)S(V), B(W)S(W)} = T_j=25^{\circ}C$ 15V, I <sub>C</sub> = 15A, V <sub>SC</sub> = 0V		1.7		V
FWD forward voltage drop	VF	Tj =25℃, - IC = 15A		1.2		V
	T <sub>on</sub>			0.7		
Switching times	Tr	$V_{\rm D}$ = 300V,		0.09		μS
	T <sub>c(on)</sub>	$V_{CC} = V_{B(U)S(U), B(V)S(V), B(W)S(W)} = 15V,$		0.2		
Switching times (Fig. 5)	T <sub>off</sub>	I <sub>C</sub> = 15A, T <sub>j</sub> =25℃,		0.7		
(1.9.0)	T <sub>f</sub>	V <sub>IN</sub> = 5V <> 0V,		0.07		
	T <sub>c(off)</sub>	V <sub>SC</sub> = 0V, Inductive Load		0.1		
	T <sub>rr</sub>			0.15		
Collector-emitter cut-off current	I <sub>CES</sub>	V <sub>CE</sub> =V <sub>CES</sub>			500	μA

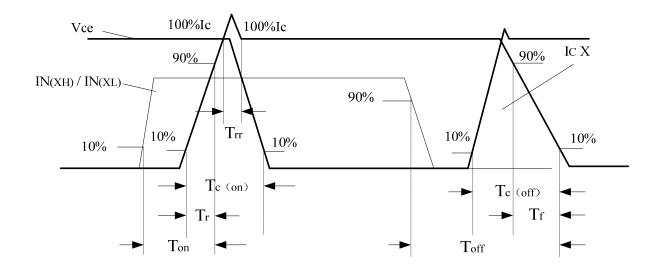


Figure 5. Switching Time Definition

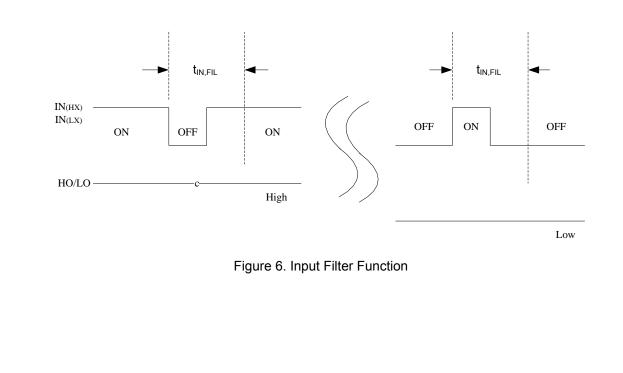
<b>CONTROL PART</b> (T <sub>j</sub> = 25°C)	l .					
Item	Symbol	Condition	Min.	Тур.	Max.	Unit
IN <sub>(UH、VH、WH)</sub> , IN <sub>(UL、VL、WL)</sub> ON threshold voltage	V <sub>th(on)</sub>		1.4	1.7	2.0	V
IN <sub>(UH、VH、WH)</sub> ,IN <sub>(UL、VL、WL)</sub> OFF threshold voltage	V <sub>th(off)</sub>		2.2	2.5	2.8	V
IN <sub>(UH、VH、WH)</sub> input bias current	IIN(UH、VH、WH)(HI)	V <sub>IN(UH、VH、WH)</sub> = 5V	-	-	220	μA
	I <sub>IN(UH、VH、WH)</sub> (LO)	$V_{IN(UH, VH, WH)} = 0V$	-	-	300	μΑ
IN(UL, VL, WL) input bias current	I <sub>IN(UL、VL、WL) (HI)</sub>	$V_{IN(UL, VL, WL)} = 5V$	-	-	220	
	IN(UL、VL、WL) (LO)	$V_{IN(UL, VL, WL)} = 0V$	-	-	300	μA
Driver IC supply voltage	V <sub>CC</sub>		13.5	15.0	16.5	V
P - side floating supply voltage	$V_{B(U)S(U),\ B(V)S(V),\ B(W)S(W)}$		13.5	15.0	16.5	V
V <sub>CC</sub> terminal input current	lc		-	-	2.3	mA
Foult output voltage	V <sub>FOH</sub>	V <sub>SC</sub> =0V (Note 2)	4.9	-	-	V
Fault output voltage	V <sub>FOL</sub>	V <sub>SC</sub> =1V	-	-	200	mV
Short circuit trip level	V <sub>SC(ref)</sub>	V <sub>CC</sub> =15V, T <sub>j</sub> = 25℃	0.41	0.46	0.51	V
Fault output pulse width	t <sub>FOD</sub>	(Note 3)	100		-	us
	UVT <sub>VCC</sub>	Trip level	8.6	9.4	10.2	V
Supply circuit under voltage	UVR <sub>VCC</sub>	Reset level	9.6	10.4	11.2	V
protection	UVH	Hysteresis	-	1.0	-	V
$IN_{(\text{UL, VL, WL})}$ Input filter time	t <sub>IN,FIL</sub>	VIN = 0 & 5V (Note 4)	100	200	-	ns
VF	Bootstrap diode forward voltage	lf=3A, Tj = 25℃	0.8	-	1.1	V
R	Limiting resistance	Individual resistor		100	-	Ohm

