

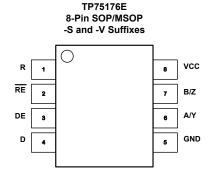
#### **Features**

- High Data Rates: 10Mbps At 5V Supply : 6Mbps At 3.3V Supply
- 13/14ns (Max) Tx/Rx Propagation Delays; 10ns (Typ) Skew
- Full Fail-safe (Open, Short, Terminated)
  Receivers
- Up to 32 Nodes on a Bus (1 unit load)
- Wide Supply Voltage 3V to 5.5V
- Low Quiescent Supply Current: 2.2 mA
- -8V to +13V Common Mode Input Voltage Range
- Bus-Pin Protection:
  - ±15 kV HBM protection
  - ±9 kV IEC61000-4-2 Contact Discharge
  - +4 kV IEC61000-4-4 Fast Transient Burst
- Pb-Free Plus Anneal Available (RoHS Compliant)

## **Applications**

- PROFIBUS<sup>®</sup> DP and FMS Networks
- SCSI "Fast 40" Drivers and Receivers
- Motor Controller/Position Encoder Systems
- Factory Automation
- Field Bus Networks
- Industrial/Process Control Networks

### Pin Configuration (Top View)



## **Description**

3PEAK's TP75176E is a ±15kV HBM ESD Protected, 3V~5.5V powered, single transceiver that meets both the RS-485 and RS-422 standards for balanced communication. It also features the larger output voltage and higher data rate - up to 10Mbps - required by high speed PROFIBUS applications, and is offered in Industrial and Extended Industrial (-40°C to +125°C) temperature ranges.

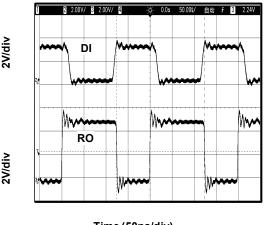
This transceiver requires a  $3V\sim5.5V$  tolerance supply, and delivers at least a 2.1V differential output voltage on 5V supply condition. This translates into better noise immunity(data integrity), longer reach, or the ability to drive up to three  $120\Omega$  terminations in "star" or other non-standard bus topologies, at the exceptional 10Mbps data rate.

Receiver (Rx) inputs feature a "Full Fail-Safe" design, which ensures a logic high Rx output if Rx inputs are floating, shorted, or terminated but undriven. Rx outputs feature high drive levels (typically >25mA @  $V_{OL}$  = 1V) to ease the design of optically isolated interfaces.

The TP75176E is available in an SOP-8 and MSOP-8 package, and is characterized from -40°C to 125°C.

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#### Loopback Test At 10Mbps/5V



Time (50ns/div)

## **Order Information**

Model Name	Order Number	Package	Transport Media, Quantity	Marking Information
TP75176E	TP75176E-SR	8-Pin SOP	Tape and Reel, 4,000	75176E
TP75176E	TP75176E-VR	8-Pin MSOP	Tape and Reel, 3,000	75176E
TP75176E	TP75176E-FR	8-Pin DFN	Tape and Reel, 4,000	75176

### **DRIVER PIN FUNCTIONS**

INPUT	ENABLE	ОПТІ	PUTS	DESCRIPTION	
D	DE	Α	В	DESCRIPTION	
NORMAL MODE					
Н	Н	Н	L	Actively drives bus High	
L	Н	L	Н	Actively drives bus Low	
Х	L	Z	Z	Driver disabled	
Х	OPEN	Z	Z	Driver disabled by default	
OPEN	Н	Н	L	Actively drives bus High	

### **RECEIVER PIN FUNCTIONS**

DIFFERENTIAL INPUT	ENABLE	OUTPUT	DESCRIPTION			
$V_{ID} = V_A - V_B$	/RE	R	DESCRIPTION			
			NORMAL MODE			
$V_{IT+} < V_{ID}$	L	Н	Receive valid bus High			
$V_{IT-} < V_{ID} < V_{IT+}$	L	?	Indeterminate bus state			
V <sub>ID</sub> < V <sub>IT</sub>	L	L	Receive valid bus Low			
X	Н	Z	Receiver disabled			
X	OPEN	Z	Receiver disabled			
Open, short, idle Bus	L	Н	Indeterminate bus state			

