



# SC8201 High Efficiency, Synchronous Boost Controller

## 1 Description

The SC8201 is a synchronous boost controller. It supports very wide input and output voltage range. The driver voltage is set to 10V to fully utilize external MOSFETs for highest efficiency.

The SC8201 supports input current limit, output current limit and over temperature protections to ensure safety under different abnormal conditions.

The SC8201 adopts 32 pin QFN 4x4 package.

## 3 Applications

- Power Bank
- USB PD
- Blue Tooth Speaker
- Industrial applications

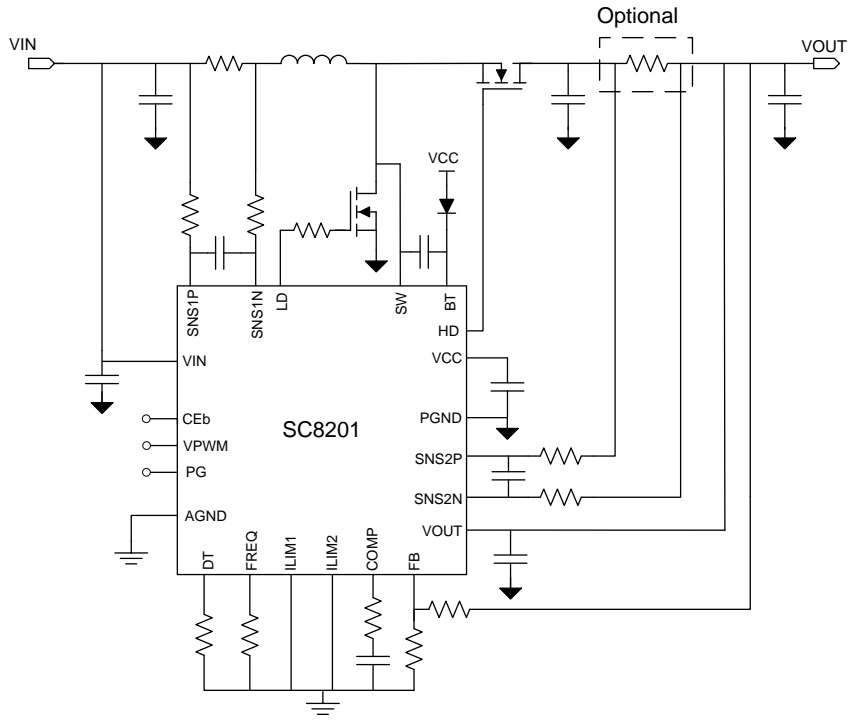
## 2 Features

- High efficient boost operation
- Dynamic adjustable output voltage
- Wide input voltage range: 2.7 V to 30 V
- Wide output voltage range: 2.7V to 36V
- Integrated 10V, 2A gate driver
- Adjustable frequency 200kHz to 600kHz
- Internal inductor current limit
- Input and output current limit
- Dynamic voltage change for output
- Under voltage protection
- QFN-32 Package