Note 2: V<sub>FO</sub> output is open collector type, so this signal line should be pulled up to the +5V power supply with approximately 4.7KΩ

Note 3: Fault output pulse width is filter capacitor of S.C. depended.

**Note 4:** For high side PWM, IN(UH, VH, WH) pulse width must be  $\geq$  1 us.

## **Input Filter Function**

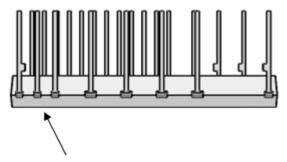


## **RECOMMENDED OPERATION CONDITIONS**

Item	Symbol	Condition	Min.	Тур.	Max.	Unit
DC – Link Supply voltage	VD	Applied between P-N	0	400	450	V
Driver IC supply voltage	V <sub>CC</sub>	Applied between V <sub>CC</sub> - COM	13.5	15.0	16.5	V
P - side floating supply voltage	V <sub>BS</sub>	Applied between $V_{B(u \cdot \ v \cdot \ w)} - V_{S(u \cdot \ v \cdot \ w)}$	13.5	15.0	16.5	V
Input ON threshold voltage	V <sub>sc(ON)</sub>	Applied between IN(UH, VH, WH) - COM	0 ~ 0.65			
Input OFF threshold voltage	V <sub>sc(OFF)</sub>	and $IN_{(UL, VL, WL)}$ - COM	4.0 ~ 5.5			
Supply voltage ripple	$\Delta V_{D}$ , $\Delta V_{DB}$		-1	-	1	V/µs
Arm shoot-through blocking time	t <sub>dead</sub>		2	-	-	μs
PWM input frequency	f <sub>PWM</sub>	$T_C \leq 100^{\circ}C$ , $T_j \leq 125^{\circ}C$	-	15	-	kHz