## **Absolute Maximum Ratings**

V <sub>DD</sub> to GND	0.3V to +7V
Input Voltages	
DI, DE, RE	0.3V to (VCC + 0.3V)
Input/Output Voltages	
A/Y, B/Z, A, B, Y, Z	15V to +15V
A/Y, B/Z, A, B, Y, Z (Transient Pulse Through $100\Omega$ ,	
Note 1)	±100V
R <sub>0</sub>	0.3V to (VCC +0.3V)
Short Circuit Duration	
Y, Z	Continuous
ESD Rating	See Specification Table
Recommended Operating Conditions Note 2	
Supply Voltage	3V~5.5V
Temperature Range	
Temperature Hange	40°C to +125°C
Bus Pin Common Mode Voltage Range	
Bus Pin Common Mode Voltage Range	8V to +13V
Bus Pin Common Mode Voltage Range	8V to +13V 158°C/W
Bus Pin Common Mode Voltage Range  Thermal Resistance, O <sub>JA</sub> (Typical)  8-Pin SOP Package	8V to +13V 158°C/W 210°C/W

Note 1: Tested according to TIA/EIA-485-A, Section 4.2.6 (±100V for 15µs at a 1% duty cycle).

**Note 2:** Do not operate at or near the maximum ratings listed for extended periods of time. Exposure to such conditions may adversely impact product reliability and result in failures not covered by warranty.

### **Electrical Characteristics**

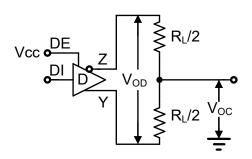
Test Conditions: V<sub>CC</sub> = 5V, Over operating free-air temperature range(unless otherwise noted)

PARAMETER		CONDITIO	ONS	MIN	TYP	MAX	UNITS	
N/ I	Driver differential-output voltage	$R_L = 54 \Omega V_{CC} = 5V$ $R_L = 54 \Omega \text{ with } V_A \text{ or } V_B \text{ from } -7 \text{ to } +12 \text{ V},$	See Figure 1A	2.3	2.5			
V <sub>OD</sub>	magnitude	$\begin{aligned} &V_{\text{CC}} = 5V \text{ (RS-485)} \\ &R_{\text{L}} = 54 \ \Omega \text{ with V}_{\text{A}} \text{ or} \\ &V_{\text{B}} \text{ from -7 to +12 V}, \\ &V_{\text{CC}} = 3V \text{ (RS-485)} \end{aligned}$		1.2	1.5		V	
V <sub>IH</sub>	Logic Input High Voltage	DI, DE, RE		1			V	
V <sub>IL</sub>	Logic Input Low Voltage	DI, DE, RE				0.5	V	
⊿ V <sub>od</sub>	Change in magnitude of driver differential-output voltage	$R_L = 54 \Omega, C_L=50 pF,$ $V_{CC} = 5V$	See Figure 1A	-0.02	-0.002	0.02	V	
V <sub>OC(SS)</sub>	Steady-stage common-mode output voltage			Vcc/2- 0.2	V <sub>CC</sub> /2	Vcc/2 +0.2	V	
△Voc	Change in differential driver common-mode output voltage	Center of two 27 $\Omega$ load resistors	See Figure 1A	-0.2	0	0.2	mV	
V <sub>OC(PP)</sub>	Peak-to-peak driver common-mode output voltage				500			
C <sub>OD</sub>	Differential output capacitance				8		pF	
V <sub>IT+</sub>	Positive-going receiver differential-input voltage threshold				-50	-10	mV	
V <sub>IT-</sub>	Negative-going receiver differential-input voltage threshold			-200	-130		mV	
V <sub>HYS</sub> <sup>(1)</sup>	Receiver differential-input voltage threshold hysteresis ( $V_{\Pi^+} - V_{\Pi^-}$ )				75		mV	
V <sub>OH</sub>	Receiver high-level output voltage	I <sub>OH</sub> = -8 mA		4.500	4.650		V	
V <sub>OL</sub>	Receiver low-level output voltage	I <sub>OL</sub> = 8 mA			0.235	0.350	V	
I <sub>1</sub>	Driver input, driver enable and receiver enable input current	DI, DE, RE			0.01	0.020	μА	
I <sub>OZ</sub>	Receiver high-impedance output current	$V_0 = 0 \text{ V or } V_{CC}$ , /RE at	V <sub>cc</sub>	-0.02	0.005	0.02	μА	
los	Driver short-circuit output current	IOS   with V <sub>A</sub> or V <sub>B</sub> from	m –7 to +12 V		120	300	mA	
I	Bus input current(driver disabled)	V <sub>CC</sub> = 4.5 to 5.5 V or	VI= 12 V			1	mA	
"	Bus input durient(driver disabled)	V <sub>CC</sub> = 0 V, DE at 0 V	VI= -7 V	-0.8			1117 (	
		Driver and receiver enabled	DE = V <sub>CC</sub> , /RE = GND, No LOAD		2.2	2.5		
		Driver enabled, receiver disabled	$DE = V_{CC}, /RE$ $= V_{CC}, No$ $LOAD$		1.5	1.8		
Icc	Supply current(quiescent)	Driver disabled, receiver enabled	DE = GND, /RE = GND, No LOAD		0.5	0.6	mA	
		Driver and receiver disabled	DE = GND, /RE = V <sub>CC</sub> , D= V <sub>cc</sub> No LOAD		0.0012	0.002		

