

HV-mW[™]、2nd Generation Quasi-Resonant (QR-II[™]) PWM Controller With PFC ON/OFF Control

FEATURES

- **Meet EPS Level 6**
- Smart PFC Control Function Integrated Proprietary QR-IITM Technology:
- •Digital Anti-jitter for Audio Noise Free Operation
 - Digital Frequency Foldback
 - Digital Frequency Jittering
- Proprietary HV-mWTM to Achieve Ultra Low **Standby Power**
- Multi-Mode Operation for High Efficiency
- 12.7us Maximum On Time
- 80KHz Maximum Frequency Limit
- 53KHz Frequency Low Clamping in QR Mode
- Maximum 65% Duty Cycle
- Adaptive Slope Compensation for CCM Mode
- Latch Plug-off Protection
- **Built-in Soft Start Function**
- **Pin Floating Protection**
- **Built-in Synchronous Slope Compensation**
- Cycle-by-Cycle Current Limiting
- Leading Edge Blanking (LEB)
- **Constant Power Limiting**
- VDD UVLO, OVP & Clamp

APPLICATIONS

Offline AC/DC Flyback Converter for

- **AC/DC** Adaptors
- **SMPS Power Supply**

TYPICAL APPLICATION

GENERAL DESCRIPTION

SF5897 is a high performance, 2nd Generation Quasi-Resonant (QR-II[™]) PWM controller for offline flyback power converter applications. The built-in proprietary **HV-mW[™]** technology and **QR-II[™]** technology with high level protection features can improve the SMPS reliability and performance. SF5897 can turn off FPC power supply for higher efficiency at light load. In SF5897, the "Digital Anti-Jitter" function can automatically select and lock a valley at a given loading, which can achieve audio noise free operation. On the other hand, the "Digital Frequency Jittering" function makes the system have superior EMI performance than conventional QR system. SF5897 is a multi mode controller. When full loadings,

the IC works in CCM mode or QR mode based on the AC line input. When the loading goes low, the IC enters into "Digital Frequency Foldback" mode to boost power conversion efficiency. When the output power is very small, the IC enters into burst mode and can achieve less than ultra low standby power.

SF5897 integrates functions and protections of Under Voltage Lockout (UVLO), VDD Over Voltage Protection (VDD OVP), Output Over Voltage Protection (Output OVP), Cycle-by-cycle Current Limiting (OCP), Pin Floating Protection, Over Load Protection (OLP), Soft Start, VDD Clamping, Gate Clamping, etc. In SF5897, VDD OVP and Output OVP are latch mode protections, the other protections are auto-recovery mode.

SF5897 is available in SOP8 package.

DC Out **PFC Controller** INV GD SF6562 cs VDD SF5897 нν 1 DEM 8 TL431 FB PFCVDD 7 2 3 VDD 6 CS 4 GND GATE 5



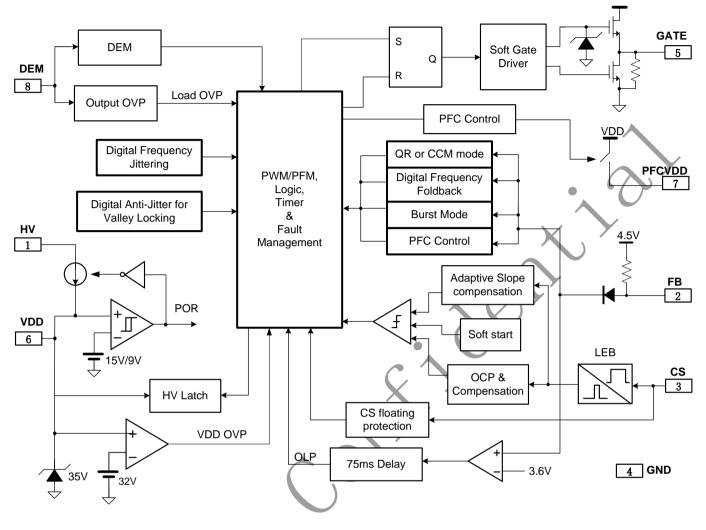
Pin Configuration DEM ΗV 1 8 SOP8 PFCVCC 2 7 FB CS VDD 3 6 GATE GND 4 5 Ordering Information Part Number Top Mark Package Tape & Reel SF5897SG SF5897SG SF5897SG SOP8 Green SF5897SGT SOP8 Green Yes **Marking Information** YWW: Year&Week code SF5897SG YWW