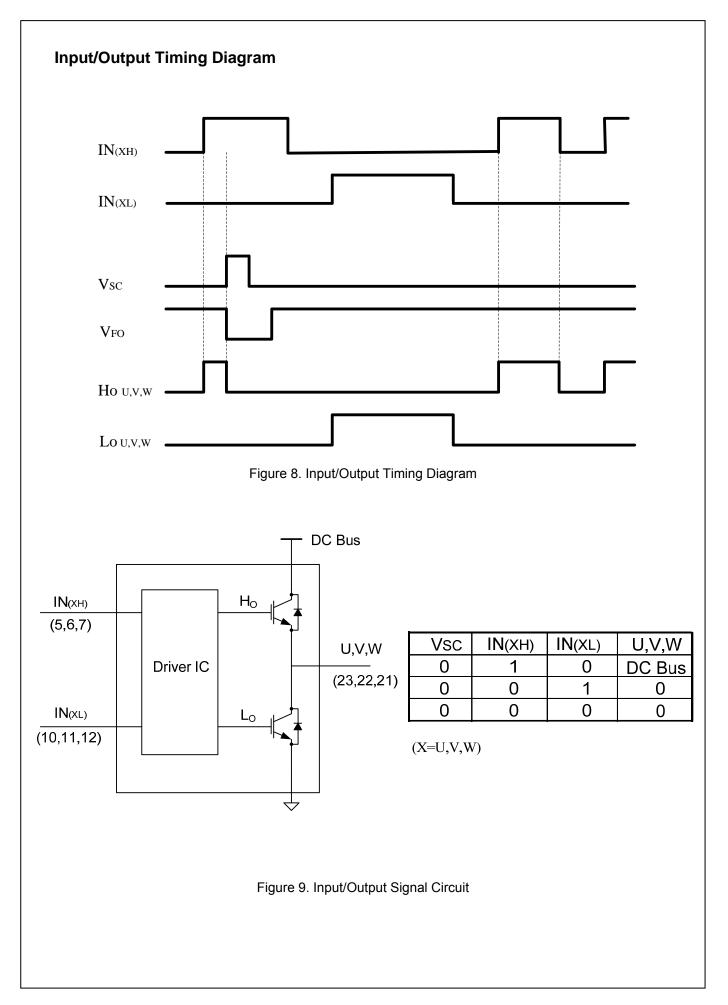
## **MECHANICAL CHARACTERISTICS AND RATINGS**

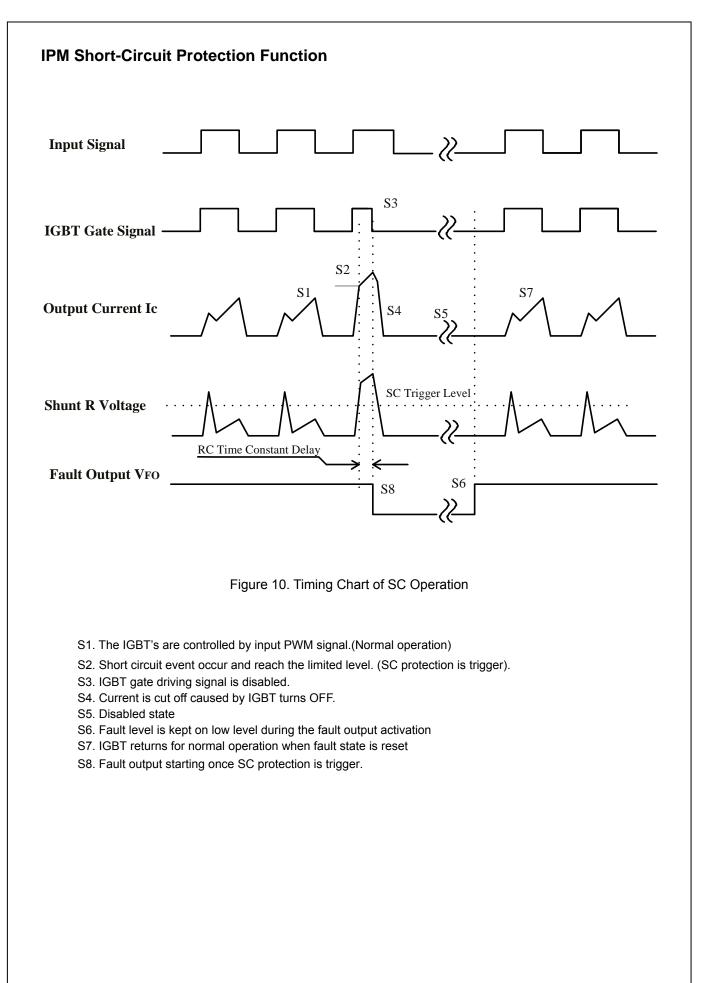
Item	Condition			Тур.	Max.	Unit
Mounting torque	Mounting screw: M3	Recommended 0.65N•m	0.60	0.65	0.70	N•m
Weight			-	11	-	g
Heat-sink flatness			-50	-	100	μm