## **Switching CHARACTERISTICS**

	PARAMETER	CONDITI	ONS	MIN	TYP	MAX	UNITS
DRIVER		-					
f <sub>MAX</sub>	Maximum Data Rate	$V_{OD} \ge \pm 1.5V$ , $R_L = 5$ . (Figure 4)	4Ω, C <sub>L</sub> = 100pF	10			Mbps
t <sub>r</sub> , t <sub>f</sub>	Driver differential-output rise and fall times	- R <sub>L</sub> = 54 Ω, C <sub>L</sub> =50pF			26		
t <sub>PHL</sub> , t <sub>PLH</sub>	Driver propagation delay	- INL - 34 12, OL-30pi	See Figure 2		14		ns
tsk(P)	Driver pulse skew,  tphl - tplh				10		
tpHz, tpLz	Driver disable time				50		ns
tpHz, tpLz	Driver enable time	Receiver enabled	See Figure 3		10		ns
trnz, trtz	Driver enable time	Receiver disabled			125		113
RECEIVER	1		T	I	T	1	1
tr, tf	Receiver output rise and fall times	_			3.4		
трнг, тргн	Receiver propagation delay time	C <sub>L</sub> =15 pF	See Figure 5		55		ns
tsk(P)	Receiver pulse skew,  tphl – tplh				10		
tphz, tplz	Receiver disable time				28		ns
tPZL(1), tPZH(1)	Receiver enable time	Driver enabled	See Figure 6		11		ns ns
tPZL(2), tPZH(2)	Treesiver chapte time	Driver disabled	See Figure 6		15		
ESD	1	•	<u> </u>				ı
RS-485		IEC61000-4-2,Air-Gap	o Discharge		±15		kV
Pins (A, Y, B, Z, A/Y,		IEC61000-4-2, Contact Discharge Method			±9		kV
B/Z)		Human Body Model, From Bus Pins to GND			±15		kV
All Other Pins		Human Body Model, բ	per MIL-STD-883		±2		kV

### **Test Circuits and Waveforms**



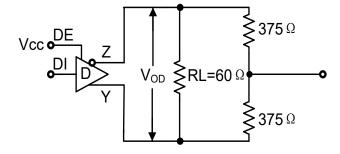
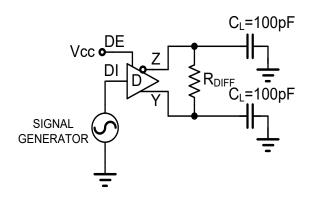
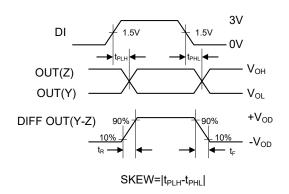


FIGURE 1A. VOD AND VOC

FIGURE 1B. VOD WITH COMMON MODE LOAD

FIGURE 1. DC DRIVER TEST CIRCUITS

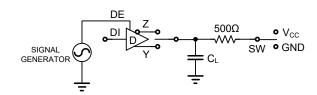




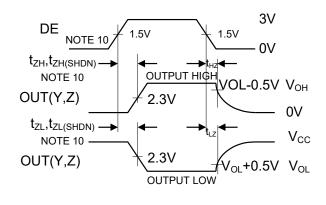
**FIGURE 2A. TEST CIRCUIT** 

FIGURE 2B. MEASUREMENT POINTS

FIGURE 2. DRIVER PROPAGATION DELAY AND DIFFERENTIAL TRANSITION TIMES



PARAMETER	OUTPUT	RE	DI	sw	CL
PARAMETER	001701	KE	ום	3 <b>W</b>	(pF)
tHZ	Y/Z	X	1/0	GND	15
tLZ	Y/Z	Х	0/1	VCC	15
tZH	Y/Z	0 (Note 9)	1/0	GND	100
tZL	Y/Z	0 (Note 9)	0/1	VCC	100
tZH(SHDN)	Y/Z	1 (Note 12)	1/0	GND	100
tZL(SHDN)	Y/Z	1 (Note 12)	0/1	VCC	100

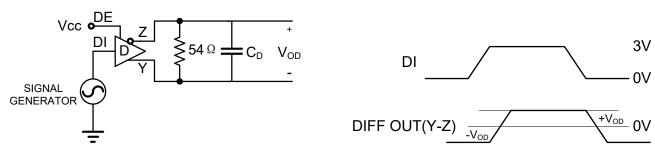


**FIGURE 3A. TEST CIRCUIT** 

FIGURE 3B. MEASUREMENT POINTS

FIGURE 3. DRIVER ENABLE AND DISABLE TIMES

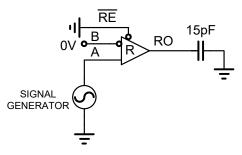
## Test Circuits and Waveforms(continue)