Pin Description

| Pin Num | Pin Name | 1/0 | Description |
|---------|----------|-----|--|
| 1 | HV | P | This pin connects to bulk capacitor for high voltage startup. |
| 2 | FB | I | Voltage feedback pin. The loop regulation is achieved by connecting a |
| | | | photo-coupler to this pin. PWM duty cycle is generated by this pin voltage |
| | | | and the current sense signal at Pin 3. |
| 3 | CS 🗡 | Ι | Current sense input pin. |
| 4 | GND | Р | IC ground pin. |
| 5 | GATE | 0 | Totem-pole gate driver output to drive the external MOSFET. |
| 6 | VDD | Р | IC power supply pin. |
| 7 | PFCVDD | 0 | Power supply output for PFC Controller. |
| 8 | DEM | | Transformer core demagnetization detection pin. This pin is also used for |
| | | | output over voltage protection (OVP). |



Block Diagram



Absolute Maximum Ratings (Note 4)

| Parameter | Value | Unit |
|--|-------------|------|
| HV Voltage range | -0.3 to 700 | V |
| VDD,PFCVDD DC Supply Voltage | 35 | V |
| VDD DC Clamp Current | 10 | mA |
| DEM Voltage Range | -0.7 to 6 | V |
| FB, CS Voltage Range | -0.3 to 7 | V |
| Package Thermal Resistance (SOP8) | 150 | °C/W |
| Maximum Junction Temperature | 150 | °C |
| Operating Temperature Range | -40 to 85 | ٥C |
| Storage Temperature Range | -65 to 150 | °C |
| Lead Temperature (Soldering, 10sec.) | 260 | °C |
| ESD Capability, HBM (Human Body Model) (Except HV Pin) | 3 | kV |
| ESD Capability, MM (Machine Model) | 250 | V |

Recommended Operation Conditions (Note 5)

| Parameter | Value | Unit |
|-------------------------------|-----------|------|
| Supply Voltage, VDD | 11 to 29 | V |
| Operating Ambient Temperature | -40 to 85 | °C |



ELECTRICAL CHARACTERISTICS

| $(T_A = 25^{\circ}C, VDD = 18V, if not otherwise noted)$ | $(T_{A} = 25^{\circ}C)$ | VDD=18V, | if not | otherwise no | oted) |
|--|-------------------------|----------|--------|--------------|-------|
|--|-------------------------|----------|--------|--------------|-------|

