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# SC8001 High Efficiency, Synchronous Buck Controller

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## 1 Description

The SC8001 is a synchronous buck controller. It supports very wide input and output voltage range. It can support applications from 2.7V to 36V input range and 2V to 36V output range. The output voltage can be dynamic adjusted through PWM signal. The driver voltage is set to 10V to fully utilize external MOSFETs for highest efficiency.

The SC8001 supports input current limit, output current limit and over temperature protections to ensure safety under different abnormal conditions. The switching frequency and current limits can be programmed through resistors freely.

The SC8001 adopts 32 pin QFN 4x4 package.

## 3 Applications

- Wall Charger
- Car Charger
- USB PD
- Industrial applications

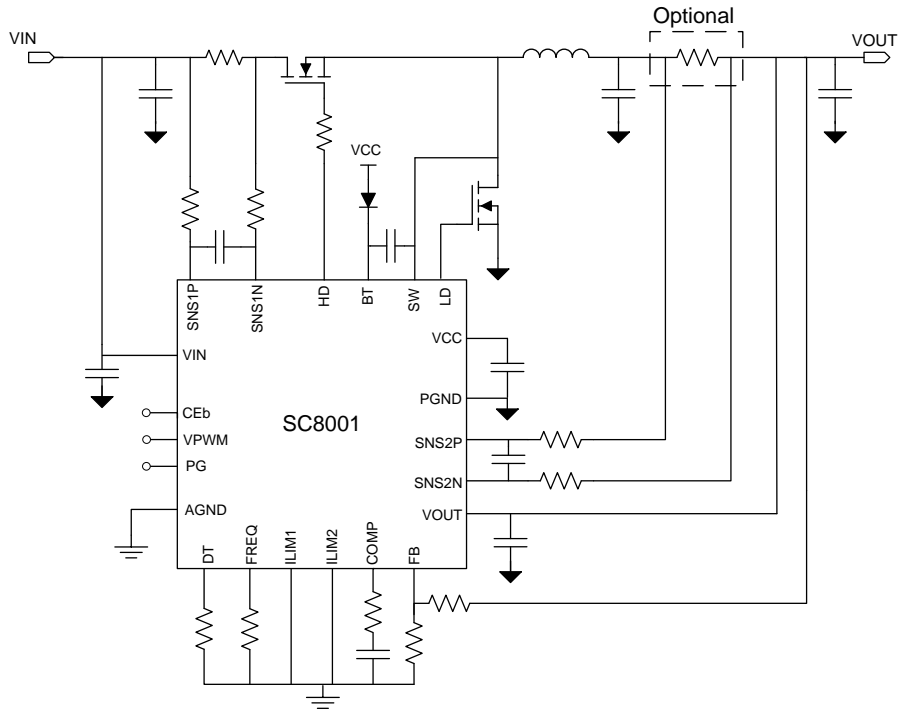
## 2 Features

- High efficient buck operation
- Dynamic adjustable output voltage
- Input / Output current limit
- Wide input voltage range: 2.7 V to 36 V
- Wide output range: 2V to 36V
- Integrated 10V, 2A gate driver
- Adjustable frequency 200kHz to 600kHz
- QFN-32 Package