**FIGURE 4A. TEST CIRCUIT** 

FIGURE 4B. MEASUREMENT POINTS

**FIGURE 4. DRIVER DATA RATE** 





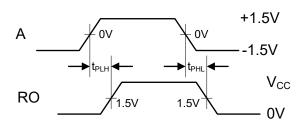
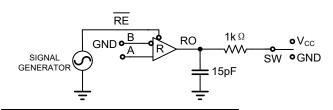


FIGURE 5B. MEASUREMENT POINTS

FIGURE 5. RECEIVER PROPAGATION DELAY AND DATA RATE



PARAMETER	DE	Α	sw
tHZ	0	+1.5V	GND
tLZ	0	-1.5V	VCC
tZH(Note 10)	0	+1.5V	GND
tZL(Note 10)	0	-1.5V	VCC
tZH(SHDN)(Note 13)	0	+1.5V	GND
tZL(SHDN)(Note 13)	0	-1.5V	VCC

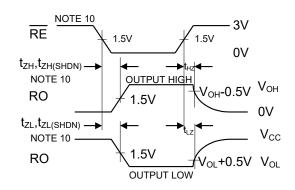


FIGURE 6A. TEST CIRCUIT

FIGURE 6B. MEASUREMENT POINTS

FIGURE 6. RECEIVER ENABLE AND DISABLE TIMES

### **Detailed Description**

#### **Application**

RS-485 and RS-422 are differential (balanced) data transmission standards used for long haul or noisy environments. RS-422 is a subset of RS-485, so RS-485 transceivers are also RS-422 compliant. RS-422 is a point-to-multipoint (multidrop) standard, which allows only one driver and up to 10 (assuming one unit load devices) receivers on each bus. RS-485 is a true multipoint standard, which allows up to 32 one unit load devices (any combination of drivers and receivers) on each bus. To allow for multipoint operation, the RS-485 specification requires that drivers must handle bus contention without sustaining any damage. Another important advantage of RS-485 is the extended common mode range (CMR), which specifies that the driver outputs and receiver inputs withstand signals that range from +12V to -7V. RS-422 and RS-485 are intended for runs as long as 4000', so the wide CMR is necessary to handle ground potential differences, as well as voltages induced in the cable by external fields.

#### Receiver (Rx) Features

TP75176E utilize a differential input receiver for maximum noise immunity and common mode rejection. Input sensitivity is better than ±200mV, as required by the RS-422 and RS-485 specifications. Rx outputs feature high drive levels (typically 25mA @ VOL = 1V) to ease the design of optically coupled isolated interfaces. Rx inputs function with common mode voltages as great as ±7V outside the power supplies (i.e., +12V and -7V), making them ideal for long networks where induced voltages are a realistic concern. All the receivers include a "full fail-safe" function that guarantees a high level receiver output if the receiver inputs are unconnected (floating), shorted together, or connected to a terminated bus with all the transmitters disabled. Receivers easily meet the data rates supported by the corresponding driver, and all receiver outputs are three-stable via the active low RE input.

#### **Driver (Tx) Features**

TP75176E driver is a differential output device that delivers at least 2.5V across a  $54\Omega$  load (RS-485), and at least 2.8V across a  $100\Omega$  load (RS-422). The drivers feature low propagation delay skew to maximize bit width, and to minimize EMI, and all drivers are three-stable via the active high DE input.

#### **High Data Rate**

RS-485/RS-422 are intended for network lengths up to 4000', but the maximum system data rate decreases as the transmission length increases. Devices operating at 10Mbps are limited to lengths less than 100'.

Twisted pair is the cable of choice for RS-485/RS-422 networks. Twisted pair cables tend to pick up noise and other electromagnetically induced voltages as common mode signals, which are effectively rejected by the differential receiver in this IC. Proper termination is imperative to minimize reflections. In point-to-point, or point-to-multipoint (single driver on bus) networks, the main cable should be terminated in its characteristic impedance (typically  $120\Omega$ ) at the end farthest from the driver. In multi-receiver applications, stubs connecting receivers to the main cable should be kept as short as possible. Multipoint (multi-driver) systems require that the main cable be terminated in its characteristic impedance at both ends. Stubs connecting a transceiver to the main cable should be kept as short as possible.