| | 8V, if not otherwise noted | | N.4.1 | T | Mart | 11 |
|------------------------|----------------------------|---------------------------------|-------|----------|--------------|--------------|
| Symbol | Parameter | Test Conditions | Min | Тур | Max | Unit |
| | upply Voltage Section | | 1 | 1. | _ | |
| I_HV1 | HV Current Source | VDD=2V, HV=500V | 2 | 4 | 7 | mA |
| I_HV2 | HV Current Source | VDD=13V, HV=500V | 1 | 2 | 3.5 | mA |
| I_HV_leak | HV leakage current | VDD=18V, HV=500V | | | 10 | uA |
| | Section (VDD Pin) | | _ | _ | | - |
| I_Startup | VDD Start up Current | | | 5 | 20 | uA |
| I_VDD_Op | Operation Current | V _{FB} =3.2V, GATE=1nF | | 2 | 3.5 | mA |
| I(VDD_latch) | VDD latch mode | | | 100 | | uA |
| | current | | | | | |
| UVLO(ON) | VDD Under Voltage | | 14 | 15 | 16 | V |
| | Lockout Exit (Startup) | | | | • | |
| UVLO(OFF) | VDD Under Voltage | | 8 | 9 | 10 | \mathbf{v} |
| | Lockout Enter | | | | | r |
| VDD_OVP | VDD Over Voltage | | 30 | 32 | 34 | V |
| | Protection trigger | | | | \mathbf{O} | |
| V _{DD} _Clamp | VDD Zener Clamp | $I(V_{DD}) = 7mA$ | 33 | 35 | | V |
| - | Voltage | | | XY | | |
| T_Softstart | Soft Start Time | | | 4 | | mSec |
| PFC Power Sup | ply Output Section (P | FCVDD Pin) | V | | | |
| Rdson | PFCVDD PMOS On | | | 30 | | ohm |
| | resistance | • | | - | | |
| T_On_debounce | | | | 15 | | mSec |
| T_Off_debounce | | | P | 150 | | mSec |
| | Section(FB Pin) | X / | | | | |
| V _{FB} Open | FB Open Voltage | | | 4.5 | | V |
| VFB_OPCI | T D Open Voltage | | | ч.5 | | v |
| I _{FB} _Short | FB short circuit | Short FB pin to GND, | | 360 | | uA |
| IFB_OHOIT | current | measure current | | 000 | | ci, (|
| A _{VCS} | PWM Input Gain | $\Delta V_{FB} / \Delta V_{es}$ | | 3.5 | | V/V |
| VFB_foldback | FB under voltage | ZVFB/ZVCS | | 1.6 | | V |
| | foldback mode is | | | 1.0 | | v |
| | entered | | | | | |
| VFB_min_duty | FB under voltage gate | | | 1.1 | | V |
| vi D_iiiii_duty | clock is off. | | | 1.1 | | v |
| VFB_PL | Power Limiting FB | | | 3.6 | | V |
| VFD_FL | Threshold Voltage | | | 3.0 | | v |
| T _D PL | Power limiting | Note 3 | | 75 | | mSec |
| | Debounce Time | Note 5 | | 15 | | moec |
| Z _{FB} IN | Input Impedance | | | 13 | | Kohm |
| | nput Section (CS Pin) | | | 15 | 1 | NUHIII |
| | | | 0.44 | 0 45 | 0.40 | M |
| Vth_OC_min | Internal current | Zero duty cycle | 0.44 | 0.45 | 0.46 | V |
| 1/4h 00 mm | limiting threshold | | | 0 77 | | V |
| Vth_OC_max | Internal current | | | 0.77 | | V |
| | limiting threshold | | | 050 | | |
| T_blanking | SENSE Input Leading | | | 250 | | nSec |
| T 00 | Edge Blanking Time | | | 00 | | |
| T _D OC | Over Current | | | 60 | | nSec |
| | Detection and Control | | | | | |
| | Delay | | | | | |
| Demagnetizatio | n Detection Section (I | | | 1 | 1 | |
| | DEM Comparator | | | 100 | | mV |
| VTH_DEM | Threshold Voltage | | | | | |
| | (Negative going edge) | | | | | |
| Vdem_clamp_H | High clamp voltage | | | 6 | | V |
| Vdem_clamp_L | Low clamp voltage | | 1 | -0.7 | | V |
| V _{TH} OVP | Output over voltage | | | 3.4 | | V |