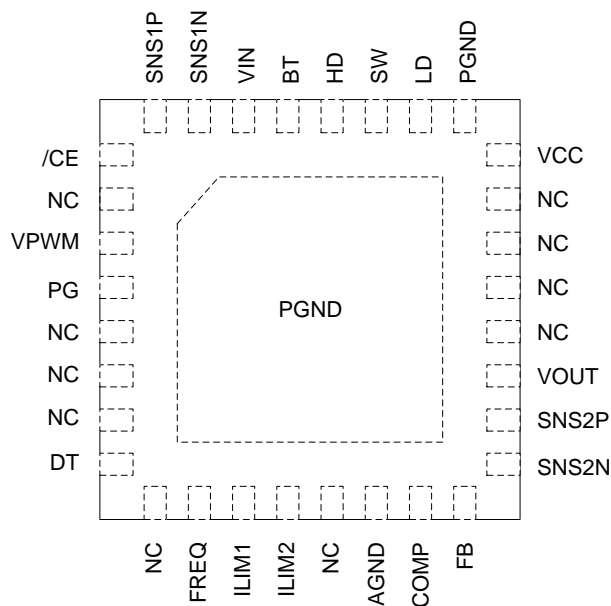
## 4 Device Information

ORDER NUMBER	PACKAGE	BODY SIZE
SC8001QDER	32 pin QFN	4mm x 4mm x 0.75mm

5 Typical Application Circuit



## 6 Terminal Configuration and Functions



TERMINAL		I/O	DESCRIPTION
NUMBER	NAME		
1	/CE	I	Chip Logic Enable, CE=Low, chip enable. Internal pull low
2	NC		Floating
3	VPWM	I	VPWM pin accepts square waveform from 20K to 100K. By adjusting duty cycle, output voltage can be adjusted according to needs. When duty=0, output voltage = 1/6 of the preset value by the feedback resistor divider at FB pin. When duty = 100%, output voltage = preset value. $V_{OUT} = V_{OUT\_SET} \times \left( \frac{1}{6} + \frac{5}{6} \times D \right)$
4	PG	O	Open drain, active high when VOUT is within 90% to 110% * VOUT target.
5	NC		Floating
6	NC		Floating
7	NC		Floating
8	DT	I	Dead Time selection. Short to ground: 20ns;68kΩ: 40ns;270kΩ: 60ns;Open: 80ns
9	NC	I	Floating
10	FREQ	I	Frequency selection Short to ground: 200kHz;68kΩ: 400kHz;Open: 600kHz

11	ILIM1	I	<p>Connect a resistor to set the current limit value of input current.</p> $I_{LIM1\_SET} = \frac{V_{REF}}{R_{ILIM1}} \times \frac{R_{SS1}}{R_{SNS1}}$ <p><math>V_{REF}</math> is the internal reference voltage 1.21V;  <math>R_{ILIM1}</math> is the resistor from ILIM1 to ground;  <math>R_{SNS1}</math> is the current sense resistor. Recommended 5mΩ-20mΩ, typical 10mΩ;  <math>R_{SS1}</math> are the resistors connected to SNS1P, SNS1N. The two resistors must be equal and the recommended value is 1kΩ.  A 2.2nF capacitor to ground is needed to bypass noise.</p>
12	ILIM2	I	<p>Connect a resistor to set the current limit value of output current.</p> $I_{LIM2\_SET} = \frac{V_{REF}}{R_{ILIM2}} \times \frac{R_{SS2}}{R_{SNS2}}$ <p><math>V_{REF}</math> is the internal reference voltage 1.21V;  <math>R_{ILIM2}</math> is the resistor from ILIM2 to ground;  <math>R_{SNS2}</math> is current sensing resistor. Recommended 5mΩ-20mΩ, typical 10mΩ;  <math>R_{SS2}</math> are the resistors connected to SNS2P, SNS2N. The two resistors must be equal and the recommended value is 1kΩ.  A 2.2nF capacitor to ground is needed to bypass noise.</p>
13	NC	I	Floating
14	AGND	IO	Analog Ground
15	COMP	O	Compensation for the control loop.
16	FB	I	<p>Feedback for output voltage.</p> $V_{OUT} = V_{REF} \times \left(1 + \frac{R_{UP}}{R_{DOWN}}\right)$ <p><math>V_{REF}</math> equals to 1.22V. <math>R_{UP}</math> and <math>R_{DOWN}</math> are the value of voltage divider.</p>
17	SNS2N	I	Negative input of current sense amplifier. Connect an external current sense resistor between SNS2P and SNS2N. Current flows from SNS2P to SNS2N.
18	SNS2P	I	Positive input of current sense amplifier. Connect an external current sense resistor between SNS2P and SNS2N. Current flows from SNS2P to SNS2N.
19	VOUT	I	Output node of the converter.
20	NC		Floating
21	NC		Floating
22	NC		Floating
23	NC		Floating
24	VCC	PWR	Output of internal regulator to provide 10V voltage for the bias voltage of internal gate drivers. Connect a 1 μF ceramic capacitor from VCC to PGND pin.