The TP75176E may also be used at slower data rates over longer cables, but there are some limitations. The Rx is optimized for high speed operation, so its output may glitch if the Rx input differential transition times are too slow. Keeping the transition times below 500ns, which equates to the Tx driving a 1000' (305m) CAT 5 cable, yields excellent performance over the full operating temperature range. For below test waveform, the transmitter was driven at 10Mps and/or with 100' (31m) CAT 5 cable, the transmitters were loaded with an RS-485 receiver in parallel with  $54\Omega$ .

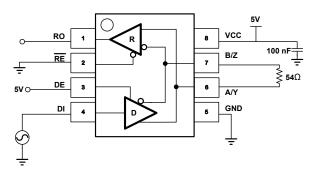


Figure 7. Loopback Test Circuit

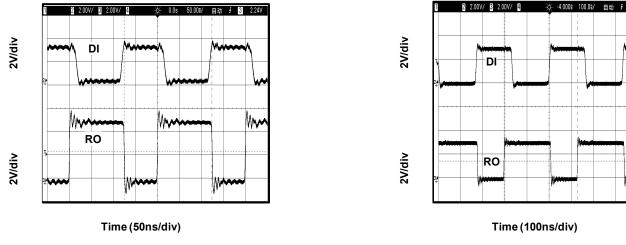


Figure 8. Loopback Test At 10Mbps/5V



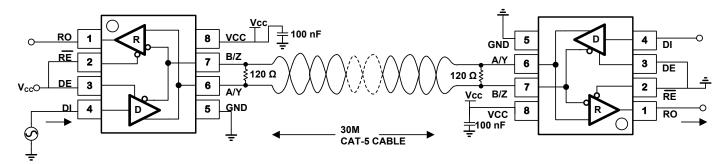


Figure 10. 10Mbps Data Rate With 30M CAT5 Cable Test Circuit

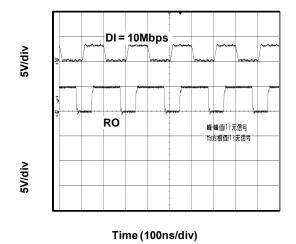
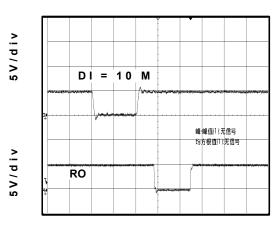


Figure 11. 5V Driver And Receiver Five Pulse Waveforms Driving 100 Feet (30 Meters)



Time (100n

Figure 12. 5V Driver And Receiver Single Pulse **Waveforms Driving 100 Feet (30 Meters)** 

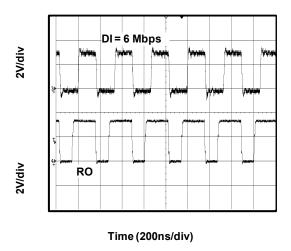


Figure 13. 3.3V Driver And Receiver Five Pulse Pulse Waveforms Driving 100 Feet (30 Meters)

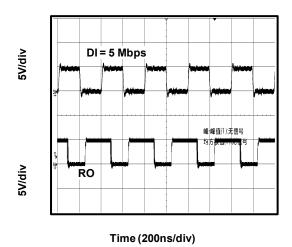


Figure 15. 5V Driver And Receiver Five Pulse Pulse Waveforms Driving 100 Feet (30 Meters)

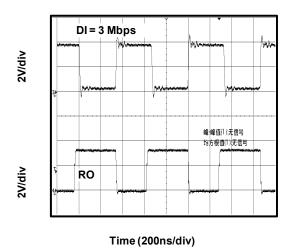
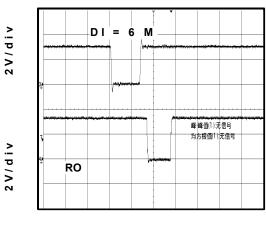
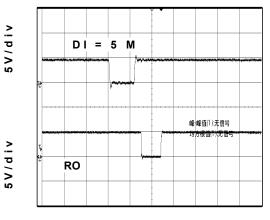


Figure 17. 3.3V Driver And Receiver Four Pulse Pulse Waveforms Driving 100 Feet (30 Meters)



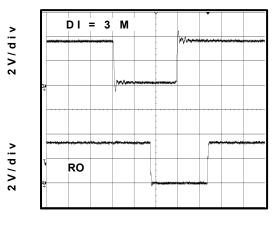
Time (200n

Figure 14. 3.3V Driver And Receiver Single Waveforms Driving 100 Feet (30 Meters)



Time (200n

Figure 16. 5V Driver And Receiver Single
Waveforms Driving 100 Feet (30 Meters)



Time (200n

Figure 18. 5V Driver And Receiver Single Waveforms Driving 100 Feet (30 Meters)

#### **Full Fail-Safe**

All the receivers include a "full fail-safe" function that guarantees a high level receiver output if the receiver inputs are unconnected (floating), shorted together, or connected to a terminated bus with all the transmitters disabled. Receivers easily meet the data rates supported by the corresponding driver, and all receiver outputs are three-stable via the active low RE input.