| 1 | | | | 1 | | |
|-----------------------|------------------------|------------------------|------|----------|-----|---------------|
| | protection threshold | | | | | |
| | Number of | | | | | |
| N _{TRUE} OVP | subsequent cycles to | | | 3 | | Cycle |
| | be true OVP | | | | | _ |
| T _{supp} | Suppression of the | Note 4 | | 2.5 | | uSec |
| | transformer ringing at | | | | | |
| | start of secondary | | | | | |
| | stroke | | | _ | | |
| T _{DEM_OUT} | Timeout after last | Note 4 | | 5 | | uSec |
| | demag transition | | | | | |
| Timer Section | | | | | T | <u> </u> |
| T_counter | Sampling Time for | | | 40 | | mSec |
| | Digital Anti-jitter | | | | | |
| | Function | | | | | |
| N_counter_max | Maximum Number for | | | 8 | | \mathcal{O} |
| | Valley Locking | | | | | |
| F_BM | Burst Mode Base | | | 22 | | KHz |
| | Frequency | | | X | | |
| Duty_max | Maximum Duty cycle | | | 65 | | % |
| Fmax_QR_H | Frequency high clamp | | 72 | 80 | 88 | KHz |
| | in QR mode | | | 00 | 00 | 1312 |
| Fmin_QR_L | Frequency low clamp | • | 47 |)52 | 57 | KHz |
| | in QR mode | | | | | |
| ∆F(shuffle)/Fosc | Frequency shuffling | Note 4 | -4 | | 4 | % |
| | range | | | | | |
| Ton_max | Maximum on time | | 11.5 | 12.7 | 14 | us |
| Toff_max | Maximum off time | | 52 | 57 | 64 | us |
| Toff_min | Minimum OFF time | Note 3 | | 2.5 | | uSec |
| Latch Protection | | $\sim \gamma$ | - | | | |
| VDD_latch_H | VDD latch mode high | | | 12 | | V |
| | voltage | | | | | |
| VLatch_release | VDD Latch Release | | | 8.7 | | V |
| | Voltage | | | | | |
| lvdd(latch) | VDD Current when | VDD= VLatch_release+1V | | 100 | | uA |
| | latch off | | | | | |
| Gate Drive Outpu | ut (GATE Pin) | | | | | |
| VOL | Output Low Level | lo = 20 mA (sink) | | | 0.3 | V |
| VOH | Output High Level | lo = 20 mA (source) | 11 | | | V |
| VG_Clamp | Output Clamp Voltage | VDD=24V | | 16 | | V |
| - | | | | | | |
| | Level | | | | | |
| T_r T f | | GATE= 1nF GATE= 1nF | | 80 40 | | nSec nSec |

Note 1. Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

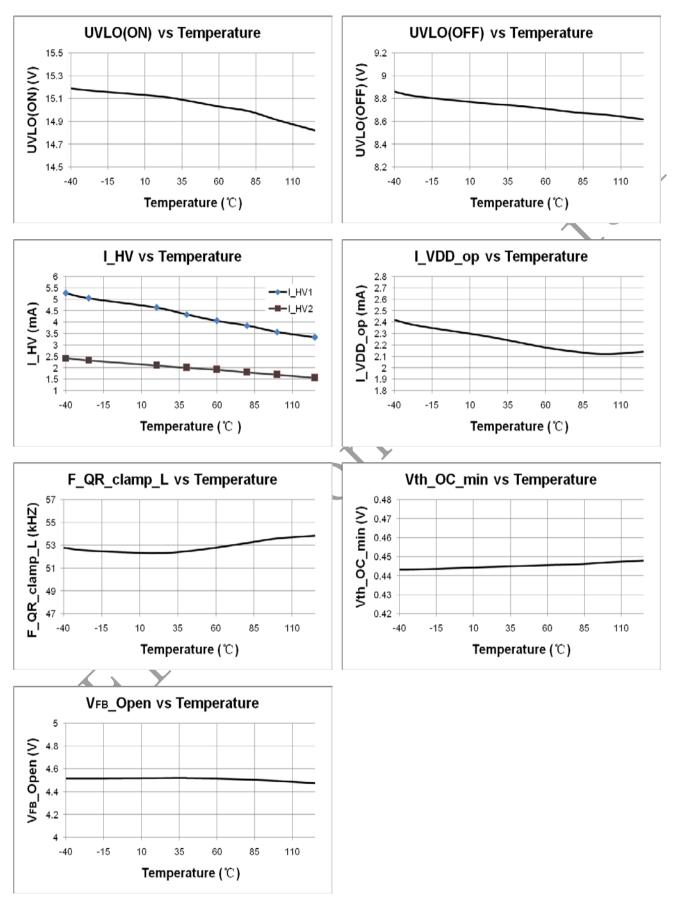
Note 2. The device is not guaranteed to function outside its operating conditions.

Note 3. The OLP debounce time is proportional to the period of switching cycle.

Note 4. Guaranteed by design.