25	PGND	PWR	Power Ground
26	LD	PWR	Low side MOSFET gate driver output
27	SW	PWR	Switching Node
28	HD	PWR	High side MOSFET gate driver output
29	BT	PWR	Connect a capacitor between BT pin and SW pin to bootstrap a voltage to provide the bias voltage for high side MOSFET gate driver.
30	VIN	I	Input node of the converter
31	SNS1N	I	Negative input of current sense amplifier. Connect an external current sense resistor between SNS1P and SNS1N. Current flows from SNS1P to SNS1N.
32	SNS1P	I	Positive input of current sense amplifier. Connect an external current sense resistor between SNS1P and SNS1N. Current flows from SNS1P to SNS1N.
	Thermal Pad		For thermal dissipation. Connect to AGND or PGND.

## 7 Specifications

### 7.1 Absolute Maximum Ratings

Over operating free-air temperature range (unless otherwise noted) <sup>(1)</sup>

		MIN	MAX	UNIT
Voltage range at terminals <sup>(2)</sup>	VIN, VOUT, SNS1P, SNS1N, SNS2P, SNS2N, /CE	-0.3	40	V
	SW	-1	41	V
	VCC, PG, VPWM	-0.3	20	V
	FREQ, ILIM1, ILIM2, COMP, DT, FB	-0.3	5.5	V
	LD	-0.3	12	V
	BT, HD 对 SW	-0.3	12	V
	BT	-0.3	49	V
	VIN, VOUT, SNS1P, SNS1N, SNS2P, SNS2N, /CE	-0.3	40	V
Temperature Range	Operating Junction, T <sub>J</sub>	-40	150	°C
	Storage temperature range, T <sub>stg</sub>	-65	150	°C

(1) Stresses beyond those listed under *absolute maximum ratings* may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under *recommended operating conditions* is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) All voltage values are with respect to network ground terminal.

### 7.2 Thermal Information

THERMAL RESISTANCE <sup>(1)</sup>		QFN-32 (4mm x 4mm)	UNIT
Θ <sub>JA</sub>	Junction to ambient thermal resistance	35	°C/W
Θ <sub>JC</sub>	Junction to case resistance	7	°C/W

(1) Measured on JESD51-7, 4-layer PCB.

### 7.3 Handling Ratings

PARAMETER	DEFINITION	MIN	MAX	UNIT
ESD <sup>(1)</sup>	Human body model (HBM) ESD stress voltage <sup>(2)</sup>	-2	2	kV
	Charged device model (CDM) ESD stress voltage <sup>(3)</sup>	-750	750	V

(1) Electrostatic discharge (ESD) to measure device sensitivity and immunity to damage caused by assembly line electrostatic discharges into the device.

(2) Level listed above is the passing level per ANSI, ESDA, and JEDEC JS-001. JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(3) Level listed above is the passing level per EIA-JEDEC JESD22-C101. JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 7.4 Recommended Operating Conditions

		MIN	TYP	MAX	UNIT
V <sub>IN</sub>	Input voltage range	2.7		36	V
V <sub>OUT</sub>	Output voltage range	2		36	V
C <sub>IN</sub>	Input Capacitance	20			μF
C <sub>OUT</sub>	Output capacitance	20			μF

L	Inductance	2.2		10	$\mu\text{H}$
$R_{\text{SNS1/2}}$	Current Sensing Resistor	5		20	$\text{m}\Omega$
$f_{\text{SW}}$	Operating frequency range	200		600	$\text{kHz}$
$f_{\text{VPWM}}$	VPWM signal frequency range	20		100	$\text{kHz}$
$D_{\text{VPWM}}$	VPWM signal duty cycle range	0		100	%
$T_{\text{J}}$	Operating junction temperature	-40		125	$^{\circ}\text{C}$

## 7.5 Electrical Characteristic

$T_J = 25^\circ\text{C}$  and  $V_{IN} = 12\text{V}$ ,  $V_{OUT} = 5\text{V}$ ,  $R_{SS1} = R_{SS2} = 1\text{k}\Omega$  unless otherwise noted.