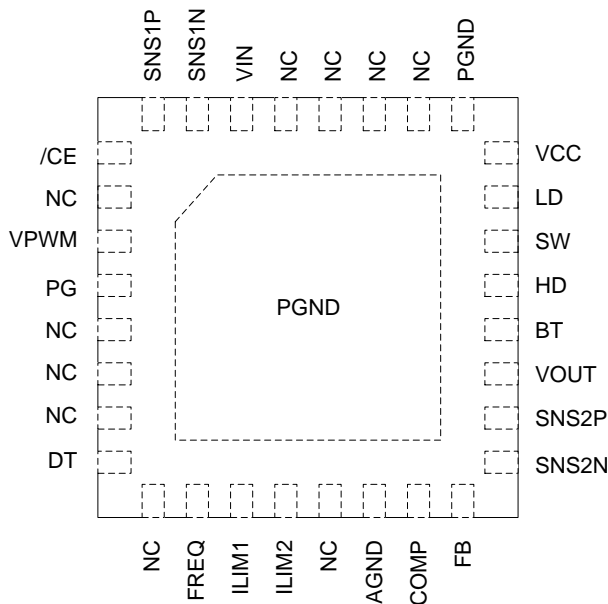
## 4 Device Information

ORDER NUMBER	PACKAGE	BODY SIZE
SC8201QDER	32 pin QFN	4mm x 4mm x 0.75mm

### 5 Typical Application Circuit



### 6 Terminal Configuration and Functions



TERMINAL		I/O	DESCRIPTION
NUMBER	NAME		
1	/CE	I	Chip Logic Enable, CE=Low, chip enable. Internal pull low
2	NC	I	Floating
3	PWM	I	PWM pin accepts square waveform from 20K to 100K. By adjusting duty cycle, output voltage can be adjusted according to needs. When duty=0, output voltage = 1/6 of the preset value by the feedback resistor divider at FB pin. When duty = 100%, output voltage = preset value. $V_{OUT} = V_{OUT\_SET} \times \left( \frac{1}{6} + \frac{5}{6} \times D \right)$
4	PG	O	Open drain, active high when VOUT is within 90% to 110% * VOUT target.
5	NC	I	Floating
6	NC	I	Floating
7	NC	I	Floating.
8	DT	I	Dead Time selection. Connect a resistor to AGND to set the dead time. Short to ground: 20ns; 68kΩ: 40ns; 270kΩ: 60ns; Open: 80ns
9	NC	I	Floating

10	FREQ	I	<p>Switching frequency selection. Connect a resistor to AGND to set the switching frequency.</p> <p>Short to ground: 200kHz; 68kΩ: 400kHz; Open: 600kHz</p>
11	ILIM1	I	<p>Connect a resistor to AGND to set the current limit value of input current.</p> $I_{IN\_LIM} = \frac{V_{REF}}{R_{ILIM1}} \times \frac{R_{SS1}}{R_{SNS1}}$ <p><math>V_{REF}</math> is the internal reference voltage 1.21V; <math>R_{LIM1}</math> is the resistor from ILIM1 to ground or to ITUNE; <math>R_{SNS1}</math> is the current sense resistor. Recommended 5mΩ-20mΩ, typical 10mΩ; <math>R_{SS1}</math> are the resistors connected to SNS1P, SNS1N. The two resistors must be equal and the recommended value are 1kΩ. A 2.2nF capacitor to ground is needed to bypass noise. If input current limit function is not needed, tie this pint to ground directly to disable the limit.</p>
12	ILIM2	I	<p>Connect a resistor to AGND to set the current limit value of output current.</p> $I_{OUT\_LIM} = \frac{V_{REF}}{R_{ILIM2}} \times \frac{R_{SS2}}{R_{SNS2}}$ <p><math>V_{REF}</math> is the internal reference voltage 1.21V; <math>R_{LIM2}</math> is the resistor from ILIM2 to ground or to ITUNE; <math>R_{SNS2}</math> is current sensing resistor. Recommended 5mΩ-20mΩ, typical 10mΩ; <math>R_{SS2}</math> are the resistors connected to SNS2P, SNS2N. The two resistors must be equal and the recommended value is 1kΩ. A 2.2nF capacitor to ground is needed to bypass noise. If input current limit function is not needed, tie this pint to ground directly to disable the limit.</p>
13	NC	I	Floating
14	AGND	IO	Analog Ground
15	COMP	O	Compensation for the control loop.
16	FB	I	<p>Feedback for output voltage.</p> $V_{OUT} = V_{REF} \times \left( 1 + \frac{R_{UP}}{R_{DOWN}} \right)$ <p><math>V_{REF}</math> equals to 1.22V. <math>R_{UP}</math> and <math>R_{DOWN}</math> are the value of voltage divider.</p>
17	SNS2N	I	Negative input of current sense amplifier. Connect an external current sense resistor between SNS2P and SNS2N. Current flows from SNS2P to SNS2N.
18	SNS2P	I	Positive input of current sense amplifier. Connect an external current sense resistor between SNS2P and SNS2N. Current flows from SNS2P to SNS2N.