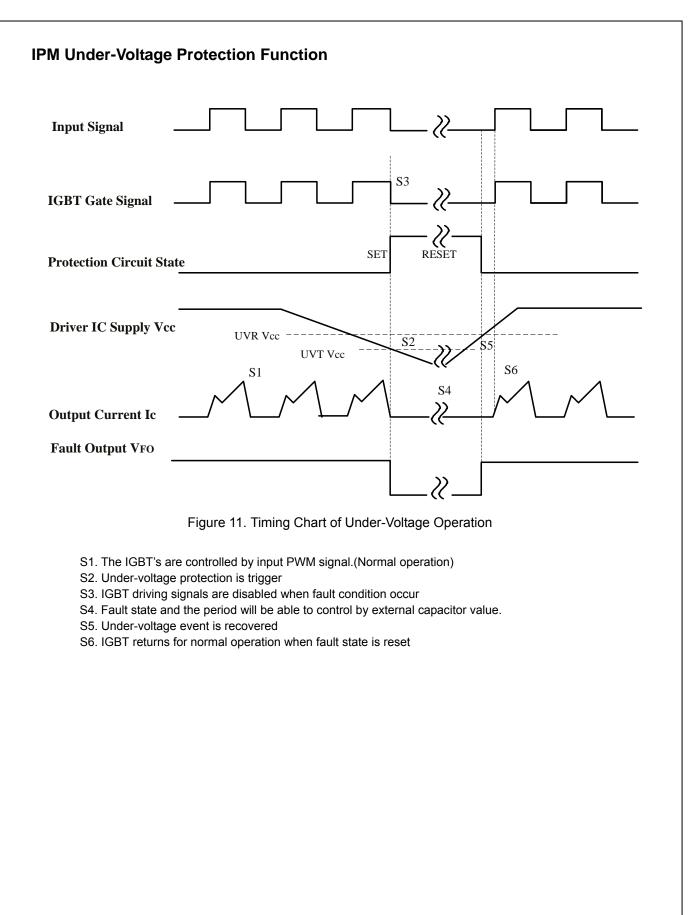


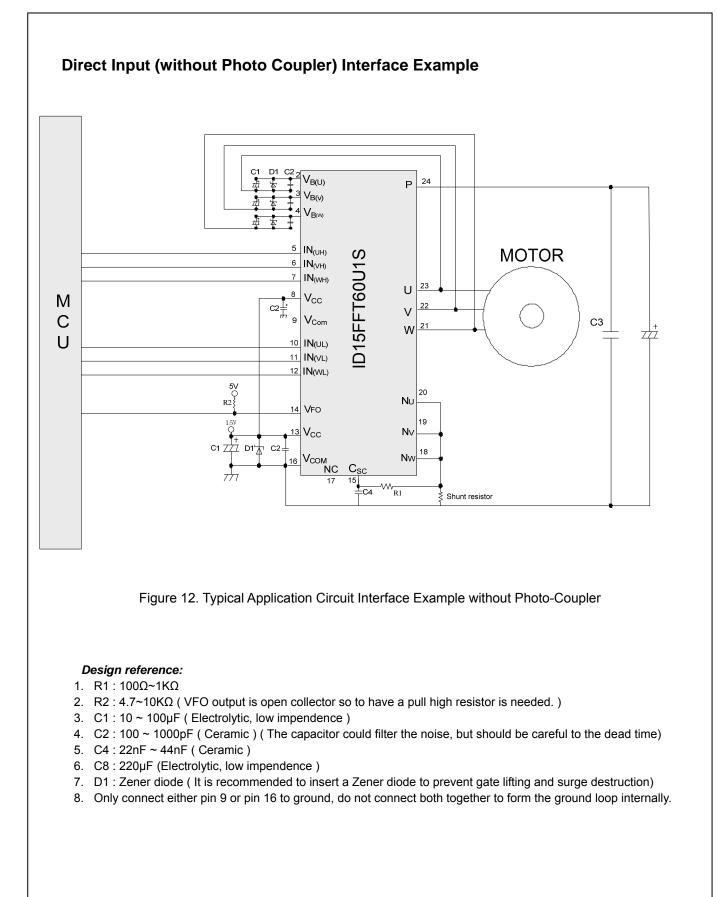
Contact to a heat sink?