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>SUPPLY VOLTAGE (VIN, VOUT)</b>						
V <sub>IN</sub>	Operating voltage		2.7		36	V
V <sub>OUT</sub>	Operating voltage		2		30	V
V <sub>UVLO</sub>	VIN under-voltage lockout threshold	DIR = Low, rising edge		2.6	2.7	V
		DIR = Low, hysteresis		160		mV
I <sub>Q</sub>	Standby current into VIN	/CE = low, controller non-switching		0.7	2	mA
I <sub>SD</sub>	Shutdown current into VIN	/CE = high		6	10	μA
<b>VCC AND DRIVER</b>						
V <sub>CC</sub>	VCC clamp voltage		9.4	10	10.6	V
I <sub>VCC_LIM</sub>	VCC current limit	V <sub>CC</sub> = 2V ~10V	50	75	100	mA
R <sub>DRV_pu</sub>	High/Low side driver pull up resistor			1.5		Ω
R <sub>DRV_pd</sub>	High/Low side driver pull down resistor			1		Ω
<b>ERROR AMPLIFIER</b>						
V <sub>FB_REF</sub>	FB reference voltage		1.214	1.22	1.226	V
V <sub>ILIMx_REF</sub>	ILIMx reference voltage		1.196	1.212	1.228	V
G <sub>mEA</sub>	Error amplifier gm			0.16		mS
R <sub>OUT</sub>	Error amplifier output resistance <sup>(1)</sup>			20		MΩ
I <sub>BIAS(FBx)</sub>	FB pin input bias current	FB in regulation			100	nA
<b>CURRENT LIMIT</b>						
I <sub>LIM1</sub>	ILIM1 current limit accuracy	I <sub>IN_LIM</sub> R <sub>SNS1</sub> ≥ 30 mV	-5%		5%	
I <sub>LIM2</sub>	ILIM2 current limit accuracy	I <sub>OUT_LIM</sub> R <sub>SNS2</sub> ≥ 30 mV	-10%		10%	
<b>SWITCHING FREQUENCY</b>						
f <sub>SW</sub>	Switching frequency	R <sub>FREQ</sub> = 0Ω	180	210	240	kHz
		R <sub>FREQ</sub> = 68kΩ (±10%)	360	410	460	kHz
		R <sub>FREQ</sub> = 270kΩ (±10%)	540	600	660	kHz
<b>INDICATION</b>						
t <sub>PG_deglitch</sub>	PG signal deglitch time	f <sub>sw</sub> = 200kHz	27	38.5	50	ms
I <sub>SINK_PG</sub>	PG sink current	V <sub>PG</sub> = 0.4 V	3.6	4.1	4.6	mA
<b>LOGIC CONTROL</b>						
R <sub>PD</sub>	/CE internal pull down resistor			1		MΩ
	PWM pin internal pull down resistor			0.5		MΩ
V <sub>IL</sub>	/CE, PWM input low voltage				0.4	V
V <sub>IH</sub>	/CE, PWM input high voltage		1.2			V
<b>Soft Start</b>						
t <sub>SS</sub>	Internal soft-start time			8	15	ms
<b>THERMAL SHUTDOWN</b>						
T <sub>SD</sub>	Thermal shutdown temperature <sup>(1)</sup>			165		°C
	Thermal shutdown hysteresis <sup>(1)</sup>			15		°C

(1) Guarantee by design



## 8 Detailed Description

The SC8001 is a synchronous buck controller with a wide input/output voltage range. The SC8001 features maximum input and output current limit capability using additional resistors. In addition, the SC8001 features output voltage dynamic change, input/output current limit dynamic change, and power MOSFETs dead time control.