19	VOUT	I	Output node of the converter.
20	BT	PWR	Connect a capacitor between BT pin and SW pin to bootstrap a voltage to provide the bias voltage for high side MOSFET gate driver.
21	HD	PWR	High side MOSFET gate driver output
22	SW	PWR	Switching Node
23	LD	PWR	Low side MOSFET gate driver output
24	VCC	PWR	Output of internal regulator to provide 10V voltage for the bias voltage of internal gate drivers. Connect a 1 $\mu$ F ceramic capacitor from VCC to PGND pin.
25	PGND	PWR	Power Ground
26	NC	I	Floating
27	NC	I	Floating
28	NC	I	Floating
29	NC	I	Floating
30	VIN	I	Input node of the converter
31	SNS1N	I	Negative input of current sense amplifier. Connect an external current sense resistor between SNS1P and SNS1N. Current flows from SNS1P to SNS1N.
32	SNS1P	I	Positive input of current sense amplifier. Connect an external current sense resistor between SNS1P and SNS1N. Current flows from SNS1P to SNS1N.
	Thermal Pad		For thermal dissipation. Connect to AGND or PGND.

## 7 Specifications

### 7.1 Absolute Maximum Ratings

Over operating free-air temperature range (unless otherwise noted) <sup>(1)</sup>

		MIN	MAX	UNIT
Voltage range at terminals <sup>(2)</sup>	VIN, VOUT, SNS1P, SNS1N, SNS2P, SNS2N, /CE	-0.3	42	V
	SW	-1	42	V
	VCC, PG, PWM	-0.3	20	V
	FREQ, ILIM1, ILIM2, COMP, DT, FB	-0.3	5.5	V
	LD	-0.3	12	V
	BT, HD to SW	-0.3	12	V
	BT	-0.3	50	V
Temperature Range	Operating Junction, T <sub>J</sub>	-40	150	°C
	Storage temperature range, T <sub>stg</sub>	-65	150	°C

(1) Stresses beyond those listed under *absolute maximum ratings* may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under *recommended operating conditions* is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) All voltage values are with respect to network ground terminal.

### 7.2 Handling Ratings

PARAMETER	DEFINITION	MIN	MAX	UNIT
ESD <sup>(1)</sup>	Human body model (HBM) ESD stress voltage <sup>(2)</sup>	-2	2	kV
	Charged device model (CDM) ESD stress voltage <sup>(3)</sup>	-750	750	V

(1) Electrostatic discharge (ESD) to measure device sensitivity and immunity to damage caused by assembly line electrostatic discharges into the device.

(2) Level listed above is the passing level per ANSI, ESDA, and JEDEC JS-001. JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(3) Level listed above is the passing level per EIA-JEDEC JESD22-C101. JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 7.3 Recommended Operating Conditions

		MIN	TYP	MAX	UNIT
V <sub>IN</sub>	Input voltage range	2.7		30	V
V <sub>OUT</sub>	Output voltage range	2.7		36	V
C <sub>IN</sub>	Input Capacitance	20			μF
C <sub>OUT</sub>	Output capacitance	20			μF
L	Inductance	2.2		10	μH
R <sub>SNS1/2</sub>	Current Sensing Resistor	5		20	mΩ
f <sub>PWM</sub>	PWM signal frequency range	20		100	kHz
D <sub>PWM</sub>	PWM signal duty cycle range	0		100	%

## 7.4 Electrical Characteristic

$T_J = 25^\circ\text{C}$  and  $V_{IN} = 12\text{V}$ ,  $V_{OUT} = 5\text{V}$ ,  $R_{SS1} = R_{SS2} = 1\text{k}\Omega$  unless otherwise noted.