CHARACTERIZATION PLOTS



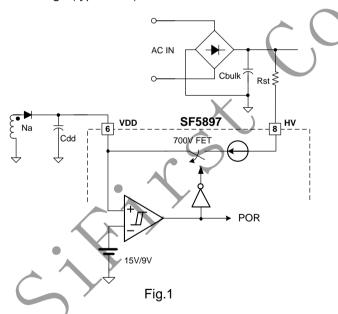


OPERATION DESCRIPTION

SF5897 is a high performance, highly integrated Quasi-Resonant (QR) PWM controller for medium to large offline flyback power converter applications. The built-in proprietary **QR-IITM** technology with high level protection features improves the SMPS reliability and performance without increasing the system cost. SF5897 can supply energy for PFC controller through the PFCVDD pin, and it will turn off the PFC output when the load is light.

◆ Proprietary HV-mW[™] Technology to Achieve Ultra Low Standby Power

HV-mW[™] proprietary SF5897 Integrates technology to achieve ultra low standby power. The core of HV-mW[™] technology is related a built-in 700V startup circuit and standby control. Fig.1 shows the high voltage (HV) startup circuit for SF5897 applications. The HV pin is connected to the line input or bulk capacitor through a resistor. During startup, the internal startup circuit is enabled and a HV current source charges the VDD hold up capacitor Cdd through Rst. When VDD reaches UVLO turn-on voltage of 15V(typical), SF5897 begins switching and the IC current consumed increased to 2mA (typical). The hold-up capacitor Cdd continues to supply VDD before the energy can be delivered from auxiliary winding Na. During this process, VDD must not drop below UVLO turnoff voltage (typical 9V).

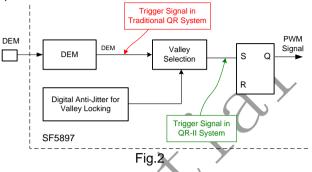


In general application, Rst is recommended to be larger than $30K\Omega$ to limit the startup current.

♦ QR-II[™] Technology Introduction • Digital Anti-Jitter for Valley Locking

Traditional QR system suffers from audio noise issues. As shown in Fig.2, traditional QR system triggers new PWM cycle using demagnetization information by sensing DEM pin voltage. However, the PWM trigger signal may toggle between different valleys at a given loading, which may cause audio noise issue.

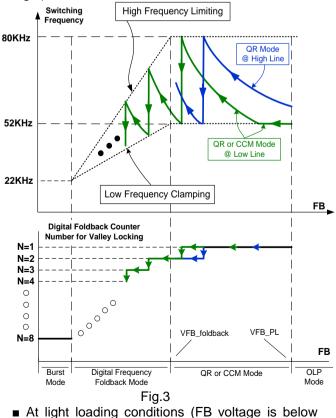
In SF5897, a "**Digital Anti-Jitter**" function is integrated to lock and select a valley at a given loading, which can achieve audio noise free operation.



• "Digital Frequency Foldback" and Multi-Mode Operation

SF5897 is a multi-mode QR controller. The proprietary **Digital Frequency Foldback**" can achieve high efficiency when the loading is light.

■ At normal or full loading conditions, the operating mode is CCM when the input is in low line range since the low clamping frequency (52KHz typical) is touched. Thus, small size transformer can be used with high power conversion efficiency. When the input is in high line input range, the IC work in QR mode with high frequency clamping (typical 80KHz), as shown in Fig.3. When FB voltage is larger than VFB_PL, the system enters into OLP mode with auto recovery protection (as illustrated in Fig.8 and Fig.9).





VFB_foldback), the IC works in "**Digital Frequency Foldback**" mode. The system frequency is limited between "High Frequency Limiting" and "Low Frequency Clamping", as shown with the dashed line in Fig.3. In "**Digital Frequency Foldback**" mode, the IC locks the switching valley and selects the valley according to the load changes. There is a counter in SF5897, the IC selects the valleys according to the registered counter number. In SF5897, the maximum counting number is 8.

■ When zero or very light load conditions, the IC enters into burst mode. In the burst mode (as illustrated in Fig.5), the valley locking counting number is fixed at 8. In this way, a small standby power can be achieved.

• PFC ON/OFF Control

SF5897 can supply energy for PFC controller using internal power P-MOSFET through the PFCVDD pin. The P-MOSFET is on at middle and high load, however when the load becomes light the P_MOSFET will be turned off for high efficiency, and SF5897 can switch the state smoothly, so high PF value and high efficiency can be achieved both.