Figure 7. Measurement Location of Heat-sink Flatness

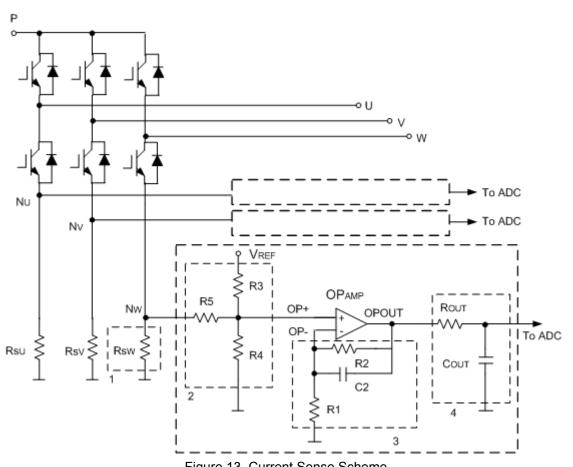








#### **Current Sense Shceme**



#### Figure 13. Current Sense Scheme

#### **Description** :

- 1、Half-bridge current sensing
- $2 \ensuremath{\,{\scriptscriptstyle \nabla}}$  Voltage shifting of the  $V_{\text{sense}}$
- 3、Voltage gain and filtering
- 4、Capacitor required by the ADC for sampling purpose

R<sub>OUT</sub> resistor is usually required in order to make the OP<sub>AMP</sub> stable when the C<sub>OUT</sub> capacitance increases

#### Design Reference :

1. R1 : 1.0 KΩ 2. R2 : 5.6 KΩ 3. R3 : 4.7 KΩ 4. R4: 910 Ω 5. R5 : 910 Ω 6.ROUT : 1.0 KΩ 7. C2 :10pF ( Ceramic )

## **Precautions on Electrostatic Electricity**

- (1) Operators must wear anti-static clothing and conductive shoes (or a leg or heel strap).
- (2) Operators must wear a wrist strap grounded to earth via a resistor of about 1 M $\Omega$ .
- (3) Soldering irons must be grounded from iron tip to earth, and must be used only at low voltages.
- (4) If the tweezers you use are likely to touch the device terminals, use anti-static tweezers and in particular avoid metallic tweezers. If a charged device touches a low-resistance tool, rapid discharge can occur. When using vacuum tweezers, attach a conductive chucking pat to the tip, and connect it to a dedicated ground used especially for anti-static purposes (suggested resistance value: 10<sup>4</sup> to 10<sup>8</sup>Ω).
- (5) Do not place devices or their containers near sources of strong electrical fields (such as above a CRT).
- (6) When storing printed circuit boards which have devices mounted on them, use a board container or bag that's protected against static charge. To avoid the occurrence of static charge or discharge due to friction, keep the boards separate from one other and do not stack them directly on top of one another.
- (7) Ensure, if possible, that any articles (such as clipboards) which are brought to any location where the level of static electricity must be closely controlled are constructed of anti-static materials.
- (8) In cases where the human body comes into direct contact with a device, be sure to wear anti-static finger covers or gloves (suggested resistance value:  $10^8\Omega$  or less).
- (9) Equipment safety covers installed near devices should have resistance ratings of  $10^{9}\Omega$  or less.
- (10) If a wrist strap cannot be used for some reason, and there is a possibility of imparting friction to devices, use an ionizer.

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