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>SUPPLY VOLTAGE (VIN, VOUT)</b>						
$V_{IN}$	Operating voltage		2.7		36	V
$V_{OUT}$	Operating voltage		3		36	V
$V_{UVLO}$	Input under-voltage lockout threshold	Rising edge		2.6	2.7	V
		Hysteresis		160		mV
$I_Q$	Standby current into VOUT pin	/CE = low, controller non-switching		0.7	2	mA
$I_{SD}$	Shutdown current into VOUT pin	/CE = high		6	10	$\mu\text{A}$
	Shutdown current into VIN pin	/CE = high			2	$\mu\text{A}$
<b>VCC AND DRIVER</b>						
$V_{CC}$	VCC clamp voltage		9.4	10	10.6	V
$I_{VCC\_LIM}$	VCC current limit	$V_{CC} = 2\text{V} \sim 10\text{V}$	50	75	100	mA
$R_{HV\_pu}$	High side driver pull up resistor			1.5		$\Omega$
$R_{HV\_pd}$	High side driver pull down resistor			1		$\Omega$
$R_{LV\_pu}$	Low side driver pull up resistor			1.5		$\Omega$
$R_{LV\_pd}$	Low side driver pull down resistor			1		$\Omega$
<b>ERROR AMPLIFIER</b>						
$V_{FB\_REF}$	FB reference voltage		1.214	1.22	1.226	V
$V_{ILIMx\_REF}$	ILIMx reference voltage		1.196	1.212	1.228	V
$G_{mEA}$	Error amplifier gm			0.16		mS
$R_{OUT}$	Error amplifier output resistance <sup>(1)</sup>			20		M $\Omega$
$I_{BIAS(FBx)}$	FBx pin input bias current	FBx in regulation			100	nA
<b>CURRENT LIMIT</b>						
$I_{LIMx}$	ILIMx current limit accuracy	$I_{IN\_LIM} R_{SNS1} \geq 30\text{ mV}$ $I_{OUT\_LIM} R_{SNS2} \geq 30\text{ mV}$	-10%		10%	
<b>SWITCHING FREQUENCY</b>						
$f_{SW}$	Switching frequency	$R_{FREQ} = 0\Omega$	180	210	240	kHz
		$R_{FREQ} = 68\text{k}\Omega (\pm 10\%)$	360	410	460	kHz
		$R_{FREQ} = 270\text{k}\Omega (\pm 10\%)$	540	600	660	kHz
<b>INDICATION</b>						
$t_{PG\_degitch}$	PG signal deglitch time	$f_{sw} = 200\text{kHz}$	27	38.5	50	ms
$I_{SINK\_PG}$	PG sink current	$V_{PG} = 0.4\text{ V}$	3.6	4.1	4.6	mA
$V_{OUT\_PG}$	VOUT power good threshold	High limit falling edge (PG from low to high)		110%		
		High limit hysteresis (PG from high to low)		5%		
		Low limit rising edge (PG from low to high)		90%		
		Low limit hysteresis (PG from high to low)		5%		
<b>LOGIC CONTROL</b>						
$R_{PD}$	/CE internal pull down resistor			1		M $\Omega$

	PWM pin internal pull down resistor		0.5	MΩ
V <sub>IL</sub>	/CE, PWM input low voltage		0.4	V
V <sub>IH</sub>	/CE, PWM input high voltage		1.2	V
<b>Soft Start</b>				
t <sub>SS</sub>	Internal soft-start time	From /CE low to 90% VOUT	8      15	ms
<b>THERMAL SHUTDOWN</b>				
T <sub>SD</sub>	Thermal shutdown temperature <sup>(1)</sup>		165	°C
	Thermal shutdown hysteresis <sup>(1)</sup>		15	°C

(1) Guarantee by design



## 8 Detailed Description

The SC8201 is a synchronous boost controller with a wide input/output voltage range. It features maximum input and output current limit capability using additional resistors, and output voltage dynamic change.