#### **Hot Plug Function**

When a piece of equipment powers up, there is a period of time where the processor or ASIC driving the RS-485 control lines (DE, RE) is unable to ensure that the RS-485 Tx and Rx outputs are kept disabled. If the equipment is connected to the bus, a driver activating prematurely during power-up may crash the bus. To avoid this scenario, the TP75176E devices incorporate a "Hot Plug" function. Circuitry monitoring VCC ensures that, during power-up and power-down, the Tx and Rx outputs remain disabled, regardless of the state of DE and RE, if VCC is less than ~2.5V. This gives the processor/ASIC a chance to stabilize and drive the RS-485 control lines to the proper states.

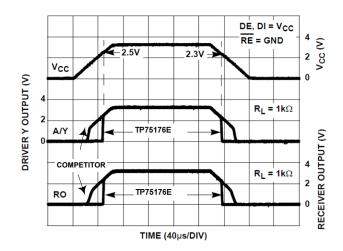


FIGURE 19. Hot Plug Performance (TP75176E) vs Competitor Without Hot Plug Circuitry

#### **ESD Protection**

All pins on these devices include 2kV Human Body Model (HBM) ESD protection structures, but the RS-485 pins (driver outputs and receiver inputs) incorporate advanced structures allowing them to survive ESD events in excess of ±15kV HBM and ±9kV (1/2 duplex) IEC61000-4-2. The RS-485 pins are particularly vulnerable to ESD strikes because they typically connect to an exposed port on the exterior of the finished product. Simply touching the port pins, or connecting a cable, can cause an ESD event that might destroy unprotected ICs. These new ESD structures protect the device whether or not it is powered up, and without degrading the RS-485 common mode range of -8V to +13V. This built-in ESD protection eliminates the need for board level protection structures (e.g., transient suppression diodes), and the associated, undesirable capacitive load they present.

#### **Transient Protection**

The bus terminals of the TP75176E transceiver family possess on-chip ESD protection against ±15 kV HBM and ±9 kV IEC61000-4-2 contact discharge. The International Electrotechnical Commision (IEC) ESD test is far more severe than the HBM ESD test. The 50% higher charge capacitance, CS, and 78% lower discharge resistance, RD of the IEC model produce significantly higher discharge currents than the HBM model.

As stated in the IEC 61000-4-2 standard, contact discharge is the preferred transient protection test method. Although IEC air-gap testing is less repeatable than contact testing, air discharge protection levels are inferred from the contact discharge test results.

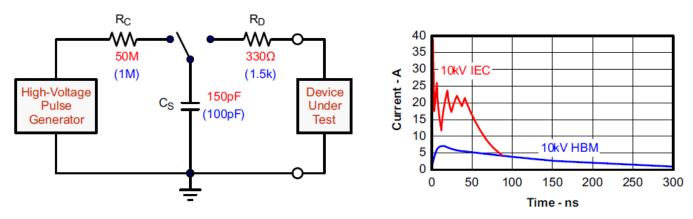


Figure 20. HBM and IEC-ESD Models and Currents in Comparison (HBM Values in Parenthesis)

The on-chip implementation of IEC ESD protection significantly increases the robustness of equipment. Common discharge events occur because of human contact with connectors and cables. Designers may choose to implement protection against longer duration transients, typically referred to as surge transients. Figure 9 suggests two circuit designs providing protection against short and long duration surge transients, in addition to ESD and Electrical Fast Transients (EFT) transients. Table 1 lists the bill of materials for the external protection devices.

EFTs are generally caused by relay-contact bounce or the interruption of inductive loads. Surge transients often result from lightning strikes (direct strike or an indirect strike which induce voltages and currents), or the switching of power systems, including load changes and short circuits switching. These transients are often encountered in industrial environments, such as factory automation and power-grid systems. Figure 10 compares the pulse-power of the EFT and surge transients with the power caused by an IEC ESD transient. In the diagram on the left of Figure 10, the tiny blue blip in the bottom left corner represents the power of a 10-kV ESD transient, which already dwarfs against the significantly higher EFT power spike, and certainly dwarfs against the 500-V surge transient. This type of transient power is well representative of factory environments in industrial and process automation. The diagram on the fright of Figure 10 compares the enormous power of a 6-kV surge transient, most likely occurring in e-metering applications of power generating and power grid systems, with the aforementioned 500-V surge transient.