• Digital Frequency Jittering

Traditional QR system suffers from EMI issues since the PWM switching frequency is actually fixed with a given loading. To improve system EMI performance, SF5897 integrates a "Digital Frequency Jittering" block to operate the system with $\pm 4\%$ frequency jittering around the PWM switching frequency.

• Low Operating Current

The operating current in SF5897 is as small as 2mA (typical). The small operating current results in higher efficiency and reduces the VDD hold-up capacitance requirement.

• Soft Start

SF5897 features an internal 4ms (typical) soft start that slowly increases the threshold of cycle-bycycle current limiting comparator during startup sequence. It helps to prevent transformer saturation and reduce the stress on the secondary diode during startup. Every restart attempt is followed by a soft start activation.

Demagnetization Detection

The transformer core demagnetization is detected by monitoring the voltage activity on the auxiliary windings through DEM pin. When the stored energy is fully released to the output, the voltage on DEM goes down. If DEM pin voltage drops below 0.1V, an internal DEM comparator is triggered and a new switching cycle is initiated following the DEM triggering. The power MOSFET is always turned on with zero inductor current such that the turn-on loss and noise can be minimized.

Ringing Suppression Timer

After power MOSFET is turned off, there will be some oscillation on Vds, which will also appear on the voltage on DEM pin. To avoid that the power MOSFET is turned on mistriggered by such oscillations, a ringing suppression timer Tsupp is implemented in SF5897. In normal operation, Tsupp starts when CS reaches the feedback voltage FB, the external power MOSFET is set to off state. During Tsupp, the external power MOSFET remains in off state and cannot be turned on gain. In SF5897, the ringing suppression timer Tsupp is set to 2.5us internally.

Leading Edge Blanking (LEB)

Each time the power MOSFET is switched on, a turn-on spike occurs across the sensing resistor. The spike is caused by primary side capacitance and secondary side rectifier reverse recovery. To avoid premature termination of the switching pulse, an internal leading edge blanking circuit is built in. During this blanking period (250ns, typical), the PWM comparator is disabled and cannot switch off the gate driver.

Adaptive Slope Compensation

InSF5897, the synchronous slope compensation circuit is integrated by adding voltage ramp onto the current sense input voltage for PWM generation. This greatly improves the close loop stability at CCM and prevents the sub-harmonic oscillation and thus reduces the output ripple voltage.

In SF5897, when the fixed frequency CCM mode is touched(as show in Fig.2), the slope compensation will be automatically added to the system to improve current loop stability. When the system leaves fix frequency CCM mode, the slope compensation will automatically disappear.

Maximum Frequency Clamp

According to the QR operation principle, the switching frequency is inversely proportional to the output power. Therefore, when the output power decreases, the switching frequency can become rather high without limiting. To meet EMI limit and to achieve high efficiency at light loading conditions, the maximum switching frequency in SF5897 is internally limited to 80KHz.

• OCP Compensation

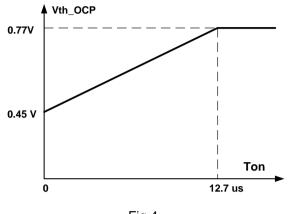
The variation of maximum output power in QR system can be rather large if no compensation is provided. The OCP threshold value is self adjusted lower at higher AC voltage. This OCP threshold slope adjustment helps to compensate the increased output power limit at higher AC voltage. In SF5897, a proprietary OCP compensation block is integrated and no external components are needed. The OCP threshold in SF5897 is a function of the switching ON time. For the ON time less than 12.7us, the OCP threshold changes linearly from



SF5897

0.45V to 0.77V. For the ON time larger than 12.7us, the OCP threshold is clamped to 0.77V, as shown in Figure 4.

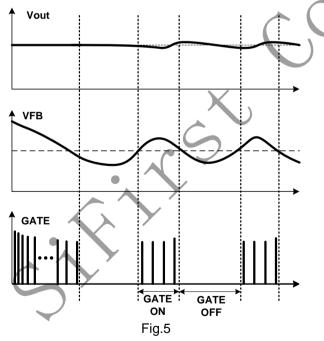
The maximum PWM duty cycle is about 65% in SF5897.