### 8.1 Feature Description

#### 8.1.1 Chip Enable (/CE)

The SC8201 turns on/off by /CE signal. When /CE input is "L", the SC8201 is turned on; when /CE input is "H", the SC8201 is turned off.

#### 8.1.2 VOUT voltage setting (FB)

The VOUT voltage is set by external resistor divider at FB pin and is calculated as:

$$V_{OUT} = V_{FB\_REF} \times \left(1 + \frac{R_{UP}}{R_{DOWN}}\right)$$

Where:

$V_{FB\_REF}$  = Internal reference voltage 1.22V

$R_{UP}$  and  $R_{DOWN}$  = Resistor divider at FB connected to VOUT and AGND.

#### 8.1.3 Output voltage POWER GOOD indicator (PG)

The PG signal indicates VOUT voltage status.

If VOUT voltage remains in between 90% ~ 110% of programmed voltage, PG pin becomes high impedance and due to the output pull-up resistor, PG out becomes "H" to indicate the output voltage is good.

If VOUT is out of normal voltage range, PG out becomes "L".

If power good indication is not required, leave PG pin floating.

#### 8.1.4 Real-time output voltage control (PWM)

The SC8201 supports VOUT voltage change by PWM signal at VPWM pin.

The VPWM pin accepts a PWM signal in the range of 20kHz to 100kHz, and its duty cycle can adjust the VOUT voltage. VOUT output voltage is calculated as:

$$V_{OUT} = V_{OUT\_SET} \times \left(\frac{1}{6} + \frac{5}{6} \times D\right)$$

Where;

$V_{OUT\_SET}$  = VOUT voltage which is set by FB resistor divider;

D = Duty cycle of PWM signal.

The relationship between VOUT voltage and D is showed in Figure 1

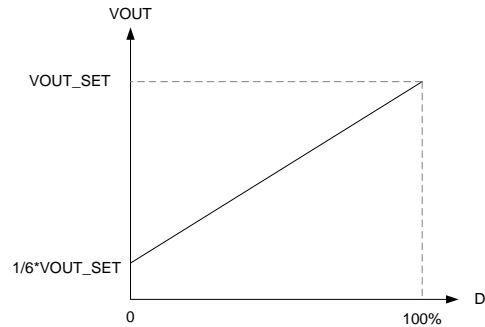


Figure 1 VOUT voltage vs PWM duty cycle.

If PWM input signal is logic high, it means 100% of duty cycle, then the output voltage become the set value by FB resistor divider.

If PWM input signal is logic low, it means 0% of duty cycle, then the output voltage become the 1/6 of the set value.

If PWM pin is left floating, due to the IC internal pull down circuit at VPWM pin, VOUT voltage becomes the 1/6 of programmed voltage.

If real-time output voltage control is not required, connect VPWM pin to VCC pin.

#### 8.1.5 Input/output current setting (ILIMx)

The SC8201 can adjust the current limit of both input side and output side by resistors at ILIM1 and ILIM2 pins.

Control Pins	Description
ILM1	Set the input current limit ( $I_{IN\_LIM}$ )
ILM2	Set the output current limit ( $I_{OUT\_LIM}$ )

The SC8201 senses the input and output current by monitoring  $R_{SNS1}$  and  $R_{SNS2}$  respectively as below figure shows.