### 8.1 Feature Description

#### 8.1.1 Chip Enable (/CE)

The SC8001 turns on/off by /CE signal. When /CE input is "L", the SC8001 is turned on; when /CE input is "H", the SC8001 is turned off.

#### 8.1.2 VOUT voltage setting (FB)

The VOUT voltage is set by external resistor divider at FB pin and is calculated as:

$$V_{OUT} = V_{FB\_REF} \times \left(1 + \frac{R_{UP}}{R_{DOWN}}\right)$$

Where:

$V_{FB\_REF}$  = Internal reference voltage 1.22V

$R_{UP}$  and  $R_{DOWN}$  = Resistor divider at FB connected to VOUT and AGND.

#### 8.1.3 Output voltage POWER GOOD indicator (PG)

The PG signal indicates VOUT voltage status.

If VOUT voltage remains in between 90% ~ 110% of programmed voltage, PG pin becomes high impedance and due to the output pull-up resistor, PG out becomes "H" to indicate the output voltage is good.

If VOUT is out of normal voltage range, PG out becomes "L".

If power good indication is not required, leave PG pin floating.

#### 8.1.4 Real-time output voltage control (PWM)

The SC8001 supports VOUT voltage change by PWM signal at PWM pin.

The PWM pin accepts a PWM signal in the range of 20kHz to 100kHz, and its duty cycle can adjust the VOUT voltage. VOUT output voltage is calculated as:

$$V_{OUT} = V_{OUT\_SET} \times \left(\frac{1}{6} + \frac{5}{6} \times D\right)$$

Where;

$V_{OUT\_SET}$  = VOUT voltage which is set by FB resistor divider;

D = Duty cycle of PWM signal.

The relationship between VOUT voltage and D is showed in

Figure 1

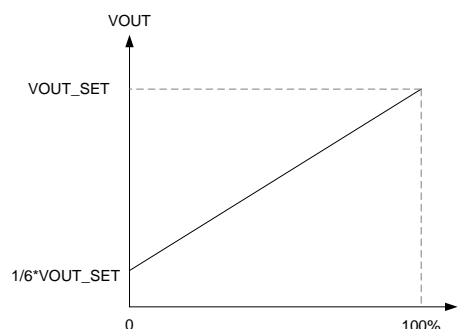


Figure 1 VOUT voltage vs PWM duty cycle.

If PWM input signal is logic high, it means 100% of duty cycle, then the output voltage become the set value by FB1 resistor divider.

If PWM input signal is logic low, it means 0% of duty cycle, then the output voltage become the 1/6 of the set value.

If PWM pin is left floating, due to the IC internal pull down circuit at PWM pin, VOUT voltage becomes the 1/6 of programmed voltage.

If real-time output voltage control is not required, connect PWM pin to VCC pin.

#### 8.1.5 Input/output current setting (ILIMx)

The SC8001 can adjust the current limit of both input side and output side by resistors at ILIM1 and ILIM2 pins.

Control Pins	Description
ILM1	Set the input current limit ( $I_{IN\_LIM}$ )
ILM2	Set the output current limit ( $I_{OUT\_LIM}$ )

The SC8001 senses the input and output current by monitoring  $R_{SNS1}$  and  $R_{SNS2}$  respectively as below figure shows.

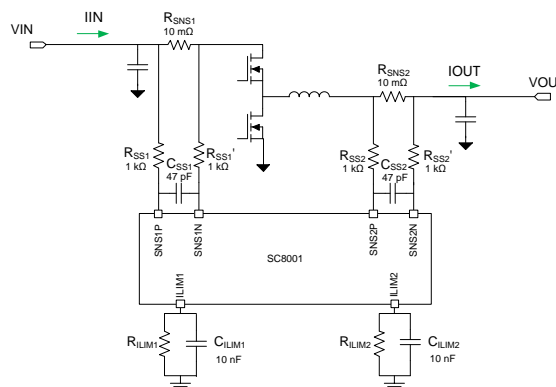


Figure 3 Input/output current monitoring circuit

R<sub>SNSx</sub> is the current sense resistor (x means 1 or 2) at input /output. The SC8001 monitors the voltage across the sense resistors R<sub>SNSx</sub> through R<sub>SSx</sub> and R<sub>SSx'</sub> and calculates the input and output current. C<sub>SSx</sub> is the filter capacitor and typically 47pF is sufficient.