Burst Mode Control

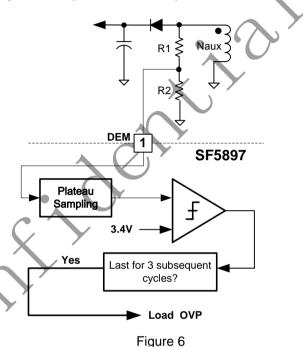
When the loading is very small, the system enters into burst mode. When VFB drops below VFB_min_duty, SF5897 will stop switching and output voltage starts to drop, which causes the VFB to rise, as shown in Fig.5. Once VFB rises above VFB_min_duty, switching resumes. Burst mode control alternately enables and disables switching, thereby reducing switching loss in standby mode.





In SF5897, the load OVP is integrated by plateau sampling the auxiliary winding in flyback phase. An internal 2.5us sampling delay guarantees a clean plateau, provided that the leakage inductance ringing has been fully damped. The threshold voltage for output OVP is 3.4V, as shown in Fig.6

If the sampled plateau voltage exceeds the OVP threshold (3.4V), an internal counter starts counting subsequent OVP events. If OVP events are detected in successive 3 cycles, the controller assumes a true OVP and it stops all switching operations. The counter has been added to prevent incorrect OVP detection which might occur during ESD or lightning events. If the output voltage exceeds the OVP threshold less than 3 successive cycles, the internal counter will be cleared and no fault is asserted. Output OVP is **latch mode** protection (mentioned below).



Latch Mode Protection

As shown in Fig.7, once a latch mode protection (such as OTP, VDD OVP, etc) is detected, switching will stop. VDD voltage will ramp up and down between VDD_latch_H (typical 12V) and UVLO(OFF) (typical 9V). The VDD ramping up current is get from HV pin. In latch mode, IC consumption current is about 100uA. The latch will not release unless AC input is unplugged from the mains.

SF SiFirst

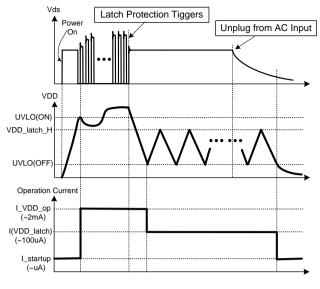


Fig.7

 Over Load Protection (OLP) / Over Current Protection (OCP) / Over Power Protection (OPP) / Open Loop Protection (OLP)

When OLP/OCP/OPP/Open Loop occurs, a fault is detected. If this fault is present for more than 75ms (typical), the protection will be triggered, the IC will experience an auto-recovery mode protection, as shown in Fig.8. The 75ms delay time is to prevent the false trigger from the power-on and turn-off transient.

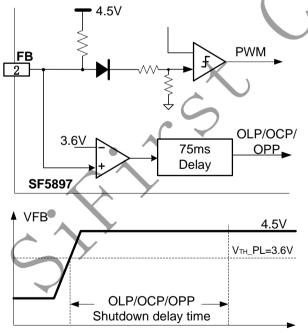
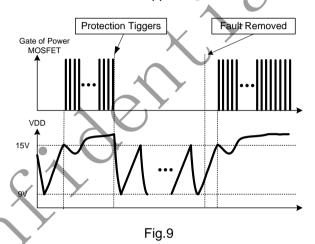


Fig.8

Auto Recovery Mode Protection

As shown in Fig.9, once a fault condition is detected, switching will stop. This will cause VDD to fall because no power is delivered form the auxiliary winding. When VDD falls to UVLO(off) (typical 9V), the protection is reset and the operating current reduces to the startup current, which causes VDD to rise, as shown in Fig.9. However, if the fault still exists, the system will experience the above mentioned process. If the fault has gone, the system resumes normal operation. In this manner, the auto restart can alternatively enable and disable the switching until the fault condition is disappeared.



VDD OVP(Over Voltage Protection)

VDD OVP (Over Voltage Protection) is implemented in SF5897 and it is a protection of **latch mode**.