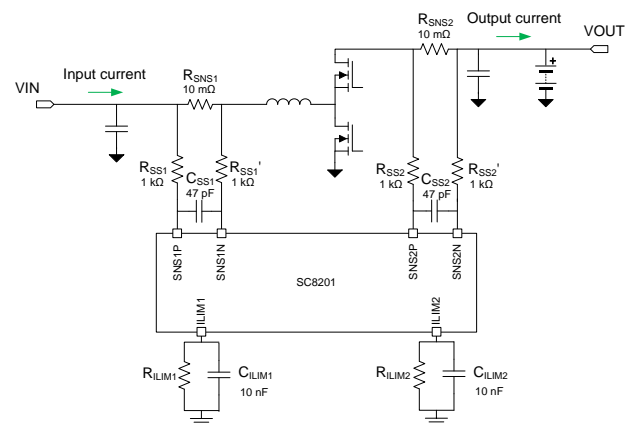


Figure 3 Input/output current monitoring circuit

$R_{SNSx}$  is the current sense resistor (x means 1 or 2) at input/output. The SC8201 monitors the voltage across the sense resistors  $R_{SNSx}$  through  $R_{SSx}$  and  $R_{SSx'}$  and calculates the input and output current.  $C_{SSx}$  is the filter capacitor and typically 47pF is sufficient.

The ILIMx pin is used to set the current limit. Connect the  $R_{ILIMx}$  resistor between ILIMx pin and GND (or ITUNE pin if IPWM function is used).

The current limit is calculated as:

$$I_{IN\_LIM} = \frac{V_{LIM\_REF}}{R_{ILIM1}} \times \frac{R_{SS1}}{R_{SNS1}}$$

$$I_{OUT\_LIM} = \frac{V_{LIM\_REF}}{R_{ILIM2}} \times \frac{R_{SS2}}{R_{SNS2}}$$

Where:

$V_{LIM\_REF}$  = Internal reference voltage 1.21V;

$R_{ILIMx}$  = Resistors at ILIMx pin;

$R_{SNSx}$  = Current sense resistors;

$R_{SSx}$  = Resistors between current sense resistor and the SC8201 pins (SNSxP, SNSxN).

$R_{SNS1}$  should be placed between MOSFET and input capacitor.  $R_{SNS2}$  can be placed either between the MOSFET and output capacitor or behind the output capacitor.

$R_{SS1}$  and  $R_{SS1'}$  should have the same value;  $R_{SS2}$  and  $R_{SS2'}$  also the same. Typically 1kΩ resistor is used.

If  $R_{SNSx}$  is changed,  $R_{SSx}/R_{SSx'}$  values need to be adjusted accordingly with below calculation:

$$\frac{R_{SSx}}{R_{SNSx}} = \frac{10 \text{ m}\Omega}{1 \text{ k}\Omega}$$

For example, If  $R_{SNSx}$  is 20mΩ, then  $R_{SSx}/R_{SSx'}$  should be 2kΩ; if  $R_{SNSx}$  is 5mΩ, then  $R_{SSx}/R_{SSx'}$  should be 500Ω.

If both VIN and VOUT current limits are programmed, the SC8201 controls the current which reaches its current limit first.

If the input/output current limit is not required, connect ILIM1/ILIM2 pin to GND.

It is not allowed to set any of the current limits to 0A. Keep the minimum current limit above 0.3A.

### 8.1.6 Dead time setting (DT)

The one of four dead times is selectable by resistor value at DT pin:

DT resistor	Dead time
0Ω	20ns
68kΩ (±10%)	40ns
270kΩ (±10%)	60ns
Open	80ns

The accuracy of the resistor at DT is allowed ±10%. DT does not support the real-time change and new resistor value change will be applied in next turn on.

When driving large power MOSFET with high  $C_{ISS}$  value, or adding driver resistors at LD or HD to adjust the MOSFET turning on/off time, it is suggested to check and change the dead time to prevent MOSFET shoot-through.

### 8.1.7 Switching frequency setting (FREQ)

The one of three switching frequency is selectable by resistor value at FREQ pin:

FREQ resistor	Switching frequency $f_{sw}$
0Ω	200kHz
68kΩ (±10%)	400kHz
Open	600kHz

The accuracy of the resistor at FREQ is allowed ±10%. The real-time switching frequency change is not valid and new resistor value change will be applied in next turn on.