The ILIMx pin is used to set the current limit. Connect the R<sub>ILIMx</sub> resistor between ILIM<sub>x</sub> pin and GND (or ITUNE pin if IPWM function is used).

The current limit is calculated as:

$$I_{IN\_LIM} = \frac{V_{LIM\_REF}}{R_{ILIM1}} \times \frac{R_{SS1}}{R_{SNS1}}$$

$$I_{OUT\_LIM} = \frac{V_{LIM\_REF}}{R_{ILIM2}} \times \frac{R_{SS2}}{R_{SNS2}}$$

Where:

V<sub>LIM\_REF</sub> = Internal reference voltage 1.21V;

R<sub>ILIMx</sub> = Resistors at ILIMx pin;

R<sub>SNSx</sub> = Current sense resistors;

R<sub>SSx</sub> = Resistors between current sense resistor and the SC8001 pins (SNSxP, SNSxN).

R<sub>SNS1</sub> should be placed between MOSFET and input capacitor. R<sub>SNS2</sub> can be placed either between the MOSFET and output capacitor or behind the output capacitor.

R<sub>SS1</sub> and R<sub>SS1'</sub> should have the same value; R<sub>SS2</sub> and R<sub>SS2'</sub> also the same. Typically 1kΩ resistor is used.

If R<sub>SNSx</sub> is changed, R<sub>SSx</sub>/R<sub>SSx'</sub> values need to be adjusted accordingly with below calculation:

$$\frac{R_{SNSx}}{R_{SSx}} = \frac{10\text{ m}\Omega}{1\text{ k}\Omega}$$

For example, If R<sub>SNSx</sub> is 20mΩ, then R<sub>SSx</sub>/R<sub>SSx'</sub> should be 2kΩ; if R<sub>SNSx</sub> is 5mΩ, then R<sub>SSx</sub>/R<sub>SSx'</sub> should be 500Ω.

If both VIN and VOUT current limits are programmed, the SC8001 controls the current which reaches its current limit first.

If the input/output current limit is not required, connect ILIM1/ILIM2 pin to GND.

**8.1.6 Dead time setting (DT)**

The one of four dead times is selectable by resistor value at DT pin:

DT resistor	Dead time
0Ω	20ns
68kΩ (±10%)	40ns
270kΩ (±10%)	60ns
Open	80ns

The accuracy of the resistor at DT is allowed ±10%. DT does not support the real-time change and new resistor

value change will be applied in next turn on.

When driving large power MOSFET with high C<sub>ISS</sub> value, or adding driver resistors at LDx or HDx to adjust the MOSFET turning on/off time, it is suggested to check and change the dead time to prevent MOSFET shoot-through.

**8.1.7 Switching frequency setting (FREQ)**

The one of three switching frequency is selectable by resistor value at FREQ pin:

FREQ resistor	Switching frequency f <sub>sw</sub>
0Ω	200kHz
68kΩ (±10%)	400kHz
Open	600kHz

The accuracy of the resistor at FREQ is allowed ±10%. The real-time switching frequency change is not valid and new resistor value change will be applied in next turn on.

**8.1.8 Feedback compensation (COMP)**

The feedback loop can be compensated by adjusting the external components to the COMP pin. Typically, the values in Figure 4 are used. If faster loop response is required, user can increase the resistor to like 10kΩ or 20kΩ. After changing the compensation, check and make sure the loop is stable under the application operation conditions.

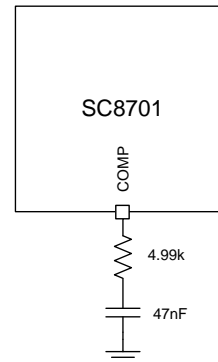


Figure 4 Feedback loop compensation setting

**8.1.9 VCC driver voltage**

The SC8001 generates driver voltage VCC internally. The VCC is selected higher voltage between VIN and VOUT, and clamped to 10V if it is higher than 10V.