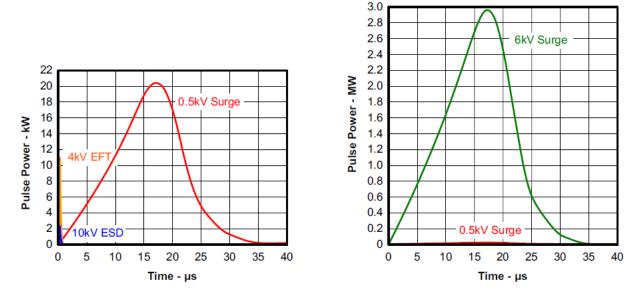


Figure 21. Power Comparison of ESD, EFT, and Surge Transients

In the case of surge transients, high-energy content is signified by long pulse duration and slow decaying pulse Power The electrical energy of a transient that is dumped into the internal protection cells of the transceiver is converted into thermal energy. This thermal

energy heats the protection cells and literally destroys them, thus destroying the transceiver. Figure 11 shows the large differences in transient energies for single ESD, EFT, and surge transients as well as for an EFT pulse train, commonly applied during compliance testing.

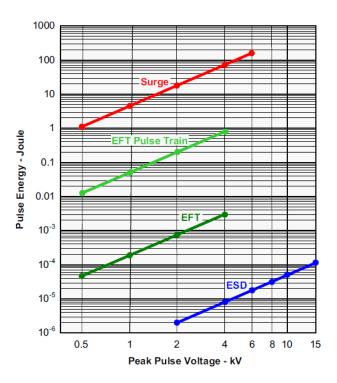


Figure 22. Comparison of Transient Energies

**Table 1. Bill of Materials** 

Device Function		Order Number	Manufacturer
485	5-V, 250-kbps RS-485 Transceiver	TP75176E	3PEAK
R1, R2	10- $\Omega$ , Pulse-Proof Thick-Film Resistor	CRCW0603010RJNEAHP	Vishay
TVS	Bidirectional 400-W Transient Suppressor	CDSOT23-SM712	Bourns
TBU1, TBU2	Bidirectional	TBU-CA-065-200-WH	Bourns
MOV1, MOV2	200mA Transient Blocking Unit 200-V, Metal-Oxide Varistor	MOV-10D201K	Bourns

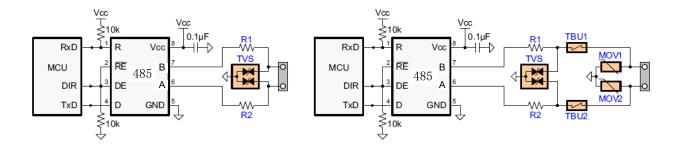


Figure 23. Transient Protections Against ESD, EFT, and Surge Transients

The left circuit shown in Figure 12 provides surge protection of  $\geq$  500-V transients, while the right protection circuits can withstand surge transients of 5 kV

## **Typical Performance Characteristics**

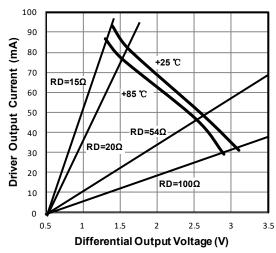
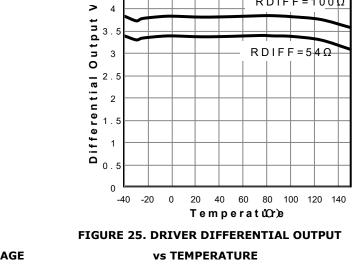


FIGURE 24. DRIVER OUTPUT CURRENT vs **VOLTAGE DIFFERENTIAL OUTPUT VOLTAGE** 



RDIFF= $100\Omega$ 

4 . 5

4

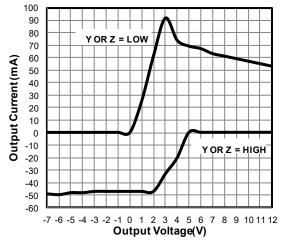
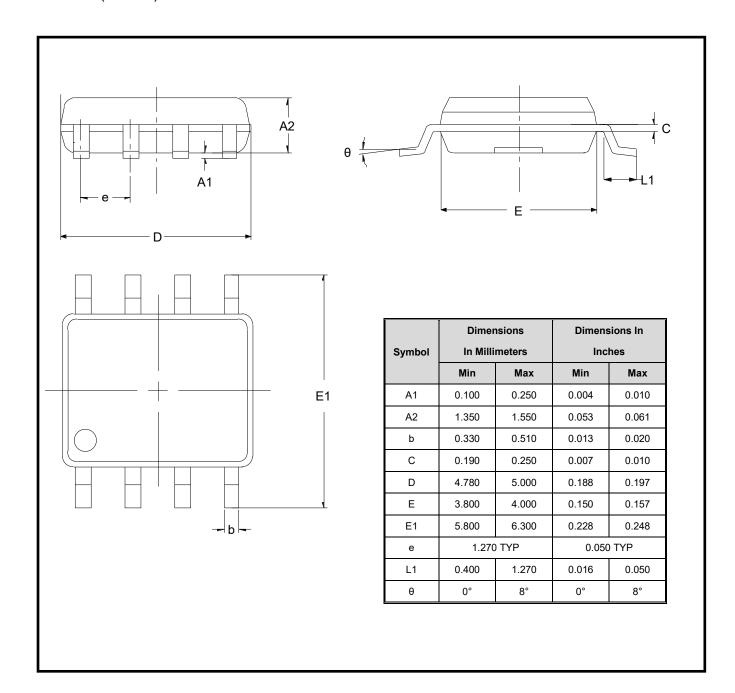