### 8.1.8 Feedback compensation (COMP)

The feedback loop can be compensated by adjusting the external components to the COMP pin. Typically, the values in Figure 4 are used. If faster loop response is required, user can increase the resistor to like 20kΩ. After changing the compensation, check and make sure the loop is stable under the application operation conditions.

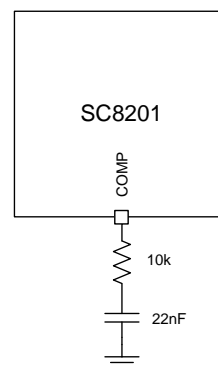


Figure 4 Feedback loop compensation setting

### 8.1.9 VCC driver voltage

The SC8201 generates driver voltage VCC internally. The VCC regulator is powered by VOUT, and clamped to 10V if VOUT is higher than 10V.

The driving signal LD to drive low side MOSFET is directly supplied from VCC; the driving signal HD to drive high side MOSFET is supplied from the diode in between VCC to BT pin, which is generated by bootstrap circuit with bootstrap capacitor between BT and SW.

## 9 Application Information

### 9.1 Input and output capacitor selection

The switching frequency of the SC8201 is in the range of 200kHz ~ 600kHz. Since MLCC ceramic capacitor has good high frequency filtering with low ESR, above 60 $\mu$ F X5R or X7R capacitors with higher voltage rating than operating voltage with margin is recommended. For example, if the highest operating voltage is 12V, select at least 16V capacitor and to secure enough margin, 25V voltage rating capacitor is recommended.

The high capacitance electrolytic capacitor and tantalum capacitor can be used for stable input and output but capacitor voltage rating should be higher than the highest operating voltage. When the tantalum capacitor is used, at least 1 $\mu$ F ceramic capacitor is needed to place in parallel. If the electrolytic capacitor is used, much more ceramic capacitors are required. For example, if a 47 $\mu$ F electrolytic capacitor is used, the ceramic capacitors' capacitance is allowed to reduce to 30 $\mu$ F ~ 40 $\mu$ F. Even higher capacitance electrolytic capacitor is used, at least 20 $\mu$ F ceramic capacitor is required.

### 9.2 Inductor selection

For the SC8201 system stability, the inductance of 2.2 $\mu$ H ~ 10  $\mu$ H inductor is required. High inductance (4.7 $\mu$ H ~ 10 $\mu$ H) is used in the system where the input voltage and output voltage difference is big, such as 5V  $V_{in}$  and 20V  $V_{out}$  or the switching frequency is low; Low inductance (2.2 $\mu$ H) is used in the system which the input voltage and output voltage difference is small but high current is required. Typically, 3.3 $\mu$ H inductor is recommended. The inductance can be adjusted for high efficiency and optimization in application.

The inductor DC resistance value (DCR) affects the conduction loss of switching regulator, so around 10m $\Omega$  DCR is recommended for the first selection. If the power is relatively small, high DCR inductor can be selected. But if switch current is high, just like around 10A, then select the lowest DCR inductor as much as possible because 10m $\Omega$  DCR also causes 1W power loss.

The inductor saturation current  $I_{SAT}$  should be higher than input / output current with sufficient margin.

### 9.3 Current sense resistor

The RSNS1 and RSNS2 are current sense resistors and 5m $\Omega$  ~ 20m $\Omega$  resistor value is recommended.

Higher resistor value leads to higher current limit accuracy but using higher resistor value in high current application

causes higher conduction loss. Typically, 10m $\Omega$  is recommended. Resistor value can be adjusted depending on current limit and target power efficiency. If  $R_{SNSx}$  valued is adjusted, related  $R_{SSx}$  value should be adjusted simultaneously.

Please refer to [8.1.5 Input/output current setting \(ILIMx\)](#) for proper  $R_{SNSx}$  and  $R_{SSx}$  values. The resistor power rating and temperature coefficient should also be considered. The power dissipation is roughly calculated as  $P=I^2R$ , and I is the highest current flowing through the resistor. The resistor power rating should be higher than roughly calculated power dissipation. The resistor value can be varied if the temperature increased and the variation is decided by temperature coefficient along with temperature change. If high accuracy of current limit is required, select lower temperature coefficient resistor as much as possible.