The driving signal LDx to drive low side MOSFET (Q2 and Q3) is directly supplied from VCC; the driving signal HDx to drive high side MOSFET (Q1 and Q4) is supplied from the diode in between VCC to BTx pin, which is generated by bootstrap circuit with bootstrap capacitor between BTx and SWx.

**8.1.10 Protections****8.1.10.1 Input UVLO**

When the IC detects VIN voltage drops below the  $V_{UVLO}$  threshold, it stops switching to avoid malfunction.

**8.1.10.2 FB Short Circuit**

When the IC detects the FB pin voltage drops below  $1/10 \cdot V_{FB\_REF}$ , the IC reduces the ILIM2 target voltage from

$V_{ILIM2\_REF}$  to  $1/10 \cdot V_{ILIM2\_REF}$ , limiting the output current.

**8.1.10.3 VOUT Short Circuit**

When the IC detects the VOUT pin voltage drops below 1~1.5V, the IC reduces the ILIM1 target voltage from  $V_{ILIM1\_REF}$  to  $1/10 \cdot V_{ILIM1\_REF}$ , limiting the input current.

## 9 Application Information

### 9.1 Input and output capacitor selection

The switching frequency of the SC8001 is in the range of 200kHz ~ 600kHz. Since MLCC ceramic capacitor has good high frequency filtering with low ESR, above 60μF X5R or X7R capacitors with higher voltage rating than operating voltage with margin is recommended. For example, if the highest operating  $V_{in}$  or  $V_{out}$  voltage is 12V, select at least 16V capacitor and to secure enough margin, 25V voltage rating capacitor is recommended.

The high capacitance electrolytic capacitor and tantalum capacitor can be used for stable input and output but capacitor voltage rating should be higher than the highest operating voltage. When the tantalum capacitor is used, at least 1μF ceramic capacitor is placed in parallel. If the electrolytic capacitor is used, much more ceramic capacitors are required. For example, if a 47μF electrolytic capacitor is used, the ceramic capacitors' capacitance is allowed to reduce to 30μF ~ 40μF. Even higher capacitance electrolytic capacitor is used, at least 20μF ceramic capacitor is required.

### 9.2 Inductor selection

For the SC8001 system stability, the inductance of 2.2μH ~ 10 μH inductor is required. High inductance (4.7μH ~ 10μH) is used in the system where the input voltage and output voltage difference is big, such as 20V  $V_{in}$  and 5V  $V_{out}$  or the switching frequency is low; Low inductance (2.2μH) is used in the system which the input voltage and output voltage difference is small but high current is required.

Typically, 3.3μH inductor is recommended. The inductance can be adjusted for high efficiency and optimization in application.

The inductor DC resistance value (DCR) affects the conduction loss of switching regulator, so around 10mΩ DCR is recommended for the first selection. If the power is relatively small, high DCR inductor can be selected. But if switch current is high, just like around 10A, then select the lowest DCR inductor as much as possible because 10mΩ DCR also causes 1W power loss.

The inductor saturation current  $I_{SAT}$  should be higher than input / output current with sufficient margin.

### 9.3 Current sense resistor

The RSNS1 and RSNS2 are current sense resistors and 5mΩ ~ 20mΩ resistor value is recommended.

Higher resistor value leads to higher current limit accuracy

but using higher resistor value in high current application causes higher conduction loss.

Typically, 10mΩ is recommended. Resistor value can be adjusted depending on current limit and target power efficiency. If  $R_{SNSx}$  value is adjusted, related  $R_{SSx}$  value should be adjusted simultaneously.

Please refer to [8.1.5 Input/output current setting \(ILIMx\)](#) for proper  $R_{SNSx}$  and  $R_{SSx}$  values. The resistor power rating and temperature coefficient should also be considered. The power dissipation is roughly calculated as  $P=I^2R$ , and  $I$  is the highest current flowing through the resistor. The resistor power rating should be higher than roughly calculated power dissipation. The resistor value can be varied if the temperature increased and the variation is decided by temperature coefficient along with temperature change. If high accuracy of current limit is required, select lower temperature coefficient resistor as much as possible.