• Pin Floating Protection

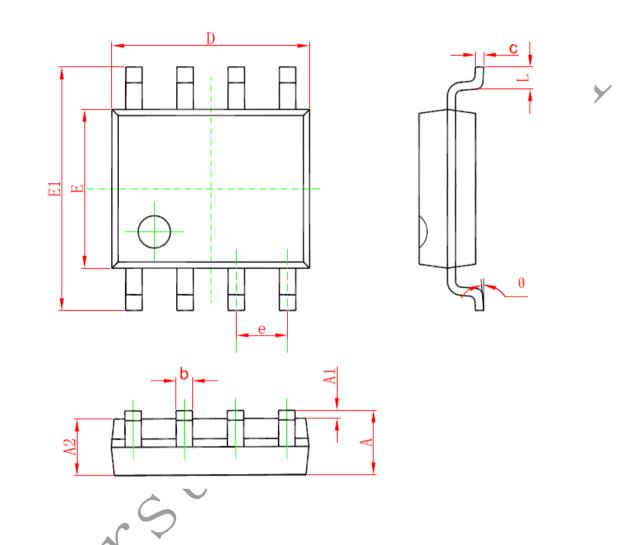
In SF5897, if pin floating situation occurs, the protection is triggered immediately and the system will experience the process of auto-recovery mode protection.

• Soft Gate Drive

The driving stage of SF5897 is a soft totem-pole gate driver to minimize EMI. Cross conduction has been avoided to minimize heat dissipation, increase efficiency, and enhance reliability.

PACKAGE MECHANICAL DATA

SOP8 PACKAGE OUTLINE DIMENSIONS



| Symbol | Dimensions I | n Millimeters | Dimensions In Inches | | |
|--------|--------------|---------------|----------------------|-------|--|
| Symbol | Min | Max | Min | Max | |
| A | 1.350 | 1.750 | 0.053 | 0.069 | |
| A1 | 0.050 | 0.250 | 0.002 | 0.010 | |
| A2 | 1.250 | 1.650 | 0.049 | 0.065 | |
| b | 0.310 | 0.510 | 0.012 | 0.020 | |
| C | 0.170 | 0.250 | 0.006 | 0.010 | |
| D | 4.700 | 5.150 | 0.185 | 0.203 | |
| E | 3.800 | 4.000 | 0.150 | 0.157 | |
| E1 | 5.800 | 6.200 | 0.228 | 0.244 | |
| е | 1.270 (BSC) | | 0.05 (| BSC) | |
| L | 0.400 | 1.270 | 0.016 | 0.050 | |
| θ | 0° | 8° | 0° | 8° | |

IMPORTANT NOTICE

SiFirst Technology Nanhai, Ltd (SiFirst) reserves the right to make corrections, modifications, enhancements, improvements and other changes to its products and services at any time and to discontinue any product or service without notice. Customers should obtain the latest relevant information before placing orders and should verify that such information is current and complete.

SiFirst warrants performance of its hardware products to the specifications applicable at the time of sale in accordance with SiFirst's standard warranty. Testing and other quality control techniques are used to the extent SiFirst deems necessary to support this warranty. Except where mandated by government requirements, testing of all parameters of each product is not necessarily performed.

SiFirst assumes no liability for application assistance or customer product design. Customers are responsible for their products and applications using SiFirst's components. To minimize the risks associated with customer products and applications, customers should provide adequate design and operating safeguards.

Reproduction of SiFirst's information in SiFirst's data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. Reproduction of this information with alteration is an unfair and deceptive business practice. SiFirst is not responsible or liable for such altered documentation. Information of third parties may be subject to additional restrictions.

Resale of SiFirst's products or services with statements different from or beyond the parameters stated by SiFirst for that product or service voids all express and any implied warranties for the associated SiFirst's product or service and is an unfair and deceptive business practice. SiFirst is not responsible or liable for any such statements.

SiFirst's products are neither designed nor intended for use in military applications. SiFirst will not be held liable for any damages or claims resulting from the use of its products in military applications.

SiFirst's products are not designed to be used as components in devices intended to support or sustain human life. SiFirst will not be held liable for any damages or claims resulting from the use of its products in medical applications.