### 9.4 MOSFET selection

The SC8201 is a synchronous boost controller and it requires two external NMOS for power switching circuit.

The  $V_{DS}$  of MOSFET should be higher than the highest operating voltage with enough margin (recommend more than 10V higher). For example, if the highest operating voltage is 20V, at least 30V rated  $V_{DS}$  MOSFET should be selected; If the highest operating voltage is 24V, 40V  $V_{DS}$  voltage rating should be selected.

In the application, if the input and output voltage are higher than 10V, driver circuit voltage can reach 10V, and  $V_{GS}$  voltage rating of MOSFET should be selected higher than 10V.

Considering PCB parasitic parameters during operation, driver voltage can be higher than VCC due to transient overshoot, and 20V  $V_{GS}$  is recommended to secure sufficient margin.

The MOSFET current  $I_D$  should be higher than the highest input and output current with enough margin.

To ensure the sufficient current capability in relatively high temperature circumstance, the current rate at  $T_A=70^\circ\text{C}$  or  $T_C = 100^\circ\text{C}$  should be considered. In addition, the power dissipation value  $P_D$  should also be considered and higher  $P_D$  is better in applications. Make sure that MOSFET power consumption must not exceed  $P_D$  value.

The MOSFET  $R_{DS(ON)}$  and input capacitor  $C_{ISS}$  impact power efficiency directly. Typically, lower  $R_{DS(ON)}$  MOSFET has higher  $C_{ISS}$ . The  $R_{DS(ON)}$  is related to conduction loss. Higher  $R_{DS(ON)}$  results in higher conduction loss, thus lower efficiency and higher thermal dissipation; the  $C_{ISS}$  is related to MOSFET switch on/off time, and longer on/off time results in higher switching loss and lower efficiency. The proper MOSEFT should be selected based on tradeoff between the  $R_{DS(ON)}$  and  $C_{ISS}$ .

Normally, if the output power is around 20W ~ 30W, the MOSFET with around 10m $\Omega$  of  $R_{DS(ON)}$  and lower than 1000pF of  $C_{ISS}$  is recommended. If the output power is

increased, the MOSFET with lower  $R_{DS(ON)}$  and under 2000pF  $C_{ISS}$  is recommended. The highest  $C_{ISS}$  is suggested not to exceed 3000pF.

If high  $C_{ISS}$  MOSFET is selected, the switching on and off time become longer, then the dead time should be adjusted with DT pin to avoid simultaneous turn on for both high side and low side MOSFETs.

### 9.5 Driver resistor and SW snubber circuit

For a convenient adjustment of MOSFET switching time and transient overshoot at EMI debugging, recommend to add 0603 series resistor between driver pins and MOSFET Gate pins, and add RC snubber (0603) circuit at SW (refer to Figure 5 Driver resistor and SW snubber circuit)

The driver resistor should be placed near to MOSFET Gate pin. At first, add  $0\Omega$  and adjust the resistor value appropriately within  $10\Omega$ . After increasing the driver resistor value, the on time of high side and low side MOSFET should be monitored. If the dead time is insufficient, adjust dead time accordingly.

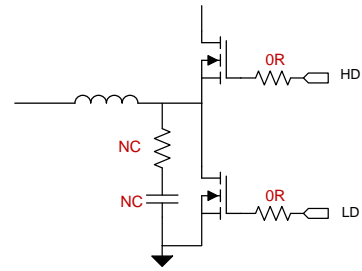


Figure 5 Driver resistor and SW snubber circuit

The RC snubber circuit is required when the overshoot at SWx needs to be suppressed. Leave RC snubber circuit as NC at the first time

Packaging Information

QFN32L(0404x0.75-0.40)