### 9.4 MOSFET selection

The SC8001 is a synchronous buck controller and it requires 2 NMOS for power switching circuit.

The  $V_{DS}$  of MOSFET should be higher than the highest operating voltage with enough margin (recommend more than 10V higher). For example, if the highest operating voltage is 20V, at least 30V rated  $V_{DS}$  MOSFET should be selected; If the highest operating voltage is 24V, 40V  $V_{DS}$  voltage rating should be selected.

In the application, if the input and output voltage are higher than 10V, driver circuit voltage can reach 10V, and  $V_{GS}$  voltage rating of MOSFET should be selected higher than ±10V.

Considering PCB parasitic parameters during operation, driver voltage can be higher than VCC due to transient overshoot, and ±20V  $V_{GS}$  is recommended to secure sufficient margin.

The MOSFET current  $I_D$  should be higher than the highest input and output current with enough margin.

To ensure the sufficient current capability in relatively high temperature circumstance, the current rate at  $T_A=70^\circ\text{C}$  or  $T_C = 100^\circ\text{C}$  should be considered. In addition, the power dissipation value  $P_D$  should also be considered and higher  $P_D$  is better in applications. Make sure that MOSFET power consumption must not exceed  $P_D$  value.

The MOSFET  $R_{DS(ON)}$  and input capacitor  $C_{ISS}$  impact power efficiency directly. Typically, lower  $R_{DS(ON)}$  MOSFET has higher  $C_{ISS}$ . The  $R_{DS(ON)}$  is related to conduction loss. Higher  $R_{DS(ON)}$  results in higher conduction loss, thus lower efficiency and higher thermal dissipation; the  $C_{ISS}$  is related to MOSFET switch on/off time, and longer on/off time results in higher switching loss and lower efficiency. The proper MOSFET should be selected based on tradeoff between the  $R_{DS(ON)}$  and  $C_{ISS}$ .

Normally, if the output power is around 20W ~ 30W, the

MOSFET with around  $10\text{m}\Omega$  of  $R_{\text{DS(ON)}}$  and lower than  $1000\text{pF}$  of  $C_{\text{ISS}}$  is recommended. If the output power is increased, the MOSFET with lower  $R_{\text{DS(ON)}}$  and under  $2000\text{pF}$   $C_{\text{ISS}}$  is recommended. The highest  $C_{\text{ISS}}$  is suggested not to exceed  $3000\text{pF}$ .

If high  $C_{\text{ISS}}$  MOSFET is selected, the switching on and off time become longer, then the dead time should be adjusted with DT pin to avoid simultaneous turn on for both high side and low side MOSFETs.

### 9.5 Driver resistor and SWx snubber circuit

For a convenient adjustment of MOSFET switching time and transient overshoot at EMI debugging, recommend to add 0603 series resistor between driver pins (LD, HD) and MOSFET Gate pins, and add RC snubber (0603) circuit at SW (refer to Figure 5 Driver resistor and SW snubber circuit)

The driver resistor should be placed near to MOSFET Gate pin. At first, add  $0\Omega$  and adjust the resistor value appropriately within  $10\Omega$ . After increasing the driver resistor value, the on time of high side and low side MOSFET should be monitored. If the dead time is insufficient, adjust dead

time accordingly.

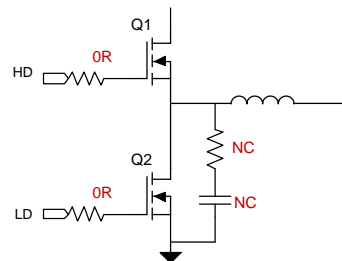


Figure 5 Driver resistor and SWx snubber circuit

The RC snubber circuit is required when the overshoot at SWx needs to be suppressed. Leave RC snubber circuit as NC at the first time

Packaging Information

QFN32L(0404x0.75-0.40)