FIGURE 26. DRIVER OUTPUT CURRENT vs SHORT

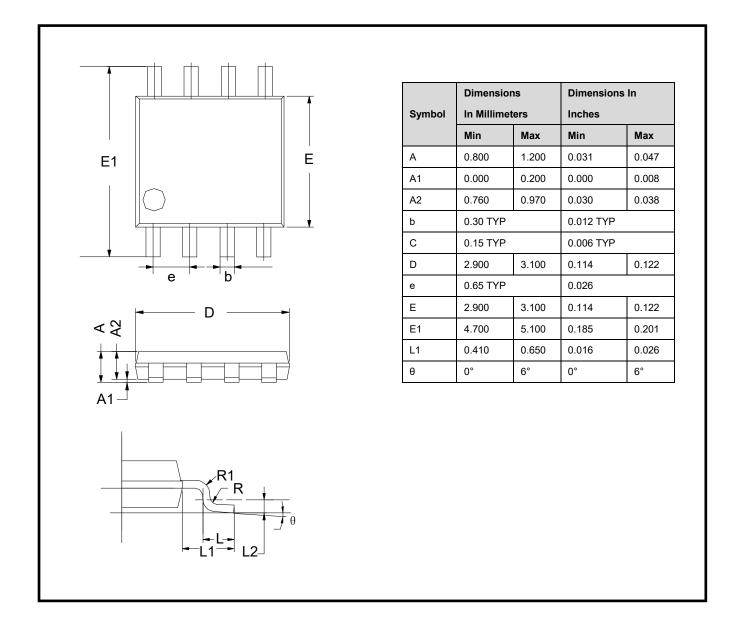
## **Package Outline Dimensions**

SOP-8 (SOIC-8)



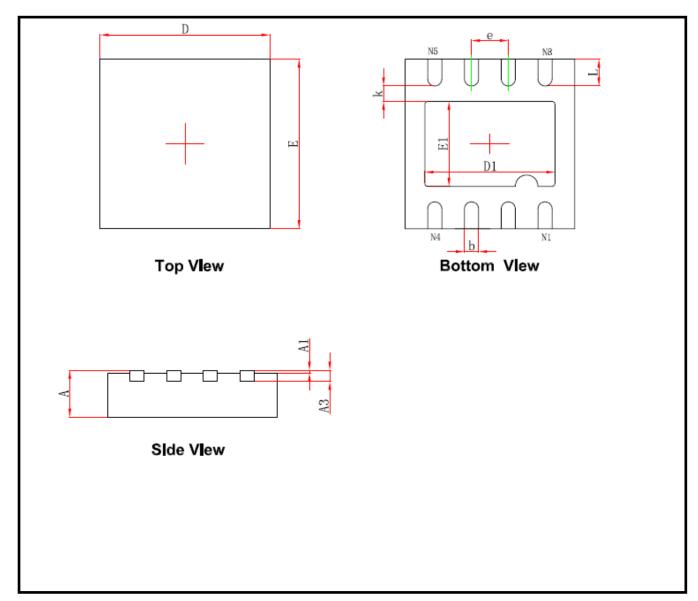
# **Package Outline Dimensions**

MSOP-8



# **Package Outline Dimensions**

## DFN-8



Cumbal	Dimensions I	n Millimeters	Dimensions In Inches		
Symbol	Min.	Max.	Min.	Max.	
Α	0.700/0.800	0.800/0.900	0.028/0.031	0.031/0.035	
A1	0.000	0.050	0.000	0.002	
A3	0.203	REF.	0.008REF.		
D	2.924	3.076	0.115	0.121	
E	2.924	3.076	0.115	0.121	
D1	2.200	2.400	0.087	0.094	
E1	1.400	1.600	0.055	0.063	
k	0.200MIN.		0.008MIN.		
b	0.200	0.300	0.008	0.012	
е	0.650	TYP.	0.026	STYP.	
L	0.399	0.551	0.016	0.022	